

Vision Sensor FH/FZ5 Series Vision System

Processing Item Function Reference Manual

FH-1□□□

FH-3□□□

FZ5-L35□

FZ5-6□□

FZ5-11□□



Introduction

Thank you for purchasing the FH/FZ5.

This manual provides information regarding functions, performance and operating methods that are required for using the FH/FZ5.



When using the FH/FZ5, be sure to observe the following:

- The FH/FZ5 must be operated by personnel knowledgeable in electrical engineering.
- To ensure correct use, please read this manual thoroughly to deepen your understanding of the product.
- Please keep this manual in a safe place so that it can be referred to whenever necessary.

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Related Manuals

The following manuals are related to the FH-series Sensor Controllers. Use these manuals for reference.

Manual name	Cat. No.	Model numbers	Application	Description
Vision System FH/FZ5 Series Processing Item Function Reference Manual (This manual)	Z341	FH-1xxx FH-3xxx FZ5-L35x FZ5-6xx FZ5-11xx	Learning about how to configure settings for processing items for the FH/FZ5 Series Vision Sensors	In this manual, we will describe how to configure settings for processing items for the FH/FZ5 Series Vision Sensors.
Vision System FH/FZ5 Series User's Manual	Z340	FH-1xxx FH-3xxx FZ5-L35x FZ5-6xx FZ5-11xx	Learning about how to configure settings for the FH/FZ5 Series Vision Sensors	In this manual, we will describe how to configure settings using the sensor controller for the FH/FZ5 Series Vision Sensors.
Vision System FH/FZ5 Series User's Manual for Communications Settings	Z342	FH-1xxx FH-3xxx FZ5-L35x FZ5-6xx FZ5-11xx	Learning about how to configure communications settings for the FH/FZ5 Series Vision Sensors	In this manual, we will describe how to configure communications settings using the sensor controller for the FH/FZ5 Series Vision Sensors.
Vision System FH Series Operation Manual for Sysmac Studio	Z343	FH-1xxx FH-3xxx	Learning about how to configure settings for and operate the sensor controller for the FH Series from the Sysmac Studio FH Tools	In this manual, we will describe how to configure settings for and operate the sensor controller for the FH Series from the Sysmac Studio FH Tools.
Sysmac Studio Version 1 Operation Manual	W504	SYS-MAC-SE2xxx	Learning about the operating procedures and functions of the Sysmac Studio	Describes the operating procedures of the Sysmac Studio.

Conventions Used in This Manual

Symbols

The symbols used in this manual have the following meanings.

Important Indicates relevant operational precautions that must be followed.

Note Indicates operation-related suggestions from OMRON.

Use of Quotation Marks and Brackets

In this manual, menus and other items are indicated as follows.

[] Menu Indicates the menu names or processing items shown in the menu bar.

" " Item name Indicates the item names displayed on the screen.

MEMO

Input image

This chapter describes how to load images from cameras.

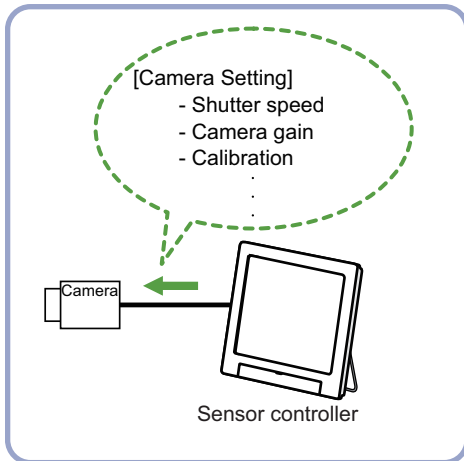
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Camera Image Input

This is a processing item specific to the FZ5 Sensor Controller.

Set the conditions for loading images from the camera and for storing images of the measured objects. This processing item must be used when measuring.

Used in the Following Case

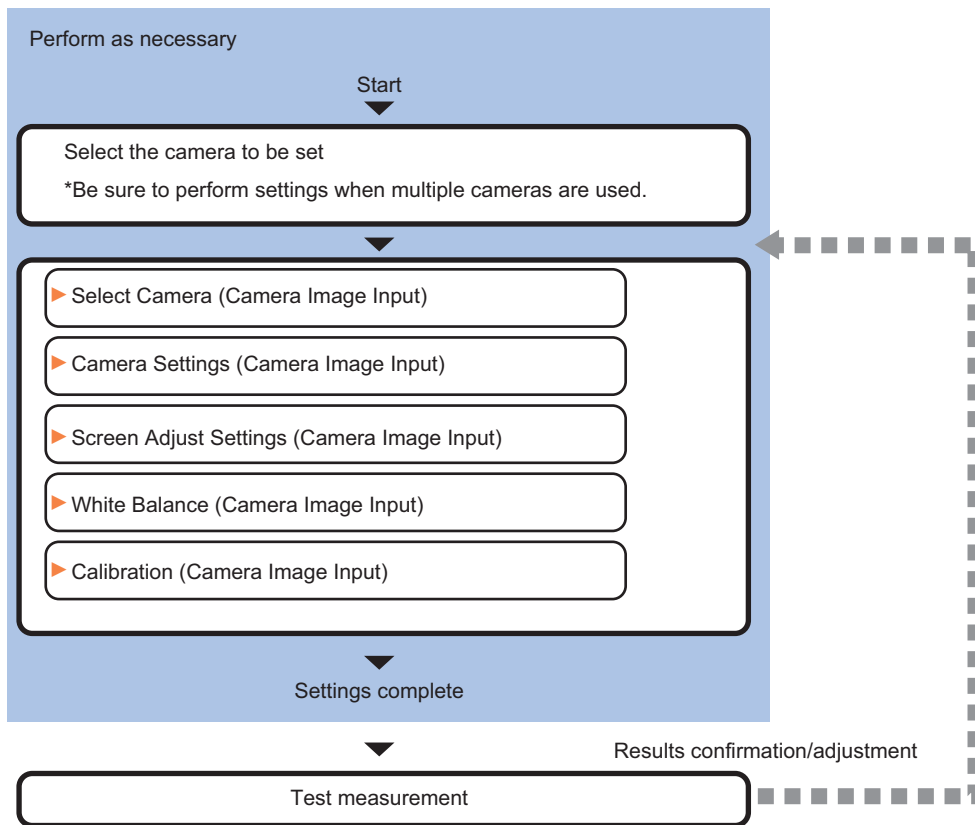


Important

- When using an intelligent camera FZ-SLCx or an auto-focus camera FZ-SZCx, camera image input and camera image input HDR cannot be used together.
- [Camera Image Input] is preset for Unit 0. Do not set any processing item other than camera image input (camera image input HDR, camera image input HDR Lite) for Unit 0.
- When switching from a color camera to a monochrome or switching to a camera with a different resolution, reconfigure the settings in the following units.
- If a camera is connected other than the one for the previous settings, the camera settings are returned to their initial settings.
- It is also possible to set multiple camera image input items to the flow and shoot images at different shutter speeds. However, in this case, if the images are logged, only the last camera image input is logged.

Settings Flow (Camera Image Input)

To set camera image input, follow the steps below.



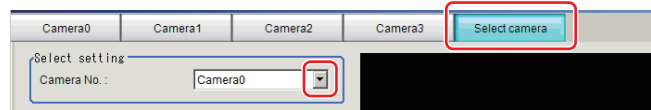
Camera Image Input Item List

Item	Description
Camera 0 to 3	Select the camera to be set.
Select camera	When multiple cameras are connected, select the camera to use for measurement. Reference: ▶ Select Camera (Camera Image Input) (p.20)
Camera setting	Specify the camera settings such as the shutter speed or electronic flash. Reference: ▶ Camera Settings (Camera Image Input) (p.20)
Screen adjust	Adjust the lighting and the lens. Reference: ▶ Screen Adjustment Settings (Camera Image Input) (p.24)
White balance	When using a color camera, adjust the white balance. Reference: ▶ White Balance (Camera Image Input) (p.30)
Calibration	Set when measurements (camera coordinate measurement values) are to be output using actual dimensions. Select the calibration setting method and generate the calibration parameters. Reference: ▶ Calibration (Camera Image Input) (p.31)

Select Camera (Camera Image Input)

When multiple cameras are connected, select the camera to use for measurement.

1 In the Item Tab area, click [Select camera].



2 Click [Camera No.] [▼] and select the camera number.

3 If multiple cameras are connected, the camera to transfer images for can be selected.

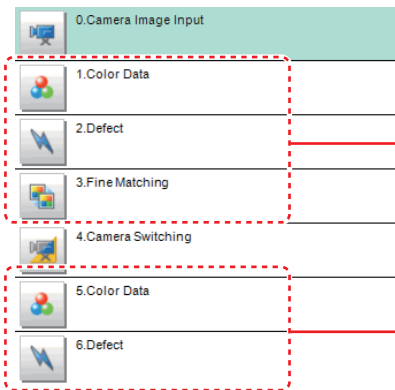
Removing the check for any camera not being used for the current scene can eliminate the transfer processing time after image input for that camera and speed up the takt time.

Important

- Transfer of images for Camera 0 is executed at the same time as image input. Therefore, even if you uncheck the checkbox for Camera 0, the image transfer time is not shortened.

Note

- The image from the camera selected in [Select camera] will be the object to be measured in the following units. If you need to switch the camera during the process, insert a [Camera Switching] unit in the scene and switch the image. Reference: ▶ Camera Switching (p.64)



The image selected through the [Select camera] option in the [0 Camera Image Input] is the object to be measured.

The image selected through the [Select camera] option in the [4 Camera Switching] is the object to be measured.

Camera Settings (Camera Image Input)

Set the following photographing conditions for each camera.

- Reference: ▶ Camera Settings (p.21)
- Reference: ▶ Frame/Field - for Monochrome Cameras Only (p.22)
- Reference: ▶ Number of lines to be read (p.23)
- Reference: ▶ Electronic Flash Setting (p.23)

Note

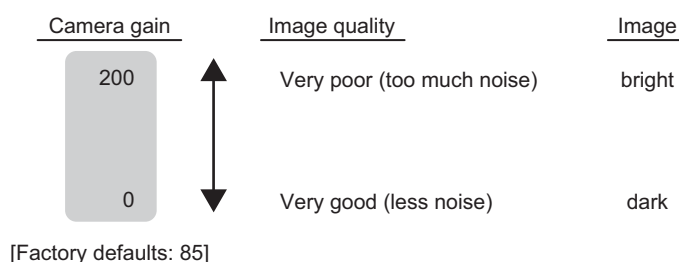
- The displayed items differ depending on the camera type and lighting mode. Perform the following procedure as necessary in accordance with the use environment.

Camera Settings

Adjust the settings related to camera shutter speed and camera gain.

Select the shutter speed appropriate to the speed of the measurement object. Choose a faster shutter speed if the measurement object is moving quickly and the image is blurred.

Adjust the camera gain when images cannot be brightened through the shutter speed, lens aperture, or lighting conditions. Usually, the factory default value can be used.

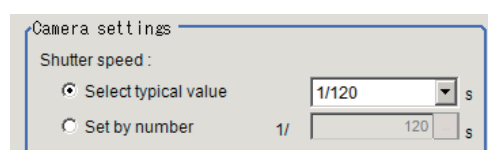


1 In the Item Tab area, click [Camera setting].



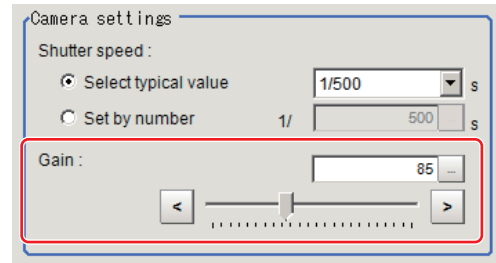
2 In the "Camera settings" area, specify the shutter speed.

The setting methods are to select from the options offered or to set the value directly.



Item	Set value [Factory default]	Description
Shutter speed	For stand-alone cameras Typical value <ul style="list-style-type: none"> • [1/120] (For FZ-SFx, FZ-SPx, FZ-SC2M/FZ-S2M, FZ-SC5M2/FZ-S5M2) • 1/200 • [1/500] (for FZ-SC/FZ-S, FZ-SLC, FZ-SZC) • 1/1000 • 1/2000 • 1/4000 • 1/8000 • 1/20000 Set by number <ul style="list-style-type: none"> • 1/10 to 1/50000 For intelligent compact cameras Typical value <ul style="list-style-type: none"> • 1/250 • 1/500 • [1/1000] • 1/2000 • 1/4000 • 1/8000 • 1/16000 • 1/30000 Set by number <ul style="list-style-type: none"> • 1/250 to 1/30000 	Option values for the shutter speed differ depending on the camera type.

3 Specify the camera gain while checking the image.



Item	Set value [Factory default]	Description
Gain	For stand-alone cameras 0 to 230 • [50] (For FZ-SFx, FZ-SPx, FZ-SC2M/FZ-S2M, FZ-SC5M/FZ-S5M) • [85] (for FZ-SC/FZ-S, FZ-SLC, FZ-SZC) For intelligent compact cameras 16 to 64 [16]	Adjust the camera gain when the shutter speed, the lens aperture, and lighting conditions cannot be used to brighten the image. Usually, the factory default value can be used.

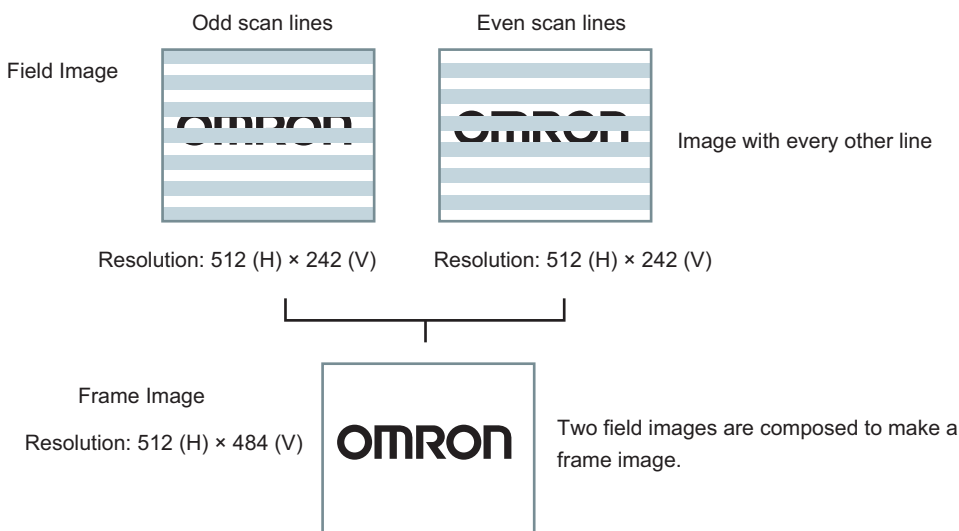
Important

- When an intelligent compact camera, FZ-SQxxxx, is connected, we recommend setting the gain value to 16 for stable operations. Measurement values may be different if the recommended value is exceeded. Be sure to thoroughly check the measurement result and set the gain value.

Frame/Field - for Monochrome Cameras Only

There are two methods to transfer one image from a camera to the sensor controller: frame read and field read. Frame read is to read all of the scanned lines of the image. The result is called a frame image. Field read is used to read half of the interlaced scanned lines of the image. The result is called the field image.

Here, select the unit to be treated as one image.



- 1 In the Item Tab area, click [Camera setting].
- 2 In the "Frame/Field" area, select either "Frame" or "Field".

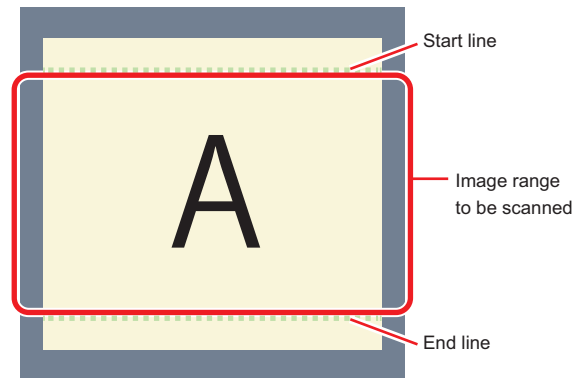
Item	Set value [Factory default]	Description
Frame/Field	[Frame]	Measurements are done in frame units.
	Field	Measurements are done in field units. Select "Field" when you prefer shorter image input time rather than higher accuracy. Processing becomes faster since each image is scanned skipping one scan line per two consecutive lines, but the measurement precision is decreased because the vertical image resolution is lower.

Number of lines to be read

By narrowing the image range to be loaded, the image scan time can be shortened.

Set the range taking the offset of the measurement object into consideration.

The part of the image narrowed down by the start line and the end line will be displayed in the Image Display area of the processing item setting window or the Main screen.



Note

About minimum number of lines

- The minimum number of lines (minimum number of lines between start and end lines) is 12 lines.2043
- For 5 megapixel cameras, the end line is fixed from 1921 to 2043.

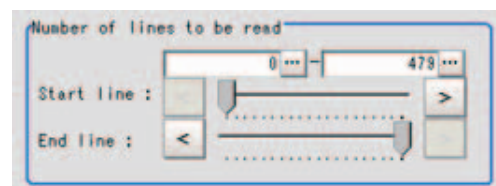
About coordinate values

- The coordinate values displayed as the measurement results are the values of the display position on the monitor.
- The coordinate values do not vary according to the settings for "Number of lines to be read".

1 In the Item Tab area, click [Camera setting].



2 Set the start/end line in the "Number of lines to be read" area.



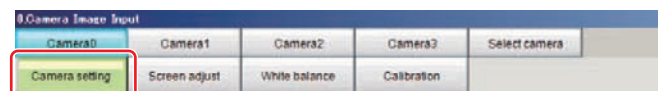
Important

- When the built-in lighting of an FZ-SQxxxx is used, it may not be possible to shorten the processing time due to restrictions on the light emission time.

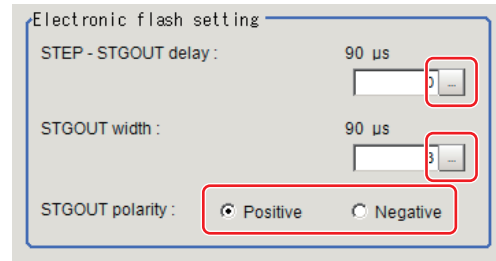
Electronic Flash Setting

This function is set when an electronic flash is used. This sets the output conditions for the signal for synchronizing the measurement and the electronic flash timing.

1 In the Item Tab area, click [Camera setting].



2 In the "Electronic flash setting" area, specify each item.



Item	Set value [Factory default]	Description
STEP - STGOUT delay	[0] to 511 (1 count 30μs)	Set the waiting time from the time the STEP signal is input until the electronic flash trigger output signal comes ON. Delay Time = Count × 30μs + 90μs The delay time depends on whether the STGOUT pulse polarity is positive or negative. The displayed time is for the positive polarity. Add 35μs to the displayed time if the polarity is negative. The delay time can be set in a range of ±10μs from the setting value.
STGOUT width	1 to 63 [3] (1 count 30μs)	Set the output time for the electronic flash trigger signal.
STGOUT	<ul style="list-style-type: none"> [Positive] Negative 	Select the pulse polarity of the electronic flash trigger. Positive polarity: Flashes synchronized with the timing of the electronic flash trigger output signal changing from OFF to ON. Negative: Flashes when the strobe trigger output signal changes from ON to OFF.

Screen Adjustment Settings (Camera Image Input)

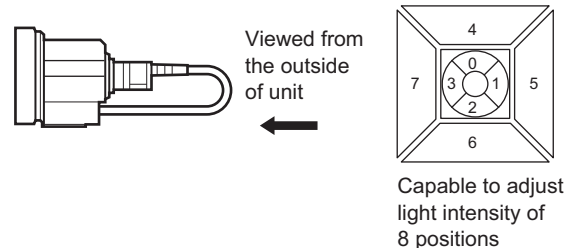
Set the lighting and lens conditions for each camera.

- Reference: ▶ **Lighting Control (p.24)**
- Reference: ▶ **Line Bright (p.28)**
- Reference: ▶ **Lens Adjustment Setting (p.29)**
- Reference: ▶ **Common Setting for All Cameras (p.30)**

Lighting Control

When a camera with a lighting function is connected, the light volume of the lighting can be adjusted from the sensor controller. Brightness can be adjusted automatically or one of the preset patterns can be selected.

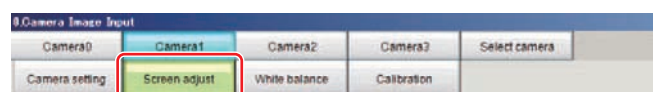
A lighting lamp image is displayed as a guide illustration.



Note

- When 1 scene contains 2 or more camera image input units, lens setting can be performed only for the first camera image input unit.

1 In the item tab area, click [Screen adjust].



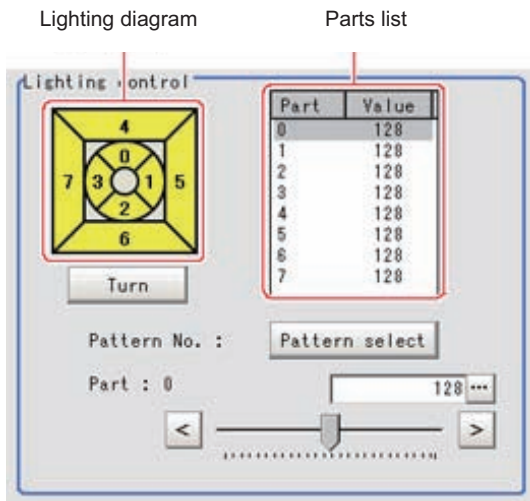
2 In the "Lighting control" area, specify the brightness.

The image display contents depend on the connected camera.

When an intelligent camera is connected

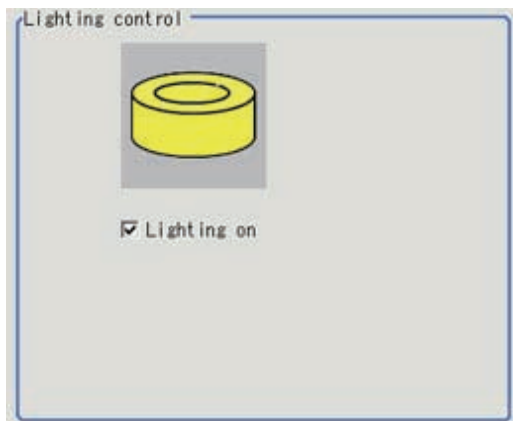
Important

- When model FZ-SLC15 is connected, only parts 0 to 3 are active. Changing parts 4 to 7 will not affect the light volume of lighting.



Item	Set value	Description
Pattern select	Pattern 0 to 16	Can be selected from a preset lighting pattern.
Turn	-	After the camera is installed, if the orientation of the camera does not match the orientation of the lighting parts, click [Turn] under the lighting diagram. The lighting diagram rotates 90 degrees clockwise each time you click [Turn].
Brightness at each part	0 to 255 × 8ch [0]	The light volume at each part can be adjusted to one of 256 levels. 0 indicates the lighting is OFF. The larger the number, the higher the brightness.

Intelligent compact camera FZ-SQxxxx is connected:

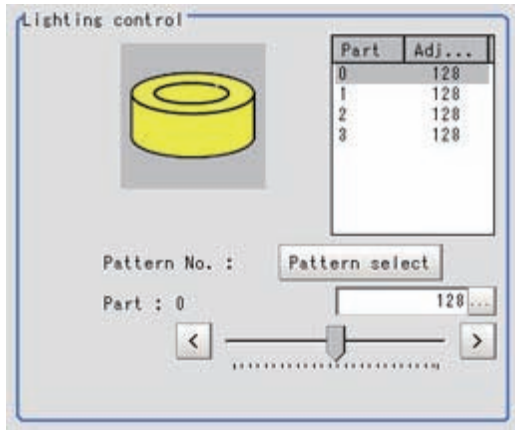


Item	Set value [Factory default]	Description
Lighting on	<ul style="list-style-type: none"> [Checked] Unchecked 	Clear the checkbox when no lighting is to be applied.

Important

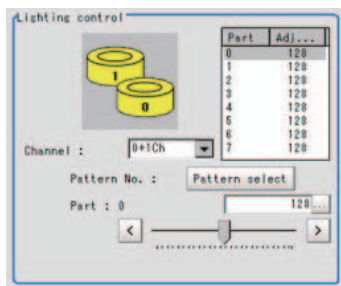
- When built-in lighting is used, the measurement processing time may be longer in comparison with when lighting is OFF.

Electronic flash controller FZ-LTA100 is connected:

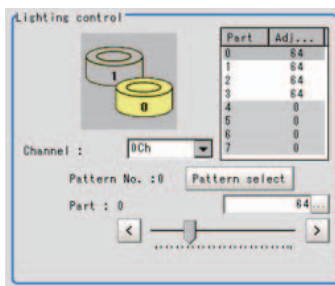


Electronic flash controller FZ-LTA200 is connected:

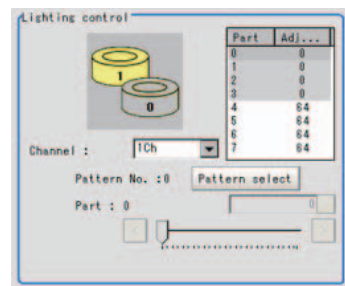
0 +1CH are used:



0CH is used:

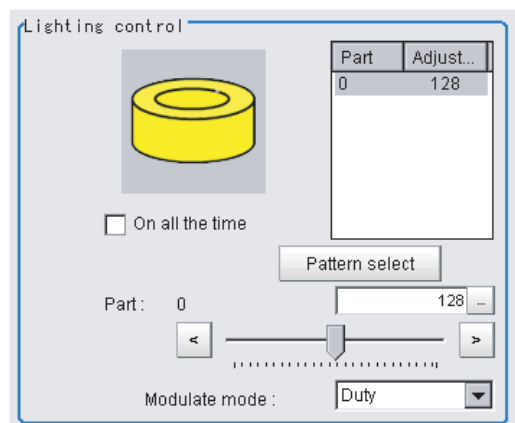


1CH is used:



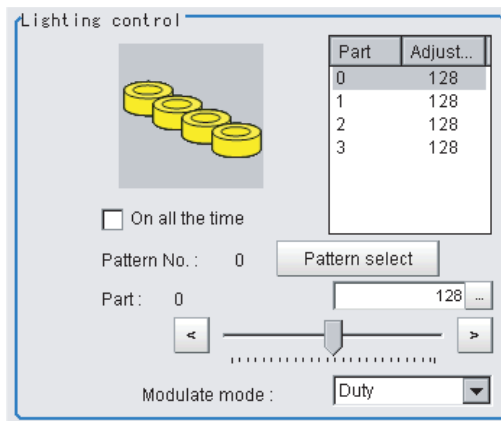
Item	Set value	Description
Pattern select	Pattern 0 to 16	Can be selected from a preset lighting pattern.
Brightness at each part	0 to 255 [0]	When 1 channel is used, the light volume can be adjusted to one of 256 levels. When 2 channels are used, the light volume can be adjusted to one of 128 levels. 0 indicates the lighting is OFF. The larger the number, the higher the brightness.

Camera with lighting controller FLV-TCC1 is connected:



Item	Set value	Description
Pattern select	---	Select from preset lighting patterns.
On all the time	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check here to keep the light turned ON all of the time regardless of the exposure time.
Module mode	<ul style="list-style-type: none"> • [Duty] • Voltage 	Select the lighting adjustment method. <ul style="list-style-type: none"> • Duty The brightness of the light is adjusted with 255 levels of the pulse width (PWM frequency: 100 Hz). • Voltage The brightness of the light is adjusted with 255 voltage levels. Select voltage lighting adjustment if you will use a high-speed shutter speed.
Part	0 to 255 [128]	Set the brightness for the selected parts.

Camera with lighting controller FLV-TCC4 is connected:



Item	Set value	Description
Pattern select	---	Select from preset lighting patterns.
On all the time	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check here to keep the light turned ON all of the time regardless of the exposure time.
Module mode	<ul style="list-style-type: none"> • [Duty] • Voltage 	Select the lighting adjustment method. <ul style="list-style-type: none"> • Duty The brightness of the light is adjusted with 255 levels of the pulse width (PWM frequency: 100 Hz). • Voltage The brightness of the light is adjusted with 255 voltage levels. Select voltage lighting adjustment if you will use a high-speed shutter speed.
Part	0 to 255 [128]	Set the brightness for the selected parts.

Important

- If you use the camera with lighting controller FLV-TCC□ for the lighting, the power consumption and lighting modes are restricted as follows:

Without external power supply

Total power consumption	Power consumption per channel	Connectability	Lighting mode ^{*1}			READY OFF time delay ^{*2}
			Always-on lighting mode	Simultaneous lighting mode	Single lighting mode	
Greater than 7.5 W	Greater than 7.5 W	Not connectable	---	---	---	---
	7.5 W or less	Connectable	NA	NA	OK	None
7.5 W or less	Less than 7.5 W	Connectable	OK	OK	OK	None

With external power supply

Total power consumption	Power consumption per channel	Connectability	Lighting mode ^{*1}			READY OFF time delay ^{*2}
			Always-on lighting mode	Simultaneous lighting mode	Single lighting mode	
Greater than 15 W	Greater than 15 W	Not connectable	---	---	---	---
	15 W or less	Connectable	NA	NA	OK	Yes
	7.5 W or less	Connectable	NA	NA	OK	None
15 W or less	Less than 15 W	Connectable	NA	OK	OK	Yes
	7.5 W or less	Connectable	NA	OK	OK	Yes
7.5 W or less	Less than 7.5 W	Connectable	OK	OK	OK	None

*1: Lighting modes

Always-on lighting mode	In this mode, the lights are always turned ON for a specific pulse cycle. The always-on lighting mode is used if you place a check in "On all the time" in the "Lighting control" area.
Simultaneous lighting mode	In this mode, all of the connected lights are turned ON in synchronization with the trigger. Set the "Adjustment" set values in the "Lighting control" area for each light to any value other than 0 for all of the parts.
Single lighting mode	In this mode, only one of the connected lights is turned ON in synchronization with the trigger. Set the "Adjustment" set value in the "Lighting control" area to any value other than 0 for the part for only one channel. The lights will not turn ON if you set two or more channels to an adjustment other than 0.

*2: Turning OFF the READY signal is delayed in comparison with not connecting a camera with lighting controller by approximately the exposure time.

Example: Connection example for connecting an external power supply and the lighting modes

- If four lights with a power consumption of 1 W each are connected to a camera with lighting controller, always-on lighting, simultaneous lighting, and single lighting are all possible.
- If four lights with power consumptions of 2 W, 3 W, 4 W, and 5 W are connected to a camera with lighting controller, simultaneous lighting and single lighting are possible.
- If four lights with power consumptions of 12 W, 1 W, 2 W, and 1 W are connected to a camera with lighting controller, only single lighting is possible.

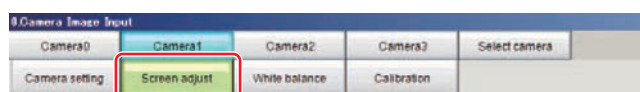
Other cameras are used:

The light volume cannot be adjusted.

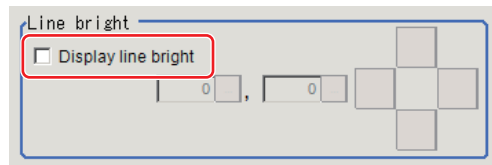
Line Bright

The graph showing the gray distribution for 1 line in the image is called the "Line bright". You can display the line brights for R, G and B for any horizontal or vertical line.

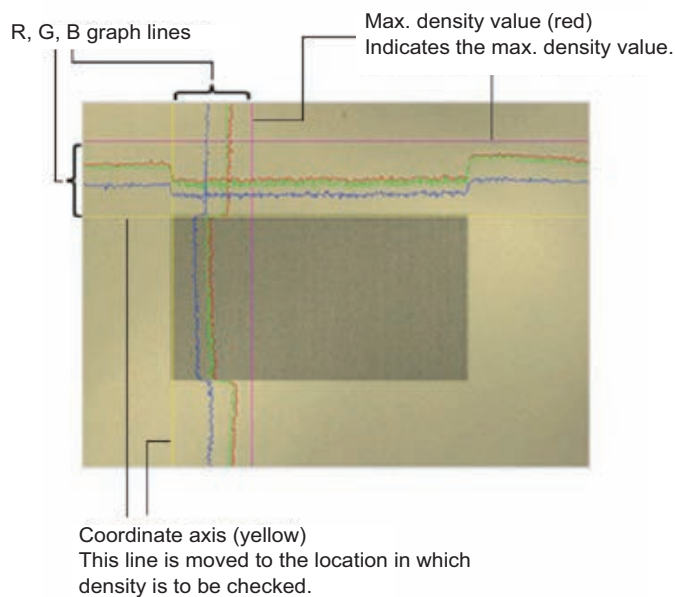
- 1 In the item tab area, click [Screen adjust].



2 Place a check at "Display line bright".



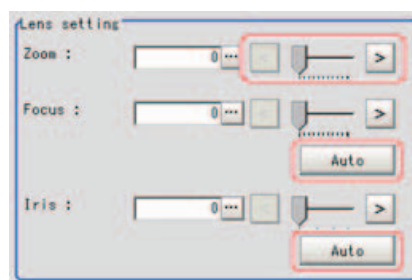
3 Move the line to the position whose density distribution you want to see.



Lens Adjustment Setting

This function is only displayed when an intelligent camera or an auto-focus camera is connected. Make lens adjustments such as the focus and zoom. The optimum value can be set automatically for the focus and iris.

- 1** In the item tab area, click [Screen adjust].
- 2** Specify the "Zoom" size while checking the image.
- 3** Click [Auto] at "Focus" and "Iris".
The focus and iris optimized for the zoomed image are set automatically.



Item	Set value [Factory default]	Description
Zoom	[0] to 1023	Displays the image zoomed in and out. Depending on the focus setting value, it may not be possible to set a large zoom value.
Focus	[0] to 1023	Adjust the focus. When [Auto] is clicked, the optimum focus for the current image is set automatically.
Iris	[0] to 31	Adjust the light volume that passes through the lens. When [Auto] is clicked, the optimum iris for the current image is set automatically.

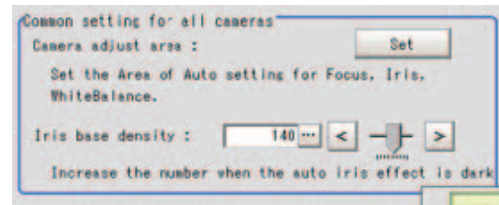
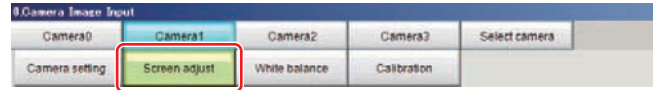
Important

- Auto focus and auto iris can only be used when setting with this screen open. They cannot be used during running.

Common Setting for All Cameras

This function is only displayed when an intelligent camera, an auto-focus camera or a color camera is connected. This sets the conditions for automatically setting the focus, iris, and white balance.

- 1 In the item tab area, click [Screen adjust].
- 2 In the "Common setting for all cameras" area, set up "Camera adjust area" and "Iris base density".



Item	Description
Camera adjust area	This sets the region for judging whether or not the state is appropriate when automatically setting the focus, iris, and white balance.
Iris base density	Increase the number when the auto iris effect is dark.

White Balance (Camera Image Input)

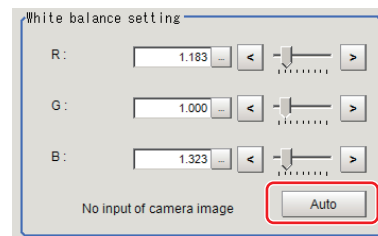
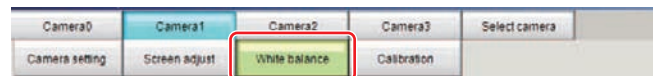
Set the white balance to make white objects look white by calibrating the color of images loaded from cameras. By adjusting the white balance, the appropriate white color can be reproduced under any lighting conditions. Appropriate values can also be set automatically.

Note

- Perform the white balance setting only when a color camera is used.
- In the following cases, make sure to perform white balance.
 - When a new system is installed
 - When the camera or lighting is changed

Since measurement results may vary with changes of the white balance setting, be sure to verify the operation after it has changed.

- 1 In the Item Tab area, click [White balance].
- 2 Shoot a white piece of paper or cloth.
- 3 Click [Auto].



Note

- When the "Too bright" or "Too dark" message is displayed, adjust the iris, shutter speed, gain and/or lighting conditions until "Automatic adjustment is possible" is displayed.

4 Adjust the "R", "G" and "B" values as necessary.

Item	Set value [Factory default]	Description
White balance setting <ul style="list-style-type: none"> • R • G • B 	0.001 to 7.999 (R, G, and B) (For intelligent compact cameras 0.001 to 3.000) For FZ-SC [R=1.183] [G=1.000] [B=1.323] For FZ-SC2M [R=1.394] [G=1.000] [B=1.222] For FZ-SFC, FZ-SPC [R=1.145] [G=1.000] [B=1.1889] For FZ-SC5M2 [R=1.351] [G=1.000] [B=2.314] For intelligent compact cameras [R=1.000] [G=1.040] [B=1.800]	Adjust the white balance. Whiteness increases when the value of "R", "G", and "B" is increased.

Calibration (Camera Image Input)

By setting the calibration, the measurement result can be converted and output as actual dimensions. The calibration method is selected here.

There are three calibration methods, point, sampling, and parameter.

- Reference: ▶ **Specifying Points and Setting (Point Specification) (p.32)**
- Reference: ▶ **Setting Calibration through Sampling Measurement (Sampling) (p.33)**
- Reference: ▶ **Inputting and Setting Values (Value Setting) (p.34)**
- Reference: ▶ **View Calibration Parameters (p.35)**

Note

- In order to output measurement results in actual dimensions, set [Calibration] to "ON" in [Output parameter] for each processing unit. If [Calibration] is "OFF" (factory default), measurement results are output as camera image coordinate values.

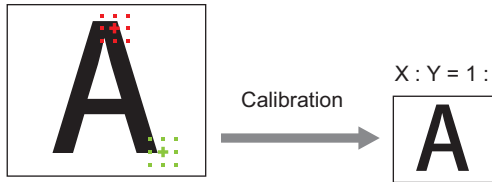
Specifying Points and Setting (Point Specification)

This is a method for performing calibration by specifying arbitrary points (in pixels). Calibration parameters are calculated automatically when actual coordinates of specified locations are entered. Up to 3 points can be specified.

- **When magnification is the same in the X and Y directions**

Specify only 2 points.

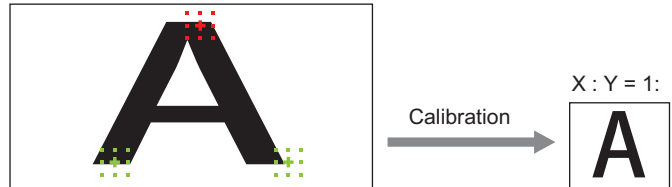
X : Y = 1 : 1



- **When magnification is not the same in the X and Y directions**

Specify 3 points.

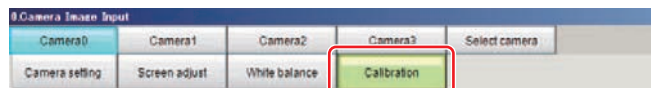
X : Y = 5 : 3



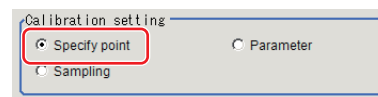
Note

- When 2 points are specified, the coordinate system is set to the left-hand system (forward in the clockwise direction). Specify 3 points to perform calibration including the coordinate system.

1 In the Item Tab area, click [Calibration].



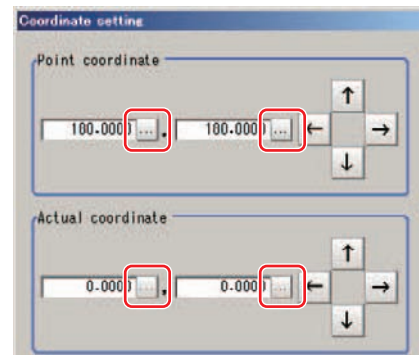
2 In the "Calibration setting" area, select "Specify point".



3 Click the first point on the screen.

4 Input the actual coordinates for the specified point.

The actual coordinate input window is displayed.

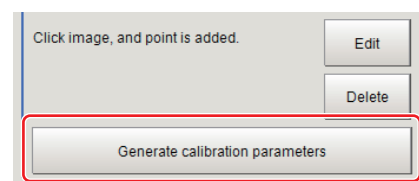


Actual coordinate	Set value [Factory default]
Point coordinate X, Y	0 to 9999.9999 [Point you clicked in the window]
Actual coordinate X, Y	-99999.9999 to 99999.9999 [0]

5 Set the 2nd and 3rd points in the same way.

6 Click [Generate calibration parameters].

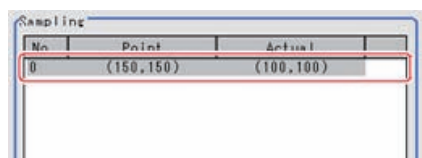
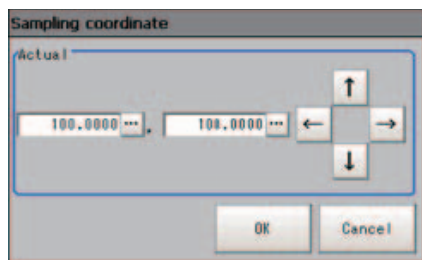
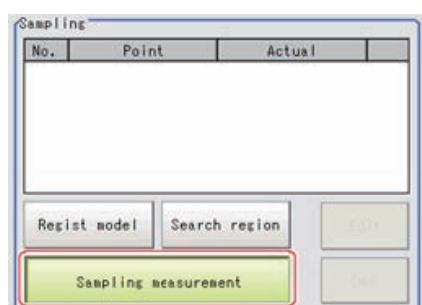
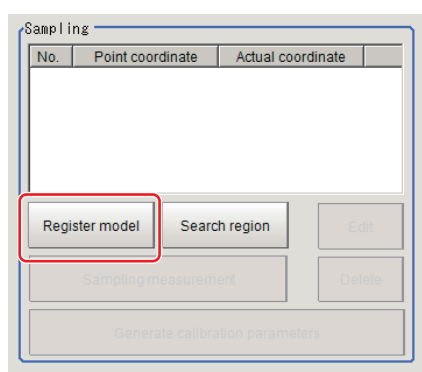
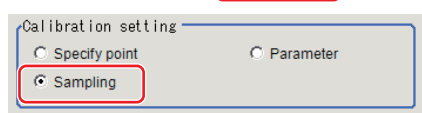
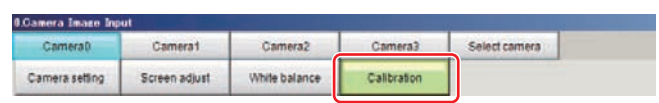
The calibration parameters will be generated.



Setting Calibration through Sampling Measurement (Sampling)

This is a method for setting calibration based on measurement results. Calibration parameters are calculated automatically when a registered model is searched and the actual coordinates for that position entered.

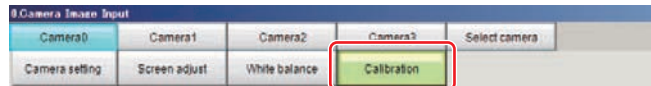
- 1** In the Item Tab area, click [Calibration].
- 2** In the "Calibration setting" area, select "Sampling".
- 3** In the "Sampling" area, click [Register model].
- 4** Use the Drawing tools to register the model.
- 5** Adjust the search region as necessary.
The default value setting is for the entire screen.
- 6** Click [Sampling measurement].
Measurement is performed.
The search result (cross-shaped cursor) is displayed in the Image Display area, and the Sampling Coordinate window is displayed.
- 7** In the Sampling Coordinate window, enter the X and Y values.
- 8** Click [OK].
Point coordinates and actual coordinates are registered in the "Sampling" area.
- 9** Move the object to be measured and repeat the Steps Reference: ▶ 3 (p.33) to Reference: ▶ 8 (p.33).
- 10** Click [Generate calibration parameters].
The calibration parameters will be generated.



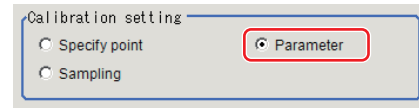
Inputting and Setting Values (Value Setting)

Enter calibration data directly with numerical values.

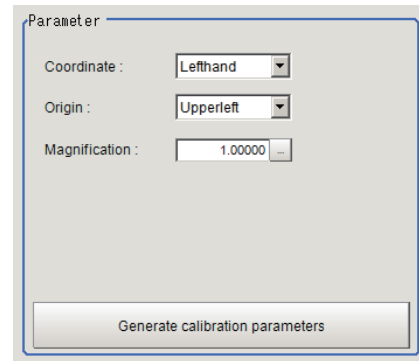
1 In the Item Tab area, click [Calibration].



2 In the "Calibration setting" area, select "Parameter".



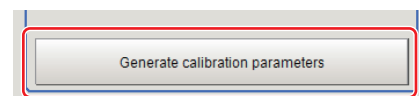
3 In the "Parameter" area, specify values for the "Coordinate", "Origin" and "Magnification".



Item	Set value [Factory default]	Description
Coordinate	<ul style="list-style-type: none"> [Lefthand] Righthand 	<p>Left-hand type: Clockwise is forward when specifying the coordinates. Right-hand type: Counter-clockwise is forward when specifying the coordinates.</p>
Origin	<ul style="list-style-type: none"> [Upperleft] Lowerleft Center 	<p>Select where the origin of the actual coordinates will be.</p>
Magnification	0.00001 to 9.99999	Specify the ratio of 1 pixel to the actual dimensions.

4 Click [Generate calibration parameters].

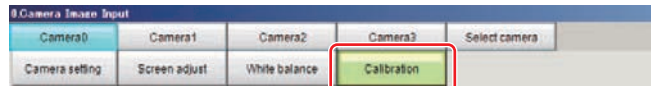
The calibration parameters will be generated.



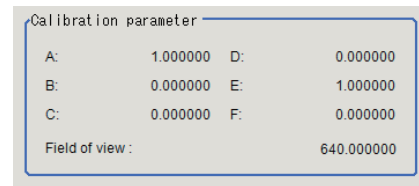
View Calibration Parameters

View the set calibration data.

1 In the Item Tab area, click [Calibration].



2 In the "Calibration parameter" area, confirm the calibration data.

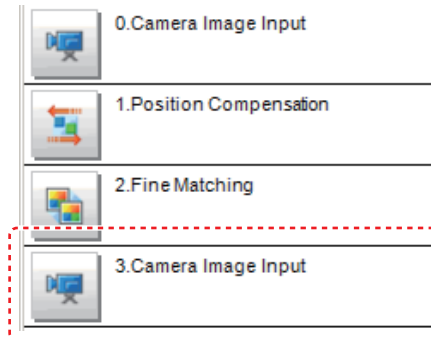


Item	Set value	Description
A	Calculation value	These are calibration conversion values. Camera coordinates are converted to actual coordinates based on these values. The conversion formulas for actual coordinates are as follows: <ul style="list-style-type: none"> • (X, Y): Measurement point (camera coordinates), Unit: pix • (X', Y'): Conversion point (actual coordinates) $X' = A \times X + B \times Y + C$ $Y' = D \times X + E \times Y + F$
B	Calculation value	
C	Calculation value	
D	Calculation value	
E	Calculation value	
F	Calculation value	
Field of view	Calculation value	This is an actual dimension in the X direction.

Additional Explanation (Camera Image Input)

Position Compensation and Camera Image Input

When creating a scene, if a [Camera Image Input] unit is positioned after a [Position Compensation] processing unit, that [Position Compensation] unit will be cancelled, which will cause a new image to be read.



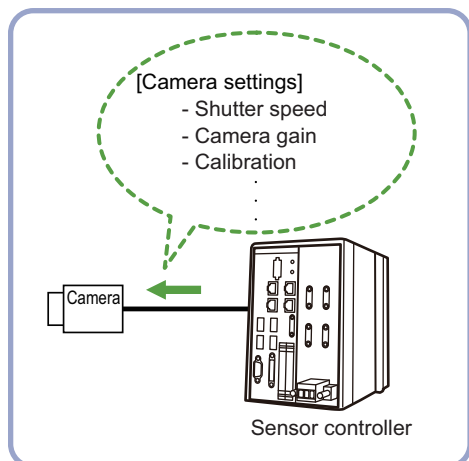
Position compensation of unit 1 is canceled and returns to the position before position compensation.

Camera Image Input FH

This is a processing item specific to the FH Sensor Controller.

Set the conditions for loading images from the camera and for storing images of the measured objects. This processing item must be used when measuring.

Used in the Following Case

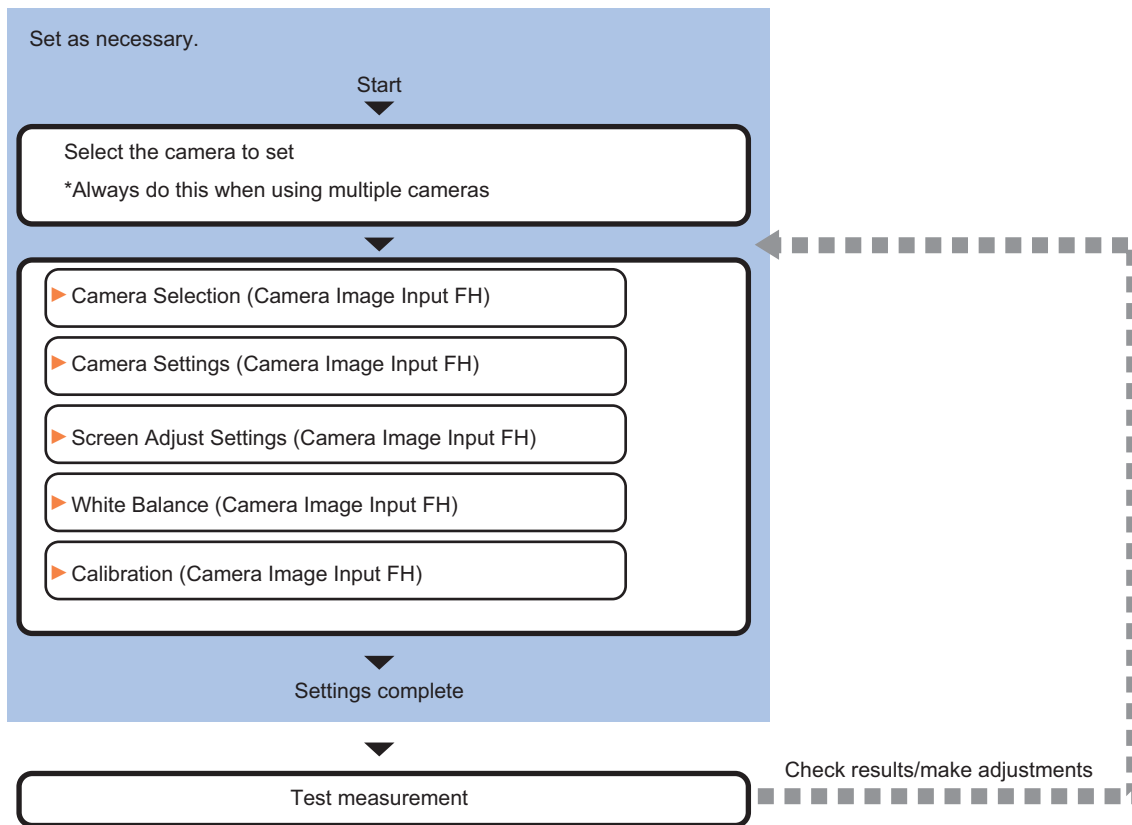


Important

- When using an intelligent camera FZ-SLCx or an auto-focus camera FZ-SZCx, camera image input and camera image input HDR cannot be used together.
- [Camera Image Input FH] is preset for Unit 0. Do not set any processing item other than camera image input (camera image input FH, camera image input HDR, camera image input HDR Lite) for Unit 0.
- When switching from a color camera to a monochrome or switching to a camera with a different resolution, reconfigure the settings in the following units.
- If a camera is connected other than the one for the previous settings, the camera settings are returned to their initial settings.
- It is also possible to set multiple camera image input items to the flow and shoot images at different shutter speeds. However, in this case, if the images are logged, only the last camera image input is logged.

Settings Flow (Camera Image Input FH)

To set camera image input, follow the steps below.



1

Input Image

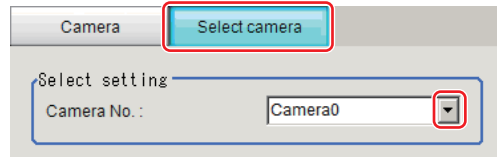
List of Camera Image Input FH Items

Item name	Description
Camera 0 to 7	Select the camera to be set.
Select camera	When multiple cameras are connected, select the camera to use for measurement.
Camera setting	Specify the camera settings such as the shutter speed or electronic flash. Reference: ▶ Camera Settings (Camera Image Input FH) (p.38)
Screen adjust	Set the adjustment of the lighting and the lens. Reference: ▶ Screen Adjustment Settings (Camera Image Input FH) (p.43)
White balance	When using a color camera, set the white balance. Reference: ▶ White Balance (Camera Image Input FH) (p.49)
Calibration	Set when measurements (camera coordinate measurement values) are to be output using actual dimensions. Select the calibration setting method and generate the calibration parameters. Reference: ▶ Calibration (Camera Image Input FH) (p.50)

Camera Selection (Camera Image Input FH)

When multiple cameras are connected, select the camera to use for measurement.

1 In the Item Tab area, click [Select camera].



2 Click [Camera No.] [▼] and select the camera number.

3 If multiple cameras are connected, the camera to transfer images for can be selected.

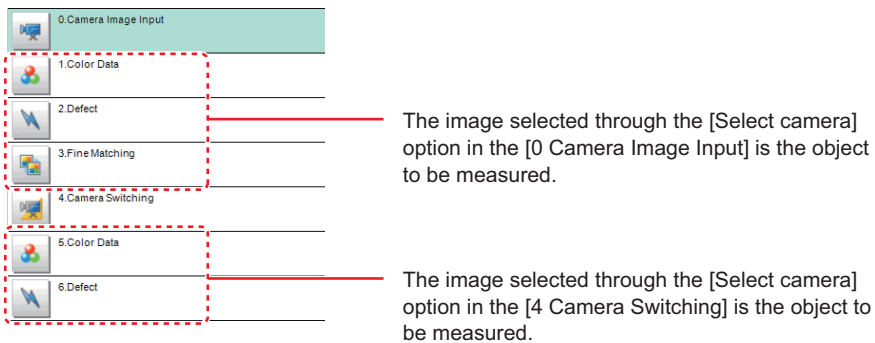
Removing the check for any camera not being used for the current scene can eliminate the transfer processing time after image input for that camera and speed up the takt time.

Important

- Transfer of images for Camera 0 is executed at the same time as image input. Therefore, even if you uncheck Camera 0, the image transfer time is not shortened.

Note

- The image from the camera selected in [Select camera] will be the object to be measured in the following units. If you need to switch the camera during the process, insert a [Camera Switching] unit in the scene and switch the image. Reference: ▶ Camera Switching (p.64)



Camera Settings (Camera Image Input FH)

Set the following photographing conditions for each camera.

- Reference: ▶ Camera Settings (p.39)
- Reference: ▶ Binning Settings - for Monochrome Cameras Only (p.41)
- Reference: ▶ Number of lines to be read (p.41)
- Reference: ▶ Electronic Flash Setting (p.42)

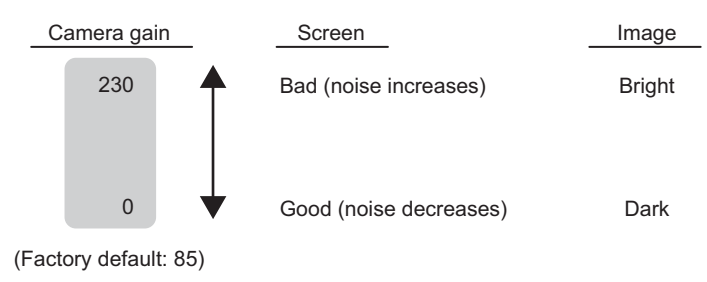
Note

- The displayed items differ depending on the camera type and lighting mode. Specify the setting for the following procedure as necessary in accordance with the use environment.

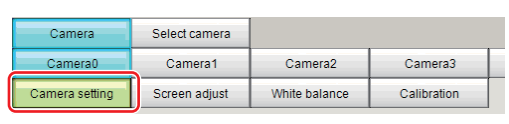
Camera Settings

Adjust the settings related to camera shutter speed and camera gain.
 Set the shutter speed appropriate to the speed of the measurement object. Choose a faster shutter speed if the measurement object is moving quickly and the image is blurred.
 Adjust the camera gain when images cannot be brightened through the shutter speed, lens aperture, or lighting conditions. Usually, the factory default value can be used.

Example Using the FZ-SC



1 In the Item Tab area, click [Camera setting].

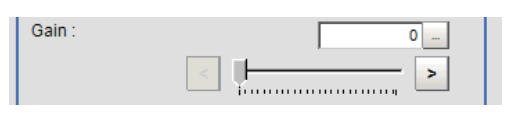


2 In the "Camera settings" area, specify the shutter speed.



Item	Setting value [Factory default]	Description
Shutter speed	For stand-alone cameras 20 to 100000 [μs] [2000] For FZ-SF/SP/S2M/SC2M/S5M2/SC5M2 20 to 100000 [μs] [8333] For intelligent compact cameras 35 to 4000 [μs] [1000]	Option values for the shutter speed differ depending on the camera type.

3 Specify the camera gain while checking the image.



Item	Setting value [Factory default]	Description
Gain	For stand-alone cameras 0 to 230 • [50] (For FZ-SFx, FZ-SPx, FZ-SC2M/FZ-S2M, FZ-SC5M2/ FZ-S5M2) • [85] (for FZ-SC/FZ-S, FZ-SLC, FZ-SZC) • For FH-SC/FH-SM 0 to 255 [0] For intelligent compact cameras 16 to 64 [16]	Adjust the camera gain when the shutter speed, the lens aperture, and lighting conditions cannot be used to brighten the image. Usually, the factory default value can be used.

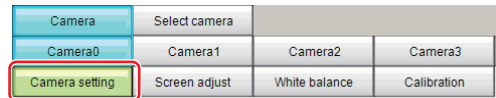
Important

- When an intelligent compact camera, FZ-SQxxxx, is connected, we recommend setting the gain value to 16 for stable operations. Measurement values may be different if the recommended value is exceeded. Be sure to thoroughly check the measurement result and set the gain value.
- Due to the specification of its imaging elements, a CMOS camera generates stripe noises when the gain setting of the camera is raised. You may also find multiple defective pixels, but they do not represent a defect or failure of the product in any way. If stripe noises and defective pixels affect the measurement results, lower the gain setting of the camera or use a CCD camera.

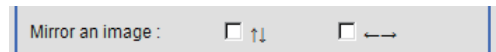
Reverse Conversion

Set this option when reversing the camera image vertically or horizontally. The order in which imaging elements are read is changed, so there won't be any delay in image transfer.

1 In the Item Tab area, click [Camera setting].



2 In the "Camera settings" area, specify the reverse conversion settings.



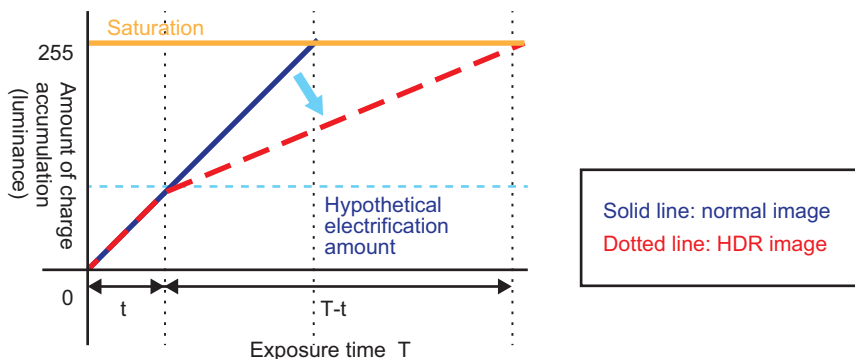
Setting item	Setting value [Factory default]	Description
Mirror an image	↑↓	<ul style="list-style-type: none"> • Checked • [Unchecked] Place a check here when reversing the camera image vertically.
	←→	<ul style="list-style-type: none"> • Checked • [Unchecked] Place a check here when reversing the camera image horizontally.

Setting Multi-slope Function (for Monochrome Cameras of FH-SMxx Only)

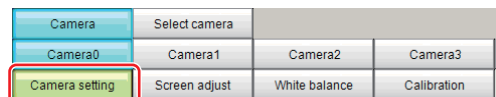
Set this option if you wish to capture a work having a wide dynamic range with a single exposure without causing saturation.

Bright pixels that have reached the charge level specified in the CMOS are clipped and the inclination of stored charge is adjusted, to prevent saturation.

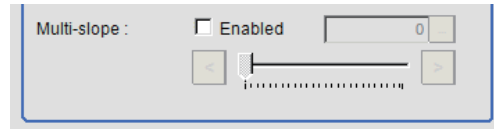
When the multi-slope function is set, pixels that saturate on normal images will no longer saturate. The stored charge amount (inclination of brightness) is changed in the CMOS during a single exposure. This function can also be set for mobile objects because, unlike with Camera Image Input HDR or Camera Image Input HDR Lite, there is no need to change the exposure time and capture and combine multiple images.



1 In the Item Tab area, click [Camera setting].



2 In the "Camera settings" area, specify the Multi-slope settings.



Setting item		Setting value [Factory default]	Description
Multi-slope	Enabled	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check here to use the multi-slope function.
	Slider	-	Set the new level of the inclination of brightness. When the slider is moved to the left, images of wide dynamic ranges can be supported. A desired level can be set on a scale of 1 to 255.

Binning Settings - for Monochrome Cameras Only

Binning is a function to add up multiple lines to obtain a single value. The frame rate of the camera can be raised by decreasing the amount of data transferred.

1 In the Item Tab area, click [Camera setting].

In the "Binning settings" area, select either "1 line" or "2 lines".

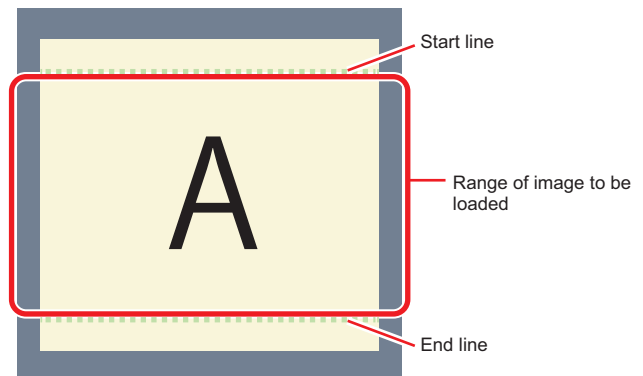
Item	Setting value [Factory default]	Description
Binning setting	[1 line]	Data is transferred line by line.
	2 lines	Data is transferred two lines at a time. Processing becomes faster since each image is scanned skipping one scan line per two consecutive lines, but the measurement precision is decreased because the vertical image resolution is lower.

Number of lines to be read

By narrowing the image range to be loaded, the image scan time can be shortened.

Set the range taking the offset of the measurement object into consideration.

The part of the image narrowed down by the start line and the end line will be displayed in the Image Display area of the processing item setting window or the Main screen.



Note

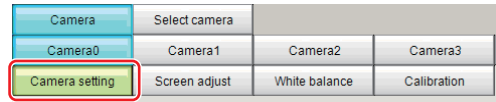
About minimum number of lines

- With the FH-SM, the minimum number of lines (minimum value between the start and end lines) is 4 line.
- With the FH-SC, the minimum number of lines is 4 lines.
- With the FX-Sxxx excluding the FZ-SQ series, the minimum number of lines is 12 lines.
- With the FZ-SQ series, the minimum number of lines is 8 lines.

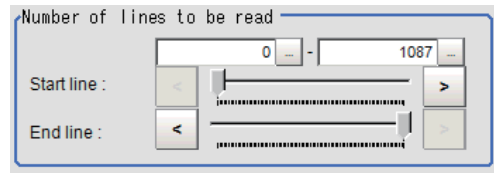
About coordinate values

- The coordinate values displayed as the measurement results are the values of the display position on the monitor.
- The coordinate values do not vary according to the settings for "Number of lines to be read".

1 In the Item Tab area, click [Camera setting].



2 Set the start/end line in the "Number of lines to be read" area.



Important

- When the built-in lighting of an FZ-SQxxxx is used, it may not be possible to shorten the processing time due to restrictions on the light emission time.

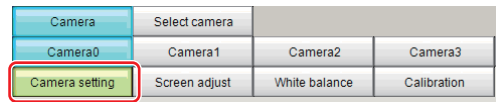
Electronic Flash Setting

This function is set when an electronic flash is used. This sets the output conditions for the signal for synchronizing the measurement and the electronic flash timing.

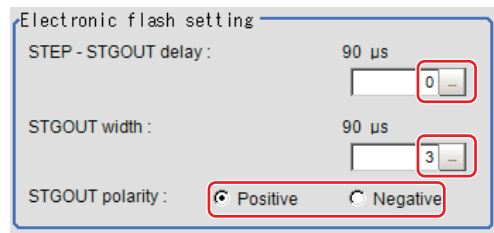
Important

- The setting here applies when "STGOUT" is selected for the output signal under [Common settings] on the [Output signal settings] page of the camera accessed by selecting [External Tools] - [System].
If "SHTOUT" is selected, the signal is controlled by each value of SHTOUT set for each line.

1 In the Item Tab area, click [Camera setting].



2 In the "Electronic flash setting" area, specify each item.



Item	Setting value [Factory default]	Description
STEP - STGOUT delay	[0] to 511 (1 count 30μs)	Set the waiting time from the time the STEP signal is input until the electronic flash trigger output signal comes ON. Delay Time = Count × 30μs + 90μs The displayed time is for the positive polarity. Add 35μs to the displayed time if the polarity is negative. The delay time can be set in a range of ±10μs from the setting value.
STGOUT width	1 to 63 [3] (1 count 30μs)	Set the output time for the electronic flash trigger signal.
STGOUT polarity	<ul style="list-style-type: none"> • [Positive] • Negative 	Select the pulse polarity of the electronic flash trigger. Positive polarity: Flashes synchronized with the timing of the electronic flash trigger output signal changing from OFF to ON. Negative: Flashes when the strobe trigger output signal changes from ON to OFF.

Screen Adjustment Settings (Camera Image Input FH)

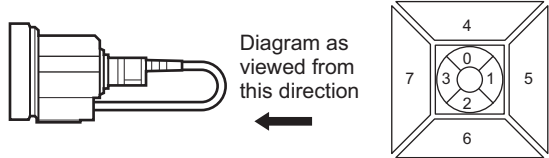
Set the lighting and lens conditions for each camera.

- Reference: ▶ Lighting Control (p.43)
- Reference: ▶ Line Bright (p.47)
- Reference: ▶ Lens Adjustment Setting (p.48)
- Reference: ▶ Common Setting for All Cameras (p.49)

Lighting Control

When a camera with a lighting function is connected, the light volume of the lighting can be adjusted from the sensor controller. Brightness can be adjusted automatically or one of the preset patterns can be selected.

A lighting lamp image is displayed as a guide illustration.



Light volume is adjustable at up to 8 locations.

Note

- When 1 scene contains 2 or more camera image input units, lens setting can be performed only for the first camera image input unit.

1 In the Item Tab area, click [Screen adjust].



2 In the "Lighting control" area, specify the brightness.

The image display contents depend on the connected camera.

When an intelligent camera is connected

Important

- When model FZ-SLC15 is connected, only parts 0 to 3 are active. Changing parts 4 to 7 will not affect the light volume of lighting.

Lighting diagram

Parts list

CH	Part	Adjust...
0	0	128
0	1	128
0	2	128
0	3	128
0	4	128
0	5	128
0	6	128

CH 0

On all the time

Modulate mode: PWM

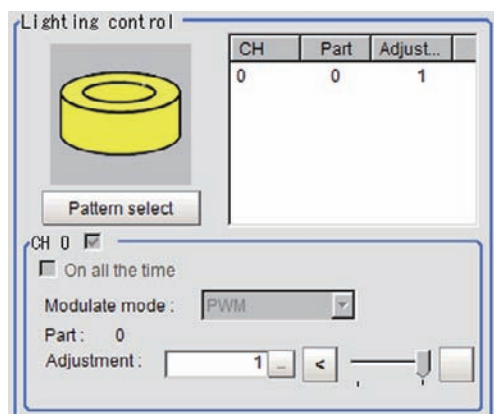
Part: 0

Adjustment: 128 < >

Item	Setting value	Description
Pattern select	Pattern 0 to 16	Select from a preset lighting pattern.

Item	Setting value	Description
Adjustment	0 to 255 × 8ch [128]	The light volume at each part can be adjusted to one of 256 levels. 0 indicates the lighting is OFF. The larger the number, the higher the brightness.

Intelligent compact camera FZ-SQxxxx is connected:

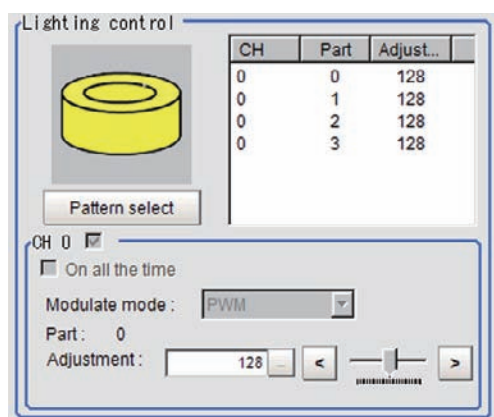


Item	Setting value [Factory default]	Description
Pattern select	Pattern 0 to 1	Select from a preset lighting pattern. Pattern 0: Lit Pattern 1: Unlit
Adjustment	0: Unlit 1: Lit	Adjust the light volume of each part.

Important

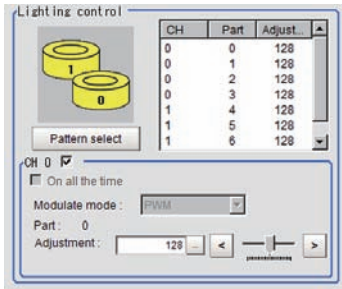
- When built-in lighting is used, the measurement processing time may be longer in comparison with when lighting is OFF.

Electronic flash controller FZ-LTA100 is connected:

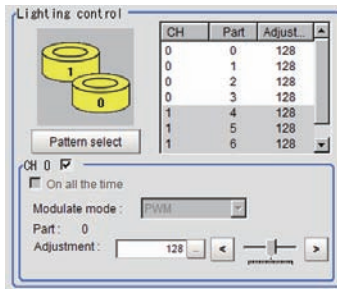


Electronic flash controller FZ-LTA200 is connected:

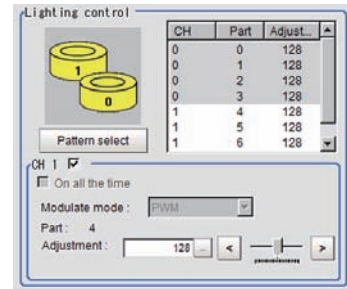
0 + 1CH are used:



0CH is used:

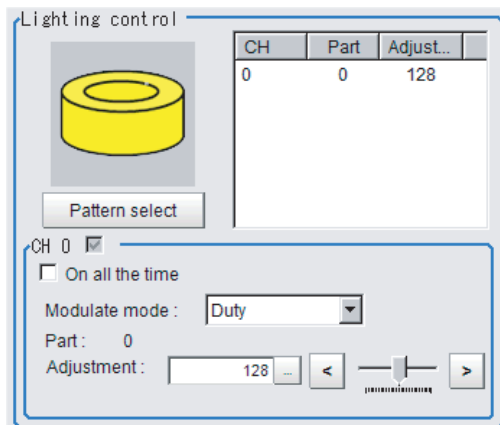


1CH is used:



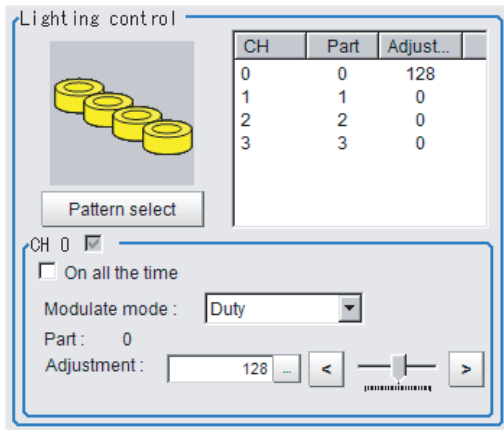
Item	Setting value	Description
Pattern select	Pattern 0 to 16	Select from a preset lighting pattern.
CH	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Place a check here to enable the channel currently selected in the part list.
Adjustment	0 to 255 [128]	When 1 channels are used, the light volume can be adjusted to one of 256 levels. When 2 channels are used, the light volume can be adjusted to one of 128 levels. 0 indicates the lighting is OFF. The larger the number, the higher the brightness.

Camera with lighting controller FLV-TCC1 is connected:



Item	Set value	Description
Pattern select	---	Select from preset lighting patterns.
On all the time	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check here to keep the light turned ON all of the time regardless of the exposure time.
Modulate mode	<ul style="list-style-type: none"> • [Duty] • Voltage 	Select the lighting adjustment method. <ul style="list-style-type: none"> • Duty The brightness of the light is adjusted with 255 levels of the pulse width (PWM frequency: 100 Hz). • Voltage The brightness of the light is adjusted with 255 voltage levels. Select voltage lighting adjustment if you will use a high-speed shutter speed.
Part	0 to 255 [128]	Set the brightness for the selected parts.

Camera with lighting controller FLV-TCC4 is connected:



Item	Set value	Description
Pattern select	---	Select from preset lighting patterns.
On all the time	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check here to keep the light turned ON all of the time regardless of the exposure time.
Modulate mode	<ul style="list-style-type: none"> • [Duty] • Voltage 	Select the lighting adjustment method. <ul style="list-style-type: none"> • Duty The brightness of the light is adjusted with 255 levels of the pulse width (PWM frequency: 100 Hz). • Voltage The brightness of the light is adjusted with 255 voltage levels. Select voltage lighting adjustment if you will use a high-speed shutter speed.
Part	0 to 255 [128]	Set the brightness for the selected parts.

Important

- If you use the camera with lighting controller FLV-TCC□ for the lighting, the power consumption and lighting modes are restricted as follows:

Without external power supply

Total power consumption	Power consumption per channel	Connectability	Lighting mode ^{*1}			READY OFF time delay ^{*2}
			Always-on lighting mode	Simultaneous lighting mode	Single lighting mode	
Greater than 7.5 W	Greater than 7.5 W	Not connectable	---	---	---	---
	7.5 W or less	Connectable	NA	NA	OK	None
7.5 W or less	Less than 7.5 W	Connectable	OK	OK	OK	None

With external power supply

Total power consumption	Power consumption per channel	Connectability	Lighting mode ^{*1}			READY OFF time delay ^{*2}
			Always-on lighting mode	Simultaneous lighting mode	Single lighting mode	
Greater than 15 W	Greater than 15 W	Not connectable	---	---	---	---
	15 W or less	Connectable	NA	NA	OK	Yes
	7.5 W or less	Connectable	NA	NA	OK	None
15 W or less	Less than 15 W	Connectable	NA	OK	OK	Yes
	7.5 W or less	Connectable	NA	OK	OK	Yes
7.5 W or less	Less than 7.5 W	Connectable	OK	OK	OK	None

*1: Lighting modes

Always-on lighting mode	In this mode, the lights are always turned ON for a specific pulse cycle. The always-on lighting mode is used if you place a check in "On all the time" in the "Lighting control" area.
Simultaneous lighting mode	In this mode, all of the connected lights are turned ON in synchronization with the trigger. Set the "Adjustment" set values in the "Lighting control" area for each light to any value other than 0 for all of the parts.
Single lighting mode	In this mode, only one of the connected lights is turned ON in synchronization with the trigger. Set the "Adjustment" set value in the "Lighting control" area to any value other than 0 for the part for only one channel. The lights will not turn ON if you set two or more channels to an adjustment other than 0.

*2: Turning OFF the READY signal is delayed in comparison with not connecting a camera with lighting controller by approximately the exposure time.

Example: Connection example for connecting an external power supply and the lighting modes

- If four lights with a power consumption of 1 W each are connected to a camera with lighting controller, always-on lighting, simultaneous lighting, and single lighting are all possible.
- If four lights with power consumptions of 2 W, 3 W, 4 W, and 5 W are connected to a camera with lighting controller, simultaneous lighting and single lighting are possible.
- If four lights with power consumptions of 12 W, 1 W, 2 W, and 1 W are connected to a camera with lighting controller, only single lighting is possible.

Other cameras are used:

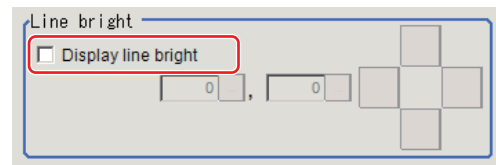
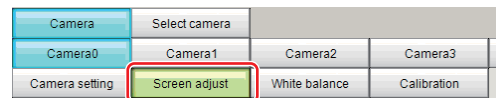
The light volume cannot be adjusted.

Line Bright

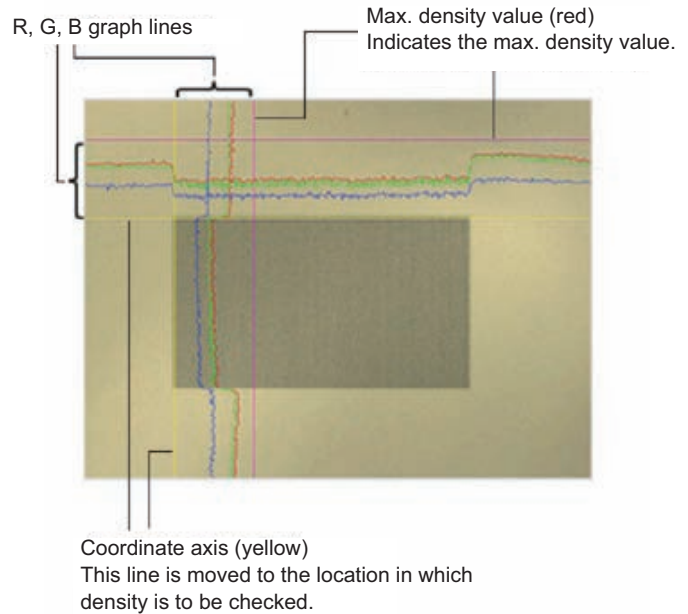
The graph showing the gray distribution for 1 line in the image is called the "Line bright". You can display the line brights for R, G and B for any horizontal or vertical line.

1 In the Item Tab area, click [Screen adjust].

2 Place a check at "Display line bright".



- 3 Move the line to the position whose density distribution you want to see.

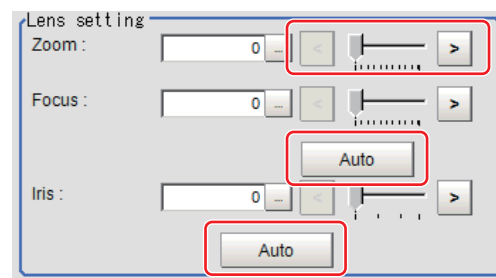
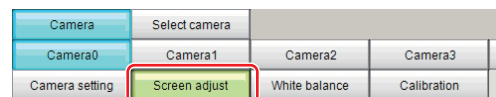


Lens Adjustment Setting

This function is only displayed when an intelligent camera or an auto-focus camera is connected. Make lens adjustments such as the focus and zoom. The optimum value can be set automatically for the focus and iris.

- 1 In the Item Tab area, click [Screen adjust].
- 2 Specify the "Zoom" size while checking the image.
- 3 Click [Auto] at "Focus" and "Iris".

The focus and iris optimized for the zoomed image are set automatically.



Item	Setting value [Factory default]	Description
Zoom	[0] to 1023	Displays the image zoomed in and out. Depending on the focus setting value, it may not be possible to set a large zoom value.
Focus	[0] to 1023	Adjust the focus. When [Auto] is clicked, the optimum focus for the current image is set automatically.
Iris	[0] to 31	Adjust the light volume that passes through the lens. When [Auto] is clicked, the optimum iris for the current image is set automatically.

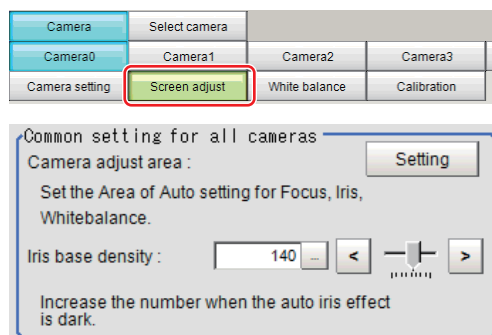
Important

- Auto focus and auto iris can only be used when setting with this screen open. They cannot be used during running.

Common Setting for All Cameras

This function is only displayed when an intelligent camera, an auto-focus camera or a color camera is connected. This sets the conditions for automatically setting the focus, iris, and white balance.

- 1 In the Item Tab area, click [Screen adjust].
- 2 In the "Common setting for all cameras" area, set up "Camera adjust area" and "Iris base density".



Item	Description
Camera adjust area	This sets the region for judging whether or not the state is appropriate when automatically setting the focus, iris, and white balance.
Iris base density	Increase the number when the auto iris effect is dark.

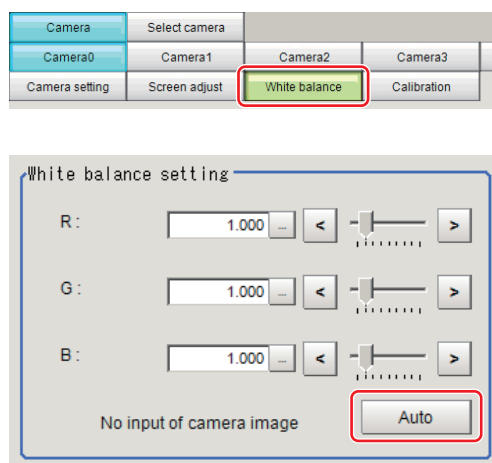
White Balance (Camera Image Input FH)

Set the white balance to make white objects look white by calibrating the color of images loaded from cameras. By adjusting the white balance, the appropriate white color can be reproduced under any lighting conditions. Appropriate values can also be set automatically.

Note

- Perform the white balance setting only when a color camera is used.
 - In the following cases, make sure to set white balance.
 - When a new system is installed
 - When a camera or lighting has been changed
- Since measurement results may vary with changes of the white balance setting, be sure to verify the operation after it has changed.

- 1 In the Item Tab area, click [White balance].
- 2 Shoot a white piece of paper or cloth.
- 3 Click [Auto].



Note

- When the "Too bright" or "Too dark" message is displayed, adjust the iris, shutter speed, gain and/or lighting conditions until "Automatic adjustment is possible" is displayed.

4 Set the "R", "G" and "B" values as necessary.

Item	Setting value [Factory default]	Description
White balance setting • R • G • B	0.001 to 7.999 (R, G, and B) (For intelligent compact cameras 0.001 to 3.000) For FZ-SC [R=1.183] [G=1.000] [B=1.323] For FZ-SC2M [R=1.394] [G=1.000] [B=1.222] For FZ-SFC, FZ-SPC [R=1.145] [G=1.000] [B=1.1889] For FZ-SC5M2 [R=1.351] [G=1.000] [B=2.314] For intelligent compact cameras [R=1.000] [G=1.040] [B=1.800] For FH-SC [R=1.000] [G=1.000] [B=1.000]	Set the white balance. Whiteness increases when the value of "R", "G", and "B" is increased.

Calibration (Camera Image Input FH)

By setting the calibration, the measurement result can be converted and output as actual dimensions. The calibration method is selected here.

There are three calibration methods, point, sampling, and parameter.

- Reference: ▶ **Specifying Points and Setting (Point Specification) (p.51)**
- Reference: ▶ **Setting Calibration through Sampling Measurement (Sampling) (p.52)**
- Reference: ▶ **Inputting and Setting Values (Value Setting) (p.53)**
- Reference: ▶ **View Calibration Parameters (p.54)**

Note

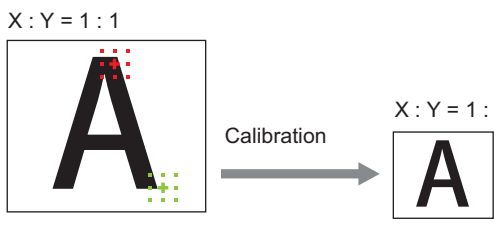
- In order to output measurement values in actual dimensions, select [Calibration] to "ON" in [Output parameter] for each processing unit. If [Calibration] is "OFF" (factory default), measurement results are output as camera image coordinate values.

Specifying Points and Setting (Point Specification)

This is a method for performing calibration by selecting arbitrary points (in pixels). Calibration parameters are calculated automatically when actual coordinates of selected locations are entered. Up to 3 points can be selected.

- **When magnification is the same in the X and Y directions**

Select only 2 points.



- **When magnification is not the same in the X and Y directions**

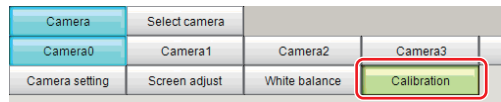
Select 3 points.



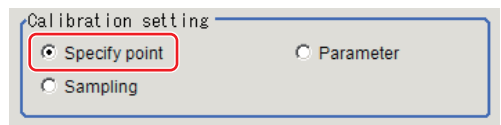
Note

- When 2 points are selected, the coordinate system is set to the left-hand system (forward in the clockwise direction). Select 3 points to perform calibration including the coordinate system.

1 In the Item Tab area, click [Calibration].



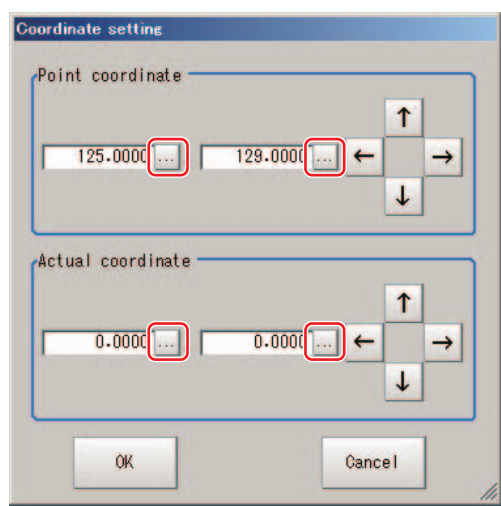
2 In the "Calibration setting" area, select "Specify point".



3 Click the first point on the screen.

4 Set the actual coordinates for the specified point.

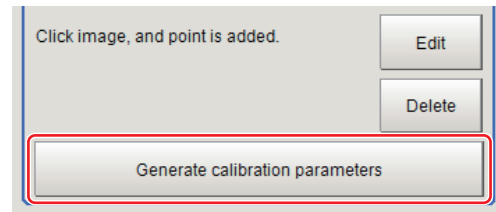
The actual coordinate input window is displayed.



Actual coordinate	Setting value [Factory default]
Point coordinate X, Y	0 to 9999.9999 [Point you clicked in the window]
Actual coordinate X, Y	-99999.9999 to 99999.9999 [0]

5 Set the 2nd and 3rd points in the same way.

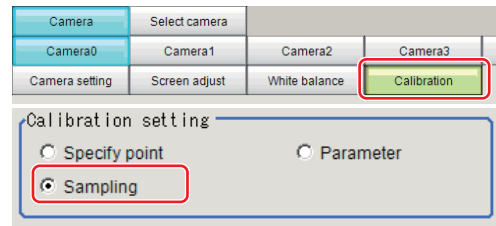
- Click **[Generate calibration parameters]**.
The calibration parameters will be generated.



Setting Calibration through Sampling Measurement (Sampling)

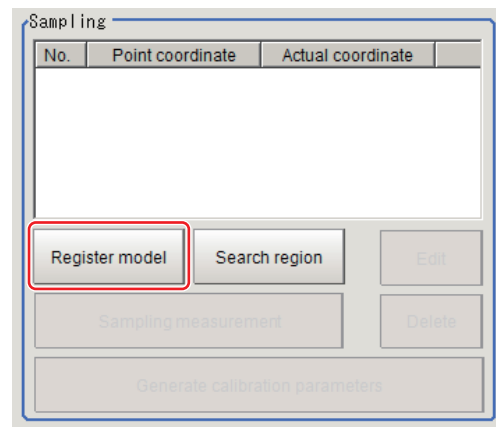
This is a method for setting calibration based on measurement results. Calibration parameters are calculated automatically when a registered model is searched and the actual coordinates for that position set.

- In the **Item Tab** area, click **[Calibration]**.



- In the "Calibration setting" area, select **"Sampling"**.

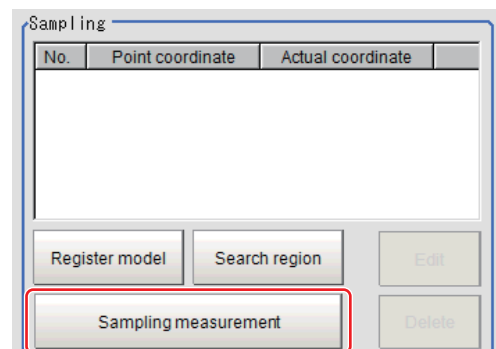
- In the "Sampling" area, click **[Register model]**.



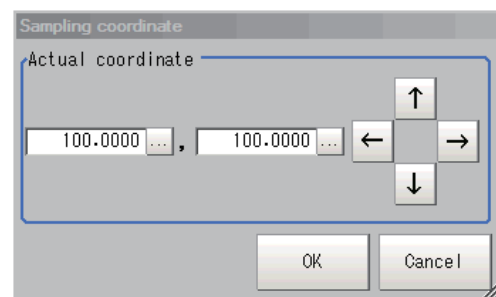
- Use the **Drawing tools** to register the model.

- Set a **search region** as necessary.
The default value setting is for the entire screen.

- Click **[Sampling measurement]**.
Measurement is performed.
The search result (cross-shaped cursor) is displayed in the Image Display area, and the Sampling Coordinate window is displayed.

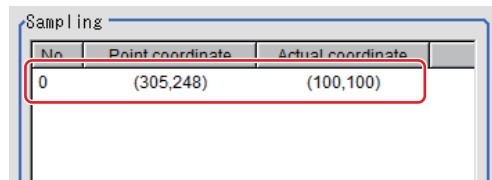


- In the **Sampling Coordinate** window, set the **X and Y** values.

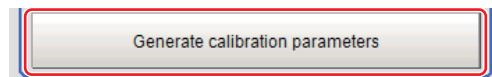


8 Click [OK].

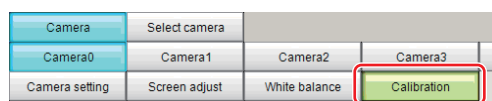
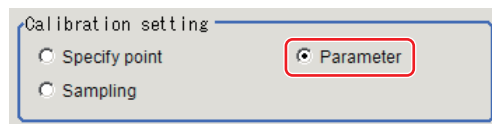
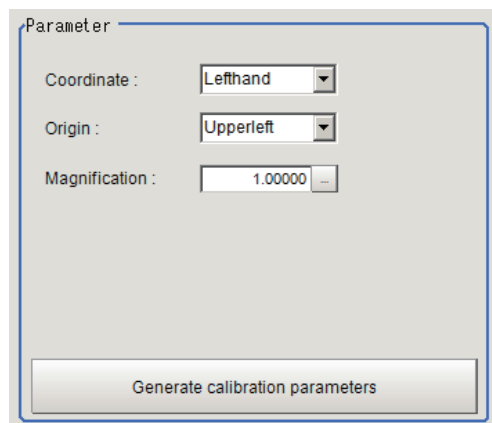
Point coordinates and actual coordinates are registered in the "Sampling" area.

**9 Move the object to be measured and repeat the Steps 3 to 8.****10 Click [Generate calibration parameters].**

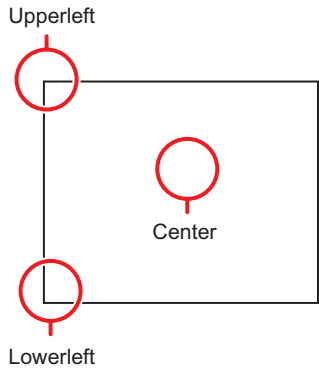
The calibration parameters will be generated.

**Inputting and Setting Values (Value Setting)**

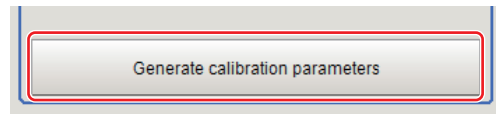
Set calibration data directly with numerical values.

1 In the Item Tab area, click [Calibration].**2 In the "Calibration setting" area, select "Parameter".****3 In the "Parameter" area, specify values for the "Coordinate", "Origin" and "Magnification".**

Item	Setting value [Factory default]	Description
Coordinate	<ul style="list-style-type: none"> [Lefthand] [Righthand] 	<p>Lefthand: Clockwise is forward when setting the coordinates. Righthand: Counter-clockwise is forward when setting the coordinates.</p>

Item	Setting value [Factory default]	Description
Origin	<ul style="list-style-type: none"> • [Upperleft] • Lowerleft • Center 	Set where the origin of the actual coordinates will be. 
Magnification	0.00001 to 9.99999	Specify the ratio of 1 pixel to the actual dimensions.

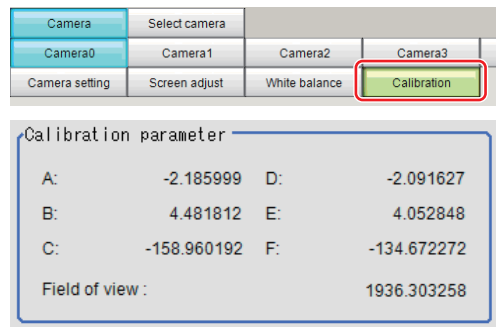
- 4** Click [Generate calibration parameters].
The calibration parameters will be generated.



View Calibration Parameters

View the set calibration data.

- 1** In the Item Tab area, click [Calibration].
- 2** In the "Calibration parameter" area, confirm the calibration data.



Item	Setting value	Description
A	Calculation value	These are calibration conversion values. Camera coordinates are converted to actual coordinates based on these values. The conversion formulas for actual coordinates are as follows: <ul style="list-style-type: none"> • (X, Y): Measurement point (camera coordinates), Unit: pix • (X', Y'): Conversion point (actual coordinates) $X' = A \times X + B \times Y + C$ $Y' = D \times X + E \times Y + F$
B	Calculation value	
C	Calculation value	
D	Calculation value	
E	Calculation value	
F	Calculation value	
Field of view	Calculation value	This is an actual dimension in the X direction.

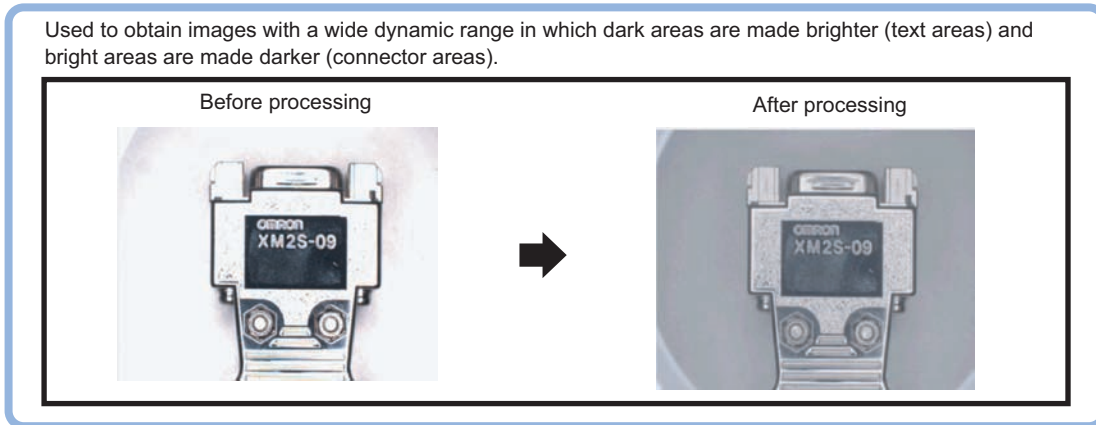
Camera Image Input HDR

You can acquire a wide dynamic range image by combining images photographed consecutively at different shutter speeds.

With objects that generate halation, images with low-contrast, and environments with fluctuation in the lighting, this processing item is an effective substitute for camera image input.

Used in the Following Case

- **To acquire stable images of objects for which halation occurs easily**



- **To measure images with low-contrast stably**

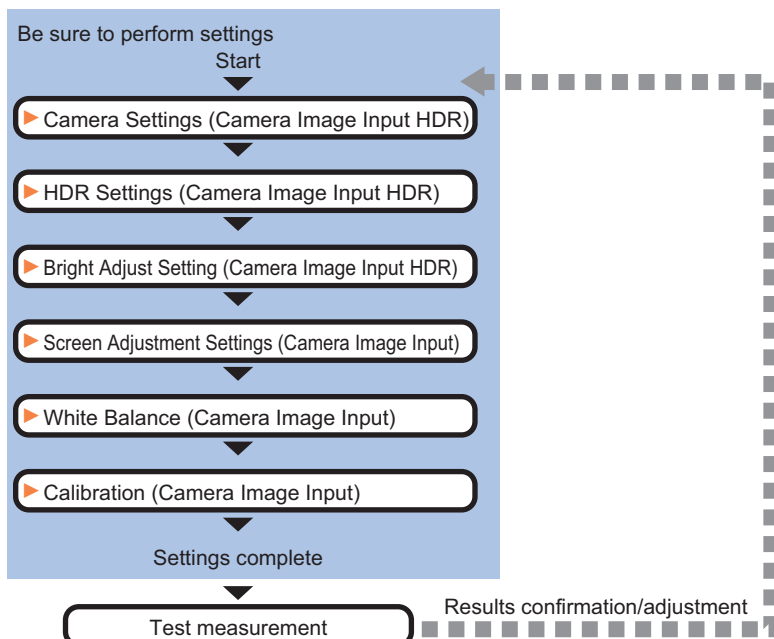
Use high-contrast mode.

Important

- [Camera Image Input] is preset for Unit 0. Do not set any processing item other than camera image input (camera image input HDR, camera image input HDR Lite, camera image input FH) for Unit 0.
- When using an intelligent camera FZ-SLCx or an auto-focus camera FZ-SZCx, camera image input and camera image input HDR cannot be used together.

Settings Flow (Camera Image Input HDR)

To set camera image input HDR, follow the steps below.



Camera Image Input HDR Item List

Item name	Description
Camera setting	Specify the camera settings such as the electronic flash. The setting method is the same as for [Camera Image Input]. Please check it. Reference: ▶ Camera Settings (Camera Image Input HDR) (p.56)
HDR setting	Carry out the image combination and photography settings. Reference: ▶ HDR Settings (Camera Image Input HDR) (p.57)
Bright adjust	Specify the brightness follow-up adjustment setting. Reference: ▶ Bright Adjust Setting (Camera Image Input HDR) (p.59)
Screen adjust	Adjust the lighting and the lens. The setting method is the same as for [Camera Image Input]. Please check it. However, the iris cannot be adjusted. Reference: ▶ Screen Adjustment Settings (Camera Image Input) (p.24)
White balance	When using a color camera, adjust the white balance. The setting method is the same as for [Camera Image Input]. Please check it. Reference: ▶ White Balance (Camera Image Input) (p.30)
Calibration	Set when measurements (camera coordinate measurement values) are to be output using actual dimensions. Select the calibration setting method and generate the calibration parameters. The setting method is the same as for [Camera Image Input]. Please check it. Reference: ▶ Calibration (Camera Image Input) (p.31)

Camera Settings (Camera Image Input HDR)

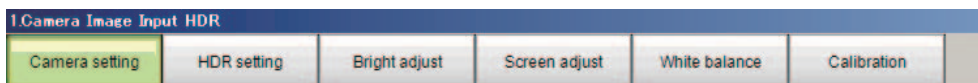
Set the following photographing conditions.

- Reference: ▶ Selection Setting (p.56)
- Reference: ▶ Camera Settings (p.57)
- Reference: ▶ Number of lines to be read (p.23)

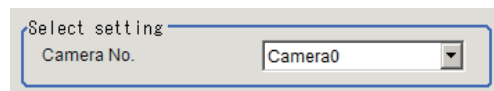
Selection Setting

When multiple cameras are connected, select the camera to use for measurement.

1 In the Item Tab area, click [Camera setting].



2 Click [Camera No.] [▼] and select the camera number.

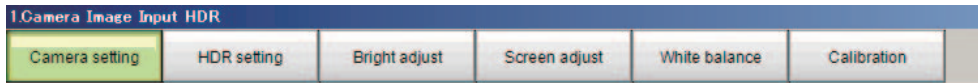


Setting item	Setting value [Factory default]	Description
Camera No.	Cam 0 to 7 [Cam 0]	Select the camera number.

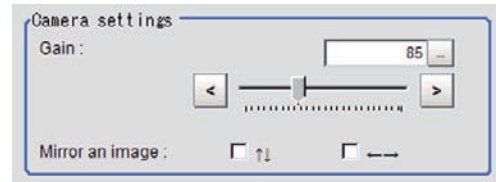
Camera Settings

Specify the camera gain and reverse conversion.

- 1 In the Item Tab area, click [Camera setting].



- 2 In the "Camera settings" area, specify the camera gain and reverse conversion settings.



Setting item	Setting value [Factory default]	Description
Gain	For stand-alone cameras 0 to 230 • [50] (For FZ-SFx, FX-SPx, FZ-SC2M/FZ-S2M, FZ-SC5M2/FZ-S5M2) • [85] (for FZ-SC/FZ-S, FZ-SLC, FZ-SZC)	Set the camera gain when the shutter speed, the lens aperture, and lighting conditions cannot be used to brighten the image. Usually, the factory default value can be used.
Mirror an image	↑↓ • Checked • [Unchecked]	Place a check here when reversing the camera image vertically.
	←→ • Checked • [Unchecked]	Place a check here when reversing the camera image horizontally.

HDR Settings (Camera Image Input HDR)

Specify the image combination method etc.

- 1 In the Item Tab area, click [HDR setting].
- 2 In the "Mode select" area, specify the mode.

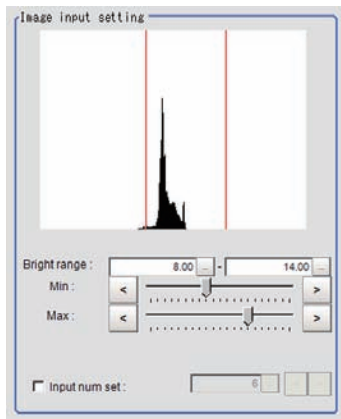
When you select the mode in the "Mode select" area and specify the measurement region on the image, the parameters are set automatically. To finely adjust the parameters, refer to the next items.

Item	Set value [Factory default]	Description
Mode select	[HDR mode]	Generate images with stable brightness by shooting multiple images with different shutter times based on the specified brightness range.
	High contrast mode	This is used to improve the contrast within an image. Specify the average brightness and brightness range, fix the shutter time, shoot multiple images, and generate images with good contrast.

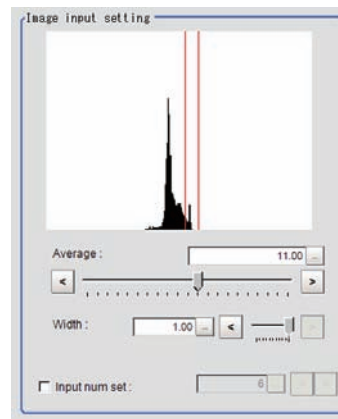
3 In the "Image input setting" area, set the items.

A brightness histogram is displayed as the graph.

HDR



High contrast mode



Item	Set value [Factory default]	Description
Min Bright range	0 to 20 [8]	This item sets the minimum brightness for combining images.
Max Bright range	0 to 20 [14]	This item sets the maximum brightness for combining images.
Input num set	<ul style="list-style-type: none"> • [Unchecked] • Checked 2 to 16 [6]	Place a check to set the number of shots manually. Setting a high shot count provides images with low noise. However, more processing time is required. Setting a low shot count shortens the processing time. However, the image is more easily affected by noise.
Average	0.00 to 20.00 [11.00]	Specify the average brightness for images shot.
Width	0.01 to 1.00 [1.00]	Specify the brightness range for images shot.
Input num set	<ul style="list-style-type: none"> • [Unchecked] • Checked 2 to 16 [6]	Place a check to set the number of shots manually. Setting a high shot count provides images with low noise. However, more processing time is required. Setting a low shot count shortens the processing time. However, the image is more easily affected by noise.

4 In the "Output setting" area, set the combination method.

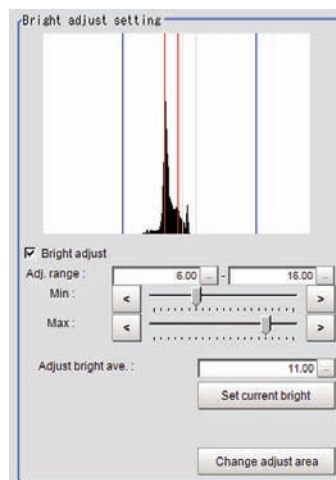
Item	Set value [Factory default]	Description
Combine type	[Normal]	Select the combination method.
	Color	Normal: Standard combination method This compensates the brightness so that dark sections on the combination image do not become all black.
	Linear	Color: This is suitable for inspecting labeling and the Gravity and Area. This compensates the saturation when there is little hue information in the combined image. Linear: This is suitable for fine matching and defect inspection. In order to output the actual brightness of the workpiece, no compensation is performed.

The current shot count and image combination time for the settings are displayed.

Bright Adjust Setting (Camera Image Input HDR)

This sets how far to track the brightness of the loaded images.

- 1 In the Item Tab area, click [Bright adjust].
- 2 Set each item in the "Bright adjust setting" area.



Item	Set value [Factory default]	Description
Bright adjust	<ul style="list-style-type: none"> • [Unchecked] • Checked 	If a check is placed at "Bright adjust", the image is output with its brightness automatically compensated. This makes it possible to obtain images with stable brightness even if the lighting conditions fluctuate, for example due to interfering light.
Min Adj. range	0.00 to 20.00 [6.00]	Specify the follow-up brightness minimum value.
Max Adj. range	0.00 to 20.00 [16.00]	Specify the follow-up brightness maximum value.
Adjust bright ave.	0.00 to 20.00 [11.00]	Specify the target for brightness follow-up. Clicking the [Set current bright] button updates this value.

When a check is placed at the "Bright adjust", the Brightness Adjustment range is displayed with blue lines in the "Histogram" area.

Change the "Adjust bright ave." and brightness adjust area.

Camera Image Input HDR Lite

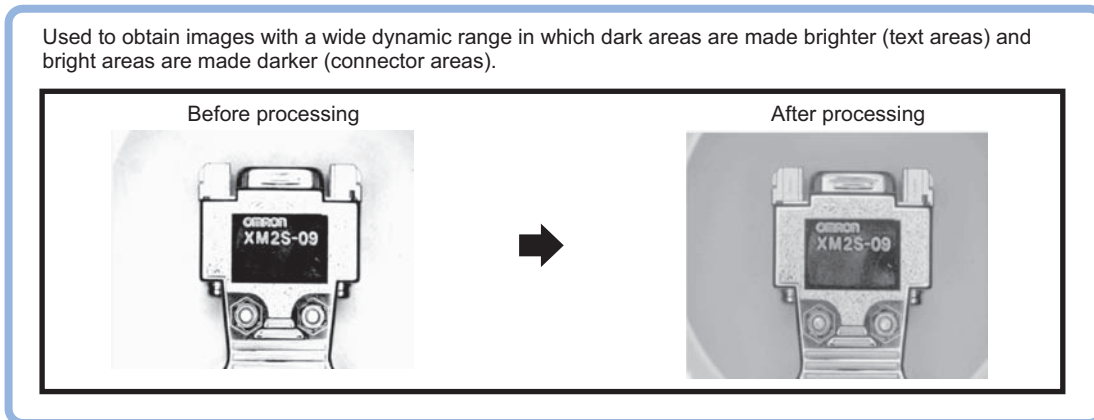
This is a processing item specific to the intelligent compact camera.

You can acquire a wide dynamic range image by combining images photographed consecutively at different shutter speeds.

With objects that generate halation, images with low-contrast, and environments with fluctuation in the lighting, this processing item is an effective substitute for camera image input.

Used in the Following Case

- To acquire stable images of objects for which halation occurs easily

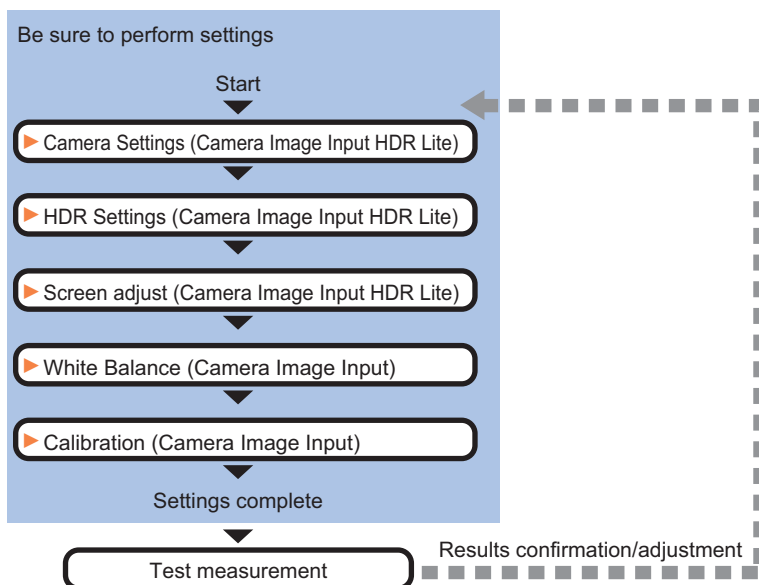


Important

- [Camera Image Input] is preset for Unit 0. Do not set any processing item other than camera image input (camera image input HDR, camera image input HDR Lite and camera image input FH) for Unit 0.

Settings Flow (Camera Image Input HDR Lite)

To set Camera Image Input HDR Lite, follow the steps below.



Camera Image Input HDR Lite Item List

Item name	Description
Camera settings	Specify the camera settings such as the electronic flash. Reference: ▶ Camera Settings (Camera Image Input HDR Lite) (p.61)
HDR setting	Specify the dynamic range and brightness setting. Specify the HDR automatic setting as necessary. Reference: ▶ HDR settings (Camera Image Input HDR Lite) (p.62)
Screen adjust	Adjust the image with or without the light adjustment or using display line bright. Reference: ▶ Screen adjust (Camera Image Input HDR Lite) (p.63)
White balance	When using a color camera, adjust the white balance. The setting method is the same as for [Camera Image Input]. Please check it. Reference: ▶ White Balance (Camera Image Input) (p.30)
Calibration	Set when measurements (camera coordinate measurement values) are to be output using actual dimensions. Select the calibration setting method and generate the calibration parameters. The setting method is the same as for [Camera Image Input]. Please check it. Reference: ▶ Calibration (Camera Image Input) (p.31)

Camera Settings (Camera Image Input HDR Lite)

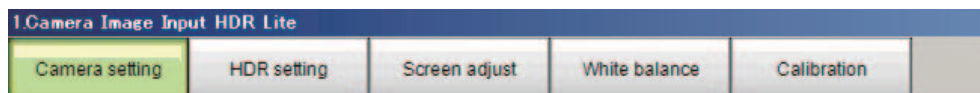
Set the following photographing conditions.

- Reference: ▶ Selection Setting (p.61)
- Reference: ▶ Number of lines to be read (p.23)
- Reference: ▶ Electronic Flash Setting (p.23)

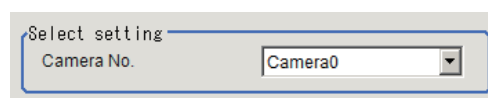
Selection Setting

When multiple cameras are connected, select the camera to use for measurement.

1 In the Item Tab area, click [Camera setting].



2 Click [Camera No.] [▼] and select the camera number.



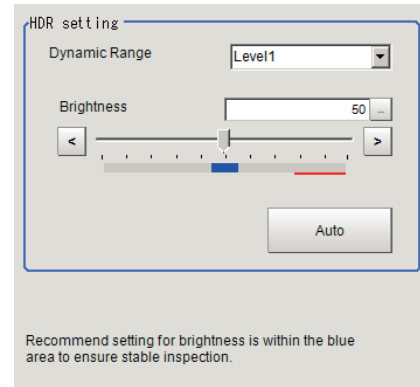
Setting item	Setting value [Factory default]	Description
Camera No.	Cam 0 to 7 [Cam 0]	Select the camera number.

HDR settings (Camera Image Input HDR Lite)

Specify the dynamic range and brightness settings.

- 1** In the Item Tab area, click [HDR Setting].
- 2** When automatic is clicked, the dynamic range and the brightness will be automatically set.

If automatic does not produce the desired result, manually adjust the dynamic range and brightness in the HDR settings.



Item	Set value [Factory default]	Description
Dynamic Range	[Level1] to Level4	Specify a dynamic range. The larger the value is, the broader the dynamic range to be combined will be.
Brightness	1 to 100	Specify the brightness settings. The larger the value is in this setting, the longer the exposure time will be. When using a high-speed line, check to make sure that there is no image blur in an actual environment. The degree of image blur can be lowered by decreasing the brightness even when the movement speed of the object is fast.

• Correlation between the level and the dynamic range

The larger the value of the level is, the larger the dynamic range to be combined will be, as illustrated below.



Important

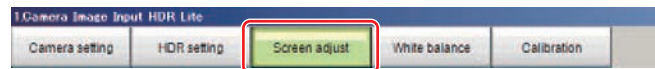
- For stable operations, we recommend setting the brightness within the range where the blue bar does not enter the red region. Measurement values may be different if the recommended range is exceeded. Be sure to thoroughly check the measurement result and set the brightness value.

Screen adjust (Camera Image Input HDR Lite)

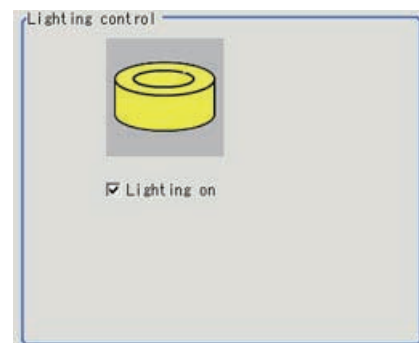
Specify the camera image input HDR Lite lighting and the line bright display settings. Specify whether or not to use the lighting. The setting method for line bright is the same as for [Camera Image Input]. Please check it.

- Reference: ▶ [Line Bright \(p.28\)](#)

1 In the Item Tab area, click [Screen adjust].



2 Set [Lighting control] as necessary.

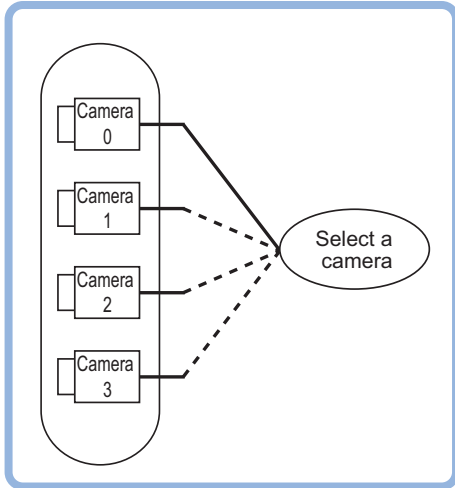


Item	Set value [Factory default]	Description
Lighting on	<ul style="list-style-type: none"> [Checked] Unchecked 	Clear the checkbox when no lighting is to be applied.

Camera Switching

Used in the Following Case

- When switching to images on cameras other than that has been set to [Camera Image Input] during scene processing



Important

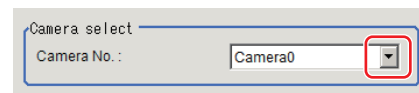
- When switching from a monochrome camera to color camera, reconfigure the settings in the following units.
- Camera switching cannot be used with camera image input HDR.

Camera Selection (Camera Switching)

1 Select the cameras used for measurement.

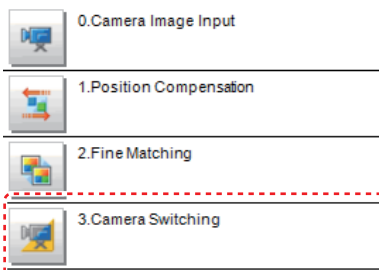
2 Click [OK].

The settings are finalized.



Additional Explanation (Camera Switching)

When creating a scene, [Position Compensation] will be disabled if [Camera Switching] is positioned after a [Position Compensation] unit, and this will restore the image of the measurement object to its former state before the position compensation was applied.



The Position Compensation for Unit 1 is being cancelled, making it restore to its former state before the Position Compensation was applied.

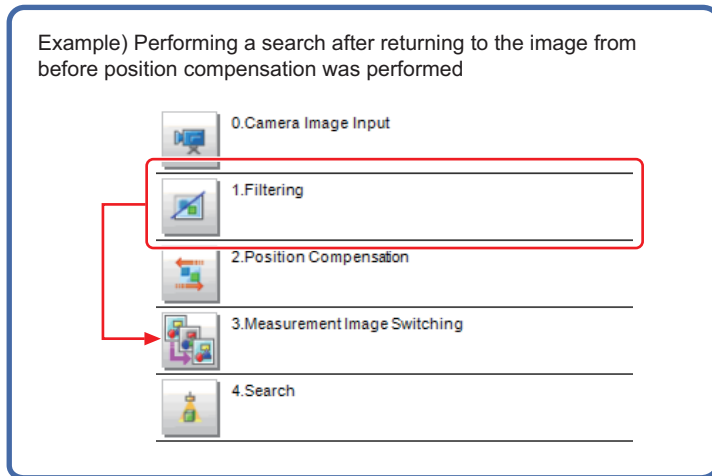
Measurement Image Switching

This sets the output image for the specified image conversion related processing items as the input image for the processing items set in the flow from this processing item onward.

This is primarily used to return converted images back to their originals and to increase the images that can be selected as conversion targets for image conversion related processing items by placing before the image conversion related processing items.

Used in the Following Case

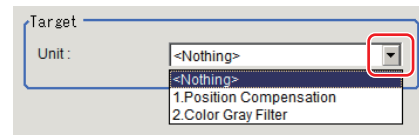
- To return a converted image to its original



Parameter Settings (Measurement Image Switching)

Specify the processing unit outputting the images to display.

- 1 Select the target unit in the "Target" area.



Note

- If <None> is left selected, the measurement image switching measurement result is NG. Be sure to select other than <None>.
- Only an image conversion related unit prior to this unit can be selected.

- 2 Click [OK].

The settings are finalized.

Key Points for Test Measurement and Adjustment (Measurement Image Switching)

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number	Explanation of image to be displayed
0	Reset image
1	Measurement image

External Reference Tables (Measurement Image Switching)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
120	Target unit	Set/Get	Unit that outputs images subject to reset 0 to 9999

Inspecting and Measuring

This chapter describes how to set up the processing items that execute measurement. In addition, key points for adjustment addressing unstable measurement results and

shortening measurement time will also be introduced.

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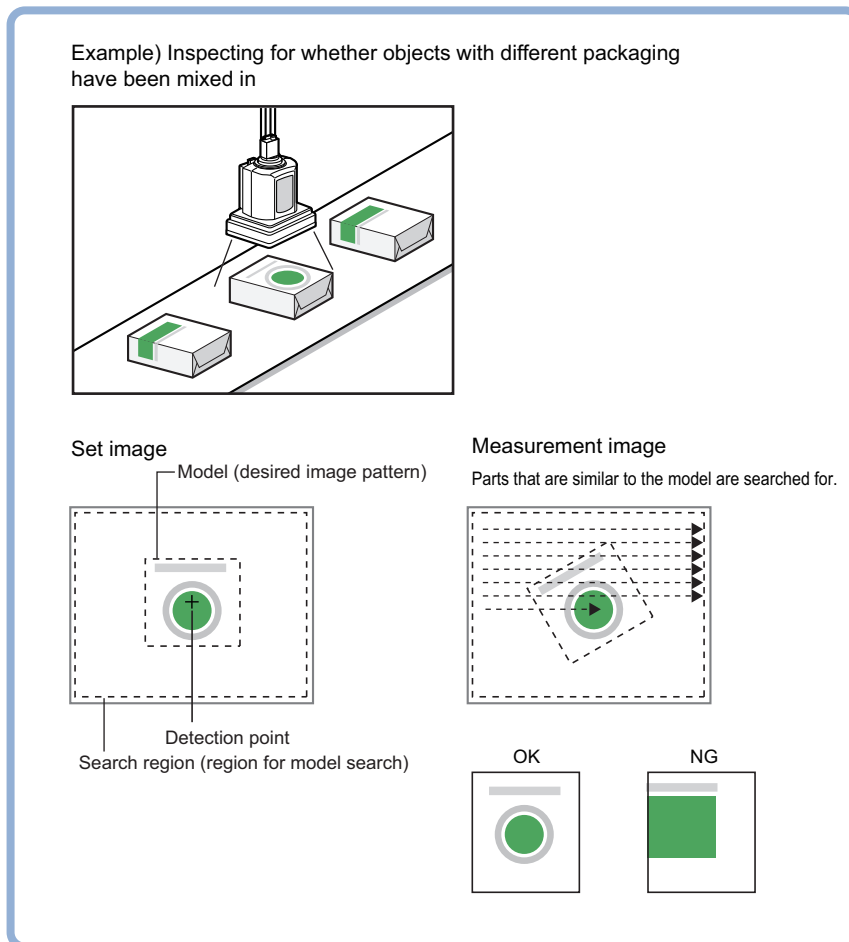
Search

Register the feature sections of the measurement object as an image pattern (model), then find the most similar part to these models from the input images to detect the position.

The correlation value showing the degree of similarity, measurement object position, and inclination can be output.

Used in the Following Case

- When identifying the shape of measurement objects (for detecting defects or foreign matter)



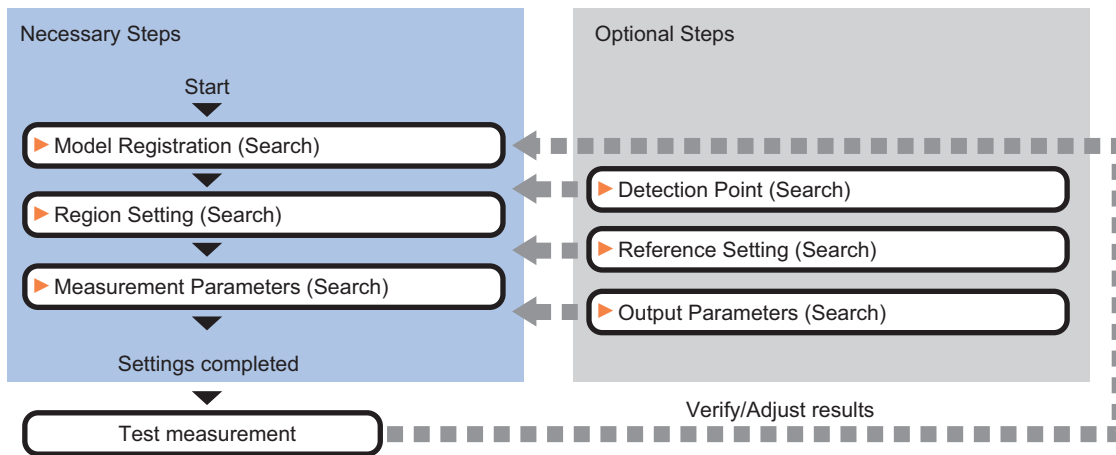
Note

- Search processing basic concepts

Reference: ▶ "Appendixes Measurement Mechanism Search Processing Mechanism" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Settings Flow (Search)

Set up searches according to the following flow.



List of Search Items

Item name	Description
Model register	This item registers the pattern characteristic of the measurement image as a model. Model parameter values can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used. Reference: ▶ Model Registration (Search) (p.70)
Region setting	This item is used to set up the measurement area. Instead of measuring the entire input image, narrowing the measurement area shortens the processing time. Reference: ▶ Region Setting (Search) (p.72)
Detection point	This item can be changed if necessary. Specify a position in the model that should be used as the detection coordinates during measurement. Usually, the central position of the set model is registered as the detection coordinates. Reference: ▶ Detection Point (Search) (p.73)
Ref. setting	This item can be changed if necessary. Specify the reference position within the camera's field of view. Reference: ▶ Reference Setting (Search) (p.74)
Measurement	This item specifies the judgement condition for measurement results. Specify the criteria to judge the measurement result if the X and Y coordinates and the correlation with the model are OK. Reference: ▶ Measurement Parameters (Search) (p.75)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Search) (p.77)

Model Registration (Search)

Register the parts to measure as the model.

The position at the time of registration is also registered in the model information. Place the measurement object in the correct position when registering a model.

1 In the Item Tab area, click [Model].

When setting a new model, you do not have to click [Model].

2 Use the drawing tools to specify the model registration range.

3 To save the entire image used for model registration, place a check at the "Save reg. model" option.



Note

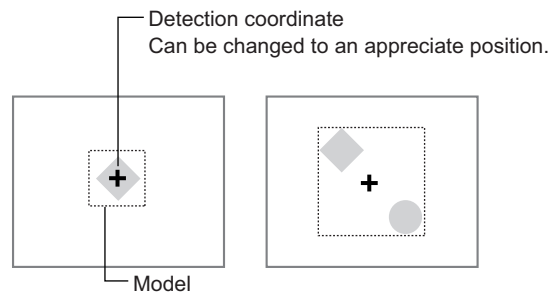
- If you save the registered model image, you can re-register the model with the same image after model parameters are adjusted. Note that the scene data size increases when a registered model image is saved.

4 Click [OK].

The model is registered.

Note

- When a model is registered, the central coordinates of the model are registered as the detection point. A detection point is a point output as a measurement value. If multiple figures are combined, the central coordinates of the circumscribed rectangle are registered.

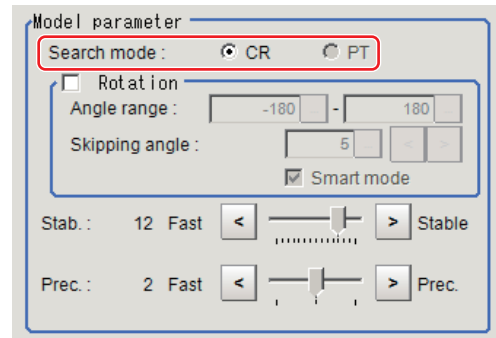


Changing Model Parameters

Model parameter values can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used.

After changing a setting, re-register the model.

- 1 In the "Model parameter" area, select the search mode, then specify a value for each item for that mode.



Setting item	Set value [Factory default]	Description
Search mode	[CR]	Search for normalizing the brightness. This method can provide stable measurement when there is fluctuation in the overall brightness and when the image has low contrast.
	PT	Measures the degree of matching with the profile. This method can measure at higher speed when the rotation angle has a wide range. It is available only when a 0.3 megapixel color camera is connected.

When CR is selected

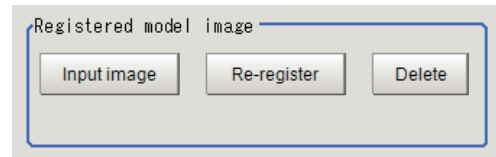
Setting item	Set value [Factory default]	Description
Rotation	<ul style="list-style-type: none"> • Checked • [Unchecked] 	When the measurement object is rotating, place a check at "Rotation" and specify how many degrees the model created rotates each time and through what range of angles. A smaller skipping angle increases stability, but slows down the processing. The forward direction is clockwise.
Angle range	[-180 to 180]	
Skipping angle	1 to 30 [5]	
Smart mode	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Checking the "Smart mode" option enables a high-speed rotation search. However, the stability may be lowered when the model shape aspect ratio is large or when the NOT mask is used.
Stab.	1 to 15 [The default value depend on the connected camera. 9 or 12]	Specify which is to have priority, measurement stability or speed. If lowering stability does not speed up processing, it is likely that many candidates have been detected. In this case, specify a larger value for "Candidate LV" or "Stab."
Prec.	1 to 3 [2]	Specify which is to have priority, measurement positional precision or speed.

When PT is selected

Setting item	Set value [Factory default]	Description
Angle range	[-180 to 180]	This item specifies the rotation angle range for searching. The normal direction is clockwise.
Stability	1 to 5 [3]	If lowering stability does not speed up processing, it is likely that many candidates have been detected. In this case, specify a larger value for "Candidate LV" or "Stab."

Displaying/Re-Registering/Deleting a Model

If you save the model registration image, it is easy to re-register the model after model parameters are changed.



Item	Description
Disp model/Input image	The model image display and input image display are switched.
Re-register	When model parameters are modified, display the original model image and re-register the model.
Delete	Deletes a model.

Region Setting (Search)

Use a rectangle to specify the area where the model is searched.

Instead of measuring the entire input image, narrowing the measurement area shortens the processing time.

- 1 In the Item Tab area, click [Region setting].**
- 2 Click [Edit].**
The figure setting area is displayed.
- 3 Specify the area in which to search for the model.**
The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.
- 4 Click [OK].**
The area to measure is registered.

Detection Point (Search)

Specify a position in the model that should be used as the detection coordinates during measurement. Usually, the central position of the set model is registered as the detection point. This function is used to change to any desired position.

A detection point can be set either directly or by referencing a unit.

Note

- After changing the detection point coordinates to another position, re-registering the model will change it back to the center coordinates of the model.

Specifying directly

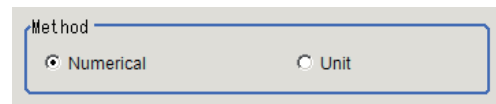
Click a position on the image you want to use as a detection point, or input coordinate data for that point.

1 In the Item Tab area, click [Detection point].

In the Display area, the current detection point is displayed with a crosshair cursor.



2 In the "Method" area, select "Numerical".

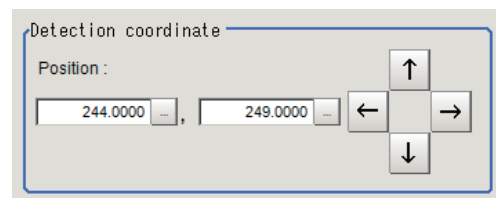


3 Click the position to be set as the detection point.

Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

4 Make fine adjustments using numeric value inputs or the arrow buttons as required.



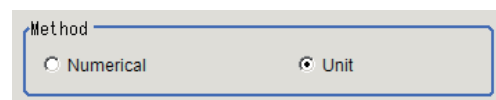
Referencing a unit

Set a detection point by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

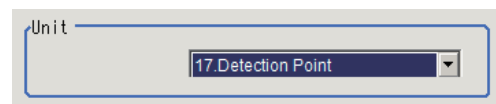
1 In the Item Tab area, click [Detection point].

In the Display area, the current detection point is displayed with a crosshair cursor.

2 In the "Method" area, select "Unit".



3 In the scene in the "Unit" area, select a detection point unit.



4 Perform the next measurement, and the detection point will be displayed.

Reference Setting (Search)

When the model is set, this position is automatically set at the same time as the reference position. This item can be set to change the reference position to any desired position. This is handy for measuring the position deviation from a certain position.

A reference position can be set either directly or by referencing a unit.

Specifying directly

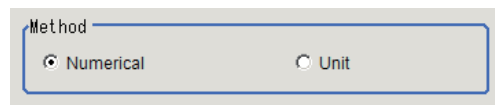
Click a position on the image you want to use as a reference position, or input coordinate data for that point.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.



2 In the "Method" area, select "Numerical".

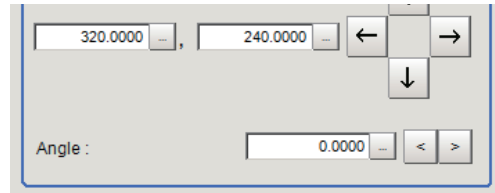


3 Click the position to be set as the reference.

Note

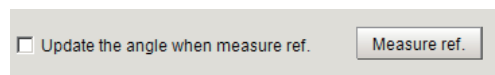
- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

4 Make fine adjustments using numeric value inputs or the arrow buttons as required.

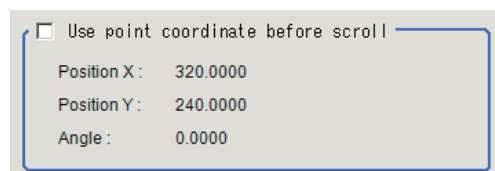


5 Set the reference angle with a numeric value.

6 To remeasure on the displayed image and set the reference, click the [Measure ref.] button. To update the reference angle at the time of reference measurement, place a check at "Update the angle when measure ref.".



7 To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".



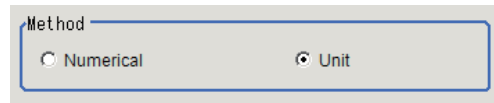
Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

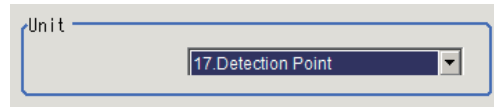
1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

2 In the "Method" area, select "Unit".



3 In the scene in the "Unit" area, select a detection point unit.



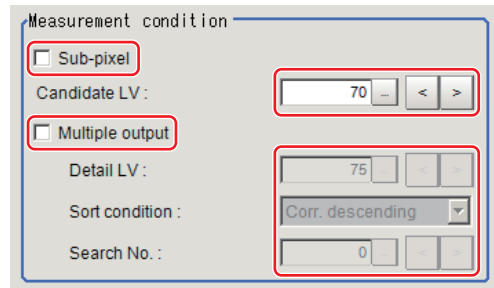
4 Perform the next measurement, and the reference will be displayed.

Measurement Parameters (Search)

Specify the search measurement conditions and the judgement conditions for the measurement results.

1 In the Item Tab area, click [Measurement].

2 In the "Measurement condition" area, specify a value for each item.



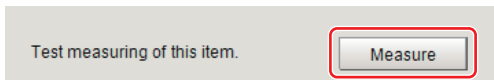
Setting item	Set value [Factory default]	Description
Sub-pixel	<ul style="list-style-type: none"> • Checked • [Unchecked] 	When a check is placed at sub-pixel, the position information can be measured in units of sub-pixels. However, this requires more processing time.
Candidate LV	0 to 100 [70]	Specify the threshold value with which to detect candidate points in a rough search. Specify a smaller value when model search results are unreliable.

When executing a multi search

Setting item	Set value [Factory default]	Description
Multiple output	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Select to execute a multi searches.
Detail LV	0 to 100 [75]	Specify the threshold value with which to detect candidate points in a detail search.

Setting item	Set value [Factory default]	Description
Sort condition	<ul style="list-style-type: none"> • Corr. ascending • [Corr. descending] • X coordinate ascending • X coordinate descending • Y coordinate ascending • Y coordinate descending 	Specify the conditions by which the search number is re-assigned. When sorting referencing the X and Y coordinates, the upper left is the origin.
Search No.	0 to 31 [0]	Specify which of the multiple detection results will be used as measured results.

3 When the setting has been changed, click [Measure] in the Detail area to verify whether measurements can be made correctly.



4 Set up the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Set value	Description
Count	0 to 32	Specify the number of detections that are judged to be OK.
Measure X	-99999.9999 to 99999.9999	Specify the range of X-axis shifting that is judged to be OK.
Measure Y	-99999.9999 to 99999.9999	Specify the range of Y-axis shifting that is judged to be OK.
Search angle	-180 to 180	Specify the range of angles that are judged to be OK.
Correlation	0 to 100	Specify the range of correlation values that are judged to be OK. However, when the correlation value of the measurement result is 0, the judgement result will be NG regardless of the lower limit setting.

Output Parameters (Search)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none">• [After scroll]• Before scroll	As measurement results, select whether to output coordinate values to external devices before or after the position deflection correction is applied.
Calibration	<ul style="list-style-type: none">• [OFF]• ON	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none">• [ON]• OFF	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (Search)

The following content is displayed in the "Detail result" area as text.

Important

- Executing test measurements will also update the measurement results and the figures in the image.

Displayed item	Description
Judge	Judgement result
Count	Count
Correlation value	Correlation value
Measure X	X coordinate of the position where the model is detected
Measure Y	Y coordinate of the position where the model is detected
Angle θ	Angle of the position where the model is detected

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Searching other positions

Parameter to be adjusted	Remedy
Model parameter	Specify a larger value for the "Prec."
	If the measurement results are unstable only when "Rotation" is selected, specify a smaller value for the "Skipping angle".
	When "Rotation" is selected, if the model shape is complex, uncheck the "Smart mode" option.
	If the image has low contrast or blurred edges, set the "Search mode" to "CR".
	If the model image consists of detailed figures, specify a larger value for "Stab."
Measurement parameter	If the precision is low, place a check at "Sub-pixel".
	If images that should be judged OK vary greatly, specify a smaller value for "Candidate LV".
	If the model image is small and unstable, specify a smaller value for the "Reduction".

The judgement is NG (insufficient memory)

Parameter to be adjusted	Remedy
Region setting	Make the search region as small as possible.
Model parameter	Bring "Stab." close to the factory default value.
	Bring the "Skipping angle" close to the factory default value.
	Specify a smaller value for "Prec."

When the processing speed is slow

Parameter to be adjusted	Remedy
Region setting	Make the search region as small as possible.
Model registration	Make the area to register as the model as small as possible.
Model parameter	If the model image is a simple figure or a large figure, specify a smaller value for "Stab." If lowering stability does not speed up processing, it is likely that many candidates have been detected. Raise the "Candidate LV" in [Measurement].
	When "Rotation" is selected and the model image is a simple figure, specify a larger value for "Skipping angle".
	When "Rotation" is selected and the model image is a simple figure, place a check at "Smart mode".
	If the position precision is high, specify a smaller value for "Prec."
	If the rotation angle range is large, set the "Search mode" to "PT".
Measurement parameter	If images that should be judged OK vary little, specify a larger value for "Candidate LV".
	If the position precision is high, uncheck "Sub-pixel".

Measurement Results for Which Output Is Possible (Search)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement result	JG	Judgement result
Count	C	Number of search items detected If none detected, 0
Correlation value	CR	Correlation value with the model
Measurement coordinate X	X	X coordinate of the position where the model is detected
Measurement coordinate Y	Y	Y coordinate of the position where the model is detected
Measurement angle	TH	Angle of the position where the model is detected
Reference position X	SX	X coordinate of the reference position of the registered model
Reference position Y	SY	Y coordinate of the reference position of the registered model
Reference angle	ST	Angle of the registered model
Detection point RX	RX	X coordinate of the registered model
Detection point RY	RY	Y coordinate of the registered model
Correlation value N (N = 00 to 31)	CRN	Detected search N correlation value (N = 00 to 31)
Position N (N = 00 to 31)	XN	Detected search N position X (N = 00 to 31)
Position N (N = 00 to 31)	YN	Detected search N position Y (N = 00 to 31)
Angle N (N = 00 to 31)	THN	Detected search N angle TH (N = 00 to 31)

External Reference Tables (Search)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Correlation value	Get only	0 to 100
6	Measure X	Get only	-99999.9999 to 99999.9999
7	Measure Y	Get only	-99999.9999 to 99999.9999
8	Measurement angle	Get only	-180 to 180
9	Reference X	Get only	-99999.9999 to 99999.9999
10	Reference Y	Get only	-99999.9999 to 99999.9999
11	Reference angle	Get only	-180 to 180
12	Detected coordinate X	Get only	-99999.9999 to 99999.9999
13	Detected coordinate Y	Get only	-99999.9999 to 99999.9999
14	Count	Get only	0 to 32
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Search mode	Set/Get	0: Correlation 1: Shape
121	With rotation	Set/Get	0: OFF 1: ON
122	Upper limit of the rotation angle	Set/Get	-180 to 180
123	Lower limit of the rotation angle	Set/Get	-180 to 180
124	Skipping angle	Set/Get	1 to 30
125	Smart mode	Set/Get	0: OFF 1: ON
126	Stab. (CR)	Set/Get	1 to 15
127	Prec.	Set/Get	1 to 3
128	Stab. (PT)	Set/Get	1 to 5
129	Reference X	Set/Get	0 to 99999.9999
130	Reference Y	Set/Get	0 to 99999.9999
132	Detection point X	Set/Get	0 to 99999.9999
133	Detection point Y	Set/Get	0 to 99999.9999
134	Sub-pixel	Set/Get	0: OFF 1: ON
135	Candidate Point Level	Set/Get	0 to 100
136	Upper limit of measure X	Set/Get	-99999.9999 to 99999.9999
137	Lower limit of measure X	Set/Get	-99999.9999 to 99999.9999
138	Upper limit of measure Y	Set/Get	-99999.9999 to 99999.9999

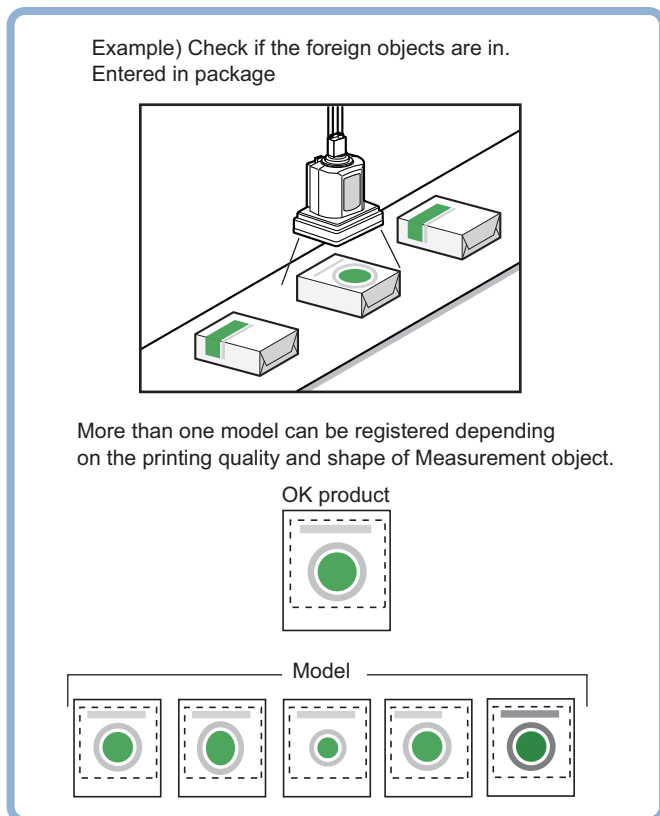
No.	Data name	Set/Get	Data range
139	Lower limit of measure Y	Set/Get	-99999.9999 to 99999.9999
140	Upper limit of the angle	Set/Get	-180 to 180
141	Lower limit of the angle	Set/Get	-180 to 180
142	Upper limit of the corr.	Set/Get	0 to 100
143	Lower limit of the corr.	Set/Get	0 to 100
144	Save registered model	Set/Get	0: OFF 1: ON
145	Candidate Point Level	Set/Get	0 to 100
146	Sort order	Set/Get	0: Correlation value ascending 1: Correlation value descending 2: X ascending 3: X descending 4: Y ascending 5: Y descending
147	Search No.	Set/Get	0 to 31
148	Upper limit of count judgement	Set/Get	0 to 32
149	Lower limit of count judgement	Set/Get	0 to 32
150	Multiple output	Set/Get	0: OFF 1: ON
1000 + NN × 4 (NN = 0 to 31)	Correlation value	Get only	0 to 100
1001 + NN × 4 (NN = 0 to 31)	Measure X	Get only	-99999.9999 to 99999.9999
1002 + NN × 4 (NN = 0 to 31)	Measure Y	Get only	-99999.9999 to 99999.9999
1003 + NN × 4 (NN = 0 to 31)	Measure angle	Get only	-180 to 180

Flexible Search

In Flexible Search, multiple measurement object features (models) are registered beforehand. Parts from input images that most resemble the multiple models are searched for, and correlation (similarity) and position are determined.

Used in the Following Case

- To treat models with only slight variations as the same and prevent excessive filtering out.

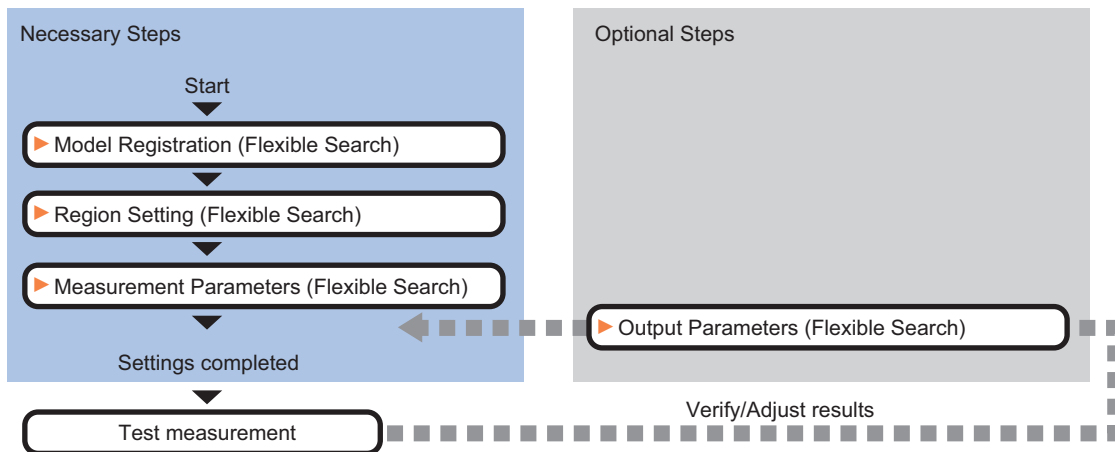


Note

- Search processing basic concepts
Reference: ▶ "Appendixes Measurement Mechanism Search Processing Mechanism" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Settings Flow (Flexible Search)

Set up flexible search according to the following steps.



List of Flexible Search Items

Item name	Description
Model register	This item registers the pattern characteristic of the measurement image as a model. Model parameter values can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used. Reference: ▶ Model Registration (Flexible Search) (p.83)
Region setting	This item is used to set up the measurement area. Instead of measuring the entire input image, narrowing the measurement area shortens the processing time. Reference: ▶ Region Setting (Flexible Search) (p.85)
Measurement	This item specifies the judgement condition for measurement results. Specify the criteria to judge the measurement result if the X and Y coordinates and the correlation with the model are OK. Reference: ▶ Measurement Parameters (Flexible Search) (p.86)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Flexible Search) (p.87)

Model Registration (Flexible Search)

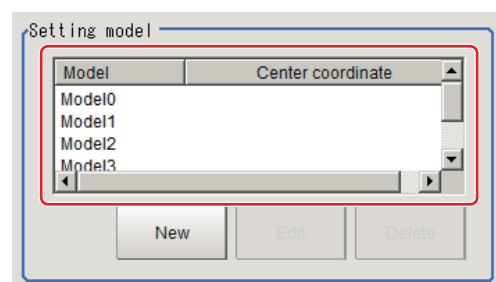
Register the parts to measure as the model.

A total of 5 models, 0 through 4, can be registered, with no restriction on the size.

If a model has different printing qualities and shapes, more than one models should be registered.

The position at the time of registration is also registered in the model information. Place the measurement object in the correct position when registering a model.

- 1** In the Item Tab area, click [Model register].
- 2** In the "Setting model" area, select a model and click [New].

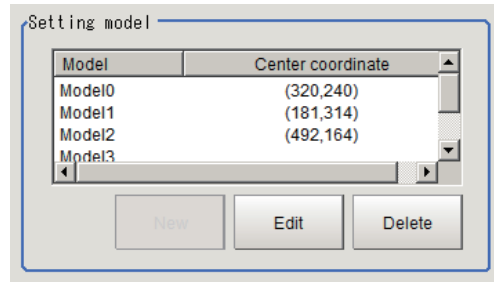


3 Use the drawing tools to specify the model registration range.

4 In the figure setting area, click [OK].

The model is registered and its center X and Y coordinate values are displayed in the "Setting model" area.

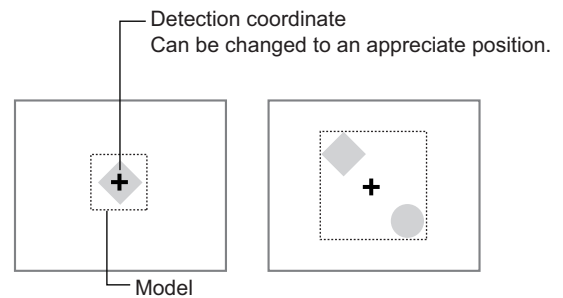
The image specified for the model is displayed in the "Image Display" area.



5 To register two or more models, repeat the Steps Reference: ▶ 2 (p.83) to Reference: ▶ 4 (p.84).

Important

- When a model is registered, the center of the model is registered as the detection point. A detection point is a point output as a measurement value. If multiple figures are combined, the central coordinates of the circumscribed rectangle are registered.

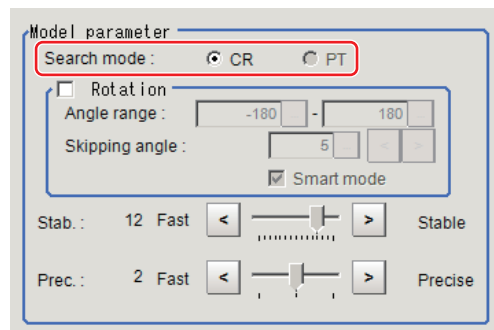


Changing Model Parameters

Model parameter values can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used.

After changing a setting, re-register the model.

1 In the "Model parameter" area, select the search mode, then specify a value for each item for that mode.



Setting item	Set value [Factory default]	Description
Search mode	[CR]	Search for normalizing the brightness. This method can provide stable measurement when there is fluctuation in the overall brightness and when the image has low contrast.
	PT	Measures the degree of matching with the model profile. This method can measure at higher speed when the rotation angle has a wide range. It is available only when a 0.3 megapixel color camera is connected.

When CR is selected

Setting item	Set value [Factory default]	Description
Rotation	<ul style="list-style-type: none"> • Checked • [Unchecked] 	When the measurement object is rotating, place a check at "Rotation" and specify how many degrees the model created rotates each time and through what range of angles. A smaller skipping angle increases stability, but slows down the processing. The normal direction is clockwise.
Angle range	[-180 to 180]	
Skipping angle	1 to 30 [5]	
Smart mode	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Checking the "Smart mode" option enables a high-speed rotation search. However, the stability may be lowered when the model shape aspect ratio is large or when the NOT mask is used.
Stab.	1 to 15 [The default value depend on the connected camera. 9 or 12]	Specify which is to have priority, measurement stability or speed. If lowering stability does not speed up processing, it is likely that many candidates have been detected. In this case, specify a larger value for "Candidate LV" or "Stab."
Prec.	1 to 3 [2]	Specify which is to have priority, measurement positional precision or speed.

When PT is selected

Setting item	Set value [Factory default]	Description
Angle range	[-180 to 180]	This item specifies the rotation angle range for searching. The normal direction is clockwise.
Stab.	1 to 5 [3]	If lowering stability does not speed up processing, it is likely that many candidates have been detected. In this case, specify a larger value for "Candidate LV" or "Stab."

Region Setting (Flexible Search)

Use a rectangle to specify the area where the model is searched.

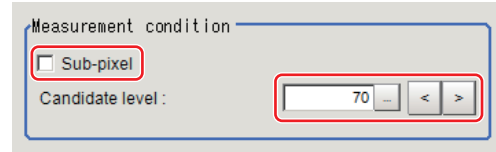
Instead of measuring the entire input image, narrowing the measurement area shortens the processing time.

- 1 In the Item Tab area, click [Region setting].**
- 2 Click [Edit].**
The figure setting area is displayed.
- 3 Specify the area in which to search for the model.**
The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.
- 4 Click [OK].**
The area to measure is registered.

Measurement Parameters (Flexible Search)

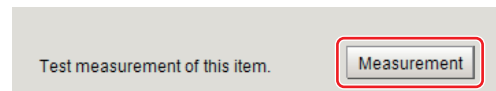
Specify the search measurement conditions and the judgement conditions for the measurement results.

- 1 In the Item Tab area, click [Measurement].
- 2 In the "Measurement condition" area, specify a value for each item.



Setting item	Set value [Factory default]	Description
Sub-pixel	<ul style="list-style-type: none"> • Checked • [Unchecked] 	When a check is placed at sub-pixel, the position information can be measured in units of sub-pixels. However, this requires more processing time.
Candidate level	0 to 100 [70]	Specify the threshold value with which to detect candidate points in a rough search. Specify a smaller value when model search results are unreliable.

- 3 When the setting has been changed, click [Measurement] in the Detail area to verify whether measurements can be made correctly.
- 4 Set up the judgement condition.



Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Set value	Description
Position X	-99999.9999 to 99999.9999	Specify the range of X-axis shifting that is judged to be OK.
Position Y	-99999.9999 to 99999.9999	Specify the range of Y-axis shifting that is judged to be OK.
Search angle	-180 to 180	Specify the range of angles that are judged to be OK.
Correlation	0 to 100	Specify the range of correlation values that are judged to be OK. However, when the correlation value of the measurement result is 0, the judgement result will be NG regardless of the lower limit setting.

Output Parameters (Flexible Search)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (Flexible Search)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Model number	Model No. of the biggest correlation
Correlation	Correlation value
Position X	X coordinate of the position where the model is detected
Position Y	Y coordinate of the position where the model is detected
Angle θ	Angle of the position where the model is detected

Note

- If the model is an ellipse, its circumscribing rectangle is displayed as the search result of the model.

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Searching other positions

Parameter to be adjusted	Remedy
Model parameter	Specify a larger value for the "Prec."
	If the measurement results are unstable only when "Rotation" is selected, specify a smaller value for the "Skipping angle".
	When "Rotation" is selected, if the model shape is complex, uncheck the "Smart mode" option.
	If the image has low contrast or blurred edges, set the "Search mode" to "CR".
	If the model image consists of detailed figures, specify a larger value for "Stab."
Measurement	If the precision is low, place a check at "Sub-pixel".
	If images that should be judged OK vary greatly, specify a smaller value for "Candidate LV".
	If the model image is small and unstable, specify a smaller value for the "Reduction".

The judgement is NG (insufficient memory)

Parameter to be adjusted	Remedy
Region setting	Make the search region as small as possible.
Model parameter	Bring "Stab." close to the factory default value.
	Bring the "Skipping angle" close to the factory default value.
	Specify a smaller value for "Prec."

When the processing speed is slow

Parameter to be adjusted	Remedy
Region setting	Make the search region as small as possible.
Model register	Make the area to register as the model as small as possible.
Model parameter	If the model image is a simple figure or a large figure, specify a smaller value for "Stab." If lowering stability does not speed up processing, it is likely that many candidates have been detected. Raise the "Candidate level" in [Measurement].
	When "Rotation" is selected and the model image is a simple figure, specify a larger value for "Skipping angle".
	When "Rotation" is selected and the model image is a simple figure, place a check at "Smart mode".
	If the position precision is high, specify a smaller value for "Prec."
	If the rotation angle range is large, set the "Search mode" to "PT".
Measurement	If images that should be judged OK vary little, specify a larger value for "Candidate level".
	If the position precision is high, uncheck "Sub-pixel".

Measurement Results for Which Output Is Possible (Flexible Search)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judgement result
Model No.	NO	Model No. of the biggest correlation
Correlation value	CR	Correlation value with the model
Measurement coordinate X	X	X coordinate of the position where the model is detected
Measurement coordinate Y	Y	Y coordinate of the position where the model is detected
Measurement angle	TH	Angle of the position where the model is detected
Reference position X	SX	X coordinate of the reference position of the registered model
Reference position Y	SY	Y coordinate of the reference position of the registered model
Reference angle	ST	Angle of the registered model
Detection point RX	RX	X coordinate of the registered model
Detection point RY	RY	Y coordinate of the registered model

External Reference Tables (Flexible Search)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Model No.	Get only	0 to 4 -1: No models found
6	Correlation value	Get only	0 to 100
7	Measure X	Get only	-99999.9999 to 99999.9999
8	Measure Y	Get only	-99999.9999 to 99999.9999
9	Measure angle	Get only	-180 to 180
10	Reference X	Get only	-99999.9999 to 99999.9999
11	Reference Y	Get only	-99999.9999 to 99999.9999
12	Reference angle	Get only	-180 to 180
13	Detection point X	Get only	-99999.9999 to 99999.9999
14	Detection point Y	Get only	-99999.9999 to 99999.9999
101	Output coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Search mode	Set/Get	0: Correlation 1: Shape
121	With rotation	Set/Get	0: OFF 1: ON
122	Upper limit of the rotation angle	Set/Get	-180 to 180
123	Lower limit of the rotation angle	Set/Get	-180 to 180

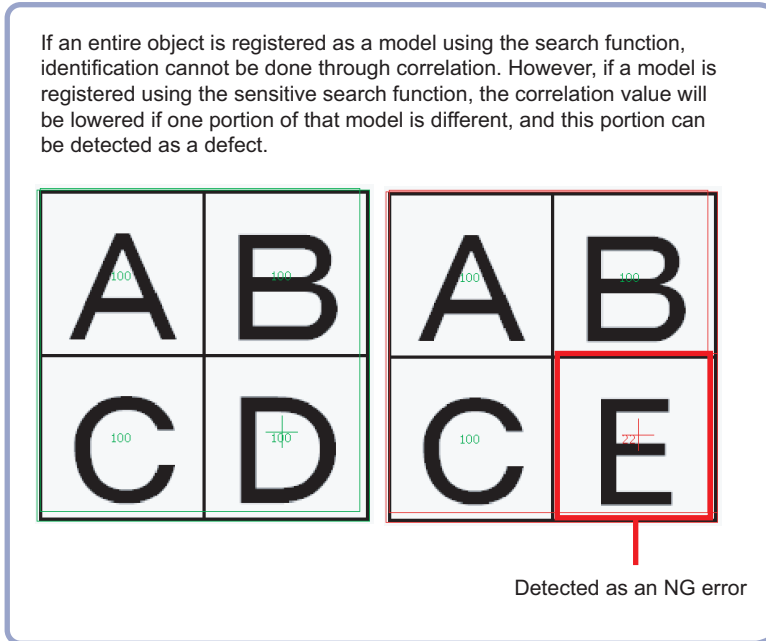
No.	Data name	Set/Get	Data range
124	Skipping angle	Set/Get	1 to 30
125	Smart mode	Set/Get	0: OFF 1: ON
126	Stab. (CR)	Set/Get	1 to 15
127	Prec.	Set/Get	1 to 3
128	Stab. (PT)	Set/Get	1 to 5
134	Sub-pixel	Set/Get	0: OFF 1: ON
135	Candidate Point Level	Set/Get	0 to 100
136	Upper limit of measure X	Set/Get	-99999.9999 to 99999.9999
137	Lower limit of measure X	Set/Get	-99999.9999 to 99999.9999
138	Upper limit of measure Y	Set/Get	-99999.9999 to 99999.9999
139	Lower limit of measure Y	Set/Get	-99999.9999 to 99999.9999
140	Upper limit of the angle	Set/Get	-180 to 180
141	Lower limit of the angle	Set/Get	-180 to 180
142	Upper limit of the corr.	Set/Get	0 to 100
143	Lower limit of the corr.	Set/Get	0 to 100

Sensitive Search

The registered models are automatically finely divided and matched in detail. Of the divided models, the one with the lowest correlation is output. Sensitive search is suitable when the difference between the model image and measurement image is small and regular searches do not produce differences in correlation.

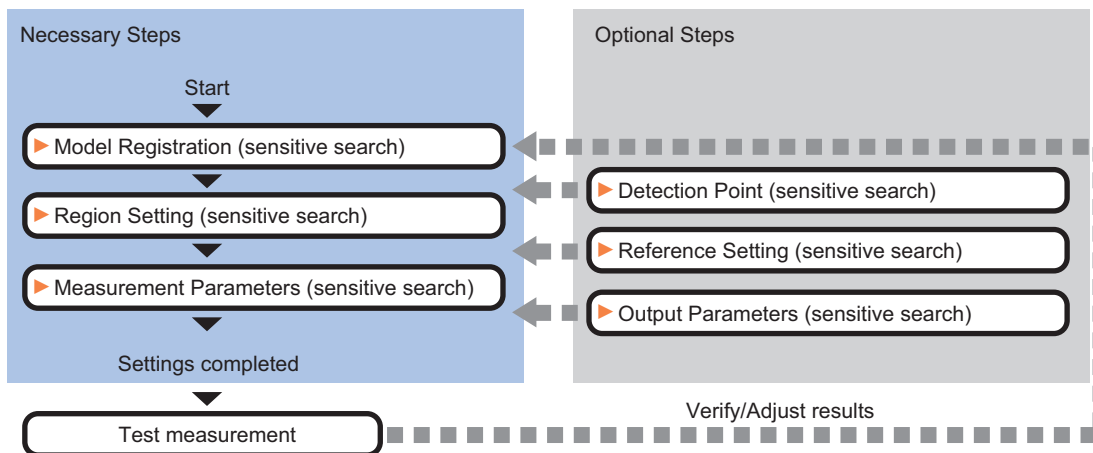
Used in the Following Case

- When identifying the shape of the divided area



Settings Flow (Sensitive Search)

Set up sensitive search according to the following steps.



List of Sensitive Search Items

Item name	Description
Model	This item registers the pattern characteristic of the measurement image as a model. Model parameter values can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used. Reference: ▶ Model Registration (Sensitive Search) (p.92)
Region setting	This item is used to set up the measurement area. Instead of measuring the entire input image, narrowing the measurement area shortens the processing time. Reference: ▶ Region Setting (Sensitive Search) (p.95)
Detection point	This item can be changed if necessary. Specify a position in the model that should be used as the detection coordinates during measurement. Usually, the central position of the set model is registered as the detection coordinates. Reference: ▶ Detection Point (Sensitive Search) (p.95)
Ref. setting	This item can be changed if necessary. Specify the reference position within the camera's field of view. Reference: ▶ Reference Setting (Sensitive Search) (p.96)
Measurement	This item specifies the judgement condition for measurement results. Specify the criteria to judge the measurement result if the X and Y coordinates and the correlation values with the model are OK. Reference: ▶ Measurement Parameters (Sensitive Search) (p.98)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Sensitive Search) (p.99)

Model Registration (Sensitive Search)

Register the parts to measure as the model.

The position at the time of registration is also registered in the model information. Place the measurement object in the correct position when registering a model.

1 In the Item Tab area, click [Model].

When setting a new model, you do not have to click [Model].

2 Use the drawing tools to specify the model registration range.

3 To save the entire image used for model registration, place a check at the "Save reg. model" option. Also, when registering a model but not holding the disable setting for the sub-region set during the last time the model was registered, uncheck the "Keep disabled state" option.



Setting item	Set value [Factory default]	Description
Keep disabled state	<ul style="list-style-type: none"> • [Checked] • Unchecked 	When the model is registered, this holds the disable setting for the sub-region set during the last time the model was registered.
Save reg. model	<ul style="list-style-type: none"> • Checked • [Unchecked] 	To save the entire image used for model registration, place a check at this option.

4 Click [OK].

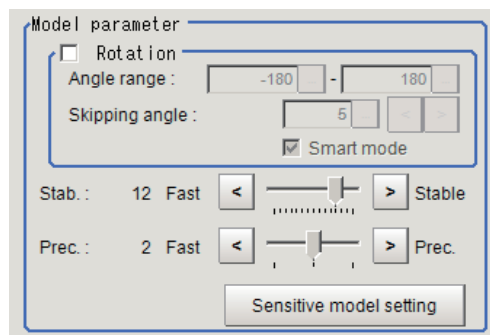
The model is registered.

Changing Model Parameters

Model parameter values can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used.

After changing a setting, re-register the model.

- 1 In the "Model parameter" area, set each item.

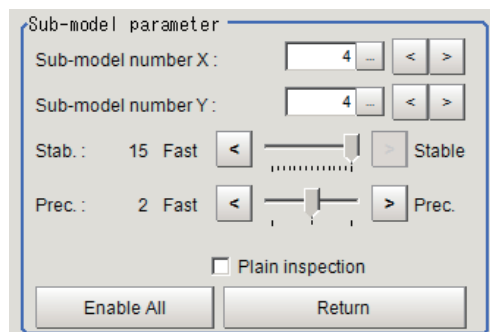


Setting item	Set value [Factory default]	Description
Rotation	<ul style="list-style-type: none"> • Checked • [Unchecked] 	When the measurement object is rotating, place a check at "Rotation" check box and specify how many degrees the model created rotates each time and through what range of angles. A smaller skipping angle increases stability, but slows down the processing. The normal direction is clockwise.
Angle range	[-180 to 180]	
Skipping angle	1 to 30 [5]	
Smart mode	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Checking the "Smart mode" option enables a high-speed rotation search. However, the stability may be lowered when the model shape aspect ratio is large or when the NOT mask is used.
Stab.	1 to 15 [The default value depend on the connected camera. 9 or 12]	Specify which is to have priority, measurement stability or speed. If lowering stability does not speed up processing, it is likely that many candidates have been detected. In this case, specify a larger value for "Candidate level" or "Stab."
Prec.	1 to 3 [2]	Specify which is to have priority, measurement positional precision or speed.

Changing Sub-model parameter

Set the "Sensitive model setting" as necessary.

- 1 Click [Sensitive model setting] in the model parameter.
- 2 Set up the Sub-model parameter.



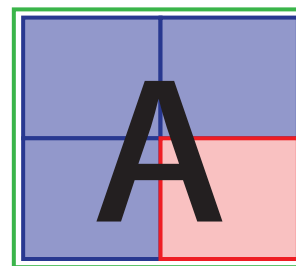
Setting item	Set value [Factory default]	Description
Sub-model number X	0 to 10 [4]	This sets the number of divisions of the registered model in the X direction.
Sub-model number Y	0 to 10 [4]	This sets the number of divisions of the registered model in the Y direction.
Stab.	1 to 15 [The default value depend on the connected camera. 12 or 15]	Specify which is to have priority, measurement stability or speed. If lowering stability does not speed up processing, it is likely that many candidates have been detected. In this case, specify a larger value for "Candidate level" or "Stab."
Prec.	1 to 3 [2]	Specify which is to have priority, measurement positional precision or speed.
Plain inspection	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Specify whether or not to inspect the plain region.

Disabled setting

You can specify enable/disable of each sub-region.

- 1 Click the region you wish to disable and select "Disabled".**

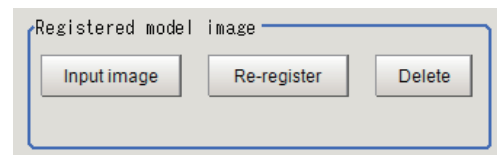
To release the disabling of a region, click "Enable All".



Divided model regions

Displaying/Re-Registering/Deleting a Model

If you save the model registration image, it is easy to re-register the model after model parameters are changed.



Item	Description
Disp model/Input image	The model image display and input image display are switched.
Re-register	When model parameters are modified, display the original model image and re-register the model.
Delete	Deletes a model.

Region Setting (Sensitive Search)

Use a rectangle to specify the area where the model is searched.

Instead of measuring the entire input image, narrowing the measurement area shortens the processing time.

- 1** In the Item Tab area, click [Region setting].
- 2** Click [Edit].
The figure setting area is displayed.
- 3** Specify the area in which to search for the model.
The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.
- 4** Click [OK].
The area to measure is registered.

Detection Point (Sensitive Search)

Specify a position in the model that should be used as the detection coordinates during measurement. Usually, the center position of the set model is registered as the detection point. This function is used to change to any desired position.

A detection point can be set either directly or by referencing a unit.

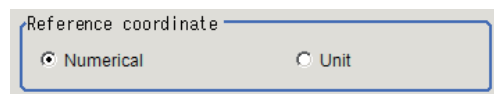
Note

- After changing the detection point coordinates to another position, re-registering the model will change it back to the center coordinates of the model.

Specifying directly

Click a position on the image you want to use as a detection point, or input coordinate data for that point.

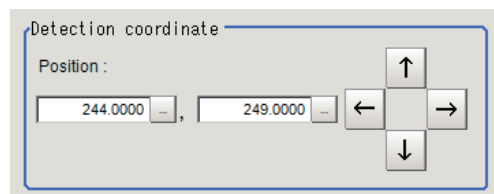
- 1** In the Item Tab area, click [Detection point].
In the Display area, the current detection point is displayed with a crosshair cursor.
- 2** In the "Method" area, select "Numerical".
- 3** Click the position to be set as the detection point.



Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

- 4** Make fine adjustments using numeric value inputs or the arrow buttons as required.



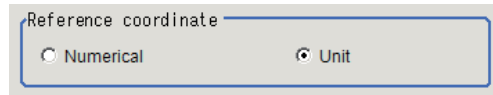
Referencing a unit

Set a detection point by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

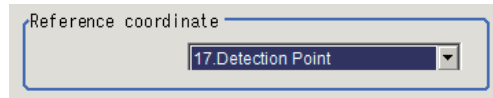
1 In the Item Tab area, click [Detection point].

In the Display area, the current detection point is displayed with a crosshair cursor.

2 In the "Method" area, select "Unit".



3 In the scene in the "Reference coordinate" area, select a detection point unit.



4 Perform the next measurement, and the detection point will be displayed.

Reference Setting (Sensitive Search)

When the model is set, this position is automatically set at the same time as the reference position. This item can be used to change the reference position to any desired position. This is handy for measuring the position deviation from a certain position.

A reference position can be set either directly or by referencing a unit.

Specifying directly

Click a position on the image you want to use as a reference position, or set coordinate data for that point.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.



2 In the "Method" area, select "Numerical".

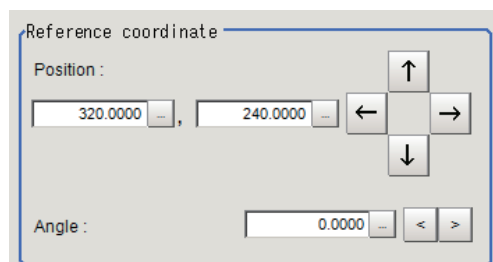


3 Click the position to be set as the reference.

Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

4 Make fine adjustments using numeric value inputs or the arrow buttons as required.



5 Set the reference angle with a numeric value.

6 To remeasure on the displayed image and set the reference, click the [Measure ref.] button. To update the reference angle at the time of reference measurement, place a check at "Update the angle when measure ref.".

Update the angle when measure ref. Measure ref.

7 To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".

Use point coordinate before scroll

Position X : 320.0000
Position Y : 240.0000
Angle : 0.0000

Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

2 In the "Method" area, select "Unit".

Method

Numerical Unit

3 In the scene in the "Unit" area, select a detection point unit.

Unit

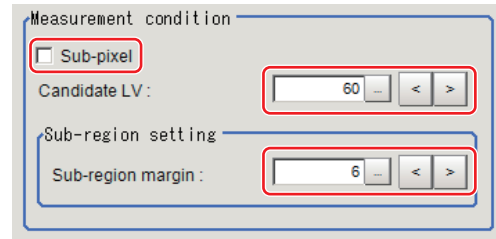
1.Detection Point

4 Perform the next measurement, and the reference will be displayed.

Measurement Parameters (Sensitive Search)

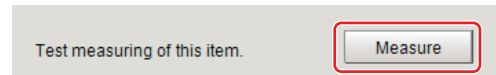
Specify the sensitive search measurement conditions and the judgement conditions for the measurement results.

- 1 In the Item Tab area, click [Measurement].
- 2 In the "Measurement condition" area, specify a value for each item.



Setting item	Set value [Factory default]	Description
Sub-pixel	<ul style="list-style-type: none"> • Checked • [Unchecked] 	When a check is placed at sub-pixel, the position information can be measured in units of sub-pixels. However, this requires more processing time.
Candidate LV	0 to 100 [60]	Specify the threshold value with which to detect candidate points in a rough search. Specify a smaller value when model search results are unstable.
Sub-region margin	0 to 10 [6]	How large a region to use for the divided model search range for the divided model size is specified in units of pixels. If 6 is set, an area that is the model size expanded by 6 pixels up, down, left, and right is the search range.

- 3 When the setting has been changed, click [Measure] in the "Detail" area to verify whether measurements can be made correctly.



- 4 Set up the judgement condition.

Setting item	Set value	Description
Measure X	-99999.9999 to 99999.9999	Specify the range of X-axis shifting that is judged to be OK.
Measure Y	-99999.9999 to 99999.9999	Specify the range of Y-axis shifting that is judged to be OK.
Search angle	-180 to 180	Specify the range of angles that are judged to be OK.
Correlation	0 to 100	Specify the range of correlation values that are judged to be OK. However, when the correlation value of the measurement result is 0, the judgement result will be NG regardless of the lower limit setting.
Deviation	For color cameras: 0 to 221 For monochrome cameras: 0 to 127	Specify the range of density deviations that are judged to be OK. The higher the proportion of plain sections, the higher this value. This is enabled when plain inspection is set in the sensitive model settings.
NG Sub-region	0 to 100	Specify the range of NG sub-region that are judged to be OK.

Output Parameters (Sensitive Search)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Set value [Factory default]	Description	
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position deflection correction is applied.	
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.	
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgment.	
Display cursor setting			
	Position	<ul style="list-style-type: none"> • [ON] • OFF 	The measurement coordinate position of the detected model is displayed at the cursor.
	Sub-region	<ul style="list-style-type: none"> • Display • [OFF] 	The coordinate position of the region with the lowest correlation value of the sub-regions is displayed at the cursor.

Key Points for Test Measurement and Adjustment (Sensitive Search)

The following content is displayed in the "Detail result" area as text.

Note

- Executing test measurements will also update the measurement results and the figures in the image.

Displayed items	Description
Judge	Judgement result
Correlation	Lowest correlation value in the sub-region
Position X	X coordinate of the position where the model is detected
Position Y	Y coordinate of the position where the model is detected
Angle θ	Angle of the position where the model is detected
Deviation	Highest density deviation in the sub-region
NG Sub-region	NG region count

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Searching other positions

Parameter to be adjusted	Remedy
Model parameter	Specify a larger value for the "Prec."
	If the measurement results are unstable only when "Rotation" is selected, specify a smaller value for the "Skipping angle".
	When "Rotation" is selected, if the model shape is complex, uncheck the "Smart mode" option.
	If the model image consists of detailed figures, specify a larger value for "Stab."
Sub-model parameter	If images that should be judged OK vary greatly, specify a larger value for "Sub-model number X" and "Sub-model number Y".
Measurement	If the precision is low, place a check at "Sub-pixel".
	If images that should be judged OK vary greatly, specify a smaller value for "Candidate level".
	If images that should be judged OK vary greatly, specify a larger value for "Sub-region margin".

The judgement is NG (insufficient memory)

Parameter to be adjusted	Remedy
Region setting	Make the search region as small as possible.
Model parameter	Bring "Stab." close to the factory default value.
	Bring the "Skipping angle" close to the factory default value.
	Specify a smaller value for "Prec."
Sub-model parameter	Specify a larger value for "Sub-model number X" and "Sub-model number Y".

When the processing speed is slow

Parameter to be adjusted	Remedy
Region setting	Make the search region as small as possible.
Model Registration	Make the area to register as the model as small as possible.
Model parameter	If the model image is a simple figure or a large figure, specify a smaller value for "Stab." If lowering stability does not speed up processing, it is likely that many candidates have been detected. Raise the "Candidate level" in [Measurement].
	When "Rotation" is selected and the model image is a simple figure, specify a larger value for "Skipping angle".
	When "Rotation" is selected and the model image is a simple figure, place a check at "Smart mode".
	If the position precision is high, specify a smaller value for "Prec."
Sub-model parameter	If images that should be judged OK vary greatly, specify a larger value for "Sub-model number X" and "Sub-model number Y".
Measurement parameter	If images that should be judged OK vary little, specify a larger value for "Candidate LV".
	If the position precision is high, uncheck "Sub-pixel".

Measurement Results for Which Output Is Possible (Sensitive Search)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judgement result
Correlation value	CR	Correlation value with the model
Deviation	DV	Deviation
Measurement coordinate X	X	X coordinate of the position where the model is detected
Measurement coordinate Y	Y	Y coordinate of the position where the model is detected
Measurement angle	TH	Angle of the position where the model is detected
Reference position X	SX	X coordinate of the reference position of the registered model
Reference position Y	SY	Y coordinate of the reference position of the registered model
Reference angle	ST	Angle of the registered model
Detection point coordinate X	RX	X coordinate of the registered model
Detection point coordinate Y	RY	Y coordinate of the registered model
NG sub-region	CT	NG region count
Sub-region Number	AN	Region number with the lowest correlation value
Sub-region Number(X)	ANX	X direction column number for the output region
Sub-region Number(Y)	ANY	Y direction line number for the output region
Sub-region Pos. X	DX	X coordinate of the detected sub-region
Sub-region Pos. Y	DY	Y coordinate of the detected sub-region
Correlation (sub-region N) (N = 0 to 99)	CRN	Correlation (sub-region N)
Deviation (sub-region N) (N = 0 to 99)	DVN	Deviation (sub-region N)

External Reference Tables (Sensitive Search)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
1	Correlation value	Get only	0 to 100
2	Deviation	Get only	For color cameras: 0.000 to 219.9705 For monochrome cameras: 0.000 to 127.000
3	Measure X	Get only	-99999.9999 to 99999.9999
4	Measure Y	Get only	-99999.9999 to 99999.9999
5	Measurement angle	Get only	-180 to 180
6	Detection point X	Get only	-99999.9999 to 99999.9999
7	Detection point Y	Get only	-99999.9999 to 99999.9999
8	Reference X	Get only	-99999.9999 to 99999.9999
9	Reference Y	Get only	-99999.9999 to 99999.9999
10	Reference angle	Get only	-180 to 180
11	NG Sub-region	Get only	0 to 100

No.	Data name	Set/Get	Data range
12	Sub-region Number	Get only	0 to 99
13	Sub-region Number(X)	Get only	0 to 9
14	Sub-region Number(Y)	Get only	0 to 9
15	Sub-region Pos. X	Get only	-99999.9999 to 99999.9999
16	Sub-region Pos. Y	Get only	-99999.9999 to 99999.9999
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
121	With rotation	Set/Get	0: OFF 1: ON
122	Upper limit of the rotation angle	Set/Get	-180 to 180
123	Lower limit of the rotation angle	Set/Get	-180 to 180
124	Skipping angle	Set/Get	1 to 30
125	Smart mode	Set/Get	0: OFF 1: ON
126	Stability	Set/Get	1 to 15
127	Precision	Set/Get	1 to 3
129	Reference X	Set/Get	0 to 9999
130	Reference Y	Set/Get	0 to 9999
132	Detection point X	Set/Get	0 to 9999
133	Detection point Y	Set/Get	0 to 9999
134	Sub-pixel	Set/Get	0: OFF 1: ON
135	Candidate Point Level	Set/Get	0 to 100
136	Upper limit of measure X	Set/Get	-99999.9999 to 99999.9999
137	Lower limit of measure X	Set/Get	-99999.9999 to 99999.9999
138	Upper limit of measure Y	Set/Get	-99999.9999 to 99999.9999
139	Lower limit of measure Y	Set/Get	-99999.9999 to 99999.9999
140	Upper limit of the angle	Set/Get	-180 to 180
141	Lower limit of the angle	Set/Get	-180 to 180
142	Upper limit of the corr.	Set/Get	0 to 100
143	Lower limit of the corr.	Set/Get	0 to 100
144	Save registered model	Set/Get	0: OFF 1: ON
145	Upper limit of deviation	Set/Get	For color cameras: 0 to 221 For monochrome cameras: 0 to 127
146	Lower limit of deviation	Set/Get	For color cameras: 0 to 221 For monochrome cameras: 0 to 127
147	Upper limit of NG Sub-region	Set/Get	0 to 100
148	Lower limit of NG Sub-region	Set/Get	0 to 100
149	Sub-region stab.	Set/Get	1 to 15
150	Sub-region prec.	Set/Get	1 to 3

No.	Data name	Set/Get	Data range
151	Sub-model number X	Set/Get	1 to 10
152	Sub-model number Y	Set/Get	1 to 10
153	Plain inspection	Set/Get	0: OFF 1: ON
154	NG Sub-region (155,156 setting/ acquisition target)	Set/Get	0 to 99
155	Enabled/disabled of sub-region	Set/Get	0: Disabled 1: Enabled
157	Display cursor (position)	Set/Get	0: OFF 1: ON
158	Display cursor (Sub-region Pos.)	Set/Get	0: OFF 1: ON
159	Sub-region margin	Set/Get	0 to 10
165	Disabled region retention flag	Set/Get	0: Not retained 1 : Retained
1000 + N (N = 0 to 99)	Correlation value of sub-region	Get only	0 to 100
1100 + N (N = 0 to 99)	Deviation of sub-region	Get only	For color cameras: 0.000 to 219.9705 For monochrome cameras: 0.000 to 127.000

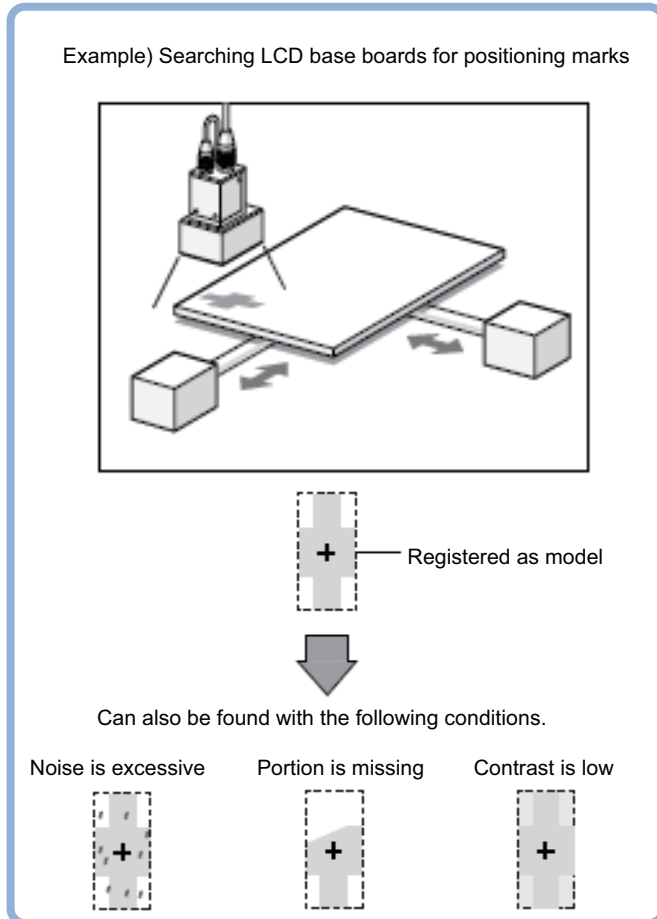
ECM Search

This processing item searches the input image for parts having a high degree of similarity to the target mark (model), and measures its correlation value (similarity) and position.

In a normal search, image pattern models are used that look at the color and light/dark information, but in an ECM search, models are used that look at the profile information. Therefore, this processing assures a reliable search even for low-contrast or noisy images.

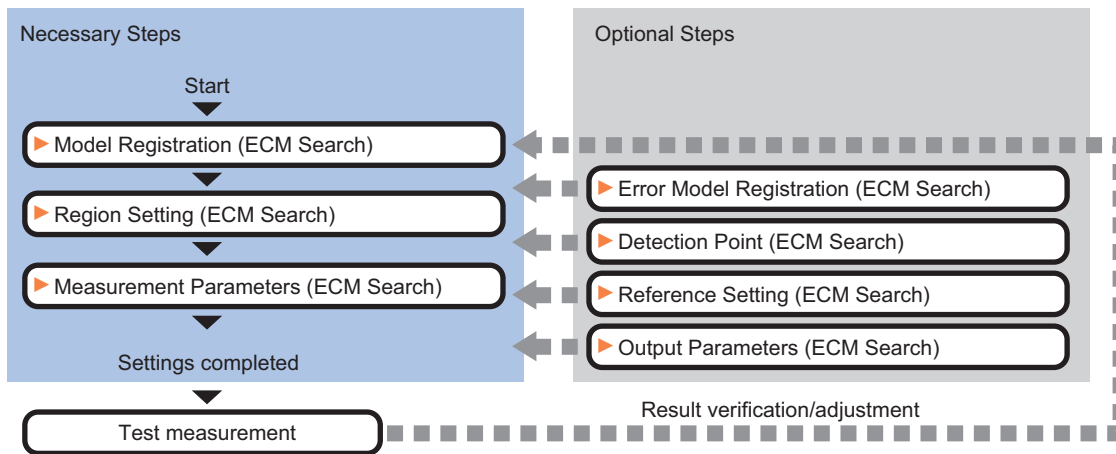
Used in the Following Case

- To measure the location of a mark



Settings Flow (ECM Search)

Set up ECM search according to the following steps.



List of ECM Search Items

Item name	Description
Model register	This item registers the pattern characteristic of the measurement image as a model. Model parameter values can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used. Reference: ▶ Model Registration (ECM Search) (p.106)
Error model	This item can be changed if necessary. As an error model, register a model with similar characteristics to the registered one, but with its correlation value lowered when measured. Reference: ▶ Error Model Registration (ECM Search) (p.109)
Region setting	This item is used to set up the measurement area. Instead of measuring the entire input image, narrowing the measurement area shortens the processing time. Reference: ▶ Region Setting (ECM Search) (p.109)
Detection point	This item can be changed if necessary. Usually, the central position of the registered model is registered as the search detection point. Reference: ▶ Detection Point (ECM Search) (p.109)
Ref. setting	This item can be changed if necessary. Usually, the central position of the registered region is registered as the reference position. Reference: ▶ Reference Setting (ECM Search) (p.111)
Measurement	This item specifies the judgement condition for measurement results. Specify the criteria to judge the measurement result if the X and Y coordinates and the correlation values with the model are OK. Reference: ▶ Measurement Parameters (ECM Search) (p.112)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (ECM search) (p.113)

Model Registration (ECM Search)

Register the pattern characteristic of the measurement object as a model. In an ECM search, only the image profile information is registered.

Important

- For ECM search, 6 pixels at each end of an image cannot be registered as a part of the model.
- If a model is re-registered, the error model is deleted. Register error models when re-registering a model.

1 In the Item Tab area, click [Model register].

When setting a new model, you do not have to click [Model register].

2 Use the drawing tools to specify the model registration range.

3 In the figure setting area, click [OK].

The model is registered.

4 Click [Edge extraction], then confirm the edge extraction image.

If there is a break in the outline of the measurement object, adjust the edge level.

Reference: ▶ Adjusting the Edge Level (p.108)

5 If there is unnecessary profile information in the model, click [Mask register] to set the mask.

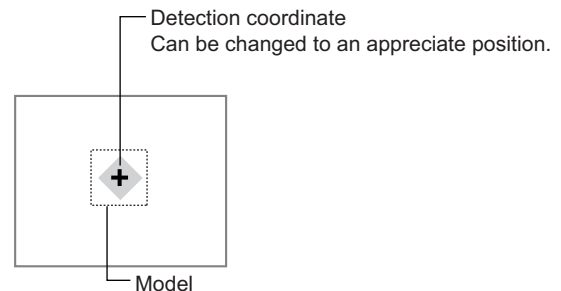
Reference: ▶ Mask any Unnecessary Items. (p.108)

6 To check the model display, click [Display model].

The registered model image is displayed in the image display area.

Note

- When a model is registered, the center coordinate of the model is registered as the detection point coordinate. A detection point is a point output as a measurement value.

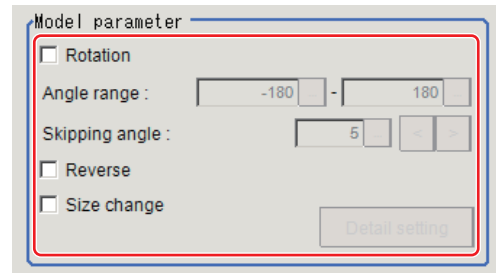


Changing Model Parameters

Model parameter values can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used.

After changing a setting, check whether measurement can be done properly by performing an actual measurement.

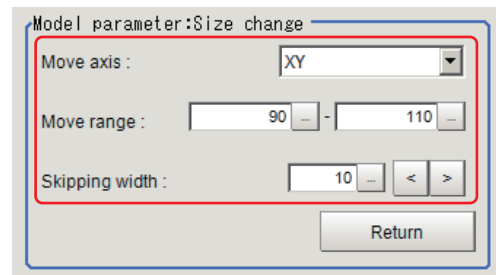
- 1 In the "Model parameter" area, specify a value for each item.**



Setting item		Set value [Factory default]	Description
Rotation		<ul style="list-style-type: none"> • Checked • [Unchecked] 	When the measurement object is rotating, select the "Rotation" check box and specify how many degrees the model created rotates each time and through what range of angles. A smaller skipping angle increases stability, but slows down the processing. The normal direction is clockwise.
Angle range	Upper limit value	-180 to [180]	
	Lower limit value	[-180] to 180	
Skipping angle		1 to 30 [5]	Specify how many degrees the model created rotates each time. A smaller angle increases stability, but slows down the processing.
Reverse		<ul style="list-style-type: none"> • Checked • [Unchecked] 	Specify whether to allow the reverse of light and dark for the model.
Size change		<ul style="list-style-type: none"> • Checked • [Unchecked] 	Specify whether to allow size change for the model. When checked, click [Detail setting] and specify a value for each item.

- 2 When the "Size change" option is checked, click [Detail setting].**

The "Model parameter: Size change" area is displayed.



Setting item	Set value [Factory default]	Description
Move axis	<ul style="list-style-type: none"> • [XY] • X • Y 	Specify the model variable direction.
Move range	50 to 150 [90,110]	Specify the range in which to change the model size.
Skipping width	1 to 99 [10]	Specify the skipping percentage within the move range by which to change models being created. A smaller skipping width increases precision, but slows down the processing.

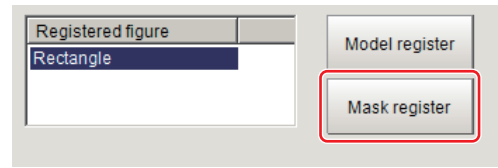
- 3 Click [Return].**

The "Model parameter" area is displayed.

Mask any Unnecessary Items.

By registering a mask, the part you do not want included in the model is excluded.

1 Click [Mask register].



2 Draw the mask figure using the drawing tools.

3 Click [OR/NOT].

The mask figure is displayed in red.

4 In the figure setting area, click [OK].

Adjusting the Edge Level

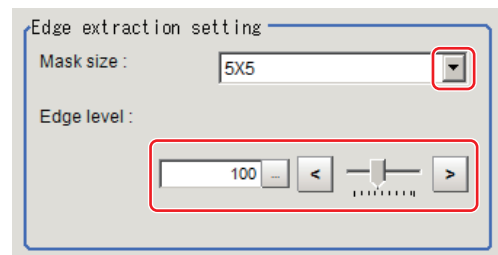
In an ECM search, processing is executed on the edge extraction image. Change this item as necessary when the edge is not extracted or is extracted along with noise.

Important

- In model registration, extract as much of the edge as possible, then delete noise etc. in the mask registration to register the entire edge of the model. On the other hand, when measuring, even if the edge has skips, an image with the noise suppressed makes it possible to search the model stably. To set separate edge extraction conditions for model registration and for measuring, after registering the model, change the edge extraction conditions.

1 In the Item Tab area, click [Edge extraction].

2 Set the items in the "Edge extraction setting" area.



Setting item	Set value [Factory default]	Description
Mask size	<ul style="list-style-type: none"> • 3 × 3 • [5 × 5] • 7 × 7 • 9 × 9 	Select the range of pixels which are used to extract the edge. With a larger mask size, search is less affected by variation in pixels.
Edge level	0 to 255 [100]	Change this when the edge is hard to see due to low contrast against the background or when unnecessary background noise must be removed. The smaller the value, the easier it is to find edges. The larger the value, the less noise will affect finding edges.

Error Model Registration (ECM Search)

Even for an image pattern with similar feature sections (for example "P" and "R"), if the model is registered as an error model, the correlation value is lower and measurement mistakes can be prevented. Only one error model can be registered.

1 In the Item Tab area, click [Error model].

2 Display the error model image.

Register the error model with the same procedure as for model registration.

Important

- Upon re-registering a model, error models are deleted. Register error models when re-registering a model. Register error models when re-registering a model.

Region Setting (ECM Search)

Use a rectangle to specify the area where the model is searched.

Instead of measuring the entire input image, narrowing the measurement area shortens the processing time.

1 In the Item Tab area, click [Region setting].

2 Click [Edit].

The figure setting area is displayed.

3 Specify the area in which to search for the model.

The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.

4 Click [OK].

The area to measure is registered.

Detection Point (ECM Search)

Specify a position in the model that should be used as the detection coordinates during measurement. Usually, the center position of the set model is registered as the detection point. This function is used to change to any desired position.

A reference position can be set either directly or by referencing a unit.

Note

- After changing the detection point coordinates to another position, re-registering the model will change it back to the center coordinates of the model.

Specifying directly

Click a position on the image you want to use as a reference position, or set coordinate data for that point.

1 In the Item Tab area, click [Detection point].

In the Display area, the current detection point is displayed with a crosshair cursor.



2 In the "Method" area, select "Numerical".

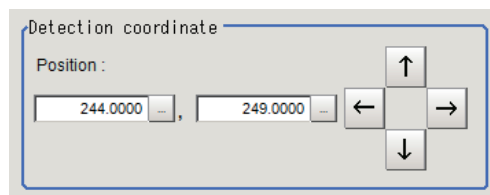


3 Click the position to be set as the detection point.

Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

4 Make fine adjustments using numeric value inputs or the arrow buttons as required.



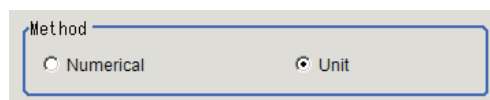
Referencing a unit

Set a detection point by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

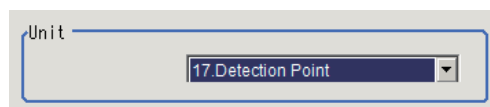
1 In the Item Tab area, click [Detection point].

In the Display area, the current detection point is displayed with a crosshair cursor.

2 In the "Method" area, select "Unit".



3 In the scene in the "Unit" area, select a detection point unit.



4 Perform the next measurement, and the detection point will be displayed.

Reference Setting (ECM Search)

When the measurement region is set, this position is automatically set at the same time as the reference position. This item can be used to change the reference position to any desired position. This is handy for measuring the position deviation from a certain position.

A reference position can be set either directly or by referencing a unit.

Specifying directly

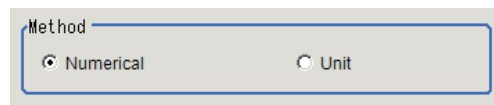
Click a position on the image you want to use as a reference position, or set coordinate data for that point.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.



2 In the "Method" area, select "Numerical".

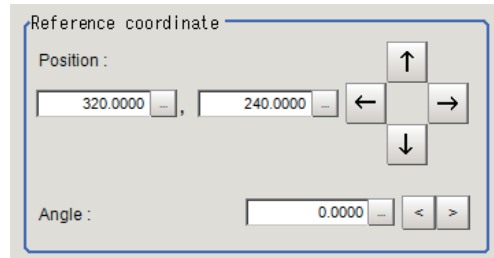


3 Click the position to be set as the reference.

Note

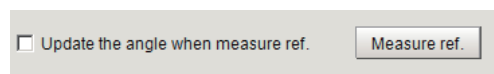
- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

4 Make fine adjustments using numeric value inputs or the arrow buttons as required.

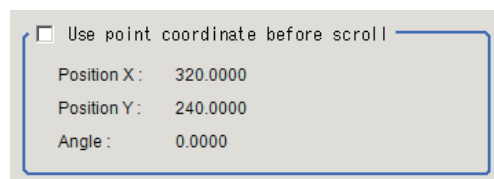


5 Input the reference angle with a numeric value.

6 To remeasure on the displayed image and set the reference, click the [Measure ref.] button. To update the reference angle at the time of reference measurement, place a check at "Update the angle when measure ref.".



7 To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".



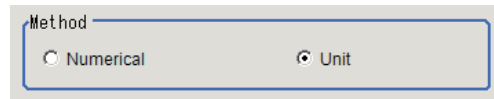
Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

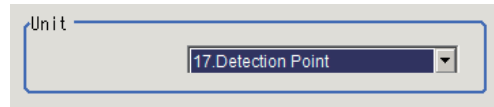
1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

2 In the "Method" area, select "Unit".



3 In the scene in the "Unit" area, select a detection point unit.



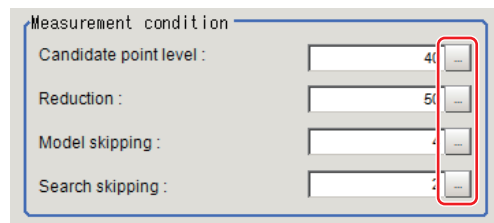
4 Perform the next measurement, and the reference will be displayed.

Measurement Parameters (ECM Search)

This item specifies the judgement condition for measurement results. Specify the criteria to judge the measurement result if the X and Y coordinates and the correlation values with the model are OK.

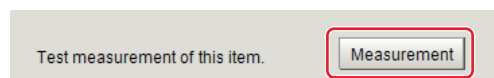
1 In the Item Tab area, click [Measurement].

2 In the "Measurement condition" area, specify a value for each item.



Setting item	Set value [Factory default]	Description
Candidate point level	0 to 99 [40]	Specify the threshold value with which to detect candidate points in a rough search. Specify a smaller value for candidate point level when model search results are unstable.
Reduction	10 to 100 [50]	Specify the percentage to which the input image and the model image are reduced during a rough search. The more the image is reduced, the faster the processing becomes, but search results may be unstable with a smaller image.
Model skipping	1 to 19 [4]	Specify how many pixels should be skipped when performing a rough search.
Search skipping	1 to 9 [2]	Specify how many pixels are skipped when performing a search for the "Search region".

3 When the setting has been changed, click [Measurement] in the "Detail" area to verify whether measurements can be made correctly.



4 Set up the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Set value	Description
Measure pos X	-99999.9999 to 99999.9999	Specify the range of X-axis shifting that is judged to be OK.
Measure pos Y	-99999.9999 to 99999.9999	Specify the range of Y-axis shifting that is judged to be OK.
Measure angle	-180 to 180	Specify the range of angles that are judged to be OK.
Correlation [Note 1]	0 to 100	Specify the range of correlation values that are judged to be OK.

[Note 1]: When the ECM correlation value of the measurement result is 0, the judgement result will be NG regardless of the measurement parameters setting.

Output Parameters (ECM search)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

1 Click [Output parameter] in the Item Tab area.

2 Specify each of the following items.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> [After scroll] Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.
Calibration	<ul style="list-style-type: none"> [OFF] ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> [ON] OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (ECM Search)

The following content is displayed in the "Detail result" area as text.

Displayed item	Description
Judge	Judgement result
Correlation	Correlation value
Position X	X coordinate of the position where the model is detected
Position Y	Y coordinate of the position where the model is detected
Angle θ	Angle of the position where the model is detected

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number.	Explanation of image to be displayed
0	Measurement image
1	Measurement image displayed with matching models overlaid Green: Matched model points Red: Unmatched model points

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Parameter to be adjusted	Remedy
Measurement	If images that should be judged OK vary greatly, specify a smaller value for "Candidate level".
	If the model image is small and unstable, specify a smaller value for the "Reduction".
Model register	Mask any unnecessary items.
	Lower the edge level.
	Register the error model.
Model parameter	If the measurement results are unstable only when "Rotation" is selected, specify a smaller value for the "Skipping angle".

When the processing speed is slow

Parameter to be adjusted	Remedy
Region setting	Make the search region as small as possible.
Model parameter	If images that should be judged OK vary little, specify a larger value for "Candidate level".
	When "Rotation" is selected and the model image is a simple figure, specify a larger value for "Skipping angle".
Measurement	Specify a smaller value of the "Reduction".
	Specify a larger value of the "Model skipping".
	Specify a larger value of the "Search skipping".

When Using Measurement Results Externally (ECM Search)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Correlation value	CR	Correlation value with the model
Measure X	X	X coordinate of the position where the model is detected
Measure Y	Y	Y coordinate of the position where the model is detected
Measurement angle	TH	Angle of the position where the model is detected
Measurement magnification MX	MX	X-axis magnification of the detected model
Measurement magnification MY	MY	Y-axis magnification of the detected model
Reference coordinate X	SX	X coordinate of the reference position of the registered model
Reference coordinate Y	SY	Y coordinate of the reference position of the registered model
Reference angle	ST	Angle of the registered model
Detection point RX	RX	X coordinate of the registered model
Detection point RY	RY	Y coordinate of the registered model

External Reference Tables (ECM Search)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Correlation value	Get only	0 to 100
6	Measure X	Get only	-99999.9999 to 99999.9999
7	Measure Y	Get only	-99999.9999 to 99999.9999
8	Angle θ	Get only	-180 to 180
9	Magnification X	Get only	50 to 150
10	Magnification Y	Get only	50 to 150
11	Reference X	Get only	-99999.9999 to 9999.9999
12	Reference Y	Get only	-99999.9999 to 9999.9999
13	Reference angle	Get only	-180 to 180
14	Detection point X	Get only	-99999.9999 to 9999.9999
15	Detection point Y	Get only	-99999.9999 to 9999.9999
101	Output coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Mask size	Set/Get	0: 3 × 3 1: 5 × 5 2: 7 × 7 3: 9 × 9
121	Edge Level	Set/Get	0 to 255
122	Detection point X	Set/Get	-99999.9999 to 9999.9999
123	Detection point Y	Set/Get	-99999.9999 to 9999.9999
124	Reference X	Set/Get	0 to 99999.9999
125	Reference Y	Set/Get	0 to 99999.9999
126	Upper limit of the corr.	Set/Get	0 to 100
127	Lower limit of the corr.	Set/Get	0 to 100
128	Upper limit of measure X	Set/Get	-99999.9999 to 99999.9999
129	Lower limit of measure X	Set/Get	-99999.9999 to 99999.9999
130	Upper limit of measure Y	Set/Get	-99999.9999 to 99999.9999
131	Lower limit of measure Y	Set/Get	-99999.9999 to 99999.9999
132	Upper limit of the angle	Set/Get	-180 to 180
133	Lower limit of the angle	Set/Get	-180 to 180
134	Candidate Point Level	Set/Get	0 to 99
135	Model skipping	Set/Get	1 to 9
136	Region skipping	Set/Get	1 to 19
137	Reduction	Set/Get	10 to 100

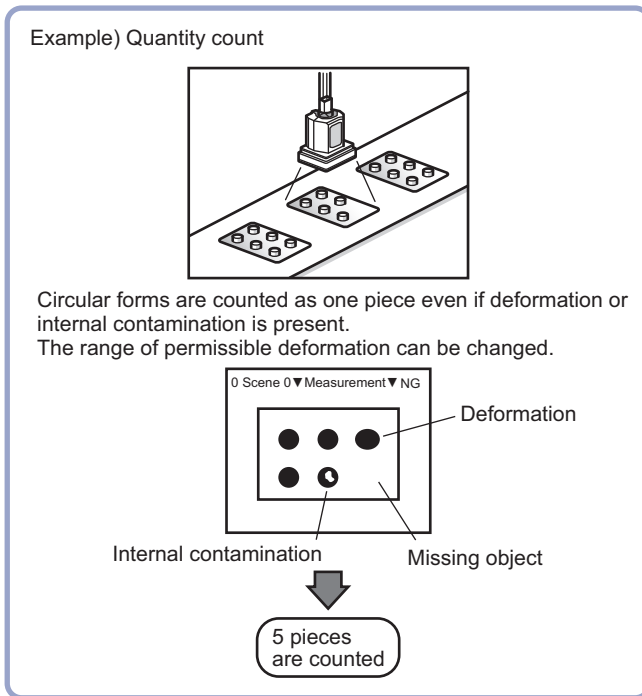
No.	Data name	Set/Get	Data range
138	With rotation	Set/Get	0: No rotation 1: With rotation
139	Lower limit of the rotation angle	Set/Get	-180 to 180
140	Upper limit of the rotation angle	Set/Get	-180 to 180
141	Skipping angle	Set/Get	1 to 30
142	Move axis	Set/Get	0: No size change 1: XY change 2: X change 3: Y change
143	Upper limit of the size change	Set/Get	50 to 150
144	Lower limit of the size change	Set/Get	50 to 150
145	Size change skipping	Set/Get	1 to 99
146	Reverse	Set/Get	0: No reverse 1: Reverse

EC Circle Search

This processing item searches the input image for parts having a high degree of similarity to the target circle mark (model), and measures its circle evaluated value (similarity) and position. In a normal search, image pattern models are used that look at the color and light/dark information. In EC Circle Search, however, models are used that look at the profile. Therefore, this processing assures a reliable search even for low-contrast or noisy images. It is also possible to measure the number of circles in the input image.

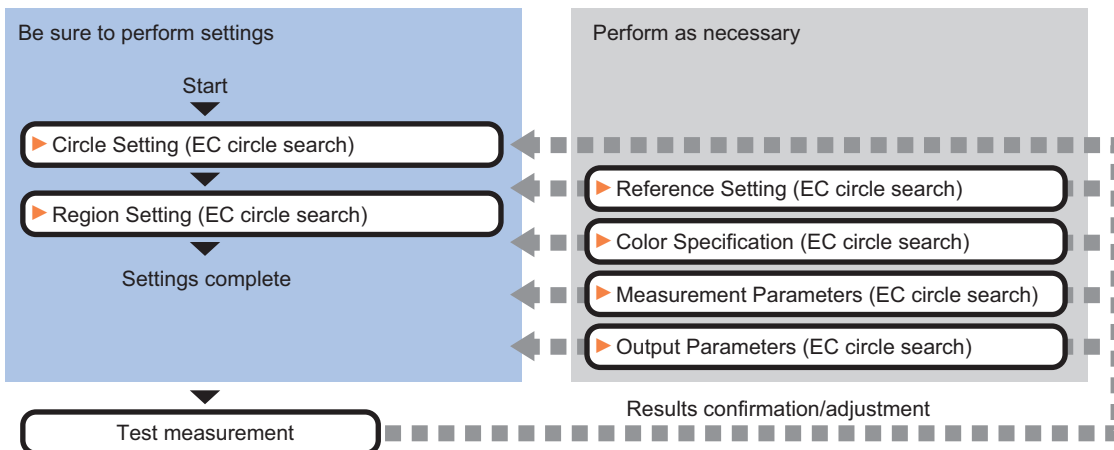
Used in the Following Case

- This counts how many circles there are of the specified size. Since circles are extracted with the shape information of "Round", the circles being deformed or dirty does not affect counting.



Settings Flow (EC Circle Search)

Set up EC circle search according to the following steps.



List of EC Circle Search Items

EC circle search items are explained below.

Item name	Description
Circle setting	This item sets the size of the circle to search for. Reference: ▶ Circle Setting (EC Circle Search) (p.118)
Region setting	This item is used to set up the measurement area. Narrowing the measurement area instead of measuring the entire input screen shortens the processing time. Reference: ▶ Region Setting (EC Circle Search) (p.119)
Ref. setting	This item can be changed if necessary. Usually, the central position of the registered region is specified as the reference position. Reference: ▶ Reference Setting (EC Circle Search) (p.119)
Color setting	This item can be changed if necessary. Select the color of the circle and the background color. If no check is placed at color setting, the circle (edge) is extracted with the brightness difference. Reference: ▶ Color Specification (EC Circle Search) (p.121)
Measurement parameter	This item changes the measurement parameter as necessary when the measurement result is unstable. Reference: ▶ Measurement Parameters (EC Circle Search) (p.121)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (EC Circle Search) (p.123)

Circle Setting (EC Circle Search)

Registers the size of the circle to search for.

Set the circle size only with the circumference figure.

1 In the Item Tab area, click [Circle register].

When setting a new circle, you do not need to click [Circle register].

2 Set the search circumference using the drawing tools.

3 In the figure setting area, click [OK].

The circle to search for is registered.

4 Click [Edge extraction] and set values.

Reference: ▶ Extracting Edges (p.118)

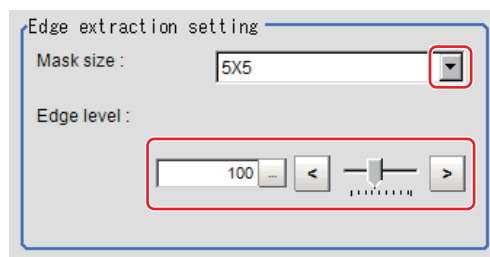
Extracting Edges

In an EC circle search, processing is executed on the edge extraction image. Change this item as necessary when the edge is not extracted or is extracted along with noise.

1 In the Item Tab area, click [Edge extraction].

2 In the "Edge extraction setting" area, click [...] or [▼] and specify a value for each item.

The "Edge level" value can be specified by dragging the slider or clicking one of the buttons at either end of the slider.



Setting item	Set value [Factory default]	Description
Mask size	<ul style="list-style-type: none"> • 3 × 3 • [5 × 5] • 7 × 7 • 9 × 9 	Select the range of pixels which are used to extract the edge. With a larger mask size, search is less affected by variation in pixels.
Edge level	0 to 255 [100]	Change this when the edge is hard to see due to low contrast against the background or when unnecessary background noise must be removed. The smaller the value, the easier it is to find edges. The larger the value, the less noise will affect finding edges.

Region Setting (EC Circle Search)

Specify the rectangular area in which to search for the circle.

Instead of measuring the entire input image, narrowing the measurement area shortens the processing time.

- 1 In the Item Tab area, click [Region setting].**
- 2 Click [Edit].**
The figure setting area is displayed.
- 3 Specify the area in which to search for the model.**
The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.
- 4 Click [OK].**
The measurement region is registered and displayed in the Image Display area.

Reference Setting (EC Circle Search)

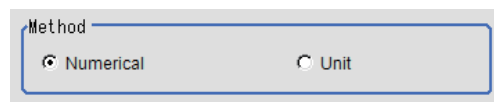
When the model is set, this position is automatically set at the same time as the reference position. This item can be used to change the reference position to any desired position. This is handy for measuring the position deviation from a certain position.

A reference position can be set either directly or by referencing a unit.

Specifying directly

Click a position on the image you want to use as a reference position, or set coordinate data for that point.

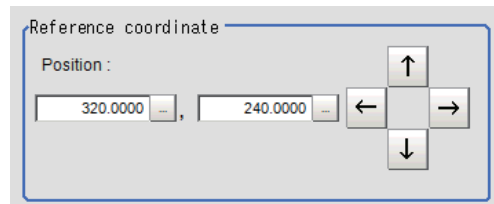
- 1 In the Item Tab area, click [Ref. setting].**
In the display area, the current reference position will be displayed as the crosshair cursor.
- 2 In the "Method" area, select "Numerical".**
- 3 Click the position to be set as the reference.**



Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

- 4 Make fine adjustments using numeric value inputs or the arrow buttons as required.



Reference coordinate

Position :

320.0000 , 240.0000

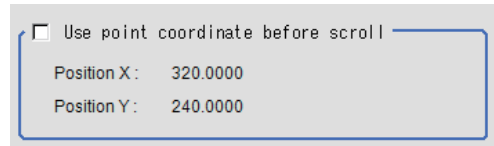
← →

↑ ↓

This panel contains two numeric input fields for X and Y coordinates, both showing 320.0000 and 240.0000 respectively. To the right of these fields are four arrow buttons (up, down, left, right) for fine-tuning the values.

- 5 To remeasure on the displayed image and set the reference, click the [Measure ref.] button.

- 6 To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".



Use point coordinate before scroll

Position X : 320.0000

Position Y : 240.0000

This panel features a checkbox labeled "Use point coordinate before scroll" which is currently unchecked. Below the checkbox, the current X and Y coordinates are displayed as 320.0000 and 240.0000.


Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

- 1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

- 2 In the "Method" area, select "Unit".

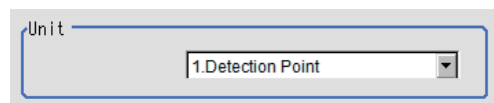


Method

Numerical Unit

This control allows selecting between "Numerical" and "Unit" methods. The "Unit" option is selected, indicated by a filled radio button.

- 3 In the scene in the "Unit" area, select a detection point unit.



Unit

1.Detection Point

This panel shows a dropdown menu for selecting a unit. The selected unit is "1.Detection Point".

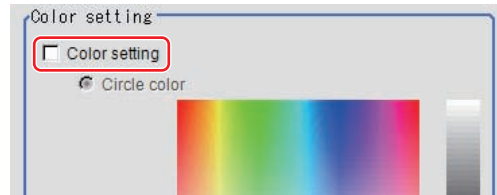
- 4 Perform the next measurement, and the reference will be displayed.

Color Specification (EC Circle Search)

This item can be changed if necessary.

Select the color of the circle and the background color. If no check is placed at color setting, the circle (edge) is extracted with the brightness difference.

- 1 In the Item Tab area, click [Color setting].
- 2 If necessary, check "Color setting" in the "Color setting" area.



- 3 Specify a color.

Enclose the location on the image to be set as the circle and the background color with a rectangle. The average color of the enclosed range is set for R, G, and B.

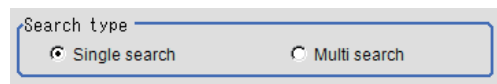
R, G, and B values can also be set with numbers. To input the values, click [...] for each of "R" (red), "G" (green), and "B" (blue). Specify the circle color and the background color separately.

Value input method: Reference: See the ► "Appendixes Basic Knowledge about Operations Inputting Values" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Measurement Parameters (EC Circle Search)

This item specifies the judgement conditions for measurement results. Specify to what degree OK is still judged in relation to measurement result coordinates (X,Y) and the circle evaluation value with the model.

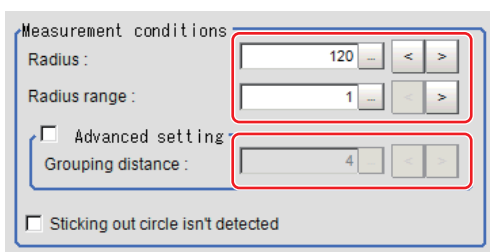
- 1 In the Item Tab area, click [Measurement].
- 2 Select the search type.



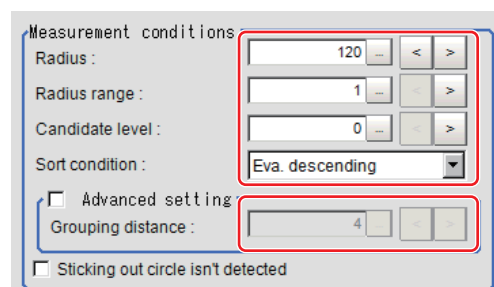
Setting item	Set value [Factory default]	Description
Search type	[Single search]	This is set when there is one circle in the measurement range.
	Multi search	This is set when there are multiple circles in the measurement range.

- 3 Set the measurement conditions.

For single search



For multi search

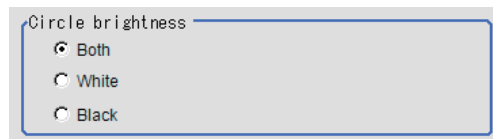


Setting item	Set value [Factory default]	Description
Radius	1 to 9999 [Radius drawn using circle resistor]	This item sets the radius of the circle measured. This is displayed on the screen with a solid blue line.

Setting item	Set value [Factory default]	Description
Radius range	[1] to 9999	This measures the measured circle radius \pm the permitted radius width. This is displayed on the screen with a broken blue line.
Candidate level (Multi search only)	[0] to 100	Specify the threshold value used when detecting candidate points in an EC circle search. Specify a smaller value when model search results are unstable.
Sort condition (Multi search only)	<ul style="list-style-type: none"> • X ascending • X descending • Y ascending • Y descending • Eva. ascending • [Eva. descending] • Radius ascending • Radius descending 	Specify the conditions by which label number is re-assigned. When sorting referencing the X and Y coordinates, the upper left is the origin.
Advanced setting	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check at setting the grouping distance.
Grouping distance	1 to 10 [4]	When circles measured overlap, this sets the distance for distinguishing circles. The smaller this value, the easier to distinguish circles.
Sticking out circle isn't detected	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check here to include circles within the range only.

For monochrome cameras:

For a monochrome camera only, the circle color parameters are displayed.



Setting item	Set value [Factory default]	Description
Circle brightness	<ul style="list-style-type: none"> • [Both] • White • Black 	This sets the circle color with the brightness.

4 Set up the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limits.

Setting item	Set value	Description
Measure pos X	-99999.9999 to 99999.9999	Specify the range of X-axis shifting that is judged to be OK.
Measure pos Y	-99999.9999 to 99999.9999	Specify the range of Y-axis shifting that is judged to be OK.
Evaluation	0 to 100	Specify the range of circle evaluated values that are judged to be OK.
Radius	0 to 99999.9999	Set the range of radiuses that is judged to be OK.
Search count	0 to 256	Specify the range of quantities that is judged to be OK.

5 Perform the display setting if required.

Setting item	Set value [Factory default]	Description
Display parameter	<ul style="list-style-type: none"> • [None] • Radius • Evaluation 	Select the type of measurement result to display on the image. The display setting applies only to the settings dialog box.

Output Parameters (EC Circle Search)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

1 Click [Output parameter] in the Item Tab area.

2 Specify a value for the items.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position deflection correction is applied.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to the overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgment.

Note

- For output coordinates and calibration, Reference: ▶ "Appendixes Measurement Mechanism Handling Coordinates" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Key Points for Test Measurement and Adjustment (EC Circle Search)

The following content is displayed in the "Detail result" area as text.

Displayed item	Description
Judge	Judgement result
Position X	X coordinate of the position where the model is detected
Position Y	Y coordinate of the position where the model is detected
Evaluation	Circle evaluated value of circles detected
Radius	Radius of circles detected
Search count	Quantity of circles detected

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Parameter to be adjusted	Processing
Measurement	If images that should be judged OK vary greatly, specify a smaller value for "Evaluation".
Circle setting	Mask any unnecessary items. Lower the edge level.

When the processing speed is slow

Parameter to be adjusted	Processing
Region setting	Make the search region as small as possible.
Measurement	If images that should be judged OK vary little, specify a larger value for "Evaluation".

Measurement Results for Which Output Is Possible (EC Circle Search)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Measurement coordinate X	X	X coordinate of the position where the circle is detected
Measurement coordinate Y	Y	Y coordinate of the position where the circle is detected
Reference position X	SX	X coordinate of the reference position of the registered circle
Reference position Y	SY	Y coordinate of the reference position of the registered circle
EC correlation value	CR	Evaluated value of circle detected
Radius	RA	Radius of circles detected
Count	CT	Quantity of circles detected
Position N	XN	Detected circle N position X (N = 0 to 255)
Position N	YN	Detected circle N position Y (N = 0 to 255)
Evaluation N	CRN	Detected circle N circle evaluated value (N = 0 to 255)
Radius N	RAN	Detected circle N circle radius (N = 0 to 255)

External Reference Tables (EC Circle Search)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Position X	Get only	-99999.9999 to 99999.9999
6	Position Y	Get only	-99999.9999 to 99999.9999
8	Reference coordinate X	Get only	-99999.9999 to 99999.9999
9	Reference coordinate Y	Get only	-99999.9999 to 99999.9999
15	Evaluation	Get only	0 to 100
18	Radius	Get only	0 to 99999.9999
19	Count	Get only	0 to 256

No.	Data name	Set/Get	Data range
101	Output coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
140	Reference X	Set/Get	0 to 9999
141	Reference Y	Set/Get	0 to 9999
142	Target	Set/Get	0: Black 1 : White 2: Black and white
143	Edge color specification	Set/Get	0: Yes 1: No
144	Circle color R	Set/Get	0 to 255
145	Circle color G	Set/Get	0 to 255
146	Circle color B	Set/Get	0 to 255
147	Background color R	Set/Get	0 to 255
148	Background color G	Set/Get	0 to 255
149	Background color B	Set/Get	0 to 255
150	Mask size	Set/Get	0: 3 × 3 1: 5 × 5 2: 7 × 7 3: 9 × 9
151	Edge level	Set/Get	0 to 255
153	Upper limit of position X	Set/Get	-99999.9999 to 99999.9999
154	Lower limit of position X	Set/Get	-99999.9999 to 99999.9999
155	Upper limit of position Y	Set/Get	-99999.9999 to 99999.9999
156	Lower limit of position Y	Set/Get	-99999.9999 to 99999.9999
159	Upper limit of evaluation	Set/Get	0 to 100
160	Lower limit of evaluation	Set/Get	0 to 100
161	Upper limit of count	Set/Get	0 to 256
162	Lower limit of count	Set/Get	0 to 256
165	Upper limit of radius	Set/Get	0 to 99999.9999
166	Lower limit of radius	Set/Get	0 to 99999.9999
171	Search type	Set/Get	0: Single search 1: Multi search
172	Candidate point level	Set/Get	0 to 100
173	Sort type	Set/Get	0: X ascending 1: X descending 2: Y ascending 3: Y descending 4: Eva. ascending 5: Eva. descending 6: Radius ascending 7: Radius descending
176	Grouping distance	Set/Get	1 to 10
177	Radius range	Set/Get	1 to 9999

No.	Data name	Set/Get	Data range
178	Radius	Set/Get	1 to 9999
180	Whether to exclude circles extruded from the range	Set/Get	0: Include 1: Exclude
1000 + N × 4 (N = 0 to 255)	Position X	Get only	-99999.9999 to 99999.9999
1001 + N × 4 (N = 0 to 255)	Position Y	Get only	-99999.9999 to 99999.9999
1002 + N × 4 (N = 0 to 255)	Evaluation	Get only	0 to 100
1003 + N × 4 (N = 0 to 255)	Radius	Get only	0 to 99999.9999

Shape Search II

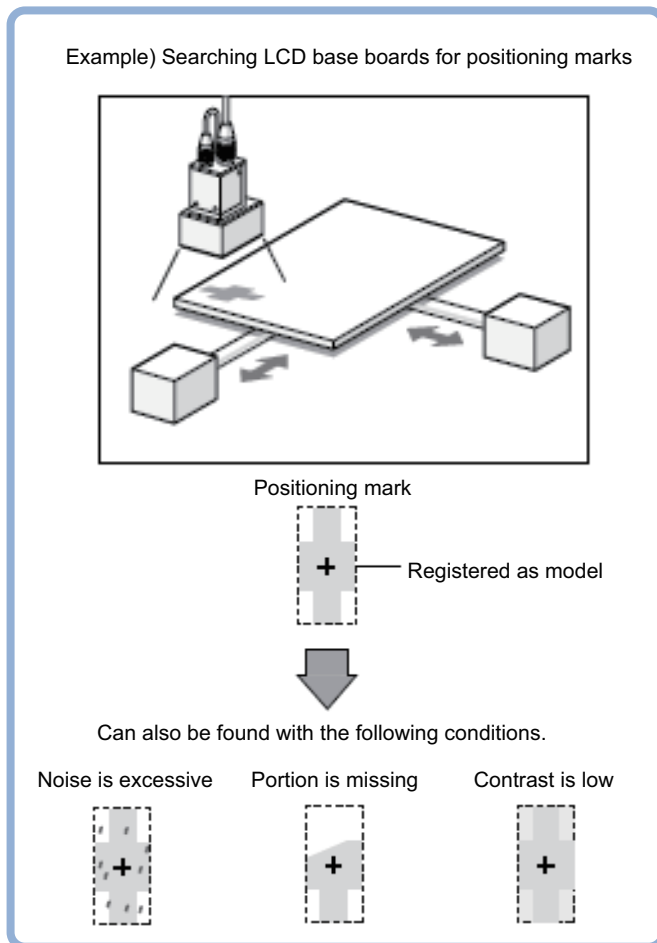
This function is for detecting user-defined target to estimate target position and pose precisely. The correlation value indicating the degree of similarity, measurement target position, and orientation can be output.

In shape search II, edge information is used as features, whereas in a normal search mode, color and texture information are used.

Since state-of-the-art object detection algorithm is exploited in shape search III, it can provides much more reliable position and pose estimation with higher speed compared to shape search II. Furthermore, it has much more parameter to tune to support a wider variety of applications.

Used in the Following Case

- Alignment mark detection and precise position estimation.



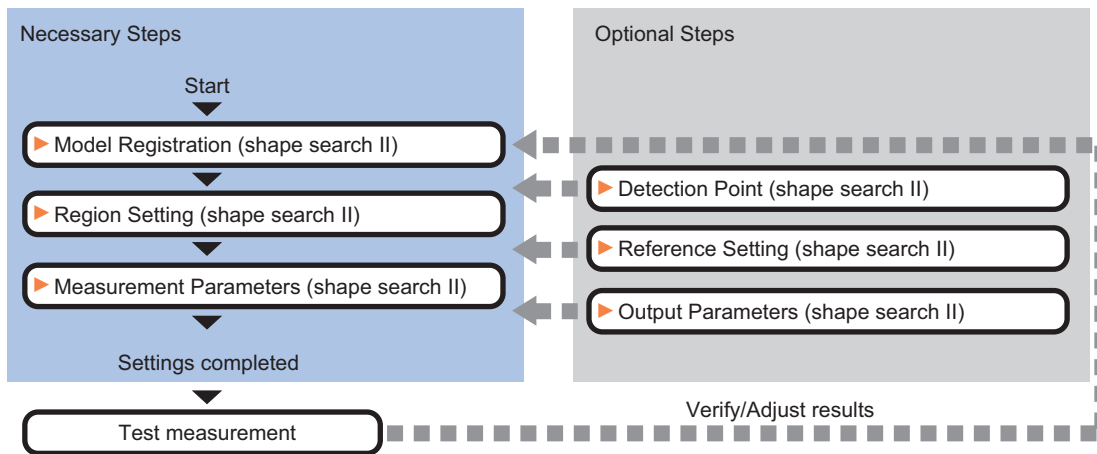
Note

- Search processing basic concepts

Reference: ▶ "Appendixes Measurement Mechanism Search Processing Mechanism" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Settings Flow (Shape Search II)

Set up shape search II according to the following steps.



List of Shape Search II Items

Item name	Description
Model	This item registers the pattern characteristic of the measurement image as a model. Change the model parameter (black and white reverse) as necessary. Reference: ▶ Model Registration (Shape Search II) (p.129)
Region setting	This item is used to set up the measurement area. Instead of measuring the entire input image, narrowing the measurement area shortens the processing time. Reference: ▶ Region Setting (Shape Search II) (p.130)
Detection point	This item can be changed if necessary. Specify a position in the model that should be used as the detection coordinates during measurement. Usually, the central position of the set model is registered as the detection coordinates. Reference: ▶ Detection Point (Shape Search II) (p.130)
Ref. setting	This item can be changed if necessary. Specify the reference position within the camera's field of view. Reference: ▶ Reference Setting (Shape Search II) (p.131)
Measurement	This item specifies the judgement condition for measurement results. Specify the criteria to judge the measurement result if the X and Y coordinates and the correlation values with the model are OK. Reference: ▶ Measurement Parameters (Shape Search II) (p.133)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Shape Search II) (p.134)

Model Registration (Shape Search II)

Register the parts to measure as the model.

The model information includes the position of the model. So place the target in the correct position in the registration process.

1 Click [Model] tab.

When setting a new model, you do not have to click [Model]. The tab is already being selected.

2 Use the Drawing tools to specify the model registration range.

3 To save the entire image used for model registration, place a check at the "Save reg. model" option.



Note

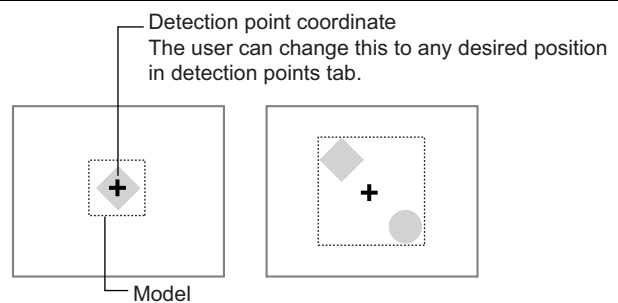
- If you save the registered model image, you can re-register the model with the same image after model parameters are adjusted. Note that the scene data size increases when a registered model image is saved.

4 Click [OK].

The model is registered.

Note

- When a model is registered, the central coordinates of the model are registered as the detection point. A detection point is a point output as a measurement value. If multiple targets are included in the same model, the detection points become the central coordinate of the bounding box that circumscribing these targets.

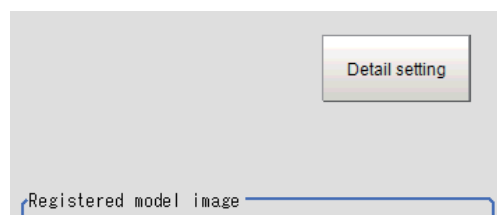


Changing model parameters

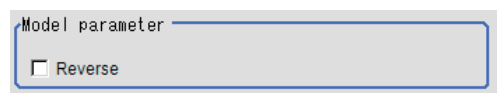
If the light and dark of the background and the workpiece, such as a shiny workpiece, reverses, specify the "Reverse" setting as necessary.

After changing a setting, re-register the model.

1 Click [Detail setting].



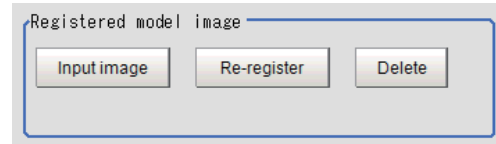
2 In the "Model parameter" area, set "Reverse".



Setting item	Set value [Factory default]	Description
Reverse	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Set whether to allow the reverse of light and dark for the model.

Displaying/Re-Registering/Deleting a Model

If you save the model registration image, it is easy to re-register the model after model parameters are changed.



Item	Description
Disp model/Input image	The model image display and input image display are switched.
Re-register	When model parameters are modified, display the original model image and re-register the model.
Delete	Deletes a model.

Region Setting (Shape Search II)

Use a rectangle to specify the area where the model is searched. Instead of measuring the entire input image, narrowing the measurement area shortens the processing time.

- 1 In the Item Tab area, click [Region setting].**
- 2 Click [Edit].**
The figure setting area is displayed.
- 3 Specify the model search range.**
The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.
- 4 Click [OK].**
The range to measure is registered.

Detection Point (Shape Search II)

Specify a position in the model that should be used as the detection coordinates during measurement. Usually, the center position of the set model is registered as the detection point. This function is used to change to any desired position.

A detection point can be set either directly or by referencing a unit.

Note

- After changing the detection point coordinates to another position, re-registering the model will change it back to the center coordinates of the model.

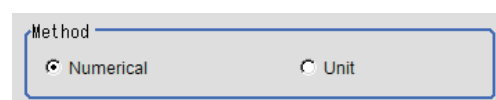
Specifying directly

Click a position on the image you want to use as a detection point, or set coordinate data for that point.

- 1 In the Item Tab area, click [Detection point].**
In the Display area, the current detection point is displayed with a crosshair cursor.



- 2 In the "Method" area, select "Numerical".**

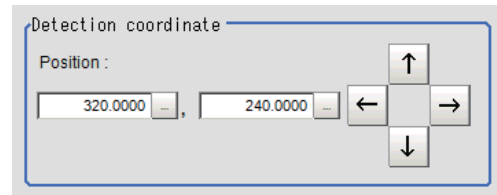


3 Click the position to be set as the detection point.

Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

4 Make fine adjustments using numeric value inputs or the arrow buttons as required.



Referencing a unit

Set a detection point by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

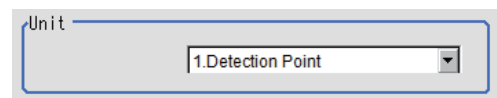
1 In the Item Tab area, click [Detection point].

In the Display area, the current detection point is displayed with a crosshair cursor.

2 In the "Method" area, select "Unit".



3 In the scene in the "Unit" area, select a detection point unit.



4 Perform the next measurement, and the detection point will be displayed.

Reference Setting (Shape Search II)

When the model is set, this position is automatically set at the same time as the reference position. This item can be set to change the reference position to any desired position. This is handy for measuring the position deviation from a certain position.

A reference position can be set either directly or by referencing a unit.

Specifying directly

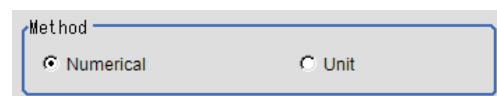
Click a position on the image you want to use as a reference position, or set coordinate data for that point.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.



2 In the "Method" area, select "Numerical".

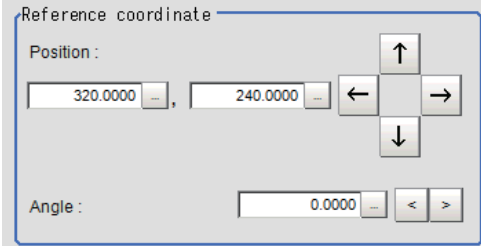


3 Click the position to be set as the reference.

Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

4 Make fine adjustments using numeric value inputs or the arrow buttons as required.



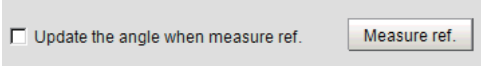
Reference coordinate

Position : ,

Angle :

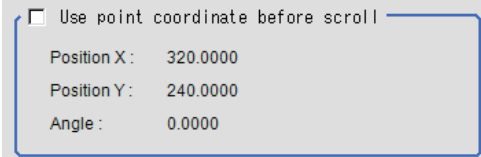
5 Set the reference angle with a numeric value.

6 To remeasure on the displayed image and set the reference, click the [Measure ref.] button. To update the reference angle at the time of reference measurement, place a check at "Update the angle when measure ref.".



Update the angle when measure ref.

7 To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".



Use point coordinate before scroll

Position X : 320.0000
Position Y : 240.0000
Angle : 0.0000

Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

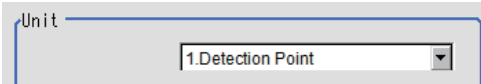
2 In the "Method" area, select "Unit".



Method

Numerical Unit

3 In the scene in the "Unit" area, select a detection point unit.



Unit

4 Perform the next measurement, and the reference will be displayed.

Measurement Parameters (Shape Search II)

Specify the search measurement conditions and the judgement conditions for the measurement results.

- 1 In the Item Tab area, click [Measurement].
- 2 In the "Measurement condition" area, specify a value for each parameter.

Setting item	Set value [Factory default]	Description
Candidate LV	0 to 100 [50]	Specify the threshold value with which to detect candidate points in a rough search. Specify a smaller value when the detection is unstable.
High-Prec.	<ul style="list-style-type: none"> • Checked • [Unchecked] 	"High-Prec" mode enables sub-pixel and sub-degree order position and pose estimation. There is just a slight increase of processing time.
Rotation	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Select the parameter when the target may be rotated and set appropriate range in "Angle range".
Angle range	-180 to 180 [-180] to [180]	Specify the angle range when "Rotation" is checked.

When executing a multi search

Setting item	Set value [Factory default]	Description
Multiple output	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Check this parameter enables multiple target detection.
Count	1 to 32 [32]	Specify the maximum number of detections.
Sort condition	<ul style="list-style-type: none"> • Corr. ascending • [Corr. descending] • X ascending • X descending • Y ascending • Y descending 	Specify the method by which the search number is re-assigned. When sorting based on the X and Y coordinates, the upper left is the origin.
Search No.	0 to 31 [0]	Specify which of the multiple detection results will be used as measured results.

- 3 When the setting has been changed, click [Measure] in the "Detail" area to verify whether measurements can be made correctly.
- 4 Set up the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Set value [Factory default]	Description
Count	0 to 32 [0] to [32]	Specify the number of detections that are judged to be OK.
Measure X	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Specify the range of X-axis shifting that is judged to be OK.
Measure Y	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Specify the range of Y-axis shifting that is judged to be OK.
Search angle θ	-180 to 180 [-180] to [180]	Specify the range of angles that are judged to be OK.
Correlation	0 to 100 [60] to [100]	Specify the range of correlation values that are judged to be OK. However, when the correlation value of the measurement result is 0, the judgement result will be NG regardless of the lower limit setting.

Output Parameters (Shape Search II)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	Select output coordinate for external devices. If "after scroll" is chose here shape search III outputs coordinates after position compensation.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (Shape Search II)

The following content is displayed in the "Detail result" area as text.

Important

- Executing test measurements will update the measurement results and the figures in the image.

Displayed items	Description
Judge	Judgement result
Count	Number of detections
Correlation	Correlation value
Position X	X coordinate of the position where the model is detected
Position Y	Y coordinate of the position where the model is detected
Angle	Angle of the position where the model is detected

The image specified in the sub image in image display setting is displayed in the Image Display area.

Sub image number.	Explanation of image to be displayed
0	Measurement image

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Searching other positions

Parameter to be adjusted	Remedy
Measurement parameter	If the precision is low, check "High-Prec."
	If detection or resulting judgement are unstable, set a smaller value for "Candidate LV", specify a smaller value for "Candidate LV".

The judgement is NG (insufficient memory)

Parameter to be adjusted	Remedy
Region setting	Make the search region as small as possible.

When the processing speed is slow

Parameter to be adjusted	Remedy
Region setting	Make the search region as small as possible.
Model registration	Make the area to register as the model as small as possible.
Measurement parameter	If images that should be judged OK vary little, specify a larger value for "Candidate LV".
	If the position precision is high, uncheck "High-Prec."

Measurement Results for Which Output Is Possible (Shape Search II)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Count	C	Number of search items detected If none detected, 0
Correlation	CR	Correlation value with the model
Position X	X	X coordinate of the position where the model is detected
Position Y	Y	Y coordinate of the position where the model is detected
Angle θ	TH	Angle of the position where the model is detected
Ref. position X	SX	X coordinate of the reference position of the registered model
Ref. position Y	SY	Y coordinate of the reference position of the registered model
Ref. angle	ST	Angle of the registered model
Detection point RX	RX	X coordinate of the registered model
Detection point RY	RY	Y coordinate of the registered model
Correlation value N (N = 00 to 31)	CRN	Detected search N correlation value (N = 00 to 31)
Position XN (N = 00 to 31)	XN	Detected search N position X (N = 00 to 31)
Position YN (N = 00 to 31)	YN	Detected search N position Y (N = 00 to 31)
Angle THN (N = 00 to 31)	THN	Detected search N angle TH (N = 00 to 31)

External Reference Tables (Shape Search II)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Correlation value	Get only	0 to 100
6	Measurement coordinate X	Get only	-99999.9999 to 99999.9999
7	Measurement coordinate Y	Get only	-99999.9999 to 99999.9999
8	Measurement angle	Get only	-180 to 180
9	Reference coordinate X	Get only	-99999.9999 to 99999.9999
10	Reference coordinate Y	Get only	-99999.9999 to 99999.9999
11	Reference angle	Get only	-180 to 180
12	Detection coordinate X	Get only	-99999.9999 to 99999.9999
13	Detection coordinate Y	Get only	-99999.9999 to 99999.9999
14	Number of detections	Get only	0 to 32
101	Output coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF

No.	Data name	Set/Get	Data range
120	With rotation	Set/Get	0: OFF 1: ON
121	Upper limit value of the rotation angle	Set/Get	-180 to 180
122	Lower limit value of the rotation angle	Set/Get	-180 to 180
124	Reverse	Set/Get	0: Do not allow black and white reverse 1: Allow black and white reverse
126	High-Prec.	Set/Get	0: OFF 1: ON
127	Reference position X	Set/Get	0.0000 to 9999.0000
128	Reference position Y	Set/Get	0.0000 to 9999.0000
133	Candidate point level	Set/Get	0 to 100
134	Detection point X	Set/Get	0.0000 to 9999.0000
135	Detection point Y	Set/Get	0.0000 to 9999.0000
136	Sort condition	Set/Get	0: Correlation value ascending 1: Correlation value descending 2: Measurement coordinate X ascending 3: Measurement coordinate X descending 4: Measurement coordinate Y ascending 5: Measurement coordinate Y descending
137	Search No.	Set/Get	0 to 31
138	Judgement upper limit for correlation value	Set/Get	0 to 100
139	Judgement lower limit for correlation value	Set/Get	0 to 100
140	Judgement upper limit for number of detections	Set/Get	0 to 32
141	Judgement lower limit for number of detections	Set/Get	0 to 32
142	Judgement upper limit for measurement coordinate X	Set/Get	-99999.9999 to 99999.9999
143	Judgement lower limit for measurement coordinate X	Set/Get	-99999.9999 to 99999.9999
144	Judgement upper limit for measurement coordinate Y	Set/Get	-99999.9999 to 99999.9999
145	Judgement lower limit for measurement coordinate Y	Set/Get	-99999.9999 to 99999.9999
146	Judgement upper limit for measurement angle	Set/Get	-180 to 180
147	Judgement lower limit for measurement angle	Set/Get	-180 to 180
161	Number of detections	Set/Get	0 to 32
168	Multiple output	Set/Get	0: OFF 1: ON
171	Save the model registration image	Set/Get	0: None 1: Save
1000 + NN (NN = 0 to 31)	Correlation value	Get only	0 to 100

No.	Data name	Set/Get	Data range
1100 + NN (NN = 0 to 31)	Measurement X	Get only	-99999.9999 to 99999.9999
1200 + NN (NN = 0 to 31)	Measurement Y	Get only	-99999.9999 to 99999.9999
1300 + NN (NN = 0 to 31)	Measurement angle	Get only	-180 to 180

Shape Search III

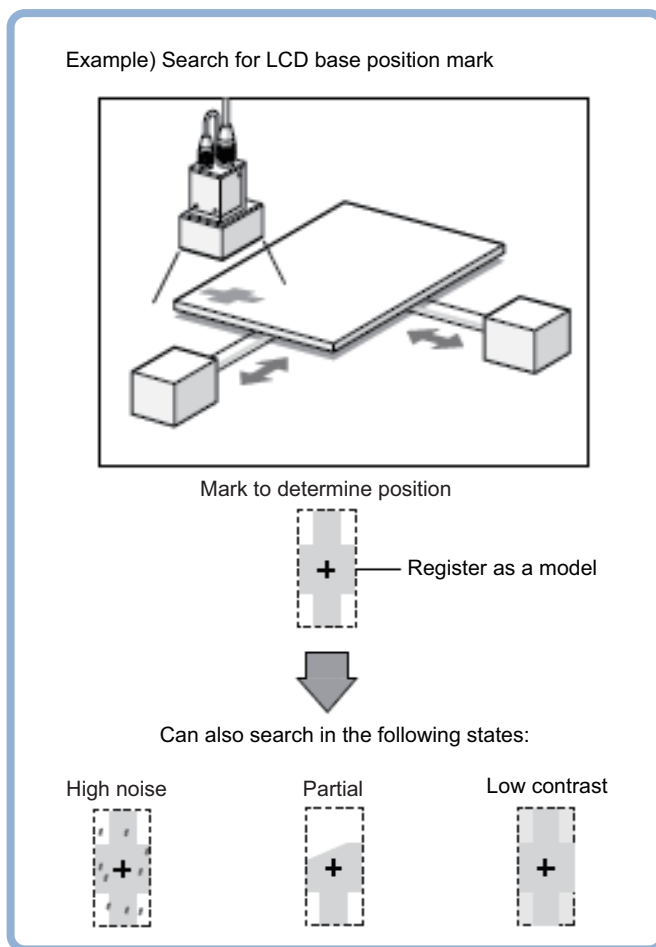
This function is for detecting user-defined target to estimate target position and pose precisely. The correlation value indicating the degree of similarity, measurement target position, and orientation can be output. In shape search III, edge information is used as features, whereas in a normal search mode, color and texture information are used.

It enables highly robust and fast detection robust to environmental variations including shadings, reflections, lightings, shape deformations, pose and noises.

Since state-of-the-art object detection algorithm is exploited in shape search III, it can provide much more reliable position and pose estimation with higher speed compared to shape search II. Furthermore, it has much more parameter to tune to support a wider variety of applications.

Used in the Following Case

- Alignment mark detection and precise position estimation.



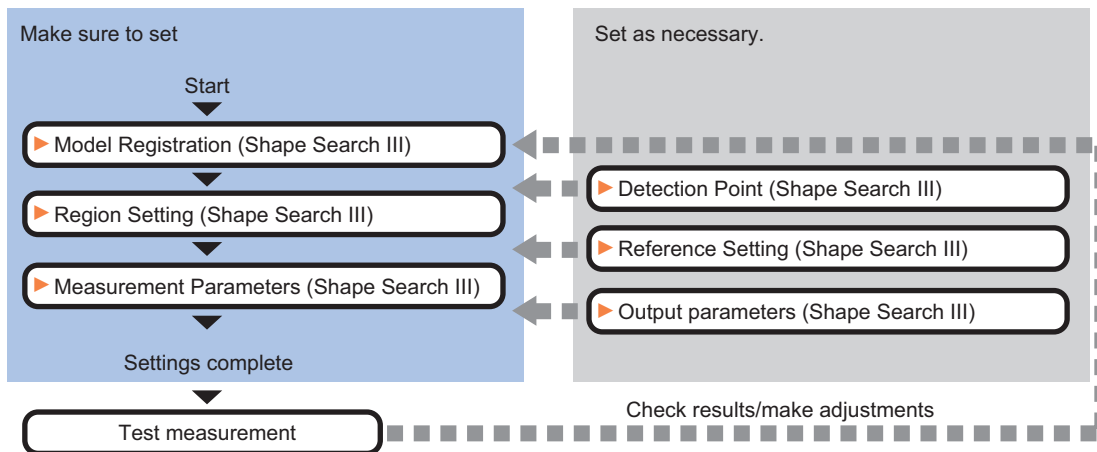
Note

- Search processing basic concepts

Reference: ▶ "Appendixes Measurement Mechanism Search Processing Mechanism" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Settings Flow (Shape Search III)

Set up shape search III according to the following steps.



List of Shape Search III Items

Item name	Description
Model	This item registers the pattern characteristic of the measurement image as a model. It changes the model parameter as necessary. Reference: ▶ Model Registration (Shape Search III) (p.141)
Region setting	This item is used to set up the measurement area. Instead of measuring the entire input image, narrowing the measurement area shortens the processing time. Reference: ▶ Region Setting (Shape Search III) (p.146)
Detection point	This item can be changed if necessary. It sets a position in the model that should be used as the detection coordinates during measurement. Usually, the central position of the set model is registered as the detection coordinates. Reference: ▶ Detection Point (Shape Search III) (p.146)
Ref. setting	This item can be changed if necessary. It sets the reference position within the camera's field of view. Reference: ▶ Reference Setting (Shape Search III) (p.147)
Measurement	This item specifies the judgement condition for measurement results. Specify the criteria to judge the measurement result if the X and Y coordinates and the correlation values with the model are OK. Reference: ▶ Measurement Parameters (Shape Search III) (p.149)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Shape Search III) (p.152)

Model Registration (Shape Search III)

Register the parts to measure as the model.

The model information includes the position of the model. So place the target in the correct position in the registration process.

1 Click [Model] tab.

When setting a new model, you do not have to click [Model].
The tab is already being selected.

2 Click [Edit].

3 Use the Drawing tools to set the model registration range.

4 To save the entire image used for model registration, place a check at the "Save reg. model" option.



Note

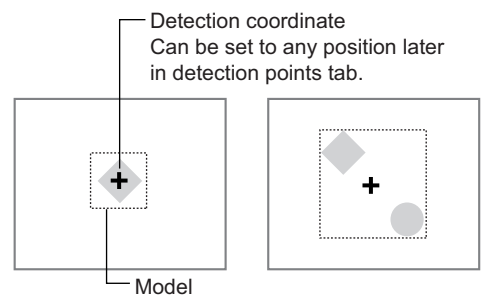
- If you save the registered model image, you can re-register the model with the same image after model parameters are adjusted. Note that the scene data size increases when a registered model image is saved.

5 Click [OK].

The model is registered.

Note

- When a model is registered, the central coordinates of the model are registered as the detection point. A detection point is a point output as a measurement value. If multiple targets are included in the same model, the detection points become the central coordinate of the bounding box that circumscribing these targets.



Creating a Model through image generation

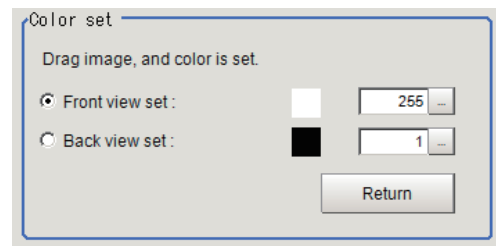
This function enables ideal shape registration through image generation.

- 1 In the "Input type" area, select "Create image".
- 2 Set each item in the "Figure type" area.

Setting item	Setting value [Factory default]	Description
Figure type	<ul style="list-style-type: none"> • [Cross] • Circle • Rectangle • Diamond 	Select the type of figure to be used for the generated image model.
Empty middle	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Select whether or not to make the generated image hollow. Select the setting according to the shape of the detection object.
Offset	0 to 99 [5]	Set how much margins will be provided for the model when it is registered. Set a value that is larger than the smooth count. If you set a rotation angle, increase the value even more. Model registration will not be possible if the model region extends beyond the image. If that occurs, reduce the value.
Smooth count	0 to 9 [1]	Set the level of smoothing applied to the generated figure according to the condition of the outline of the detection object. If the outline is clear, reduce the value. If the outline is not clear, increase the value.
Equal XY	<ul style="list-style-type: none"> • Checked • [Unchecked] 	If you place a check here, the length and width settings will become the same for X and Y.

Setting item	Setting value [Factory default]	Description
Outside (Cross) Length X (Cross) Length Y (Cross) Width X (Cross) Width Y (Circle) Radius (Rectangle) Length X (Rectangle) Length Y (Diamond) Length X (Diamond) Length Y	0 to 9999 [100] [100] [20] [20] [50] [100] [50] [100] [50]	Set the dimensions of the outline of the figure to be generated.
Middle (Cross) Length X (Cross) Length Y (Cross) Width X (Cross) Width Y (Circle) Radius (Rectangle) Length X (Rectangle) Length Y (Diamond) Length X (Diamond) Length Y	0 to 9999 [80] [80] [10] [10] [25] [50] [25] [50] [25]	Set the dimensions of the hollow part of the figure to be generated.

3 Click "Color set" to set the colors of the generated image.



Setting item	Setting value [Factory default]	Description
Color set	<ul style="list-style-type: none"> • [Front view set] • Back view set 	Drag the image, and the brightness information set here will be updated.
Front view set	1 to 255 [255]	Set the foreground color of the generated image.
Back view set	1 to 255 [1]	Set the background color of the generated image.

4 On the image, click the position you want to use as the center coordinate of the figure to be generated.

Fine adjustments are possible in the "Specify center coordinate" group.

5 Click [Regist].

6 To save the generated image, click "Save image".

7 Click [OK].

Model registration is finished successfully.

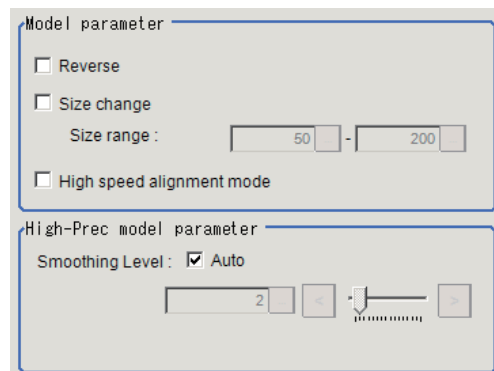
Changing Model Parameters

Tuning model parameters enables improvement of unstable detection or faster processing.

1 Click [Detail setting].



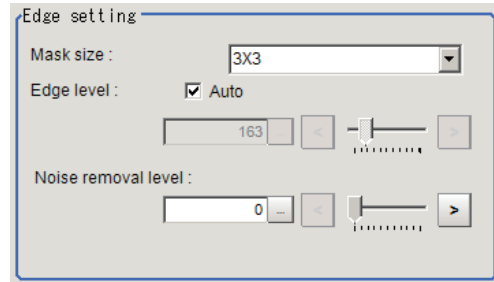
2 In the "Model parameter" area, set each item.



Setting item	Setting value [Factory default]	Description
Reverse	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Select whether to accept inversion of dark and bright area in the model.
Size change	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Select whether to allow size change.
Size range	50 to 200 [50] to [200]	Set the range of size change.
Smoothing Level	1 to 16 [4]	Set the level of smoothing for precise search. The image becomes more robust to external disturbances such as noise and blur. as the value increases, however at the same time, the detailed features are more likely to be lost.
Smoothing Level: Auto	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Select whether or not to automatically determine smoothing level.
High speed alignment mode	<ul style="list-style-type: none"> • Checked • [Unchecked] 	If the parameter is checked, high-speed processing is enabled. Note that this features are effective only for simple shapes such as alignment marks. If there are many edges coming from many textures, it may result in unstable detection or position/pose estimates.

Changing the Edge Extraction Setting

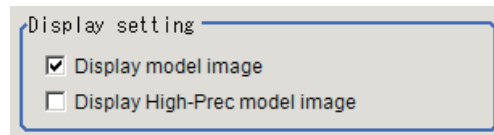
1 Set the items in the "Edge setting" area.



Setting item	Setting value [Factory default]	Description
Mask size	<ul style="list-style-type: none"> • [3 × 3] • 5 × 5 • 7 × 7 	Select the size of kernels used in edge extraction. Larger mask size are effective for extracting blurred or low contrast edges.
Edge level	0 to 1024	Change this when the edge is hard to see due to low contrast against the background or when unnecessary background noise must be removed. The smaller the value, the easier it is to find edges. The larger the value, the less noise will affect finding edges.
Edge level: Auto	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Select whether or not to automatically determine the edge level.
Noise removal level	0 to 100 [0]	Specify the level to which detailed features are removed in model registration process. In the noise removal process, edges are connected and divided into a set of groups of line segments, and then these line segments are removed one by one from shorter segments according to the value. Setting a larger value removes longer line segments.

Changing Display Settings

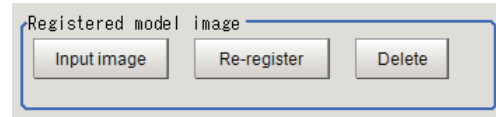
1 In the "Display setting" area, set the items.



Setting item	Setting value [Factory default]	Description
Display model image	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Display model images.
Display High-Prec model image	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Display high-precision model images.

Displaying/Re-Registering/Deleting a Model

If you save the model registration image, it is easy to re-register the model after model parameters are changed.



Item	Description
Disp model/Input image	Switches the model image view and input image view.
Re-register	Select "Disp. model" above and then tune parameters and click this button to re-register the model.
Delete	Deletes a model.

Region Setting (Shape Search III)

Use a rectangle to set the area where the model is searched.

Instead of measuring the entire input image, narrowing the measurement area reduces the processing time.

1 In the Item Tab area, click [Region setting].

2 Click [Edit].

The figure setting area is displayed.

3 Set the area in which to search for the model.

The rectangle covering the entire image region is set. Adjust the size and position of the rectangle.

4 Click [OK].

The area to measure is registered.

Detection Point (Shape Search III)

It sets a position in the model that should be used as the detection result coordinates during measurement. In default setting, the center position of the set model is registered as the detection point. This function is used to change to any desired position.

The detection point can either be set directly, or by referring to a unit.

Note

- After changing the detection point coordinates to another position, re-registering the model will change it back to the center coordinates of the model.

Specifying directly

Click a position on the image you want to use as a detection point, or input coordinate data for that point.

1 In the Item Tab area, click [Detection point].

In the Display area, the current detection point is displayed with a crosshair cursor.



2 In the "Method" area, select "Numerical".

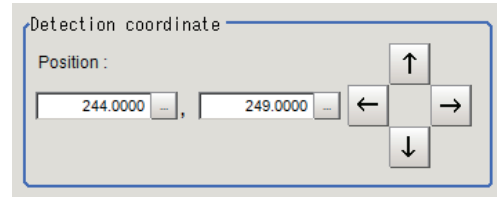


3 Click the position to be set as the detection point.

Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

- 4 Make fine adjustments using numeric value inputs or the arrow buttons as required.**



Referencing a unit

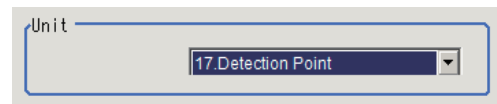
Set a detection point by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

- 1 In the Item Tab area, click [Detection point].**
In the Display area, the current detection point is displayed with a crosshair cursor.

- 2 In the "Method" area, select "Unit".**



- 3 In the scene in the "Unit" area, select a detection point unit.**



- 4 Perform the next measurement, and the detection point will be displayed.**

Reference Setting (Shape Search III)

When the model is set, this position is automatically set at the same time as the reference position. This item can be set to change the reference position to any desired position. This is handy for measuring the position deviation from a certain position.

A reference position can be set either directly or by referencing a unit.

Specifying directly

Click a position on the image you want to use as a reference position, or input coordinate data for that point.

- 1 In the Item Tab area, click [Ref. setting].**
In the display area, the current reference position will be displayed as the crosshair cursor.



- 2 In the "Method" area, select "Numerical".**

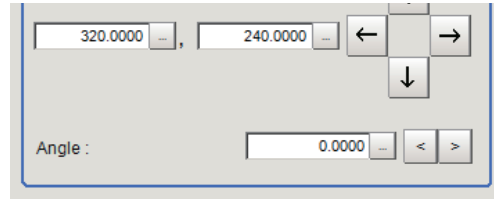


- 3 Click the position to be set as the reference.**

Note

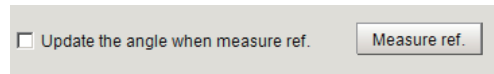
- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

4 Make fine adjustments using numeric value inputs or the arrow buttons as required.

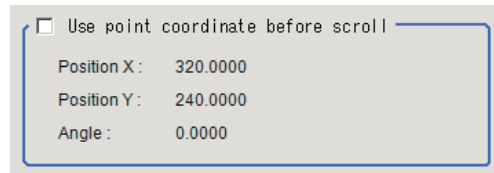


5 Set the reference angle with a numeric value.

6 To remeasure on the displayed image and set the reference, click the [Measure ref.] button. To update the reference angle at the time of reference measurement, place a check at "Update the angle when measure ref.".



7 To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".



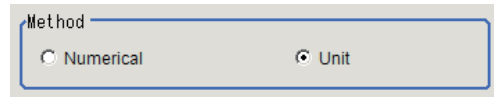
Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

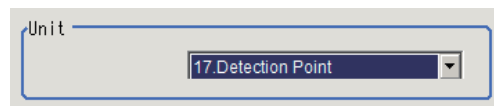
1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

2 In the "Method" area, select "Unit".



3 In the scene in the "Unit" area, select a detection point unit.

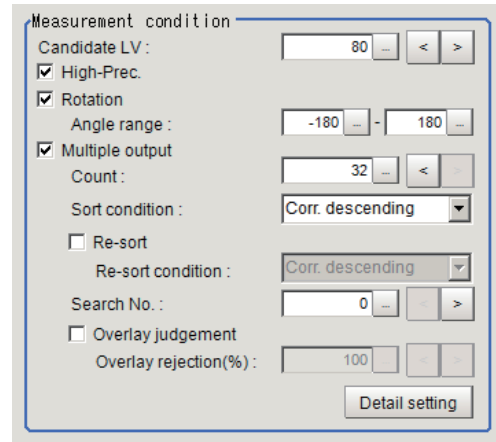


4 Perform the next measurement, and the reference will be displayed.

Measurement Parameters (Shape Search III)

Specify the search measurement conditions and the judgement conditions for the measurement results.

- 1 In the Item Tab area, click [Measurement].
- 2 In the "Measurement condition" area, specify a value for each item.



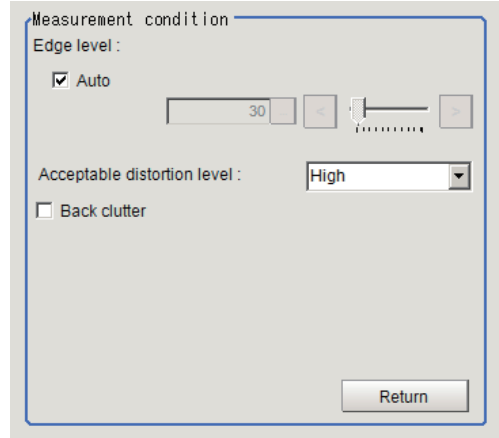
Setting item	Setting value [Factory default]	Description
Candidate LV	0 to 100 [50]	Specify the threshold value with which to detect candidate points in a rough search. Specify a smaller value when the detection is unstable.
High-Prec.	<ul style="list-style-type: none"> • [Checked] • Unchecked 	"High-Prec." mode enables sub-pixel and sub-degree order position and pose estimation. There is just a slight increase of processing time.
Rotation	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Select the parameter when the target may be rotated and set appropriate range in "Angle range".
Angle range	-180 to 180 [-180] to [180]	Specify the angle range when "Rotation" is checked.

When executing a multi search

Setting item	Setting value [Factory default]	Description
Multiple output	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Check this parameter enables multiple target detection.
Count	1 to 32 [32]	Specify the maximum number of detections. If it detects more objects than the specified value, these matches are sorted out to output up to the specified value from the top.
Sort condition	<ul style="list-style-type: none"> • Corr. ascending • [Corr. descending] • X ascending • X descending • Y ascending • Y descending 	Select the method by which the search number is re-assigned. When sorting based on the X and Y coordinates, the upper left is the origin.
Re-sort	<ul style="list-style-type: none"> • Checked • [Unchecked] 	This enable 2nd sort for the sorted results in the 1st step using the other condition. In this sort, only the data up to the number specified in "Count" parameter.
Re-sort condition	<ul style="list-style-type: none"> • Corr. ascending • [Corr. descending] • X ascending • X descending • Y ascending • Y descending 	Select the method for re-sort.

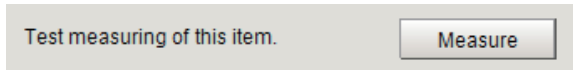
Setting item	Setting value [Factory default]	Description
Search No.	0 to 31 [0]	Specify which of the multiple detection results will be used as measured results.
Overlay judgement	<ul style="list-style-type: none"> • Checked • [Unchecked] 	If "Overlap judgement" is checked, overlapping results will be removed. The judgment is based on overlapping of rectangle surrounding each target.
Overlay rejection (%)	1 to 100 [100]	Set the degree to which overlaps are removed by overlap judgement.

3 When making the detailed settings, click "Detail setting" and set each item.



Setting item	Setting value [Factory default]	Description
Edge level: Auto Edge Level	<ul style="list-style-type: none"> • [Checked] • Unchecked 0 to 1024 [30]	Set the level to be recognized as an edge on the measurement image.
Acceptable distortion level	<ul style="list-style-type: none"> • Low • Medium • [High] 	Determine the sensitivity to edge distortion. If the parameter is set "high", the correlation value will not be damaged even when there is slight distortion.
Back clutter	<ul style="list-style-type: none"> • Checked • [Unchecked] 	If you place a check for "Complex background", measurement will become stable when the background has many edges. <div style="border: 1px solid black; padding: 2px; width: fit-content;"> Note </div> For the FZ5-L35□ or FZ5-6□□, a warning message will be displayed if you place a check here. If you place a check for [Back clutter], memory may not be sufficient. If the measurement result is [NG (insufficient memory)], perform the following adjustments to remedy the situation. <ul style="list-style-type: none"> • Make the measurement region smaller. (Reference: ▶ Region Setting (Shape Search III) (p.146)) • Increase the candidate level. (Reference: ▶ Model Registration (Shape Search III) (p.141)) • Decrease the range of the image that varies radically (Reference: ▶ Model Registration (Shape Search III) (p.141))

4 When the setting has been changed, click [Measure] in the "Detail" area to verify whether measurements can be made correctly.



5 Set up the judgement condition.

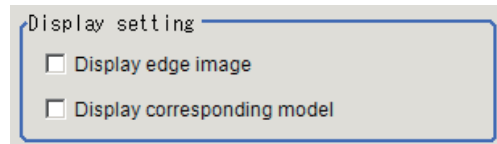
Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Setting value [Factory default]	Description
Count	0 to 32 [0] to [32]	Specify the number of detections that are judged to be OK.

Setting item	Setting value [Factory default]	Description
Measure X	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Specify the range of X coordinate position that is judged to be OK.
Measure Y	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Specify the range of Y coordinate position that is judged to be OK.
Search angle	-180 to 180 [-180] to [180]	Specify the range of angles that are judged to be OK.
Correlation	0 to 100 [60] to [100]	Specify the range of correlation values that are judged to be OK. However, when the correlation value of the measurement result is 0, the judgement result will be NG regardless of the lower limit setting.

6 Change the display settings as necessary.



Setting item	Setting value [Factory default]	Description
Display edge image	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check here to display an edge image.
Display corresponding model	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Check here to view local matching of edge features.

Output Parameters (Shape Search III)

Set how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- 1 Click [Output parameter] in Item Tab area.
- 2 Specify each of the following items.

Setting item	Setting value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	Select output coordinate for external devices. If "after scroll" is chose here shape search III outputs coordinates after position compensation.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Specify whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Shape Search III)

The following content is displayed in the "Detail result" area as text.

Important

- Executing test measurements will update the measurement results and the figures in the image.

Displayed items	Description
Judge	Judgement result
Count	Number of detections
Correlation	Correlation value
Position X	X coordinate of the position where the model is detected
Position Y	Y coordinate of the position where the model is detected
Angle θ	Angle of the position where the model is detected

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image.	Explanation of image to be displayed
0	Measurement image
1	Measurement image with detection results overlaid.
2	Edge image
3	Edge image with detection results overlaid. Green: Matched model points Yellow: Model points matched but with different directions Red: Unmatched model points

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Parameter to be adjusted	Troubleshooting
Measurement	If there are false detections, specify a larger value for "Candidate LV".
	If individual works vary significantly and the correlation value tends to be low, specify a "High" value for "Acceptable distortion level".
	If there are false detections on complicated patterns, raise "edge level" to prevent mis-match by noisy edges in the model.

Searching other positions

Parameter to be adjusted	Troubleshooting
Measurement	If the precision is low, check "High-Prec.".
	If detection or resulting judgement are unstable, set a smaller value for "Candidate LV".
	If the background has many edges, place a check at "Back clutter".

The judgement is NG (insufficient memory)

Parameter to be adjusted	Troubleshooting
Region setting	Make the search region as small as possible.

When the processing speed is slow

Parameter to be adjusted	Troubleshooting
Region setting	Make the search region as small as possible.

Parameter to be adjusted	Troubleshooting
Model register	Make the area to register as the model as large as possible.
	If the target pattern is simple shape, enable the "High speed alignment mode".
	When detecting circular, uncheck "Rotation".
	When detecting square, decrease the range between the upper and lower limits of "Angle".
Measurement	If correlation scores are stably high enough, specify a larger value for "Candidate LV".
	If the position precision is high enough, uncheck "High-Prec.".

Measurement Results for Which Output Is Possible (Shape Search III)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Number of detections	C	Number of search items detected If none detected, 0
Correlation value	CR	Correlation value with the model
Position X	X	X coordinate of the position where the model is detected
Position Y	Y	Y coordinate of the position where the model is detected
Angle θ	TH	Angle of the position where the model is detected
Reference X	SX	X coordinate of the reference position of the registered model
Reference Y	SY	Y coordinate of the reference position of the registered model
Reference angle	ST	Angle of the registered model
Detection point RX	RX	X coordinate of the registered model
Detection point RY	RY	Y coordinate of the registered model
Correlation value N (N = 00 to 31)	CRN	Detected search N correlation value (N = 00 to 31)
Position N (N = 00 to 31)	XN	Detected search N position X (N = 00 to 31)
Position N (N = 00 to 31)	YN	Detected search N position Y (N = 00 to 31)
Angle N (N = 00 to 31)	THN	Detected search N angle TH (N = 00 to 31)

External Reference Tables (Shape Search III)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Correlation value	Get only	0 to 100
6	Position X	Get only	-99999.9999 to 99999.9999
7	Position Y	Get only	-99999.9999 to 99999.9999
8	Measure angle	Get only	-180 to 180
9	Reference X	Get only	-99999.9999 to 99999.9999
10	Reference Y	Get only	-99999.9999 to 99999.9999
11	Reference angle	Get only	-180 to 180

No.	Data name	Set/Get	Data range
12	Detection coordinate X	Get only	-99999.9999 to 99999.9999
13	Detection coordinate Y	Get only	-99999.9999 to 99999.9999
14	Number of detections	Get only	0 to 32
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	With rotation	Set/Get	0: OFF 1: ON
121	Upper limit of the rotation angle	Set/Get	-180 to 180
122	Lower limit of the rotation angle	Set/Get	-180 to 180
124	Reverse	Set/Get	0: Do not allow black and white reverse 1: Allow black and white reverse
126	High-Prec.	Set/Get	0: OFF 1: ON
127	Reference X	Set/Get	0.0000 to 9999.0000
128	Reference Y	Set/Get	0.0000 to 9999.0000
129	Reference angle θ	Set/Get	-180.0 to 180.0
130	With/without size change	Set/Get	0: OFF 1: ON
131	Upper limit of the size change	Set/Get	50 to 200(%)
132	Lower limit of the size change	Set/Get	50 to 200(%)
133	Candidate Point Level	Set/Get	0 to 100
134	Detection point X	Set/Get	0.0000 to 9999.0000
135	Detection point Y	Set/Get	0.0000 to 9999.0000
136	Sort condition	Set/Get	0: Correlation value ascending 1: Correlation value descending 2: Measurement coordinate X ascending 3: Measurement coordinate X descending 4: Measurement coordinate Y ascending 5: Measurement coordinate Y descending
137	Search No.	Set/Get	0 to 31
138	Judgement upper limit for correlation value	Set/Get	0 to 100
139	Judgement lower limit for correlation value	Set/Get	0 to 100
140	Judgement upper limit for number of detections	Set/Get	0 to 32
141	Judgement lower limit for number of detections	Set/Get	0 to 32

No.	Data name	Set/Get	Data range
142	Judgement upper limit for measurement coordinate X	Set/Get	-99999.9999 to 99999.9999
143	Judgement lower limit for measurement coordinate X	Set/Get	-99999.9999 to 99999.9999
144	Judgement upper limit for measurement coordinate Y	Set/Get	-99999.9999 to 99999.9999
145	Judgement lower limit for measurement coordinate Y	Set/Get	-99999.9999 to 99999.9999
146	Judgement upper limit for measurement angle	Set/Get	-180 to 180
147	Judgement lower limit for measurement angle	Set/Get	-180 to 180
150	Edge level (measurement)	Set/Get	0 to 1024
161	Number of detections	Set/Get	0 to 32
168	Multiple output	Set/Get	0: OFF 1: ON
171	Save registered model	Set/Get	0: None 1: Save
172	Edge level (measurement) auto setting	Set/Get	0: OFF 1: ON
173	High-speed alignment mode	Set/Get	0: OFF 1: ON
174	Filter size	Set/Get	0: 3 × 3 1: 5 × 5 2: 7 × 7
177	Smoothing level	Set/Get	1 to 16
178	Edge level (model) auto setting	Set/Get	0: OFF 1: ON
180	Allowable distortion level	Set/Get	0: Low 1: Medium 2: High
181	Noise removal level	Set/Get	0 to 100
182	Display search model image	Set/Get	0: OFF 1: ON
183	Complex background	Set/Get	0: OFF 1: ON
227	Re-sort	Set/Get	0: OFF 1: ON
228	Re-sort condition	Set/Get	0: Correlation value ascending 1: Correlation value descending 2: X ascending 3: X descending 4: Y ascending 5: Y descending

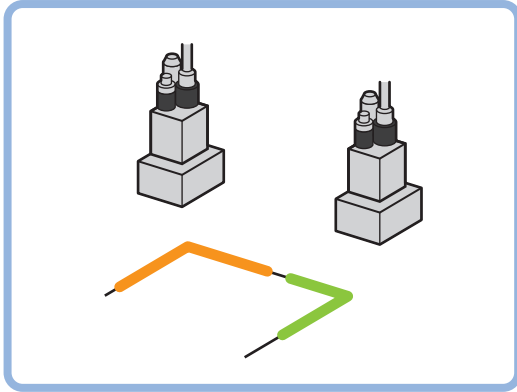
No.	Data name	Set/Get	Data range
229	Overlap judgement	Set/Get	0: OFF 1: ON
230	Allowable overlap ratio	Set/Get	1 to 100
231	Reference unit number for reference coordinate	Set/Get	-1 to 9999
232	Reference type of reference coordinate	Set/Get	0: Set by number 1: Unit reference
233	Reference angle update	Set/Get	0: Not update 1: Update
234	Reference unit number for detection point coordinate	Set/Get	-1 to 9999
235	Reference type of detection point coordinate	Set/Get	0: Set by number 1: Unit reference
236	Use coordinates before position compensation	Set/Get	0: Not used 1 : Used
237	Coordinate X before position compensation	Set/Get	-99999.9999 to 99999.9999
238	Coordinate Y before position compensation	Set/Get	-99999.9999 to 99999.9999
239	Angle before position compensation	Set/Get	-180 to 180
240	Rotation angle	Set/Get	-180 to 180
241	Outline length X of diamond	Set/Get	0 to 9999
242	Outline length Y of diamond	Set/Get	0 to 9999
243	Hollow length X of diamond	Set/Get	0 to 9999
244	Hollow length Y of diamond	Set/Get	0 to 9999
1000 + NN (NN = 0 to 31)	Correlation value	Get only	0 to 100
1100 + NN (NN = 0 to 31)	Position X	Get only	-99999.9999 to 99999.9999
1200 + NN (NN = 0 to 31)	Position Y	Get only	-99999.9999 to 99999.9999
1300 + NN (NN = 0 to 31)	Measure angle	Get only	-180 to 180

Ec Corner

This processing item measures a corner position (corner) of a work. The intersection of two lines generated from the edge information of two sides of a square work is measured. A desired corner can be measured by setting the length, direction, edge intensity and other conditions.

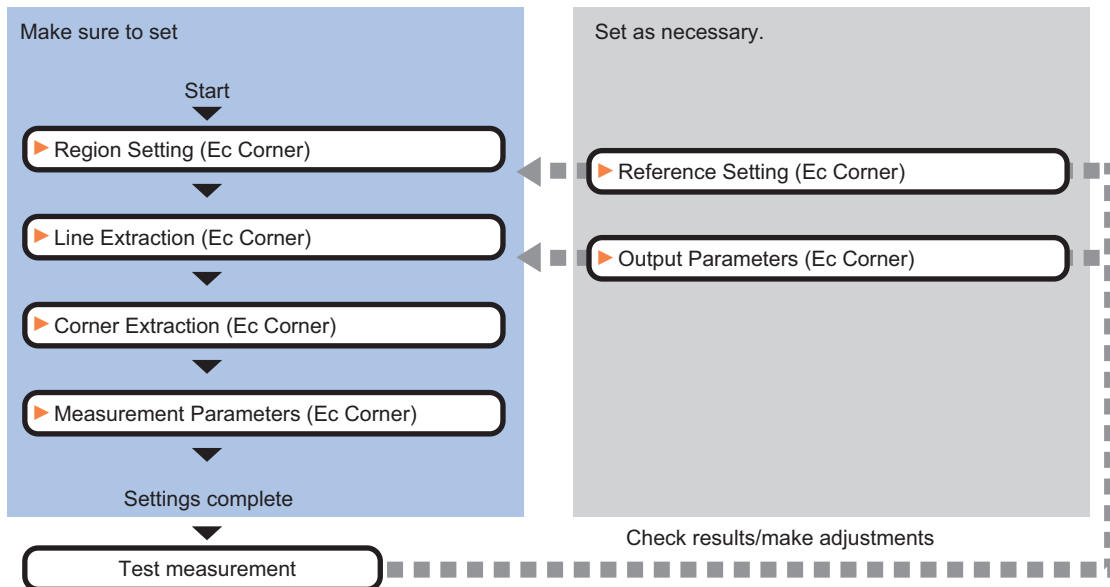
Used in the Following Case

- When you want to align the work position based on the feature of its corner



Settings Flow (Ec Corner)

Set up EC corner according to the following steps.



List of Ec Corner Items

Item name	Description
Region setting	This item is used to set up the measurement area. Reference: ▶ Region Setting (Ec Corner) (p.159)
Ref. setting	Change as necessary. This is changed when measuring the position deviation from a certain position. Reference: ▶ Reference Setting (Ec Corner) (p.160)
Line extraction	This item sets the conditions for extracting a line. Reference: ▶ Line Extraction (Ec Corner) (p.161)
Corner extraction	This item sets the conditions for extracting a corner. Reference: ▶ Corner Extraction (Ec Corner) (p.162)
Measurement	Set the sort conditions/judgement conditions of corners. Data of the specified number is output as measurement data. Reference: ▶ Measurement Parameters (Ec Corner) (p.164)
Output parameter	This item can be changed if necessary. Select the measurement result coordinates and set how to handle the coordinates. Reference: ▶ Output Parameters (Ec Corner) (p.165)

Region Setting (Ec Corner)

This item is used to set up the measurement area.

Use the rectangle to set up the measurement region for [Ec corner].

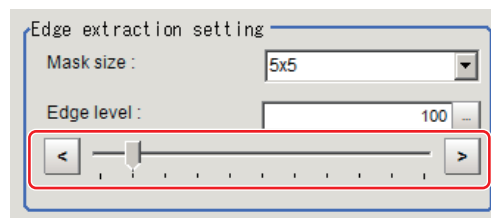
- 1 In the Item Tab area, click [Region setting].**
- 2 Use the drawing tools to set the measurement region.**

- 3 In the figure setting area, click [OK].**

The measurement region is registered and displayed in the Image Display area.

- 4 Click [Edge extraction], then confirm the edge extraction image.**

If the profile of the measurement object is interrupted or has too many edges, adjust the edge level.



Setting item	Setting value [Factory default]	Description
Mask size	<ul style="list-style-type: none"> • 3 × 3 • [5 × 5] • 7 × 7 • 9 × 9 	Select the range of pixels which are used to extract the edge. With a larger mask size, search is less affected by variation in pixels.
Edge level	0 to 1000 [100]	Change this when the edge is hard to see due to low contrast against the background or when unnecessary background noise must be removed. The smaller the value, the easier it is to find edges. The larger the value, the less noise will affect finding edges.

Reference Setting (Ec Corner)

When the model is set, this position is automatically set at the same time as the reference position. This item can be set to change the reference position to any desired position. This is handy for measuring the position deviation from a certain position.

A reference position can be set either directly or by referencing a unit.

Specifying directly

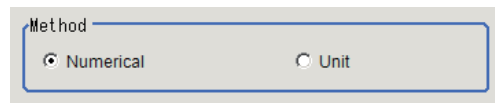
Click the position on the image that you want to set as the reference position, or set the coordinates.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.



2 In the "Method" area, select "Numerical".

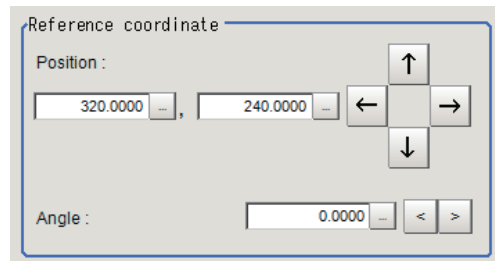


3 Click the position to be set as the reference.

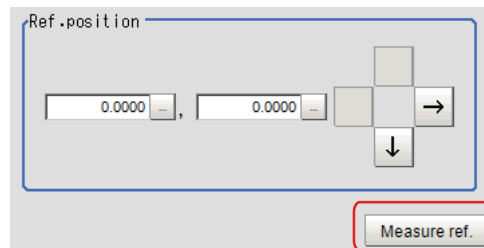
Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

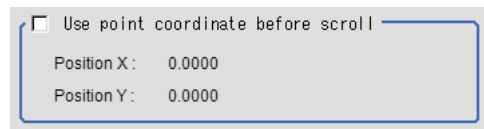
4 Make fine adjustments using numeric value inputs or the arrow buttons as required.



5 To remeasure on the displayed image and set the reference, click the [Measure ref.] button.



6 To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".



Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate and Y coordinate.

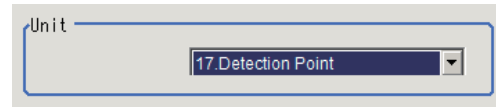
1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

2 In the "Method" area, select "Unit".



3 In the scene in the "Unit" area, select a detection point unit.



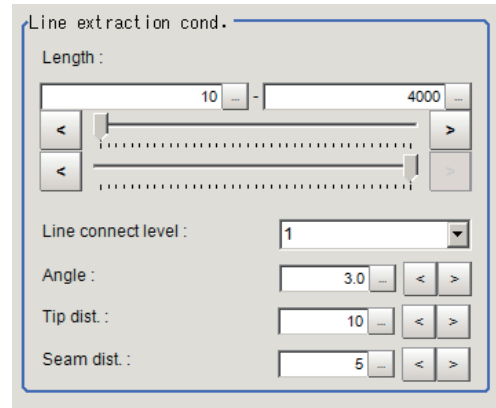
4 Perform the next measurement, and the reference will be displayed.

Line Extraction (Ec Corner)

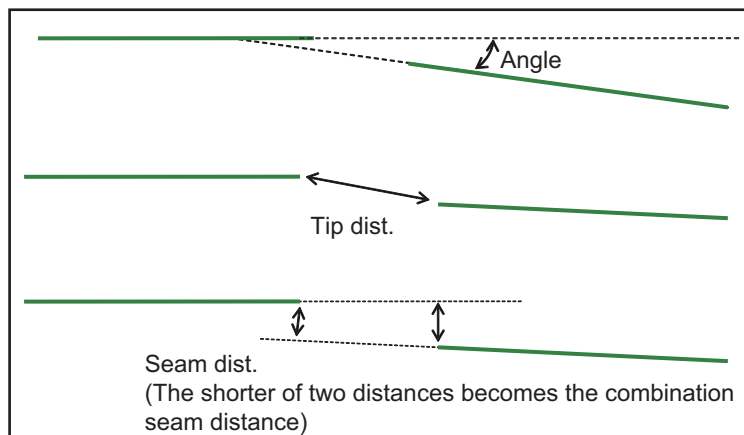
This item sets the conditions for extracting a line.

1 In the Item Tab area, click [Line extraction].

2 In the "Line extraction cond." area, set the conditions for extracting a line.



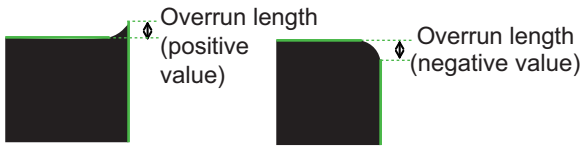
Setting item	Setting value [Factory default]	Description
Length	5 to 4000 [10] to [4000]	Set the length of edges to be extracted.
Line connect level	<ul style="list-style-type: none"> • [1] • 2 • 3 • 4 • 5 • Custom 	Select the degree to which fragmented lines detected by edge extraction are connected. The higher the level, the more likely the lines are connected.
Angle	0.0 to 30.0 [3.0]	Set the angle range to be used when two lines are connected. Increasing this value allows two lines of different inclinations to be connected.
Tip dist.	0 to 1000 [10]	Set the vertex distance to be used when two lines are connected. Increasing this value allows distant lines to be connected.
Seam dist.	0 to 1000 [5]	Set the distance condition to be used when two lines are connected, where an extension of one line comes closest to the vertex of the other line. Increasing this value allows lines offset vertically to the lines to be connected.



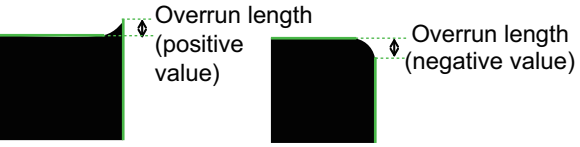
Corner Extraction (Ec Corner)

This item sets the conditions for extracting a corner.

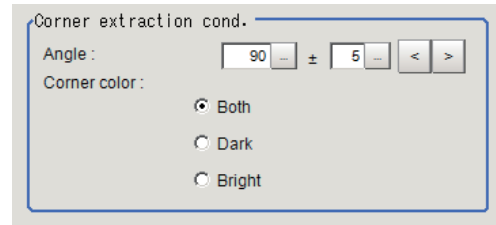
- 1 In the Item Tab area, click [Corner extraction].
- 2 In the "Line 0 cond." area, set the conditions for line 0.

Setting item	Setting value [Factory default]	Description
Length	5 to 4000 [10] to [4000]	Set the length for extracting line 0.
Angle	[0] to 359	Set the angle for extracting line 0.
Overrun	-1000 to 1000 [-10] to [10]	Set the length range to be used when specifying whether the tips of two lines that constitute a corner have penetrated through the corner or are not reaching the corner (unit: pix). If the tips have penetrated through the corner, the overrun length becomes a positive value; whereas, if the tips are not reaching the corner, the overrun length becomes a negative value. 

- 3 In the "Line 1 cond." area, set the conditions for line 1.

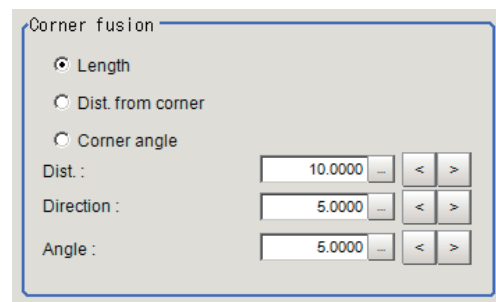
Setting item	Setting value [Factory default]	Description
Length	5 to 4000 [10] to [4000]	Set the length for extracting line 1.
Angle	[0] to 359	Set the angle for extracting line 1.
Overrun	-1000 to 1000 [-10] to [10]	Set the length range to be used when specifying whether the tips of two lines that constitute a corner have penetrated through the corner or are not reaching the corner (unit: pix). If the tips have penetrated through the corner, the overrun length becomes a positive value; whereas, if the tips are not reaching the corner, the overrun length becomes a negative value. 

4 In the "Corner extraction cond." area, set the conditions for corners.



Setting item	Setting value [Factory default]	Description
Angle	10 to 350 [90]	Set the angle range for a corner.
±	0 to 180 [5]	Set the margin of angle error.
Corner color	<ul style="list-style-type: none"> • [Both] • Dark • Bright 	Select the light/dark relationship of the corner and background.

5 If necessary, click [Advanced setting] and set the intersection fusion condition.



Setting item	Setting value [Factory default]	Description
Corner fusion	<ul style="list-style-type: none"> • Length • Dist. from corner • Corner angle 	<p>If all detected corners include two corners that each meet all of the three conditional relationships of "Fusion distance," "Fusion line angle range" and "Fusion corner angle range," fuse the corners into one according to the priorities specified below.</p> <p>Length: Keep the corner with the longer total length of the two lines constituting the corner.</p> <p>Dist. from corner: Keep the corner with the smaller total overrun of the two lines.</p> <p>Corner angle: Keep the corner whose angle formed by the two lines is closer to the "Angle range" set as a corner condition.</p>
Dist.	0 to 1000.0000 [10.0000]	Set the linear distance between the corners.
Direction	0 to 20.0000 [5.0000]	Set the difference between the angles formed by the two sets of lines constituting the corners.
Angle	0 to 20.0000 [5.0000]	Set the angle difference between the corners.

Measurement Parameters (Ec Corner)

Set the sort conditions/judgement conditions of corners.

Data of the specified number is output as measurement data.

- 1 In the Item Tab area, click [Measurement].
- 2 In the "Sort cond." area, set the sorting conditions.

Sort cond.

Order :

Ascendin Descendi

Corner No. :

Setting item	Setting value [Factory default]	Description
Order	<ul style="list-style-type: none"> • [Corner X] • Corner Y • Length 	Select the sorting method for the measurement results.
	<ul style="list-style-type: none"> • [Ascending] • Descending 	
Corner No.	[0] to 99	Set the corner number for the data to be output.

- 3 When the setting has been changed, click [Measure] to verify whether measurements can be made correctly.

Test measuring of this item.

- 4 Set up the judgement condition.

Setting item	Setting value [Factory default]	Description
Corner X	[-99999.9999] to [99999.9999]	Set the range of X coordinates of corner that is judged to be OK.
Corner Y	[-99999.9999] to [99999.9999]	Set the range of Y coordinates of corner that is judged to be OK.
Angle	[0.0000] to [360.0000]	Specify the formed angles that are judged to be OK.
Count	[1] to [100]	Specify the number of detections of corner that is judged to be OK.

Output Parameters (Ec Corner)

Set how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Setting value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Specify whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Ec Corner)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Corner X	X Coordinate of measured corner
Corner Y	Y coordinate of measured corner
Angle	Formed angle of measured corner
Number of detections	Number of detections of corner

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image.	Explanation of image to be displayed
0	Measurement image

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Parameter to be adjusted	Troubleshooting
Measurement	Reduce the distance between the upper and lower limits of line length range for extracting lines, to reduce false detections.
	Raise the line connection level to prevent the lines constituting the corners to be detected from being interrupted.
	Set the narrowest possible conditions for extracting corners, to reduce false detections.

When the processing speed is slow

Parameter to be adjusted	Troubleshooting
Region setting	Specify as small a value as possible for FigureInfo=Region.

Parameter to be adjusted	Troubleshooting
Measurement	Minimize the distance between the upper and lower limits of line length range for extracting lines.
	Minimize the distance between the upper and lower limits of overrun range for extracting corners.
	Minimize the distance between the upper and lower limits of length range for extracting corners.
	Minimize the distance between the upper and lower limits of angle range for extracting corners.

When judgement is NG

State	Parameter to be adjusted	Troubleshooting
There are lines but they are not detected	Corner extraction	Expand and extend the overrun range in both the positive direction and negative direction so that corners can be formed.

Measurement Results for Which Output Is Possible (Ec Corner)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Corner X	X	Corner coordinate X
Corner Y	Y	Corner coordinate Y
Angle	TH	Formed angle of measured corner
Number of detections	CT	Number of detections
Reference X	SX	Reference X
Reference Y	SY	Reference Y
Corner XN (N = 0 to 99)	XN	Corner coordinate XN
Corner YN (N = 0 to 99)	YN	Corner coordinate YN
Angle N (N = 0 to 99)	THN	Formed angle N of measured corner
Angle N of line 0 (N = 0 to 99)	DIRLN	Inclination N of line 0
Angle N of line 1 (N = 0 to 99)	DIRRN	Inclination N of line 1

External Reference Tables (Ec Corner)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Number of detections	Get only	0 to 100
6	Corner coordinate X	Get only	-99999.9999 to 99999.9999
7	Corner coordinate Y	Get only	-99999.9999 to 99999.9999
8	Angle	Get only	0 to 360
9	Reference position X coordinate	Get only	-99999.9999 to 99999.9999
10	Reference position Y coordinate	Get only	-99999.9999 to 99999.9999
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Edge level	Set/Get	0 to 1000
121	Filter size	Set/Get	0: 3 × 3 1: 5 × 5 2: 7 × 7 3: 9 × 9
122	Lower limit of line length	Set/Get	5 to 4000
123	Upper limit of line length	Set/Get	5 to 4000
124	Combination angle	Set/Get	0.0 to 30.0
125	Combination tip distance	Set/Get	0 to 1000
126	Combination seam distance	Set/Get	0 to 1000
127	Line 0 condition Lower limit of length range	Set/Get	5 to 4000
128	Line 0 condition Upper limit of length range	Set/Get	5 to 4000
129	Line 1 condition Lower limit of length range	Set/Get	5 to 4000
130	Line 1 condition Upper limit of length range	Set/Get	5 to 4000
131	Line 0 condition Line angle	Set/Get	0 to 359
132	Line 0 condition Line angle range	Set/Get	0 to 180
133	Line 1 condition Line angle	Set/Get	0 to 359
134	Line 1 condition Line angle range	Set/Get	0 to 180
135	Formed angle	Set/Get	10 to 350
136	Formed angle range	Set/Get	0 to 180

No.	Data name	Set/Get	Data range
137	Line 0 condition Lower limit of overrun range	Set/Get	-1000 to 1000
138	Line 0 condition Upper limit of overrun range	Set/Get	-1000 to 1000
139	Line 1 condition Lower limit of overrun range	Set/Get	-1000 to 1000
140	Line 1 condition Upper limit of overrun range	Set/Get	-1000 to 1000
141	Detection object color	Set/Get	0: Both 1: Corner (dark) - Background (light) 2: Corner (light) - Background (dark)
149	Sort order	Set/Get	0: Cross point X 1: Cross point Y 2: Line length
150	Sort sequence	Set/Get	0: Ascending 1: Descending
151	Output number	Set/Get	0 to 99
155	With/without intersection fusion	Set/Get	0: OFF 1: ON
156	Fusion distance	Set/Get	0 to 1000
157	Fusion line angle range	Set/Get	0 to 20
158	Fusion corner angle range	Set/Get	0 to 20
159	Intersection fusion condition	Set/Get	0: Priority on line length 1: Priority on distance from intersection 2: Priority on corner angle
160	Judgement condition: Lower limit of corner X	Set/Get	-99999.9999 to 99999.9999
161	Judgement condition: Upper limit of corner X	Set/Get	-99999.9999 to 99999.9999
162	Judgement condition: Lower limit of corner Y	Set/Get	-99999.9999 to 99999.9999
163	Judgement condition: Upper limit of corner Y	Set/Get	-99999.9999 to 99999.9999
164	Judgement condition: Lower limit of angle	Set/Get	0 to 360
165	Judgement condition: Upper limit of angle	Set/Get	0 to 360
166	Judgement condition: Lower limit of number of detections	Set/Get	0 to 100
167	Judgement condition: Upper limit of number of detections	Set/Get	0 to 100
168	Reference X	Set/Get	0 to 9999
169	Reference Y	Set/Get	0 to 9999
171	Line connection level	Set/Get	0: 1 1: 2 2: 3 3: 4 4: 5 5: Custom

No.	Data name	Set/Get	Data range
173	Reference unit number for reference coordinate	Set/Get	-1 to 9999
174	Reference type of reference coordinate	Set/Get	0: Set by number 1: Unit reference
176	Use coordinates before position compensation	Set/Get	0: Not used 1 : Used
177	Coordinate X before position compensation	Set/Get	-99999.9999 to 99999.9999
178	Coordinate Y before position compensation	Set/Get	-99999.9999 to 99999.9999
10000 + N (N = 0 to 99)	Position	Get only	-99999.9999 to 99999.9999
10100 + N (N = 0 to 99)	Position	Get only	-99999.9999 to 99999.9999
10200 + N (N = 0 to 99)	Formed angle N	Get only	0 to 360

Ec Cross

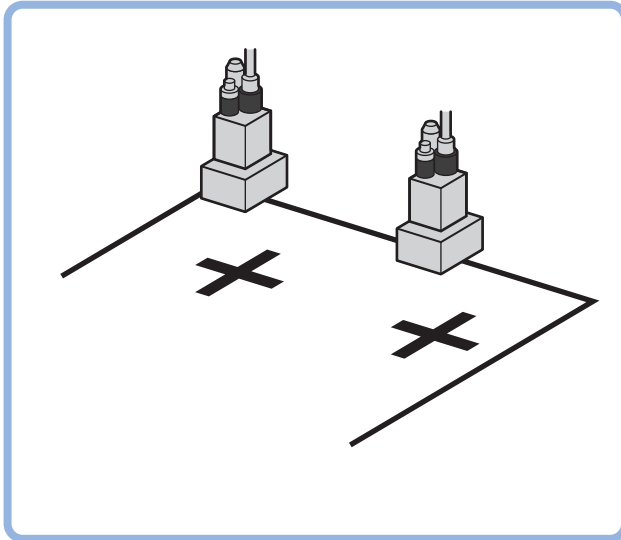
Detect crosshair shapes created by crosshair marks and other edges.

The center position of a crosshair shape is measured using the lines created by the edge information on each side of the crosshair.

A desired crosshair shape can be measured by specifying the length, direction, edge intensity and other conditions.

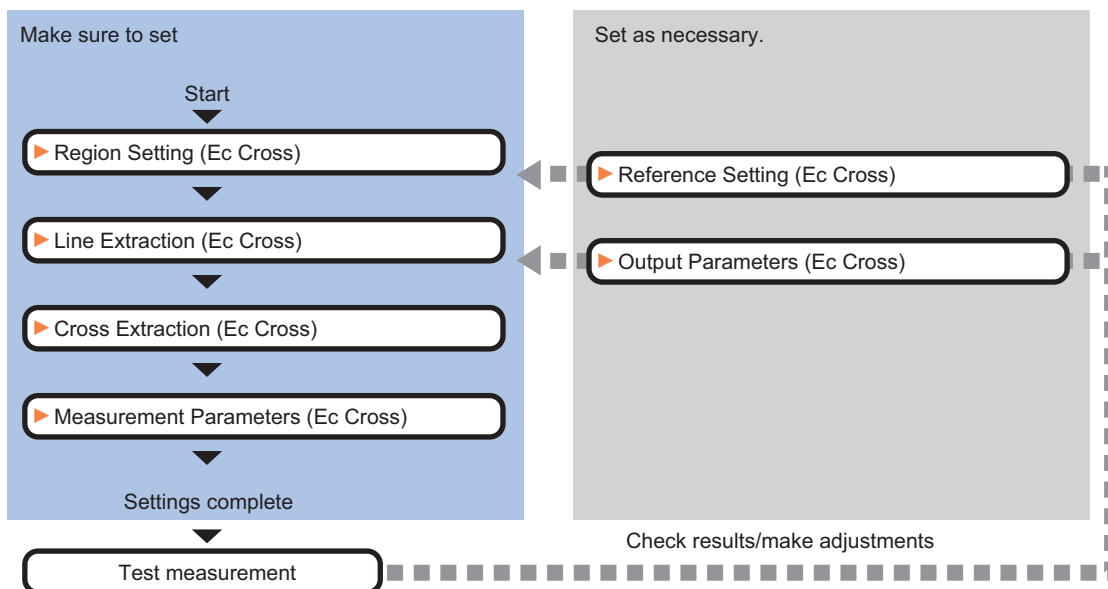
Used in the Following Case

- When you want to align the work position based on a crosshair-shaped mark



Settings Flow (Ec Cross)

Set up EC cross according to the following steps.



List of Ec Cross Items

Item name	Description
Region setting	This item is used to set up the measurement area. Instead of measuring the entire input image, narrowing the measurement area shortens the processing time. Reference: ▶ Region Setting (Ec Cross) (p.171)
Ref. setting	Change as necessary. This is changed when measuring the position deviation from a certain position. Reference: ▶ Reference Setting (Ec Cross) (p.172)
Line extraction	This item sets the conditions for extracting a line. Reference: ▶ Line Extraction (Ec Cross) (p.174)
Cross extraction	Set the conditions for extraction a crosshair shape. Reference: ▶ Cross Extraction (Ec Cross) (p.175)
Measurement	Set the sort conditions/judgement conditions of crosshair shapes. Data of the specified number is output as measurement data. Reference: ▶ Measurement Parameters (Ec Cross) (p.176)
Output parameter	This item can be changed if necessary. Select the measurement result coordinates and set how to handle the coordinates. Reference: ▶ Output Parameters (Ec Cross) (p.177)

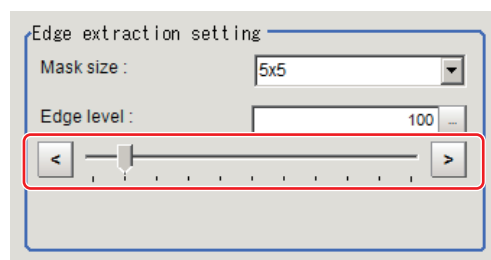
Region Setting (Ec Cross)

This item is used to set up the measurement area.

Use the rectangle to set up the measurement region for [Ec Cross].

- 1** In the Item Tab area, click [Region setting].
- 2** Use the Drawing tools to set the measurement region.
- 3** In the figure setting area, click [OK].
The measurement region is registered and displayed in the Image Display area.
- 4** Click [Edge extraction], then confirm the edge extraction image.

If the profile of the measurement object is interrupted or has too many edges, adjust the edge level.



Setting item	Setting value [Factory default]	Description
Mask size	<ul style="list-style-type: none"> • 3 × 3 • [5 × 5] • 7 × 7 • 9 × 9 	Select the range of pixels which are used to extract the edge. With a larger mask size, search is less affected by variation in pixels.
Edge level	0 to 1000 [100]	Change this when the edge is hard to see due to low contrast against the background or when unnecessary background noise must be removed. The smaller the value, the easier it is to find edges. The larger the value, the less noise will affect finding edges.

Reference Setting (Ec Cross)

When the model is set, this position is automatically set at the same time as the reference position. This item can be set to change the reference position to any desired position. This is handy for measuring the position deviation from a certain position.

A reference position can be set either directly or by referencing a unit.

Specifying directly

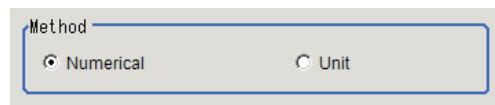
Click the position on the image that you want to set as the reference position, or set the coordinates.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.



2 In the "Method" area, select "Numerical".

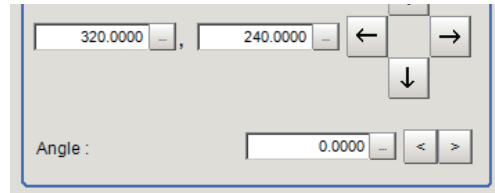


3 Click the position to be set as the reference.

Note

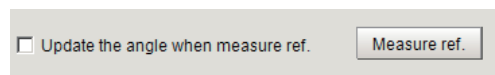
- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

4 Make fine adjustments using numeric value inputs or the arrow buttons as required.

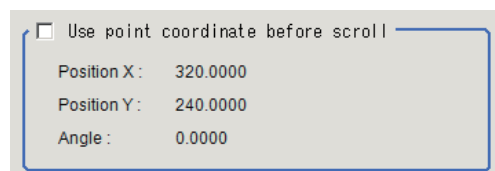


5 Set the reference angle with a numeric value.

6 To remeasure on the displayed image and set the reference, click the [Measure ref.] button. To update the reference angle at the time of reference measurement, place a check at "Update the angle when measure ref.".



7 To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".



Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

1 In the Item Tab area, click [Ref. setting].

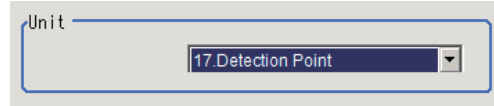
In the display area, the current reference position will be displayed as the crosshair cursor.

2 In the "Method" area, select "Unit".



A screenshot of a software interface showing a 'Method' selection box. The box contains two radio buttons: 'Numerical' and 'Unit'. The 'Unit' radio button is selected, indicated by a small dot inside the circle.

3 In the scene in the "Unit" area, select a detection point unit.



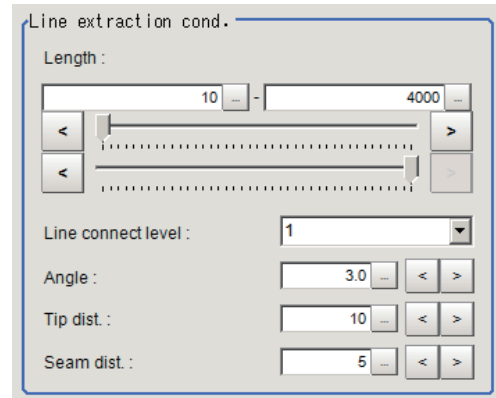
A screenshot of a software interface showing a 'Unit' selection box. The box contains a dropdown menu with the text '17.Detection Point' and a downward-pointing arrow.

4 Perform the next measurement, and the reference will be displayed.

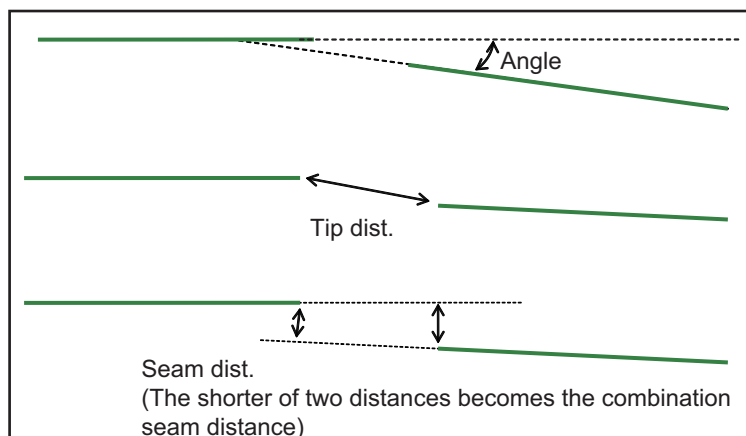
Line Extraction (Ec Cross)

This item sets the conditions for extracting a line.

- 1 In the Item Tab area, click [Line extraction].
- 2 In the "Line extraction cond." area, set the conditions for extracting a line.



Setting item	Setting value [Factory default]	Description
Length	5 to 4000 [10] to [4000]	Set the length of edges to be extracted.
Line connect level	<ul style="list-style-type: none"> • [1] • 2 • 3 • 4 • 5 • Custom 	Select the degree to which fragmented lines detected by edge extraction are connected. The higher the level, the more likely the lines are connected.
Angle	0.0 to 30.0 [3.0]	Set the angle range to be used when two lines are connected. Increasing this value allows two lines of different inclinations to be connected.
Tip dist.	0 to 1000 [10]	Set the vertex distance to be used when two lines are connected. Increasing this value allows distant lines to be connected.
Seam dist.	0 to 1000 [5]	Set the distance condition to be used when two lines are connected, where an extension of one line comes closest to the vertex of the other line. Increasing this value allows lines offset vertically to the lines to be connected.



Cross Extraction (Ec Cross)

Set the conditions for intersecting lines.

- 1 In the Item Tab area, click [Cross extraction].
- 2 In the "Line 0 cond." area, set the conditions for parallel line 0.

Line 0 cond.

Length: -

Width: -

Setting item	Setting value [Factory default]	Description
Length	5 to 4000 [10] to [4000]	Set the length of parallel line 0.
Width	1 to 1000 [10] to [100]	Set the width of parallel line 0.

- 3 In the "Line 1 cond." area, set the conditions for parallel line 1.

Line 1 cond.

Length: -

Width: -

Setting item	Setting value [Factory default]	Description
Length	5 to 4000 [10] to [4000]	Set the length of parallel line 1.
Width	1 to 1000 [10] to [100]	Set the width of parallel line 1.

- 4 In the "Advanced cond." area, set the detection conditions.

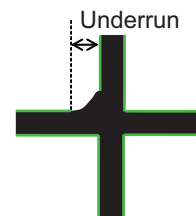
Advanced cond.

Underrun0: -

Underrun1: -

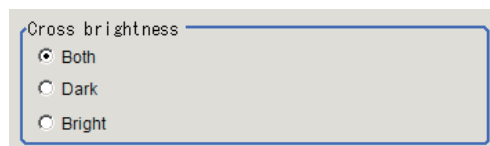
Detection line count: < >

Setting item	Setting value [Factory default]	Description
Underrun 0	[0] to [1000]	Set the level to which a cross with a rounded or pointed intersection or intersection concealed due to external disturbance is allowed. Set the range of crosses not reaching the intersection that are still recognized as crosses.
Underrun 1	[0] to [1000]	



Setting item	Setting value [Factory default]	Description
Detection line count	<ul style="list-style-type: none"> • 2 • 3 • [4] 	<p>Set a number of parallel line sets that are judged forming a cross. If the image does not have external disturbances, a total of four sets of parallel lines, which configure the cross, are detected, and those parallel lines are at the top, bottom, left, and right sides when looked from the center of the cross.</p> <p>When a straight line is not detected by being hidden or broken by an external disturbance, detection of a cross becomes possible by changing a number of detection lines.</p> <p>At least 2 sets must be set. (In case of 2 sets, each set of parallel lines has to be straight.)</p>

- 5** In the "Cross brightness" area, set the brightness relationship of the crosshair and background.

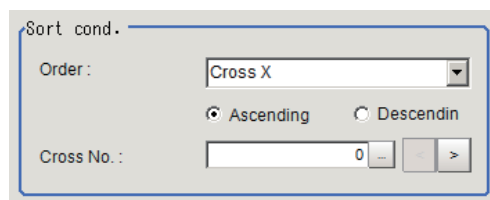


Setting item	Setting value [Factory default]	Description
Cross brightness	<ul style="list-style-type: none"> • [Both] • Dark • Bright 	Select the light/dark relationship of the crosshair and background.

Measurement Parameters (Ec Cross)

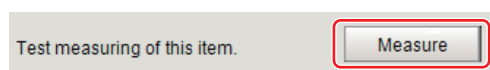
Set the sort conditions/judgement conditions of crosshairs.

- 1** In the Item Tab area, click [Measurement].
- 2** In the "Sort cond." area, set the sorting conditions.



Setting item	Setting value [Factory default]	Description
Order	<ul style="list-style-type: none"> • [Cross X] • Cross Y • Length • [Ascending] • Descending 	Select the sorting method to be applied to those measurement results where there are multiple intersections.
Cross No.	[0] to 9	Set the cross number for the data to be output.

- 3** When the setting has been changed, click [Measure] to verify whether measurements can be made correctly.
- 4** Set up the judgement condition.



Setting item	Setting value [Factory default]	Description
Cross X	[-99999.9999] to [99999.9999]	Set the range of X coordinates of crosshair that is judged to be OK.

Setting item	Setting value [Factory default]	Description
Cross Y	[-99999.9999] to [99999.9999]	Set the range of Y coordinates of crosshair that is judged to be OK.
Angle	[-45] to [45]	Set the crosshair angles that are judged to be OK.
Count	[1] to [10]	Set the number of detections of crosshair that is judged to be OK.

Output Parameters (Ec Cross)

Set how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Setting value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Specify whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Ec Cross)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Cross X	X coordinate of measured crosshair
Cross Y	Y coordinate of measured crosshair
Angle	Angle of measured crosshair
Number of detections	Number of detections of crosshair

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image.	Explanation of image to be displayed
0	Measurement image

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Parameter to be adjusted	Troubleshooting
Measurement	Reduce the distance between the upper and lower limits of line length range for extracting lines, to reduce false detections.
	Raise the line connection level to prevent the lines constituting the corners to be detected from being interrupted.
	Set the narrowest possible conditions for extracting crosses, to reduce false detections.

When the processing speed is slow

Parameter to be adjusted	Troubleshooting
Region setting	Specify as small a value as possible for FigureInfo=Region.
Measurement	Minimize the distance between the upper and lower limits of line length range for extracting lines.
	Minimize the range between the upper and lower limits of underrun distance set as part of cross extracting conditions.
	Minimize the range between the upper and lower limits of cross extracting width.
	Minimize the range between the upper and lower limits of cross extracting length.
	Specify as large a value as possible for the number of detection lines for extracting crosses.

When judgement is NG

State	Parameter to be adjusted	Troubleshooting
There are lines but they are not detected	Cross extraction	Expand and extend the overrun range in both the positive direction and negative direction so that corners can be formed.

Measurement Results for Which Output Is Possible (Ec Cross)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Cross coordinate X	X	Cross coordinate X
Cross coordinate Y	Y	Cross coordinate Y
Angle	TH	Angle
Number of detections	CT	Number of detections
Reference X	SX	Reference X
Reference Y	SY	Reference Y
Reference angle	ST	Reference angle
Cross coordinate XN (N = 0 to 99)	XN	Cross coordinate XN
Cross coordinate YN (N = 0 to 99)	YN	Cross coordinate YN
Angle N (N = 0 to 99)	THN	Angle N

External Reference Tables (Ec Cross)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Number of detections	Get only	0 to 10
6	Cross coordinate X	Get only	-99999.9999 to 99999.9999
7	Cross coordinate Y	Get only	-99999.9999 to 99999.9999
8	Angle	Get only	-45 to 45
9	Reference position X coordinate	Get only	-99999.9999 to 99999.9999
10	Reference position Y coordinate	Get only	-99999.9999 to 99999.9999
11	Reference angle	Get only	-180 to 180
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Edge level	Set/Get	0 to 1000
121	Filter size	Set/Get	0: 3 × 3 1: 5 × 5 2: 7 × 7 3: 9 × 9
122	Lower limit of line length	Set/Get	5 to 4000
123	Upper limit of line length	Set/Get	5 to 4000
124	Combination angle	Set/Get	0.0 to 30.0
125	Combination tip distance	Set/Get	0 to 1000
126	Combination seam distance	Set/Get	0 to 1000
127	Conditions for parallel line 0 Lower limit of length range	Set/Get	5 to 4000
128	Conditions for parallel line 0 Upper limit of length range	Set/Get	5 to 4000
129	Conditions for parallel line 1 Lower limit of length range	Set/Get	5 to 4000
130	Conditions for parallel line 1 Upper limit of length range	Set/Get	5 to 4000
138	Number of detection lines	Set/Get	2 to 4
139	Conditions for parallel line 0 Lower limit of underrun range	Set/Get	0 to 1000
140	Conditions for parallel line 0 Upper limit of underrun range	Set/Get	0 to 1000
141	Conditions for parallel line 1 Lower limit of underrun range	Set/Get	0 to 1000
142	Conditions for parallel line 1 Upper limit of underrun range	Set/Get	0 to 1000

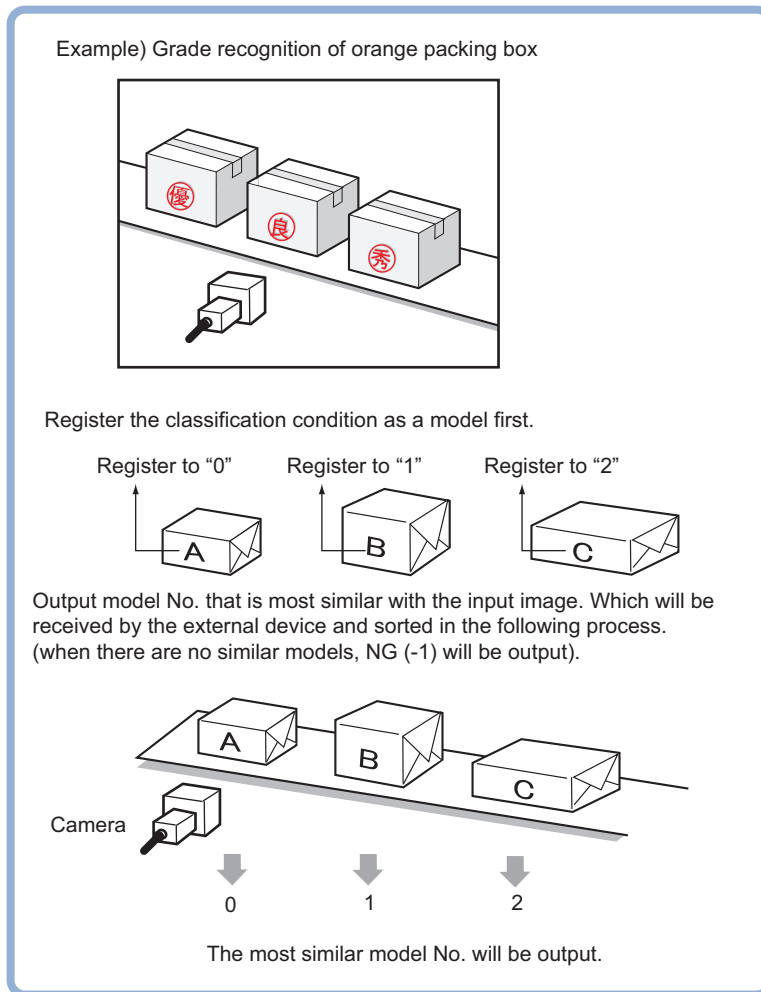
No.	Data name	Set/Get	Data range
143	Conditions for parallel line 0 Min. width	Set/Get	1 to 1000
144	Conditions for parallel line 0 Max. width	Set/Get	1 to 1000
145	Conditions for parallel line 1 Min. width	Set/Get	1 to 1000
146	Conditions for parallel line 1 Max. width	Set/Get	1 to 1000
148	Detection object color	Set/Get	0: Both 1: Cross (dark) - Background (light) 2: Cross (light) - Background (dark)
156	Sort order	Set/Get	0: Cross X 1: Cross Y 2: Line length
157	Sort sequence	Set/Get	0: Ascending 1: Descending
158	Output number	Set/Get	0 to 99
162	Fusion distance	Set/Get	0 to 1000
163	Judgement condition: Lower limit of cross X	Set/Get	-99999.9999 to 99999.9999
164	Judgement condition: Upper limit of cross X	Set/Get	-99999.9999 to 99999.9999
165	Judgement condition: Lower limit of cross Y	Set/Get	-99999.9999 to 99999.9999
166	Judgement condition: Upper limit of cross Y	Set/Get	-99999.9999 to 99999.9999
167	Judgement condition: Lower limit of angle	Set/Get	-45 to 45
168	Judgement condition: Upper limit of angle	Set/Get	-45 to 45
169	Judgement condition: Lower limit of number of detections	Set/Get	0 to 10
170	Judgement condition: Upper limit of number of detections	Set/Get	0 to 10
171	Reference X	Set/Get	0 to 9999
172	Reference Y	Set/Get	0 to 9999
173	Reference angle	Set/Get	-180 to 180
174	Line connection level	Set/Get	0: 1 1: 2 2: 3 3: 4 4: 5 5: Custom
176	Reference unit number for reference coordinate	Set/Get	-1 to 9999
177	Reference type of reference coordinate	Set/Get	0: Set by number 1: Unit reference
178	Reference angle update	Set/Get	0: Not update 1: Update

No.	Data name	Set/Get	Data range
179	Use coordinates before position compensation	Set/Get	0: Not used 1 : Used
180	Coordinate X before position compensation	Set/Get	-99999.9999 to 99999.9999
181	Coordinate Y before position compensation	Set/Get	-99999.9999 to 99999.9999
182	Angle before position compensation	Set/Get	-180 to 180
10000 + N (N = 0 to 9)	Position	Get only	-99999.9999 to 99999.9999
10100 + N (N = 0 to 9)	Position	Get only	-99999.9999 to 99999.9999
10200 + N (N = 0 to 9)	Angle N	Get only	-45 to 45

Classification

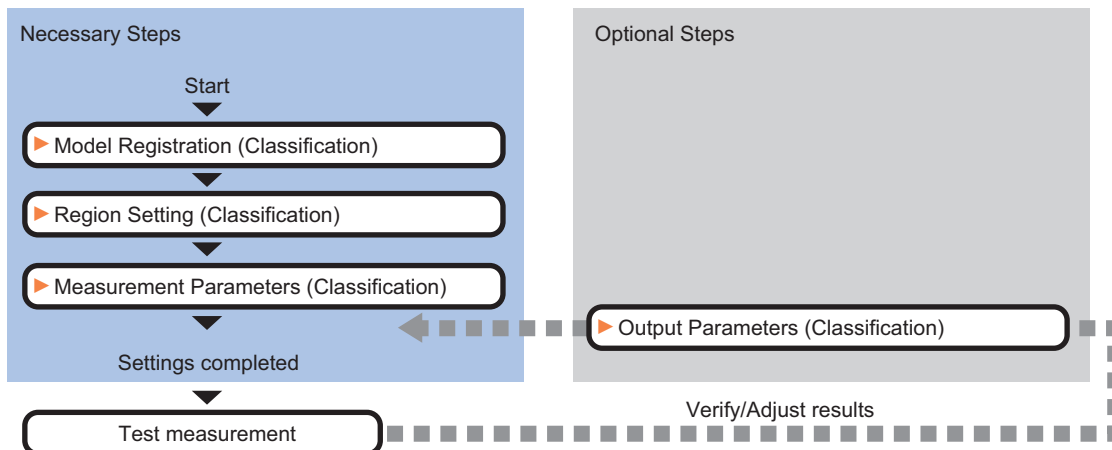
Used in the Following Case

- When various kinds of products on a production line need to be classified and identified



Settings Flow (Classification)

Classification can be set up as follows.



List of Classification Items

Item name	Description
Model	This item registers the pattern characteristic of the measurement image as a model. Model parameter values can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used. Reference: ▶ Model Registration (Classification) (p.183)
Region setting	This item is used to set up the measurement area. Instead of measuring the entire input image, narrowing the measurement area shortens the processing time. Reference: ▶ Region Setting (Classification) (p.186)
Measurement	This item specifies the judgement condition for measurement results. Specify the criteria to judge the measurement result if the X and Y coordinates and the correlation values with the model are OK. Reference: ▶ Measurement Parameters (Classification) (p.186)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Classification) (p.187)

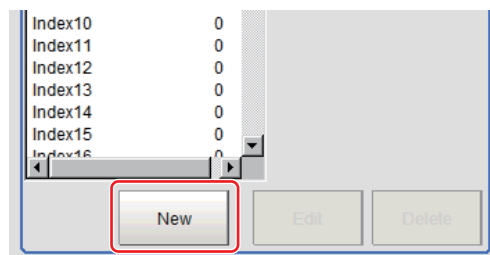
Model Registration (Classification)

Pre-register as models the sections to be used as reference for classification.

Models can be registered with any of 200 indexes, from 0 to 199, and up to 5 models can be registered for each index.

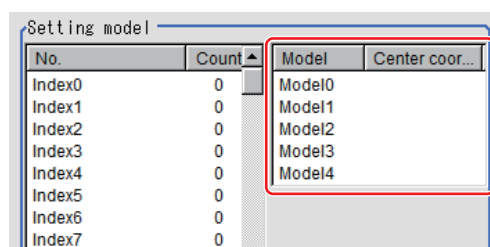
When there is variation among the model print quality and shapes, pre-register multiple models for the same index.

- 1 In the Item Tab area, click [Model].
- 2 In the "Setting model" area, select a model and click [New].

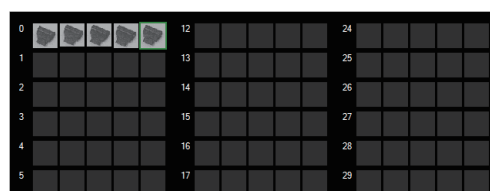


- 3 Use the Drawing tools to specify the model registration range.
- 4 Click [OK].

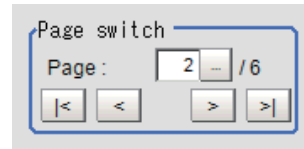
The model is registered and its central X and Y coordinate values are displayed in the "Setting model" area.



The image specified for the model is displayed in the Image Display area.



Set the page in the Switch Page area to display models with index numbers 36 or more.



Note

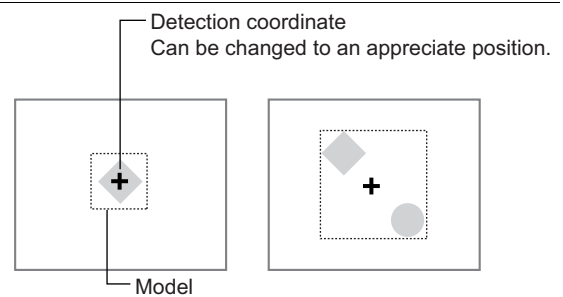
Model Status and Measurement Processing

- Measurement time and accuracy may be affected by the status of model in the following ways. Please select measurement objects that are in good condition (clean) for Model Registration.
- In the case of large or complicated models, processing time is prolonged.
- With extremely small models or models without features, search processing is unstable.

5 To register two or more models, repeat the Steps Reference: ▶ 2 (p.183) to Reference: ▶ 4 (p.183) .

Note

- When a model is registered, the central coordinates of the model are registered as the detection point. A detection point is a point output as a measurement value. If multiple figures are combined, the central coordinates of the circumscribed rectangle are registered.

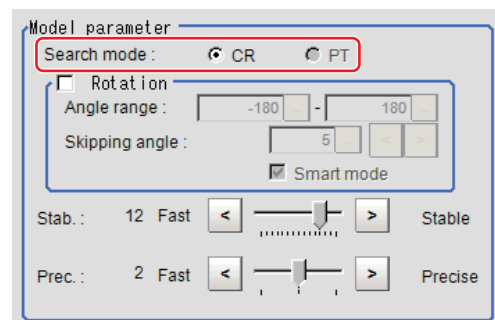


Changing Model Parameters

Model parameter values can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used.

After changing a setting, re-register the model.

- 1 In the "Model parameter" area, select the search mode, then specify a value for each item for that mode.**



Setting item	Set value [Factory default]	Description
Search mode	[CR]	Search normalizing the brightness. This method can provide stable measurement when there is fluctuation in the overall brightness and when the image has low contrast.
	PT	Measures with the degree of matching to the profile of the model. This method can measure at higher speed when the rotation angle has a wide range. It is available only when a 0.3 megapixel color camera is connected.

When CR is selected

Setting item	Set value [Factory default]	Description
Rotation	<ul style="list-style-type: none"> • Checked • [Unchecked] 	When the measurement object is rotating, select the "Rotation" check box and specify how many degrees the model created rotates each time and through what range of angles. A smaller skipping angle increases stability, but slows down the processing. The normal direction is clockwise.
Angle range	[-180 to 180]	
Skipping angle	1 to 30 [5]	
Smart mode	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Checking the "Smart mode" option enables a high-speed rotation search. However, the stability may be lowered when the model shape aspect ratio is large or when the NOT mask is used.
Stab.	1 to 15 [The default value depend on the connected camera. 9 or 12]	Specify which is to have priority, measurement stability or speed. If lowering stability does not speed up processing, it is likely that many candidates have been detected. In this case, specify a larger value for "Candidate level" or "Stab."
Prec.	1 to 3 [2]	Specify which is to have priority, measurement positional precision or speed.

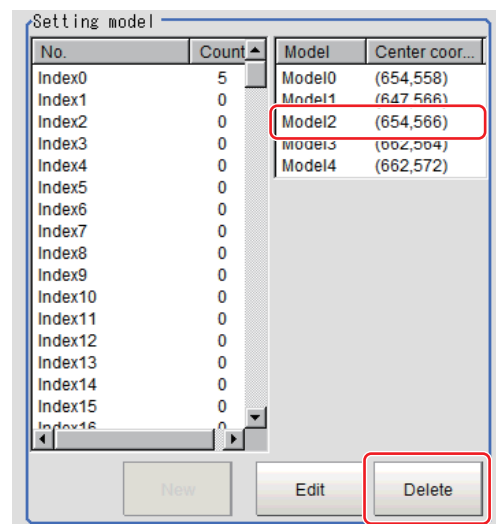
When PT is selected

Setting item	Set value [Factory default]	Description
Angle range	[-180 to 180]	This item specifies the rotation angle range for searching. The normal direction is clockwise.
Stability	1 to 5 [3]	If lowering stability does not speed up processing, it is likely that many candidates have been detected. In this case, specify a larger value for "Candidate level" or "Stab."

Deleting a Model

Deletes a registered model.

- 1 Select the model from the list and click [Delete].



Region Setting (Classification)

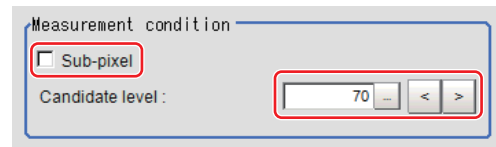
Use the rectangle to set up the measurement region for [Classification].

- 1** In the Item Tab area, click [Region setting].
- 2** Click [Edit].
The figure setting area is displayed.
- 3** Specify the area in which to search for the model.
The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.
- 4** Click [OK].
The area to measure is registered.

Measurement Parameters (Classification)

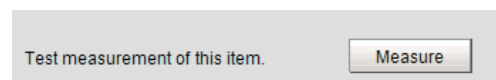
Specify the search measurement conditions and the judgement conditions for the measurement results.

- 1** In the Item Tab area, click [Measurement].
- 2** In the "Measurement condition" area, specify a value for each item.



Setting item	Set value [Factory default]	Description
Sub-pixel	<ul style="list-style-type: none"> • Checked • [Unchecked] 	When a check is placed at sub-pixel, the position information can be measured in units of sub-pixels. However, this requires more processing time.
Candidate level	0 to 100 [70]	Specify the threshold value with which to detect candidate points in a rough search. Specify a smaller value when model search results are unreliable.

- 3** When the setting has been changed, click [Measure] in the "Detail" area to verify whether measurements can be made correctly.
- 4** Set up the judgement condition.



Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Set value	Description
Position X	-99999.9999 to 99999.9999	Specify the range of X-axis shifting that is judged to be OK.
Position Y	-99999.9999 to 99999.9999	Specify the range of Y-axis shifting that is judged to be OK.
Search angle	-180 to 180	Specify the range of angles that are judged to be OK.
Correlation	0 to 100	Specify the range of correlation values that are judged to be OK. However, when the correlation value of the measurement result is 0, the judgement result will be NG regardless of the lower limit setting.

Output Parameters (Classification)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Classification)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Index	Index No. of the biggest correlation
Model number	Model No. of the biggest correlation
Correlation value	Correlation value with the model
Position X	X coordinate of the position where the model is detected
Position Y	Y coordinate of the position where the model is detected
Angle θ	Angle of the position where the model is detected

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Searching other positions

Parameter to be adjusted	Remedy
Model parameter	Specify a larger value for the "Prec."
	If the measurement results are unstable only when "Rotation" is selected, specify a smaller value for the "Skipping angle".
	When "Rotation" is selected, if the model shape is complex, uncheck the "Smart mode" option.
	If the image has low contrast or blurred edges, set the "Search mode" to "CR".
	If the model image consists of detailed figures, specify a larger value for "Stab."

Parameter to be adjusted	Remedy
Measurement	If the precision is low, place a check at "Sub-pixel".
	If images that should be judged OK vary greatly, specify a smaller value for "Candidate level".
	If the model image is small and unstable, specify a smaller value for the "Reduction".

The judgement is NG (insufficient memory)

Parameter to be adjusted	Remedy
Region setting	Make the search region as small as possible.
Model parameter	Bring "Stab." close to the factory default value.
	Bring the "Skipping angle" close to the factory default value.
	Specify a smaller value for "Prec.".

When the processing speed is slow

Parameter to be adjusted	Remedy
Region setting	Make the search region as small as possible.
Model	Make the area to register as the model as small as possible.
Model parameter	If the model image is a simple figure or a large figure, specify a smaller value for "Stab." If lowering stability does not speed up processing, it is likely that many candidates have been detected. Raise the "Candidate level" in [Measurement].
	When "Rotation" is selected and the model image is a simple figure, specify a larger value for "Skipping angle".
	When "Rotation" is selected and the model image is a simple figure, place a check at "Smart mode".
	If the position precision is high, specify a smaller value for "Prec.".
	If the rotation angle range is large, set the "Search mode" to "PT".
Measurement	If images that should be judged OK vary little, specify a larger value for "Candidate level".
	If the position precision is high, uncheck "Sub-pixel".

Measurement Results for Which Output Is Possible (Classification)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Index	IN	Index No. with the highest correlation value
Model No.	NO	Model No. with the highest correlation value
Correlation value	CR	Correlation value with the model
Measurement position X	X	X coordinate of the position where the model is detected
Measurement position Y	Y	Y coordinate of the position where the model is detected
Measurement angle	TH	Angle of the position where the model is detected
Reference position X	SX	Reference coordinate X of the registered model
Reference position Y	SY	Reference coordinate Y of the registered model
Detection point RX	RX	X coordinate of the registered model
Detection point RY	RY	Y coordinate of the registered model

External Reference Tables (Classification)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Index	Get only	-1: No models found 0 to 199
6	Model No.	Get only	-1: No models found 0 to 4
7	Correlation value	Get only	0 to 100
8	Measure X	Get only	-99999.9999 to 99999.9999
9	Measure Y	Get only	-99999.9999 to 99999.9999
10	Angle θ	Get only	-180 to 180
11	Reference X	Get only	-99999.9999 to 99999.9999
12	Reference Y	Get only	-99999.9999 to 99999.9999
13	Reference angle	Get only	-180 to 180
14	Detection coordinate X	Get only	-99999.9999 to 99999.9999
15	Detection coordinate Y	Get only	-99999.9999 to 99999.9999
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Search mode	Set/Get	0: Correlation 1: Shape
121	With rotation	Set/Get	0: OFF 1: ON
122	Upper limit of the rotation angle	Set/Get	-180 to 180
123	Lower limit of the rotation angle	Set/Get	-180 to 180
124	Skipping angle	Set/Get	1 to 30
125	Smart mode	Set/Get	0: OFF 1: ON
126	Stab. (CR)	Set/Get	1 to 15
127	Prec.	Set/Get	1 to 3
128	Stab. (PT)	Set/Get	1 to 5
134	Sub-pixel	Set/Get	0: OFF 1: ON
135	Candidate Point Level	Set/Get	0 to 100
136	Upper limit of measure X	Set/Get	-99999.9999 to 99999.9999
137	Lower limit of measure X	Set/Get	-99999.9999 to 99999.9999
138	Upper limit of measure Y	Set/Get	-99999.9999 to 99999.9999
139	Lower limit of measure Y	Set/Get	-99999.9999 to 99999.9999

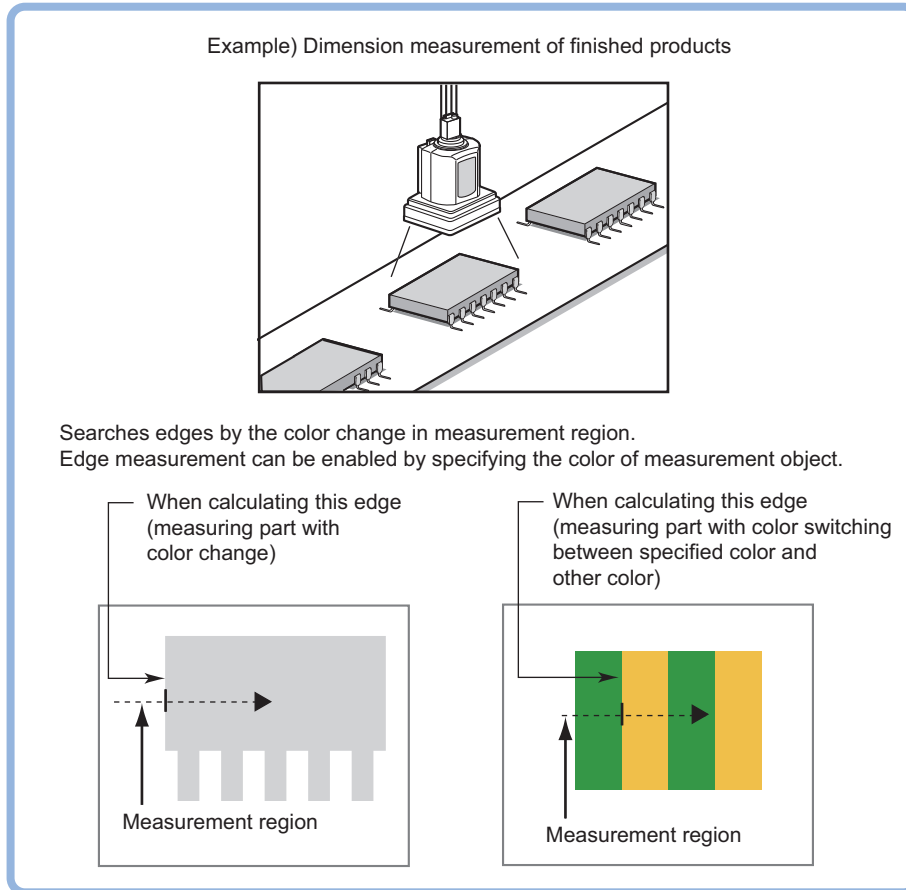
No.	Data name	Set/Get	Data range
140	Upper limit of the angle	Set/Get	-180 to 180
141	Lower limit of the angle	Set/Get	-180 to 180
142	Upper limit of the corr.	Set/Get	0 to 100
143	Lower limit of the corr.	Set/Get	0 to 100

Edge Position

This processing item detects the position of the measurement object by using the change in color within the measurement region.

Used in the Following Case

- To calculate edge coordinates of measurement objects



- To find the width of a measurement object

Using a Expression, the width of a measurement object can be calculated from the difference between two edge positions.

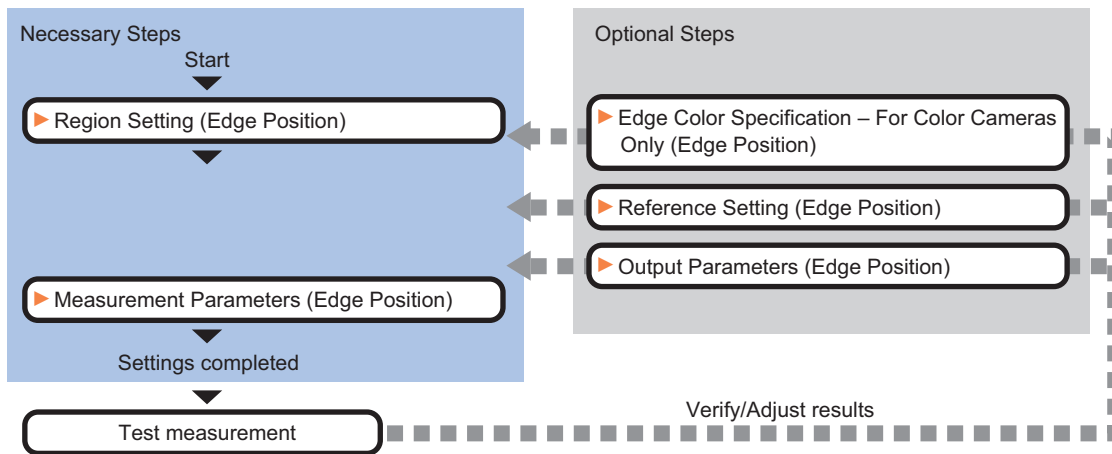
Note

- Edge processing basic concepts

Reference: ▶"Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Settings Flow (Edge Positions)

Set the edge position with the following steps.



List of Edge Position Items

Item name	Description
Region setting	This item is used to set up the measurement area. Reference: ▶ Region Setting (Edge Position) (p.193)
Edge color (for color cameras only)	If the color of the edges to be detected is decided, specify the color. Reference: ▶ Edge Color Specification - For Color Cameras Only (Edge Position) (p.194)
Ref. setting	The edge position is registered as the reference when the region is set. Change as necessary. Reference: ▶ Reference Setting (Edge Positions) (p.194)
Measurement	This item specifies the judgement condition for measurement results. Measurement parameter can be changed as needed to address unstable measurement results. The displayed items depend on whether your camera is a color or monochrome camera. Normally, the factory default value will be used. Reference: ▶ Measurement Parameters (Edge Positions) (p.196)
Output parameter	This item can be changed if necessary. Normally, the factory default value may be used. Select the measurement result coordinates and set how to handle the coordinates. Reference: ▶ Output Parameters (Edge Position) (p.198)

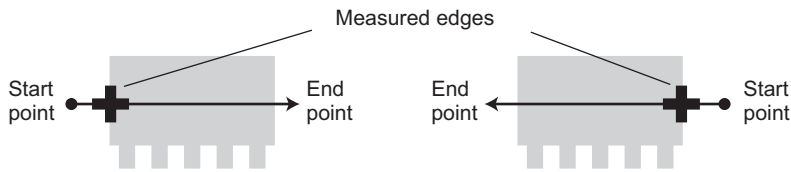
Region Setting (Edge Position)

This item is used to set up the measurement area.

Use a straight line (arrow), circumference, or arc to specify a measurement region for [Edge position].

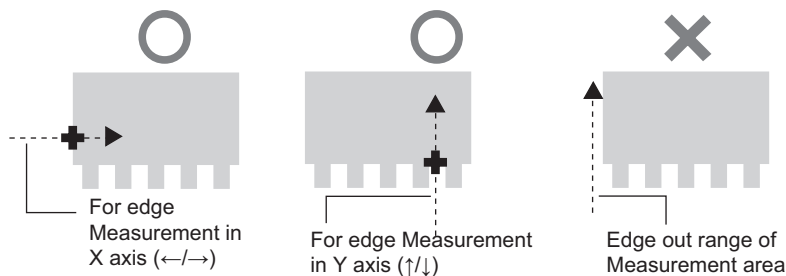
Note

- The edge is scanned from the start point of the area toward the end point.
When setting up the measurement region, pay attention to the detection direction of the edge.



Drawing the line from left to right and from right to left will lead to different measured edges.

- Measurement cannot be performed if there is no edge within the measurement region. When determining the size and position of the measurement region, take into account the movement range of the measurement object.



-----▶: Measurement region

- 1** In the Item Tab area, click [Region setting].
- 2** Use the Drawing tools to specify the measurement region.
- 3** In the figure setting area, click [OK].

The measurement region is registered and displayed in the Image Display area.

Note

- Use the zoom function if the measurement region is too small to identify the direction of the arrow.
Reference: ▶"Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

- 4** When a circumference or arc is selected as the registered figure, select the edge search direction.

If a check is placed at the "Circle/Arc with width counterclockwise" option, the edge is searched counterclockwise. If this option is unchecked, the edge is searched clockwise.

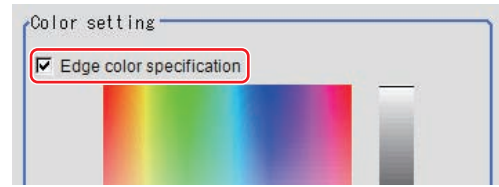
Region parameter
 Circle / Arc with width counterclockwise

Edge Color Specification - For Color Cameras Only (Edge Position)

This item selects the color of the edges to be detected.

If the target color changes, this setting is not necessary. If the color is not specified, positions in the measurement region where the color changes drastically are detected as an edge.

- 1 In the Item Tab area, click [Edge color].
- 2 Place a check at "Edge color specification" in the "Color setting" area.



- 3 This item selects the color to be detected as edges.

Setting method	Description
Image Display area	Specify a region on the image that includes the target color. The average color of the specified region is registered.
Color chart	Click the reference color on the color chart to specify it. The RGB values for the specified color are displayed at the bottom.
R, G, B	The color to be detected is set with the RGB values.
Difference R, G, B	This sets the allowable color difference for detecting the edge, using the specified color as the reference. The larger the difference values, the larger the color range that is used to detect the edge.
Detection mode	<p>Color IN: The position where a color other than the specified color changes to the specified color is detected as the edge.</p> <p>Color OUT: The position where the specified color changes to a color other than the specified color is detected as the edge.</p> <p>For "Color IN" edge measurement mode</p> <p>For "Color OUT" edge measurement mode</p>

Reference Setting (Edge Positions)

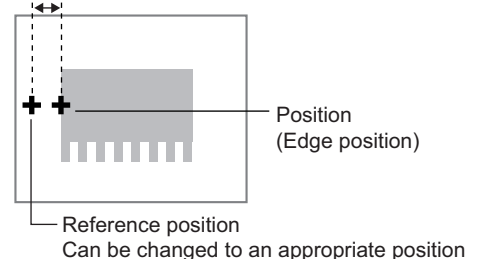
When the measurement region is set, this position is automatically set at the same time as the reference position. This item can be used to change the reference position to any desired position.

Note

Reference position usage method: Measuring the distance from a specific position

- Positional deviation can be inspected by calculating the difference between the reference position and the measured position with an expression.

After changing the reference position to any desired position, changing the measurement region will automatically change it back to the default position.



A reference position can be set either directly or by referencing a unit.

Specifying directly

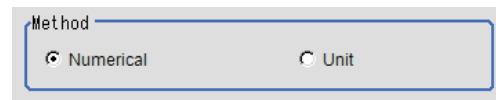
Click a position on the image you want to use as a reference position, or set coordinate data for that point.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.



2 In the "Method" area, select "Numerical".

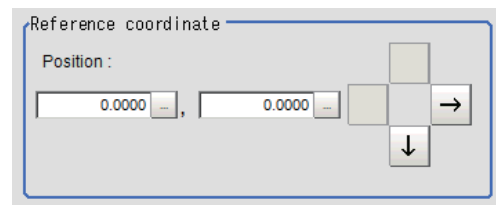


3 Click the position to be set as the reference.

Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

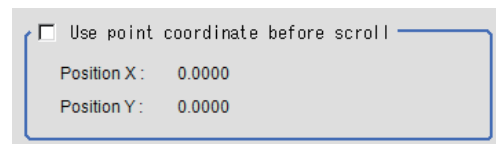
4 Make fine adjustments using numeric value inputs or the arrow buttons as required.



5 To remeasure on the displayed image and set the reference, click the [Measure ref.] button.



6 To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".



Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

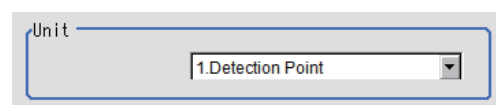
1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

2 In the "Method" area, select "Unit".



3 In the scene in the "Unit" area, select a detection point unit.



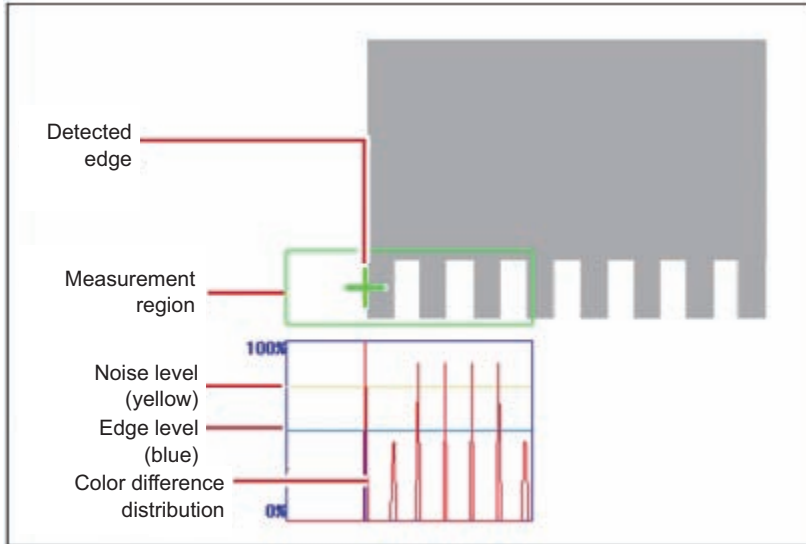
4 Perform the next measurement, and the reference will be displayed.

Measurement Parameters (Edge Positions)

This item specifies the judgement condition for measurement results. Measurement parameter can be changed as needed to address unstable measurement results.

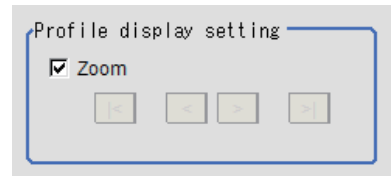
1 In the Item Tab area, click [Measurement].

The edge profile of the measurement region is displayed as a graph in the Image Display area.



Note

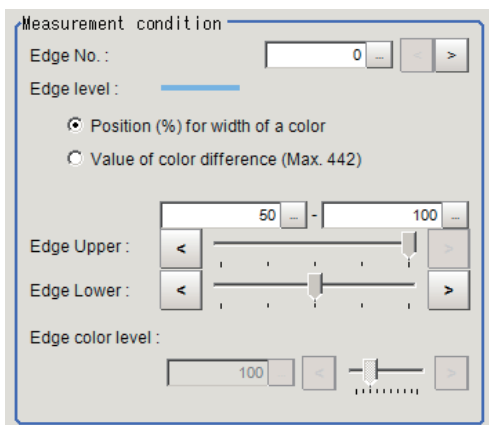
- When the region is a circumference or arc, you can display the graph enlarged in the vertical direction. Place a check at "Zoom" and click the button to adjust.



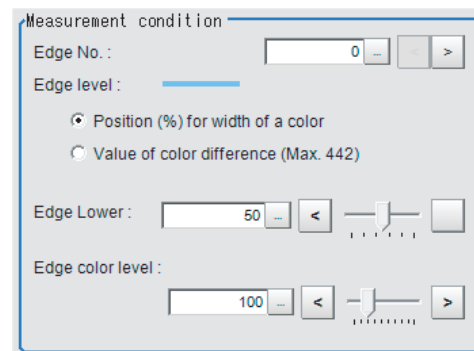
2 If necessary, specify a value for each item in the "Measurement condition" area.

For color cameras:

Edge Color Not Specified



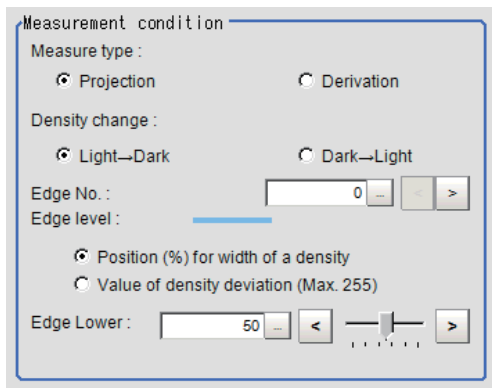
Edge Color Specified



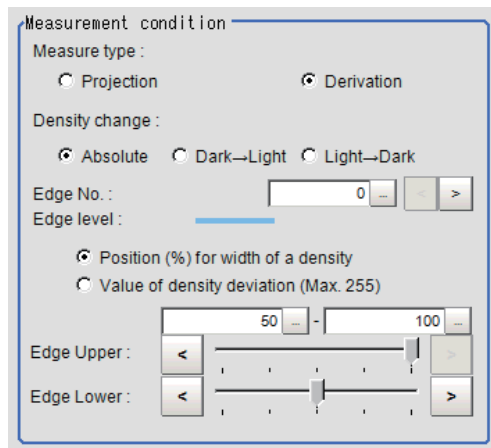
Setting item	Set value [Factory default]	Description
Edge No.	0 to 99 [0]	Specify the edge number used to extract edges. Edge numbers are assigned to detected edges starting from 0 and going on in the direction from the start point (the arrow point) to the end point (the direction of arrow) in the selected area.
Edge Upper (only when edge color is not specified) Edge Lower	<ul style="list-style-type: none"> Position (%) for width of a color 0 to 100 [50] to [100] Value of color 0 to 442 [20] to [442] 	Set a range of a color difference level with which the edge is detected. Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Edge color level	0 to 442 [100]	This emphasis level can be specified only if the edge color to detect is specified.

For monochrome cameras:

When the measurement method is "Projection"



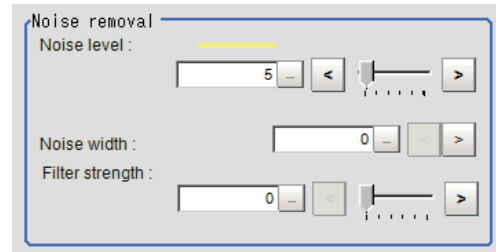
When the measurement method is "Derivation"



Setting item	Set value [Factory default]	Description
Measure type	<ul style="list-style-type: none"> [Projection] Derivation 	As the measurement type, specify either projection or derivation. Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Density change	Absolute (only when the measurement method is "Derivation") <ul style="list-style-type: none"> [Dark→Light] Light→Dark 	Select whether a black-to-white change or a white-to-black change should be recognized as a density change in the specified region.
Edge No.	0 to 99 [0]	Specify the edge number used to extract edges. Edge numbers are assigned to detected edges starting from 0 and going on in the direction from the start point (the arrow point) to the end point (the direction of arrow) in the selected area.

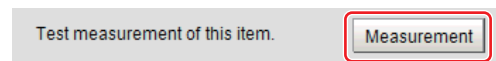
Setting item	Set value [Factory default]	Description
Edge Upper Edge Lower	<ul style="list-style-type: none"> Position (%) for width of a density 0 to 100 [50] to [100] Value of density 0 to 255 [20] to [255] 	<p>Select the density change level to be detected as edges.</p> <p>The upper limit of edges can be set only when the measurement method is "Derivation".</p> <p>Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"</p>

3 If necessary, set each item in the "Noise removal" area.



Setting item	Set value [Factory default]	Description
Noise level	<ul style="list-style-type: none"> For color cameras: 0 to 442 [5] For monochrome cameras: 0 to 255 [5] 	<p>When edges are incorrectly detected due to noise, increase this value.</p> <p>Reference: ▶ "Appendixes Measurement Mechanism Noise Level" in the "Vision System FH/FZ5 Series User's Manual (Z340)"</p>
Noise width	0 to 9999 [0]	<p>Set the width for judging noise.</p> <p>When detection is affected by noise, increase this value.</p> <p>Reference: ▶ "Appendixes Measurement Mechanism Noise Width" in the "Vision System FH/FZ5 Series User's Manual (Z340)"</p>
Filter strength	0 to 100 [0]	<p>If a valley appears in the histogram around the edge threshold value due to noises, smoothen the edge profile using a filter to prevent wrong error detection from being detected.</p> <p>Strengthening the filter smoothen the edge profile further.</p>

4 When the setting has been changed, click [Measurement] in the Detail area to verify whether measurements can be made correctly.



5 Set up the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Set value	Description
Edge position X	-99999.9999 to 99999.9999	Specify the range of X-axis shifting that is judged to be OK.
Edge position Y	-99999.9999 to 99999.9999	Specify the range of Y-axis shifting that is judged to be OK.

Output Parameters (Edge Position)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

1 Click [Output parameter] in the Item Tab area.

2 Specify each of the following items.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none">• [After scroll]• Before scroll	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.
Calibration	<ul style="list-style-type: none">• [OFF]• ON	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none">• [ON]• OFF	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Edge Position)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Edge position X	X coordinate of the measured edge position
Edge position Y	Y coordinate of the measured edge position

The image specified in the sub image in image display setting is displayed in the Image Display area.

Sub image number	Explanation of image to be displayed
0	Measurement image
1	Profile display

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Parameter to be adjusted	Remedy
Measurement	If the color of the edges to be detected is decided, specify the color with [Edge color]. If results are not stable even with the color specified, specify a larger value for the color variance range.
	If noise is detected as an edge, specify larger values for "Noise level" and "Noise width".

Measurement Results for Which Output Is Possible (Edge Position)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

Measurement items	Character string	Description
Edge position X	X	X coordinate of the measured edge position
Edge position Y	Y	Y coordinate of the measured edge position
Reference coordinate X	SX	Reference X
Reference coordinate Y	SY	Reference Y

External Reference Tables (Edge Position)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Edge position X	Get only	0 to 99999.9999
6	Edge position Y	Get only	0 to 99999.9999
7	Reference X	Get only	0 to 99999.9999
8	Reference Y	Get only	0 to 99999.9999
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF, 1: ON
103	Reflect to overall judgement	Set/Get	0: ON, 1: OFF
120	Edge color specification	Set/Get	0: OFF 1: ON
121	Edge color R	Set/Get	0 to 255
122	Edge color G	Set/Get	0 to 255
123	Edge color B	Set/Get	0 to 255
124	Difference R	Set/Get	0 to 127
125	Difference G	Set/Get	0 to 127
126	Difference B	Set/Get	0 to 127
127	Edge detection mode	Set/Get	0: Color IN 1: Color OUT
129	Reference X	Set/Get	0 to 99999
130	Reference Y	Set/Get	0 to 99999
131	Edge No.	Set/Get	0 to 99
132	Edge Level	Set/Get	0 to 100
133	Noise level	Set/Get	0 to 442
134	Noise width	Set/Get	0 to 9999
135	Edge color level	Set/Get	0 to 442
136	Upper limit of the edge position X	Set/Get	-99999.9999 to 99999.9999
137	Lower limit of the edge position X	Set/Get	-99999.9999 to 99999.9999
138	Upper limit of the edge position Y	Set/Get	-99999.9999 to 99999.9999
139	Lower limit of the edge position Y	Set/Get	-99999.9999 to 99999.9999

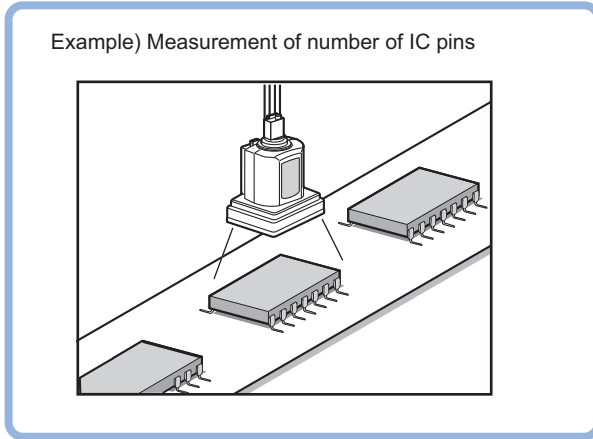
No.	Data name	Set/Get	Data range
140	Monochrome edge detection mode	Set/Get	0: Light→Dark 1: Dark→Light
141	Edge level absolute value	Set/Get	0 to 442
142	Edge level specification method	Set/Get	0: % 1: Absolute value
143	Clockwise/ Counterclockwise	Set/Get	0: Clockwise 1: Counterclockwise
144	Measure type	Set/Get	0: Projection 1: Derivation
145	Monochrome Projection edge detection mode	Set/Get	0: Absolute 1: Dark→Light 2: Light→Dark
146	Edge Level Upper limit	Set/Get	0 to 100
147	Edge level Upper limit absolute value	Set/Get	0 to 442
148	Filter Strength	Set/Get	0 to 100
158	Setting unit of reference coordinate	Set/Get	-1 to 9999
159	Setting type of reference coordinate	Set/Get	0: Numerical 1: Unit
160	Use point coordinate before scroll	Set/Get	0: Not use 1: Use
161	Position X before scroll	Set/Get	-99999.9999 to 99999.9999
162	Position Y before scroll	Set/Get	-99999.9999 to 99999.9999

Edge Pitch

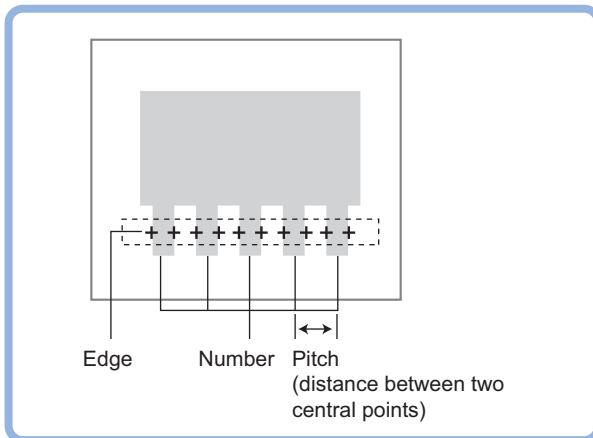
Finds and counts the edges by measuring the color change within the measurement region.

Used in the Following Case

- When calculating number of pins of IC or connectors



- To calculate the pin width and the distance (pitch) between mid-points between two pins

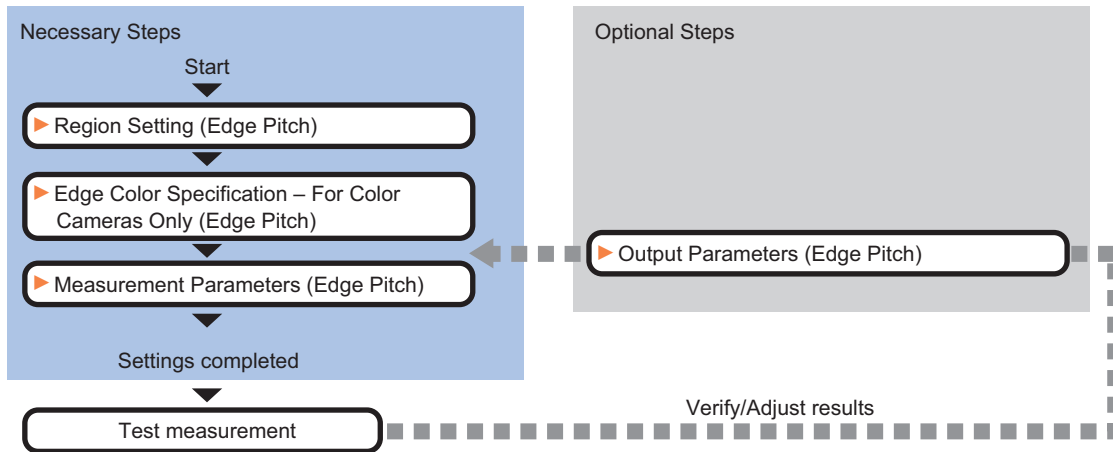


Note

- Edge image measurement processing mechanism
Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Settings Flow (Edge Pitch)

Set the Edge Pitch with the following steps.



Item List for Edge Pitch

Item name	Description
Region setting	This item is used to set up the measurement area. Reference: ▶ Region Setting (Edge Pitch) (p.203)
Edge color (for color cameras only)	This item selects the color information for the edges to be detected. Reference: ▶ Edge Color Specification - For Color Cameras Only (Edge Pitch) (p.204)
Measurement	This item specifies the judgement condition for measurement results. Measurement parameter can be changed as needed to address unstable measurement results. Specify the pitch and width for counting edges. The displayed items depend on whether your camera is a color or monochrome camera. Normally, the factory default value will be used. Reference: ▶ Measurement Parameters (Edge Pitch) (p.204)
Output parameter	This item can be changed if necessary. Normally, the factory default value may be used. Select the measurement result coordinates and set how to handle the coordinates. Reference: ▶ Output Parameters (Edge Pitch) (p.207)

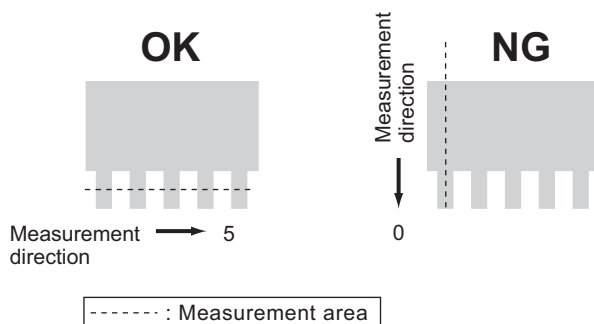
Region Setting (Edge Pitch)

This item is used to set up the measurement area.

Use a straight line, circumference, or arc to specify a measurement region for [Edge Pitch].

Note

- When setting up a measurement region, please include all the edges to be detected.



- 1** In the Item Tab area, click [Region setting].
- 2** Use the Drawing tools to specify the measurement region.
- 3** In the figure setting area, click [OK].

The measurement region is registered and displayed in the Image Display area.

Edge Color Specification - For Color Cameras Only (Edge Pitch)

Specify the target color to be counted.

- 1** In the Item Tab area, click [Edge color].
- 2** Specify the target color for the edges to be counted (used as the reference color for edge detecting).

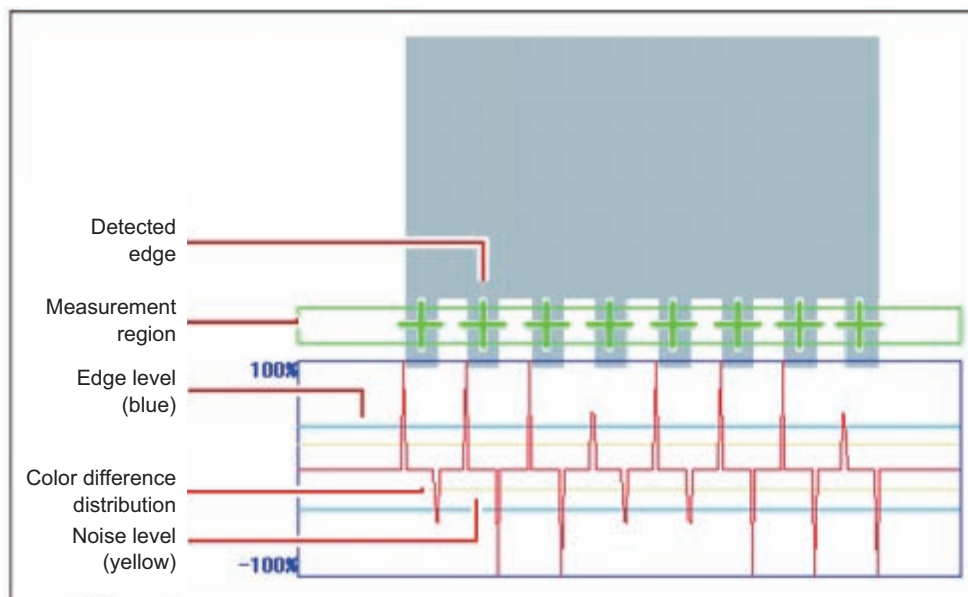
Setting method	Description
Image Display area	Specify a region on the image that includes the target color. The average color of the specified region is registered.
Color chart	Click the color on the color chart to specify it. The RGB values for the specified color are displayed at the bottom.
R, G, B	The color to be detected is set with the RGB values.
Difference R, G, B	This sets the allowable color difference for detecting the edge, using the specified color as the reference. The larger the difference values, the larger the color range that is used to detect the edge.

Measurement Parameters (Edge Pitch)

This item specifies the judgement condition for measurement results. Also specify the range for positions to be judged as OK.

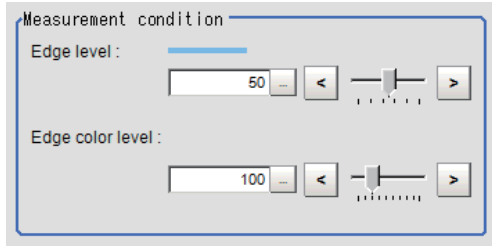
- 1** In the Item Tab area, click [Measurement].

The edge profile of the measurement region (straight line) is displayed in the Image Display area.



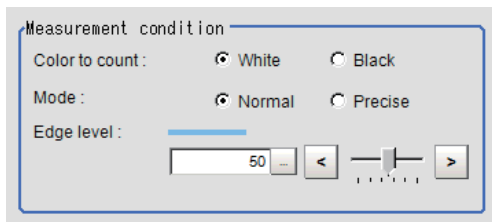
2 If necessary, specify a value for each item in the "Measurement condition" area.

For color cameras:



Setting item	Set value [Factory default]	Description
Edge level	0 to 100 [50]	Specify a color changing level with which the edge is detected. When the measurement result is lower than the actual number of edges, specify a smaller value for the edge level. On the other hand, when the measurement result is higher than the actual number of edges, specify a larger value for the edge level. Reference: ▶ "Appendixes Measurement Mechanism Edge Level" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Edge color level	0 to 442 [100]	Set the emphasis level for the edge color specified with [Edge color].

For monochrome cameras:

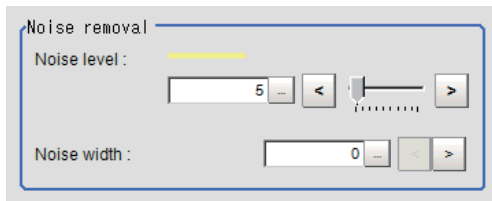


Important

- Up to 1000 edges can be measured, but only a maximum of 256 can be displayed on the screen.

Setting item	Set value [Factory default]	Description
Color to count	<ul style="list-style-type: none"> • [White] • Black 	Select an edge color to be measured.
Mode	<ul style="list-style-type: none"> • [Normal] • Precise 	If the pin width or gap is less than 2 pixels, select precise.
Edge level	0 to 100 [50]	Specify the density change level to be detected as edges. When the measurement result is lower than the actual number, specify a smaller value for the edge level (or the minimum level). On the other hand, when the measurement result is higher than the actual number, specify a larger value for the edge level (or the minimum level). Reference: ▶ "Appendixes Measurement Mechanism Edge Level" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

3 If necessary, set each item in the "Noise removal" area.



Setting item	Set value [Factory default]	Description
Noise level	0 to 442 [5]	When detection is affected by noise, increase this value. Reference: ▶ "Appendixes Measurement Mechanism Noise Level" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Noise width	0 to 9999 [0]	Set the width for judging noise. When detection is affected by noise, increase this value. Reference: ▶ "Appendixes Measurement Mechanism Noise Width" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Filter strength	0 to 100 [0]	If a valley appears in the histogram around the edge threshold value due to noises, smoothen the edge profile using a filter to prevent wrong error detection from being detected. Strengthening the filter smoothen the edge profile further.

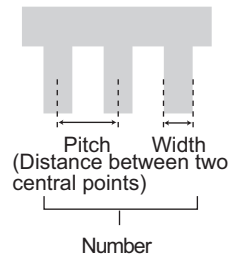
4 When the setting has been changed, click [Measurement] in the "Detail" area to verify whether measurements can be made correctly.

Test measurement of this item.

Measurement

5 Set up the judgement condition.

Setting item	Set value	Description
Edges	0 to 999	Specify a range to be judged as OK.
Pitch	0 to 99999.9999	
Ave pitch	0 to 99999.9999	
Width	0 to 99999.9999	
Ave width	0 to 99999.9999	



6 If a circumference with a width or an arc with a width is set for the region, set the profile display settings as required.

Setting item	Set value [Factory default]	Description
Enlarged display	[Not Visible]	If you place a check here, the profile will be displayed for the length along the circumference of the circumference with a width or arc with a width. Use an enlarged display to check the details of the profile.
	Visible	

Output Parameters (Edge Pitch)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position deflection correction is applied.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Edge Pitch)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Number of edges	Number of edges
Average pitch	Average edge pitch
Max. pitch	Edge maximum pitch
Min. pitch	Edge minimum pitch
Average width	Average edge width
Max. width	Edge maximum width
Min. width	Edge minimum width

The image specified in the sub image in image display setting is displayed in the Image Display area.

Sub image number	Explanation of image to be displayed
0	Measurement image
1	Profile display

Key Points for Adjustment

Select the adjustment method referring to the following points.

Parameter to be adjusted	Remedy
Edge color	If edges cannot be detected properly, specify a larger value for the color variance range.
Measurement	If noise is detected as an edge, specify a larger value for "Noise level" and "Noise width".
Edge level	When the measurement result is lower than the actual number of edges, specify a smaller value for the "Edge level". On the other hand, when the measurement result is higher than the actual number of edges, specify a larger value for the "Edge level".

Measurement Results for Which Output Is Possible (Edge Pitch)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judgement result
Number of Edge Pins	N	Number of detected edges
Average pitch	P	Average pitch of detected edges
Max. pitch	PH	Maximum pitch of detected edges
Min. pitch	PL	Minimum pitch of detected edges
Average width	W	Average width of detected edges
Max. width	WH	Maximum width of detected edges
Min. width	WL	Minimum width of detected edges

External Reference Tables (Edge Pitch)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG -10: Error(Image format mismatch) -11: Error(unregistered model) -12: Error(insufficient memory) -20: Error(other errors)
5	Number of Edge Pins	Get only	0 to 999
6	Average pitch	Get only	0 to 99999.9999
7	Max. pitch	Get only	0 to 99999.9999
8	Min. pitch	Get only	0 to 99999.9999
9	Average width	Get only	0 to 99999.9999
10	Max. width	Get only	0 to 99999.9999
11	Min. width	Get only	0 to 99999.9999
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF

No.	Data name	Set/Get	Data range
120	Edge color R	Set/Get	0 to 255
121	Edge color G	Set/Get	0 to 255
122	Edge color B	Set/Get	0 to 255
123	Edge color difference R	Set/Get	0 to 127
124	Edge color difference G	Set/Get	0 to 127
125	Edge color difference B	Set/Get	0 to 127
127	Edge Level	Set/Get	0 to 100
128	Noise Level	Set/Get	0 to 442
129	Noise width	Set/Get	0 to 9999
130	Upper limit of edge pitch	Set/Get	0 to 1000
131	Lower limit of edge pitch	Set/Get	0 to 1000
132	Upper limit of average pitch	Set/Get	0 to 99999.9999
133	Lower limit of average pitch	Set/Get	0 to 99999.9999
134	Upper limit of the pitch	Set/Get	0 to 99999.9999
135	Lower limit of the pitch	Set/Get	0 to 99999.9999
136	Upper limit of average width	Set/Get	0 to 99999.9999
137	Lower limit of Average width	Set/Get	0 to 99999.9999
138	Upper limit of the width	Set/Get	0 to 99999.9999
139	Lower limit of the width	Set/Get	0 to 99999.9999
140	Edge color level	Set/Get	0 to 442
141	Color to count	Set/Get	0: White 1: Black
142	Mode	Set/Get	0: Normal 1: Precise

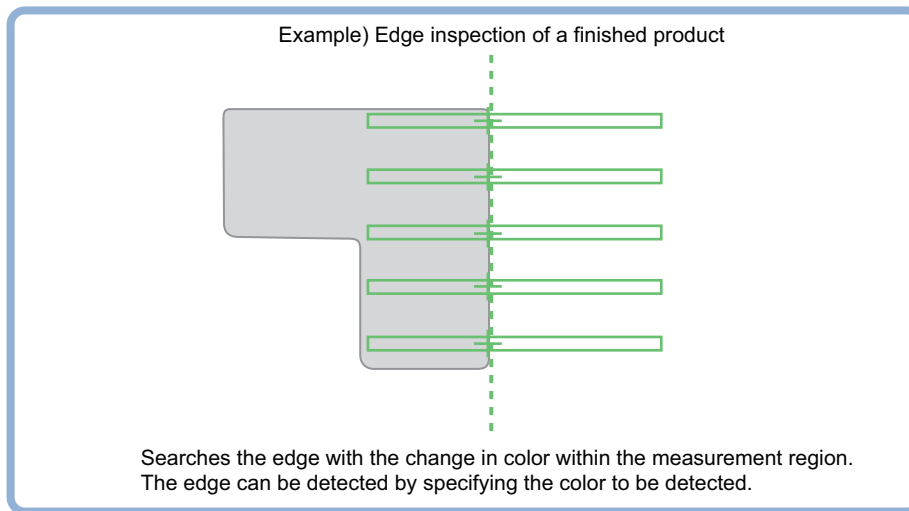
Scan Edge Position

This processing item detects the position of the measurement object by using the change in color within the measurement region. By dividing the measurement region, the following effects can be expected compared to ordinary edge position measurement.

- Detailed information, such as the closest point or furthest point from the measurement start point, can be calculated.
- The inclination or degree of unevenness of the measured object can be calculated.

Used in the Following Case

- To calculate multiple edge positions of the measurement object from statistical data

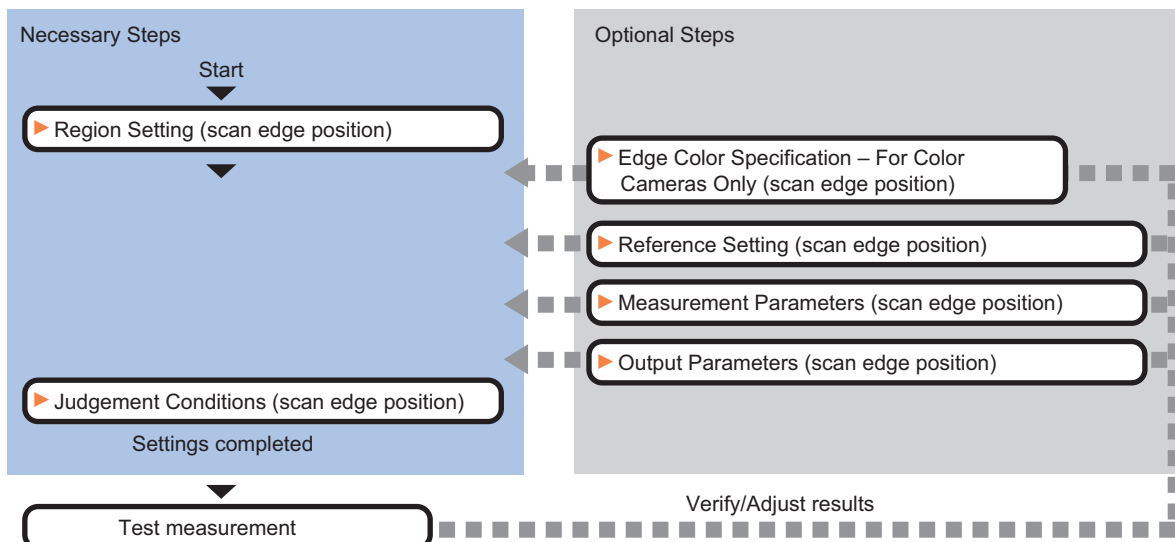


Note

- Edge image measurement processing mechanism
Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Settings Flow (Scan Edge Position)

Set the scan edge position with the following steps.



Item List for Scan Edge Position

Item name	Description
Region setting	This item is used to set up the measurement area. Reference: ▶ Region Setting (Scan Edge Position) (p.211)
Edge color (for color cameras only)	If the color of the edges to be detected is decided, specify the information for the edge color to be detected. Reference: ▶ Edge Color Specification - For Color Cameras Only (Scan Edge Position) (p.212)
Ref. setting	This item can be changed if necessary. The edge position measured once is registered when the region is set. Reference: ▶ Reference Setting (Scan Edge Position) (p.213)
Measurement	This item changes the measurement parameter as necessary when the measurement result is unstable. The displayed items depend on whether your camera is a color or monochrome camera. Normally, the factory default value will be used. Reference: ▶ Measurement Parameters (Scan Edge Positions) (p.215)
Judgement	This item specifies the judgement condition for measurement results. Reference: ▶ Judgement Conditions (Scan Edge Position) (p.218)
Output parameter	This item can be changed if necessary. Normally, the factory default value may be used. Select the measurement result coordinates and set how to handle the coordinates. Reference: ▶ Output Parameters (Scan Edge Position) (p.219)

Region Setting (Scan Edge Position)

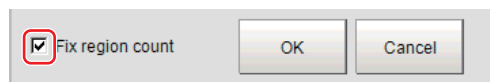
This item is used to set up the measurement area.

Specify the measurement region for [Scan Edge Position] by using wide straight lines.

1 In the Item Tab area, click [Region setting].

2 Use the Drawing tools to specify the measurement region.

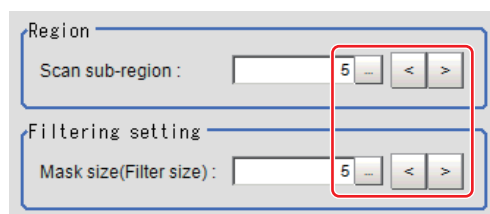
To align with the measurement area and change the number of measurement points, uncheck this.



3 In the figure setting area, click [OK].

The measurement region is registered and displayed in the Image Display area.

4 Set the measurement point and the filter size for the region.



Setting item	Set value [Factory default]	Description
Scan sub-region	1 to 100 [5]	Set the measurement point for the region.
Mask size	1 to 200 [5]	Set the filter size when smoothing the measurement point vicinity. When 5 is set, smoothing is processed for a total of 11 points: the measurement point and the 5 pixels before and after it.

5 The region is divided equally.

Division of Scan Area

The scan region, when the number of measurement points is 1



The scan region, when the number of measurement points is 2



The scan region, when the number of measurement points is 3

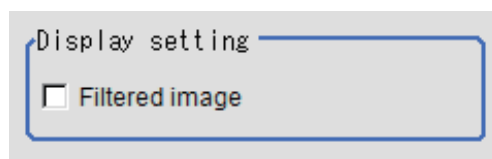


The scan region, when the number of measurement points is 4



6 Perform the display setting if required.

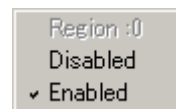
Placing a check at [Filtered image] makes it easier to change the filtering setting.



Setting item	Set value [Factory default]	Description
Filtered image	<ul style="list-style-type: none"> [Unchecked] Checked 	If checked, the filtered image of the ranges set with the Scan sub-region and Filter size after smoothing is displayed.

Note

- You can specify enable/disable for each edge measurement number. Clicking edge measurement points displays the following screen.



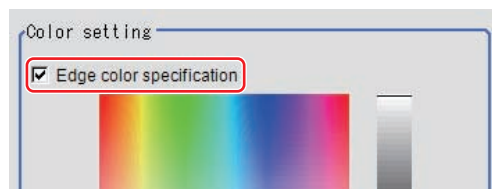
Edge Color Specification - For Color Cameras Only (Scan Edge Position)

This item selects the color of the edges to be detected.

If the target color changes, this setting is not necessary. If the color is not specified, positions in the measurement region where the color changes drastically are detected as an edge.

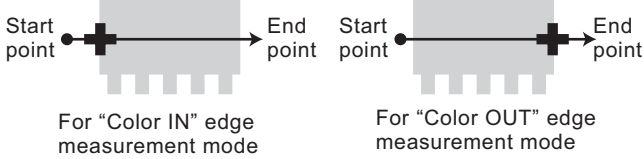
1 In the Item Tab area, click [Edge color].

2 Place a check at "Edge color" in the "Color setting" area.



3 This item selects the color to be detected as edges.

Setting methods	Description
Image Display area	Specify a region on the image that includes the target color. The average color of the specified region is registered.
Color chart	Click the reference color on the color chart to specify it. The RGB values for the specified color are displayed at the bottom.
R, G, B	The color to be detected is set with the RGB values.

Setting methods	Description
Difference R, G, B	This sets the allowable color difference for detecting the edge, using the specified color as the reference. The larger the difference values, the larger the color range that is used to detect the edge.
Detection mode	<p>Color IN: The position where a color other than the specified color changes to the specified color is detected as the edge.</p> <p>Color OUT: The position where the specified color changes to a color other than the specified color is detected as the edge.</p>  <p>For "Color IN" edge measurement mode</p> <p>For "Color OUT" edge measurement mode</p>

Reference Setting (Scan Edge Position)

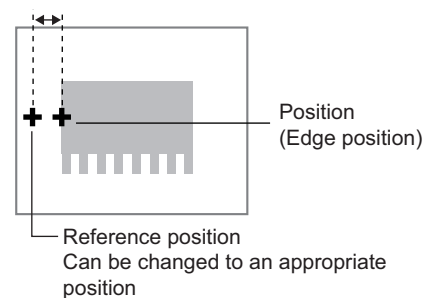
When the measurement region is set, this position is automatically set at the same time as the reference position. This item can be used to change the reference position to any desired position.

Note

Reference position usage method: Measuring the distance from a specific position

- Positional deviation can be inspected by calculating the difference between the reference position and the measured position with an expression.

After changing the reference position to any desired position, changing the measurement region will automatically change it back to the default position.



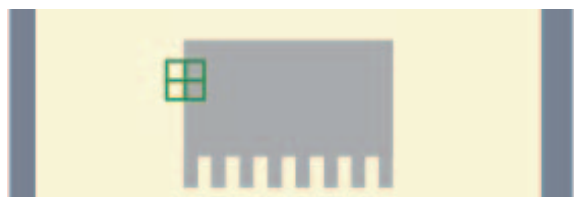
A reference position can be set either directly or by referencing a unit.

Specifying directly

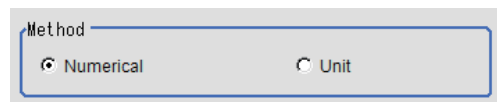
Click a position on the image you want to use as a reference position, or set coordinate data for that point.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.



2 In the "Method" area, select "Numerical".



3 Click the position to be set as the reference.

Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

4 Make fine adjustments using numeric value inputs or the arrow buttons as required.

5 To remeasure on the displayed image and set the reference, click the [Measure ref.] button.

6 To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".

Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

2 In the "Method" area, select "Unit".

3 In the scene in the "Unit" area, select a detection point unit.

4 Perform the next measurement, and the reference will be displayed.

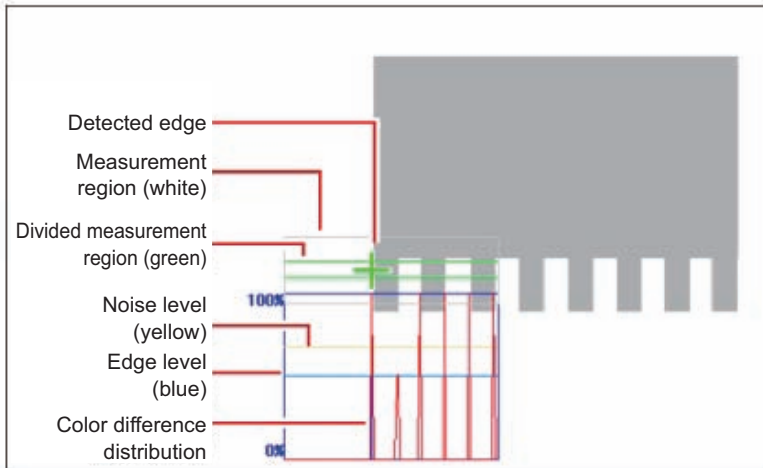
Measurement Parameters (Scan Edge Positions)

Measurement parameters can be changed as needed to address unstable measurement results. Normally, the factory default value will be used.

After changing a setting, check whether measurement can be done properly by performing an actual measurement.

1 In the Item Tab area, click [Measurement].

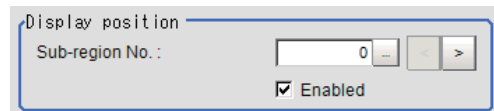
The edge profile of the measurement region is displayed as a graph in the Image Display area.



2

Inspecting and Measuring

2 Set the value of each item in the Display position area.



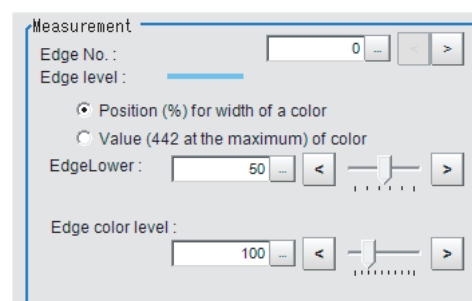
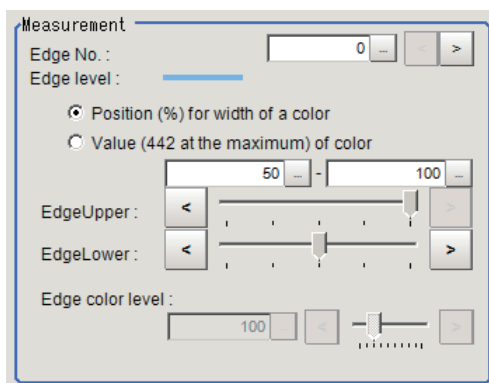
Setting item	Set value [Factory default]	Description
Sub-region No.	[0] to 99	Specify the edge measurement number for which the edge profile is displayed.
Enabled	<ul style="list-style-type: none"> [Checked] [Unchecked] 	Specify enable/disable for the displayed edge measurement number. When disabled (unchecked) is specified, that edge measurement number is not measured.

3 Set the value of each item in the "Measurement" area.

For color cameras:

Edge Color Not Specified

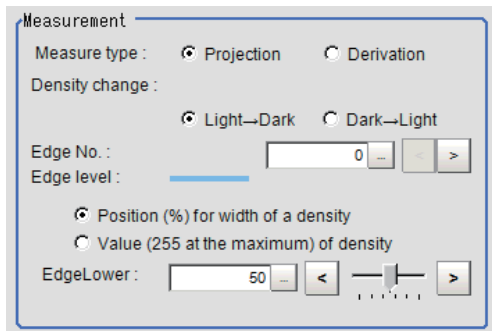
Edge Color Specified



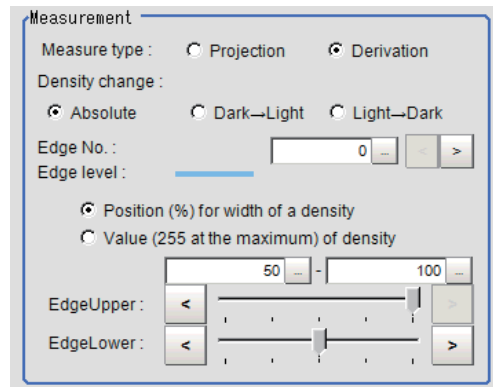
Setting item	Set value [Factory default]	Description
Edge No.	0 to 99 [0]	Specify the edge number used to extract edges. Edge numbers are assigned to detected edges starting from 0 and going on in the direction from the start point (the arrow point) to the end point (the direction of arrow) in the selected area.
Edge Upper (only when edge color is not specified) Edge Lower	<ul style="list-style-type: none"> Position (%) for width of a color 0 to 100 [50] to [100] Value of color 0 to 442 [20] to [442] 	Set a range of a color difference level with which the edge is detected. Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Edge color level	0 to 442 [100]	This emphasis level can be specified only if the edge color to detect is specified.

For monochrome cameras:

When the measurement method is "Projection"

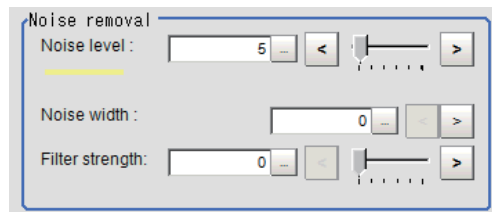


When the measurement method is "Derivation"



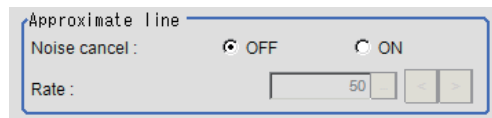
Setting item	Set value [Factory default]	Description
Measure type	<ul style="list-style-type: none"> [Projection] Derivation 	As the measurement type, specify either projection or derivation. Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Method" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Density change	<ul style="list-style-type: none"> Absolute (only when the measurement method is "Derivation") [Light→Dark] Dark→Light 	Select whether a black-to-white change or a white-to-black change should be recognized as a density change in the specified region.
Edge No.	0 to 99 [0]	Specify the edge number used to extract edges. Edge numbers are assigned to detected edges starting from 0 and going on in the direction from the start point (the arrow point) to the end point (the direction of arrow) in the selected area.
Edge Upper Edge Lower	<ul style="list-style-type: none"> Position (%) for width of a density 0 to 100 [50] to [100] Value of density 0 to 255 [20] to [255] 	Select the density change level to be detected as edges. The upper limit of edges can be set only when the measurement method is "Derivation". Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

4 If necessary, set each item in the "Noise removal" area.



Setting item	Set value [Factory default]	Description
Noise level	0 to 442 [5]	When detection is affected by noise, increase this value. Reference: ▶ "Appendixes Measurement Mechanism Noise Level" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Noise width	0 to 9999 [0]	Set the width for judging noise. When detection is affected by noise, increase this value. Reference: ▶ "Appendixes Measurement Mechanism Noise Width" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Filter strength	0 to 100 [0]	If a valley appears in the histogram around the edge threshold value due to noises, smoothen the edge profile using a filter to prevent wrong error detection from being detected. Strengthening the filter smoothen the edge profile further.

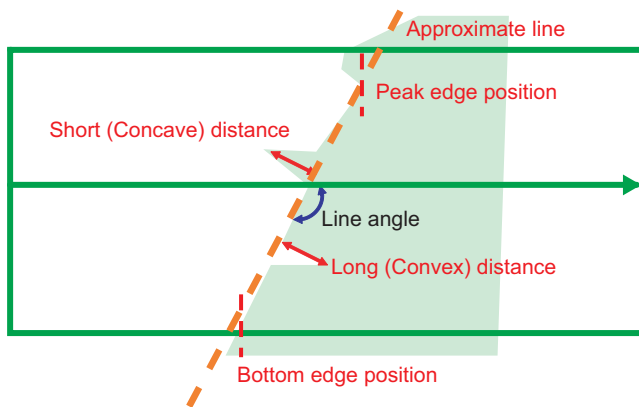
5 In the "Approximate line" area, specify the point to be used for the calculation of approximate lines.



Setting item	Set value [Factory default]	Description
Noise cancel	<ul style="list-style-type: none"> • ON • [OFF] 	When a check is placed at [ON], an approximate line is found by excluding the points with large deviation among the measured points.

Judgement Conditions (Scan Edge Position)

Specify the range to be judged as OK.



- 1 In the Item Tab area, click [Judgement].
- 2 Set up the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limits.

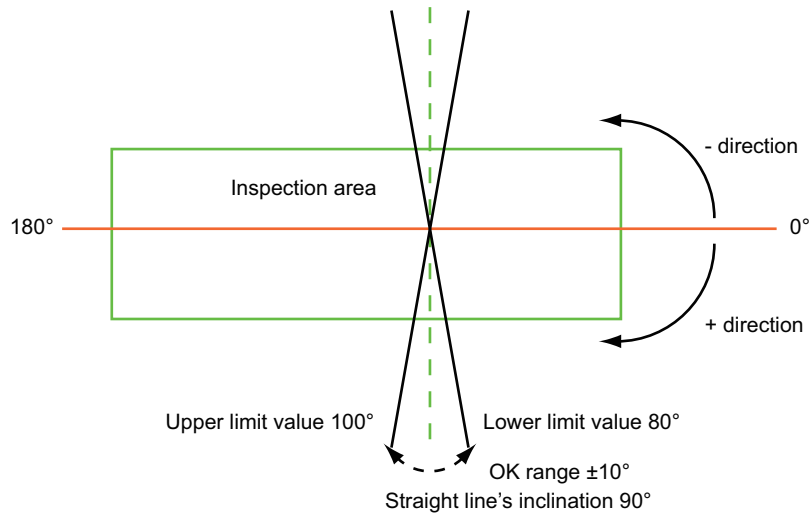
Setting item	Set value	Description
Peak edge position X	-99999.9999 to 99999.9999	Specify the X-axis upper and lower limits of the peak edge position X judged to be OK.
Peak edge position Y	-99999.9999 to 99999.9999	Specify the Y-axis upper and lower limits of the peak edge position Y judged to be OK.
Bottom edge position X	-99999.9999 to 99999.9999	Specify the X-axis upper and lower limits of the bottom edge position X judged to be OK.
Bottom edge position Y	-99999.9999 to 99999.9999	Specify the Y-axis upper and lower limits of the bottom edge position Y judged to be OK.
Edge position X Ave.	-99999.9999 to 99999.9999	Specify the X-axis upper and lower limits of the average edge position judged to be OK.
Edge position Y Ave.	-99999.9999 to 99999.9999	Specify the Y-axis upper and lower limits of the average edge position judged to be OK.
Long distance Max.	0 to 99999.9999	Specify the upper and lower limits of the long distance maximum judged to be OK.
Long distance Min.	0 to 99999.9999	Specify the upper and lower limits of the long distance minimum judged to be OK.
Short distance Max.	0 to 99999.9999	Specify the upper and lower limits of the short distance maximum judged to be OK.
Short distance Min.	0 to 99999.9999	Specify the upper and lower limits of the short distance minimum judged to be OK.
Deviation	0 to 99999.9999	Specify the upper and lower limits of the deviation judged to be OK.
Line angle	-180 to 180	Specify the upper and lower limits of the line angle judged to be OK.
Lost point count	0 to 100	Specify the upper and lower limits of the lost point count judged to be OK.

Note

- Judgement condition of the straight line's inclination

To set $90^\circ \pm 10^\circ$ (80° to 90° , -80° to -90°) range as OK, set the judgement condition to 80° to 100° .

The range of straight line's inclination is -89.999° to 90° . Internally, the angle X of -90° to 0° is the same value as $X + 180^\circ$, the angle X of 90° to 180° is the same value as $X - 180^\circ$.



Output Parameters (Scan Edge Position)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

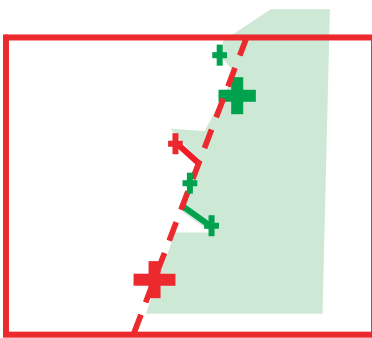
- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

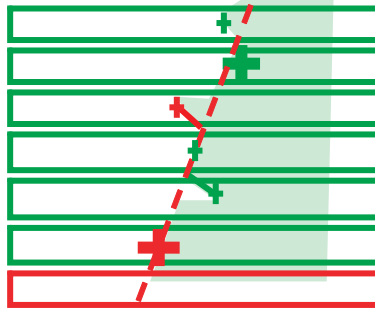
Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgment results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (Scan Edge Position)

In addition to the camera input image, the measured region, a graphic display of the measured results, and the edge position (the crosshair cursor) are also displayed as results in the Image Display area.



Edge position display (Sub image 0)



Display of edge position in each divided part (Sub image 1)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Peak edge position X	X coordinate of the edge that is the furthest from the start point of the measurement region
Peak edge position Y	Y coordinate of the edge that is the furthest from the start point of the measurement region
Bottom edge position X	X coordinate of the edge that is the closest to the start point of the measurement region
Bottom edge position Y	Y coordinate of the edge that is the closest to the start point of the measurement region
Edge position X Ave.	The average of X coordinates of all the edges
Edge position Y Ave.	The average of Y coordinates of all the edges
Long distance Max.	The maximum distance between the approximate line and edge position (plus direction)
Short distance Max.	The minimum distance between the approximate line and the edge position (minus direction)
Deviation	Deviations in concavity and convexity (Value of the standard deviation for the distance of each edge point from the linear regression)
Line angle	The straight line's inclination against the measurement region
Lost point count	Number of parts for which the detection of edges has failed

The image specified in the sub image in image display setting is displayed in the Image Display area.

Sub image number.	Explanation of image to be displayed
0	Measurement image
1	Scan region

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Parameter to be adjusted	Remedy
Measurement	If the color of the edges to be detected is decided, specify the color with [Edge color]. If results are not stable even with the color specified, specify a larger value for the color variance range.
	If noise is detected as an edge, specify larger values for "Noise level" and "Noise width".

Measurement Results for Which Output Is Possible (Scan Edge Position)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judgement result
Peak edge position X	PEAKX	X coordinate of the edge that is the furthest from the start point of the measurement region
Peak edge position Y	PEAKY	Y coordinate of the edge that is the furthest from the start point of the measurement region
Bottom edge position X	BOTTOMX	X coordinate of the edge that is the closest to the start point of the measurement region
Bottom edge position Y	BOTTOMY	Y coordinate of the edge that is the closest to the start point of the measurement region
Edge position X Ave.	X	The average of X coordinates of all the edges
Edge position Y Ave.	Y	The average of Y coordinates of all the edges
Reference coordinate	SX	X coordinate of the reference coordinates
Reference coordinate	SY	Y coordinate of the reference coordinates
Long distance Max.	PMAXD	The maximum distance between the approximate line and edge position (plus direction)
Long distance Min.	PMIND	The minimum distance between the approximate line and the edge position (plus direction)
Short distance Max.	BMAXD	The maximum distance between the approximate line and the edge position (minus direction)
Short distance Min.	BMIND	The minimum distance between the approximate line and the edge position (minus direction)
Deviation	DEV	Deviations in concavity and convexity
Angle	TH	The straight line's inclination against the measurement region
Lost point count	LOST	Number of parts for which the detection of edges has failed
Line Param. A	A	A in the expression for the approximate line $AX + BY + C = 0$.
Line Param. B	B	B in the expression for the approximate line $AX + BY + C = 0$.
Line Param.C	C	C in the expression for the approximate line $AX + BY + C = 0$.

External Reference Tables (Scan Edge Position)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgment (not yet measured) 1: Judgment result OK -1: Judgment result NG
1	Peak edge position X	Get only	0 to 99999.9999
2	Peak edge position Y	Get only	0 to 99999.9999
3	Bottom edge position X	Get only	0 to 99999.9999
4	Bottom edge position Y	Get only	0 to 99999.9999
5	Edge position X Ave.	Get only	-1 to 99999.9999
6	Edge position Y Ave.	Get only	-1 to 99999.9999
7	Long distance Max.	Get only	-1 to 99999.9999

No.	Data name	Set/Get	Data range
8	Long distance Min.	Get only	-1 to 99999.9999
9	Short distance Max.	Get only	-1 to 99999.9999
10	Short distance Min.	Get only	-1 to 99999.9999
11	Deviation	Get only	-1 to 99999.9999
12	Angle	Get only	-180 to 180
13	Lost point	Get only	0 to 100
14	Linear coefficient A	Get only	-99999.9999 to 99999.9999
15	Linear coefficient B	Get only	-99999.9999 to 99999.9999
16	Linear coefficient C	Get only	-99999.9999 to 99999.9999
17	Reference X	Get only	0 to 99999.9999
18	Reference Y	Get only	0 to 99999.9999
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Edge color specification	Set/Get	0: OFF 1: ON
121	Edge color R	Set/Get	0 to 255
122	Edge color G	Set/Get	0 to 255
123	Edge color B	Set/Get	0 to 255
124	Difference R	Set/Get	0 to 255
125	Difference G	Set/Get	0 to 255
126	Difference B	Set/Get	0 to 255
127	Detection mode	Set/Get	0: Color IN 1: Color OUT
129	Reference X	Set/Get	0 to 99999.9999
130	Reference Y	Set/Get	0 to 99999.9999
131	Edge No.	Set/Get	0 to 99
132	Edge Level	Set/Get	0 to 100
133	Noise Level	Set/Get	0 to 442
134	Noise width	Set/Get	0 to 99999
135	Edge color level	Set/Get	0 to 442
136	Upper limit of the maximum edge position X	Set/Get	-99999.9999 to 99999.9999
137	Lower limit of the maximum edge position X	Set/Get	-99999.9999 to 99999.9999
138	Upper limit of the maximum edge position Y	Set/Get	-99999.9999 to 99999.9999
139	Lower limit of the maximum edge position Y	Set/Get	-99999.9999 to 99999.9999
140	Upper limit of the minimum edge position X	Set/Get	-99999.9999 to 99999.9999

No.	Data name	Set/Get	Data range
141	Lower limit of the minimum edge position X	Set/Get	-99999.9999 to 99999.9999
142	Upper limit of the minimum edge position Y	Set/Get	-99999.9999 to 99999.9999
143	Lower limit of the minimum edge position Y	Set/Get	-99999.9999 to 99999.9999
144	Upper limit of the edge position X Ave.	Set/Get	-99999.9999 to 99999.9999
145	Lower limit of the edge position X Ave.	Set/Get	-99999.9999 to 99999.9999
146	Upper limit of the edge position Y Ave.	Set/Get	-99999.9999 to 99999.9999
147	Lower limit of the edge position Y Ave.	Set/Get	-99999.9999 to 99999.9999
148	Upper limit of the long distance Max.	Set/Get	0 to 99999.9999
149	Lower limit of the long distance Max.	Set/Get	0 to 99999.9999
150	Upper limit of the short distance Max.	Set/Get	0 to 99999.9999
151	Lower limit of the short distance Max.	Set/Get	0 to 99999.9999
152	Upper limit of the deviation	Set/Get	0 to 99999.9999
153	Lower limit of the deviation	Set/Get	0 to 99999.9999
154	Upper limit of the angle	Set/Get	-180 to 180
155	Lower limit of the angle	Set/Get	-180 to 180
156	Upper limit of the lost point	Set/Get	0 to 100
157	Lower limit of the lost point	Set/Get	0 to 100
158	Monochrome edge detection mode	Set/Get	0: Light→Dark 1: Dark→Light
159	Edge level absolute value	Set/Get	0 to 442
160	Edge level specification method	Set/Get	0: % 1: Absolute value
162	Scan sub-region	Set/Get	1 to 100
163	Scan width	Set/Get	1 to 99999
164	Display area	Set/Get	0 to 99
165	Noise cancel	Set/Get	0: OFF 1: ON
166	Measure type	Set/Get	0: Projection 1: Differential
167	Area division method	Set/Get	0: Do not fix number of area divisions 1: Fix the number of area divisions
168	Edge Level Upper limit	Set/Get	0 to 100
169	Edge Level Upper Limit absolute value	Set/Get	0 to 442
170	Monochrome Derivation edge detection mode	Set/Get	0 to 2

No.	Data name	Set/Get	Data range
171	FNC Rate	Set/Get	0 to 100
177	Filter Strength	Set/Get	0 to 100
178	Setting unit of reference coordinate	Set/Get	-1 to 9,999
179	Setting type of reference coordinate	Set/Get	0: Numerical 1: Unit
180	Use point coordinate before scroll	Set/Get	0: Not use 1: Use
181	Position X before scroll	Set/Get	-99999.9999 to 99999.9999
182	Position Y before scroll	Set/Get	-99999.9999 to 99999.9999

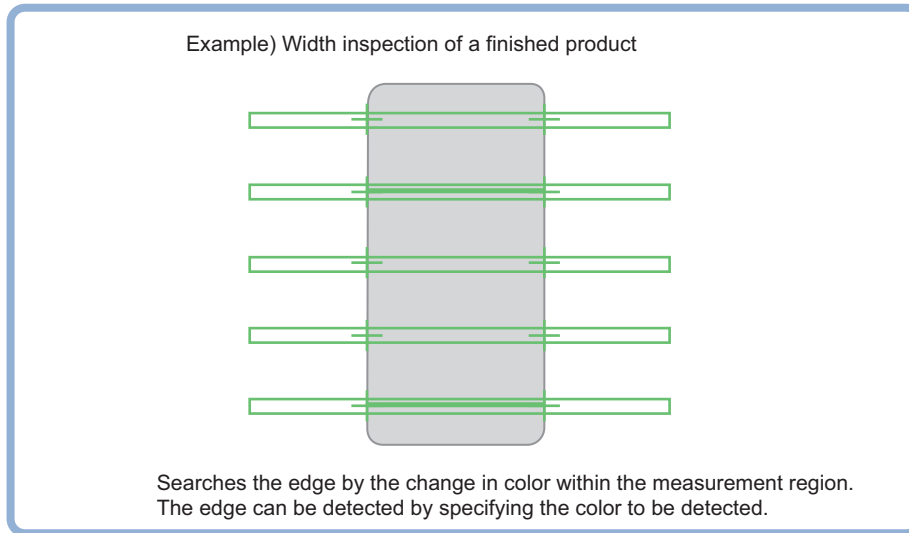
Scan Edge Width

This processing item detects the position of the measurement object by using the change in color within the measurement region. By dividing the measurement region, you can get the following values.

- Local width of the work
- Average width of the work

Used in the Following Case

- When getting several widths of a measurement object



- To find the width of a measurement object

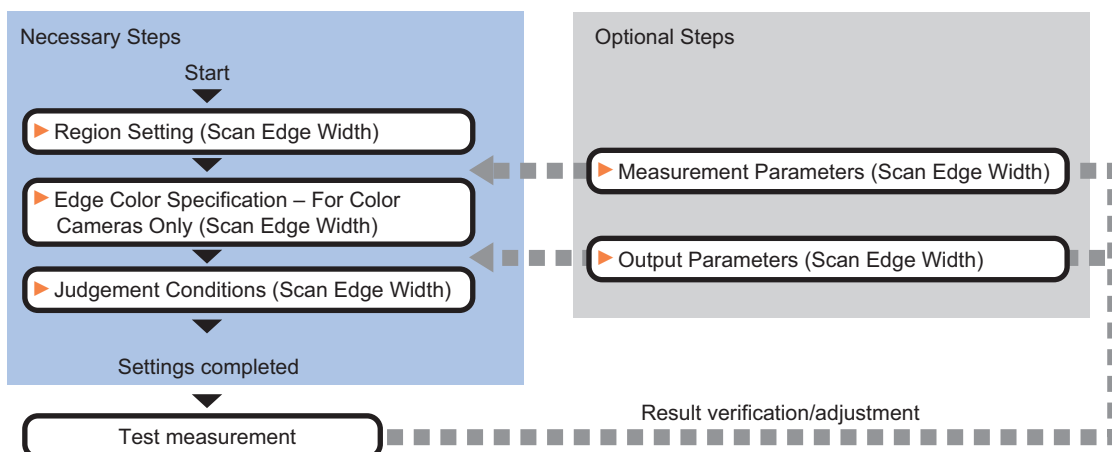
Using a Expression, the width of a measurement object can be calculated from the difference between two edge positions.

Note

- Edge image measurement processing mechanism
Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Settings Flow (Scan Edge Width)

Set the scan edge width with the following steps.



Item List for Scan Edge Width

Item name	Description
Region setting	This item is used to set up the measurement area. Reference: ▶Region Setting (Scan Edge Width) (p.226)
Edge color (for color cameras only)	This item selects the color information for the edges to be detected. Reference: ▶Edge Color Specification - For Color Cameras Only (Scan Edge Width) (p.227)
Measurement	This item changes the measurement parameter as necessary when the measurement result is unstable. The displayed items depend on whether your camera is a color or monochrome camera. Normally, the factory default value will be used. Reference: ▶Measurement Parameters (Scan Edge Width) (p.228)
Judgement	This item specifies the judgement condition for measurement results. Reference: ▶Judgement Conditions (Scan Edge Width) (p.231)
Output parameter	This item can be changed if necessary. Normally, the factory default value may be used. Select the measurement result coordinates and set how to handle the coordinates. Reference: ▶Output Parameters (Scan Edge Width) (p.231)

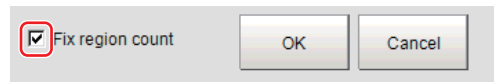
Region Setting (Scan Edge Width)

This item is used to set up the measurement area.

Specify the measurement region of [Scan Edge Width] by using a wide line.

- 1 In the Item Tab area, click [Region setting].**
- 2 Use the Drawing tools to specify the measurement region.**

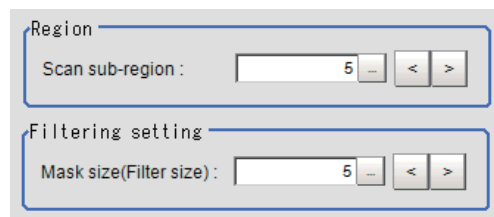
To align with the measurement area and change the number of measurement points, uncheck this.



- 3 In the figure setting area, click [OK].**

The measurement region is registered and displayed in the Image Display area.

- 4 Set the measurement point and the filter size for the region.**



Setting item	Set value [Factory default]	Description
Scan sub-region	1 to 100 [5]	Set the measurement point for the region.
Mask size	1 to 200 [5]	Set the filter size when smoothing the measurement point vicinity. When 5 is set, smoothing is processed for a total of 11 points: the measurement point and the 5 pixels before and after it.

5 The region is divided equally.

The scan region, when the number of measurement points is 1



The scan region, when the number of measurement points is 2



The scan region, when the number of measurement points is 3

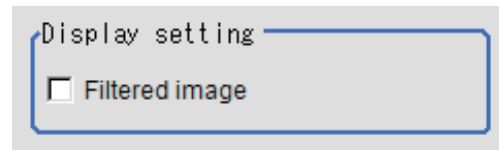


The scan region, when the number of measurement points is 4



6 Perform the display setting if required.

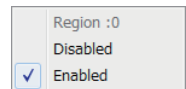
Placing a check at [Filtered image] makes it easier to change the filtering setting.



Setting item	Set value [Factory default]	Description
Filtered image	<ul style="list-style-type: none"> • [Unchecked] • Checked 	If checked, the filtered image of the ranges set with the Scan sub-region and Filter size after smoothing is displayed.

Note

- You can specify enable/disable for each edge measurement number. Clicking edge measurement points displays the following screen.

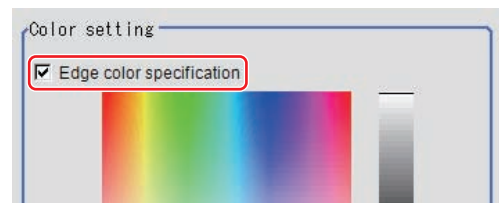


Edge Color Specification - For Color Cameras Only (Scan Edge Width)

This item selects the color of the edges to be detected.

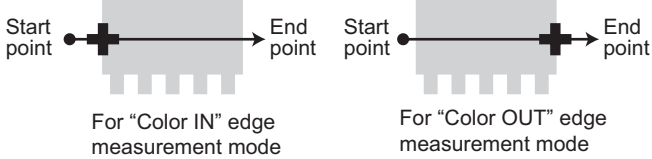
If the target color changes, this setting is not necessary. If the color is not specified, positions in the measurement region where the color changes drastically are detected as an edge.

- In the Item Tab area, click [Edge color].
- Place a check at "Edge color specification" in the "Color setting" area.



- This item selects the color to be detected as edges.

Setting methods	Description
Image Display area	Specify a region on the image that includes the target color. The average color of the specified region is registered.
Color chart	Click the reference color on the color chart to specify it. The RGB values for the specified color are displayed at the bottom.
R, G, B	The color to be detected is set with the RGB values.

Setting methods	Description
Difference R, G, B	This sets the allowable color difference for detecting the edge, using the specified color as the reference. The larger the difference values, the larger the color range that is used to detect the edge.
Detection mode	<p>Color IN: The position where a color other than the specified color changes to the specified color is detected as the edge.</p> <p>Color OUT: The position where the specified color changes to a color other than the specified color is detected as the edge.</p>  <p>For "Color IN" edge measurement mode</p> <p>For "Color OUT" edge measurement mode</p>

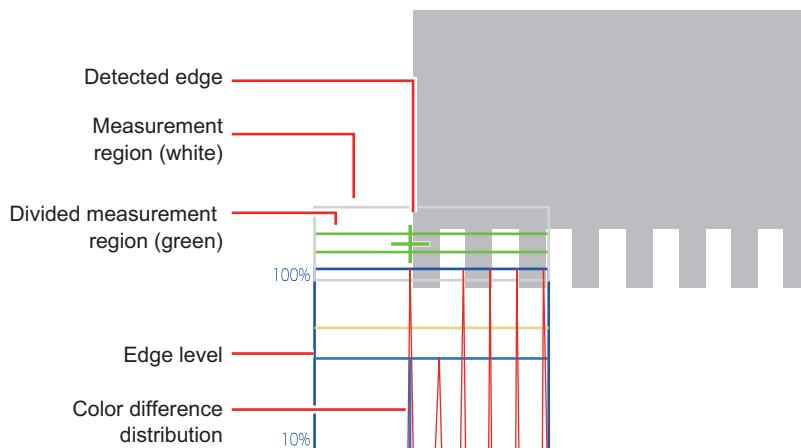
Measurement Parameters (Scan Edge Width)

Measurement parameters can be changed as needed to address unstable measurement results. Normally, the factory default value will be used.

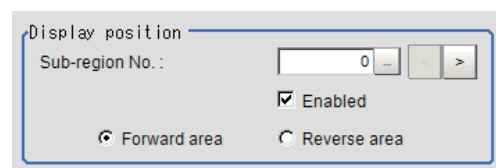
After changing a setting, check whether measurement can be done properly by performing an actual measurement.

1 In the Item Tab area, click [Measurement].

The edge profile of the measurement region is displayed as a graph in the Image Display area.



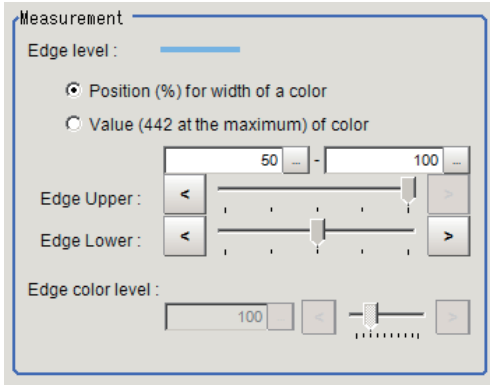
2 You can specify enable/disable for each edge measurement number.



Setting item	Set value [Factory default]	Description
Sub-region No.	[0] to 99	Set the edge measurement number for which the edge profile is displayed.
Enabled	<ul style="list-style-type: none"> [Checked] Unchecked 	Specify enable/disable for the displayed edge measurement number. When disabled (unchecked) is specified, measurement is not performed.
	<ul style="list-style-type: none"> [Forward area] Reverse area 	<p>Forward area: The edge is searched for from the start point of the area toward the end point.</p> <p>Reverse area: The edge is searched for from the end point of the area toward the start point.</p>

3 Set the value of each item in the "Measurement" area.

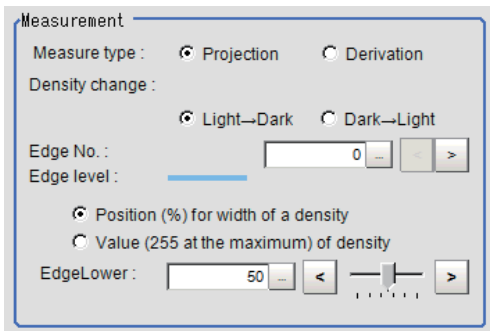
For color cameras:



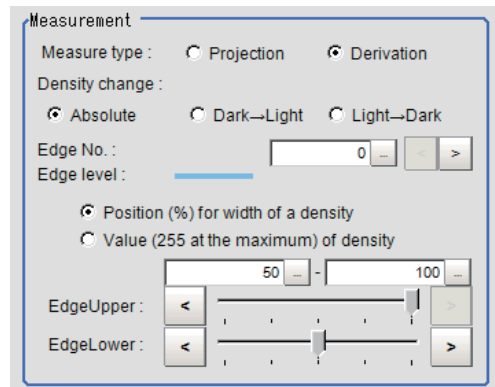
Setting item	Set value [Factory default]	Description
Edge No.	0 to 9 [0]	Specify the edge number used to extract edges. Edge numbers are assigned to detected edges starting from 0 and going on in the direction from the start point (the arrow point) to the end point (the direction of arrow) in the selected area.
Edge Upper Edge Lower	<ul style="list-style-type: none"> Position (%) for width of a color 0 to 100 [50] to [100] Value of color 0 to 442 [20] to [442] 	Set a range of a color difference level with which the edge is detected. Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Edge color level	0 to 442 [100]	This emphasis level can be specified only if the edge color to detect is specified.

For monochrome cameras:

When the measurement method is "Projection"



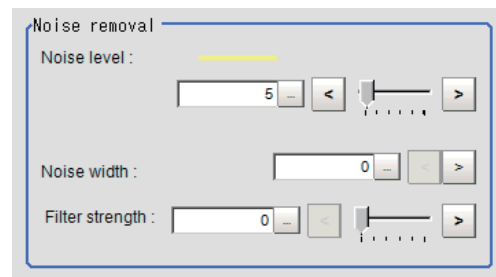
When the measurement method is "Derivation"



Setting item	Set value [Factory default]	Description
Measure type	<ul style="list-style-type: none"> [Projection] Derivation 	As the measurement type, specify either projection or derivation. Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Method" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Setting item	Set value [Factory default]	Description
Density change	<ul style="list-style-type: none"> Absolute (only when the measurement method is "Derivation") [Light→Dark] Dark→Light 	Select whether a black-to-white change or a white-to-black change should be recognized as a density change in the specified region.
Edge Upper Edge Lower	<ul style="list-style-type: none"> Position (%) for width of a density 0 to 100 [50] to [100] Value of density 0 to 255 [20] to [255] 	Select the density change level to be detected as edges. The upper limit of edges can be set only when the measurement method is "Derivation". Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

4 If necessary, set each item in the "Noise removal" area.



Setting item	Set value [Factory default]	Description
Noise level	0 to 442 [5]	When detection is affected by noise, increase this value. Reference: ▶ "Appendixes Measurement Mechanism Noise Level" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Noise width	0 to 9999 [0]	Set the width for judging noise. When detection is affected by noise, increase this value. Reference: ▶ "Appendixes Measurement Mechanism Noise Width" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Filter strength	0 to 100 [0]	If a valley appears in the histogram around the edge threshold value due to noises, smoothen the edge profile using a filter to prevent wrong error detection from being detected. Strengthening the filter smoothen the edge profile further.

Judgement Conditions (Scan Edge Width)

Specify the range to be judged as OK.

- 1 In the Item Tab area click [Judgement].
- 2 Set up the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Set value	Description
Edge width Max.	0 to 99999.9999	Specify the upper and lower limits of the maximum width judged to be OK.
Edge width Min.	0 to 99999.9999	Specify the upper and lower limits of the minimum width judged to be OK.
Edge width Ave.	0 to 99999.9999	Specify the upper and lower limits of the average width judged to be OK.
Lost width count	0 to 100	Specify the upper and lower limits of the lost width count judged to be OK.

Output Parameters (Scan Edge Width)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position deflection correction is applied.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Scan Edge Width)

The following contents can be displayed as text in the "Detail result" area.

Displayed items	Description
Judge	Judgement result
Edge width Max.	The maximum value of edge width
Edge width Min.	The minimum value of edge width
Edge width Ave.	The average value of all the edge width
Lost width count	The number of the scanned areas for which the detection of width failed

The image specified in the sub image in image display setting is displayed in the Image Display area.

Sub image number	Explanation of image to be displayed
0	Measurement image
1	Scan region

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Parameter to be adjusted	Remedy
Measurement	If the color of the edges to be detected is decided, specify the color with [Edge color]. If results are not stable even with the color specified, specify a larger value for the color variance range.
	If noise is detected as an edge, specify larger values for "Noise level" and "Noise width".

Measurement Results for Which Output Is Possible (Scan Edge Width)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Edge width Max.	MAXW	The maximum value of edge width
Edge width Min.	MINW	The minimum value of edge width
Edge width Ave.	AVEW	The average value of all the edge width
Lost width count	LOST	The number of the scanned areas for which the detection of width failed

External Reference Tables (Scan Edge Width)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgment (unmeasured) 1: Judgment result OK -1: Judgment result NG
1	Edge width Max.	Get only	0 to 99999.9999
2	Edge width Min.	Get only	0 to 99999.9999
3	Edge width Ave.	Get only	0 to 99999.9999
4	Lost width count	Get only	0 to 100
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Edge color specification	Set/Get	0: OFF 1: ON
121	Edge color R	Set/Get	0 to 255
122	Edge color G	Set/Get	0 to 255
123	Edge color B	Set/Get	0 to 255
124	Difference R	Set/Get	0 to 127
125	Difference G	Set/Get	0 to 127
126	Difference B	Set/Get	0 to 127
127	Detection mode	Set/Get	0: Color IN 1: Color OUT
129	Edge Level	Set/Get	0 to 100
130	Noise Level	Set/Get	0 to 442
131	Noise width	Set/Get	0 to 99999
132	Edge color level	Set/Get	0 to 442
133	Upper limit of the Max. width	Set/Get	0 to 99999.9999
134	Lower limit of the Max. width	Set/Get	0 to 99999.9999
135	Upper limit of the Min.width	Set/Get	0 to 99999.9999
136	Lower limit of the Min.width	Set/Get	0 to 99999.9999
137	Upper limit of the average width	Set/Get	0 to 99999.9999
138	Lower limit of the average width	Set/Get	0 to 99999.9999
139	Upper limit of the lost width count	Set/Get	0 to 100
140	Lower limit of the lost width count	Set/Get	0 to 100
141	Monochrome edge detection mode	Set/Get	0: Light→dark 1: Dark→light
142	Edge level absolute value	Set/Get	0 to 442

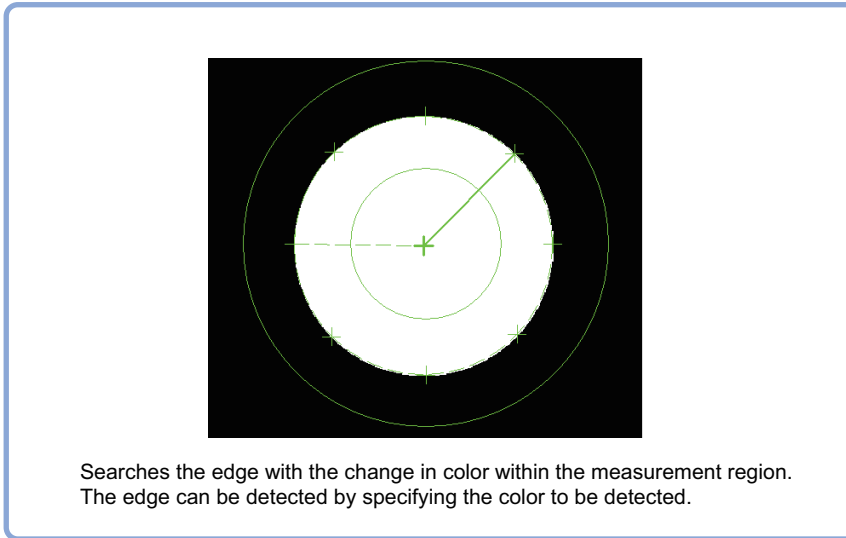
No.	Data name	Set/Get	Data range
143	Edge level specification method	Set/Get	0: % 1: Absolute value
145	Measurement point	Set/Get	1 to 100
146	Mask size	Set/Get	0 to 200
147	Display area	Set/Get	1 to 99
148	Display area (direction)	Set/Get	0: Forward 1: Reverse
149	Measure type	Set/Get	0: Projection 1: Derivation
150	Area division method	Set/Get	0: Do not fix number of area divisions 1: Fix the number of area divisions
151	Monochrome Derivation edge detection mode	Set/Get	0: Absolute 1: Dark→Light 2: Light→Dark
152	Edge Level Upper limit	Set/Get	0 to 100
153	Edge level Upper limit absolute value	Set/Get	0 to 442
154	Filter Strength	Set/Get	0 to 100

Circular Scan Edge Position

This processing item detects the position of the circular measurement object by using the change in color within the measurement region.

Used in the Following Case

- To obtain the center of the circle and the radius from multiple edges of a circular measurement object

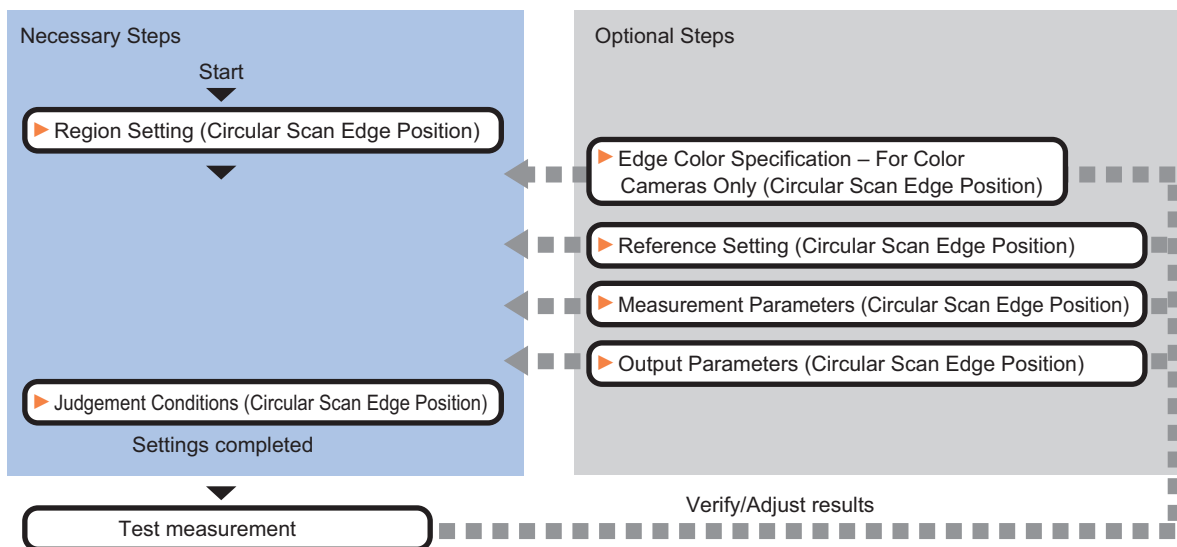


Note

- Edge image measurement processing mechanism
Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Settings Flow (Circular Scan Edge Position)

Set the circular scan edge position with the following steps.



Item List for Circular Scan Edge Position

Item name	Description
Region setting	This item is used to set up the measurement area. Reference: ▶ Region Setting (Circular Scan Edge Position) (p.236)
Edge color (for color cameras only)	If the color of the edges to be detected is decided, specify the information for the edge color to be detected. Reference: ▶ Edge Color Specification - For Color Cameras Only (Circular Scan Edge Position) (p.237)
Ref. setting	This item can be changed if necessary. The edge position measured once is registered when the region is set. Reference: ▶ Reference Setting (Circular Scan Edge Position) (p.238)
Measurement	This item changes the measurement parameter as necessary when the measurement result is unstable. The displayed items depend on whether your camera is a color or monochrome camera. Normally, the factory default value will be used. Reference: ▶ Measurement Parameters (Circular Scan Edge Position) (p.240)
Judgement	This item specifies the judgement condition for measurement results. Reference: ▶ Judgment Conditions (Circular Scan Edge Position) (p.242)
Output parameter	This item can be changed if necessary. Normally, the factory default value may be used. Select the measurement result coordinates and set how to handle the coordinates. Reference: ▶ Output Parameters (Circular Scan Edge Position) (p.243)

Region Setting (Circular Scan Edge Position)

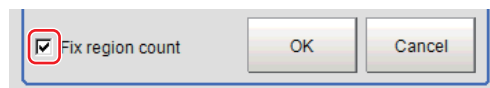
This item is used to set up the measurement area.

Specify the measurement region for [Circular Scan Edge Position] by using circular shapes.

1 In the Item Tab area, click [Region setting].

2 Use the Drawing tools to specify the measurement region.

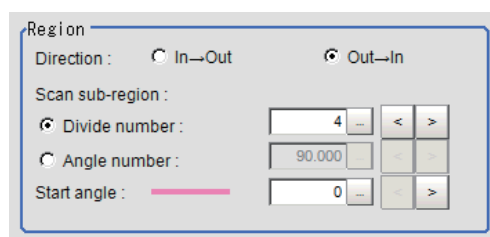
To align with the measurement area and specify the measurement point again, uncheck "Fix region count".



3 Click [OK].

The measurement region is registered and displayed in the Image Display area.

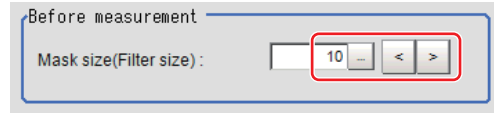
4 Specify the method of measurement, the measurement point, and the start angle for the region.



Setting item	Set value [Factory default]	Description
Direction	<ul style="list-style-type: none"> • [Out→In] • In→Out 	Set the measurement direction.
Scan sub-region		Set the measurement point. Use either the "Divide num" or the "Divide angle" for this setting.
Divide number	3 to 360 [4]	Set the number of divisions for the circle. The specified value is used as the measurement point.

Setting item	Set value [Factory default]	Description
Angle number	1.000 to 179.999 [90.000]	Set the skipping angle for the circle. The measurement point is determined based on the specified angle.
Start angle	0 to 359 [0]	Set the start angle to specify a region.

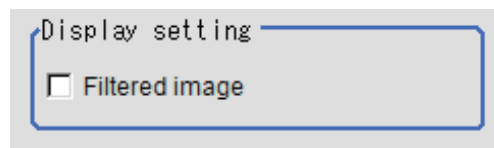
5 Set the mask size for the region.



Setting item	Set value [Factory default]	Description
Mask size	0 to 1000 [10]	Set the filter size when smoothing the measurement point vicinity. When 5 is set, smoothing is processed for a total of 11 points: the measurement point and the 5 pixels before and after it.

6 Perform the display setting if required.

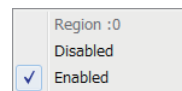
Placing a check at [Filtered image] makes it easier to change the filtering setting.



Setting item	Set value [Factory default]	Description
Filtered image	<ul style="list-style-type: none"> [Unchecked] Checked 	If checked, the filtered image of the ranges set with the Scan sub-region and Filter size after smoothing is displayed.

Note

- Enable or disable setting can be specified for each edge measurement number. Clicking edge measurement points displays the following screen.

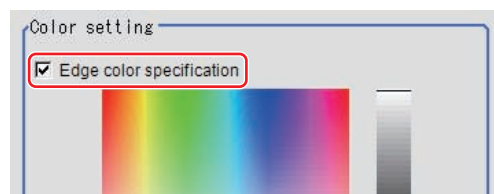


Edge Color Specification - For Color Cameras Only (Circular Scan Edge Position)

This item selects the color of the edges to be detected.

If the target color changes, this setting is not necessary. If the color is not specified, positions in the measurement region where the color changes drastically are detected as an edge.

- In the Item Tab area, click [Edge color].
- Place a check at "Edge color specification" in the "Color setting" area.



- This item selects the color to be detected as edges.

Item	Set value [Factory default]	Description
Image Display area	-	Specify a region on the image that includes the target color. The average color of the specified region is registered.
Color chart	-	Click the reference color on the color chart to specify it. The RGB values for the specified color are displayed at the bottom.

Item	Set value [Factory default]	Description
R, G, B	0 to 255 [255]	The color to be detected is set with the RGB values.
Difference R, G, B	0 to 127 [5]	This sets the allowable color difference for detecting the edge, using the specified color as the reference. The larger the difference values, the larger the color range that is used to detect the edge.
Detection mode	<ul style="list-style-type: none"> • [Color IN] • Color OUT 	<p>Color IN: The position where a color other than the specified color changes to the specified color is detected as the edge.</p> <p>Color OUT: The position where the specified color changes to a color other than the specified color is detected as the edge.</p>

Reference Setting (Circular Scan Edge Position)

When the measurement region is set, this position is automatically set at the same time as the reference position. This item can be used to change the reference position to any desired position. This is handy for measuring the position deviation from a certain position.

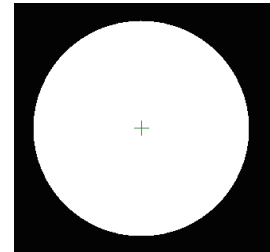
A reference position can be set either directly or by referencing a unit.

Specifying directly

Click a position on the image you want to use as a reference position, or set coordinate data for that point.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.



2 In the "Method" area, select "Numerical".

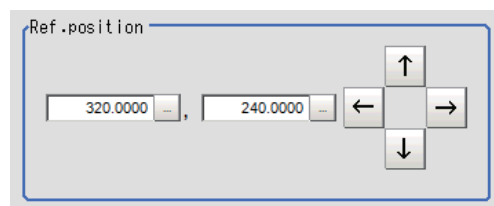


3 Click the position to be set as the reference.

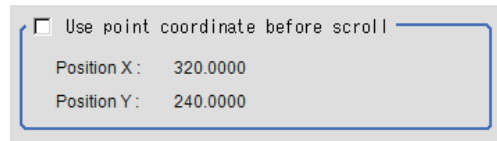
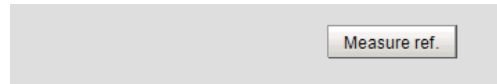
Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

4 Make fine adjustments using numeric value inputs or the arrow buttons as required.



- 5** To remeasure on the displayed image and set the reference, click the [Measure ref.] button.
- 6** To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".



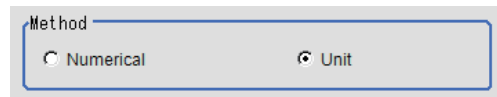
Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

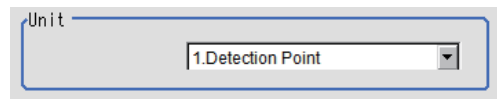
- 1** In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

- 2** In the "Method" area, select "Unit".



- 3** In the scene in the "Unit" area, select a detection point unit.



- 4** Perform the next measurement, and the reference will be displayed.

Measurement Parameters (Circular Scan Edge Position)

Measurement parameters can be changed as needed to address unstable measurement results. Normally, the factory default value will be used.

After changing a setting, check whether measurement can be done properly by performing an actual measurement.

1 In the Item Tab area, click [Measurement].



The edge profile of the measurement region is displayed as a graph in the Image Display area.

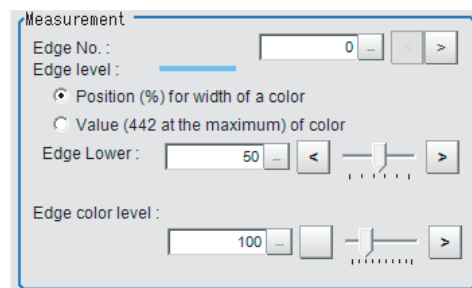
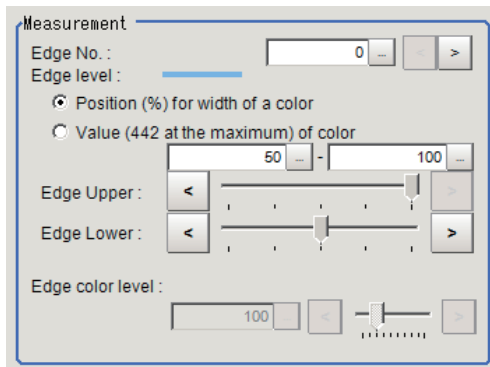
Setting item	Set value [Factory default]	Description
Sub-region No.	0 to 359 [0]	Specify the edge measurement number for which the edge profile is displayed.

2 Set the value of each item in the "Measurement" area.

For color cameras:

Edge Color Not Specified

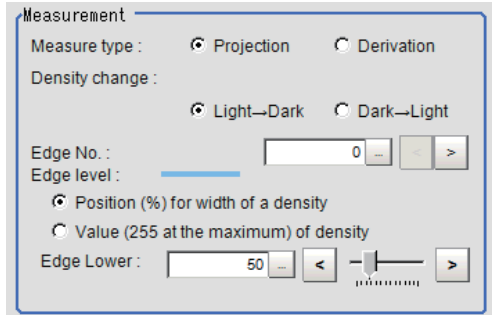
Edge Color Specified



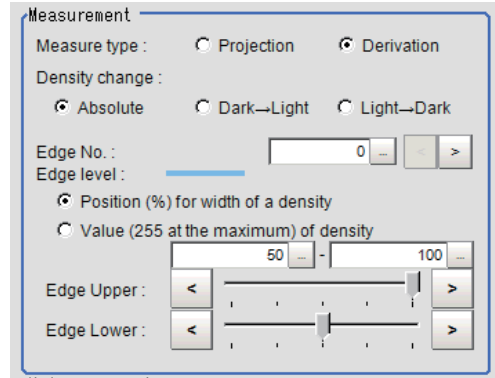
Setting item	Set value [Factory default]	Description
Edge No.	0 to 99 [0]	Specify the edge number used to extract edges. Edge numbers are assigned to detected edges starting from 0 and in the direction from the start point (the arrow) to the end point (the arrow point) in the selected region.
Edge Upper (only when edge color is not specified) Edge Lower	<ul style="list-style-type: none"> Position (%) for width of a color 0 to 100 [50] to [100] Value of color 0 to 442 [20] to [442] 	Set a range of a color difference level with which the edge is detected. Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Edge color level	0 to 442 [100]	This emphasis level can be set only if the edge color to detect is specified.

For monochrome cameras:

When the measurement method is "Projection"

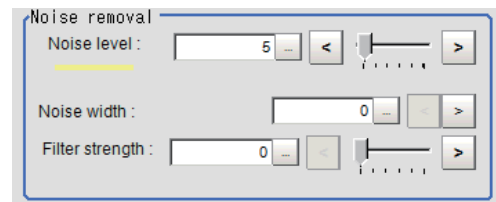


When the measurement method is "Derivation"



Setting item	Set value [Factory default]	Description
Measure type	<ul style="list-style-type: none"> • [Projection] • Derivation 	As the measurement type, specify either projection or derivation. Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Method" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Density change	<ul style="list-style-type: none"> • Absolute (only when the measurement method is "Derivation") • [Light→Dark] • Dark→Light 	Set whether a black-to-white change or a white-to-black change should be recognized as a density change in the specified region.
Edge No.	0 to 99 [0]	Specify the edge number used to extract edges. Edge numbers are assigned to detected edges starting from 0 and in the direction from the start point (the arrow) to the end point (the arrow point) in the selected region.
Edge Upper Edge Lower	<ul style="list-style-type: none"> • Position (%) for width of a density 0 to 100 [50] to [100] • Value of density 0 to 255 [20] to [255] 	Set the density change level to be detected as edges. The upper limit of edges can be set only when the measurement method is "Derivation". Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

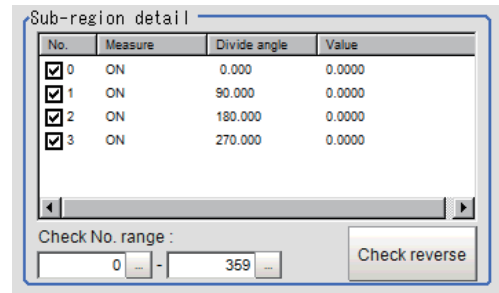
3 If necessary, set each item in the "Noise removal" area.



Setting item	Set value [Factory default]	Description
Noise level	<ul style="list-style-type: none"> • For color cameras 3 to 442 [5] • For monochrome cameras 0 to 255 [5] 	When detection is affected by noise, increase this value. Reference: ▶ "Appendixes Measurement Mechanism Noise Level" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Setting item	Set value [Factory default]	Description
Noise width	0 to 9999 [0]	Set the width for judging noise. When detection is affected by noise, increase this value. Reference: ▶ "Appendixes Measurement Mechanism Noise Width" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Filter strength	0 to 100 [0]	If a valley appears in the histogram around the edge threshold value due to noises, smoothen the edge profile using a filter to prevent wrong error detection from being detected. Strengthening the filter smoothen the edge profile further.

4 In the "Sub-region detail" area, set enable or disable measurement as required.

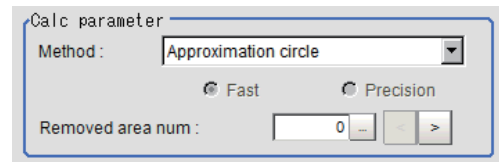


Setting item	Set value [Factory default]	Description
Check No. range	0 to 359 [0] to [359]	Specify the edge measurement number for which to perform batch reversing of the enable or disable measurement setting. Click [Check reverse] to reverse the check box settings of the edge measurement number within the range.

Judgment Conditions (Circular Scan Edge Position)

Specify the range to be judged as OK.

1 In the circle calculation parameter, set the calculation method as required.



Setting item	Set value [Factory default]	Description
Calc parameter	<ul style="list-style-type: none"> [Approximation circle] Smallest enclosing circle 	Specify the circle calculation method. When the calculation from the smallest enclosing circle is selected, specify fast speed or high precision. <ul style="list-style-type: none"> Circular Regression: The circle is calculated with the least square method. Smallest enclosing circle (Fast): A circle that encloses all points is calculated. Smallest enclosing circle (High precision): A circle that encloses all points and that circumscribes three points is calculated.
	<ul style="list-style-type: none"> [Fast] Precision 	
Removed area num	0 to 360 [0]	Set the number of regions to remove. The differences from the circular regression calculated from all measurement points are eliminated in the order of the largest to the smallest.

2 Set up the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Set value [Factory default]	Description
Center X	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Set the range of center coordinate Xs that are judged to be OK.
Center Y	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Set the range of center coordinate Ys that are judged to be OK.
Radius	0 to 99999.9999 [0] to [99999.9999]	Set the range of radiuses that is judged to be OK.
Radius Max.	0 to 99999.9999 [0] to [99999.9999]	Set the maximum radius that is judged to be OK.
Radius Min.	0 to 99999.9999 [0] to [99999.9999]	Set the minimum radius that is judged to be OK.
Decentration X	-99999.999 to 99999.9999 [-99999.9999] to [99999.9999]	Set the range of decentration Xs that is judged to be OK.
Decentration Y	-99999.999 to 99999.9999 [-99999.9999] to [99999.9999]	Set the range of decentration Ys that is judged to be OK.
Lost point count	0 to 360 [0] to [360]	Set the range for the number of lost points that is judged to be OK.

Output Parameters (Circular Scan Edge Position)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

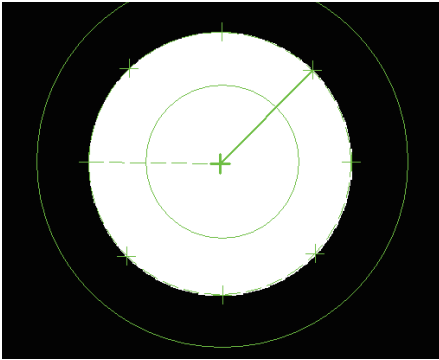
- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- Click [Output parameter] in the Item Tab area.
- Specify each of the following items.

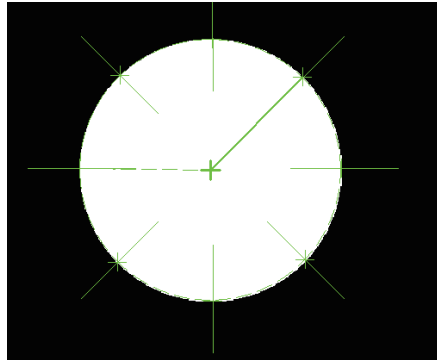
Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> [After scroll] Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.
Calibration	<ul style="list-style-type: none"> [OFF] ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> [ON] OFF 	Enables choosing whether or not the judgment results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (Circular Scan Edge Position)

In addition to the camera input image, the measured region, a graphic display of the measured results, and the edge position (the crosshair cursor) are also displayed as results in the Image Display area.



Edge position display (Sub image 0)



Display of edge position in each divided part (Sub image 1)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Center coordinate X	The center X coordinate of the calculation result
Center coordinate Y	The center Y coordinate of the calculation result
Radius	The radius of the calculation result
Maximum radius	The maximum radius of the calculation result
Minimum radius	The minimum radius of the calculation result
Decentration X	The decentration X of the calculation result
Decentration Y	The decentration Y of the calculation result
Number of lost points	Number of parts for which the detection of edges has failed

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Parameter to be adjusted	Remedy
Measurement	If the color of the edges to be detected is decided, specify the color with [Edge color]. If results are not stable even with the color specified, specify a larger value for the color variance range.
	If noise is detected as an edge, specify larger values for "Noise level" and "Noise width".

Measurement Results for Which Output Is Possible (Circular Scan Edge Position)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	The judgment result for the unit 1: OK 0: Not yet measured -1: NG
Center coordinate X	X	The center X coordinate of the calculation result
Center coordinate Y	Y	The center Y coordinate of the calculation result
Radius	R	The radius of the calculation result
Maximum radius	MAXR	The maximum radius of the calculation result
Minimum radius	MINR	The minimum radius of the calculation result
Decentration X	DEX	The decentration X of the calculation result
Decentration Y	DEY	The decentration Y of the calculation result
Number of lost points	LOST	Number of parts for which the detection of edges has failed
Reference coordinate X	SX	X coordinate of the reference coordinates
Reference coordinate Y	SY	Y coordinate of the reference coordinates
Maximum radius region number	MAXNO	The region number for the maximum radius
Minimum radius region number	MINNO	The region number for the minimum radius

External Reference Tables (Circular Scan Edge Position)

No.	Data name	Set/Get	Data range
0	Overall judgement result	Get only	1: OK 0: Not yet measured -1: NG
5	Center coordinate X	Get only	-99999.9999 to 99999.9999
6	Center coordinate Y	Get only	-99999.9999 to 99999.9999
7	Radius	Get only	0 to 99999.9999
8	Maximum radius	Get only	0 to 99999.9999
9	Minimum radius	Get only	0 to 99999.9999
10	Decentration X	Get only	-99999.9999 to 99999.9999
11	Decentration Y	Get only	-99999.9999 to 99999.9999
12	Number of lost points	Get only	0 to 360
13	Reference X	Get only	0 to 99999.9999
14	Reference Y	Get only	0 to 99999.9999
15	Maximum radius region number	Get only	0 to 359
16	Minimum radius region number	Get only	0 to 359
17	Approx. radius	Get only	0 to 99999.9999
101	Output coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
125	Region that displays the edge profile	Set/Get	0 to 359
127	Fix the measurement point count	Set/Get	0: Not fixed 1: Fixed
140	Removed region number	Set/Get	0 to 360
141	Reference X	Set/Get	0 to 99999.9999
142	Reference Y	Set/Get	0 to 99999.9999
143	Circle calculation method	Set/Get	0: Calculated from the circular regression 1: Calculated from the minimum enclosing circle
144	Enclosing circle calculation method	Set/Get	0: Fast 1: High precision
145	Center coordinate X upper limit	Set/Get	-99999.9999 to 99999.9999
146	Center coordinate X lower limit	Set/Get	-99999.9999 to 99999.9999
147	Center coordinate Y upper limit	Set/Get	-99999.9999 to 99999.9999
148	Center coordinate Y lower limit	Set/Get	-99999.9999 to 99999.9999
149	Radius upper limit	Set/Get	0 to 99999.9999

No.	Data name	Set/Get	Data range
150	Radius lower limit	Set/Get	0 to 99999.9999
151	Maximum radius upper limit	Set/Get	0 to 99999.9999
152	Maximum radius lower limit	Set/Get	0 to 99999.9999
153	Minimum radius upper limit	Set/Get	0 to 99999.9999
154	Minimum radius lower limit	Set/Get	0 to 99999.9999
155	Decentration X upper limit	Set/Get	-99999.9999 to 99999.9999
156	Decentration X lower limit	Set/Get	-99999.9999 to 99999.9999
157	Decentration Y upper limit	Set/Get	-99999.9999 to 99999.9999
158	Decentration Y lower limit	Set/Get	-99999.9999 to 99999.9999
159	Number of lost points upper limit	Set/Get	0 to 360
160	Number of lost points lower limit	Set/Get	0 to 360
200	Edge color specification	Set/Get	0: No color specification 1: With color specification
201	Edge color R	Set/Get	0 to 255
202	Edge color G	Set/Get	0 to 255
203	Edge color B	Set/Get	0 to 255
204	Difference R	Set/Get	0 to 127
205	Difference G	Set/Get	0 to 127
206	Difference B	Set/Get	0 to 127
207	Edge detection mode	Set/Get	0: Specified color IN 1: Specified color OUT
208	Edge No.	Set/Get	0 to 99
209	Edge Level	Set/Get	0 to 100
210	Noise level	Set/Get	0 to 442
211	Noise width	Set/Get	0 to 9999
212	Edge color enhancement level	Set/Get	0 to 442
213	Monochrome edge detection mode	Set/Get	0: Light→Dark 1: Dark→Light
214	Edge level absolute value	Set/Get	0 to 442
215	Edge level specification method	Set/Get	0: % 1: Absolute value
216	Measure type	Set/Get	0: Projection 1: Derivation
217	Monochrome Derivation edge detection mode	Set/Get	0: Absolute 1: Dark→Light 2: Light→Dark
218	Edge Level Upper limit	Set/Get	0 to 100
219	Edge level Upper limit absolute	Set/Get	0 to 442
220	Filter Strength	Set/Get	0 to 100
221	Setting unit of reference coordinate	Set/Get	-1 to 9999

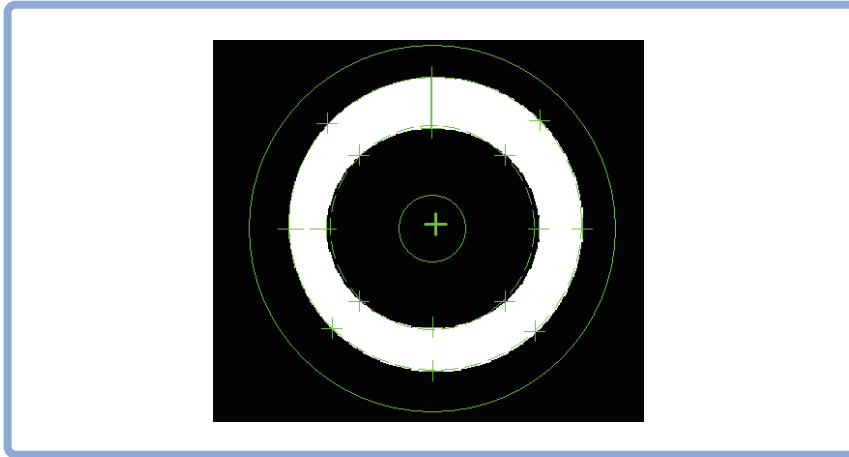
No.	Data name	Set/Get	Data range
222	Setting type of reference coordinate	Set/Get	0: Numerical 1: Unit
223	Use point coordinate before scroll	Set/Get	0: Not use 1: Unit
224	Position X before scroll	Set/Get	-99999.9999 to 99999.9999
225	Position Y before scroll	Set/Get	-99999.9999 to 99999.9999

Circular Scan Edge Width

This processing item detects the width of the measurement object by using the change in color within the measurement region.

Used in the Following Case

- When getting multiple widths of a circular object

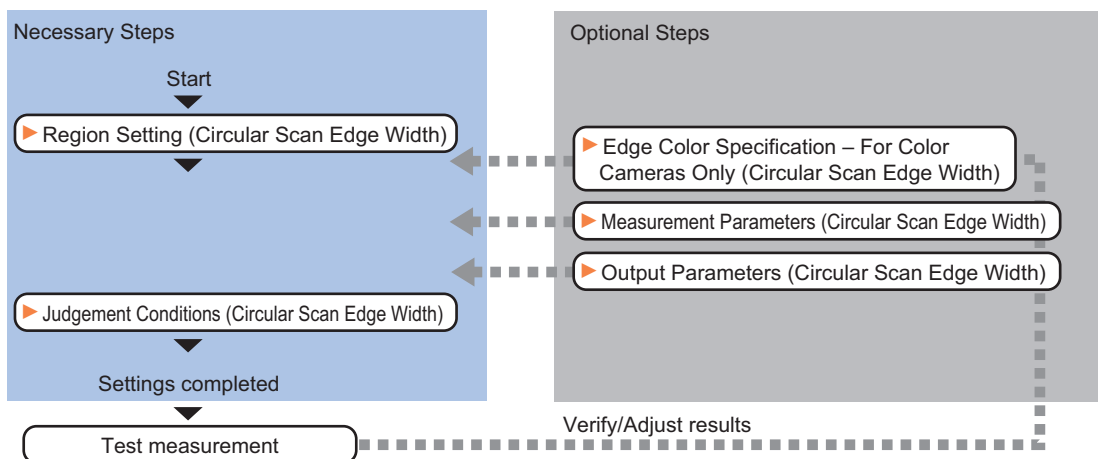


Note

- Edge image measurement processing mechanism
Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Settings Flow (Circular Scan Edge Width)

Set the circular scan edge width with the following steps.



Item List for Circular Scan Edge Width

Item name	Description
Region setting	This item is used to set up the measurement area. Reference: ▶Region Setting (Circular Scan Edge Width) (p.250)
Edge color (for color cameras only)	This item selects the color information for the edges to be detected. Reference: ▶Edge Color Specification - For Color Cameras Only (Circular Scan Edge Width) (p.252)
Measurement	This item changes the measurement parameter as necessary when the measurement result is unstable. The displayed items depend on whether your camera is a color or monochrome camera. Normally, the factory default value will be used. Reference: ▶Measurement Parameters (Circular Scan Edge Width) (p.252)
Judgement	This item specifies the judgement condition for measurement results. Reference: ▶Judgement Conditions (Circular Scan Edge Width) (p.255)
Output parameter	This item can be changed if necessary. Normally, the factory default value may be used. Select the measurement result coordinates and set how to handle the coordinates. Reference: ▶Output Parameters (Circular Scan Edge Width) (p.256)

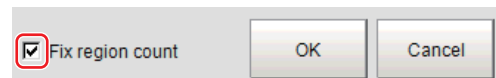
Region Setting (Circular Scan Edge Width)

This item is used to set up the measurement area.

Specify the measurement region of [Circular Scan Edge Width] by using circular shapes.

- 1 In the Item Tab area, click [Region setting].**
- 2 Use the Drawing tools to specify the measurement region.**

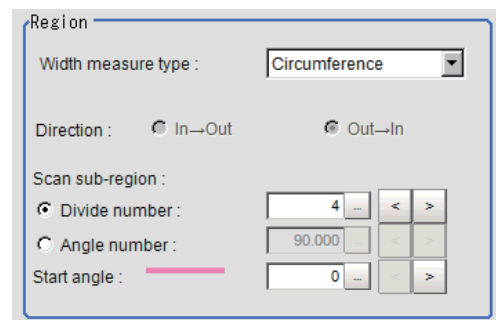
To align with the measurement area and specify the measurement point again, uncheck "Fix region count".



- 3 Click [OK].**

The measurement region is registered and displayed in the Image Display area.

- 4 In the "Region" area, specify a value for each item.**



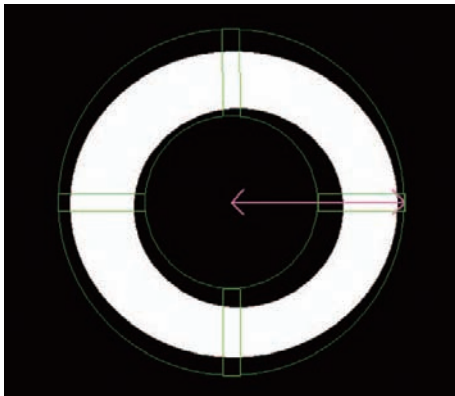
Setting item	Set value [Factory default]	Description
Width measure type	<ul style="list-style-type: none"> [Circumference] Diameter 	Select the measurement target for the workpiece.
Direction	<ul style="list-style-type: none"> In→Out [Out→In] 	Set the measurement direction when [Diameter] is selected.
Scan sub-region		Set the measurement point. Use either the "Divide num" or the "Divide angle" for this setting.

Setting item		Set value [Factory default]	Description
	Divide number	3 to 360 [4]	Set the number of divisions for the circle. The specified value is used as the measurement point.
	Angle number	When the width measure type is circumference 1.000 to 179.999 When the width measure type is diameter 1.000 to 90.000 [90.000]	Set the skipping angle for the circle. The measurement point is determined based on the specified angle.
Start angle		0 to 359 [0]	Set the start angle to specify a region.

Important

- When the width measurement target is set to "Diameter" and the number of divisions and the skipping angle are set to an odd number value, 1 will be added to these settings so that they become even numbers.

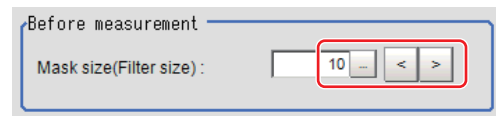
The region is divided by the specified number of points.



Explanations of the display

- Green solid line:
Represents the circular region.
- Rectangle:
Represents the sub-region.
- Pink solid line:
Represents the angle and the measurement direction (arrow) to specify the region.

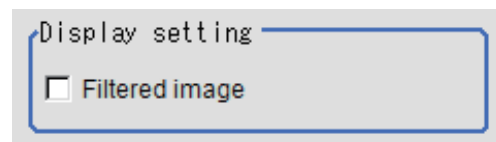
5 Specify the filtering settings as necessary.



Setting item	Set value [Factory default]	Description
Mask size	0 to 1000 [10]	Set the filter size when smoothing the measurement point vicinity. When 5 is set, smoothing is processed for a total of 11 points: the measurement point and the 5 pixels before and after it.

6 Perform the display setting if required.

Placing a check at [Filtered image] makes it easier to change the filtering setting.



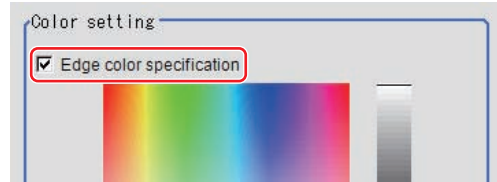
Setting item	Set value [Factory default]	Description
Filtered image	<ul style="list-style-type: none"> [Unchecked] Checked 	If checked, the filtered image of the ranges set with the Scan sub-region and Filter size after smoothing is displayed.

Edge Color Specification - For Color Cameras Only (Circular Scan Edge Width)

This item selects the color of the edges to be detected.

If the target color changes, this setting is not necessary. If the color is not specified, positions in the measurement region where the color changes drastically are detected as an edge.

- 1** In the Item Tab area, click [Edge color].
- 2** Place a check at "Edge color specification" in the "Color setting" area.



- 3** This item selects the color to be detected as edges.

Setting method	Set value [Factory default]	Description
Image Display area	-	Specify a region on the image that includes the target color. The average color of the specified region is registered.
Color chart	-	Click the reference color on the color chart to specify it. The RGB values for the specified color are displayed at the bottom.
R, G, B	0 to 255 [255]	The color to be detected is set with the RGB values.
Difference R, G, B	0 to 127 [5]	This sets the allowable color difference for detecting the edge, using the specified color as the reference. The larger the difference values, the larger the color range that is used to detect the edge.
Detection mode	<ul style="list-style-type: none"> • [Color IN] • Color OUT 	<p>Specified color IN: The position where a color other than the specified color changes to the specified color is detected as the edge. Specified color OUT: The position where the specified color changes to a color other than the specified color is detected as the edge.</p> <div style="display: flex; justify-content: space-around; align-items: center;"> <div style="text-align: center;"> <p>For "Color IN" edge measurement mode</p> </div> <div style="text-align: center;"> <p>For "Color OUT" edge measurement mode</p> </div> </div>

Measurement Parameters (Circular Scan Edge Width)

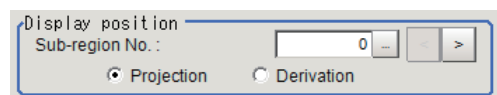
Measurement parameters can be changed as needed to address unstable measurement results. Normally, the factory default value will be used.

After changing a setting, check whether measurement can be done properly by performing an actual measurement.

- 1** In the Item Tab area, click [Measurement].

The edge profile of the measurement region is displayed as a graph in the Image Display area.

- 2** In the "Display position" area, specify a value for each item.

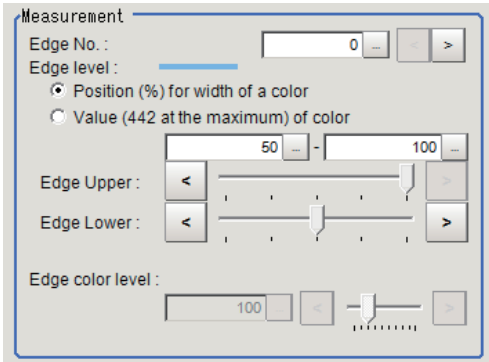


Setting item	Set value [Factory default]	Description
Sub-region No.	0 to 359 [0]	Set the edge measurement number for which the edge profile is displayed.
	<ul style="list-style-type: none"> • [Projection] • Derivation 	Projection: The edge is searched from the center toward the outside direction. Derivation: The edge is searched from the outside of the circle toward the center.

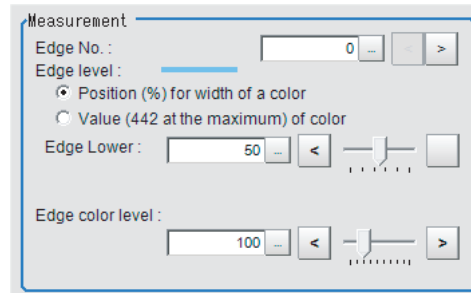
3 Set the value of each item in the "Measurement" area.

For color cameras:

Edge Color Not Specified



Edge Color Specified

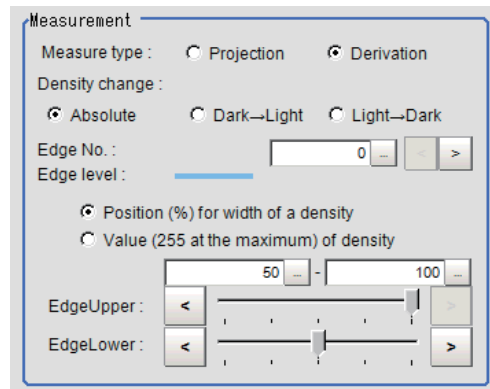
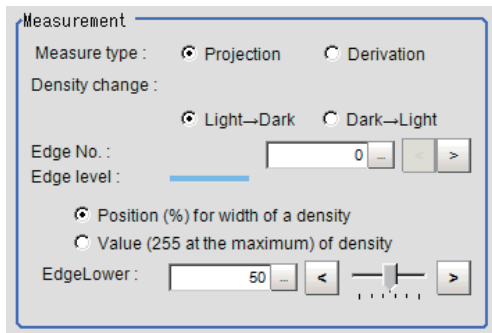


Setting item	Set value [Factory default]	Description
Edge No.	0 to 99 [0]	Specify the edge number used to extract edges. Edge numbers are assigned to detected edges starting from 0 and in the direction from the start point (the arrow) to the end point (the arrow point) in the selected region.
Edge Upper (only when edge color is not specified) Edge Lower	<ul style="list-style-type: none"> • Position (%) for width of a color 0 to 100 [50] to [100] • Value of color 0 to 442 [20] to [442] 	Set a range of a color difference level with which the edge is detected. Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Edge color level	0 to 442 [100]	This emphasis level can be set only if the edge color to detect is specified.

For monochrome cameras:

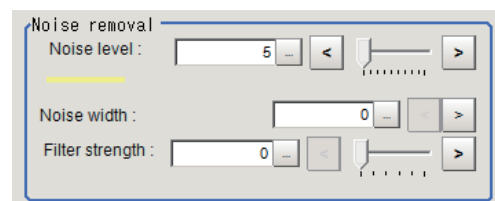
When the measurement method is "Projection"

When the measurement method is "Derivation"



Setting item	Set value [Factory default]	Description
Measure type	<ul style="list-style-type: none"> • [Projection] • Derivation 	As the measurement type, specify either projection or derivation. Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Method" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Density change	<ul style="list-style-type: none"> • Absolute (only when the measurement method is "Derivation") • [Light→Dark] • Dark→Light 	Set whether a black-to-white change or a white-to-black change should be recognized as a density change in the specified region.
Edge No.	0 to 99 [0]	Specify the edge number used to extract edges. Edge numbers are assigned to detected edges starting from 0 and in the direction from the start point (the arrow) to the end point (the arrow point) in the selected region.
Edge Upper Edge Lower	<ul style="list-style-type: none"> • Position (%) for width of a density 0 to 100 [50] to [100] • Value of density 0 to 255 [20] to [255] 	Set the density change level to be detected as edges. The upper limit of edges can be set only when the measurement method is "Derivation". Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

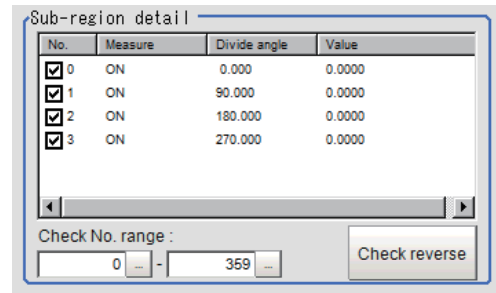
4 If necessary, set each item in the "Noise removal" area.



Setting item	Set value [Factory default]	Description
Noise level	<ul style="list-style-type: none"> • For color cameras 0 to 442 [5] • For monochrome cameras 0 to 255 [5] 	When detection is affected by noise, increase this value. Reference: ▶ "Appendixes Measurement Mechanism Noise Level" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Noise width	0 to 9999 [0]	Set the width for judging noise. When detection is affected by noise, increase this value. Reference: ▶ "Appendixes Measurement Mechanism Noise Width" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Setting item	Set value [Factory default]	Description
Filter strength	0 to 100 [0]	If a valley appears in the histogram around the edge threshold value due to noises, smoothen the edge profile using a filter to prevent wrong error detection from being detected. Strengthening the filter smoothen the edge profile further.

- 5** In the "Sub-region detail" area, set enable or disable measurement as required.



Setting item	Set value [Factory default]	Description
Check No. range	0 to 359 [0] to [359]	Specify the edge measurement number for which to perform batch reversing of the enable or disable measurement setting. Click [Check reverse] to reverse the check box settings of the edge measurement number within the range.

Judgement Conditions (Circular Scan Edge Width)

Specify the range to be judged as OK.

- 1** In the Item Tab area click [Judgement].
- 2** Set up the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Set value [Factory default]	Description
Edge width Max.	0 to 99999.9999 [0] to [99999.9999]	Specify the upper and lower limits of the maximum width judged to be OK.
Edge width Min.	0 to 99999.9999 [0] to [99999.9999]	Specify the upper and lower limits of the minimum width judged to be OK.
Edge width Ave.	0 to 99999.9999 [0] to [99999.9999]	Specify the upper and lower limits of the average width judged to be OK.
Lost width count	0 to 360 [0] to [360]	Specify the upper and lower limits of the lost width count judged to be OK.

Output Parameters (Circular Scan Edge Width)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Set value [Factory default]	Description
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgment results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (Circular Scan Edge Width)

The following contents can be displayed as text in the "Detail result" area.

Displayed items	Description
Judge	Judgement result
Edge width Max.	The maximum value of edge width
Edge width Min.	The minimum value of edge width
Edge width Ave.	The average value of all the edge width
Lost width count	The number of the scanned areas for which the detection of width failed

The image specified in the sub image in image display setting is displayed in the Image Display area.

Sub image number.	Explanation of image to be displayed
0	Measurement image
1	Scan region

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Parameter to be adjusted	Remedy
Measurement	If the color of the edges to be detected is decided, specify the color with [Edge color]. If results are not stable even with the color specified, specify a larger value for the color variance range.
	If noise is detected as an edge, specify larger values for "Noise level" and "Noise width".

Measurement Results for Which Output Is Possible (Circular Scan Edge Width)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Edge width Max.	MAXW	The maximum value of edge width
Edge width Min.	MINW	The minimum value of edge width
Edge width Ave.	AVEW	The average value of all the edge width
Lost width count	LOST	The number of the scanned areas for which the detection of width failed
Edge width Max. region No.	MAXNO	Region number of maximum edge width
Edge width Min. region No.	MINNO	Region number of minimum edge width

External Reference Tables (Circular Scan Edge Width)

No.	Data name	Set/Get	Data range
0	Overall judgement result	Get only	1: OK 0: Not yet measured -1: NG
5	Edge width Max.	Get only	0 to 99999.9999
6	Edge width Min.	Get only	0 to 99999.9999
7	Edge width Ave.	Get only	0 to 99999.9999
10	Lost width count	Get only	0 to 360
11	Region number of maximum edge width	Get only	0 to 359
12	Region number of minimum edge width	Get only	0 to 359
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
125	Region that displays the edge profile	Set/Get	0 to 359
127	Fix the measurement point count	Set/Get	0: Not fixed 1: Fixed
140	Width measure type	Set/Get	0: Circle width 1: Diameter
141	Edge profile display direction	Set/Get	0: Forward 1: Reverse
142	Upper limit of maximum edge width	Set/Get	0 to 99999.9999
143	Lower limit of maximum edge width	Set/Get	0 to 99999.9999
144	Upper limit of minimum edge width	Set/Get	0 to 99999.9999
145	Lower limit of minimum edge width	Set/Get	0 to 99999.9999
146	Upper limit of average edge width	Set/Get	0 to 99999.9999
147	Lower limit of average edge width	Set/Get	0 to 99999.9999
148	Upper limit of number of lost width count	Set/Get	0 to 360

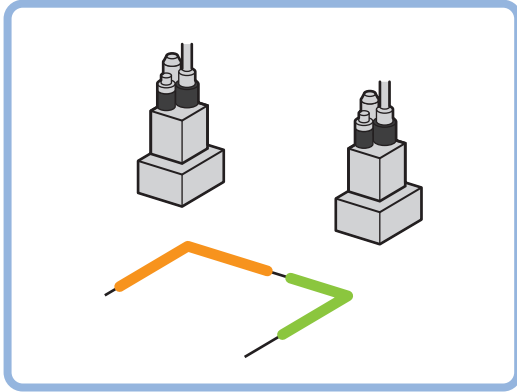
No.	Data name	Set/Get	Data range
149	Lower limit of number of lost width count	Set/Get	0 to 360
200	Edge color specification	Set/Get	0: No color specification 1: With color specification
201	Edge color R	Set/Get	0 to 255
202	Edge color G	Set/Get	0 to 255
203	Edge color B	Set/Get	0 to 255
204	Difference R	Set/Get	0 to 127
205	Difference G	Set/Get	0 to 127
206	Difference B	Set/Get	0 to 127
207	Edge detection mode	Set/Get	0: Specified color IN 1: Specified color OUT
208	Edge No.	Set/Get	0 to 99
209	Edge Level	Set/Get	0 to 100
210	Noise level	Set/Get	0 to 442
211	Noise width	Set/Get	0 to 9999
212	Edge color enhancement level	Set/Get	0 to 442
213	Monochrome edge detection mode	Set/Get	0: Light→Dark 1: Dark→Light
214	Edge level absolute value	Set/Get	0 to 442
215	Edge level specification method	Set/Get	0: % 1: Absolute value
216	Measure type	Set/Get	0: Projection 1: Differential
217	Monochrome Derivation edge detection mode	Set/Get	0: Absolute 1: Dark→Light 2: Light→Dark
218	Edge Level Upper limit	Set/Get	0 to 100
219	Edge level Upper limit absolute value	Set/Get	0 to 442
220	Filter Strength	Set/Get	0 to 100

Intersection

This processing item measures a corner position (corner) of a work.
Calculate approximate lines from the edge information on two sides of a square work to measure the angle formed at the intersection of the two lines.

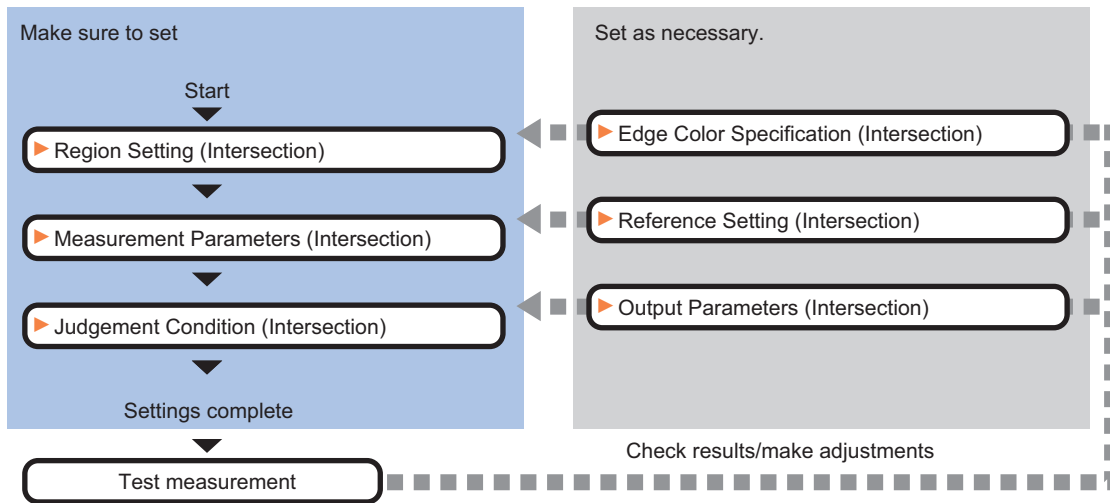
Used in the Following Case

- When you want to align the work position based on the feature of its corner



Settings Flow (Intersection)

Follow the steps below to set up intersection coordinates.



List of Intersection Items

Item name	Description
Region setting	This item sets the scan edge area (wide line) for each the two sides to be measured. Reference: ▶ Region Setting (Intersection) (p.260)
Edge color	This item sets the color of the edges to be detected. If the target color changes, this setting is not necessary. If the color is not set, positions in the measurement region where the color changes drastically are detected as an edge. Reference: ▶ Edge Color Specification - For Color Cameras Only (Intersection) (p.261)
Ref. setting	The edge position is registered as the reference when the region is set. Change as necessary. This is changed when measuring the position deviation from a certain position. Reference: ▶ Reference Setting (Intersection) (p.262)
Measurement	This item sets the parameters relating to edge measurement and Line Regression calculation to measure the intersection coordinates. Reference: ▶ Measurement Parameters (Intersection) (p.263)
Judgement	This item specifies the judgement condition for measurement results. Reference: ▶ Judgement Condition (Intersection) (p.266)
Output parameter	This item can be changed if necessary. Select the measurement result coordinates and set how to handle the coordinates. Reference: ▶ Output Parameters (Intersection) (p.266)

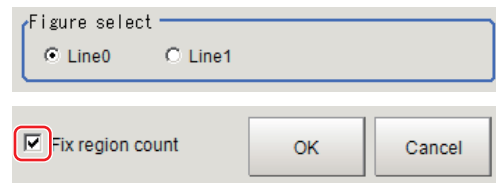
Region Setting (Intersection)

This item is used to set up the measurement area.

Specify the measurement region for [Intersection Coordinates] by using wide lines.

1 In the Item Tab area, click [Region setting].

2 Select the figure to be set.



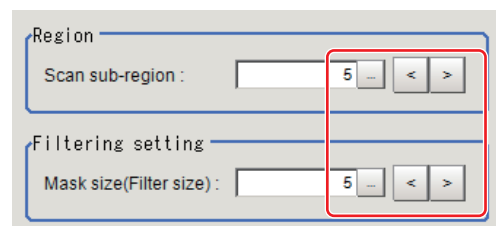
3 Use the Drawing tools to set the measurement region.

To align with the measurement area and change the number of measurement points, uncheck this.

4 In the figure setting area, click [OK].

The measurement region is registered and displayed in the Image Display area.

5 Set the measurement point and the filter size for the region.



Setting item	Setting value [Factory default]	Description
Scan sub-region	1 to 100 [5]	Set the measurement point for the region.
Mask size (Filter size)	1 to 1000 [5]	Set the filter size when smoothing the measurement point vicinity. When 5 is set, smoothing is processed for a total of 11 points: the measurement point and the 5 pixels before and after it.

6 The region is divided equally.

Scan region when scan sub-region is 1



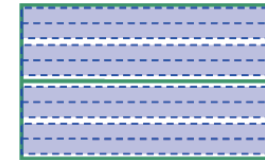
Scan region when scan sub-region is 2



Scan region when scan sub-region is 3

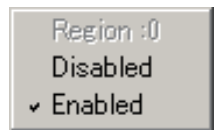


Scan region when scan sub-region is 4



Note

- Enable or disable setting can be specified for each edge measurement number. Clicking edge measurement points displays the following screen.



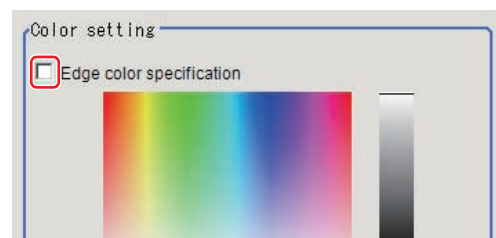
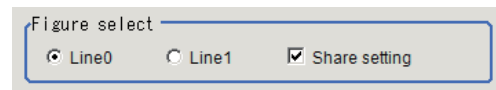
7 Repeat steps 2 to 6, and set the region of line 1.

Edge Color Specification - For Color Cameras Only (Intersection)

This item sets the color of the edges to be detected.

If the target color changes, this setting is not necessary. If the color is not set, positions in the measurement region where the color changes drastically are detected as an edge.

- 1 In the Item Tab area, click [Edge color].
- 2 Select the figure to be color specified. Uncheck "Share setting" if you want to use different settings for line 0 and line 1.
- 3 Place a check at [Edge color specification] in the "Color setting" area.
- 4 Set the color to be detected as edges.



Setting Methods	Description
Image Display area	Set a region on the image that includes the target color. The average color of the set region is registered.
Color chart	Click the reference color on the color chart to set it. The RGB values for the set color are displayed at the bottom.
R, G, B	The color to be detected is set with the RGB values.
Difference R, G, B	Set the allowable color difference for detecting the edge, using the set color as the reference. The larger the difference values, the larger the color range that is used to detect the edge.

Setting Methods	Description
Detection mode	<p>Color IN: The position where a color other than the specified color changes to the specified color is detected as the edge.</p> <p>Color OUT: The position where the specified color changes to a color other than the specified color is detected as the edge.</p>

Reference Setting (Intersection)

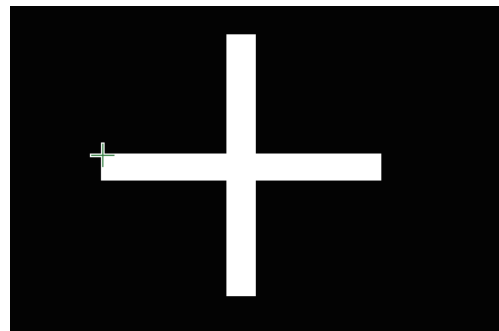
When the measurement region is set, this position is automatically set at the same time as the reference position. This item can be used to change the reference position to any desired position. A reference position can be set either directly or by referencing a unit.

Specifying directly

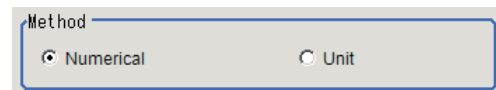
Click a position on the image you want to use as a reference position, or set coordinate data for that point.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.



2 In the "Method" area, select "Numerical".

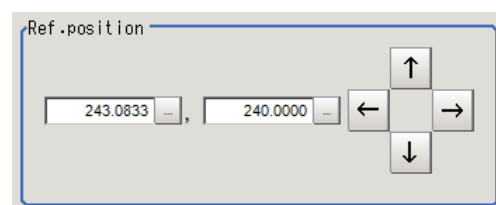


3 Click the position to be set as the reference.

Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

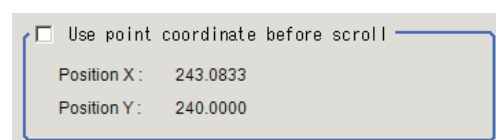
4 If necessary, finely adjust with numeric input and the arrow buttons.



5 To remeasure on the displayed image and set the reference, click the [Measure ref.] button.



6 To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".



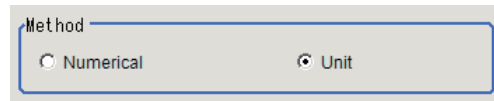
Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

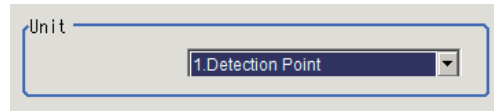
1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

2 In the "Method" area, select "Unit".



3 In the scene in the "Unit" area, select a detection point unit.



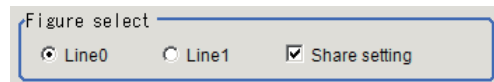
4 Perform the next measurement, and the reference will be displayed.

Measurement Parameters (Intersection)

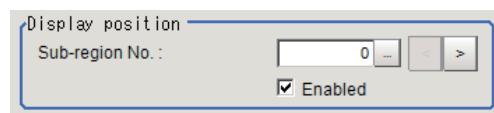
Set the measurement conditions of intersection coordinates.

1 In the Item Tab area, click [Measurement].

2 In the "Figure select" area, select the lines to be set.



3 In the "Display position" area, set the region number if the region is enabled.

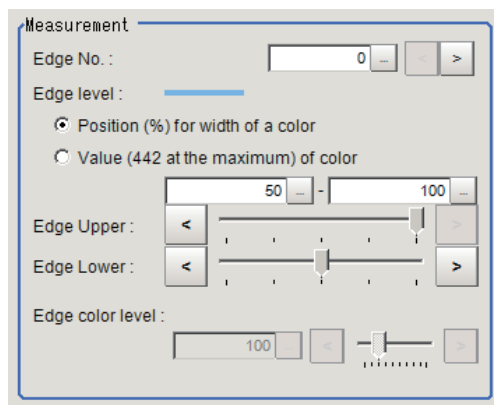


Setting item	Setting value [Factory default]	Description
Sub-region No.	[0] to 99	Set the edge measurement number for which the edge profile is displayed.
Enabled	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Select enable/disable for the displayed edge measurement number. When disabled (unchecked) is selected, that edge measurement number is not measured.

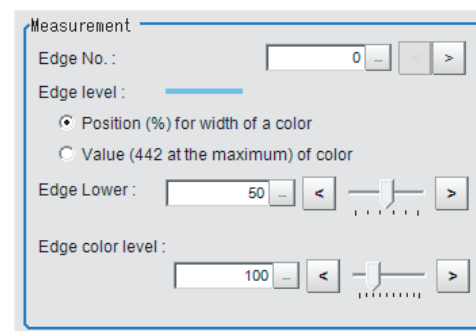
4 Set the value of each item in the "Measurement" area.

For color cameras:

Edge Color Not Specified



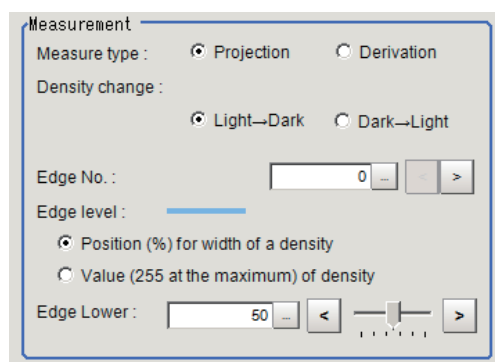
Edge Color Specified



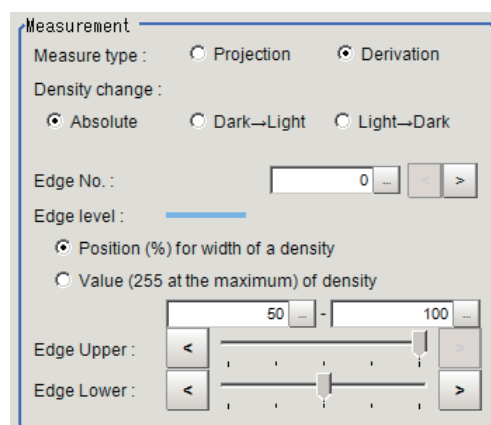
Setting item	Setting value [Factory default]	Description
Edge No.	0 to 99 [0]	Set the edge number used to extract edges. Edge numbers are assigned to detected edges starting from 0 and in the direction from the start point (the arrow) to the end point (the arrow point) in the selected region.
Edge Upper (only when edge color is not specified) Edge Lower	<ul style="list-style-type: none"> Position (%) for width of a color 0 to 100 [50] to [100] Value (442 at the maximum) of color [20] to [442] 	Set a range of a color difference level with which the edge is detected. Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Edge color level	0 to 442 [100]	This emphasis level can be set only if the edge color to detect is set.

For monochrome cameras:

When the measurement method is "Projection"

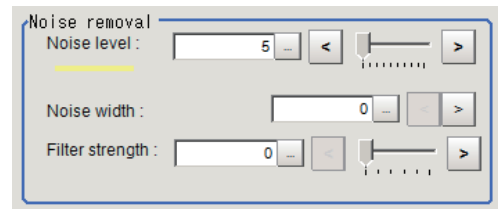


When the measurement method is "Derivation"



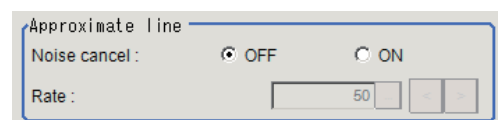
Setting item	Setting value [Factory default]	Description
Measure type	<ul style="list-style-type: none"> • [Projection] • Derivation 	As the measurement type, select either projection or derivation. Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Method" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Density change	<ul style="list-style-type: none"> • Absolute value (only when the measurement method is "Derivation") • [Light → Dark] • Dark → Light 	Select whether a black-to-white change or a white-to-black change should be recognized as a density change in the specified region.
Edge No.	0 to 99 [0]	Set the edge number used to extract edges. Edge numbers are assigned to detected edges starting from 0 and in the direction from the start point (the arrow) to the end point (the arrow point) in the selected region.
Edge Upper Edge Lower	<ul style="list-style-type: none"> • Position (%) for width of a density 0 to 100 [50] to [100] • Value (255 at the maximum) of density [20] to [255] 	Set the density change level to be detected as edges. The upper limit of edges can be set only when the measurement method is "Derivation". Reference: ▶ "Appendixes Measurement Mechanism Edge Detection Measurement" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

5 If necessary, set each item in the "Noise removal" area.



Setting item	Setting value [Factory default]	Description
Noise level	0 to 442 [5]	When detection is affected by noise, increase this value. Reference: ▶ "Appendixes Measurement Mechanism Noise Level" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Noise width	0 to 9999 [0]	Set the width for judging noise. When detection is affected by noise, increase this value. Reference: ▶ "Appendixes Measurement Mechanism Noise Width" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
Filter strength	0 to 100 [0]	Set the filter strength. Specifying a larger value here makes the change in color difference (density) distribution more gradual.

6 In the "Approximate line" area, select the point to be used for the calculation of approximate lines.



Setting item	Setting value [Factory default]	Description
Noise cancel	<ul style="list-style-type: none"> • ON • [OFF] 	When a check is placed at [ON], an approximate line is found by excluding the points with large deviation among the measured points.
Rate	0 to 100 [50]	Set the rate for all of the measurement points used to calculate the approximate line. If there is a lot of noise, set a smaller value to eliminate a lot of noise points when calculating the approximate line. If there is little noise, set a larger value to use more measurement points to increase the accuracy when calculating the approximate line.

Judgement Condition (Intersection)

Specify the range to be judged as OK.

- 1 In the Item Tab area, click [Judgement].
- 2 Set up the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Setting value	Description
Intersection X	-99999.9999 to 99999.9999	Set the range of X coordinates of intersection that is judged to be OK.
Intersection Y	-99999.9999 to 99999.9999	Set the range of Y coordinates of intersection that is judged to be OK.
Angle	0.0000 to 180.0000	Set the angle formed by two lines that are judged to be OK.
Lost point count (Line 0)	0 to 100	Set the lost point count to be judged as OK.
Lost point count (Line 1)		

Output Parameters (Intersection)

Set how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Setting value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.

Setting item	Setting value [Factory default]	Description
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Specify whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Intersection)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Intersection coordinate X	X coordinate of measured intersection
Intersection coordinate Y	Y coordinate of measured intersection
Angle	Angle of measured 2 lines
Lost point count (line 0)	Lost point count of measured line 0
Lost point count (line 1)	Lost point count of measured line 1

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

State	Parameter to be adjusted	Troubleshooting
Approximate lines are not stable due to noise.	Measurement	Use the noise removal function to make sure approximate lines are measured stably.

When judgement is NG

Parameter to be adjusted	Troubleshooting
Region setting	Confirm that the approximate line calculated for line 0 intersects with the approximate line calculated for line 1. If the approximate lines are parallel, a judgement will be NG.

Measurement Results for Which Output Is Possible (Intersection)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Intersection coordinate X	X	X coordinate of intersection
Intersection coordinate Y	Y	Y coordinate of intersection
Angle	TH	Angle between two lines
Reference X	SX	X coordinate of the reference coordinates
Reference Y	SY	Y coordinate of the reference coordinates
Peak edge position X of line 0	PEEKX0	X coordinate of the edge of line 0 that is the furthest from the start point of the measurement region

Measurement items	Character string	Description
Peak edge position Y of line 0	PEEKY0	Y coordinate of the edge of line 0 that is the furthest from the start point of the measurement region
Bottom edge position X of line 0	BOTTOMX0	X coordinate of the edge of line 0 that is the closest from the start point of the measurement region
Bottom edge position Y of line 0	BOTTOMY0	Y coordinate of the edge of line 0 that is the closest from the start point of the measurement region
Edge position X Ave. of line 0	AVEX0	The average of X coordinates of all the edges of line 0
Edge position Y Ave. of line 0	AVEY0	The average of Y coordinates of all the edges of line 0
Long distance Max. of line 0	PMAXD0	The maximum distance between the approximate line and edge position of line 0 (plus direction)
Long distance Min. of line 0	PMIND0	The minimum distance between the approximate line and edge position of line 0 (plus direction)
Short distance Max. of line 0	BMAXD0	The maximum distance between the approximate line and edge position of line 0 (minus direction)
Short distance Min. of line 0	BMIND0	The minimum distance between the approximate line and edge position of line 0 (minus direction)
Deviation of line 0	DEV0	Concave and convex deviation of line 0
Angle of line 0	LINETH0	The line 0's inclination against the measurement region
Lost point count of line 0	LOST0	Number of parts for which the detection of edges of line 0 has failed
Line parameter A of line 0	A0	A in the expression for the approximate line of line 0 $AX + BY + C = 0$.
Line parameter B of line 0	B0	B in the expression for the approximate line of line 0 $AX + BY + C = 0$.
Line parameter C of line 0	C0	C in the expression for the approximate line of line 0 $AX + BY + C = 0$.
Peak edge position X of line 1	PEEKX1	X coordinate of the edge of line 1 that is the furthest from the start point of the measurement region
Peak edge position Y of line 1	PEEKY1	Y coordinate of the edge of line 1 that is the furthest from the start point of the measurement region
Bottom edge position X of line 1	BOTTOMX1	X coordinate of the edge of line 1 that is the closest from the start point of the measurement region
Bottom edge position Y of line 1	BOTTOMY1	Y coordinate of the edge of line 1 that is the closest from the start point of the measurement region
Edge position X Ave. of line 1	AVEX1	The average of X coordinates of all the edges of line 1
Edge position Y Ave. of line 1	AVEY1	The average of Y coordinates of all the edges of line 1
Long distance Max. of line 1	PMAXD1	The maximum distance between the approximate line and edge position of line 1 (plus direction)
Long distance Min. of line 1	PMIND1	The minimum distance between the approximate line and edge position of line 1 (plus direction)
Short distance Max. of line 1	BMAXD1	The maximum distance between the approximate line and edge position of line 1 (minus direction)
Short distance Min. of line 1	BMIND1	The minimum distance between the approximate line and edge position of line 1 (minus direction)
Deviation of line 1	DEV1	Concave and convex deviation of line 1
Angle of line 1	LINETH1	The line 1's inclination against the measurement region
Lost point count of line 1	LOST1	Number of parts for which the detection of edges of line 1 has failed
Line parameter A of line 1	A1	A in the expression for the approximate line of line 1 $AX + BY + C = 0$.
Line parameter B of line 1	B1	B in the expression for the approximate line of line 1 $AX + BY + C = 0$.
Line parameter C of line 1	C1	C in the expression for the approximate line of line 1 $AX + BY + C = 0$.

External Reference Tables (Intersection)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
1	Intersection coordinate X	Get only	-99999.9999 to 99999.9999
2	Intersection coordinate Y	Get only	-99999.9999 to 99999.9999
3	Angle	Get only	0 to 180
4	Reference X	Get only	0.0000 to 9999.0000
5	Reference Y	Get only	0.0000 to 9999.0000
10	Peak edge position X of line 0	Get only	0.0000 to 99999.9999
11	Peak edge position Y of line 0	Get only	0.0000 to 99999.9999
12	Bottom edge position X of line 0	Get only	0.0000 to 99999.9999
13	Bottom edge position Y of line 0	Get only	0.0000 to 99999.9999
14	Edge position X Ave. of line 0	Get only	-1.0000 to 99999.9999
15	Edge position Y Ave. of line 0	Get only	-1.0000 to 99999.9999
16	Long distance Max. of line 0	Get only	-1.0000 to 99999.9999
17	Long distance Min. of line 0	Get only	-1.0000 to 99999.9999
18	Short distance Max. of line 0	Get only	-1.0000 to 99999.9999
19	Short distance Min. of line 0	Get only	-1.0000 to 99999.9999
20	Deviation of line 0	Get only	-1.0000 to 99999.9999
21	Angle of line 0	Get only	-180 to 180
22	Lost point count of line 0	Get only	0 to 100
23	Linear coefficient A of line 0	Get only	-99999.9999 to 99999.9999
24	Linear coefficient B of line 0	Get only	-99999.9999 to 99999.9999
25	Linear coefficient C of line 0	Get only	-99999.9999 to 99999.9999
30	Peak edge position X of line 1	Get only	0.0000 to 99999.9999
31	Peak edge position Y of line 1	Get only	0.0000 to 99999.9999
32	Bottom edge position X of line 1	Get only	0.0000 to 99999.9999
33	Bottom edge position Y of line 1	Get only	0.0000 to 99999.9999
34	Edge position X Ave. of line 1	Get only	-1.0000 to 99999.9999
35	Edge position Y Ave. of line 1	Get only	-1.0000 to 99999.9999
36	Long distance Max. of line 1	Get only	-1.0000 to 99999.9999
37	Long distance Min. of line 1	Get only	-1.0000 to 99999.9999
38	Short distance Max. of line 1	Get only	-1.0000 to 99999.9999
39	Short distance Min. of line 1	Get only	-1.0000 to 99999.9999
40	Deviation of line 1	Get only	-1.0000 to 99999.9999
41	Angle of line 1	Get only	-180 to 180
42	Lost point count of line 1	Get only	0 to 100
43	Linear coefficient A of line 1	Get only	-99999.9999 to 99999.9999
44	Linear coefficient B of line 1	Get only	-99999.9999 to 99999.9999
45	Linear coefficient C of line 1	Get only	-99999.9999 to 99999.9999

No.	Data name	Set/Get	Data range
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Reference X	Set/Get	0.0000 to 99999.9999
121	Reference Y	Set/Get	0.0000 to 99999.9999
122	Share setting (Edge color specification)	Set/Get	0: Not shared 1: Shared
123	Share setting (Measurement parameter)	Set/Get	0: Not shared 1: Shared
124	Line number currently selected	Set/Get	0: Line 0 1: Line 1
130	Upper limit of intersection X coordinate	Set/Get	-99999.9999 to 99999.9999
131	Lower limit of intersection X coordinate	Set/Get	-99999.9999 to 99999.9999
132	Upper limit of intersection Y coordinate	Set/Get	-99999.9999 to 99999.9999
133	Lower limit of intersection Y coordinate	Set/Get	-99999.9999 to 99999.9999
134	Angle upper limit	Set/Get	0 to 180
135	Angle lower limit	Set/Get	0 to 180
136	Upper limit of lost point count (line 0)	Set/Get	0 to 100
137	Lower limit of lost point count (line 0)	Set/Get	0 to 100
138	Upper limit of lost point count (line 1)	Set/Get	0 to 100
139	Lower limit of lost point count (line 1)	Set/Get	0 to 100
200	Edge color specification (line 0)	Set/Get	0: No color specification 1: With color specification
201	Edge color R (line 0)	Set/Get	0 to 255
202	Edge color G (line 0)	Set/Get	0 to 255
203	Edge color B (line 0)	Set/Get	0 to 255
204	Difference R (line 0)	Set/Get	0 to 127
205	Difference G (line 0)	Set/Get	0 to 127
206	Difference B (line 0)	Set/Get	0 to 127
207	Edge detection mode (line 0)	Set/Get	0: Specified color IN 1: Specified color OUT
208	Edge number (line 0)	Set/Get	0 to 99
209	Edge level (line 0)	Set/Get	0 to 100
210	Noise level (line 0)	Set/Get	0 to 442
211	Noise width (line 0)	Set/Get	0 to 9999
212	Edge color enhancement level (line 0)	Set/Get	0 to 442
213	Monochrome edge detection mode (line 0)	Set/Get	0: Light→Dark 1: Dark→Light
214	Edge level absolute value (line 0)	Set/Get	0 to 442

No.	Data name	Set/Get	Data range
215	Edge level specification method (line 0)	Set/Get	0: % 1: Absolute value
216	Scan sub-region (line 0)	Set/Get	1 to 100
217	Filter size (line 0)	Set/Get	1 to 1000
218	Display range (line 0)	Set/Get	0 to 99
219	Noise cancel (line 0)	Set/Get	0: OFF 1: ON
220	Measure type (line 0)	Set/Get	0: Projection 1: Differential
221	Fix region count (line 0)	Set/Get	0: Not fixed 1: Fixed
222	Monochrome Derivation edge detection mode (line 0)	Set/Get	0: Absolute 1: Dark→Light 2: Light→Dark
223	Edge Level Upper limit (line 0)	Set/Get	0 to 100
224	Edge level Upper limit absolute value (line 0)	Set/Get	0 to 442
225	Filter Strength (line 0)	Set/Get	0 to 100
226	Rate (line 0)	Set/Get	0 to 100
250	Edge color specification (line 1)	Set/Get	0: No color specification 1: With color specification
251	Edge color R (line 1)	Set/Get	0 to 255
252	Edge color G (line 1)	Set/Get	0 to 255
253	Edge color B (line 1)	Set/Get	0 to 255
254	Difference R (line 1)	Set/Get	0 to 127
255	Difference G (line 1)	Set/Get	0 to 127
256	Difference B (line 1)	Set/Get	0 to 127
257	Edge detection mode (line 1)	Set/Get	0: Specified color IN 1: Specified color OUT
258	Edge number (line 1)	Set/Get	0 to 99
259	Edge level (line 1)	Set/Get	0 to 100
260	Noise level (line 1)	Set/Get	0 to 442
261	Noise width (line 1)	Set/Get	0 to 9999
262	Edge color level (line 1)	Set/Get	0 to 442
263	Monochrome edge detection mode (line 1)	Set/Get	0: Light→Dark 1: Dark→Light
264	Edge level absolute value (line 1)	Set/Get	0 to 442
265	Edge level specification method (line 1)	Set/Get	0: % 1: Absolute value
266	Scan sub-region (line 1)	Set/Get	1 to 100
267	Filter size (line 1)	Set/Get	1 to 1000
268	Display range (line 1)	Set/Get	0 to 99
269	Noise cancel (line 1)	Set/Get	0: OFF 1: ON
270	Measure type (line 1)	Set/Get	0: Projection 1: Differential

No.	Data name	Set/Get	Data range
271	Fix region count (line 1)	Set/Get	0: Not fixed 1: Fixed
272	Monochrome derivation edge detection mode (line 1)	Set/Get	0: Absolute value 1: Dark → Light 2: Light → Dark
273	Upper limit of edge level (line 1)	Set/Get	0 to 100
274	Upper limit absolute value of edge level (line 1)	Set/Get	0 to 442
275	Filter strength (line 1)	Set/Get	0 to 100
276	Extraction ratio (line 1)	Set/Get	0 to 100
278	Reference unit number for reference coordinate	Set/Get	-1 to 9999
279	Reference type of reference coordinate	Set/Get	0: Set by number 1: Unit reference
280	Use coordinates before position compensation	Set/Get	0: Not used 1 : Used
281	Coordinate X before position compensation	Get only	-99999.9999 to 99999.9999
282	Coordinate Y before position compensation	Get only	-99999.9999 to 99999.9999

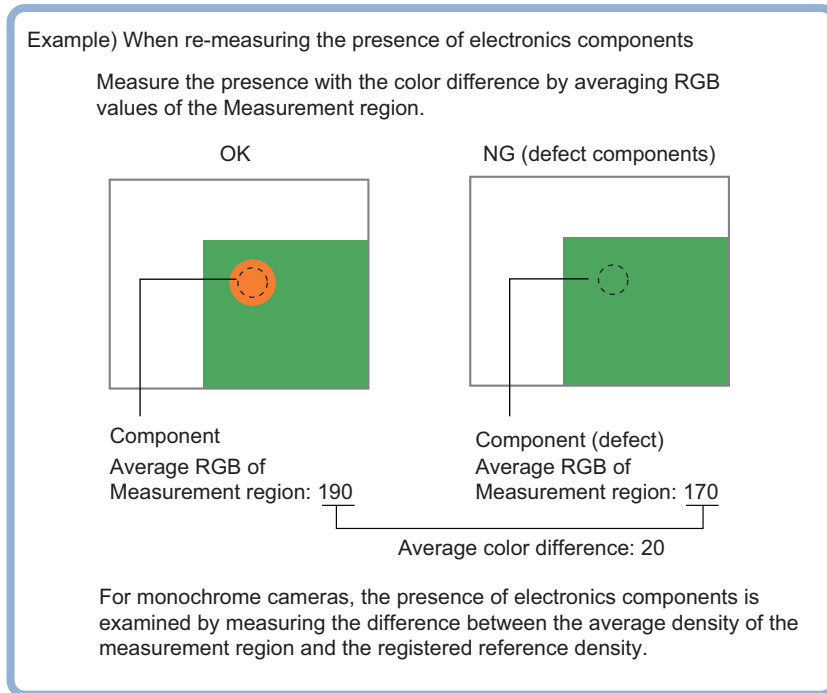
Color Data

Inspect by finding the average color of the measurement region and using its difference from the registered reference color and the color variation in the measurement area. Alternatively, you can only detect the color tone while neglect the effect of image brightness.

For monochrome cameras, examination is performed by measuring the difference between the average density of the measurement region and the registered reference density (density average), and the density deviation in the measurement region (density deviation).

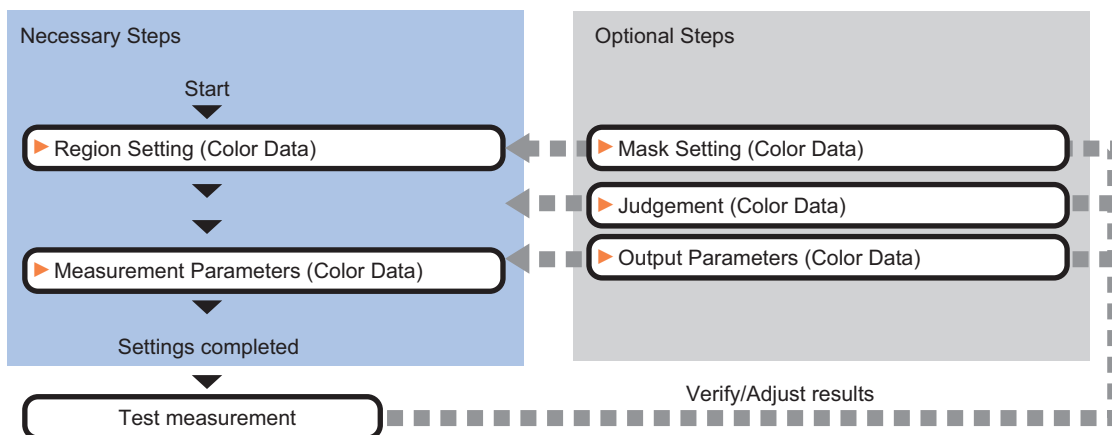
Used in the Following Case

- When measuring the presence of measurement objects



Settings Flow (Color Data)

Set the color data with the following steps.



List of Color Data Items

Item name	Description
Region setting	This item is used to set up the measurement area. While the input image can be measured as a whole, a quick and reliable measurement can be performed by set up the measured range. Reference: ▶ Region Setting (Color Data) (p.274)
Mask setting	Set it when masking a region. The measurement result of another processing item can also be used for masking. Reference: ▶ Mask Setting (Color Data) (p.275)
Measurement	Measurement parameters can be changed as needed to address unstable measurement results or for faster processing. Reference: ▶ Measurement Parameters (Color Data) (p.278)
Judgement	This item can be changed if necessary. Normally, the factory default value will be used. This item specifies the judgement condition for measurement results. <ul style="list-style-type: none"> • For color cameras Set the average color (RGB) value and deviation and set what the maximum difference is for judging the object to be OK. The measurement result of HSV can be judged to be OK. • For monochrome cameras Specify the average density value and deviation and set what the maximum difference is for judging the object to be OK.
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Specify whether to reflect the judgement result to the overall judgement of the scene. Reference: ▶ Output Parameters (Color Data) (p.280)

Region Setting (Color Data)

This item is used to set up the measurement area. It is possible to measure the entire input image, but restricting the range enables accurate measurement in a short period of time.

A measurement region for [Color Data] can be specified as a rectangle, circle (ellipse), circumference, or polygon.

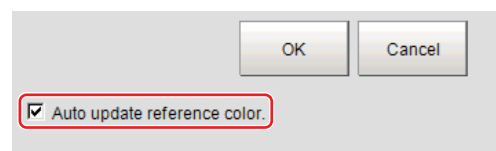
Note

- Up to 8 graphs can be used together to draw the measured region. Complex areas can be drawn through image integration or by removing unnecessary sections from the measurement region.

- 1 In the Item Tab area, click [Region setting].**
- 2 Select a button in the Drawing tools.**
- 3 In the figure setting area, specify a region to be measured.**
- 4 In the figure setting area, click [OK].**

The measurement region is registered and displayed in the Image Display area.

- 5 To register a color in the region as a reference color, place a check at "Auto update reference color.".**



Note

- When a check is placed at "Auto update reference color.", the average color within the region is automatically registered as the reference color when the region is registered. Each time the region is updated, the reference color is updated.
To hold the reference color constant, uncheck this option and register the reference color with the measurement parameters.
Reference: ▶ Measurement Parameters (Color Data) (p.278)

Mask Setting (Color Data)

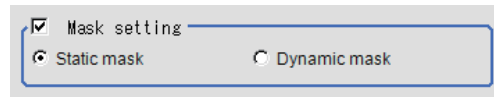
Mask the measurement region when measuring it.

There are two types of masks, namely, a static mask that sets the mask region independent of measurement and a dynamic mask that uses images generated in another unit for each measurement.

Creating a static mask

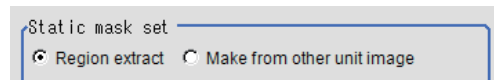
A static mask can be created manually or from an image of another unit.

- 1 In the Mask setting area, select "Static mask".



Generating a mask manually

- 1 In the Static mask set area, select "Region extract".

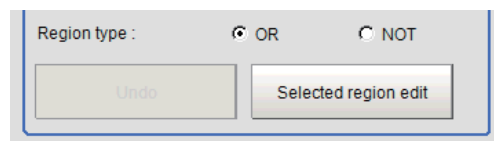


- 2 Select the selection region type OR or NOT and drag an image directly.

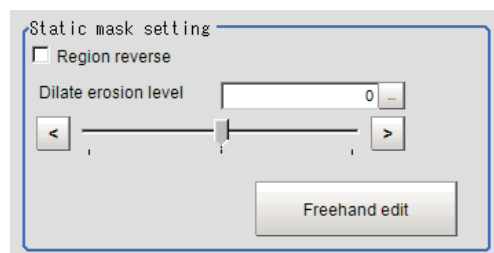
A region is created along successive similar colors from the selected place. It is not masked if the selection region type is OR. It is masked if the selection region type is NOT.

To deselect a selected region, click [Undo].

To edit a region selected with OR/NOT, click [Selected region edit].



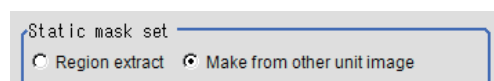
- 3 Adjust the mask created in the Static mask setting area.



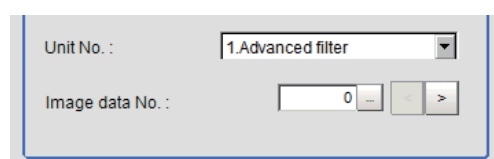
Setting item	Setting value [Factory default]	Description
Region reverse	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check to revert the created mask region.
Dilate erosion level	-10 to 10 [0]	Perform fine adjustment on the mask region using expansions/shrinkage. The region is expanded if a positive value is set. The region is shrunk if a negative value is set.

Creating a static mask from an image of another unit

- 1 In the Static mask set area, select "Make from other unit image".



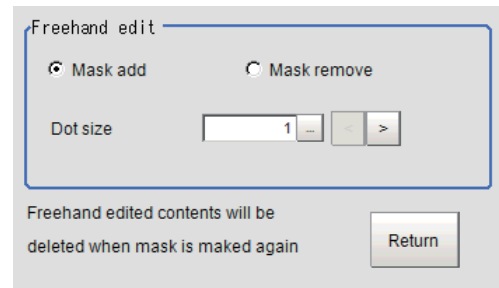
- 2 Set the unit number and image data number.



Setting item	Setting value [Factory default]	Description
Unit No.	-	Specify the number of the unit whose image will be referenced. The reference unit should be able to output binarized images. For example, select a labeling filter processing image for advanced filtering.
Image data No.	0 to 3 [0]	If the unit supports advanced filtering, numbers 0 to 3 can be set. Otherwise, it is fixed to 0.

Performing fine adjustment on a static mask

- 1 To perform fine adjustment on a mask region, click [Freehand edit] in the Static mask setting area.



Setting item	Setting value [Factory default]	Description
Freehand edit	<ul style="list-style-type: none"> • Mask add] • Mask remove 	Select a process performed using the free hand edit.
Dot size	1 to 20 [1]	Set the size of dots used when drawing images on the screen.

- 2 Click [Return] to exit the free hand edit.

Clearing the static mask setting

To clear the static mask setting, click [Clear].

Creating a dynamic mask

- 1 In the Mask setting area, select "Dynamic mask".
- 2 Set the unit number and image data number in the Unit reference area.

Mask setting

Mask setting
 Static mask
 Dynamic mask

Unit reference

Unit No. : 1.Advanced filter

Image data No. : 0

Setting item	Setting value [Factory default]	Description
Unit No.	-	Set the number of the unit being referred to for the mask region. The reference unit should be able to output binarized images. For example, select a labeling filter processing image for advanced filtering.
Image data No.	0 to 3 [0]	If the unit supports advanced filtering, numbers 0 to 3 can be set. Otherwise, it is fixed to 0.

Setting display

Perform the display setting if required.

Show setting

Image type : Mask and image

Mask region color : Black

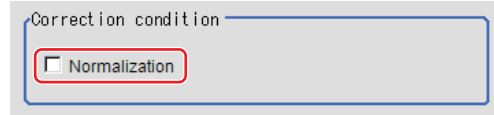
Setting item	Setting value [Factory default]	Description
Image type	<ul style="list-style-type: none"> • Measure image • Mask binary image • [Mask and image] 	Select the type of an image to be displayed. Measure image: Measured image Mask binary image: Binarized image for masking Mask and image: Post-masking image
Mask region color	<ul style="list-style-type: none"> • [Black] • White • Red • Green • Blue 	Select the color of the region extracted as a mask.

Measurement Parameters (Color Data)

Set the reference color and judgment conditions.

For color cameras:

- 1 In the Item Tab area, click [Measurement].
- 2 If necessary, check the "Normalization" option in the "Correction condition" area.

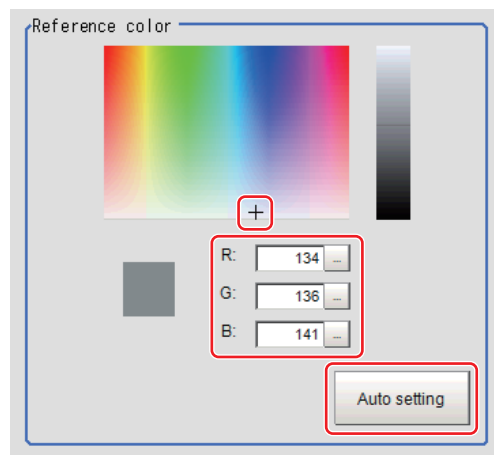


Normally, the factory default value will be used. After changing a setting, check whether measurement can be done properly by performing an actual measurement.

Setting item	Set value [Factory default]	Description
Normalization	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Specify whether to normalize the brightness in calculating the color difference. When checked, the result is not affected by the total brightness and only the color tone can be detected.

- 3 In the "Reference color" area, specify the reference color.

This operation is not needed when there is a check at "Auto update reference color." when the region is registered.



Setting method	Description
Color chart	Clicking the color chart displays the RGB values for the specified color at the bottom.
R, G, B	Set the RGB values with numbers.
Auto setting	If you click [Auto setting], the average color of the measurement region is displayed as the reference color.

Judgement Condition (Color Data)

This item specifies the judgement condition for measurement results.

- 1 When the setting has been changed, click [Measurement] to verify whether measurements can be made correctly.

Test measurement of this item.

Measurement

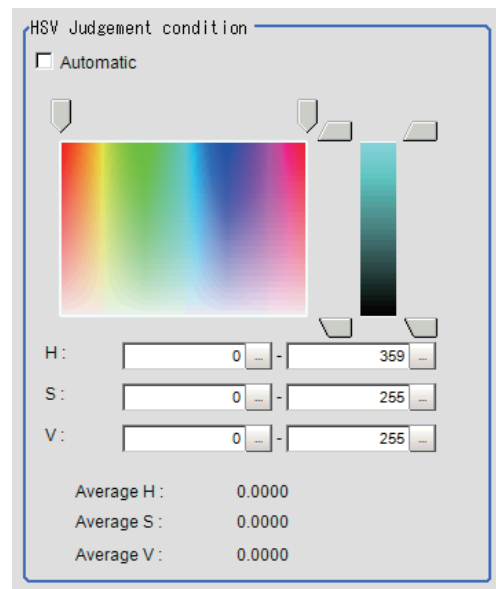
- 2 In the RGB Judgement condition area, set the judgement condition.

Setting item	Setting value	Description
Color difference	0 to 442	Specify the upper and lower limit values for the difference between the average color of the measurement region and the reference color.
Color deviation	0 to 221	Specify the upper and lower limit values for the deviation of the average color in the measurement region.

HSV parameters can also be used to set the judgement condition.

- 1 Place a check at [Automatic].
- 2 In the Image Display area, specify the color range you want to detect by dragging the cursor from the upper left corner to the lower right corner of that area.

The color of the specified area is automatically set.



Setting item	Setting value [Factory default]	Description
Automatic	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Specifying the color to be measured on the image automatically sets the hue, saturation, and brightness.
H	0 to 359	Set the color phase (difference of color hues).
S	0 to 255	Set color saturation (difference of color saturation).
V	0 to 255	Set the brightness (difference of brightness).

For monochrome cameras

- 1 When the setting has been changed, click [Measurement] to verify whether measurements can be made correctly.
- 2 Set up the judgement condition.

Setting item	Setting value	Description
Density average	0 to 255	Specify the upper and lower limit values for judging the average density of the measurement region.
Density deviation	0 to 127	Specify the upper and lower limit values for the deviation of the average density in the measurement region.

Output Parameters (Color Data)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Choose whether or not to reflect this in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none">• [ON]• OFF	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Color Data)

The following content can be confirmed in the "Detail result" area using text.

For color cameras

Displayed items	Description
Judge	Judgement result
Average R	R (red) element average value
Average G	G (green) element average value
Average B	B (blue) element average value
Color difference	The color difference between the average color and reference color in the measurement region
Color deviation	Color deviation in the measurement region
H average	Average H (Hue) component value
S average	Average S (Saturation) component value
V average	Average V (Value) component value

For monochrome cameras

Displayed items	Description
Judge	Judgement result
Density average	Difference between the average density and the reference density in the measurement region
Density deviation	Density deviation in the measurement region

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Parameter to be adjusted	Remedy
Measurement	For a color camera, place a check at [Normalization].

When the processing speed is slow

Parameter to be adjusted	Remedy
Region setting	Set the measurement region to be as small as possible.

Measurement Results for Which Output Is Possible (Color Data)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

For color cameras

Measurement items	Character string	Description
Judge	JG	Judgement result
R average	AR	R (red) element average value
G average	AG	G (green) element average value
B average	AB	B (blue) element average value
Color difference	AD	The color difference between the average color and reference color in the measurement region
Color deviation	DV	Color deviation in the measurement region
H average	AH	Average H (Hue) component value
S average	AS	Average S (Saturation) component value
V average	AV	Average V (Value) component value

For monochrome cameras

Measurement items	Character string	Description
Judge	JG	Judgement result
Density average	AD	Difference between the average density and the reference density in the measurement region
Density deviation	DV	Color deviation in the measurement region

External Reference Tables (Color Data)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgment result OK -1: Judgment result NG
5	Average R component value	Get only	0 to 255
6	Average G component value	Get only	0 to 255

No.	Data name	Set/Get	Data range
7	Average B component value	Get only	0 to 255
8	Color difference	Get only	0 to 442
9	Color deviation	Get only	0 to 221
10	Density average (for monochrome cameras only)	Get only	0 to 255
11	Density deviation value (for monochrome cameras only)	Get only	0 to 127
12	Reference average value	Get only	0 to 255
13	Reference deviation value	Get only	0 to 127
14	Density average difference	Get only	0 to 255
15	Density deviation difference	Get only	0 to 127
16	H average value	Get only	0 to 359
17	S average value	Get only	0 to 255
18	V average value	Get only	0 to 255
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Normalization	Set/Get	0: OFF 1: ON
121	Reference color R	Set/Get	0 to 255
122	Reference color G	Set/Get	0 to 255
123	Reference color B	Set/Get	0 to 255
124	Upper limit for color difference	Set/Get	0 to 442
125	Lower limit for color difference	Set/Get	0 to 442
126	Upper limit for color deviation	Set/Get	0 to 221
127	Lower limit for color deviation	Set/Get	0 to 221
128	Reference density average	Set/Get	0 to 255
129	Reference density deviation	Set/Get	0 to 127
130	Upper limit for density average (for monochrome cameras only)	Set/Get	0 to 255
131	Lower limit for density average (for monochrome cameras only)	Set/Get	0 to 255
132	Upper limit for density deviation (for monochrome cameras only)	Set/Get	0 to 127

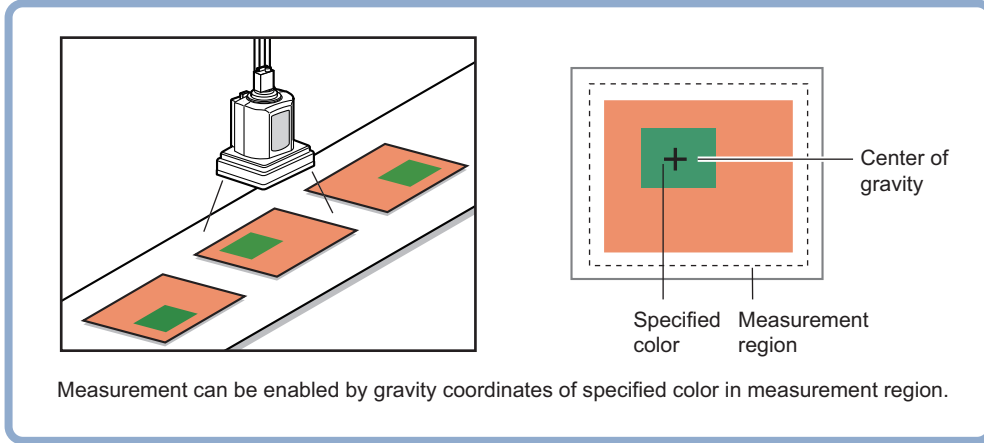
No.	Data name	Set/Get	Data range
133	Lower limit for density deviation (for monochrome cameras only)	Set/Get	0 to 127
136	Upper limit for H average value	Set/Get	0 to 359
137	Lower limit for H average value	Set/Get	0 to 359
138	Upper limit for S average value	Set/Get	0 to 255
139	Lower limit for S average value	Set/Get	0 to 255
140	Upper limit for V average value	Set/Get	0 to 255
141	Lower limit for V average value	Set/Get	0 to 255
150	Region reverse	Set/Get	0: Not reverse 1: Reverse
151	Dilate erosion level	Set/Get	-10 to 10
152	Static mask type	Set/Get	0: Region extract 1: Region of image reference
153	Static mask unit reference no	Set/Get	-1 to 9999
154	Static mask image no	Set/Get	0 to 99
155	Dynamic mask unit reference no	Set/Get	-1 to 9999
156	Dynamic mask image no	Set/Get	0 to 99
157	Mask type	Set/Get	0: Static mask 1: Dynamic mask
158	Display image type	Set/Get	0: Measure image 1: Mask binary image 2: Mask and image
163	Is mask	Set/Get	0: OFF 1: ON
164	Mask region display color	Set/Get	0: Black 1: White 2: Red 3: Green 4: Blue

Gravity and Area

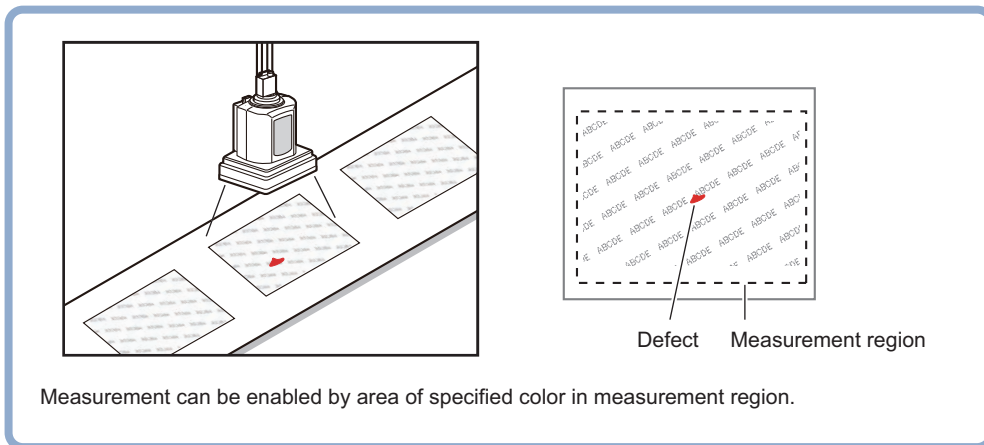
Inspect using the area of the specified color.

Used in the Following Case

- Label deviation measurement

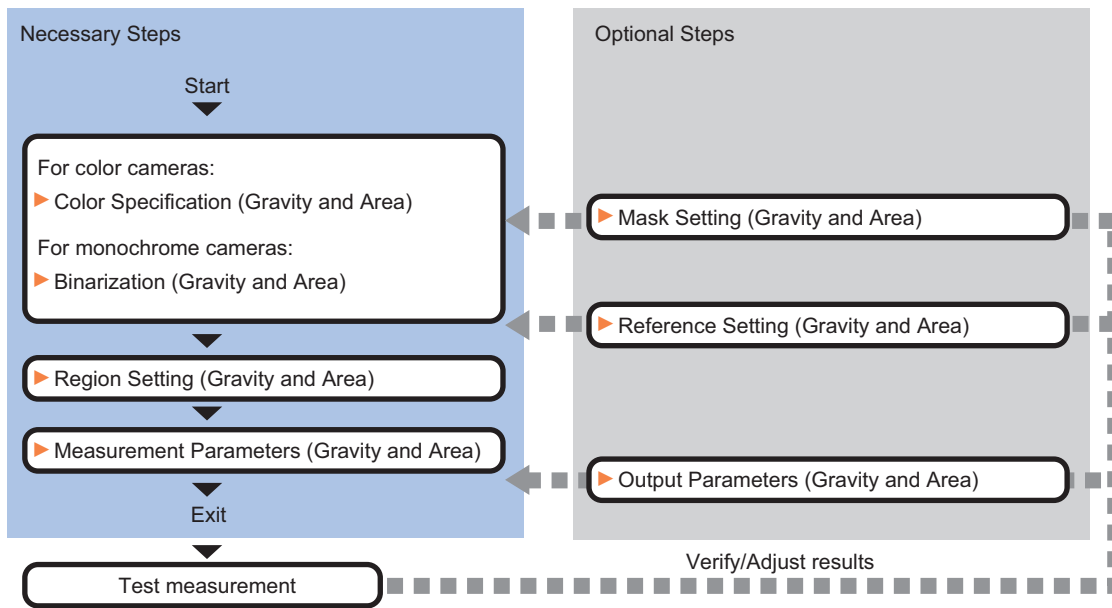


- Detection of defects, contamination, and stains of measurement objects whose appearance is not defined



Settings Flow (Gravity and Area)

Set the Gravity and Area with the following steps.



List of Gravity and Area Items

Item name	Description
Color (for color cameras only)	This item selects the color whose area and center of gravity are to be measured. Since the color hue, color saturation, and brightness can be selected, then fine-tuning can be performed to colors. Reference: ▶ Color Specification (Gravity and Area) (p.286)
Binary (for monochrome cameras only)	This item specifies the binary level for converting 256-tone grayscale images input from the camera into binary images. Converted white pixels are measured. Adjust the binary level so that the measurement object is converted to white pixels. Reference: ▶ Binarization (Gravity and Area) (p.288)
Region setting	This item is used to set up the measurement area. While the input image can be measured as a whole, a quick and reliable measurement can be performed by set up the measured range. Reference: ▶ Region Setting (Gravity and Area) (p.288)
Mask setting	Set it when masking a region. The measurement result of another processing item can also be used for masking. Reference: ▶ Mask Setting (Gravity and Area) (p.289)
Ref. setting	This item can be changed if necessary. Usually, the central position of the registered region is registered as the reference position. Reference: ▶ Reference Setting (Gravity and Area) (p.291)
Measurement	This item specifies the judgement condition for measurement results. Specify the upper and lower limit values for the area and the gravity center X/Y. Measurement parameters can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used. Reference: ▶ Measurement Parameters (Gravity and Area) (p.292)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Gravity and Area) (p.294)

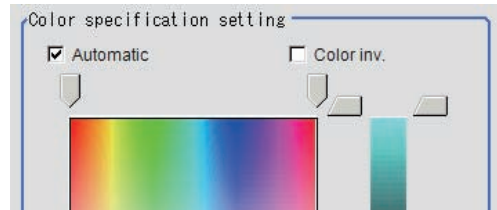
Color Specification (Gravity and Area)

When connecting a color camera, specify the color to be measured. There are two specification methods: specifying the color to be extracted in the image or specifying the color with the hue, saturation, and brightness values.

This section describes how to specify colors in an image and gives an example of the procedure for finely adjusting with numeric input afterwards.

- 1** In the Item Tab area, click [Color].
- 2** Place a check at [Automatic].
- 3** In the Image Display area, specify the color range you want to detect by dragging the cursor from the upper left corner to the lower right corner of that area.

The color of the specified area is automatically set.

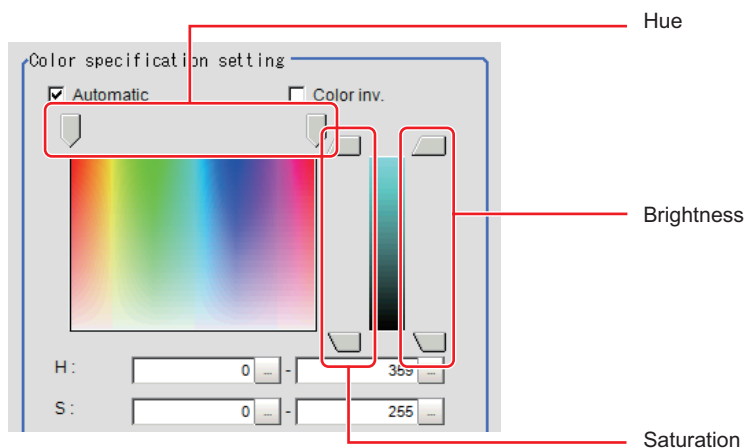


- 4** Finely adjust the hue, saturation, and brightness if necessary.

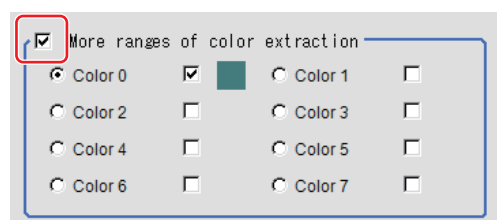
Adjust either by adjusting on the color chart or by inputting numbers.

Item	Set value [Factory default]	Description
H	0 to 359	Specify the color phase (difference of color hues).
S	0 to 255	Specify color saturation (difference of color saturation).
V	0 to 255	Specify the brightness (difference of brightness).
Automatic	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Specifying the color to be measured on the image automatically sets the hue, saturation, and brightness.
Color inv.	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Everything other than the specified color becomes the measurement target.

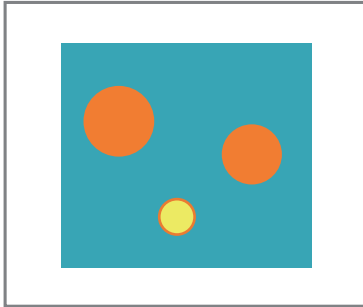
About color charts



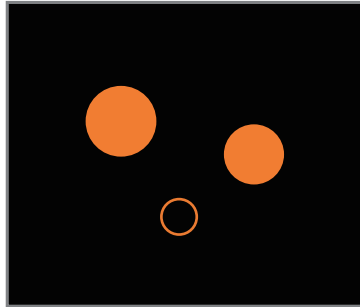
- 5** To specify multiple colors, place a check at "More ranges of color extraction".



Setting item	Set value [Factory default]	Description
More ranges of color extraction	<ul style="list-style-type: none"> • Checked • [Unchecked] 	If you place a check at this option, you can set up to 8 colors.



Extract image
(before specifying colors)



Extract image
(after specifying colors – background color: black)

6 If necessary, set the display conditions for displayed images.

Exclude this color
Background color : Black

Display setting
Image type : All color image

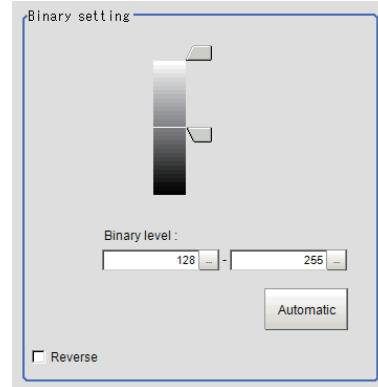
Setting item	Set value [Factory default]	Description
Exclude this color	<ul style="list-style-type: none"> • Checked • [Unchecked] 	If you place a check at this option, pixels within the HSV range are excluded from color extraction. The priority order for exclusion is that the higher color extraction range numbers are given priority. This setting is disabled if "More ranges of color extraction" is unchecked.
Background color	<ul style="list-style-type: none"> • [Black] • White • Red • Green • Blue 	The background section outside the extracted image is filled with the specified colors.
Image type	<ul style="list-style-type: none"> • Measurement image • [All color image] • Selected color image • Binary image 	This sets the state of the image to display.

Binarization (Gravity and Area)

When a monochrome camera is connected, the 256-tone grayscale images taken in from the camera are converted into binary black-and-white images before the images are measured. Converted white pixels are measured.

This specifies the level for converting grayscale images into binary images.

- 1** In the Item Tab area, click [Binary].
- 2** In the "Binary setting" area, specify the reference density range.



Item		Set value [Factory default]	Description
Binary level	Upper limit value	0 to 255 [255]	Specify the level for converting 256-tone grayscale images to binary images. Adjust the binary level so that the measurement object is converted to white pixels. You can also set the binary level so that only intermediate density is measured.
	Lower limit value	0 to 255 [128]	
Automatic		-	Optimum binary levels are calculated automatically and set.
Reverse		<ul style="list-style-type: none"> • Checked • [Unchecked] 	This item reverses black and white colors.

Region Setting (Gravity and Area)

This item is used to set up the measurement area. It is possible to measure the entire input image, but restricting the range enables accurate measurement in a short period of time.

Use a rectangle, circle (ellipse), circumference, or polygon to specify a measurement region for [Gravity and Area]. Up to 8 figures can be combined to draw the measurement region.

- 1** In the Item Tab area, click [Region setting].
- 2** Use the Drawing tools to specify the measurement region.
- 3** In the figure setting area, click [OK].

The measurement region is registered and displayed in the Image Display area.

- 4** If necessary, in the "Display setting" area, set up display settings for the images displayed in the Image Display area.

Setting item	Set value [Factory default]	Description
Extract image	<ul style="list-style-type: none"> • [Checked] • Unchecked 	If you place a check at this option, image set with the color specification is displayed.

Mask Setting (Gravity and Area)

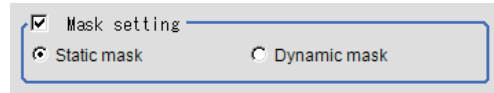
Mask the measurement region when measuring it.

There are two types of masks, namely, a static mask that sets the mask region independent of measurement and a dynamic mask that uses images generated in another unit for each measurement.

Creating a static mask

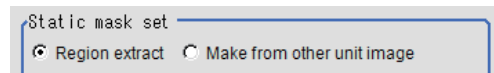
A static mask can be created manually or from an image of another unit.

- 1 In the Mask setting area, select "Static mask".



Generating a mask manually

- 1 In the Static mask set area, select "Region extract".

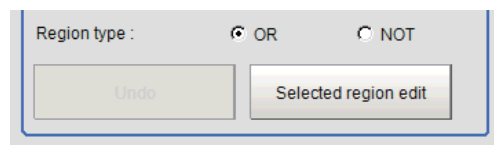


- 2 Select the selection region type OR or NOT and drag an image directly.

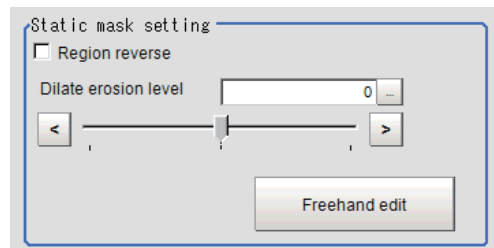
A region is created along successive similar colors from the selected place. It is not masked if the selection region type is OR. It is masked if the selection region type is NOT.

To deselect a selected region, click [Undo].

To edit a region selected with OR/NOT, click [Selected region edit].



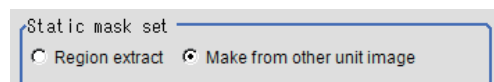
- 3 Adjust the mask created in the Static mask setting area.



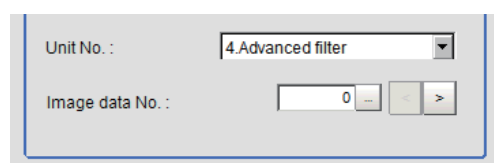
Setting item	Setting value [Factory default]	Description
Region reverse	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check to revert the created mask region.
Dilate erosion level	-10 to 10 [0]	Perform fine adjustment on the mask region using expansions/shrinkage. The region is expanded if a positive value is set. The region is shrunk if a negative value is set.

Creating a static mask from an image of another unit

- 1 In the Static mask set area, select "Make from other unit image".



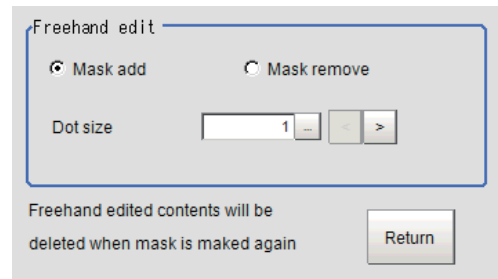
- 2 Set the unit number and image data number.



Setting item	Setting value [Factory default]	Description
Unit No.	-	Specify the number of the unit whose image will be referenced. The reference unit should be able to output binarized images. For example, select a labeling filter processing image for advanced filtering.
Image data No.	0 to 3 [0]	If the unit supports advanced filtering, numbers 0 to 3 can be set. Otherwise, it is fixed to 0.

Performing fine adjustment on a static mask

- 1 To perform fine adjustment on a mask region, click [Freehand edit] in the Static mask setting area.



Setting item	Setting value [Factory default]	Description
Freehand edit	<ul style="list-style-type: none"> • [Mask add] • Mask remove 	Select a process performed using the free hand edit.
Dot size	1 to 20 [1]	Set the size of dots used when drawing images on the screen.

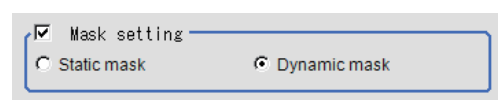
- 2 Click [Return] to exit the free hand edit.

Clearing the static mask setting

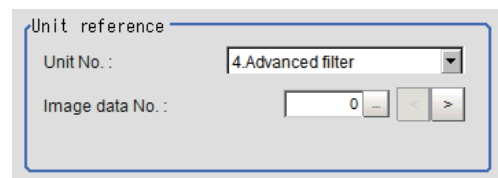
To clear the static mask setting, click [Clear].

Creating a dynamic mask

- 1 In the Mask setting area, select "Dynamic mask".



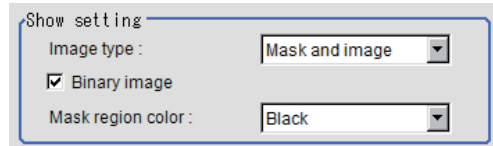
- 2 Set the unit number and image data number in the Unit reference area.



Setting item	Setting value [Factory default]	Description
Unit No.	-	Set the number of the unit being referred to for the mask region. The reference unit should be able to output binarized images. For example, select a labeling filter processing image for advanced filtering.
Image data No.	0 to 3 [0]	If the unit supports advanced filtering, numbers 0 to 3 can be set. Otherwise, it is fixed to 0.

Setting display

Perform the display setting if required.



Setting item	Setting value [Factory default]	Description
Image type	<ul style="list-style-type: none"> • Measure image • Mask binary image • [Mask and image] 	Select the type of an image to be displayed. Measure image: Measured image Mask binary image: Binarized image for masking Mask and image: Post-masking image
Mask region color	<ul style="list-style-type: none"> • [Black] • White • Red • Green • Blue 	Select the color of the region extracted as a mask.

Reference Setting (Gravity and Area)

When the measurement region is set, the center of gravity is automatically set at the same time as the reference position. This item is used to change the reference position to any desired position. This is handy for measuring the position deviation from a certain position. In the same way for the reference area, when the region settings are made, they are set automatically based on the measurement region.

A reference position can be set either directly or by referencing a unit.

Specifying directly

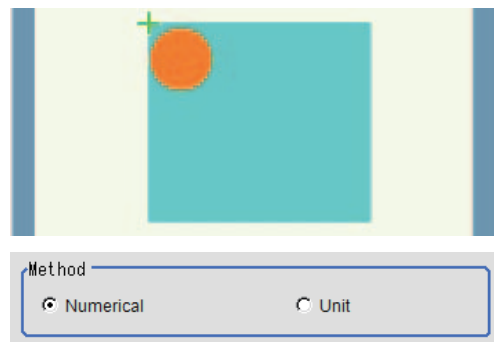
Click a position on the image you want to use as a reference position, or set coordinate data for that point.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

2 In the "Method" area, select "Numerical".

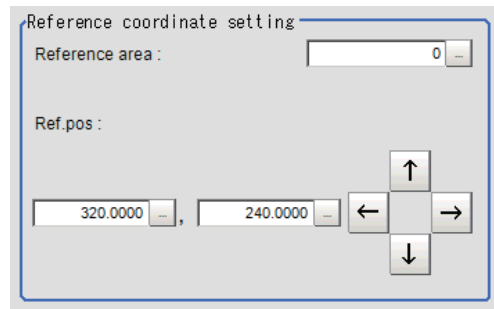
3 Click the position to be set as the reference.



Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

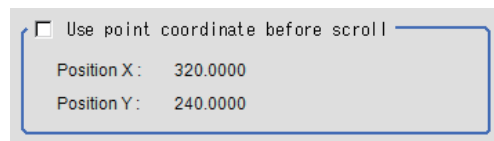
4 Make fine adjustments using numeric value inputs or the arrow buttons as required.



5 To remeasure on the displayed image and set the reference, click the [Measure ref.] button.



6 To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".



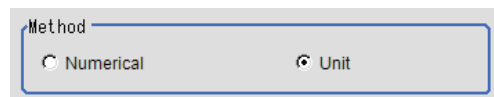
Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

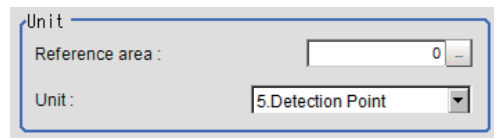
1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

2 In the "Method" area, select "Unit".



3 In the scene in the "Unit" area, select a detection point unit.



4 Perform the next measurement, and the reference will be displayed.

Measurement Parameters (Gravity and Area)

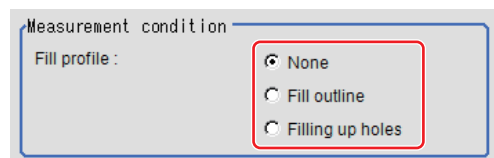
This item specifies the judgement condition for measurement results. Specify the upper and lower limit values for the area and the gravity center X/Y.


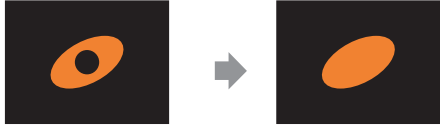
Measurement parameters can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used.

1 In the Item Tab area, click [Measurement].

2 If necessary, in the "Measurement condition" area, select an option for [Fill profile].

If the measurement target has holes in it, specify how to process the holes. Normally, the factory default value will be used.



Setting item	Set value [Factory default]	Description
Fill profile	[None]	The empty section in the center is not filled in.
	Fill outline	<p>In the measurement region, the part between the extracted-color start point and end point in the X-axis direction is measured as having the extracted color. Since filling is applied only to the X-axis direction, the processing is faster than filling up holes.</p> <p>Input image Fill profile image</p> 
	Filling up holes	<p>The part surrounded by the extracted color, like a doughnut hole, is filled with the extracted color.</p> <p>Input image Image after filling up hole</p> 

3 If necessary, in the "Display setting" area, set up display settings for the images displayed in the Image Display area.

4 When the setting has been changed, click [Measurement] in the "Detail" area to verify whether measurements can be made correctly.

Test measurement of this item

Measurement

5 Set up the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limits.

Setting item	Set value	Description
Area	0 to 999999999.9999	Specify the area to be judged as OK.
Gravity X	-99999.9999 to 99999.9999	Specify the range of X-axis shifting that is judged to be OK.
Gravity Y	-99999.9999 to 99999.9999	Specify the range of Y-axis shifting that is judged to be OK.

Output Parameters (Gravity and Area)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • After scroll • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgment results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (Gravity and Area)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Area	Area
Gravity X	Gravity X
Gravity Y	Gravity Y

The image specified in the sub image in image display setting is displayed in the Image Display area.

Sub image number.	Explanation of image to be displayed
0	Measurement image
1	Extract image

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

For color cameras:

Parameter to be adjusted	Remedy
Color	Click the area whose color will be sampled and the area whose color will not be sampled. The setup should be such that two stable sections of hue, saturation and brightness are formed.

For monochrome cameras:

Parameter to be adjusted	Remedy
Binary	Adjust the binary level.

Measurement Results for Which Output Is Possible (Gravity and Area)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Area	AR	Area
Gravity X	X	Center of gravity X coordinate
Gravity Y	Y	Center of gravity Y coordinate
Reference area	SA	Reference area
Reference point X	SX	Reference position X coordinate
Reference point Y	SY	Reference position Y coordinate

External Reference Tables (Gravity and Area)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Area	Get only	0 to 999999999.9999
6	Gravity X	Get only	-99999.9999 to 99999.9999
7	Gravity Y	Get only	-99999.9999 to 99999.9999
8	Reference area	Get only	0 to 999999999
9	Reference X	Get only	-99999.9999 to 99999.9999
10	Reference Y	Get only	-99999.9999 to 99999.9999
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Register the max. color hue	Set/Get	0 to 359
121	Register the min. color hue	Set/Get	0 to 359
122	Register the max. color saturation	Set/Get	0 to 255
123	Register the min. color saturation	Set/Get	0 to 255
124	Register the max. color brightness	Set/Get	0 to 255
125	Register the min. color brightness	Set/Get	0 to 255
126	Extract image	Set/Get	0: OFF 1: ON
127	Background color	Set/Get	0: Black 1: White 2: Red 3: Green 4: Blue
128	Fill profile	Set/Get	0: OFF 1: Fill profile 2: Filling up holes

No.	Data name	Set/Get	Data range
129	Color inv. (reverse for monochrome)	Set/Get	0: OFF 1: ON
132	Reference area	Set/Get	0 to 999999999.9999
133	Reference X	Set/Get	0 to 99999
134	Reference Y	Set/Get	0 to 99999
135	Upper limit of the area	Set/Get	0 to 999999999.9999
136	Lower limit of the area	Set/Get	0 to 999999999.9999
137	Upper limit of gravity X	Set/Get	-99999.9999 to 99999.9999
138	Lower limit of gravity X	Set/Get	-99999.9999 to 99999.9999
139	Upper limit of gravity Y	Set/Get	-99999.9999 to 99999.9999
140	Lower limit of gravity Y	Set/Get	-99999.9999 to 99999.9999
141	Upper limit of the binary level	Set/Get	0 to 255
142	Lower limit of the binary level	Set/Get	0 to 255
143	Binary image	Set/Get	0: ON 1: OFF
144	Image type	Set/Get	0: Measurement image 1: All color image 2: Selection color image 3: Binary image
145	Multiple selections	Set/Get	0: Multiple selections disabled 1: Multiple selections enabled
160 + N ^{*1} × 10	Flag N ^{*1} used for registered color	Set/Get	0: Not used 1 : Used
161 + N ^{*1} × 10	Flag N ^{*1} for registered color OR/NOT	Set/Get	0: OR 1: NOT
162 + N ^{*1} × 10	Register the max. color hue N ^{*1}	Set/Get	0 to 359
163 + N ^{*1} × 10	Register the min. color hue N ^{*1}	Set/Get	0 to 359
164 + N ^{*1} × 10	Register the max. color saturation N ^{*1}	Set/Get	0 to 255
165 + N ^{*1} × 10	Register the min. color saturation N ^{*1}	Set/Get	0 to 255
166 + N ^{*1} × 10	Register the max. color brightness N ^{*1}	Set/Get	0 to 255
167 + N ^{*1} × 10	Register the min. color brightness N ^{*1}	Set/Get	0 to 255
168 + N ^{*1} × 10	Background color N ^{*1}	Set/Get	0: Black 1 : White 2: Red 3: Green 4: Blue
301	Setting unit of reference coordinate	Set/Get	-1 to 9999
302	Setting type of reference coordinate	Set/Get	0: Numerical 1: Unit
303	Use point coordinate before scroll	Set/Get	0: Not use 1: Use
304	Position X before scroll	Set/Get	-99999.9999 to 99999.9999
305	Position Y before scroll	Set/Get	-99999.9999 to 99999.9999
311	Region reverse	Set/Get	0: Not reverse 1: Reverse
312	Dilate erosion level	Set/Get	-10 to 10

No.	Data name	Set/Get	Data range
313	Static mask type	Set/Get	0: Region extract 1: Region of image reference
314	Static mask unit reference no	Set/Get	-1 to 9999
315	Static mask image no	Set/Get	0 to 99
316	Dynamic mask unit reference no	Set/Get	-1 to 9999
317	Dynamic mask image no	Set/Get	0 to 99
318	Mask type	Set/Get	0: Static mask 1: Dynamic mask
319	Display image type	Set/Get	0: Measure image 1: Mask binary image 2: Mask and image
324	Is mask	Set/Get	0: OFF 1: ON
325	Mask region display color	Set/Get	0: Black 1: White 2: Red 3: Green 4: Blue

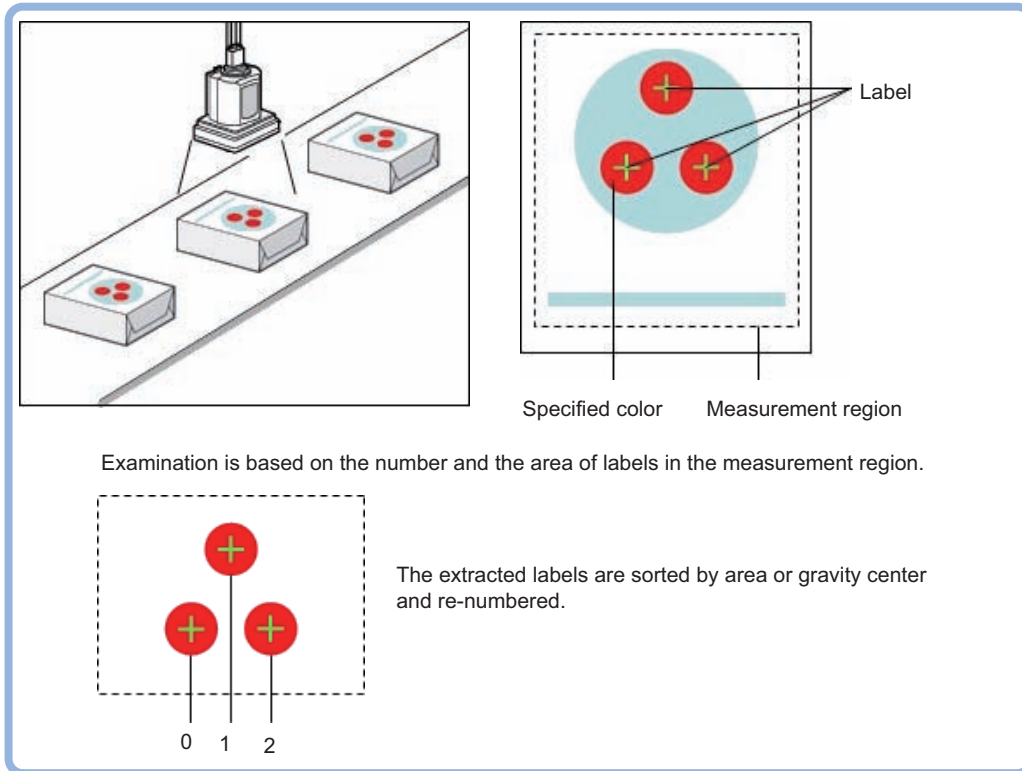
*1: N = 0 - 7 (color extraction range 0 to 7)

Labeling

You can count the number of labels with a specified color or find the area and center of gravity of a specified label number.

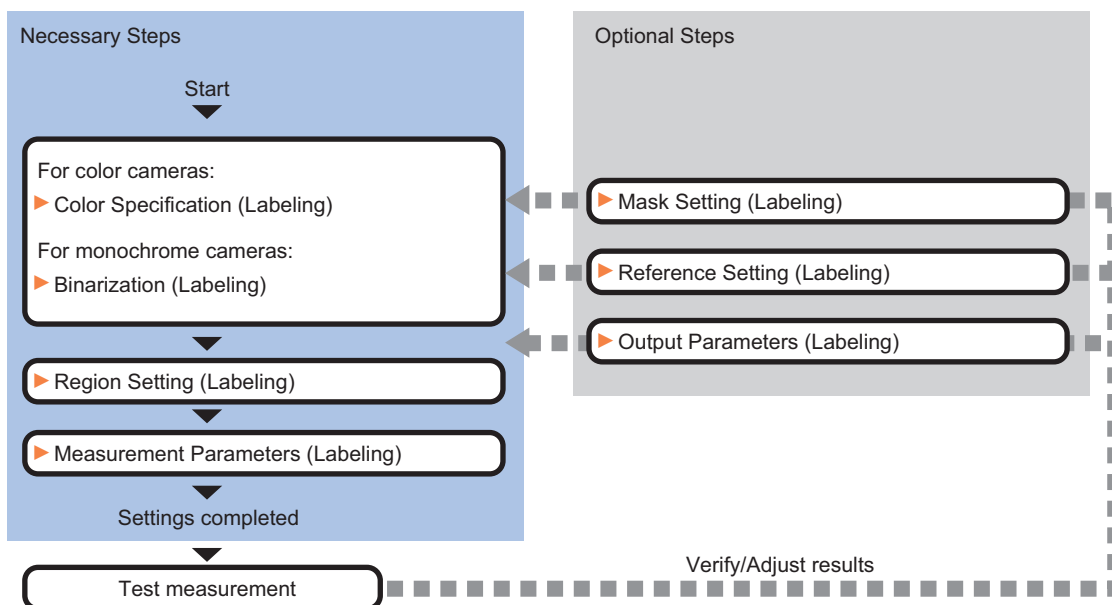
Used in the Following Case

- Label count inspection



Settings Flow (Labeling)

Labeling can be set up as follows.



List of Labeling Items

Item name	Description
Color (for color cameras only)	This item selects the color whose area and center of gravity are to be measured. Since the color hue, color saturation, and brightness can be selected, then fine-tuning can be performed to colors. Reference: ▶ Color Specification (Labeling) (p.299)
Binary (for monochrome cameras only)	This item specifies the binary level for converting 256-tone grayscale images input from the camera into binary images. Converted white pixels are measured. Adjust the binary level so that the measurement object is converted to white pixels. Reference: ▶ Binarization (Labeling) (p.301)
Region setting	This item is used to set up the measurement area. While the input image can be measured as a whole, a quick and reliable measurement can be performed by set up the measured range. Reference: ▶ Region Setting (Labeling) (p.302)
Mask setting	Set it when masking a region. The measurement result of another processing item can also be used for masking. Reference: ▶ Mask Setting (Labeling) (p.302)
Ref. setting	This item can be changed if necessary. Usually, the central position of the registered region is registered as the reference position. Reference: ▶ Reference Setting (Labeling) (p.305)
Measurement	This item specifies the judgement condition for measurement results. It specifies the upper and lower limit values for the number of labels, the area and the center of gravity X and Y. Measurement parameters can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used. Reference: ▶ Measurement Parameters (Labeling) (p.306)
Output parameter	This item can be changed if necessary. Normally, the factory default value may be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Labeling) (p.309)

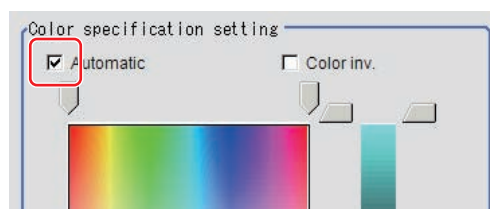
Color Specification (Labeling)

When connecting a color camera, specify the color to be measured. There are two specification methods: specifying the color to be extracted in the image or specifying the color with the hue, saturation, and brightness values.

This section describes how to specify colors in an image and gives an example of the procedure for finely adjusting with numeric input afterwards.

- 1** In the Item Tab area, click [Color].
- 2** Place a check at [Automatic].
- 3** In the Image Display area, specify the color range you want to detect by dragging the cursor from the upper left corner to the lower right corner of that area.

The color of the specified area is automatically set.

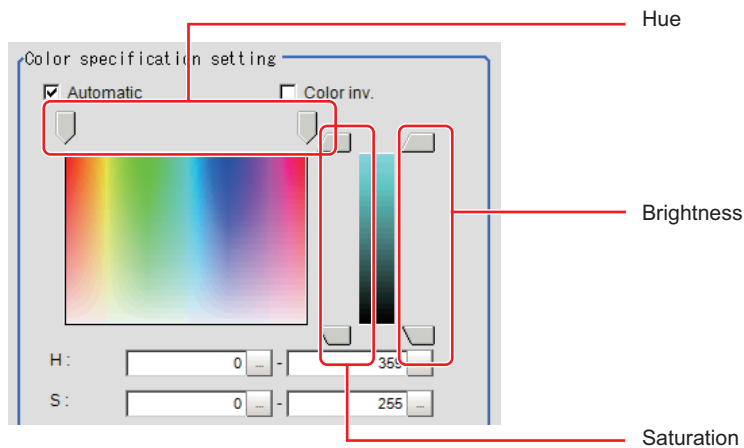


- 4** Finely adjust the hue, saturation, and brightness if necessary.

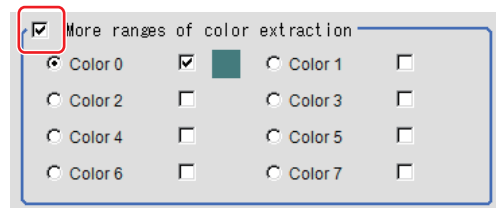
Adjust either by adjusting on the color chart or by inputting numbers.

Item	Set value [Factory default]	Description
H	0 to 359	Specify the color phase (difference of color hues).
S	0 to 255	Specify color saturation (difference of color saturation).
V	0 to 255	Specify the brightness (difference of brightness).
Automatic	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Specifying the color to be measured on the image automatically sets the hue, saturation, and brightness.
Color inv.	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Everything other than the specified color becomes the measurement target.

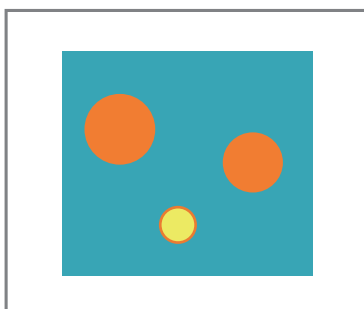
About color charts



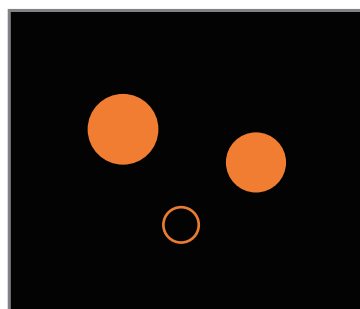
5 To specify multiple colors, place a check at "More ranges of color extraction".



Setting item	Set value [Factory default]	Description
More ranges of color extraction	<ul style="list-style-type: none"> • Checked • [Unchecked] 	If you place a check at this option, you can set up to 8 colors.

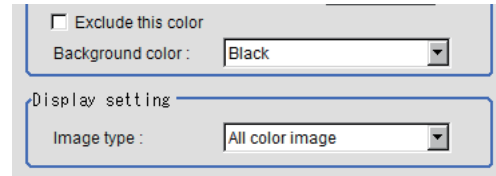


Extract image
(before specifying colors)



Extract image
(after specifying colors – background color: black)

6 If necessary, set the display conditions for displayed images.



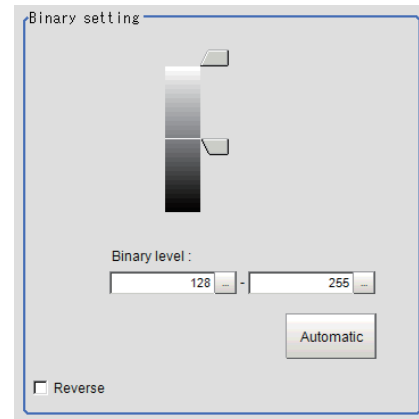
Setting item	Set value [Factory default]	Description
Exclude this color	<ul style="list-style-type: none"> • Checked • [Unchecked] 	If you place a check at this option, pixels within the HSV range are excluded from color extraction. The priority order for exclusion is that the higher color extraction range numbers are given priority. This setting is disabled if "More ranges of color extraction" is unchecked.
Background color	<ul style="list-style-type: none"> • [Black] • White • Red • Green • Blue 	The background section outside the extracted image is filled with the specified colors.
Image type	<ul style="list-style-type: none"> • Measurement image • [All color image] • Selected color image • Binary image 	This sets the state of the image to display.

Binarization (Labeling)

When a monochrome camera is connected, the 256-tone grayscale images taken in from the camera are converted into binary black-and-white images before the images are measured. Converted white pixels are measured.

This specifies the level for converting grayscale images into binary images.

- 1** In the Item Tab area, click [Binary].
- 2** In the "Binary setting" area, specify the reference density range.



Item	Set value [Factory default]	Description
Binary level	Upper limit value 0 to 255 [255]	Specify the level for converting 256-tone grayscale images to binary images. Adjust the binary level so that the measurement object is converted to white pixels. You can also set the binary level so that only intermediate density is measured.
	Lower limit value 0 to 255 [128]	
Automatic	-	Optimum binary levels are calculated automatically and set.
Reverse	<ul style="list-style-type: none"> • [Checked] • Unchecked 	This item reverses black and white colors.

Region Setting (Labeling)

This item is used to set up the measurement area. It is possible to measure the entire input image, but restricting the range enables accurate measurement in a short period of time.

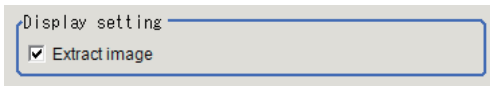
Use a rectangle, straight line, circle (ellipse), wide circle, or polygon to specify a measurement region for [Labeling].

- 1** In the Item Tab area, click [Region setting].
- 2** Use the Drawing tools to specify the measurement region.
- 3** In the figure setting area, specify a region to be measured.
- 4** In the figure setting area, click [OK].

The measurement region is registered and displayed in the Image Display area.

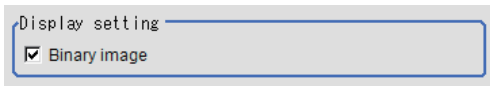
- 5** If necessary, in the "Display setting" area, set up display settings for the images displayed in the Image Display area.

For color cameras:



Setting item	Set value [Factory default]	Description
Extract image	<ul style="list-style-type: none"> • [Checked] • Unchecked 	If you place a check at this option, image set with the color specification are displayed.

For monochrome cameras:



Setting item	Set value [Factory default]	Description
Binary image	<ul style="list-style-type: none"> • [Checked] • Unchecked 	The image is displayed in binary with black and white.

Mask Setting (Labeling)

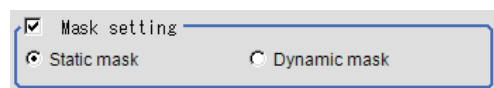
Mask the measurement region when measuring it.

There are two types of masks, namely, a static mask that sets the mask region independent of measurement and a dynamic mask that uses images generated in another unit for each measurement.

Creating a static mask

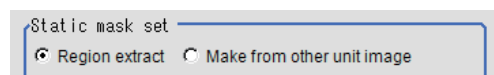
A static mask can be created manually or from an image of another unit.

- 1** In the Mask setting area, select "Static mask".



Generating a mask manually

- 1** In the Static mask set area, select "Region extract".

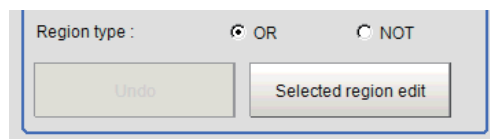


2 Select the selection region type OR or NOT and drag an image directly.

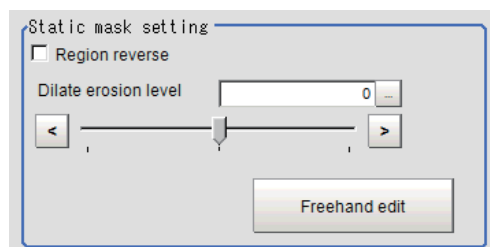
A region is created along successive similar colors from the selected place. It is not masked if the selection region type is OR. It is masked if the selection region type is NOT.

To deselect a selected region, click [Undo].

To edit a region selected with OR/NOT, click [Selected region edit].



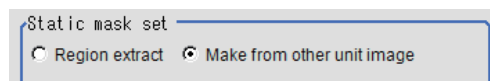
3 Adjust the mask created in the Static mask setting area.



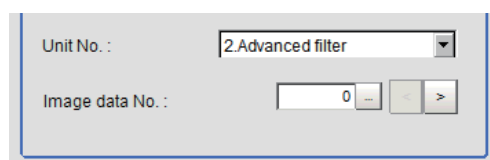
Setting item	Setting value [Factory default]	Description
Region reverse	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check to revert the created mask region.
Dilate erosion level	-10 to 10 [0]	Perform fine adjustment on the mask region using expansions/shrinkage. The region is expanded if a positive value is set. The region is shrunk if a negative value is set.

Creating a static mask from an image of another unit

1 In the Static mask set area, select "Make from other unit image".



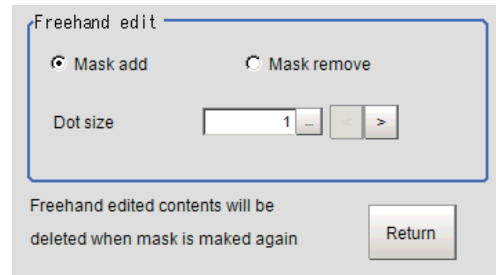
2 Set the unit number and image data number.



Setting item	Setting value [Factory default]	Description
Unit No.	-	Specify the number of the unit whose image will be referenced. The reference unit should be able to output binarized images. For example, select a labeling filter processing image for advanced filtering.
Image data No.	0 to 3 [0]	If the unit supports advanced filtering, numbers 0 to 3 can be set. Otherwise, it is fixed to 0.

Performing fine adjustment on a static mask

- 1 To perform fine adjustment on a mask region, click [Freehand edit] in the Static mask setting area.



Setting item	Setting value [Factory default]	Description
Freehand edit	<ul style="list-style-type: none"> • [Mask add] • Mask remove 	Select a process performed using the free hand edit.
Dot size	1 to 20 [1]	Set the size of dots used when drawing images on the screen.

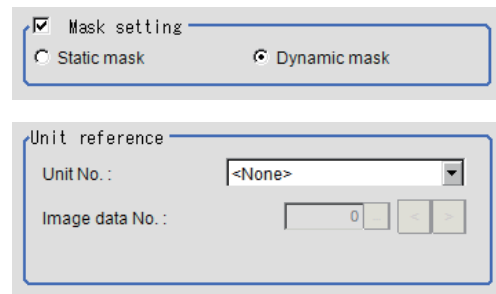
- 2 Click [Return] to exit the free hand edit.

Clearing the static mask setting

To clear the static mask setting, click [Clear].

Creating a dynamic mask

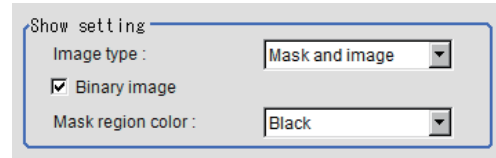
- 1 In the Mask setting area, select "Dynamic mask".
- 2 Set the unit number and image data number in the Unit reference area.



Setting item	Setting value [Factory default]	Description
Unit No.	-	Set the number of the unit being referred to for the mask region. The reference unit should be able to output binarized images. For example, select a labeling filter processing image for advanced filtering.
Image data No.	0 to 3 [0]	If the unit supports advanced filtering, numbers 0 to 3 can be set. Otherwise, it is fixed to 0.

Setting display

Perform the display setting if required.



Setting item	Setting value [Factory default]	Description
Image type	<ul style="list-style-type: none"> • Measure image • Mask binary image • [Mask and image] 	Select the type of an image to be displayed. Measure image: Measured image Mask binary image: Binarized image for masking Mask and image: Post-masking image
Mask region color	<ul style="list-style-type: none"> • [Black] • White • Red • Green • Blue 	Select the color of the region extracted as a mask.

Reference Setting (Labeling)

This item can be changed if necessary. When the region is set, the reference position is automatically set at the center of gravity of the measurement region. In the same way for the reference area, when the region settings are made, they are set automatically based on the measurement region.

This item can be used to change the reference position to any desired position.

A reference position can be set either directly or by referencing a unit.

Specifying directly

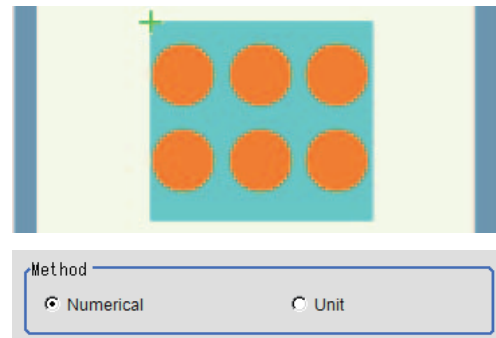
Click a position on the image you want to use as a reference position, or set coordinate data for that point.

1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

2 In the "Method" area, select "Numerical".

3 Click the position to be set as the reference.



Note

- Displaying the image enlarged makes this clicking easier.
Reference: ▶ "Appendixes Basic Knowledge about Operations Using the Zoom Function" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

- 4 Make fine adjustments using numeric value inputs or the arrow buttons as required.

Reference coordinate setting

Reference area :

Ref.pos :

,

- 5 To use data before position compensation for the reference setting coordinates, place a check at "Use point coordinate before scroll".

Use point coordinate before scroll

Position X : 0.0000

Position Y : 0.0000

Referencing a unit

Set a reference by referencing a detection point unit with registered X coordinate, Y coordinate and angle data.

- 1 In the Item Tab area, click [Ref. setting].

In the display area, the current reference position will be displayed as the crosshair cursor.

- 2 In the "Method" area, select "Unit".

Method

Numerical Unit

- 3 In the scene in the "Unit" area, select a detection point unit.

Unit

Reference area :

Unit :

- 4 Perform the next measurement, and the reference will be displayed.

Measurement Parameters (Labeling)

This item specifies the judgement condition for measurement results.

Measurement parameters can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used.

- 1 In the Item Tab area, click [Measurement].
- 2 If necessary, in the "Labeling condition" area, specify a value for each item.

Labeling condition


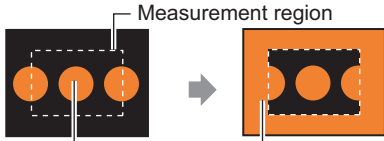
Filling up holes Outside trimming

Sort condition :

Sort order : Ascending Descending

Label No. :

Label maximum :

Setting item	Set value [Factory default]	Description
Filling up holes	<ul style="list-style-type: none"> • Checked • [Unchecked] 	<p>Select the process method for the part encircled by the designated color circle.</p> <p>When checked, the hole is processed as having the specified color.</p> <p>Input image Image after filling up hole</p> 
Outside trimming	<ul style="list-style-type: none"> • Checked • [Unchecked] 	<p>This option can be used only when there is a section of the designated color in the measurement region that does not need to be measured.</p> <p>When "Checked" is set, the whole area outside of the measurement region is extracted as having the specified color.</p> <p>Measurement region</p>  <p>When calculating the position and area of this label</p> <p>The area outside of the measurement region turns the color of the measurement target. Sort mode: Area descending Label No.: 1 With the settings above, the position and area of the middle label will be measured.</p>
Sort condition	<ul style="list-style-type: none"> • [Area] • X • Y • Elliptic major axis • Elliptic minor axis • Elliptic ratio • Rectangle width • Rectangle height • Rectangle X1 • Rectangle Y1 • Perimeter • Circularity • Fit rect major axis • Fit rect minor axis • Fit rect ratio • Inscribed circle X • Inscribed circle Y • Inscribed circle R • Circum. circle X • Circum. circle Y • Circum. circle R • Number of holes 	<p>Specify the conditions by which label number is re-assigned.</p> <p>When sorting referencing the X and Y coordinates, the upper left is the origin.</p>
Sort order	<ul style="list-style-type: none"> • Ascending • [Descending] 	<p>Set the direction for sorting.</p> <p>Ascending: Numbers are assigned from smaller values to larger. Descending: Numbers are assigned from larger values to smaller.</p>
Label No.	<p>For FZ5-3xx, FZ5-6xx: [0] to 2499</p> <p>For FH-1xxx, FH-3xxx: [0] to 9998</p>	<p>Set the label number for the data to be output.</p>

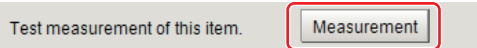
Setting item	Set value [Factory default]	Description
Label maximum	For FZ5-3xx, FZ5-6xx: 0 to 2500 For FH-1xxx, FH-3xxx: 0 to 9999	Set the maximum number of labels to be output.

3 If necessary, in the "Display setting" area, set up display settings for the images displayed in the Image Display area.

4 Set the extraction conditions.

Setting item	Set value [Factory default]	Description
Extraction condition	<ul style="list-style-type: none"> • [Not selected] • Area • Gravity X • Gravity Y • Elliptic major axis • Elliptic minor axis • Elliptic ratio • Rectangle width • Rectangle height • Rectangle X1 • Rectangle Y1 • Perimeter • Circularity • Fit rect major axis • Fit rect minor axis • Inscribed circle R • Circum. circle R • Number of holes 	Set the extraction conditions.
Extraction condition setting	<ul style="list-style-type: none"> • [AND] • OR 	Set the "Extraction conditions". AND: When all the set "Extraction conditions" are fulfilled. OR: When any of the set "Extraction conditions" is fulfilled.

5 When the setting has been changed, click [Measurement] in the "Detail" area to verify whether measurements can be made correctly.



Judgement Conditions (Labeling)

1 In the Item Tab area, click [Judgement].

2 If necessary, specify a value for each item.

To set feature quantities 4-7, click the [Feature data 4-7] button.

Setting item	Set value [Factory default]	Description
Judgement condition		
<ul style="list-style-type: none"> • [None] • Number of labels • Total area • Area • Gravity X • Gravity Y • Elliptic axis angle • Elliptic major axis • Elliptic minor axis • Elliptic ratio • Rectangle width • Rectangle height • Rectangle X1 • Rectangle Y1 	0.000 to 9999999.999	Set up the judgement condition.

3 If necessary, in the "Display setting" area, set up display settings for the images displayed in the Image Display area.

Output Parameters (Labeling)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

1 Click [Output parameter] in the Item Tab area.

2 Specify each of the following items.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgment results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (Labeling)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Number of labels	Number of labels
Area	Area
Gravity X	Gravity X
Gravity Y	Gravity Y

The image specified in the sub image in image display setting is displayed in the Image Display area.

Sub image number.	Explanation of image to be displayed
0	Measurement image
1	Extracted image

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

For color cameras:

Parameter to be adjusted	Remedy
Color	Click the area whose color will be sampled and the area whose color will not be sampled. The setup should be such that two stable sections of hue, saturation and brightness are formed.

For monochrome cameras:

Parameter to be adjusted	Remedy
Binary	Adjust the binary level.

Measurement Results for Which Output Is Possible (Labeling)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Number of labels	L	Number of labels
Total area	TAR	Total area
Area	AR	Area
Gravity X	X	Center of gravity X coordinate
Gravity Y	Y	Center of gravity Y coordinate
Reference area	SA	Reference area
Reference X	SX	Reference position X coordinate
Reference Y	SY	Reference position Y coordinate
Feature quantity 0 to 7	FDA to FDH	Measurement value of the feature quantity selected in the extraction conditions
Feature quantity 0 to 7 [0]	FDA0 to FDH0	Measurement date of feature quantity

Measurement items	Character string	Description
Feature quantity 0 to 7 [1]	FDA1 to FDH1	Measurement date of feature quantity
Feature quantity 0 to 7 [2]	FDA2 to FDH2	Measurement date of feature quantity
• • •	• • •	• • •
Feature quantity 0 to 7 [99]	FDA99 to FDH99	Measurement date of feature quantity

External Reference Tables (Labeling)

No.	Data name	Set/Get	Data range
0	Judge	Get	0: No judgement (unmeasured) 1: Judgment result OK -1: Judgement result NG
5	Number of labels	Get	0 to 2500
6	Area	Get	0 to 999999999.9999
7	Gravity X	Get	-99999.9999 to 99999.9999
8	Gravity Y	Get	-99999.9999 to 99999.9999
9	Reference area	Get	0 to 999999999
10	Reference X	Get	-99999.9999 to 99999.9999
11	Reference Y	Get	-99999.9999 to 99999.9999
101	Output coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Max. color difference	Set/Get	0 to 359
121	Min. color difference	Set/Get	0 to 359
122	Max. saturation	Set/Get	0 to 255
123	Min. saturation	Set/Get	0 to 255
124	Max. brightness	Set/Get	0 to 255
125	Min. brightness	Set/Get	0 to 255
126	Extract image	Set/Get	0: OFF 1: ON
127	Background color	Set/Get	0: Black 1 : White 2: Red 3: Green 4: Blue
128	Reference area	Set/Get	0 to 999999999
129	Reference X	Set/Get	0 to 99999
130	Reference Y	Set/Get	0 to 99999
131	Color inv. (reverse for monochrome)	Set/Get	0: OFF 1: ON
132	Filling up holes	Set/Get	0: OFF 1: ON

No.	Data name	Set/Get	Data range
133	Outside trimming	Set/Get	0: OFF 1: ON
134	Upper limit of the object area range	Set/Get	0 to 999999999.9999
135	Lower limit of the object area range	Set/Get	0 to 999999999.9999
136	Sort condition	Set/Get	0: Area ascending 1: Area descending 2: X-coordinate ascending 3: X-coordinate descending 4: Y-coordinate ascending 5: Y-coordinate descending
137	Label No.	Set/Get	0 to 2499 (For FZ5-3xx, FZ5-6xx) 0 to 9998 (For FH-1xxx, FH-3xxx)
138	Upper limit of the number of labels	Set/Get	0 to 2500 (For FZ5-3xx, FZ5-6xx) 0 to 9999 (For FH-1xxx, FH-3xxx)
139	Lower limit of the number of labels	Set/Get	0 to 2500 (For FZ5-3xx, FZ5-6xx) 0 to 9999 (For FH-1xxx, FH-3xxx)
140	Upper limit of the area	Set/Get	0 to 999999999.9999
141	Lower limit of the area	Set/Get	0 to 999999999.9999
142	Upper limit of the gravity X	Set/Get	-99999.9999 to 99999.9999
143	Lower limit of the gravity X	Set/Get	-99999.9999 to 99999.9999
144	Upper limit of the gravity Y	Set/Get	-99999.9999 to 99999.9999
145	Lower limit of the gravity Y	Set/Get	-99999.9999 to 99999.9999
146	Upper limit of the binary level (for monochrome cameras only)	Set/Get	0 to 255
147	Lower limit of the binary level (for monochrome cameras only)	Set/Get	0 to 255
148	Binary image (for monochrome cameras only)	Set/Get	0: OFF 1: ON
149	Image kind	Set/Get	0: Measurement image 1: All color image 2: Selection color image 3: Binary image
150	Multiple selections	Set/Get	0: Multiple selections disabled 1: Multiple selections enabled
160 + N ^{*1} × 10	Flag N ^{*1} used for registered color	Set/Get	0: Not used 1 : Used
161 + N ^{*1} × 10	Flag N ^{*1} for registered color OR/NOT	Set/Get	0: OR 1: NOT
162 + N ^{*1} × 10	Register the max. color hue N ^{*1}	Set/Get	0 to 359
163 + N ^{*1} × 10	Register the min. color hue N ^{*1}	Set/Get	0 to 359
164 + N ^{*1} × 10	Register the max. color saturation N ^{*1}	Set/Get	0 to 255
165 + N ^{*1} × 10	Register the min. color saturation N ^{*1}	Set/Get	0 to 255

No.	Data name	Set/Get	Data range
$166 + N^{*1} \times 10$	Register the max. color brightness N^{*1}	Set/Get	0 to 255
$167 + N^{*1} \times 10$	Register the min. color brightness N^{*1}	Set/Get	0 to 255
$168 + N^{*1} \times 10$	Background color N^{*1}	Set/Get	0: Black 1 : White 2: Red 3: Green 4: Blue
301	Setting unit of reference coordinate	Set/Get	-1 to 9999
302	Setting type of reference coordinate	Set/Get	0: Numerical 1: Unit
303	Use point coordinate before scroll	Set/Get	0: Not use 1: Use
304	Position X before scroll	Set/Get	-99999.9999 to 99999.9999
305	Position Y before scroll	Set/Get	-99999.9999 to 99999.9999
311	Region reverse	Set/Get	0: Not reverse 1: Reverse
312	Dilate erosion level	Set/Get	-10 to 10
313	Static mask type	Set/Get	0: Region extract 1: Region of image reference
314	Static mask unit reference no	Set/Get	-1 to 9999
315	Static mask image no	Set/Get	0 to 99
316	Dynamic mask unit reference no	Set/Get	-1 to 9999
317	Dynamic mask image no	Set/Get	0 to 99
318	Mask type	Set/Get	0: Static mask 1: Dynamic mask
319	Display image type	Set/Get	0: Measure image 1: Mask binary image 2: Mask and image
324	Is mask	Set/Get	0: OFF 1: ON
325	Mask region display color	Set/Get	0: Black 1: White 2: Red 3: Green 4: Blue
$501 + N^{*1} \times 10$	Extraction condition N^{*1}	Set/Get	0: OFF 1: Area 2: Gravity X 3: Gravity Y 4: Elliptical approximate major axis 5: Elliptical approximate minor axis 6: Ratio for flat approximate ellipse 7: Width of circumscribed rectangle 8: Height of circumscribed rectangle 9: Rectangle X1 10: Rectangle Y1

No.	Data name	Set/Get	Data range
503 + N ^{*1} × 10	Extraction condition upper limit N ^{*1}	Set/Get	-999999999.9999 to 999999999.9999
504 + N ^{*1} × 10	Extraction condition lower limit N ^{*1}	Set/Get	-999999999.9999 to 999999999.9999
600 + N ^{*2} × 10	Judgement condition N ^{*2}	Set/Get	0: OFF 1: Number of labels 2: Total area 3: Area 4: Gravity X 5: Gravity Y 6: Elliptic axis angle 7: Elliptical approximate major axis 8: Elliptical approximate minor axis 9: Ratio for flat approximate ellipse 10: Width of circumscribed rectangle 11: Height of circumscribed rectangle 12: Upper left X coordinate of circumscribed rectangle 13: Upper left Y coordinate of circumscribed rectangle
601 + N ^{*2} × 10	Judgement condition display flag N ^{*2}	Set/Get	0: OR 1: NOT
602 + N ^{*2} × 10	Judgement condition upper limit N ^{*2}	Set/Get	-999999999.9999 to 999999999.9999
603 + N ^{*2} × 10	Judgement condition lower limit N ^{*2}	Set/Get	-999999999.9999 to 999999999.9999
1000 + N ^{*3}	Feature data	Set/Get	-999,999,999.9999 to +999,999,999.9999
1100 + N ^{*3}	Feature data	Set/Get	-999,999,999.9999 to +999,999,999.9999
1200 + N ^{*3}	Feature data	Set/Get	-999,999,999.9999 to +999,999,999.9999
1300 + N ^{*3}	Feature data	Set/Get	-999,999,999.9999 to +999,999,999.9999
1400 + N ^{*3}	Feature data	Set/Get	-999,999,999.9999 to +999,999,999.9999
1500 + N ^{*3}	Feature data	Set/Get	-999,999,999.9999 to +999,999,999.9999
1600 + N ^{*3}	Feature data	Set/Get	-999,999,999.9999 to +999,999,999.9999
1700 + N ^{*3}	Feature data	Set/Get	-999,999,999.9999 to +999,999,999.9999

*1: N = 0 - 2 (Extraction condition 0 to 2)

*2: N = 0 - 7 (Judgement condition 0 to 7)

*3: N = 0 - 99

Label Data

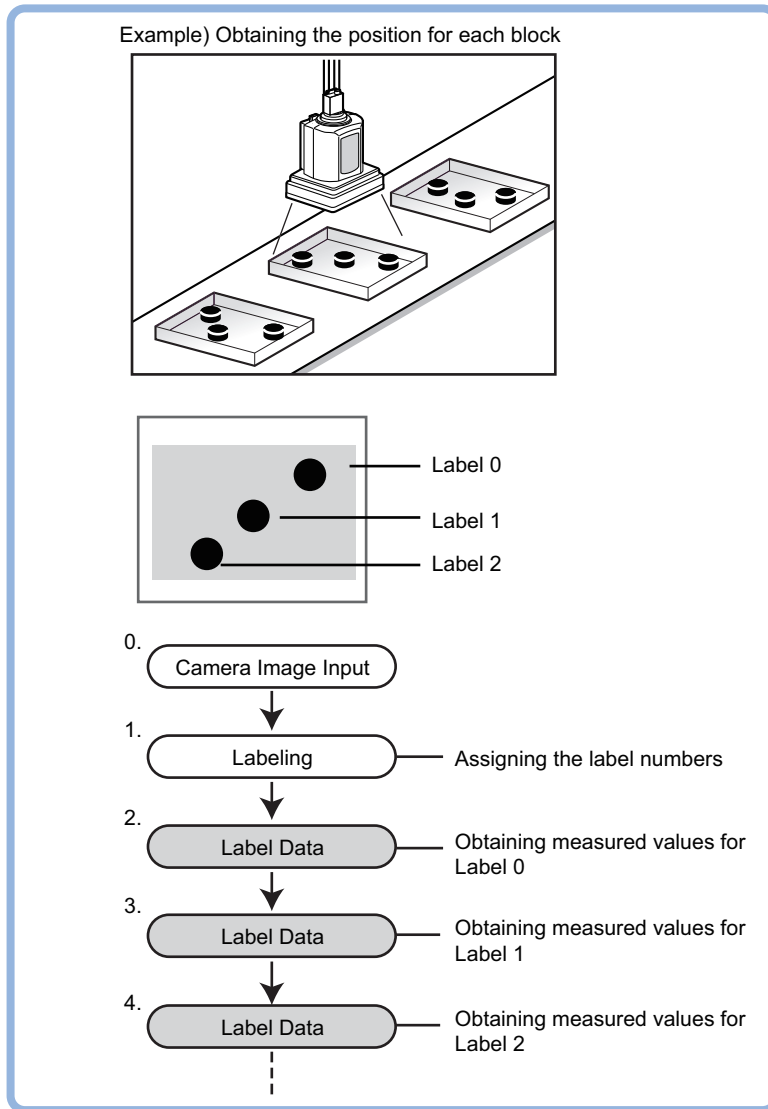
You can specify a desired label number and obtain measurement values for that label stored by other processing units.

The processing items that can be set up as reference objects are the following items that perform the labeling processing.

- Labeling

Used in the Following Case

- Label position acquisition

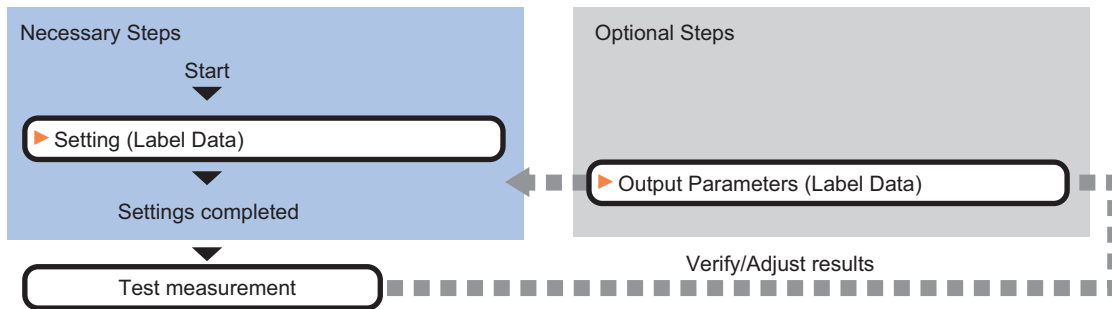


Note

- Do not insert the following processing items between Label Data and Labeling units.
 - Camera Image Input
 - Camera Switching
 - Position Compensation
 - Color Gray Filter
 - Filtering

Settings Flow (Label Data)

Set up the label data with the following steps.



List of Label Data Items

Item name	Description
Setting	Specify the unit number and label number of the processing unit that is designated as the reference object. In addition, specify the judgement conditions for measurement results. Specify the upper and lower limit values for the area and the gravity center X/Y. Reference: ▶ Setting (Label Data) (p.316)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Label Data) (p.317)

Setting (Label Data)

Specify the unit number and label number of the unit set for labeling reference. In addition, specify the judgement conditions for measurement results.

After changing a setting, check whether measurement can be done properly by performing an actual measurement.

- 1 In the Item Tab area, click [Setting].
- 2 In the "Label setting" area, specify each item.

Setting item	Set value [Factory default]	Description
Label unit	[None] to 9999	Specify the number of the unit for which the reference object processing item has been set up. As an option, display the number of the unit for which the following processing items have been set up. • Labeling
Label No.	[0] to 2499 (For FZ5-3xx, FZ5-6xx) [0] to 9998 (For FH-1xxx, FH-3xxx)	Specify the number of the label for the reference object.

- 3** When the setting has been changed, click [Measure] in the Detail area to verify whether measurements can be made correctly.

Test measuring of this item.

Measure

- 4** Set up the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Set value	Description
Area	0 to 999999999.9999	Specify the area to be judged as OK.
Gravity X	-99999.9999 to 99999.9999	Specify the range of X-axis shifting that is judged to be OK.
Gravity Y	-99999.9999 to 99999.9999	Specify the range of Y-axis shifting that is judged to be OK.

Output Parameters (Label Data)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- Click [Output parameter] in the Item Tab area.
- Specify each of the following items.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> [After scroll] Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.
Calibration	<ul style="list-style-type: none"> [OFF] ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> [ON] OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Test Measurement (Label Data)

The following contents are displayed as text in the "Detail result" area.

Displayed items	Description
Judge	Judgement result
Area	Area
Gravity X	Gravity X
Gravity Y	Gravity Y

Measurement Results for Which Output Is Possible (Label Data)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Label No.	LN	Label No.
Area	AR	Area
Gravity X-coordinate	X	Center of gravity X position
Gravity Y-coordinate	Y	Center of gravity Y position

External Reference Tables (Label data)

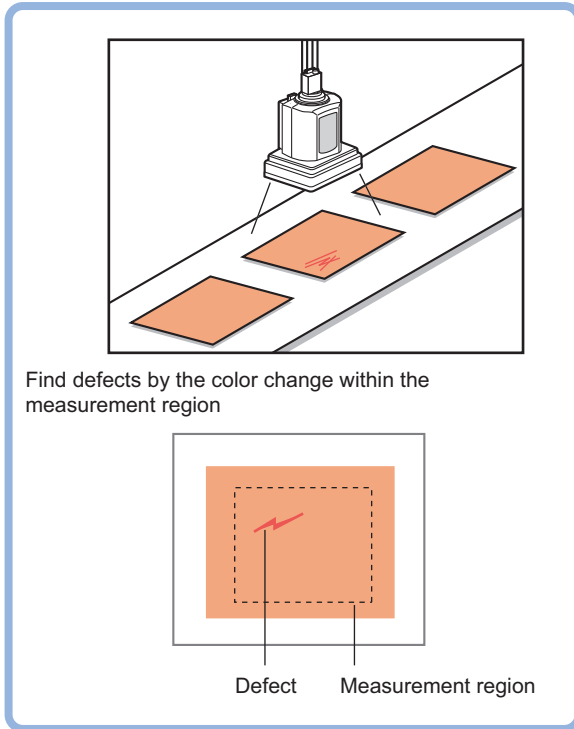
No.	Data name	Set/Get	Data range
0	Judge	Get	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Label No.	Get	0 to 2499 (For FZ5-3xx, FZ5-6xx) 0 to 9998 (For FH-1xxx, FH-3xxx)
6	Area	Get	0 to 999999999.9999
7	Gravity X	Get	-99999.9999 to 99999.9999
8	Gravity Y	Get	-99999.9999 to 99999.9999
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Label unit	Set/Get	-1: None 0 to 9999
121	Label No.	Set/Get	0 to 2499 (For FZ5-3xx, FZ5-6xx) 0 to 9998 (For FH-1xxx, FH-3xxx)
122	Upper limit of the area	Set/Get	0 to 999999999.9999
123	Lower limit of the area	Set/Get	0 to 999999999.9999
124	Upper limit of gravity X	Set/Get	-99999.9999 to 99999.9999
125	Lower limit of gravity X	Set/Get	-99999.9999 to 99999.9999
126	Upper limit of gravity Y	Set/Get	-99999.9999 to 99999.9999
127	Lower limit of gravity Y	Set/Get	-99999.9999 to 99999.9999

Defect

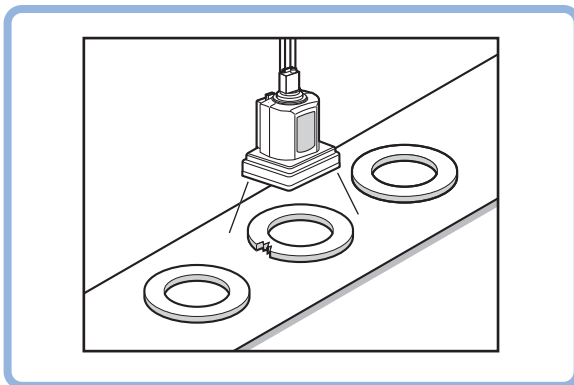
Detect defects and contamination using color variation within the measurement region. This is real color processing, so even if defect and contamination colors change or the background color changes, stable inspection is possible.

Used in the Following Case

- Detecting defects, contaminations and spots on plain measurement objects



- Measure appearance defects and defects of parts

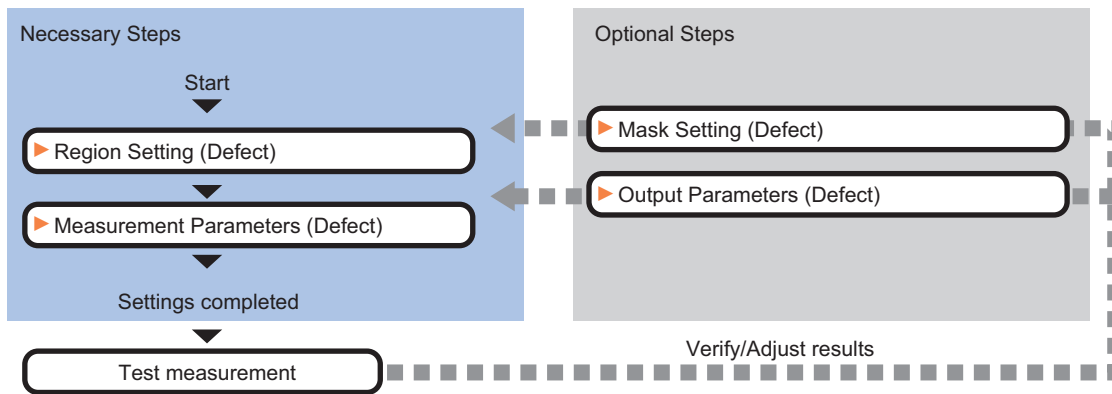


Note

- With Defect, defects and contamination on patterns and characters can not be detected.

Settings Flow (Defect)

Make the defect/contamination settings with the following flow.



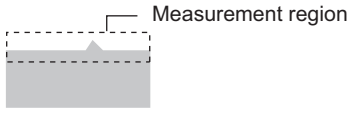
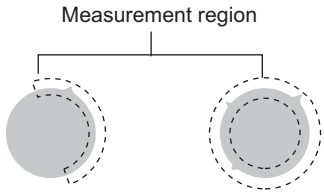
List of Defect Items

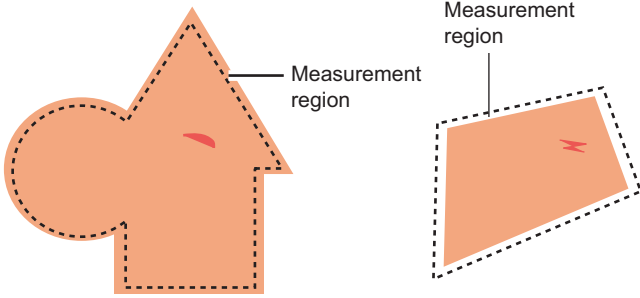
Item name	Description
Region setting	This item is used to set up the measurement area. Instead of measuring the entire input image, narrowing the measurement area shortens the processing time. Reference: ▶ Region Setting (Defect) (p.320)
Mask setting	Set it when masking a region. The measurement result of another processing item can also be used for masking. Reference: ▶ Mask Setting (Defect) (p.321)
Measurement	This item specifies the judgement condition for measurement results. Measurement parameters can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used. Reference: ▶ Measurement Parameters (Defect) (p.324)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Defect) (p.326)

Region Setting (Defect)

This item is used to set up the measurement area.

Use a rectangle, wide line, ellipse (circle), wide circle, wide arc or polygon to specify a measurement region for [Defect]. Up to 8 figures can be drawn.

PT	Description
Wide line	Selected when detecting defects and burrs of the measurement objects. 
Wide circle, wide arc	Selected when detecting defects and burrs of the circle measurement objects. 

PT	Description
Rectangle, ellipse (circle), polygon	<p>Selected when detecting the overall defects of specified zones and measurement objects.</p> 

- 1** In the Item Tab area, click [Region setting].
- 2** Use the Drawing tools to specify the measurement region.
Up to 8 figures can be combined.
- 3** In the figure setting area, click [OK].
The measurement region is registered and displayed in the Image Display area.

Mask Setting (Defect)

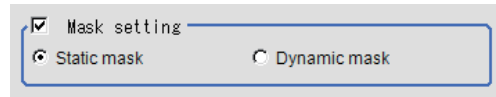
Mask the measurement region when measuring it.

There are two types of masks, namely, a static mask that sets the mask region independent of measurement and a dynamic mask that uses images generated in another unit for each measurement.

Creating a static mask

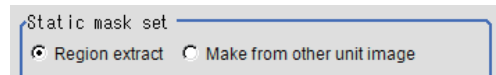
A static mask can be created manually or from an image of another unit.

- 1** In the Mask setting area, select "Static mask".



Generating a mask manually

- 1** In the Static mask set area, select "Region extract".

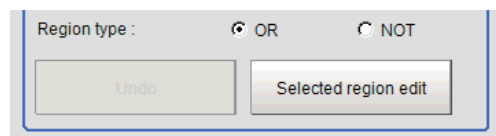


- 2** Select the selection region type OR or NOT and drag an image directly.

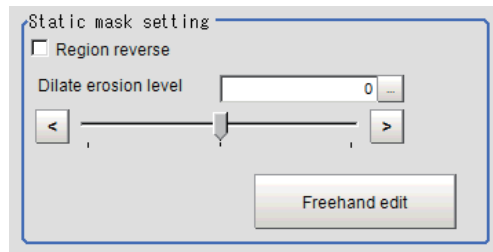
A region is created along successive similar colors from the selected place. It is not masked if the selection region type is OR. It is masked if the selection region type is NOT.

To deselect a selected region, click [Undo].

To edit a region selected with OR/NOT, click [Selected region edit].



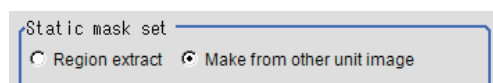
3 Adjust the mask created in the Static mask setting area.



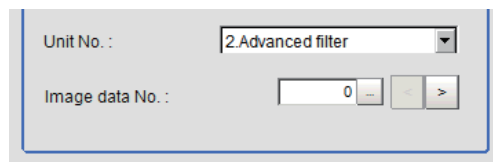
Setting item	Setting value [Factory default]	Description
Region reverse	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check to revert the created mask region.
Dilate erosion level	-10 to 10 [0]	Perform fine adjustment on the mask region using expansions/shrinkage. The region is expanded if a positive value is set. The region is shrunk if a negative value is set.

Creating a static mask from an image of another unit

1 In the Static mask set area, select "Make from other unit image".



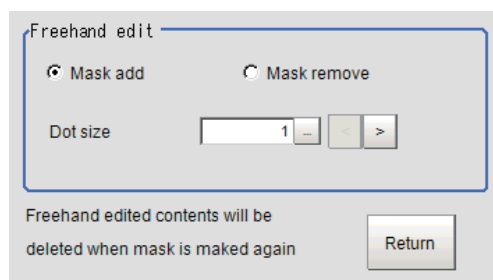
2 Set the unit number and image data number.



Setting item	Setting value [Factory default]	Description
Unit No.	-	Specify the number of the unit whose image will be referenced. The reference unit should be able to output binarized images. For example, select a labeling filter processing image for advanced filtering.
Image data No.	0 to 3 [0]	If the unit supports advanced filtering, numbers 0 to 3 can be set. Otherwise, it is fixed to 0.

Performing fine adjustment on a static mask

1 To perform fine adjustment on a mask region, click [Freehand edit] in the Static mask setting area.



Setting item	Setting value [Factory default]	Description
Freehand edit	<ul style="list-style-type: none"> • [Mask add] • Mask remove 	Select a process performed using the free hand edit.
Dot size	1 to 20 [1]	Set the size of dots used when drawing images on the screen.

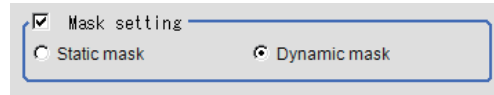
2 Click [Return] to exit the free hand edit.

Clearing the static mask setting

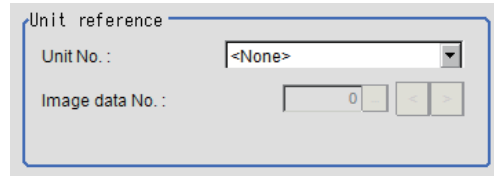
To clear the static mask setting, click [Clear].

Creating a dynamic mask

- 1 In the Mask setting area, select "Dynamic mask".



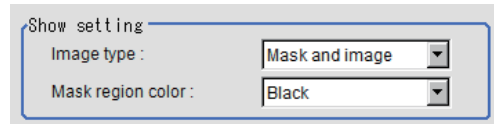
- 2 Set the unit number and image data number in the Unit reference area.



Setting item	Setting value [Factory default]	Description
Unit No.	-	Set the number of the unit being referred to for the mask region. The reference unit should be able to output binarized images. For example, select a labeling filter processing image for advanced filtering.
Image data No.	0 to 3 [0]	If the unit supports advanced filtering, numbers 0 to 3 can be set. Otherwise, it is fixed to 0.

Setting display

Perform the display setting if required.



Setting item	Setting value [Factory default]	Description
Image type	<ul style="list-style-type: none"> • Measure image • Mask binary image • [Mask and image] 	Select the type of an image to be displayed. Measure image: Measured image Mask binary image: Binarized image for masking Mask and image: Post-masking image
Mask region color	<ul style="list-style-type: none"> • [Black] • White • Red • Green • Blue 	Select the color of the region extracted as a mask.

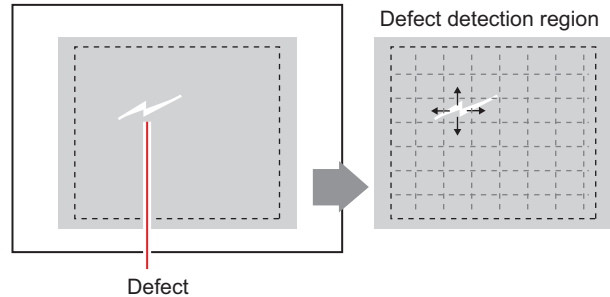
Measurement Parameters (Defect)

This item specifies the judgement condition for measurement results. Measurement parameters can be changed as needed to address unstable measurement results or to increase the processing speed.

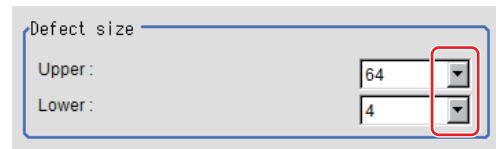
Note

Defect detection mechanism

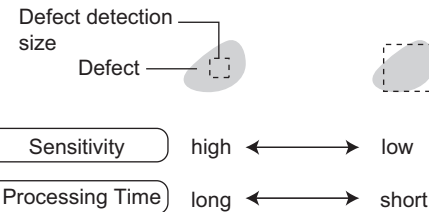
- After measurement region is drawn, a rectangle (defect detection region) is automatically formed in this region. While moving the defect detection region around, calculate the RGB color averages at each location and find the defect detection difference with surrounding defects. This difference is called the defect level. Calculate the defect level for all defect detection areas. If the maximum value exceeds the judgement value, it is judged that there are defects in the measurement region.



- In the Item Tab area, click [Measurement].
- Set the value of each item in the "Defect size" area.

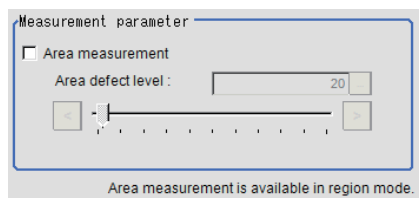


Setting item	Set value [Factory default]	Description
Defect size	<ul style="list-style-type: none"> • 4 • 8 • 12 • 16 • 24 • 32 • 64 [4] to [64]	Specify the upper and lower limits of defect detection size based on the size of scratch or contamination to be detected. A defect detection region is automatically created with the number of pixels for the defects size. The larger the difference between upper and lower limits, the easier to detect defects/contamination of various sizes. For both upper and lower limits, higher values for defect detection size limits leads to weaker detection sensitivity and shorter processing time.

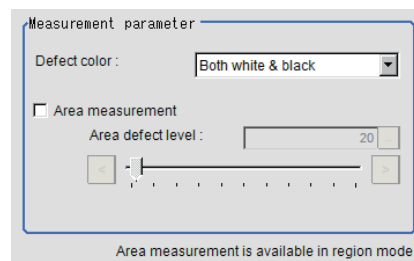


- If necessary, set the value of each item in the "Measurement parameter" area.

For color cameras:



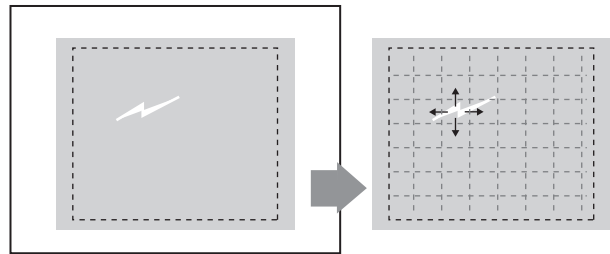
For monochrome cameras:



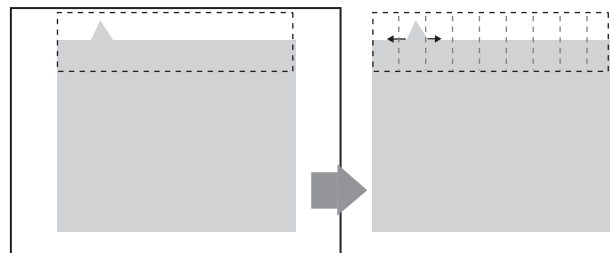
Setting item	Set value [Factory default]	Description
Area measurement	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check when you want to measure the size of defects. This item can divide the high defect detection regions into groups and output the surface and center of gravity coordinates of the group with the largest area. However, when only one region is specified with "Wide line", "Wide circle", or "Arc", area measurement is not possible.
Area defect level	0 to 999 [20]	If you place a check at Area Measurement, set defect level counted in the defect area.
Detect color (for monochrome cameras only)	Black only	Select this value to detect defects that look darker than the background.
	White only	Select this value to detect defects that look lighter than the background.
	[Both white & black]	Select this value when the brightness of defects is not known.

Note**Region inspection mode**

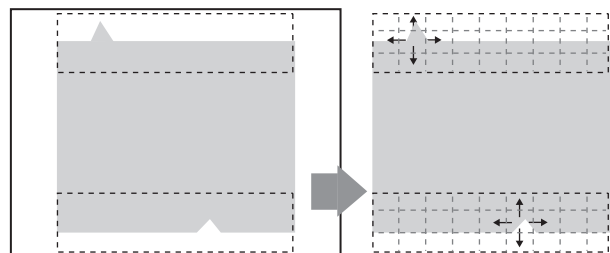
The comparison direction depends on the measurement region shapes and number.
For a rectangle, ellipse or polygon, comparison is with the defect detection regions above, below, left and right. This is called region inspection mode.



For a wide line, wide arc or wide circle, comparison is only with the two neighboring defect detection regions.



However, even for a wide line, wide arc or wide circle, when two or more figures are drawn, measurement is in region inspection mode.

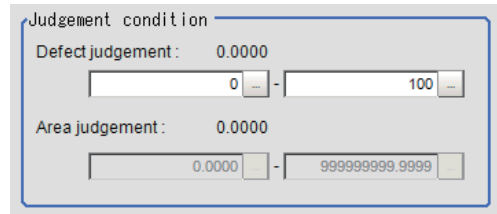


- 4** When the setting has been changed, click [Measurement] in the Detail area to verify whether measurements can be made correctly.

Test measurement of this item.

Measurement

5 Set up the judgement condition.



Item	Set value [Factory default]	Description
Defect judgement	0 to 999 [0] to [100]	Specify the range of defect judgement values that are judged to be OK.
Area judgement	0 to 307200 (for a 0.3-megapixel camera) 0 to 1920000 (for a 2-megapixel camera) 0 to 4320000 (for a 5-megapixel camera)	Specify the range of area judgement values that are judged to be OK.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Output Parameters (Defect)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- Click [Output parameter] in the Item Tab area.
- Choose whether or not to reflect this in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> [ON] [OFF] 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Defect)

In the "Detail result" area on the Main screen, you can confirm the following contents in text.

Displayed items	Description
Judge	Judgement result
Defect	Measured defect level
Position X	X Coordinate of measured defect position
Position Y	Y coordinate of measured defect position
Area	The measured maximum defect area
Gravity X	The center of gravity X coordinates of the measured maximum defect area
Gravity Y	The center of gravity Y coordinates of the measured maximum defect area

The image specified in the sub image in image display setting is displayed in the Image Display area.

Sub image number.	Explanation of image to be displayed
0	Measurement image
1	Defect profile [when area measurement is present]

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Noise is detected as defects.

Parameter to be adjusted	Remedy
Measurement	Specify a larger value for "Defect judgement" in the judgement conditions.

Judgement will be NG.

Parameter to be adjusted	Remedy
Measurement	Make the measurement region larger than the lower limit of the defect size. Or make the lower limit of the defect detection size smaller than the measurement region.

When the processing speed is slow

Parameter to be adjusted	Remedy
Measurement	Specify a larger value for the "Defect size".
	Reduce the difference between the upper and lower limits of [Defect size].

Measurement Results for Which Output Is Possible (Defect)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judgement result
Defect	F	Measured defect level
Position of defect	X	X Coordinate of measured defect position
Position of defect	Y	Y coordinate of measured defect position
Defect area	AR	The measured maximum defect area
Defect gravity	GX	The center of gravity X coordinates of the measured maximum defect area
Defect gravity	GY	The center of gravity Y coordinates of the measured maximum defect area

External Reference Tables (Defect)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Defect	Get only	0 to 999
6	Position X	Get only	0 to 99999.9999
7	Position Y	Get only	0 to 99999.9999
8	Defect area	Get only	0 to 999999999.9999
9	Defect gravity X	Get only	0 to 99999.9999
10	Defect gravity Y	Get only	0 to 99999.9999
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Upper limit of defect size	Set/Get	0: 4 1: 8 2: 12 3: 16 4: 24 5: 32 6: 64
121	Lower limit of defect size	Set/Get	0: 4 1: 8 2: 12 3: 16 4: 24 5: 32 6: 64
122	Upper limit of defect judgement	Set/Get	0 to 999
123	Defect color	Set/Get	0: Both 1: White 2: Black
124	Area measurement	Set/Get	0: OFF 1: ON
125	Area meas, LV	Set/Get	0 to 999
126	Upper limit of area judgement	Set/Get	0 to 999999999.9999
127	Lower limit of area judgement	Set/Get	0 to 999999999.9999
128	Lower limit of defect judgement	Set/Get	0 to 999
150	Region reverse	Set/Get	0: Not reverse 1: Reverse
151	Dilate erosion level	Set/Get	-10 to 10
152	Static mask type	Set/Get	0: Region extract 1: Region of image reference
153	Static mask unit reference no	Set/Get	-1 to 9999
154	Static mask image no	Set/Get	0 to 99

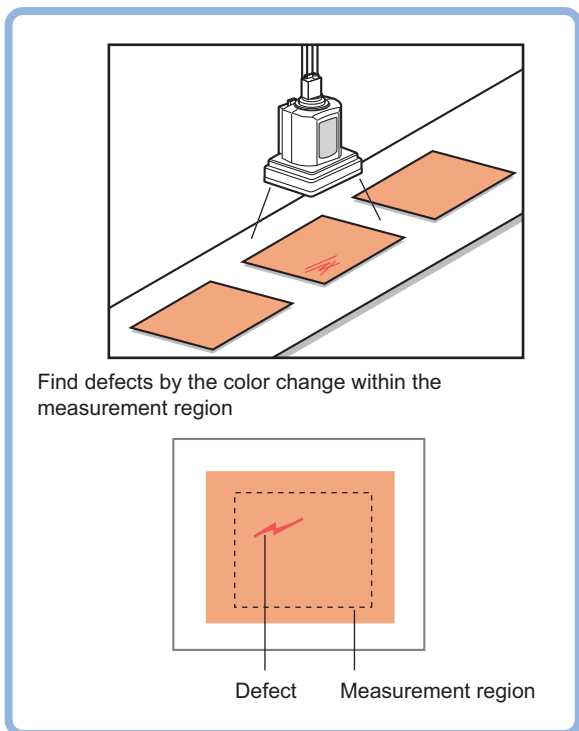
No.	Data name	Set/Get	Data range
155	Dynamic mask unit reference no	Set/Get	-1 to 9999
156	Dynamic mask image no	Set/Get	0 to 99
157	Mask type	Set/Get	0: Static mask 1: Dynamic mask
158	Display image type	Set/Get	0: Measure image 1: Mask binary image 2: Mask and image
163	Is mask	Set/Get	0: OFF 1: ON
164	Mask region display color	Set/Get	0: Black 1: White 2: Red 3: Green 4: Blue

Precise Defect

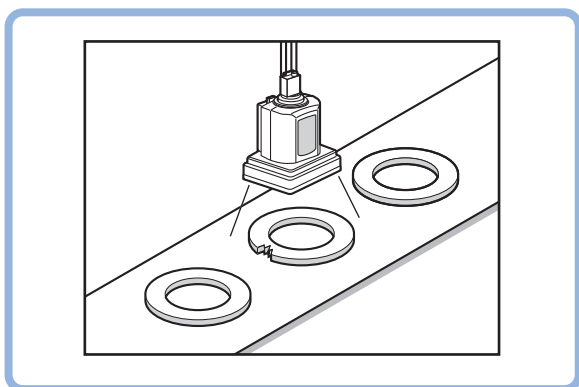
Defects and contamination on plain measurement objects can be detected with high precision by performing differential processing on the image. By changing the size of elements used for detection, comparison intervals, etc., fine customization of speed and precision is possible.

Used in the Following Case

- Detecting defects, contaminations and spots on plain measurement objects

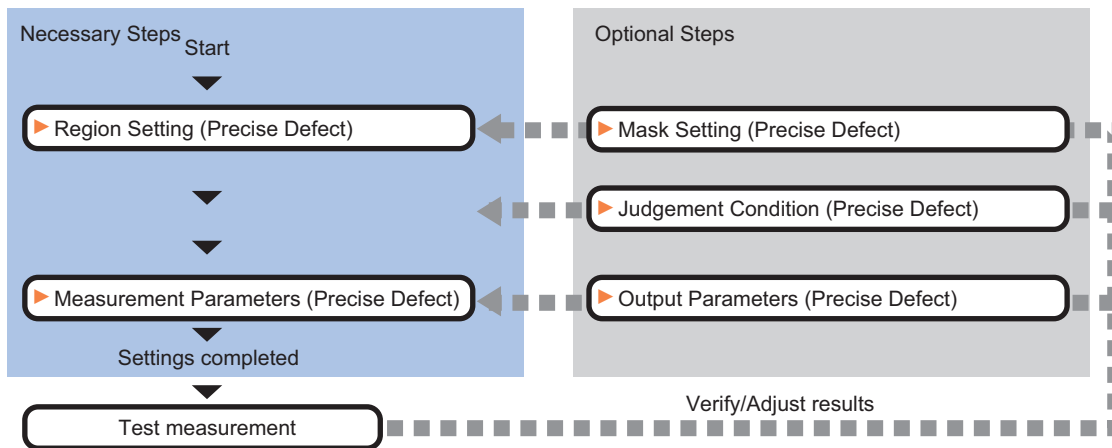


- Measure appearance defects and defects of parts



Settings Flow (Precise Defect)

Precise Defect settings are made with the following flow.



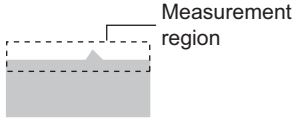
List of Precise Defect Items

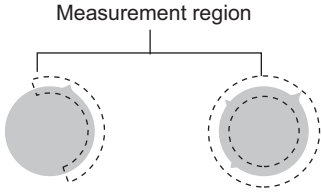
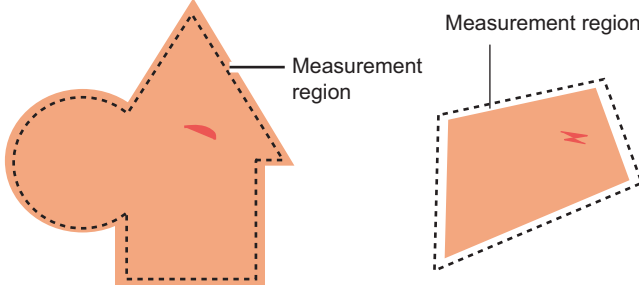
Item name	Description
Region setting	This item is used to set up the measurement area. Instead of measuring the entire input image, narrowing the measurement area shortens the processing time. Reference: ▶ Region Setting (Precise Defect) (p.331)
Mask setting	Set it when masking a region. The measurement result of another processing item can also be used for masking. Reference: ▶ Mask Setting (Precise Defect) (p.332)
Measurement	This item specifies the judgement condition for measurement results. Measurement parameters can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used. Reference: ▶ Measurement Parameters (Precise Defect) (p.335)
Judgement condition	This item can be changed if necessary. Normally, the factory default value will be used. This item specifies the judgement condition for measurement results. Reference: ▶ Judgement Condition (Precise Defect) (p.337)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Precise Defect) (p.338)

Region Setting (Precise Defect)

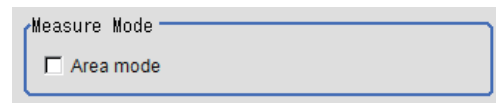
This item is used to set up the measurement area.

Use a rectangle, wide line, ellipse (circle), wide circle, wide arc or polygon to specify a measurement region for [Precise Defect]. Up to 8 figures can be drawn.

PT	Description
Wide line	Selected when detecting defects and burrs of the measurement objects. Measurement can be performed in region mode by checking "Measure in region mode". 

PT	Description
Circumference, Wide arc	<p>Selected when detecting defects and burrs of the circle measurement objects. Measurement can be performed in region mode by checking "Measure in region mode".</p> 
Rectangle, Ellipse (circle), Polygon	<p>Selected when detecting the overall defects of specified zones and measurement objects.</p> 

- 1** In the Item Tab area, click [Region setting].
- 2** Use the Drawing tools to specify the measurement region.
Up to 8 figures can be combined.
- 3** In the figure setting area, click [OK].
The measurement region is registered and displayed in the Image Display area.
- 4** When performing measurement in region mode for wide line, wide circle or arc in a single figure, check "Area" in the Measure Mode area.



Mask Setting (Precise Defect)

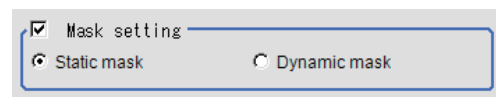
Mask the measurement region when measuring it.

There are two types of masks, namely, a static mask that sets the mask region independent of measurement and a dynamic mask that uses images generated in another unit for each measurement.

Creating a static mask

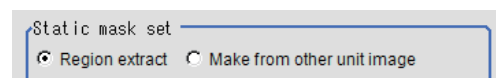
A static mask can be created manually or from an image of another unit.

- 1** In the Mask setting area, select "Static mask".



Generating a mask manually

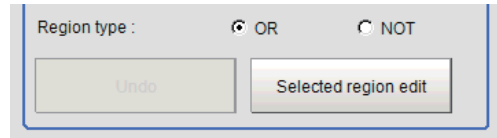
- 1** In the Static mask set area, select "Region extract".



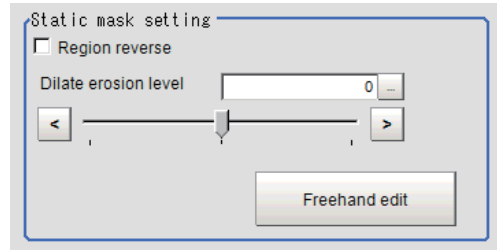
2 Select the selection region type OR or NOT and drag an image directly.

A region is created along successive similar colors from the selected place. It is not masked if the selection region type is OR. It is masked if the selection region type is NOT.

To deselect a selected region, click [Undo].
To edit a region selected with OR/NOT, click [Selected region edit].



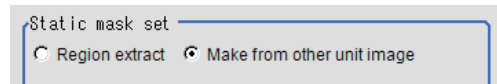
3 Adjust the mask created in the Static mask setting area.



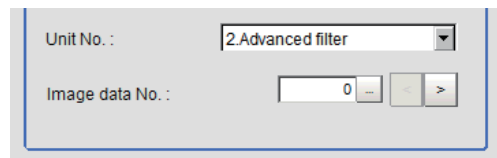
Setting item	Setting value [Factory default]	Description
Region reverse	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check to revert the created mask region.
Dilate erosion level	-10 to 10 [0]	Perform fine adjustment on the mask region using expansions/shrinkage. The region is expanded if a positive value is set. The region is shrunk if a negative value is set.

Creating a static mask from an image of another unit

1 In the Static mask set area, select "Make from other unit image".



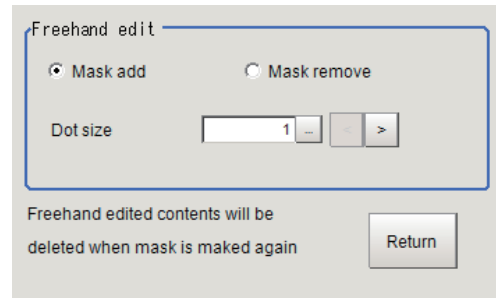
2 Set the unit number and image data number.



Setting item	Setting value [Factory default]	Description
Unit No.	-	Specify the number of the unit whose image will be referenced. The reference unit should be able to output binarized images. For example, select a labeling filter processing image for advanced filtering.
Image data No.	0 to 3 [0]	If the unit supports advanced filtering, numbers 0 to 3 can be set. Otherwise, it is fixed to 0.

Performing fine adjustment on a static mask

- 1 To perform fine adjustment on a mask region, click [Freehand edit] in the Static mask setting area.



Setting item	Setting value [Factory default]	Description
Freehand edit	<ul style="list-style-type: none"> • [Mask add] • Mask remove 	Select a process performed using the free hand edit.
Dot size	1 to 20 [1]	Set the size of dots used when drawing images on the screen.

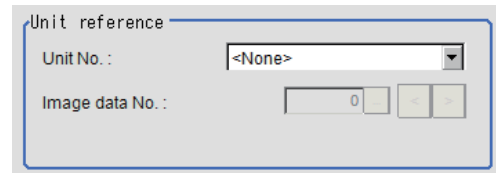
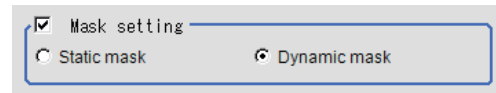
- 2 Click [Return] to exit the free hand edit.

Clearing the static mask setting

To clear the static mask setting, click [Clear].

Creating a dynamic mask

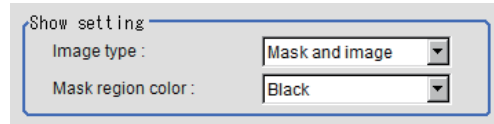
- 1 In the Mask setting area, select "Dynamic mask".
- 2 Set the unit number and image data number in the Unit area.



Setting item	Setting value [Factory default]	Description
Unit No.	-	Set the number of the unit being referred to for the mask region. The reference unit should be able to output binarized images. For example, select a labeling filter processing image for advanced filtering.
Image data No.	0 to 3 [0]	If the unit supports advanced filtering, numbers 0 to 3 can be set. Otherwise, it is fixed to 0.

Setting display

Perform the display setting if required.



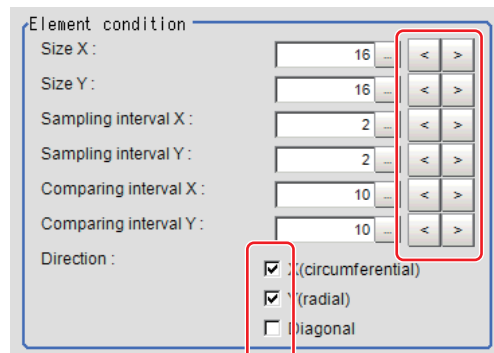
Setting item	Setting value [Factory default]	Description
Image type	<ul style="list-style-type: none"> • Measure image • Mask binary image • [Mask and image] 	Select the type of an image to be displayed. Measure image: Measured image Mask binary image: Binarized image for masking Mask and image: Post-masking image
Mask region color	<ul style="list-style-type: none"> • [Black] • White • Red • Green • Blue 	Select the color of the region extracted as a mask.

Measurement Parameters (Precise Defect)

This item specifies the judgement condition for measurement results. Measurement parameters can be changed as needed to address unstable measurement results or to increase the processing speed.

1 In the Item Tab area, click [Measurement].

2 Set the detection parameters.



Setting item	Set value [Factory default]	Description
Size X	4 to 64 [16]	Specify the X-axis size of defects/contamination to be detected. The higher this value, the higher the degree of defects for large defects. Specify in units of pixels.
Size Y	4 to 64 [16]	Specify the Y-axis size of defects/contamination to be detected. The higher this value, the higher the degree of defects for large defects. Specify in units of pixels.
Sampling interval X	1 to 64 [2]	Specify the interval for creating elements along the X axis. The smaller this value, the greater the defect detection performance, but the slower the processing speed. Specify in units of pixels.
Sampling interval Y	1 to 64 [2]	Specify the interval for creating elements along the Y axis. The smaller this value, the greater the defect detection performance, but the slower the processing speed. Specify in units of pixels.
Comparing interval X	1 to 32 [10]	Set the number of neighboring elements compared with when the degree of defect is calculated, For example, if the sampling interval X is set to 4 and the comparing interval X is set to 2, comparison is with separate elements of $4 \times 2 = 8$ pixels along the X axis.

Setting item	Set value [Factory default]	Description
Comparing interval Y	1 to 32 [10]	This sets the number of neighboring elements compared with when the degree of defect is calculated, For example, if the sampling interval Y is set to 4 and the comparing interval Y is set to 2, comparison is with separate elements of $4 \times 2 = 8$ pixels along the Y axis.
Direction	<ul style="list-style-type: none"> • X (circumferential) • Y (radial) • Diagonal 	Set the direction for detecting defects. The smaller the direction setting count, the shorter the processing time.

Note

- Measurement mode

In Precise Defect measurement, the measurement mode depends on the number of registered region figures and their types. The way to make elements depends on the measurement mode. The relationship between the figure and measurement mode is as in the table below.

	Single figure						Multiple figures
	Line	Circumference	Arc	Ellipse	Rectangle	Polygon	
Measurement mode	Line	Wide circle and arc	Wide circle and arc	Region	Region	Region	Region

Line mode:

- The direction parallel to the measurement region straight line is the X axis and the direction perpendicular is the Y axis. The shape of elements is rectangular. The element width and length are the number of pixels specified with the element size X and Y.

Wide circle and arc mode:

- The circumferential direction along the measurement region wide circle (arc) is the X axis and the radial direction is the Y axis. The shape of elements is fan-shaped. If the circumference length of the wide circle (arc) of the measurement region is set to N, the element circumferential direction width is $360 \text{ degrees} \times \frac{\text{element size X}}{N}$. The element radial direction width is the number of pixels specified with the element size Y. The element circumferential direction width is defined as an angle, so the closer the element to the outer circumference, the larger the element.

Region mode:

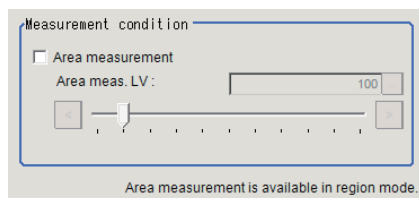
- The direction parallel to the measurement region is the X axis and the direction perpendicular is the Y axis. The shape of elements is rectangular. The element width and length are the number of pixels specified with the element size X and Y.

3 If necessary, set the value of each item in the "Measurement condition" area.

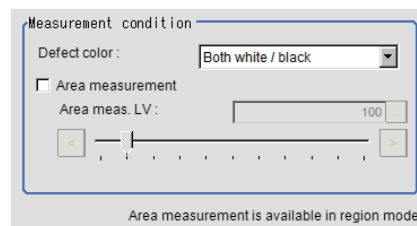
Value input method: Reference: ▶ "Appendixes Basic Knowledge about Operations Inputting Values" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

The "Area meas. LV" can be set also by dragging the slider or by clicking the buttons at the ends of the slider.

For color cameras:



For monochrome cameras:

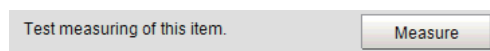


Setting item	Set value [Factory default]	Description
Defect color (for monochrome cameras only)	Black	Select this value when defects look blackish compared to the background.
	White	Select this value when defects look whitish compared to the background.
	[Both white / black]	Select this value when the brightness of defects is not known.
Area measurement	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check when you want to measure the size of defects. This item can divide the high defect detection regions into groups and output the surface and center of gravity coordinates of the group with the largest area. However, when only one region is specified with "Wide line", "Wide circle", or "Arc", area measurement is not possible.
Area meas. LV	0 to 999 [100]	If you place a check at Area Measurement, set defect level counted in the defect area.

Judgement Condition (Precise Defect)

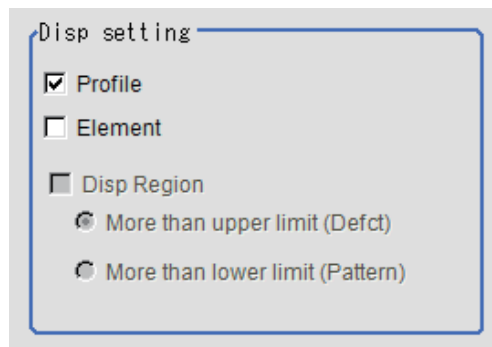
This item specifies the judgement condition for measurement results.

- 1** In the Item Tab area, click [Judgement condition].
- 2** When the setting has been changed, click [Measure] in the "Detail" area to verify whether measurements can be made correctly.
- 3** Set up the judgement condition.



Setting item	Setting value [Factory default]	Description
Defect judge	0 to 999	Specify the range of defect judgement values that are judged to be OK.
Area judge	0 to 999,999,999.9999 0 to 307,200 (0.3 megapixel cameras) 0 to 1,920,000 (2 megapixel cameras) 0 to 4,320,000 (5 megapixel cameras)	Specify the range of area judgement values that are judged to be OK.
Defect number	0 to 2,500 (FZ5-3xx and FZ5-6xx) 0.0000 to 999,999,999.9999 (FH-1xxx and FH-3xxx)	Specify the range of the number of defects that are judged to be OK.

4 If necessary, set the display conditions for displayed images.



Setting item	Set value [Factory default]	Description
Profile	<ul style="list-style-type: none"> • [Checked] • Unchecked 	<p>Set the profile display.</p> <p>The maximum degree of defect along the X(circumferential) and Y(radial) is displayed with red lines. If you click in the measurement region on the image area, the profile in the XY directions from this point is displayed with yellow lines.</p>
Element	<ul style="list-style-type: none"> • Checked • [Unchecked] 	<p>Set the comparison element display. Elements are created automatically during measurement. The density is calculated for each element and the position of defects/contamination is detected from the degree of their variation.</p>
Disp Region	<ul style="list-style-type: none"> • [Checked] • Unchecked 	<p>Place a check to display the defect area. If checked, specify More than upper limit (Defect) or More than lower limit (Pattern).</p>

Output Parameters (Precise Defect)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- 1** Click [Output parameter] in the Item Tab area.
- 2** Choose whether or not to reflect this in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Precise Defect)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Defect value	Measured defect level
Position X	X Coordinate of measured defect position
Position Y	Y coordinate of measured defect position
Defect Area	The measured maximum defect area
Gravity X	The center of gravity X coordinates of the measured maximum defect area
Gravity Y	The center of gravity Y coordinates of the measured maximum defect area
Defect number	Number of measured defects

The image specified in the sub image in image display setting is displayed in the Image Display area.

Sub image number	Explanation of image to be displayed
0	Measurement image
1	Defect profile [when area measurement is present] If the region display is enabled, the defect area display image specified [when no area measurement].

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Noise is detected as defects.

Parameter to be adjusted	Remedy
Measurement	Specify a larger value for "Defect judge" in the judgement conditions.

Judgement will be NG.

Parameter to be adjusted	Remedy
Measurement	Make the measurement region larger than the value of the element size.

When the processing speed is slow

Parameter to be adjusted	Remedy
Measurement	Specify a larger value for the element creation interval.

Measurement Results for Which Output Is Possible (Precise Defect)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judgement result
Defect	F	Measured defect level
Measurement coordinate X	X	X Coordinate of measured defect position
Measurement coordinate Y	Y	Y coordinate of measured defect position

Measurement items	Character string	Description
Defect area	AR	The measured maximum defect area
Gravity X	GX	The center of gravity X coordinates of the measured maximum defect area
Gravity Y	GY	The center of gravity Y coordinates of the measured maximum defect area
Defect number	NM	Number of measured defects

External Reference Tables (Precise Defect)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (not yet measured) 1: Judgement result OK -1: Judgement result NG
5	Defect	Get only	0 to 999
6	Position X	Get only	0 to 999999999.9999
7	Position Y	Get only	0 to 999999999.9999
8	Area	Get only	0 to 999999999.9999
9	Gravity X	Get only	0 to 999999999.9999
10	Gravity Y	Get only	0 to 999999999.9999
11	Defect number	Get only	0 to 2500 (for FZ5-3xx, FZ5-6xx) 0 to 999999999 (for FH-1xxx, FH-3xxx)
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Size X	Set/Get	4 to 64
121	Size Y	Set/Get	4 to 64
122	Sampling interval X	Set/Get	1 to 64
123	Sampling interval Y	Set/Get	1 to 64
124	Comparing interval X	Set/Get	1 to 32
125	Comparing interval Y	Set/Get	1 to 32
126	Detection object color (for monochrome cameras only)	Set/Get	0: Both white/black 1: White 2: Black
127	Defect detection direction X	Set/Get	0: OFF 1: ON
128	Defect detection direction Y	Set/Get	0: OFF 1: ON
129	Inclined defect detection direction	Set/Get	0: OFF 1: ON
130	Upper limit of defect judgement value	Set/Get	0 to 999
131	Area measurement	Set/Get	0: OFF 1: ON
132	Area meas, LV	Set/Get	0 to 999
133	Upper limit of area judgement	Set/Get	0 to 999999999.9999
134	Profile display	Set/Get	0: OFF 1: ON

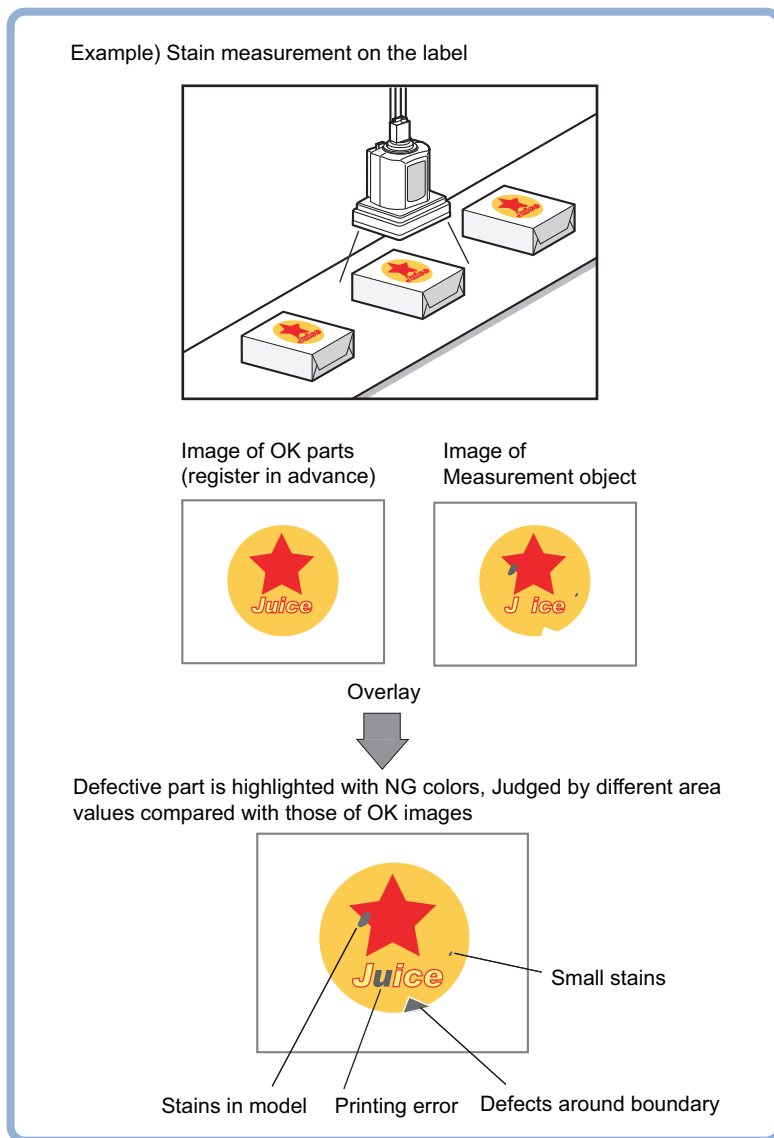
No.	Data name	Set/Get	Data range
135	Element display	Set/Get	0: OFF 1: ON
136	Lower limit of area judgement	Set/Get	0 to 999999999.9999
137	Lower limit of defect judgement value	Set/Get	0 to 999
138	Area mode	Set/Get	0: OFF 1: ON
139	Region display	Set/Get	0: OFF 1: ON
140	Defect number Lower Judge	Set/Get	0 to 2500
141	Defect number Upper Judge	Set/Get	0 to 2500
142	Display defect kind	Set/Get	0: More than upper limit (Defect) 1: More than lower limit (Pattern)
150	Region reverse	Set/Get	0: Not reverse 1: Reverse
151	Dilate erosion level	Set/Get	-10 to 10
152	Static mask type	Set/Get	0: Region extract 1: Region of image reference
153	Static mask unit reference no	Set/Get	-1 to 9999
154	Static mask image no	Set/Get	0 to 99
155	Dynamic mask unit reference no	Set/Get	-1 to 9999
156	Dynamic mask image no	Set/Get	0 to 99
157	Mask type	Set/Get	0: Static mask 1: Dynamic mask
158	Display image type	Set/Get	0: Measure image 1: Mask binary image 2: mask and image
163	Is mask	Set/Get	0: OFF 1: ON
164	Mask region display color	Set/Get	0: Black 1: White 2: Red 3: Green 4: Blue

Fine Matching

Differences can be detected in a fast and highly precise way by overlapping registered fine images with input images (matching).

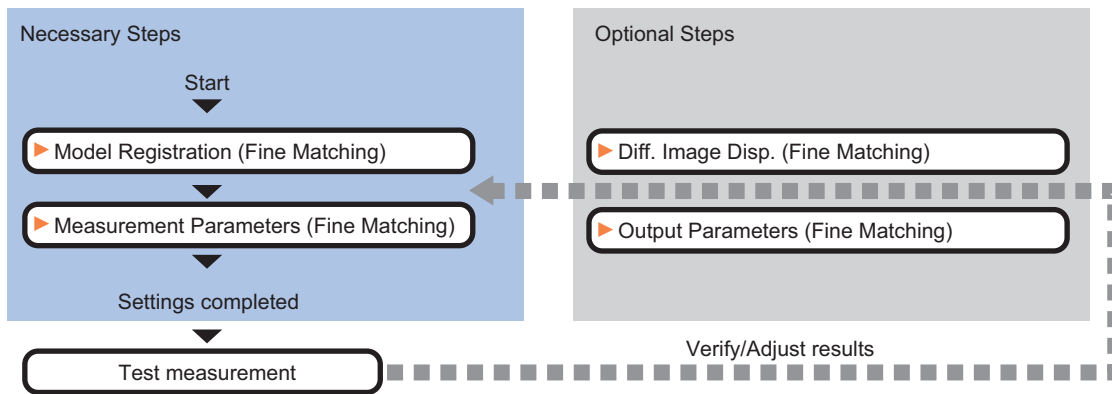
Used in the Following Case

- To precisely detect trivial defects at the edges of text and patterns



Settings Flow (Fine Matching)

Set up fine matching in the follow steps.

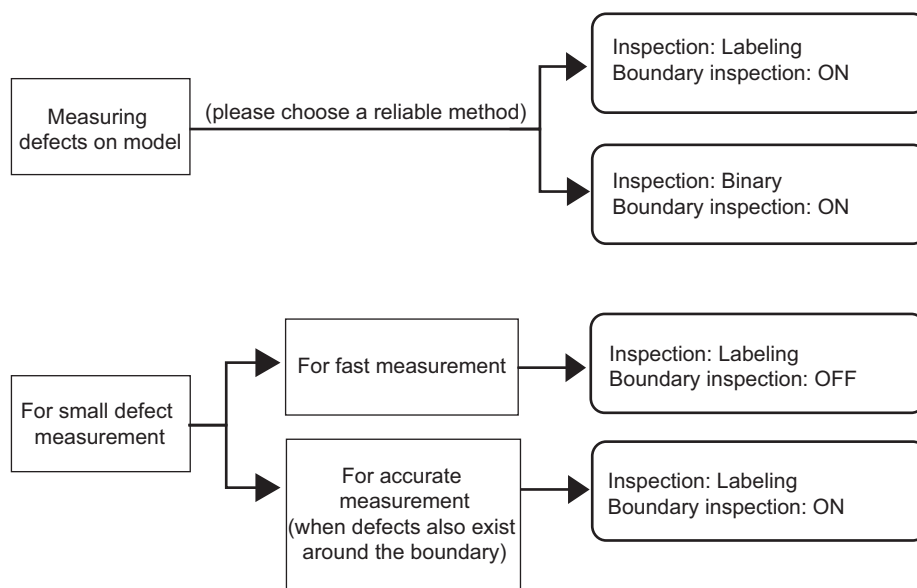


List of Fine Matching Items

Item name	Description
Model register	This item registers the pattern characteristic of the measurement image as a model. Model parameter values can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used. Reference: ▶ Model Registration (Fine Matching) (p.344)
Diff. image disp.	Modify this setting as necessary when defects cannot be detected successfully. This sets the reference grayscale used when calculating differences between the model and the inspected object image. Normally, the factory default value will be used. Reference: ▶ Difference Image Display (Fine Matching) (p.346)
Measurement	This item specifies the judgement condition for measurement results. Specify the criteria to judge the measurement result if the X and Y coordinates and the correlation values with the model are OK. Measurement parameters can be changed as needed to address unstable measurement results or to increase the processing speed. Reference: ▶ Measurement Parameters (Fine Matching) (p.348)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Fine Matching) (p.350)

Note

- Specify [Boundary inspection] in [Model register] and [Inspection] in [Measurement] according to the inspection objectives.



Model Registration (Fine Matching)

Register a fine image as the model. By matching this model with input images, unmatched parts will be detected as defects during inspection.

Note

Ranges that can be registered as models

- The two pixels on the edge of the screen are not registered as a model.
- The registering range will be lower if the images of measurement object are set with Filtering. When you set the image reading range using a camera with the partial scanning function, the range is also limited. Reference: ▶ Filtering (p.425)
- When figures are drawn overlapping, the settings for objects set up afterward are enabled. Reference: ▶ "Appendixes Setting Figures" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

1 In the Item Tab area, click [Model register].

When setting a new model, you do not have to click [Model register].

2 Use the Drawing tools to specify the model registration range.

3 In the figure setting area, click [OK].

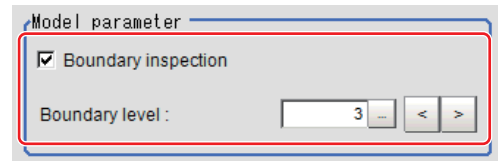
The model is registered.

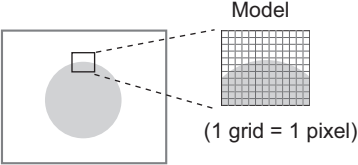


Changing Model Parameters

The range can be changed as needed to address unstable measurement results. Normally, the factory default value will be used.

After changing a setting, check whether measurement can be done properly by performing an actual measurement.

- 1 In the "Model parameter" area, specify a value for each item.



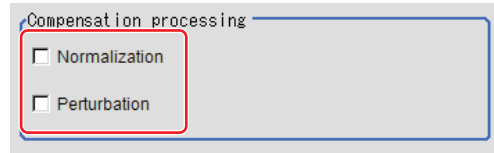
Setting item	Set value [Factory default]	Description
Boundary inspection	[Checked]	Defects around boundaries with color changes can also be detected. The edges similar to those in the model image are not regarded as defects. Check this option when inspecting defects around boundaries, such as chips and burrs. Defects along a direction different from the model image profile are detected in the range of pixels of profile \pm boundary level.
	Unchecked	<p>Boundary areas are excluded from the inspection. This can prevent matching mistakes due to positional deviation of measurement objects, but defects around boundaries cannot be detected. "Boundary level" can be used to specify how many pixels around boundaries should be excluded from the inspection.</p> <div style="display: flex; align-items: center;">  <div style="margin-left: 10px;"> <p>Model</p> <p>(1 grid = 1 pixel)</p> </div> </div> <p>Measurement image</p> <div style="display: flex; align-items: flex-start;">  <div style="margin-left: 10px;"> <p>If the measurement object moves up slightly, its difference with the model will be detected as the edge part.</p> </div> </div> <div style="display: flex; align-items: flex-start;">  <div style="margin-left: 10px;"> <p>When setting Edge Measurement to "Disabled", the range of the "Model edge \pm Boundary level" will be outside of the measurement object. Example) When "Edge level" is 3, the range with a width of 6 pixels will not be outside of the measurement object.</p> </div> </div>
Boundary level	0 to 8 [3]	Select the degree of assimilation of variations around boundaries. Depending on the "Boundary inspection" value, the meaning is different.




Difference Image Display (Fine Matching)

This sets the reference grayscale used when calculating differences between the model and the inspected object image. Modify this setting as necessary when defects cannot be detected successfully. Normally, the factory default value will be used.

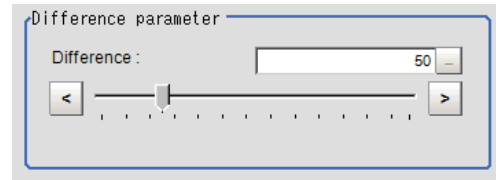
After changing a setting, check whether measurement can be done properly by performing an actual measurement.



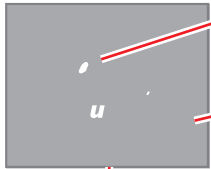
- 1 In the Item Tab area, click [Diff. image disp.].
- 2 In the "Compensation processing" area, select a value for each item.



Setting item	Set value [Factory default]	Description
Normalization	<ul style="list-style-type: none"> • Checked • [Unchecked] 	<p>Specify whether to perform normalization based on the brightness in the registered model.</p> <p>When Normalization is checked, the density is adjusted before matching, so that the matching is not affected by changes in the total image brightness or the lighting fluctuations.</p> <p>When normalization is performed on the measured objects without patterns, the total image brightness is changed and the measurement does not work correctly.</p> <div style="text-align: center;"> <p>Model image</p>  <p>Measurement image (When the whole image turns dark)</p>  <p>Normalization processing →</p>  </div>
Perturbation	<ul style="list-style-type: none"> • Checked • [Unchecked] 	<p>If you place a check here, in order to prevent mistaken detection of slight positional deviation of measurement objects as differences, slight positional deviations are corrected before matching. However, this requires more processing time.</p>

3 Input the "Difference" in the "Difference parameter" area.

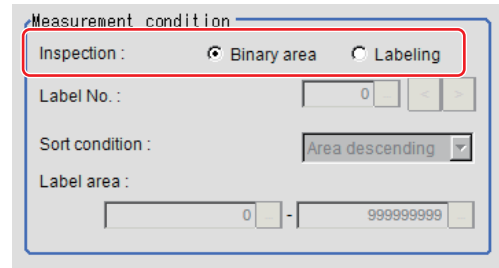


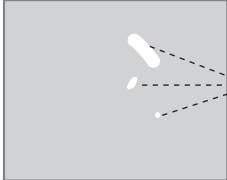
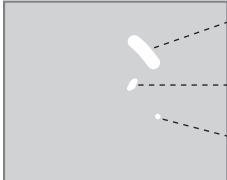
Item	Set value [Factory default]	Description
Difference	0 to 255 [50]	<p>This sets the reference grayscale used when calculating differences between the model and the inspected object image. Pixels with a difference equal to or greater than Difference are converted to white and other pixels are converted to black, so that only defects are converted to white and measured.</p> <div style="display: flex; justify-content: space-around;"> <div style="text-align: center;"> <p>Model Image</p>  </div> <div style="text-align: center;"> <p>Inspected object image</p>  </div> </div> <p style="text-align: center; margin: 10px 0;">↓</p> <div style="display: flex; align-items: center;"> <div style="text-align: center; margin-right: 10px;"> <p>Difference</p>  </div> <div style="margin-left: 10px;"> <p>Pixels with difference equals to or greater than Difference are white</p> <p>Other pixels (with smaller difference with the model) are black</p> <p>Adjust the parameter with an NG image displayed, so that you can refer to the difference image.</p> </div> </div>

Measurement Parameters (Fine Matching)

This item specifies the judgement conditions for measurement conditions and measurement results.

- 1 In the Item Tab area, click [Measurement].
- 2 Select "Inspection" in the "Measurement condition" area.

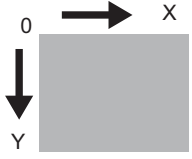
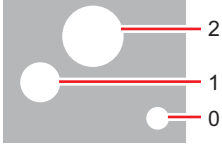
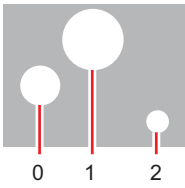
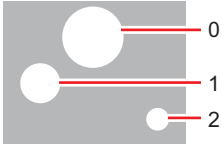


Setting item	Set value [Factory default]	Description
Inspection		Images that are different from the model will be converted into binary images internally. "Inspection" that is used to detect binary images should be selected.
	[Binary area]	Defect is judged based on the total area of white pixels. 
	[Labeling]	A white pixel will be detected as 1 label, which is then compared with a label which is consistent with the set conditions to determine whether or not it is a defect. 

If "Binary area" is selected, the following operations are not necessary.

When Labeling is selected, the following items are set.

Item	Set value [Factory default]	Description
Label No.	0 to 2499 [0]	Specify the label number used to determine whether defects exist. Different settings for "Sort condition" will lead to different number assignment.

Item	Set value [Factory default]	Description
Sort condition		Specify the conditions by which label number is re-assigned. When sorting referencing the X and Y coordinates, the upper left is the origin. This will not affect the coordinate systems set up through the [Camera Image Input] calibration. 
	Area ascending	Number re-assigning begins from the labels with smaller areas. 
	[Area descending]	Number re-assigning begins from labels with larger area.
	X ascending	Number re-assigning begins from the label with a smaller gravity X coordinate. 
	X descending	Number re-assigning begins from the label with a larger gravity X coordinate.
	Y ascending	Number re-assigning begins from the label with a smaller gravity Y coordinate. 
	Y descending	Number re-assigning begins from the label with a larger gravity Y coordinate.
Label area	[0] to [999999999]	Specify the range of the area to be judged as a label.

- 3** When the setting has been changed, click [Measurement] in the Detail area to verify whether measurements can be made correctly.

Test measurement of this item.

Measurement

- 4** Set up the judgement condition.

Setting item	Set value	Description
Quantity	0 to 9999	Specify the range of the number of labels that is judged to be OK. When "Binary area" is used, the white pixels as a whole will be regarded as one label.
Area	0 to 9999999999.9999	Specify the range of the area that is judged to be OK. When the "Labeling" is used, the area of the label number will be specified instead.

Setting item	Set value	Description
Defect pos X	-99999.9999 to 99999.9999	Specify the X and Y axis move ranges for the center of gravity positions that are judged to be OK. When the "Labeling" is used, the center of gravity position of the label number will be specified instead.
Defect pos Y	-99999.9999 to 99999.9999	Specify the X and Y axis move ranges for the center of gravity positions that are judged to be OK. When the "Labeling" is used, the center of gravity position of the label number will be specified instead.

Note

- Defect coordinates give the center of gravity position of detected defects.

Output Parameters (Fine Matching)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- Click [Output parameter] in the Item Tab area.
- Specify each of the following items.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> [After scroll] Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.
Calibration	<ul style="list-style-type: none"> [OFF] ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> [ON] OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Fine Matching)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Quantity	Number of defects
Area	Defect area
Defect coordinate X	Defect coordinate X
Defect coordinate Y	Defect coordinate Y

The image specified in the sub image in image display setting is displayed in the Image Display area.

Sub image number.	Explanation of image to be displayed
0	Measurement image
1	Difference image display

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

When non-existent defects are detected around the boundary

Parameter to be adjusted	Remedy
Model	Uncheck "Boundary inspection".
Measurement	Set "Labeling" as the "Inspection".

When noise is detected as defects/defects cannot be detected

Parameter to be adjusted	Remedy
Diff. image disp.	Adjust "Difference".

Measurement object near plain area

Parameter to be adjusted	Remedy
Diff. image disp.	Uncheck "Normalization".

When the processing speed is slow

Parameter to be adjusted	Remedy
Model	Uncheck "Boundary inspection".
Measurement	Set "Labeling" as the "Inspection".

Measurement Results for Which Output Is Possible (Fine Matching)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judgement result
Quantity	DA	Number of labeling
Area	AR	Area
Defect position	X	X coordinate of center of gravity position of measured defects
Defect position	Y	Y coordinate of center of gravity position of measured defects

External Reference Tables (Fine Matching)

No.	Data name	Set/Get	Data range
0	Judgement result	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Number of labeling	Get only	0 to 9999
6	Area	Get only	0 to 999999999.9999
7	Position X	Get only	-99999.9999 to 99999.9999
8	Position Y	Get only	-99999.9999 to 99999.9999
101	Output coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Boundary inspection	Set/Get	0: OFF 1: ON
121	Boundary level	Set/Get	0 to 9
122	Normalization	Set/Get	0: OFF 1: ON
123	Perturbation processing	Set/Get	0: OFF 1: ON
124	Difference	Set/Get	0 to 255
125	Inspection	Set/Get	0: Binary 1: Labeling
126	Label No.	Set/Get	0 to 2499
127	Sort condition	Set/Get	0: Area ascending 1: Area descending 2: X ascending 3: X descending 4: Y ascending 5: Y descending
128	Upper limit of label area condition	Set/Get	0 to 999999999.9999
129	Lower limit of label area condition	Set/Get	0 to 999999999.9999
130	Upper limit of quantity judgement	Set/Get	0 to 9999
131	Lower limit of quantity judgement	Set/Get	0 to 9999
132	Upper limit of area judgement	Set/Get	0 to 999999999.9999
133	Lower limit of area judgement	Set/Get	0 to 999999999.9999
134	Upper limit of position X	Set/Get	-99999.9999 to 99999.9999
135	Lower limit of position X	Set/Get	-99999.9999 to 99999.9999
136	Upper limit of position Y	Set/Get	-99999.9999 to 99999.9999
137	Lower limit of position Y	Set/Get	-99999.9999 to 99999.9999

Character Inspection

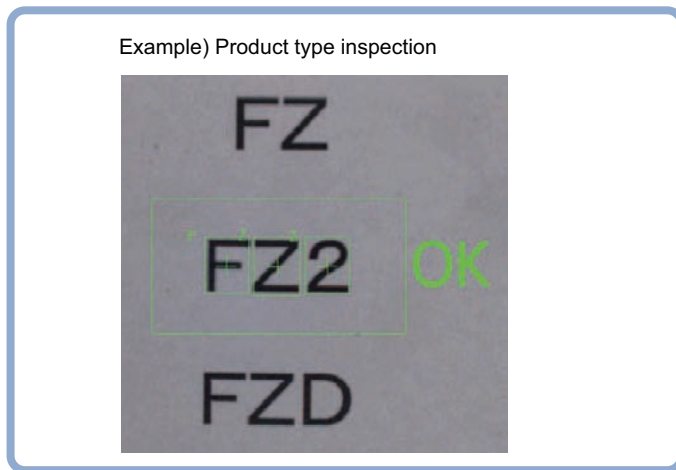
Using model images registered in a [Model Dictionary], this processing item performs character recognition by correlation searches.

Important

- The model dictionary needs to be created in advance.
Reference: ▶ Model Dictionary (p.370)

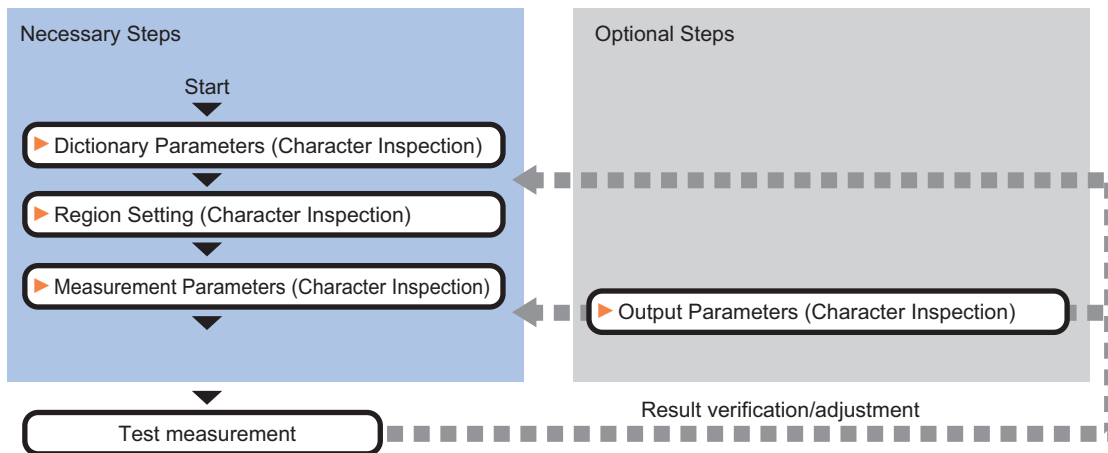
Used in the Following Case

- When identifying standard character data (check of product model name)



Settings Flow (Character Inspection)

The setting procedure for character inspection is as follows:



List of Character Inspection Items

Item name	Description
Dictionary	This item specifies the processing unit number for the model dictionary to use for character recognition. Reference: ▶ Dictionary Parameters (Character Inspection) (p.354)
Region setting	This item is used to set up the measurement area. Instead of measuring the entire input image, narrowing the measurement area shortens the processing time. Reference: ▶ Region Setting (Character Inspection) (p.355)
Measurement	This item specifies the judgement condition for measurement results. Specify the criteria to judge the measurement result if the X and Y coordinates and the correlation values with the model are OK. Reference: ▶ Measurement Parameters (Character Inspection) (p.355)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Character Inspection) (p.357)

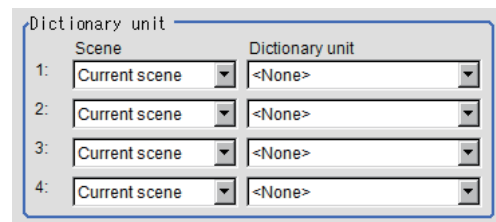
Dictionary Parameters (Character Inspection)

This item selects the processing unit number for the model dictionary to use for character inspection.

1 In the Item Tab area, click [Dictionary].

2 In the "Dictionary unit" area, select the unit number.

A dictionary unit other than the currently used scene can also be used.



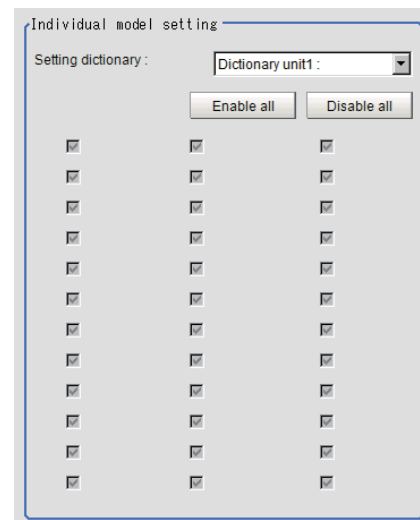
3 If necessary, specify an index to use.

1 Click [▼] and select the dictionary unit to be specified.

The following character strings are registered.

2 Place a check at the character(s) to use for character inspection.

Click the [Enable all]/[Disable all] button to enable/disable all registered characters.



4 Click [OK].

The model dictionary to use is set.

Region Setting (Character Inspection)

This item is used to set up the measurement area.

Instead of measuring the entire input image, narrowing the measurement area shortens the processing time.

This item specifies the measurement region of [Character Inspection] using a rectangle.

- 1 In the Item Tab area, click [Region setting].**
- 2 Click [Edit].**
The figure setting area is displayed.
- 3 Specify the area in which to search for the model.**
The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.
- 4 Click [OK].**
The range to measure is registered.

Note

Number of characters that can be inspected

- Up to 32 characters can be inspected in the measurement region.

Measurement Parameters (Character Inspection)

Set the character inspection contents, the trimming method and the judgement conditions for the measurement results.

- 1 In the Item Tab area, click [Measurement].**
- 2 In the "Inspection condition" area, specify a value for each item.**

Setting item	Set value [Factory default]	Description
Inspection mode	<ul style="list-style-type: none"> • [OCR] • OCR + Count • OCV 	Select the inspection mode of characters. <ul style="list-style-type: none"> • OCR: The character string is read in. • OCR + Count: The character string is read in. Also, the number of characters is inspected. • OCV: Inspects whether or not the same characters are lined up as the preset correct character string combination.
Direction	<ul style="list-style-type: none"> • [→] • ↓ • ← • ↑ 	Specify the direction of character reading.

Setting item	Set value [Factory default]	Description
Horizontal succession	[0] to 99	If the characters are too close together to read in well, increase this. Specify the allowable overlapping range to be read for candidate points. This item is valid when "Direction" is [->] [-<].
Vertical succession	[0] to 99	Specify the allowable overlapping range to be read for candidate points. This item is valid when "Direction" is [↓] [↑].
Dictionary candidate	<ul style="list-style-type: none"> • [Unchecked] (Not used) • Checked (Used) 	Specify whether to use candidate point levels specified in the Model Dictionary or not.
Rough candidate	0 to 100 [40]	When "Dictionary candidate" is unchecked, specify a value for the Rough candidate.
Detail candidate	0 to 100 [60]	When "Dictionary candidate" is unchecked, specify a value for the Detailed candidate.

3 Set up the judgement condition.

The screenshot shows a dialog box titled "Judgement condition". It has the following fields and controls:

- Dictionary correlation
- Correlation: [60] with left and right arrow buttons.
- Lower limit of stability: [0] with left and right arrow buttons.
- Character count: [1] - [32] with left and right arrow buttons.
- Verification string: [] with a right arrow button.

Setting item	Set value [Factory default]	Description
Dictionary correlation	<ul style="list-style-type: none"> • [Unchecked] (Not used) • [Checked] (Used) 	Specify whether to use the correlation lower limit set in the Model Dictionary or not.
Correlation	0 to 100 [60]	When "Dictionary correlation" is unchecked, specify the Correlation.
Lower limit of stability	0 to 100 [0]	<p>The displayed stability value is the value obtained by subtracting the correlation value of the second candidate from the correlation value of the first candidate for the read character.</p> <p>The stability is low when the difference between the candidate correlation values is small, and there is a possibility that the character was misread.</p> <p>A stability higher than the lower limit of stability is OK.</p>
Character count	1 to 32	When "Inspection mode" is "OCR + Count", specify the judgement condition for the number of characters.
Verification string	A string with up to 32 characters. [(None)]	When "Inspection mode" is "OCV", specify the Verification string. "*" in the Verification string is a wild card. Verification of whether a character is "*" is not possible. For sections to be judged OK no matter what characters are present and to just inspect whether or not there are characters at all, use "**".

Output Parameters (Character Inspection)

Select how measurement results are output to an external device. This item can be changed if necessary. Normally, the factory default value will be used.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify a value for each item.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Select whether have the judgement result of this processing unit reflected in the overall judgement of the scene.
Character output	<ul style="list-style-type: none"> • [Unchecked] • Checked 	Specify whether to output read-in character strings to an external device.
	<ul style="list-style-type: none"> • [RS-232C/ RS-422] • Ethernet 	When "Character output" is checked (output), this specifies the device to which strings are output. Character strings are output as ASCII code character strings. When kanji or other characters that are not ASCII codes are included, they are not output correctly.

Note

- For character output, if there was no read character string, then the delimiter is output.

Key Points for Test Measurement and Adjustment (Character Inspection)

The following content is displayed in the "Detail result" area as text.

Displayed items	Color of display	Description
Judge	OK/Unmeasured: Black NG: Red	Judgement result
NG cause	0: Black Other than 0: Red	The following character strings are displayed. When there are multiple factors, the output is ORed. If both the correlation value and the character count are NG, "3" is output. 0: OK 1: Correlation values NG 2: Character count NG 4: Verification NG
Chara count	When the NG cause is the character count NG: Red Other NG: Black	The number of measured characters is displayed.
Read string	When the NG cause is verification NG: Red Other NG: Black	A character string read from the target unit is displayed.
Correlation value	When the NG cause for each character is the correlation value NG: Red Other NG: Black	The correlation values for each character are displayed. Example) When 0123 is read Correlation values: 0(99) 1(56) 2(80) 3(27)
Stability	When the NG cause of each character is stability NG: Red Otherwise: Black	Shows the stability of each character.

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

When the reading is unstable

Parameter to be adjusted	Remedy
Measurement	If characters are close, specify larger values for "Horizontal succession", "Vertical succession".

The judgement is NG (insufficient memory).

Parameter to be adjusted	Remedy
Region setting	Specify as small a value as possible for FigureInfo=Region.

When the processing speed is slow

Parameter to be adjusted	Remedy
Region setting	Specify as small a value as possible for FigureInfo=Region.

Measurement Results for Which Output Is Possible (Character Inspection)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judgement result
Chara. Num	NUM	Chara. Num
NG cause	NG	NG cause
For following items, additional expression data with 32 characters is allocated for each character. (* represents the character number.)		
Unit No.*	CUNO*	Detected unit No. for the *th character
Index No.*	CINDEX*	Detected index number for the *th character
Model No.*	CMODEL*	Detected model number for the *th character
Chara. code*	CCHAR*	Character code for the *th character Reference: ▶ "Appendixes Character Code Table" in the "Vision System FH/FZ5 Series User's Manual (Z340)"
NG Cause *	CNG*	NG cause for the *th character

About Output at PLC Link

1 About output of character inspection

If PLC link communication is performed, selecting the "Character output" check box among the output parameters for character inspection will cause character string data to be output to the PLC link output area.

If 32 characters are read (read character string: 0123456789...UV), a continuous ASCII code data string is output as shown below.

Output area

Top channel	Name	Output contents
+0ch	1st character, 2nd character	3031 (ASCII code corresponding to character "0," ASCII code corresponding to character "1")
+1ch	3rd character, 4th character	3233 (ASCII code corresponding to character "2," ASCII code corresponding to character "3")
• • •		
+15ch	31st character, 32nd character	5556 (ASCII code corresponding to character "U," ASCII code corresponding to character "V")

2 How to receive character string data

As you do when serial data is output via PLC link, control the DSAdata output request bit and GATE data completion request bit.

Since the entire character string comprises 1 data, DSA control is performed once if there is only 1 character inspection unit.

External Reference Tables (Character Inspection)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
1	Chara. Num	Get only	0 to 32
2	NG cause	Get only	0x0000 to 0x0007
3	Read string	Get only	Character string
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120 to 123	Dictionary unit number	Set/Get	-1: OFF 0 to 9999
124	Inspection mode	Set/Get	0: OCR 1: OCR + Count 2: OCV
125	Direction	Set/Get	0: → 1: ↓ 2: ← 3: ↑
126	Character output	Set/Get	0: OFF 1: ON
127	Character output destination	Set/Get	0: RS-232C/RS-422 1: Ethernet
129	Horizontal succession	Set/Get	0 to 99
130	Vertical succession	Set/Get	0 to 99
132	Dictionary candidate point level usage flag	Set/Get	0: Not used 1: Used
133	Rough candidate	Set/Get	0 to 100
134	Detail candidate	Set/Get	0 to 100
135	Dictionary correlation usage flag	Set/Get	0: Not used 1: Used

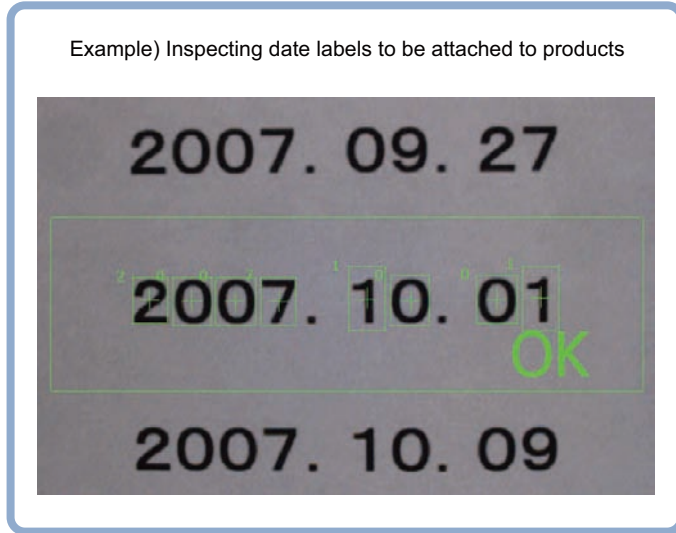
No.	Data name	Set/Get	Data range
136	Lower limit value of correlation value	Set/Get	0 to 100
137	Upper limit of chara. Num	Set/Get	1 to 32
138	Lower limit of chara. Num	Set/Get	1 to 32
139	Verification string	Set/Get	Character string with 32 characters or less
140+N (N=0 to 35)	Model 1 usage flag	Set/Get	0: Not used 1 : Used
176+N (N=0 to 35)	Model 2 usage flag	Set/Get	0: Not used 1 : Used
212+N (N=0 to 35)	Model 3 usage flag	Set/Get	0: Not used 1 : Used
248+N (N=0 to 35)	Model 4 usage flag	Set/Get	0: Not used 1 : Used
284+N (N=0 to 3)	Scene No.	Set/Get	-1: Current scene 0 to 9999
288	Lower limit of stability	Set/Get	0 to 100
1000+N (N=0 to 31)	Unit No.	Get only	-1: None 0 to 9999
1032+N (N=0 to 31)	Detected index	Get only	0 to 35
1064+N (N=0 to 31)	Detected model No.	Get only	0 to 4
1096+N (N=0 to 31)	Chara. code	Get only	0 to 0xFFFF (UTF-16 code)
1128+N (N=0 to 31)	Detected NG cause	Get only	0 to 7
1160+N (N=0 to 31)	Correlation value	Get only	0 to 100
1192+N (N=0 to 31)	Detected coordinate X	Get only	-99999.9999 to 99999.9999
1224+N (N=0 to 31)	Detected coordinate Y	Get only	-99999.9999 to 99999.9999
1256+N (N=0 to 31)	Detected angle	Get only	-180 to 180
1288+N (N=0 to 31)	Reference X	Get only	-99999.9999 to 99999.9999
1320+N (N=0 to 31)	Reference Y	Get only	-99999.9999 to 99999.9999
1352+N (N=0 to 31)	Reference angle	Get only	-180 to 180
1384+N (N=0 to 31)	Detected scene No.	Get only	-1: Current scene 0 to 9999
1416+N (N=0 to 31)	Second correlation value	Get only	0 to 100
1448+N (N=0 to 31)	Second index No.	Get only	0 to 35
1480+N (N=0 to 31)	Stability	Get only	0 to 100

Date Verification

This processing item creates a target string from the current date/time and compares it with read-in strings.

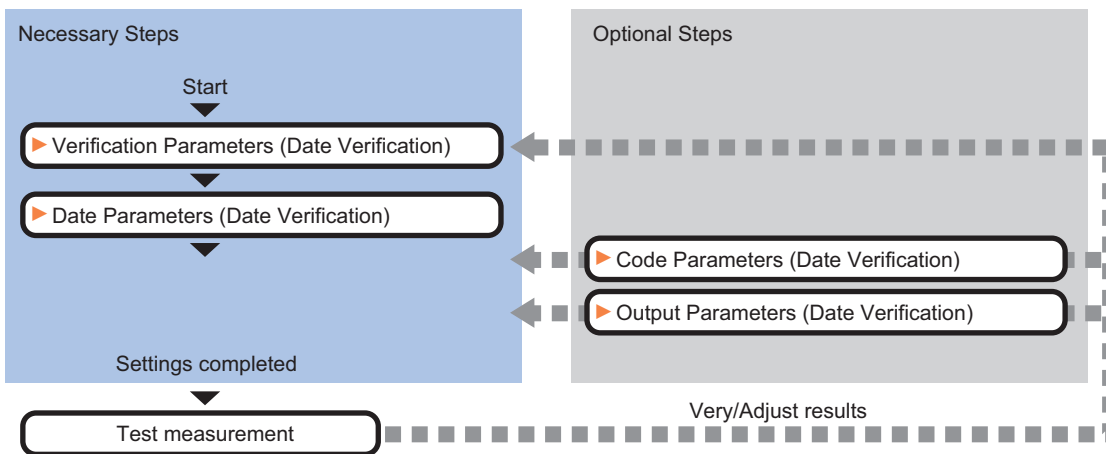
Used in the Following Case

- When inspecting date of manufacture



Settings Flow (Date Verification)

Follow the steps below to set up [Date Verification].



List of Date Verification Items

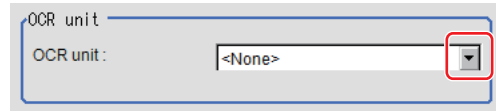
Item name	Description
Verification	This item sets parameters of the verification string. Reference: ▶ Verification Parameters (Date Verification) (p.362)
Date parameter	This item sets the date/time format and update conditions. Reference: ▶ Date Parameters (Date Verification) (p.364)
Code parameter	Set this to print the date encrypted in such a way that it is difficult for the user to recognize. Setting what codes show also makes possible automatic updating. Reference: ▶ Code Parameters (Date Verification) (p.365)

Item name	Description
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Use the output parameter to specify how to handle the coordinates. Reference: ▶ Output Parameters (Date Verification) (p.367)

Verification Parameters (Date Verification)

This item sets the verification target and the verification source character string.
The character string read in Character Inspection is the target for verification.

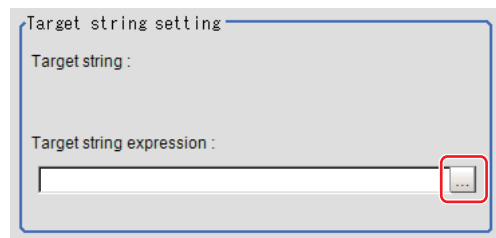
- 1 In the Item Tab area, click [Verification].
- 2 This item sets the general OCR unit for verification.



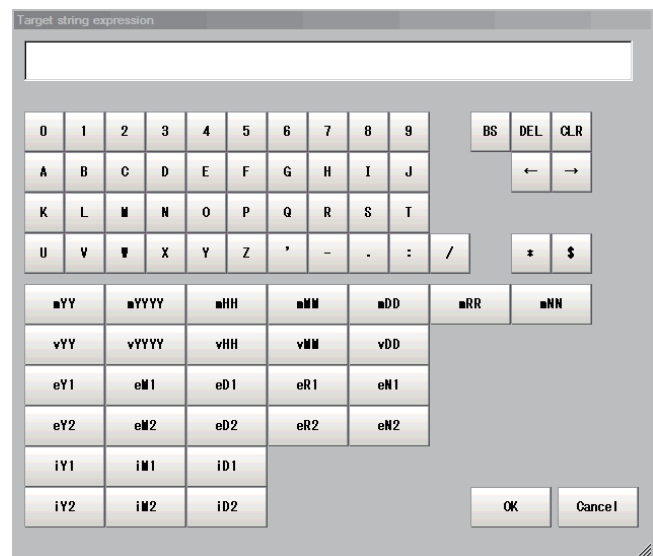
Note

- Always set Character Inspection in a unit before the Date Verification unit.

- 3 In the "Target string setting" area, click [...] for "Target string expression".
The String setting dialog is displayed.



- 4 This item sets the character string that is the source for verification.
Input the date format and the preceding and following character strings.



Label	Description
0 to 9	Normal numeric value input
A to Z	Normal alphabet input
' - . : /	Normal mark input
*	Character presence judgement
\$	Number judgement
mYY	The last two digits of the current year
mYYYY	Four digits of the current year
mHH	Two digits of the current year in the Japanese Heisei calendar

Label	Description
mMM	Current month
mDD	Current day
mRR	Current hour
mNN	Current minute
vYY	The last two digits of the year after a set period of time
vYYYY	Four digits of the year after a set period of time
vHH	Two digits of the year after a set period of time in the Japanese Heisei calendar
vMM	Month after a set period of time
vDD	Day after a set period of time
eY1	Encrypted year 1
eM1	Encrypted month 1
eD1	Encrypted day 1
eR1	Encrypted hour 1
eN1	Encrypted minute 1
eY2	Encrypted year 2
eM2	Encrypted month 2
eD2	Encrypted day 2
eR2	Encrypted hour 2
eN2	Encrypted minute 2
iY1	Encrypted year 1 after a set period of time
iM1	Encrypted month 1 after a set period of time
iD1	Encrypted day 1 after a set period of time
iY2	Encrypted year 2 after a set period of time
iM2	Encrypted month 2 after a set period of time
iD2	Encrypted day 2 after a set period of time

5 Click [OK].

Date Parameters (Date Verification)

This item sets the date/time format and update conditions.

- 1 In the Item Tab area, click [Date parameter].
- 2 When comparing with character strings with an expiration date limit, set each item in the "Period setting" area.

Setting item	Set value [Factory default]	Description
Year	0 to 99 [0]	This item sets the usage period from the current date. Example) When the current date is Oct. 1, 2007 and the usage period is 10 days, the expiration date is Oct. 11, 2007.
Month	0 to 99 [0]	
Day	-999 to 999 [0]	

- 3 In the "Date setting" area, specify a value for each item.

Setting item	Set value [Factory default]	Description
Auto Update	<ul style="list-style-type: none"> • Not update • First measure • [Always update] 	Set the year, month and day updating conditions. The clock time is always updated. <ul style="list-style-type: none"> • Not update: The date is stored into memory when the processing unit is registered. The date is not updated until the next time date update is executed with the menu. • First measure: The date is updated during the first measurement after start up. • Always update: The date is updated every measurement.
Zero suppress	<ul style="list-style-type: none"> • [0] • Space 	Set how the tens digits of the month and day are displayed.
Calculation order	<ul style="list-style-type: none"> • [Month->Day] • Day->Month 	Set whether to calculate the month first or the day first when the usage period is set. (This affects calculation of end of month.)
Month end adjust	<ul style="list-style-type: none"> • [Last day of current month] • First day of next month • Gap day of next month 	Set the adjustment method that will be used if the result of the expiration date calculation is an invalid date. Example) When the current date is Jan. 31 and the usage period is 1 month "Last day of current month" = Feb. 28 "First day of next" = March 1 "Gap day of next" = March 3

4 Set the time margin.

Setting item	Set value [Factory default]	Description
Back margin	0 to 99 [0]	Set the time before the current time to be judged OK The unit is minutes. Example) If 10 is set, an OK judgement is rendered up to the character string 10 minutes before the verification string.
Ahead margin	0 to 99 [0]	Set the time after the current time to be judged OK The unit is minutes. Example) If 10 is set, an OK judgement is rendered up to the character string 10 minutes after the verification string.

Clicking [Date update] updates the date information of the verification string.

Code Parameters (Date Verification)

Preset what the codes show so that date verification is possible even when printing the date encrypted in such a way that it is difficult for the user to recognize.

The setting methods are to set on the screen or set with a PC.

Important

- If a usage period is set, encrypted characters cannot be used for character verification.

Setting on the Screen

This describes the setting method, using an example in which October is encrypted as X.

- 1 In the Item Tab area, click [Code parameter].
- 2 Place a check at "Code month 1 flag".

Note

Code month 1 and code month 2

- Set up code files for 2 patterns in order to be ready for setup changes. Select a check at the one to use.

- 3 Place a check at "Code month 1" in the "Code detail setting" area.

- 4 Click [...] for "10".

The software keyboard is displayed. Input "X".

Input a character string of up to 4 characters.

01:	<input type="text"/>	--
02:	<input type="text"/>	--
03:	<input type="text"/>	--
04:	<input type="text"/>	--
05:	<input type="text"/>	--
06:	<input type="text"/>	--
07:	<input type="text"/>	--
08:	<input type="text"/>	--
09:	<input type="text"/>	--
10:	x	--
11:	<input type="text"/>	--
12:	<input type="text"/>	--

Setting with a PC

Code files are complex, so performing the settings with a PC makes file editing easier and minimizes mistakes. Saving an empty CSV file first and then editing and reading it with a PC makes setting the values more efficient.

Saving code files

Make an empty file for editing on the PC.

If encryption parameters are already set on the screen, a file reflecting those settings is saved.

- 1** In the Item Tab area, click [Code parameter].
- 2** Place a check at the flag used in the encrypted character strings to be edited.

Code flag setting

- Code year 1 flag
- Code year 2 flag
- Code month 1 flag
- Code month 2 flag
- Code day 1 flag
- Code day 2 flag
- Code hour 1 flag
- Code hour 2 flag
- Code minute 1 flag
- Code minute 2 flag

- 3** In the "Code file" area, click [Save code file].

Code file

Load code file

Save code file

- 4** Set the save destination folder and file name, and click [OK].

The code file is saved (in CSV format).

Code file format

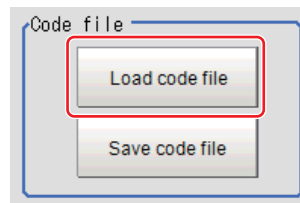
- The first line shows the "Code".
- The second line shows the "Flag". Input "1" when used.
- The third line and subsequent lines contain codes for each number.

Months and days start from "1".

5																				
6																				
7																				
8																				
9																				
10																				
11																				
12																				
13																				
14																				
15																				
16																				
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27																				
28																				
29																				
30																				
31																				
32																				
.																				
.																				
.																				
98																				
99																				

Reading code files

- 1 In the Item Tab area, click [Code parameter].
- 2 In the "Code file" area, click [Load code file].



- 3 In the file selection window, select the code file (in CSV format) to read and click [OK].
The code file is read and the content is displayed in the window.

Output Parameters (Date Verification)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Choose whether or not to reflect this in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Test Measurement (Date Verification)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Target string	Target string setting is displayed.
Read string	A character string read from the OCR unit is displayed.

Measurement Results for Which Output Is Possible (Date Verification)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Date Verification)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
1	Verification string	Get only	Character string with 32 characters or less
2	Read string	Get only	Character string with 32 characters or less
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	OCR unit number	Set/Get	-1: OFF 0 to 9999
125	Term year	Set/Get	0 to 99
126	Term month	Set/Get	0 to 99
127	Term day	Set/Get	0 to 999
128	Auto Update	Set/Get	0: Not update 1: First measurement after startup 2: Always update
129	Zero suppress	Set/Get	0: 0 1: Space
130	Calculation order	Set/Get	0: Month→Day 1: Day→Month
131	Month end adjust	Set/Get	0: Last day of now 1: First day of next 2: Gap day of next
132	Back margin	Set/Get	0 to 99
133	Ahead margin	Set/Get	0 to 99
134	Code year 1 flag	Set/Get	0: Not used 1 : Used
135	Code year 2 flag	Set/Get	0: Not used 1 : Used

No.	Data name	Set/Get	Data range
136	Code month 1 flag	Set/Get	0: Not used 1 : Used
137	Code month 2 flag	Set/Get	0: Not used 1 : Used
138	Code day 1 flag	Set/Get	0: Not used 1 : Used
139	Code day 2 flag	Set/Get	0: Not used 1 : Used
140	Code hour 1 flag	Set/Get	0: Not used 1 : Used
141	Code hour 2 flag	Set/Get	0: Not used 1 : Used
142	Code minute 1 flag	Set/Get	0: Not used 1 : Used
143	Code minute 2 flag	Set/Get	0: Not used 1 : Used
150	Character string year 1 flag	Set/Get	0: Not used 1 : Used
151	Character string year 2 flag	Set/Get	0: Not used 1 : Used
152	Character string month 1 flag	Set/Get	0: Not used 1 : Used
153	Character string month 2 flag	Set/Get	0: Not used 1 : Used
154	Character string day 1 flag	Set/Get	0: Not used 1 : Used
155	Character string day 2 flag	Set/Get	0: Not used 1 : Used
156	Character string hour 1 flag	Set/Get	0: Not used 1 : Used
157	Character string hour 2 flag	Set/Get	0: Not used 1 : Used
158	Character string minute 1 flag	Set/Get	0: Not used 1 : Used
159	Character string minute 2 flag	Set/Get	0: Not used 1 : Used
160	Operation code number	Set/Get	0 to 99

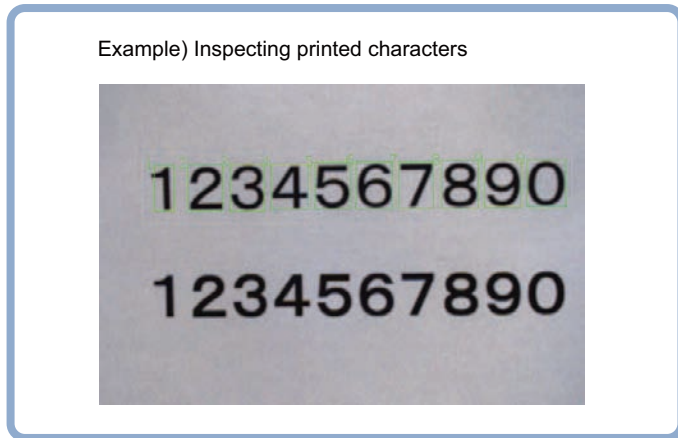
Model Dictionary

Register a model to use for [Character Inspection].

Model data registered in the [Model Dictionary] can be referred to from multiple [Character Inspection] items in the same scene.

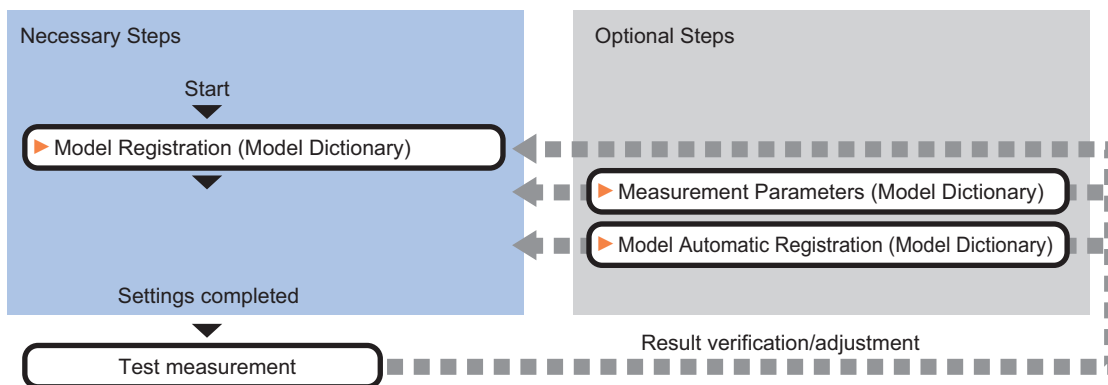
Used in the Following Case

- To create the dictionary to be used for Character Inspection and Date Verification



Settings Flow (Model Dictionary)

Follow the steps below to set up [Model Dictionary].



List of Model Dictionary Items

Model Dictionary items are explained below.

Item name	Description
Model	Register the characters and marks as the model. Model parameter values can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used. Reference: ▶ Model Registration (Model Dictionary) (p.371)
Measurement	This item can be changed if necessary. Reference: ▶ Measurement Parameters (Model Dictionary) (p.373)
Auto registration	When registering multiple characters as models, auto registration is handy. This method encloses a character string, cuts out one character at a time from it and registers them as models. Reference: ▶ Model Automatic Registration (Model Dictionary) (p.374)

Model Registration (Model Dictionary)

Register the characters and marks as the model.

Models can be registered with any of 36 indexes, from 0 to 35, and up to 5 models can be registered for each index.

Select the character type.

By factory default, 0 to 9 and A to Z are assigned to indexes 0 to 35. These assignments can be changed as necessary with the "%" and "#" codes.

0		
1		
2		
3		
4		
5		
6		
7		
8		
9		
A	C	O
B	D	P
	E	Q
	F	R
	G	S
	H	T
	I	U
	J	V
	K	W
	L	X
	M	Y
	N	Z

2

Inspecting and Measuring

1 In the Item Tab area, click [Model].

When setting a new model, you do not have to click [Model].

2 Set the character type.

String setting	
String 0~11:	0123456789AB
String 12~23:	CDEFGHIJKLMN
String 24~35:	OPQRSTUVWXYZ:

Registering a Model

This method is for registering models one character at a time.

Note

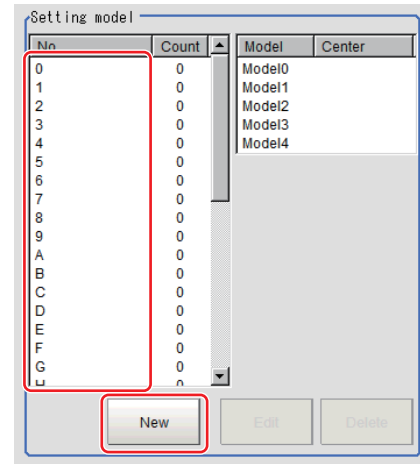
- When registering multiple characters as models, auto registration is handy.
Reference: ▶ Model Automatic Registration (Model Dictionary) (p.374)

1 In the Item Tab area, click [Model].

2 When the measurement object is rotating, set the Angle range for the "Model parameter" area.

Reference: ▶ Changing Model Parameters (p.372)

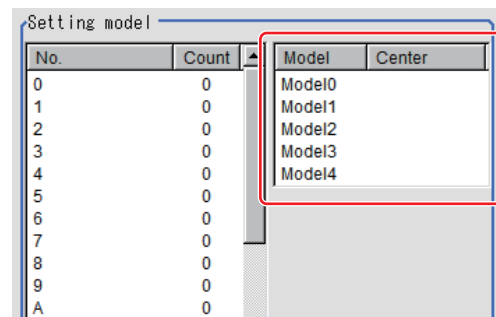
- 3** Select the index to register the model in, then click [New].



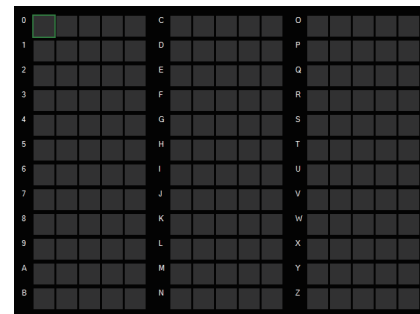
- 4** Use the Drawing tools to specify the model registration range.

- 5** Click [OK].

The model is registered and its central X and Y coordinate values are displayed in the "Setting model" area.



The image specified for the model is displayed in the Image Display area.



- 6** To register two or more models, repeat the Steps Reference: ▶ 3 (p.372) to Reference: ▶ 5 (p.372) .

Changing Model Parameters

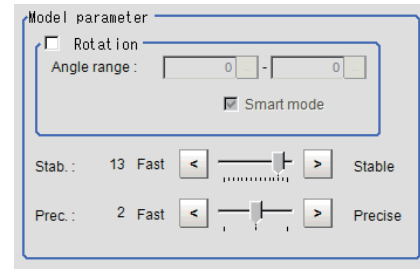
Model parameter values can be changed as needed to address unstable measurement results or to increase the processing speed. Normally, the factory default value will be used.

After changing a setting, check whether measurement can be done properly by performing an actual measurement.

Important

- After model parameters are modified, re-register all models.

1 In the "Model parameter" area, specify a value for each item.



Setting item	Set value [Factory default]	Description
Rotation	<ul style="list-style-type: none"> • Checked • [Unchecked] 	When the measurement object rotates, place a check at "Rotation" and set the Angle range during a search. The normal direction is clockwise.
Angle range	-45 to 45 [0]	
Smart mode	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Checking the "Smart mode" option enables a high-speed rotation search. The stability may be lowered when the model shape aspect ratio is large or when the NOT mask is used.
Stab.	1 to 15 [13]	Specify which is to have priority, detection stability or speed. If lowering stability does not speed up processing, it is likely that many candidates have been detected. In this case, specify a larger value for "Candidate level" or "Stab."
Prec.	1 to 3 [2]	Specify which is to have priority, measurement positional precision or speed.

Measurement Parameters (Model Dictionary)

This item can be changed if necessary. Normally, the factory default value will be used.

1 In the Item Tab area, click [Measurement].

2 In the "Measurement condition" area, specify a value for each item.

Setting item	Set value [Factory default]	Description
Batch setting	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Specify whether to set all Measurement values at the same time. <ul style="list-style-type: none"> • Checked: The same contents are set for all indexes. • Unchecked: The contents are only set for the selected index.
Correlation	0 to 100 [60]	Specify the lower limit of correlation values that are judged to be OK. This is the threshold for whether or not the candidate can be read in as a character.
Rough candidate	0 to 100 [40]	Specify the threshold value with which to detect candidate points in a rough search. Specify a smaller value when model search results are unstable.
Detail candidate	0 to 100 [60]	Specify the threshold value with which to detect candidate points in a detail search. Only the candidate points higher than this level are extracted as characters.

Model Automatic Registration (Model Dictionary)

This method encloses a character string, cuts out one character at a time from it and registers them as models. When an auto extraction region is set enclosing the character string, the characters are automatically extracted one at a time. Register each character in the appropriate character index. If 5 models have already been registered for an index, auto registration cannot be set.

1 In the Item Tab area, click [Auto registration].

2 In the Detail area, select "Auto extract region".



3 Click [Edit].



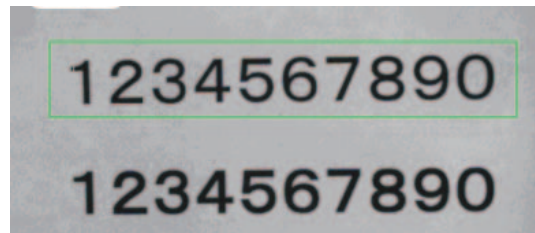
4 Specify the range to register as the auto extract region using the Drawing tools.

5 In the figure setting area, click [OK].

The auto extract region is registered.

6 Click [Extract model].

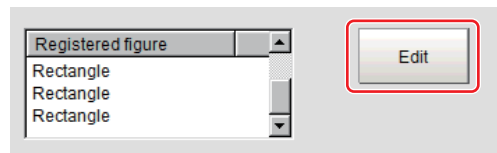
A model is extracted automatically and the extracted result (gray frame) is displayed in the Image Display area.



7 In the Detail area, select "Auto model region".

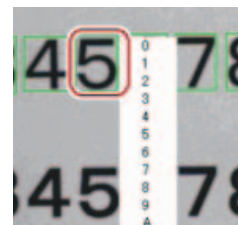


8 To adjust an extracted region, click [Edit].



9 Click the model region in the Image Display area.

An index list is displayed.



10 Select the index to register to.

11 Click [Register model].

A message which indicates the number of registered models is displayed.

12 Click [OK].

The model is registered.

With the same operation, register the models for the other extraction regions.

Key Points for Test Measurement and Adjustment (Model Dictionary)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Parameter to be adjusted	Remedy
Model	If the model image consists of detailed figures, specify a larger value for "Stab."
	When "Rotation" is selected, if the model shape is complex, uncheck the "Smart mode" option.
Measurement	If images that should be judged OK vary greatly, specify a smaller value for "Candidate level".

When the processing speed is slow

Parameter to be adjusted	Remedy
Model	If the model image is a simple figure or a large figure, specify a smaller value for "Stab." If lowering stability does not speed up processing, it is likely that many candidates have been detected. Raise the "Candidate level" in [Measurement].
	When "Rotation" is selected, if the model shape is simple, place a check at the "Smart mode" option.
Measurement	If images that should be judged OK vary little, specify a larger value for "Candidate level".

Measurement Results for Which Output Is Possible (Model Dictionary)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judgement result

External Reference Tables (Model Dictionary)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
121	With rotation	Set/Get	0: OFF 1: ON
122	Upper limit of the rotation angle	Set/Get	-45 to 45
123	Lower limit of the rotation angle	Set/Get	-45 to 45
125	Smart mode	Set/Get	0: OFF 1: ON
126	Stab.	Set/Get	1 to 15
127	Prec.	Set/Get	1 to 3

2D Code

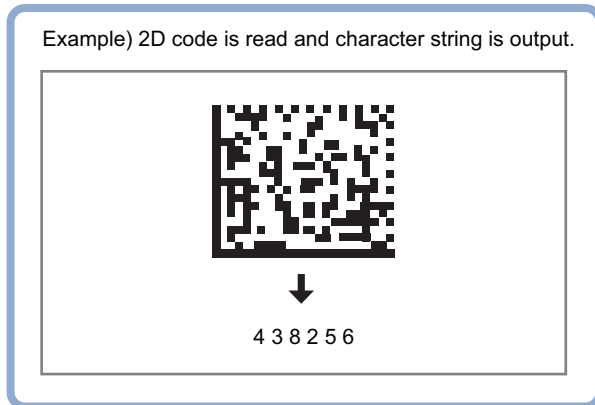
Read in 2D Code.

Processing can also classify the read-in results.

With 2D Code, detailed communication and reading result can be output.

Used in the Following Case

- To classify with 2D Code

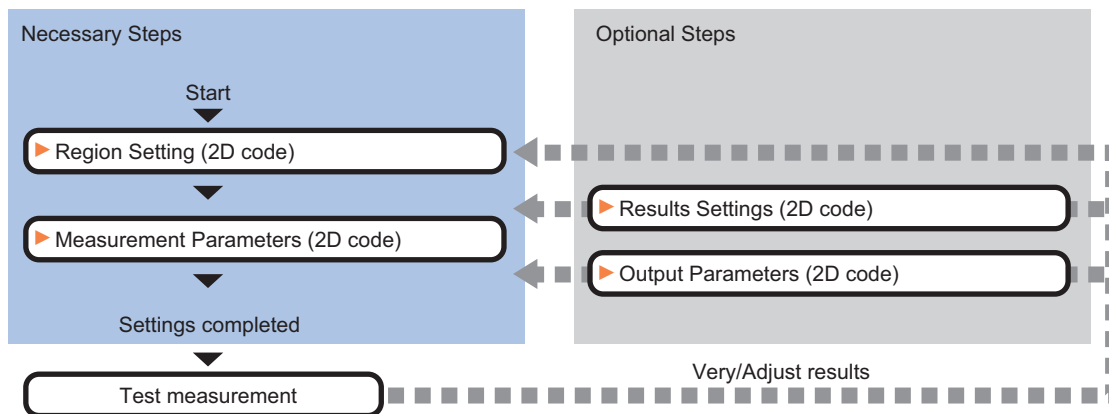


Important

- Does not support 2D Code with Japanese included. Supports 2D Code that are composed entirely of ASCII code.

Settings Flow (2D Code)

The setting procedure for 2D Code is as follows.



List of 2D Code Items

Item name	Description
Region setting	This item is used to set up the measurement area. Restricting the measurement range can shorten the processing time. Reference: ▶ Region Setting (2D Code) (p.377)
Measurement	This item specifies the judgement condition for measurement results. Set the code type and the number of characters to be judged as OK. Reference: ▶ Measurement Parameters (2D Code) (p.377)
Result setting	Set the measurement results. Judgement results can be classified. Reference: ▶ Results Settings (2D Code) (p.381)

Item name	Description
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Reference: ▶ Output Parameters (2D Code) (p.381)

Region Setting (2D Code)

Specify the rectangular area in which to search for 2D Code.

Restricting the measurement range can shorten the processing time.

- 1 In the Item Tab area, click [Region setting].**
- 2 Click [Edit].**
The figure setting area is displayed.
- 3 Specify the area in which to search for 2D Code.**
The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.
- 4 Click [OK].**
The range to measure is registered.

Important

- Set the region such that the number of pixels of the measurement region is 5003712 pixels or less.
- Set the measurement region such that it contains only 1 2D Code.
If there is more than one 2D Code in the measurement region, measurement may not be performed correctly.

Measurement Parameters (2D Code)

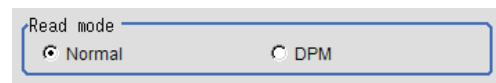
This item specifies the judgement conditions for measurement conditions and measurement results.

When the [Teaching] button is pressed, detailed settings are set automatically.

If you then click the [Measurement] button, measurement is executed, the detected 2D Code region is displayed on the image and the measurement results are displayed as measurement value of the judgement condition.

If measurement cannot be carried out successfully with this procedure, adjust the parameters shown below.

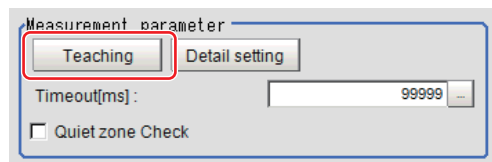
- 1 In the Item Tab area, click [Measurement].**
- 2 Select the read mode.**



Setting item	Set value [Factory default]	Description
Read mode	<ul style="list-style-type: none"> • [Normal] • DPM 	Usually, set this to "Normal". Select DPM to read 2D code to which direct parts marking (DPM) was applied.

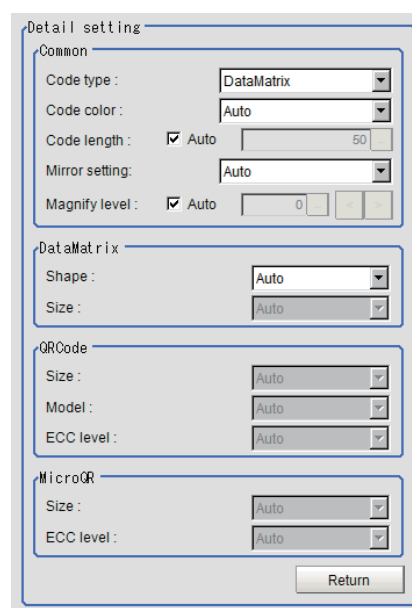
3 To teach, click [Teaching].

The detailed settings are set automatically.



Setting item	Set value [Factory default]	Description
Timeout	50 to 99999 [99999]	Stop and terminate the process if the measurement for this processing item cannot be completed within the specified time period. Note that the actual timeout time may be longer than the specified time period.
Quiet zone Check (only when the read mode is Normal)	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Check if there is any space around 2D code.

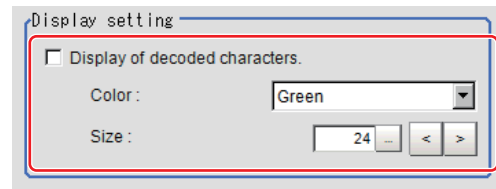
4 When making the detailed settings, click "Detail setting" and set each item.



Setting item	Set value [Factory default]	Description
Common		
Code type	<ul style="list-style-type: none"> • [Auto] • DataMatrix • QRCode • MicroQR • PDF417 • MicroPDF 	Set the code type. The symbol sizes that can be read in are as follows. DataMatrix: Symbol size 64 × 64 max. QRCode: Symbol size 57 × 57 max. (Version 10)
Code color	<ul style="list-style-type: none"> • [Auto] • Black • White 	Specify the color of the 2D Code to read. Auto: Select to automatically determine the color setting. Black: Select this for black 2D Code with white background. White: Select this for white 2D Code with black background.
Code length: Auto	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Place a check when automatically determining the code length.
Code length	50 to 2448 [50]	Specify the code length.
Mirror setting	<ul style="list-style-type: none"> • [Auto] • Normal • Reverse 	Specify whether to reverse the image horizontally.

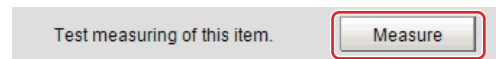
Setting item		Set value [Factory default]	Description
	Magnify level: Auto	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Select whether to automatically set the reduction ratio of images when reading code.
	Magnify level	<ul style="list-style-type: none"> • 0 to 4 • [0] 	Set the reduction ratio for images when reading code. It is determined by the teaching process.
DataMatrix			Specify when DataMatrix is selected for Code type.
	Shape	<ul style="list-style-type: none"> • [Auto] • Square • Rectangle 	Set the shape of DataMatrix.
	Size	For DM square <ul style="list-style-type: none"> • [Auto] • 10 × 10 • 12 × 12 • : • 64 × 64 For DM rectangle: <ul style="list-style-type: none"> • [Auto] • 8 × 18 • 8 × 32 • : • 16 × 48 	Set the size of DataMatrix.
QRCode			Specify when QRCode is selected for Code type.
	Size	<ul style="list-style-type: none"> • [Auto] • 21 × 21 • 25 × 25 • : • 57 × 57 	Set the size of QR code.
	Model	<ul style="list-style-type: none"> • [Auto] • Model 1 • Model 2 	Set the model of QR code.
	ECC level	<ul style="list-style-type: none"> • [Auto] • M • L • H • Q 	Specify the ECC level (error correction level) for QR code.
MicroQR			Specify when MicroQR is selected for Code type.
	Size	<ul style="list-style-type: none"> • [Auto] • 11 × 11 • 13 × 13 • 15 × 15 • 17 × 17 	Select the size of MicroQR.
	ECC level	<ul style="list-style-type: none"> • [Auto] • L • M • Q 	Select the ECC level (error correction level) for MicroQR.

5 Make the display settings for read-in character strings.

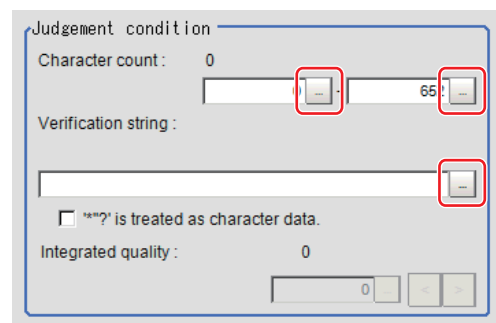


Setting item	Set value [Factory default]	Description
Display of decoded characters.	<ul style="list-style-type: none"> • [Unchecked] • Checked 	Place a check when displaying the read-in character strings on the screen.
Color	<ul style="list-style-type: none"> • Black • White • Red • [Green] • Blue 	Specify the color of characters displayed on the screen.
Size	10 to 200 [24]	Set the display size for character strings.

6 When the setting has been changed, click [Measure] in the "Detail" area to verify whether measurements can be made correctly.



7 Set up the judgement condition.



Setting item	Set value	Description
Character count	0 to 652	Specify the character count to be judged as OK.
Verification string	-	Specify the classification strings to be judged as OK. Up to 32 characters can be set.
'*' '?' is treated as character data.	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Checked: '*' and '?' are handled as normal characters. Unchecked: '*' and '?' are handled as special characters. *': Substitution for character string (with 0 or more characters) ?': Substitution for 1 character
Integrated quality (lower limit value) (only when the read mode is Normal)	0 to 4 [0]	Specify the integrated quality to be judged as OK. It can be set when the code type is DataMatrix, PDF417 or MicroPDF.

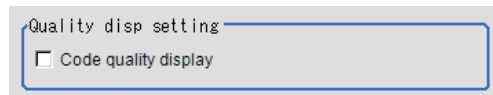
Results Settings (2D Code)

Results can be classified according to the judgement results.

- 1 In the Item Tab area, click [Result setting].
- 2 Register the character string that will be the reference for classification.

Setting item	Set value	Description
Classification string	-	Set the Comparison character string. Up to 32 characters can be set.
'*' '?' is treated as character data.	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Checked: '*' and '?' are handled as normal characters. Unchecked: '*' and '?' are handled as special characters. '*': Substitution for character string (with 0 or more characters) '?': Substitution for 1 character

- 3 If necessary, set the quality display for the "Detail result" display area.



Setting item	Set value	Description
Code quality display	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Select whether or not to display the integrated quality.

Output Parameters (2D Code)

Select how measurement results are output to an external device. This item can be changed if necessary. Normally, the factory default value will be used.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.
Character output	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Set whether to output character strings.
Communication output	<ul style="list-style-type: none"> • [RS-232C/RS-422] • Ethernet 	Set the output destination.
Header	<ul style="list-style-type: none"> • [None] • STX • ESC 	Set the header of communication output.
Footer	<ul style="list-style-type: none"> • [CR] • CR+LF • ETX • LF 	Set the footer of communication output.
FCS	<ul style="list-style-type: none"> • Available • [None] 	Set whether to output FCS (frame check sequence). FCS performs an XOR of each byte from the beginning to the end of data and converts the result (8 bits) into two ASCII format characters. The reliability of communication can be increased by adding FCS to the output data.
Reading character output		

Setting item		Set value [Factory default]	Description
	Reading character output	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Set whether to output character strings.
	Output range specify	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Set when specifying the range of character strings to be output. This can be set to a range of 1 to 652.
	Output range specify	1 to 652 [1] to [652]	Specify the range of output character count. This can be set to a range of 1 to 652.
	Character count output	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Specify whether to output the character count of the character string.
	Character code size	<ul style="list-style-type: none"> • [2bytes] • 4bytes 	Select the character code size for character output.
	Code quality output	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Set whether to output the 2D Code quality.
Output when reading error occurs			
	Error character output	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Specify whether to output the specified character string when there is a reading error. If a check is placed, the character string entered in the lower frame is output. Up to 20 characters can be input.
	Error code output	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Set whether to output error codes. Error codes are as follows: ?E000: The 2D code cannot be found. ?E200: Timeout ?E300: There are too many 2D Code to be recognized.

Character Output

Characters are output in the ASCII format as follows:

- **When read successfully**

Header + character count + code quality + reading characters + FCS + footer + delimiters

- **When not read successfully**

Header + error code + error characters + FCS + footer + delimiters

Item	Description
Header	What is specified for the Header is output. (None may be specified.) None is output for PLC link.
Character count	This is output only when "Character count output" is specified. Only the reading characters are counted as part of the character count, and if "Output range specify" is specified, the character count of only that range is output. For example, if no character is present in the output range, such as when the read character count is 1 and the output range is 2 to 3, 0 will be output. If "Reading character output" is not specified, 0 will be output. If kanji characters are included in the reading characters, one kanji character is counted as 1. (This is different from byte count.) The output can be switched between 2 bytes and 4 bytes. 0 is added to the left digit if the character count is less than the byte count (Example: 0010 for 10). "--" is output if the character count in 2-byte output reaches 100 or more.
Code quality	This is output only when the "Code quality output" is specified. The output format is "CxxxFxxxExxx". C represents the contrast, while F and E represent the focus and the cell recognition rate, respectively. xxx represents each value (0 to 100), and 0 is added to the left digit if the value is less than 3 digits (Example: 005 for 5).

Item	Description
Reading character	This is output only if "Reading character output" is specified. If "Output range specify" is specified, only the characters of that range are output. For example, if no character is present in the output range, such as when the read character count is 1 and the output range is 2 to 3, no character will be output.
Error code	This is output only when "Error code output" is specified.
Error character	This is output only when "Error character output" is specified.
FCS	This is output only when "FCS" is set to "Available". The value obtained through an XOR in unit of bytes is output. The applicable range includes the character count, code quality, reading characters, error codes and error characters. 0 will be output if nothing that can be output is present in the applicable range. None is output for PLC link.
Footer	What is specified for the Footer is output. None is output for PLC link.
Delimiter	The delimiters specified in the system data are added only for serial communication non-procedure output.

Key Points for Test Measurement and Adjustment (2D Code)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Index	Index matched as the result of comparison with the classification comparison character strings
Detected character count	Number of characters detected
Detected character strings	Character strings detected
Cell recognition rate [Note 1]	A value used to check the error correction rate. The fewer the words whose errors corrected, the better the recognition rate.
Contrast [Note 1]	Evaluate the sharpness of an image. If an image is defocused, code cannot be identified. The displayed value will be smaller as it becomes defocused.
Focus [Note 1]	Evaluate the number of false cell detections in the finder pattern, timing pattern and data region. The displayed value is smaller when there are many false cell detections and reading is unstable.
Integrated quality [Note 2]	Integrated quality [Note 2]
Decode [Note 2]	Decode [Note 2]
Contrast [Note 2]	Contrast [Note 2]
Modulation [Note 2]	Modulation [Note 2]
Fixed pattern damage [Note 2]	Fixed pattern damage [Note 2]
Axis non-uniformity [Note 2]	Axis non-uniformity [Note 2]
Error correction during unused time [Note 2]	Error correction during unused time [Note 2]
Print expansion/contraction [Note 2]	Print expansion/contraction [Note 2]
Print expansion/contraction X [Note 2]	Print expansion/contraction X [Note 2]
Print expansion/contraction Y [Note 2]	Print expansion/contraction Y [Note 2]
Scan [Note 2]	Scan [Note 2]

Displayed items	Description
Integrated quality [Note 3]	Integrated quality [Note 3]
Decode [Note 3]	Decode [Note 3]
RAP symbol contrast [Note 3]	RAP symbol contrast [Note 3]
RAP minimum reflection rate [Note 3]	RAP minimum reflection rate [Note 3]
RAP minimum edge contrast [Note 3]	RAP minimum edge contrast [Note 3]
RAP modulation [Note 3]	RAP modulation [Note 3]
RAP defection [Note 3]	RAP defection [Note 3]
Degree of easiness of RAP decoding [Note 3]	Degree of easiness of RAP decoding [Note 3]
RAP addition index [Note 3]	RAP addition index [Note 3]
RAP integrated quality [Note 3]	RAP integrated quality [Note 3]
Effective codeword ratio [Note 3]	Effective codeword ratio [Note 3]
Unused error correction [Note 3]	Unused error correction [Note 3]
Degree of easiness of decoding [Note 3]	Degree of easiness of decoding [Note 3]
Defection [Note 3]	Defection [Note 3]
Modulation [Note 3]	Modulation [Note 3]

The display items checked in the result settings tab Grade display setting are displayed.

The grade code is displayed with a letter with numeric expression in parentheses, such as "A (4) to F (0)".

[Note 1] Read mode: Only displayed in DPM mode.

[Note 2] Read mode: Displayed if it is standard, the code type is DM and "Display code quality" is selected.

[Note 3] Read mode: Displayed if it is standard, the code type is PDF/MicroPDF and "Display code quality" is selected.

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

When codes cannot be read in correctly

Parameter to be adjusted	Remedy
Region setting	Check whether there are codes to read in the measurement region.
Measurement parameter	Check if the settings, such as "Code type", "Code color", "Code length", and "Mirror setting", are specified correctly.
Timeout	Check to make sure that the specified time is not too short.

* Codes may not be recognized if the code size is set too small or too large.

Measurement Results for Which Output Is Possible (2D Code)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement result	JG	Judgement result
Decoded character count	DN	Character count
Index	IDX	Index matched as the result of comparison with the classification comparison character strings
Cell recognition rate	CRR	The rate is calculated based on the "the number of error code word to be correctable", which is determined by the size and the error correction level, and the number of error code words that are actually corrected. (1 - (number of error code words corrected) / (number of error code words that can be corrected)) × 100
Contrast	CT	Contrast
Focus	FCS	Focus
Integrated quality	GD0	Integrated quality
Decode	GD1	Decode
Contrast	GD2	Contrast
Modulation	GD3	Modulation
Fixed pattern damage	GD4	Fixed pattern damage
Axis non-uniformity	GD5	Axis non-uniformity
Grid non-uniformity	GD6	Grid non-uniformity
Correction of error not used	GD7	Correction of error not used
Print expansion/contraction	GD8	Print expansion/contraction
Print expansion/contraction X	GD9	Print expansion/contraction X
Print expansion/contraction Y	GD10	Print expansion/contraction Y
Integrated quality	GP0	Integrated quality
Decode	GP1	Decode
RAP symbol contrast	GP2	RAP symbol contrast
RAP minimum reflection rate	GP3	RAP minimum reflection rate
RAP minimum edge contrast	GP4	RAP minimum edge contrast
RAP modulation	GP5	RAP modulation
RAP defection	GP6	RAP defection
Degree of easiness of RAP decoding	GP7	Degree of easiness of RAP decoding
RAP addition index	GP8	RAP addition index
RAP integrated quality	GP9	RAP integrated quality
Effective codeword ratio	GP10	Effective codeword ratio

Measurement items	Character string	Description
Correction of error not used	GP11	Correction of error not used
Degree of easiness of decoding	GP12	Degree of easiness of decoding
Defection	GP13	Defection
Modulation	GP14	Modulation

About Output at PLC Link

1 About output by 2D Code

In a PLC link communication, if a check is placed for "Reading character output", "Character count output" and "Code quality output" in the output parameter settings, the content of the items checked are output in the output area of the PLC link.

If 32 characters are read in ASCII format (read character string: 0123456789...UV) with "Reading character output" specified, and "Character count output" and "Code quality output" both not specified, a continuous ASCII format data string is output as shown below.

Output area

Top channel	Name	Output contents
+0ch	1st character, 2nd character	3031 (ASCII code corresponding to character "0," ASCII code corresponding to character "1")
+1ch	3rd character, 4th character	3233 (ASCII code corresponding to character "2," ASCII code corresponding to character "3")
• • •		
+15ch	31st character, 32nd character	5556 (ASCII code corresponding to character "U," ASCII code corresponding to character "V")

Shift-JIS and other 2-byte characters can be output by a total of 16 characters, with 1 character output to each channel.

2 How to receive character string data

As you do when serial data is output via PLC link, control the DSAdata output request bit and GATE data completion request bit.

Since the entire character string comprises 1 data, DSA control is performed once if there is only one 2D Code unit.

External Reference Tables (2D Code)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
6	Decoded character count	Get only	Number of characters included in code detected
7	Decoded character string	Get only	Character string included in code detected
8	Index	Get only	0 to 35 -1: Where there was no match with any of the index comparison strings, or the index comparison string has not been set up.
9	Error code	Get only	0: Completed successfully -1: The 2D code cannot be found. -3: Timeout -7: Process could not be completed with too large a volume of data.
18	Cell recognition rate	Get only	The rate is calculated based on the "the number of error code word to be correctable", which is determined by the size and the error correction level, and the number of error code words that are actually corrected. $(1 - (\text{number of error code words corrected}) / (\text{number of error code words that can be corrected})) \times 100$
19	Contrast	Get only	0 to 100
20	Focus	Get only	0 to 100
21	Overall quality	Get only	0 to 4
22	Decode	Get only	0 to 4
23	Contrast	Get only	0 to 4
24	Modulation	Get only	0 to 4
25	Fixed pattern damage	Get only	0 to 4
26	Axial nonuniformity	Get only	0 to 4
27	Grid nonuniformity	Get only	0 to 4
28	Unused error correction	Get only	0 to 4
29	Print Scale	Get only	0 to 4
30	Print Scale X	Get only	0 to 4
31	Print Scale Y	Get only	0 to 4
33	Overall quality	Get only	0 to 4
34	Decode	Get only	0 to 4
35	RAP contrast	Get only	0 to 4
36	RAP reflectance	Get only	0 to 4
37	RAP edge contrast	Get only	0 to 4
38	RAP modulation	Get only	0 to 4
39	RAP defect	Get only	0 to 4
40	RAP decodability	Get only	0 to 4
41	RAP additional	Get only	0 to 4
42	RAP overall quality	Get only	0 to 4
43	Code word yield	Get only	0 to 4

No.	Data name	Set/Get	Data range
44	Unused error correction	Get only	0 to 4
45	Decodability	Get only	0 to 4
46	Defect	Get only	0 to 4
47	Modulation	Get only	0 to 4
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Code type	Set/Get	Normal 0: DataMatrix 1: QRCode 2: MicroQR 3: PDF417 4: MicroPDF DPM 0: Auto 1: DataMatrix 2: QRCode
121	Code color	Set/Get	0: Automatic 1: Black 2: White
122	Symbol size (for DM square)	Set/Get	0: Automatic 1: 10 × 10 2: 12 × 12 ••• 16: 64 × 64
123	Symbol size (for DM rectangle)	Set/Get	0: Automatic 1: 8 × 18 2: 8 × 32 ••• 6: 16 × 48
124	Symbol size (for QR)	Set/Get	0: Automatic 1: 21 × 21 2: 25 × 25 ••• 10: 57 × 57
125	DM code shape	Set/Get	0: Automatic 1: DM square 2: DM rectangle
126	QR code shape	Set/Get	0: Automatic 1: Square
127	Code length	Set/Get	Number of pixels for the size of the code (Longer side for a rectangle)
128	Mirror setting	Set/Get	0: Automatic 1: Normal 2: Reverse
129	QR code model	Set/Get	0: Automatic 1: Model 1 2: Model 2
130	QR code ECC level	Set/Get	0: Automatic 1: M 2: L 3: H 4: Q

No.	Data name	Set/Get	Data range
131	Timeout	Set/Get	50 to 99999 ms
133	Character output flag	Set/Get	0: Not output 1 : Output
134	Output range specify	Set/Get	0: Not set 1: Set
135	Output ending digit	Set/Get	1 to 652
136	Output starting digit	Set/Get	1 to 652
137	Output device	Set/Get	0: RS-232C/422 1: Ethernet
138	Error character output flag	Set/Get	0: Not output 1: Output
139	Message output while outputting an error	Set/Get	Output character string when error occurred
140	Automatic code length setting	Set/Get	1: Automatic 0: The specified code length is applied.
141	Error code output flag	Set/Get	0: Not output 1: Output
142	Magnify level	Set/Get	0 to 4
143	Magnify level auto	Set/Get	0: Use the Magnify level specified value. 1: Auto
144	Quiet zone	Set/Get	0: OFF 1: ON
145	Integrated quality	Set/Get	0 to 4
146	Read mode	Set/Get	0: Normal 1: DPM
147	MicroQR size	Set/Get	0: Auto 1: 11 × 11 2: 13 × 13 3: 15 × 15 4: 17 × 17
148	ECC level	Set/Get	0: Auto 1: L 2: M 3: Q
170	Upper limit of number of characters detected	Set/Get	0 to 652
171	Lower limit of number of characters detected	Set/Get	0 to 652
172	Judgement comparison character string	Set/Get	Comparison string used for judgement
173	Flag used for special character judgement	Set/Get	0: "*" and "?" are considered to be wild cards. 1: "*" and "?" are considered to be character strings.
174	Flag used for special character classification	Set/Get	0: "*" and "?" are considered to be wild cards. 1: "*" and "?" are considered to be character strings.
175	Flag showing character string display results	Set/Get	0 : Not displayed 1 : Displayed

No.	Data name	Set/Get	Data range
176	Character string display color	Set/Get	0: Black 1 : White 2: Red 3: Green 4: Blue
177	Character string display size	Set/Get	10 to 200
178	Communication header	Set/Get	0: OFF 1: STX 2: ESC
179	Communication footer	Set/Get	0: CR 1: CR + LF 2: ETX 3: LF
180	FCS flag	Set/Get	0: OFF 1: ON
181	Character count output flag	Set/Get	0: OFF 1: 2 bytes 2: 4 bytes
182	Code quality output flag	Set/Get	0: OFF 1: ON
183	Code quality display flag	Set/Get	0: OFF 1: ON
184	Character external output flag	Set/Get	0: OFF 1: ON
300 to 335	Classification comparison character string	Set/Get	Comparison character string used for classification

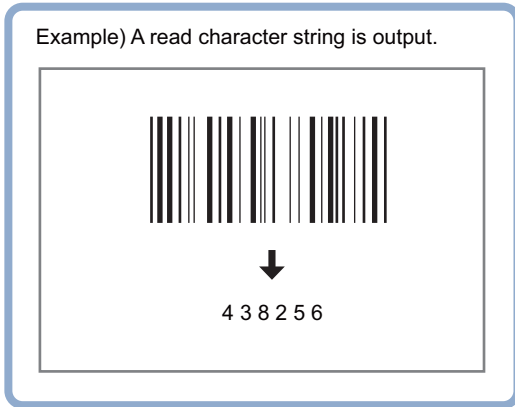
Barcode

Read in barcodes.

Processing can also classify the read-in results.

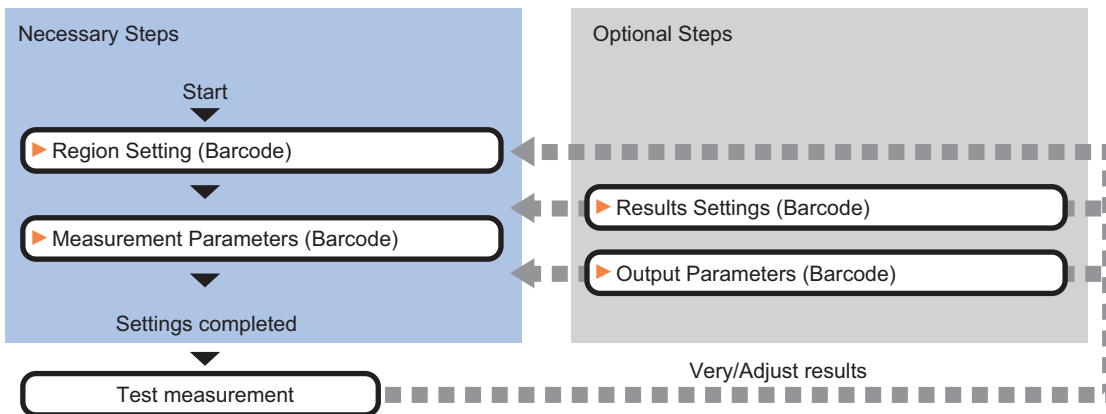
Used in the Following Case

- To read in barcodes and output them to an external device



Settings Flow (Barcode)

Barcode can be set up as follows.



List of Barcode Items

Item name	Description
Region setting	This item is used to set up the measurement area. Restricting the measurement area can shorten the processing time. Reference: ▶ Region Setting (Barcode) (p.392)
Measurement	This item specifies the judgement condition for measurement results. Set the code type and the number of characters to be judged as OK. Reference: ▶ Measurement Parameters (Barcodes) (p.392)
Result setting	Set the measurement results. Judgement results can be classified. Reference: ▶ Results Settings (Barcode) (p.395)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Reference: ▶ Output Parameters (Barcode) (p.395)

Region Setting (Barcode)

Specify the rectangular area in which to search for the barcodes.
Restricting the measurement area can shorten the processing time.

- 1** In the Item Tab area, click [Region setting].
- 2** Click [Edit].
The figure setting area is displayed.
- 3** Specify the area in which to search for the barcodes.
The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.
- 4** Click [OK].
The range to measure is registered.

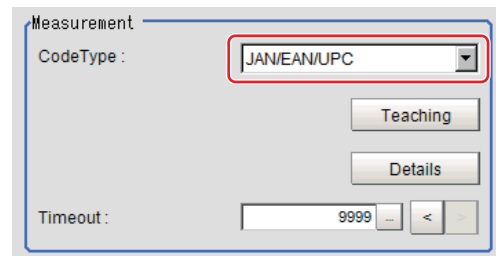
Important

- Set the region such that the number of pixels in the measurement region is 5003712 pixels or less.
- Set the measurement region such that it contains only 1 barcode.
If there is more than one bar code in the measurement region, measurement may not be performed correctly.
- Set the measurement region such that it includes a quiet zone.

Measurement Parameters (Barcodes)

This item sets the judgement conditions for measurement conditions and measurement results.
When the Teaching button is pressed, the code type and advanced settings are set automatically.
If you then click the Measure button, measurement is executed, the detected barcode region is displayed on the image and the measurement results are displayed as measurement value of the judgement condition.
If measurement cannot be carried out successfully with this procedure, adjust the parameters shown below.

- 1** In the Item Tab area, click [Measurement].
- 2** In the "Measurement" area, set the Code Type.



Setting item	Set value [Factory default]	Description
Code Type	<ul style="list-style-type: none"> • [JAN/EAN/UPC] • Code39 • Codabar • ITF • Code93 • Code 128/GS1-128 • GS1 DataBar • Pharmacode 	Select the code type for the code to read.

Note

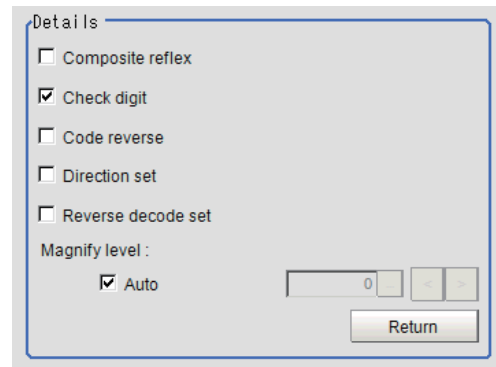
- The designations of the following code types are standardized to those conforming to GS1Databar from 2010. With FH/FZ5, current designation "GS1Databar" and old designation "RSS" are both indicated. Select each code type of a new designation conforming to GS1Databar.
GS1 Databar code type new/old comparison table

Code type name	Official name
GS1 DataBar (RSS-14)	GS1 DataBar Omni-directional
GS1 DataBar (RSS Lim.)	GS1 DataBar Limited
GS1 DataBar (RSS Exp.)	GS1 DataBar Expanded

3 To teach, click [Teaching].

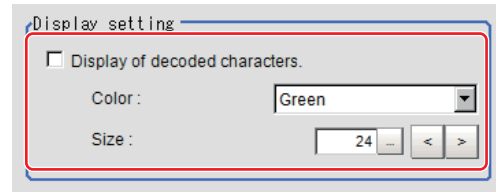
The code type and detailed settings are set automatically.

4 When making the detailed settings, click "Details" and set each item.



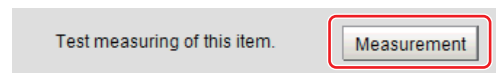
Setting item	Set value [Factory default]	Description
Composite reflex	<ul style="list-style-type: none"> Checked [Unchecked] 	Select whether or not to read composite code.
Check digit	<ul style="list-style-type: none"> [Checked] Unchecked 	Select whether or not to perform check using the check digit. When check is performed, the check digit is not included in the read character string.
Code reverse	<ul style="list-style-type: none"> Checked [Unchecked] 	Select whether or not to read reversed black/white code.
Direction set	<ul style="list-style-type: none"> Checked [Unchecked] 	Select the direction in which to read barcodes. Reading is performed horizontally when there is no check. Reading is performed vertically when there is a check. This item is selectable when the code type is "Pharmacode."
Reverse decode set	<ul style="list-style-type: none"> Checked [Unchecked] 	Select whether or not to use reverse mode. This item is selectable when the code type is "Pharmacode."
Auto magnify level	<ul style="list-style-type: none"> [Checked] Unchecked 	Select whether or not to set the image magnify level automatically when reading code. Stable reading is enabled if there is a check, but the processing time will increase.
Magnify level	0 to 4 [4]	Set the image magnify level to be applied when reading code. If reading the code is difficult for a high-resolution Camera or image, increase the value. The value is updated when teaching is performed.

5 When changing the display settings, set each item in the "Display setting" area.

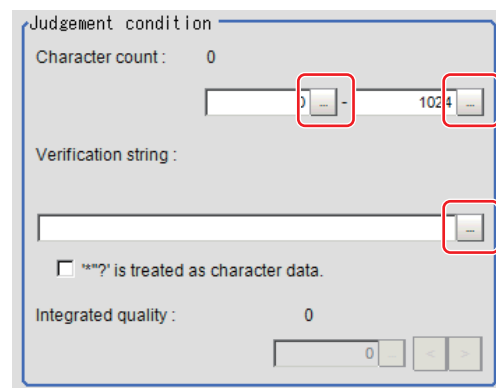


Setting item	Set value [Factory default]	Description
Color	<ul style="list-style-type: none"> • Black • White • Red • [Green] • Blue 	Select the display color for character strings.
Size	10 to 200 [24]	Set the display size for character strings.

6 When the setting has been changed, click [Measurement] in the "Detail" area to verify whether measurements can be made correctly.



7 Set up the judgement condition.



Setting item	Set value	Description
Character count	0 to 1024 [1024]	Specify the character count to be judged as OK.
Verification string	Up to 32 characters can be set.	Specify the character strings to be judged as OK.
? is treated as character data.	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Checked: '' and '?' are handled as normal characters. Unchecked: '*' and '?' are handled as special characters. '*?': Substitution for character string (with 0 or more characters) '?': Substitution for 1 character
Integrated quality	0 to 4 [4]	Specify the integrated quality to be judged as OK.

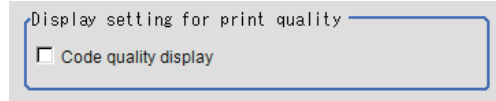
Results Settings (Barcode)

Results can be classified according to the judgement results.

- 1 In the Item Tab area, click [Result setting].
- 2 Register the character string that will be the reference for classification.

Setting item	Set value	Description
Classification string	-	Set the Verification string. Up to 32 characters can be set.
'*' '?' is treated as character data.	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Checked: '*' and '?' are handled as normal characters. Unchecked: '*' and '?' are handled as special characters. '*': Substitution for character string (with 0 or more characters) '?': Substitution for 1 character

- 3 If necessary, set the quality display for the "Detail result" display area.



Setting item	Set value	Description
Code quality display	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Select whether or not to display integrated quality.

Output Parameters (Barcode)

Select how measurement results are output to an external device. This item can be changed if necessary. Normally, the factory default value will be used.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.
Character output	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Set whether to output character strings.
Error output	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Set whether to output errors.
Error output character string	-	Input the character string output when there is an error. Up to 20 characters can be input.
Output device	<ul style="list-style-type: none"> • [RS-232C/RS-422] • Ethernet 	Set the output destination.

Key Points for Test Measurement and Adjustment (Barcode)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Index	Index matched as the result of comparison with the classification comparison character strings
Character count	Number of characters detected
Read string	Character strings detected Up to 40 characters are displayed (with a new line after every 15th character). From the 41st character on is displayed as "...". Example) Detected character strings <ul style="list-style-type: none"> • 123456789012345 • 123456789012345 • 1234567890... (□ indicates a double-byte space.)
Overall quality [Note 1]	Result of overall quality

[Note 1]: This is displayed only when "Code quality display" check box is selected in the result setting (Barcode).

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

After teaching has been executed, the read-in character contents are different.

Parameter to be adjusted	Remedy
Measurement	The code type may have been detected incorrectly. <ul style="list-style-type: none"> • Select the code type manually, then measure again. • Set the Narrow bar size and Wide bar size in the Advanced setting to match the displayed barcode image, then execute teaching again. • If the bars are too narrow or there is not much difference in density between the background and the image, correct the image with filtering and execute teaching.

Measurement Results for Which Output Is Possible (Barcode)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judgement result
Number of decoded character	DN	Number of characters detected
Index	IDX	Index matched as the result of comparison with the classification comparison character strings
Integrated quality	GT	Integrated quality
Integrated quality	GB0	Integrated quality 1D
Decode	GB1	Decode 1D
Symbol contrast	GB2	Symbol contrast 1D
Minimum reflection ratio	GB3	Minimum reflection ratio 1D
Minimum edge contrast	GB4	Minimum edge contrast 1D
Modulation	GB5	Modulation 1D

Measurement items	Character string	Description
Defect	GB6	Defect 1D
Decodability	GB7	Decodability 1D
Additional	GB8	Additional 1D
Integrated quality	GP0	Integrated quality 2D
Decode	GP1	Decode 2D
RAP symbol contrast	GP2	RAP symbol contrast
RAP minimum reflection ratio	GP3	RAP minimum reflection ratio
RAP minimum edge contrast	GP4	RAP minimum edge contrast
RAP modulation	GP5	RAP modulation
RAP defect	GP6	RAP defect
RAP decodability	GP7	RAP decodability
RAP additional	GP8	RAP additional
RAP overall quality	GP9	RAP overall quality
Code word yield	GP10	Code word yield
Unused error correction	GP11	Unused error correction
Decodability	GP12	Decodability 2D
Defect	GP13	Defect 2D
Additional	GP14	Modulation 2D

About Output at PLC Link

1 About output by barcodes

If PLC link communication is performed, selecting the "Character output" check box among the Output parameter will cause character string data to be output to the PLC link output area. (FZ3 Ver. 2.10 or later)
If 32 characters are read (read character string: 0123456789...UV), a continuous ASCII code data string is output as shown below.

Output area

Top channel	Name	Output contents
+0ch	1st character, 2nd character	3031 (ASCII code corresponding to character "0," ASCII code corresponding to character "1")
+1ch	3rd character, 4th character	3233 (ASCII code corresponding to character "2," ASCII code corresponding to character "3")
• • •		
+15ch	31st character, 32nd character	5556 (ASCII code corresponding to character "U," ASCII code corresponding to character "V")

2 How to receive character string data

As you do when serial data is output via PLC link, control the DSAdata output request bit and GATE data completion request bit.

Since the entire character string comprises 1 data, DSA control is performed once if there is only 1 barcode unit.

External Reference Tables (Barcode)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
6	Decoded character count	Get only	Number of characters detected
7	Decoded character string	Get only	Character strings detected
8	Index	Get only	0 to 127: Index matched as the result of comparison with the classification comparison character strings -1: Where there was no match with any of the index comparison strings, or the index comparison string has not been set up.
9	Integrated quality	Get only	0 to 4
10	Integrated 1D	Get only	0 to 4
11	Decode 1D	Get only	0 to 4
12	Symbol contrast 1D	Get only	0 to 4
13	Minimum reflection ratio 1D	Get only	0 to 4
14	Minimum edge contrast 1D	Get only	0 to 4
15	Modulation 1D	Get only	0 to 4
16	Defect 1D	Get only	0 to 4
17	Decodability 1D	Get only	0 to 4
18	Additional 1D	Get only	0 to 4
19	Integrated 2D	Get only	0 to 4
20	Decode 2D	Get only	0 to 4
21	RAP symbol contrast	Get only	0 to 4
22	RAP minimum reflection ratio	Get only	0 to 4
23	RAP minimum edge contrast	Get only	0 to 4
24	RAP modulation	Get only	0 to 4
25	RAP defect	Get only	0 to 4
26	RAP decodability	Get only	0 to 4
27	RAP additional	Get only	0 to 4
28	RAP overall quality	Get only	0 to 4
29	Code word yield	Get only	0 to 4
30	Unused error correction	Get only	0 to 4
31	Decodability 1D	Get only	0 to 4
32	Defect 1D	Get only	0 to 4
33	Modulation 1D	Get only	0 to 4
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF

No.	Data name	Set/Get	Data range
120	Code type	Set/Get	0: JAN/EAN/UPC 1: Code39 2: Codabar 3: ITF 4: Code93 5: Code128/GS1-128 6: GS1 DataBar 7: Pharmacode
121	Flag used for special character judgement	Set/Get	0: "*" are considered to be wild cards 1: "*" are considered to be character strings
122	Flag used for special character classification	Set/Get	0: "*" are considered to be wild cards 1: "*" are considered to be character strings
123	Flag showing character string display results	Set/Get	Flag regarding whether or not character string is displayed
124	Character string display color	Set/Get	0: Black 1 : White 2: Red 3: Green 4: Blue
125	Character string display size	Set/Get	10 to 100
136	Check digit	Set/Get	0: Check digit is not used 1: Check digit is used
137	Number of characters detected setting	Set/Get	1 to 1024
162	Upper limit of number of characters detected	Set/Get	0 to 1024
163	Lower limit of number of characters detected	Set/Get	0 to 1024
164	Judgement comparison character string	Set/Get	Comparison string used for judgement
170	Code color	Set/Get	0: Black 1: White
171	Composite code read flag	Set/Get	0: OFF 1: ON
172	Timeout	Set/Get	0 to 9999
173	Direction set (Pharmacode only)	Set/Get	0: Horizontal direction 1: Vertical direction
174	Reverse decode set (Pharmacode only)	Set/Get	0: OFF 1: ON
175	Lower limit for overall grade	Set/Get	0 to 4
190	Overall quality set	Set/Get	0: Not displayed 1: Displayed
200	Auto	Set/Get	0: OFF 1: ON
201	Magnify level	Set/Get	0 to 4
300 to 335	Classification comparison character string	Set/Get	Verification string used for classification
400	Character output flag	Set/Get	0: Not output 1: Output

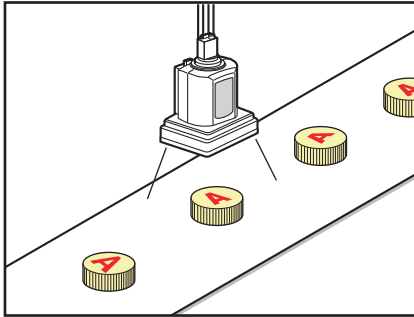
No.	Data name	Set/Get	Data range
401	Output device	Set/Get	0: RS-232C 1: Ethernet
402	Error output	Set/Get	Error output flag
403	Error message	Set/Get	Message output while outputting an error

Circle Angle

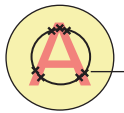
Used in the Following Case

- To correct the tilting of circle measurement objects

Example) Appearance measurement while correcting the nut rotation



Draw a circle to encircle the part that has the basic features of the image in order to define the registering conditions for featured points/measured points.



Based on the conditions defined on the sensor controller, inspect the featured points on the circumference with the pixel unit, which will be registered as the reference position.

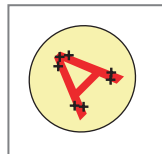
x x

x x (Featured points for the reference position)

Reference image



Input image

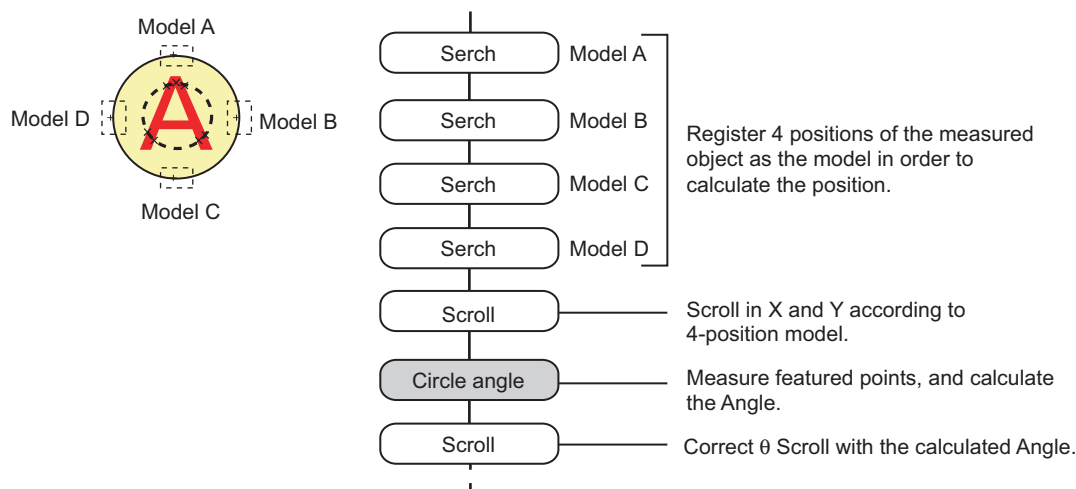


The degree of angle is calculated by comparing the featured points of the reference image with those of the input image.

Note

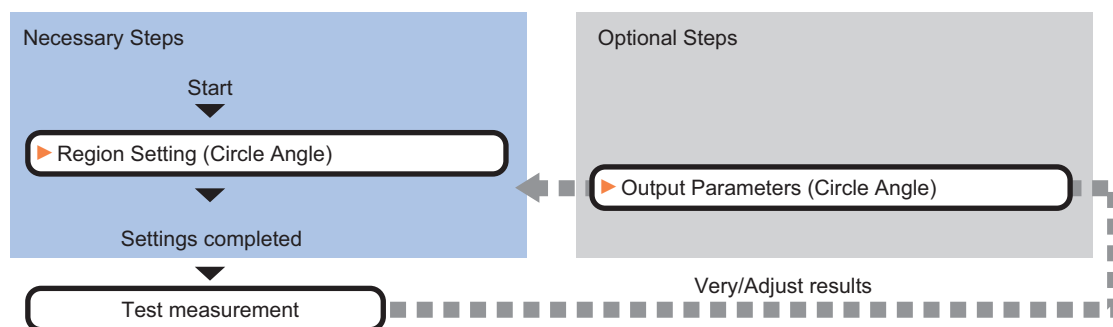
- The center position of the measured object should be always fixed in order to efficiently use the Circle Angle. Prior to Circle Angle, processing items related to position correction should be performed, making the central coordinates of the measurement object stay at a fixed position.

Example)



Settings Flow (Circle Angle)

The Circle Angle should be set up with the following procedure.



List of Circle Angle Items

Item name	Description
Region setting	This item is used to set up the measurement area. Instead of measuring the entire input image, narrowing the measurement area shortens the processing time. If measurement results are unstable, change detection conditions as needed. Normally, the factory default value will be used. Reference: ▶ Region Setting (Circle Angle) (p.403)
Output parameter	This item can be changed if necessary. Normally, the factory default value may be used. Select the measurement result coordinates and set how to handle the coordinates. Reference: ▶ Output Parameters (Circle Angle) (p.404)

Region Setting (Circle Angle)

This item is used to set up the measurement area. This item specifies the measurement region for [Circle Angle] with a circle. Ellipses cannot be set. If measurement results are unstable, change detection conditions as needed.

Note



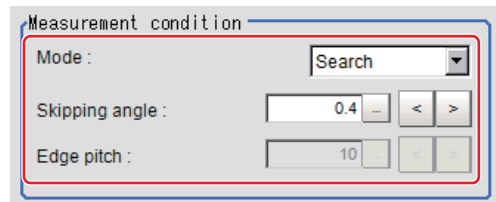
•When drawing the measurement region, the featured part should lie on the circumference.

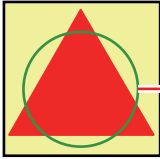
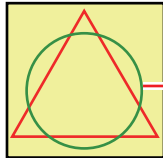
- 1 In the Item Tab area, click [Region setting].
- 2 Use the Drawing tools to specify the measurement region.
- 3 In the figure setting area, click [OK].

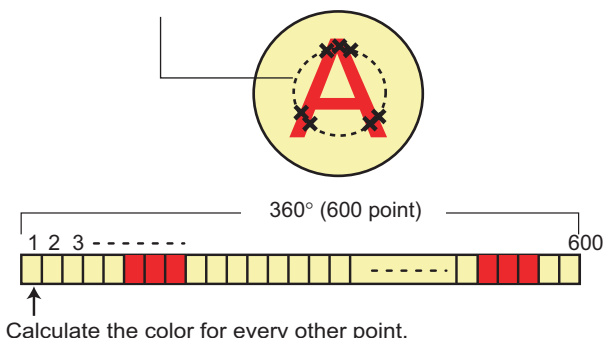
The measurement region is registered and displayed in the Image Display area.

- 4 If necessary, set a value for each item in the "Measurement condition" area.

After changing a setting, check whether measurement can be done properly by performing an actual measurement.



Setting item	Set value [Factory default]	Description
Mode	[Search]	This option compares the color difference with the surrounding pixels and determines the angle based on the color information.
	Edge	<p>The angle is determined based on the position of the points with a large color difference from the neighboring pixels.</p>  <p>This mode is suitable for the following types of measurement objects.</p>
	Defect	<p>The angle is determined based on the position of the points with a large color difference from the surrounding pixels.</p>  <p>This mode is suitable for the following types of measurement objects.</p>

Setting item	Set value [Factory default]	Description
Skipping angle	0.1 to 10 [0.4]	<p>Specify the interval degrees for extracting points. The color of all the points on the circumference (360° circumference/skipping angle) corresponding to the set skipping angle.</p> <p>Example) When the scale unit is 0.6° Measure 600 point on this line in the pixel unit.</p>  <p>360° (600 point)</p> <p>1 2 3 ----- 600</p> <p>Calculate the color for every other point.</p> <p>For the initial setting, the optimal value will be automatically set up based on the radius of the drawn circle. The bigger the value set, the faster the processing, but the lower the detection angle and rotation precision.</p>
Edge pitch	1 to 99 [10]	<p>Specify the spacing for calculating the color difference. This item is enabled only when "Mode" is set to "Edge" or "Defect".</p>

[Note 1]: Comparison is with the pixel separated by exactly the comparison interval (the value set in "Edge Pitch").

Output Parameters (Circle Angle)

Specify how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

Important

- After setting up the measurement parameters, changing the output parameters will cause measurement results to vary accordingly. If the output parameters have been changed, re-specify the measurement, too.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Set up each item.

Setting item	Set value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position deflection correction is applied.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	<p>Select whether to reflect the calibration in the values output to the external device as measurement results.</p> <p>ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.</p>

Key Points for Test Measurement and Adjustment (Circle Angle)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Rotation angle	Measured Angle
Center position X	Center position X of circle in measurement results
Center position Y	Center position Y of circle in measurement results
Reference angle	Angle of the circle drawn as the measurement region
Reference X	Reference position X of the circle drawn as the measurement region
Reference Y	Reference position Y of the circle drawn as the measurement region

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are unstable

Parameter to be adjusted	Remedy
Region setting	Specify a smaller value for the "Skipping angle".
Measurement flow	When the center position of measurement objects is not fixed, add position compensation to the flow so that the central coordinates of the measurement objects give a fixed position.

When the processing speed is slow

Parameter to be adjusted	Remedy
Region setting	Specify a larger value for the "Skipping angle".
	Set the "Mode" to "Edge" or "Defect".

Measurement Results for Which Output Is Possible (Circle Angle)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judgement result
Center position X	X	Center position X of circle in measurement results
Center position Y	Y	Center position Y of circle in measurement results
Rotation angle	TH	Angle of measurement results Output range -180° to 180°
Reference position X	SX	Reference position X of the circle drawn as the measurement region [Note 1]
Reference position Y	SY	Reference Y of the circle drawn as the measurement region [Note 1]
Reference angle	ST	Angle drawn as the measurement region

[Note 1]: Since measuring is performed at the same position every time for Circle Angle, "Center X = Reference SX, Center Y = Reference SY".

External Reference Tables (Circle Angle)

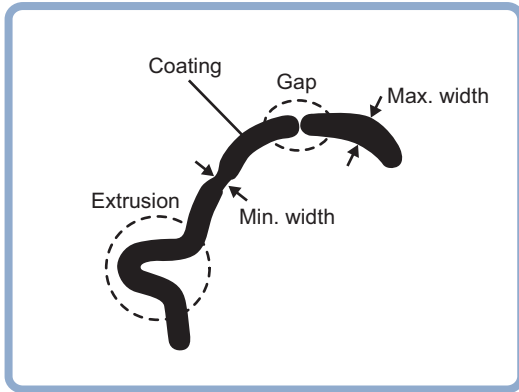
No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Center position X	Get only	0 to 99999.9999
6	Center position Y	Get only	0 to 99999.9999
7	Rotation angle	Get only	-180 to 180
8	Reference X	Get only	0 to 99999.9999
9	Reference Y	Get only	0 to 99999.9999
10	Reference angle	Get only	-180 to 180
101	Output coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
120	Mode	Set/Get	0: Search 1: Edge 2: Defect
121	Skipping angle	Set/Get	0.1 to 10
122	Edge pitch	Set/Get	1 to 99

Glue Bead Inspection

Inspect the coated condition of coating (sealer, etc.). You can inspect coating of a specified color for gaps or runoffs along the coating path. In addition to inspecting the above, you can also measure the maximum width, minimum width and average of coating.

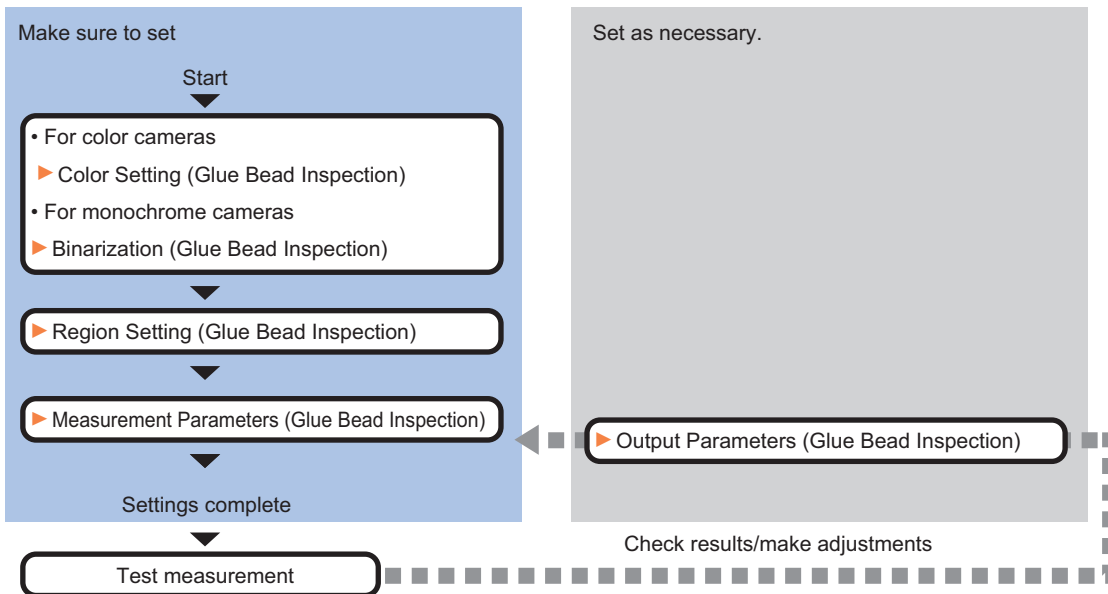
Used in the Following Case

- When you want to inspect coating for gaps and runoffs



Settings Flow (Glue Bead Inspection)

Setting of coating gap inspection follows the flow shown below.



List of Glue Bead Inspection Items

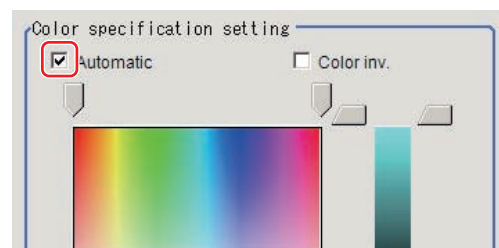
Item name	Description
Color (for color cameras only)	Set the color of coating to be extracted. Reference: ▶ Color Setting (Glue Bead Inspection) (p.408)
Binarization (for monochrome cameras only)	This item specifies the binary level for converting 256-tone grayscale images input from the camera into binary images. Converted white pixels are measured. Adjust the binary level so that the measurement object is converted to white pixels. Reference: ▶ Binarization (Glue Bead Inspection) (p.410)

Item name	Description
Region setting	Set the inspection region. Reference: ▶ Region Setting (Glue Bead Inspection) (p.411)
Measurement	Set up the measurement condition and judgement condition. Reference: ▶ Measurement Parameters (Glue Bead Inspection) (p.411)
Output parameter	Specifies whether or not the judgement results of the processing unit is reflected in the scene overall judgement. Reference: ▶ Output Parameters (Glue Bead Inspection) (p.413)

Color Setting (Glue Bead Inspection)

Set the color of coating to be extracted. Make sure the regions other than coating will be shown in the specified background color. There are two setting methods: setting the color to be extracted in the image or setting the color with the hue, saturation, and brightness values. This section describes with an example of the procedure for setting colors in an image and adjusting with numeric input afterwards.

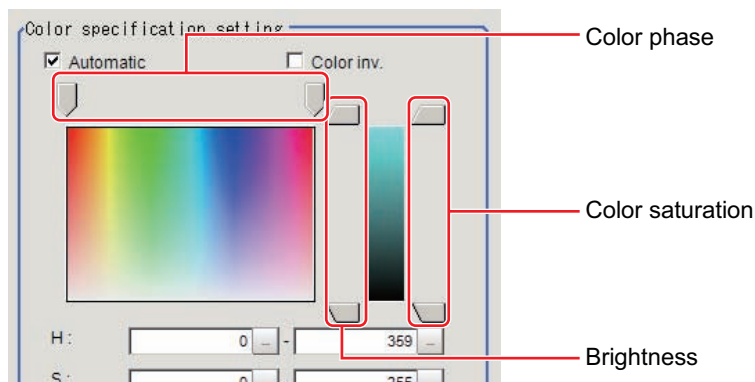
- 1 In the Item Tab area, click [Color].**
- 2 Place a check at [Automatic].**



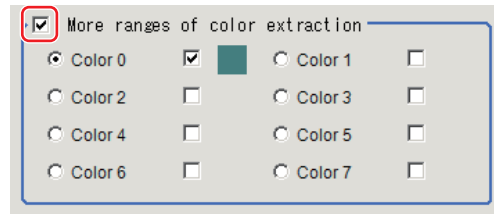
- 3 In the Image Display area, specify the color range you want to detect by dragging the cursor from the upper left corner to the lower right corner of that area.**
The color of the specified area is automatically set.
- 4 Finely adjust the hue, saturation, and brightness if necessary.**
Adjust either by adjusting on the color chart or by inputting numbers.

Setting item	Setting value [Factory default]	Description
H	0 to 359	Set the color phase (difference of color hues).
S	0 to 255	Set color saturation (difference of color saturation).
V	0 to 255	Set the brightness (difference of brightness).
Automatic	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Setting the color to be extracted on the image automatically sets the hue, saturation, and brightness.
Color inv.	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Everything other than the specified color becomes the extraction target.

About color charts

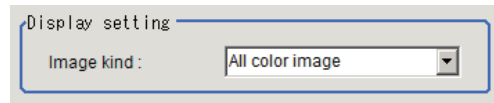
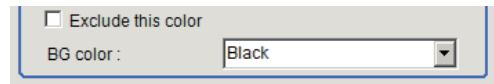


5 In multiple setting areas, specify each item.



Setting item	Setting value [Factory default]	Description
More ranges of color extraction	Checked [Unchecked]	If you place a check at this option, you can set up to 8 colors.

6 If necessary, set the display conditions for displayed images.



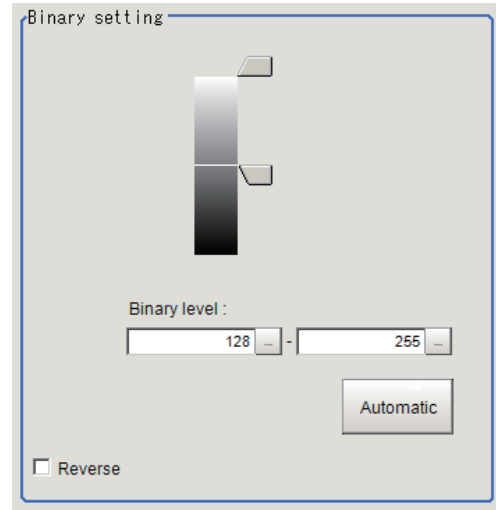
Setting item	Setting value [Factory default]	Description
Exclude this color	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Placing a check here excludes the pixels in the specified color range from the extraction target. The priority order for exclusion is that the higher color extraction range numbers are given priority. This setting is disabled if "More ranges of color extraction" is unchecked.
BG color	<ul style="list-style-type: none"> • [Black] • White • Red • Green • Blue 	The background section outside the extracted image is filled with the selected colors.
Image kind	<ul style="list-style-type: none"> • Measurement image • [All color image] • Selection color image • Binary image 	This selects the state of the image to display.

Binarization (Glue Bead Inspection)

When a monochrome camera is connected, the 256-tone grayscale images taken in from the camera are converted into binary black-and-white images before the images are measured. Converted white pixels are measured.

This specifies the level for converting grayscale images into binary images.

- 1** In the Item Tab area, click [Binary].
- 2** In the "Binary setting" area, set the reference density range.



Setting item		Setting value [Factory default]	Description
Binary level	Upper limit	0 to 255 [128]	Specify the level for converting 256-tone grayscale images to binary images. Set the binary level so that the measurement object is converted to white pixels. You can also set the binary level so that only intermediate density is measured.
	Lower limit	0 to 255 [128]	
Automatic		-	Optimum binary levels are calculated automatically and set.
Reverse		<ul style="list-style-type: none"> • Checked • [Unchecked] 	This item reverses black and white colors.

- 3** If necessary, set up display settings for the images displayed in the "Display setting" area.



Setting item		Setting value [Factory default]	Description
Binary image		<ul style="list-style-type: none"> • [Checked] • Unchecked 	The image is displayed in binary with black and white.

Region Setting (Glue Bead Inspection)

Set the inspection region and extract the coating path. All you need is register three items--measurement region, start line and end line--and then click [Create reference path], and a path will be extracted automatically. Set the mask region as necessary.

- 1** In the Item Tab area, click [Region setting].
- 2** Click [Inspection area].
The figure setting area is displayed.
- 3** Set the range over which to create a reference path.
The figure setting area is displayed.
- 4** Click [OK].
- 5** Similarly, click [Start point] and [End point] to set the start position of creation and end position of creation along the reference path.
- 6** If necessary, click [Mask area] to set the range of region search, and then click [OK].
- 7** Click [Register route].
The target coating path for inspection is registered.

Measurement Parameters (Glue Bead Inspection)

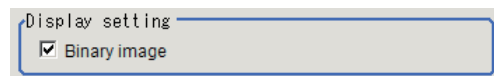
Set the inspection measurement conditions and the judgement conditions for the measurement results.

- 1** In the Item Tab area, click [Measurement].
- 2** In the "Measurement condition" area, specify a value for each item.

Setting item	Setting value [Factory default]	Description
Inspection kind	<ul style="list-style-type: none"> • [Only width inspection] • Only route inspection • Both inspection 	Select the inspection type.
Noise cut	<ul style="list-style-type: none"> • OFF • [ON] 	Select whether or not to process noise removal. Set this option if fine pixel noises generate. Basically the processing should be set to "ON" to ensure stable measurement.
Labeling	<ul style="list-style-type: none"> • OFF • [ON] 	Select whether or not to process noise removal using the labeling filter. Set this option if noises generate. You can use this processing to measure only the labels in the range set in "Object area range ". Basically the processing should be set to "ON" to ensure stable measurement.
Object area range	0 to 99999999 [100 to 99999999]	Set the area range of labels to be measured.

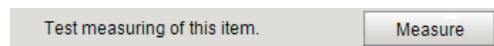
Setting item	Setting value [Factory default]	Description
Fill profile	<ul style="list-style-type: none"> • [None] • Fill profile • Filling up holes 	Select the fill profile method. You can use the Fill profile setting item when the Labeling setting item is set to ON.

3 In the "Display setting" area, set the image display settings.



Setting item	Setting value [Factory default]	Description
Binary image	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Use this option when binary images are displayed.

4 When the setting has been changed, click [Measure] in the "Detail" area to verify whether measurements can be made correctly.



5 Set up the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Setting value [Factory default]	Description
Route len. (Long)	0.0000 to 99999.9999 [0.0000] to [99999.9999]	Set the range of path lengths (long) that is judged to be OK.
Route len. (Short)	0.0000 to 99999.9999 [0.0000] to [99999.9999]	Set the range of path lengths (short) that is judged to be OK.
Min. width	0.0000 to 99999.9999 [0.0000] to [99999.9999]	Set the minimum width that is judged to be OK.
Max. width	0.0000 to 99999.9999 [0.0000] to [99999.9999]	Set the maximum width that is judged to be OK.
Avg. width	0.0000 to 99999.9999 [0.0000] to [99999.9999]	Set the average width that is judged to be OK.
Gap width	0.0000 to 99999.9999 [0.0000]	Set the gap width along a path that are judged to be OK.

Output Parameters (Glue Bead Inspection)

Set how measurement results are output to an external device. This item can be changed if necessary. Normally, the factory default value will be used.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Setting value [Factory default]	Description
Output coordinates	<ul style="list-style-type: none"> • [After scroll] • Before scroll 	As measurement results, select whether to output coordinate values to external devices before or after the position compensation is applied.
Calibration	<ul style="list-style-type: none"> • [OFF] • ON 	Select whether to reflect the calibration in the values output to the external device as measurement results. ON: Output the coordinates converted into actual dimensions. OFF: Output the camera coordinate values.
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Specify whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Glue Bead Inspection)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
State	Coated condition of measured coating
Min. width	Maximum width of measured coating
Max. width	Minimum width of measured coating
Gap width	Gap width of measured coating

Key Points for Adjustment

Select the adjustment method referring to the following points.

When a path creation error occurs

State	Parameter to be adjusted	Troubleshooting
Either the start position or end position is set outside the measurement region.	Region setting	Set the start position or end position, whichever is applicable, inside the measurement region.
Either the start position or end position is yet to be registered.	Region setting	Set the start position or end position, whichever is applicable.
Either the start position or end position is inappropriate to fully enclose coating.	Region setting	Register the start position or end position, whichever is applicable, so that the two positions are set vertically across coating.
Coating is gapped between the start position and end position.	Region setting	If coating is gapped in the middle, register multiple coating gap inspections and set separate inspection parts.
Width between paths of a spiral path is sometimes measured.	Region setting	Divide the spiral into regions corresponding to individual turns and set a unit for each region.

When judgement is NG

State	Parameter to be adjusted	Troubleshooting
The judgement is NG (insufficient memory)	Region setting	Adjust the region so that the reference path becomes shorter.

Measurement Results for Which Output is Possible (Glue Bead Inspection)

Measurement items	Character string	Description
Judge	JG	1: OK 0: Unmeasured -1: NG
State	ST	Condition of measured result 0: Detectable 1: Gapped 2: Path error -1: Unmeasured -2: Region not yet registered -3: Coating not yet detected -4: Excessive path (insufficient memory)
Min. width	MINWD	Min. width
Max. width	MAXWD	Max. width
Average width	AVGWD	Average width
Gap width	GAPWD	Gap width
Coordinate X1 with the minimum width	MINX1	X coordinate X 1 with the minimum width
Coordinate Y with the minimum width	MINY1	Y Coordinate Y1 with the minimum width
Coordinate X2 with the minimum width	MINX2	X coordinate X2 with the minimum width
Coordinate Y2 with the minimum width	MINY2	Y coordinate Y2 with the minimum width
Coordinate X1 with the maximum width	MAXX1	X coordinate X 1 with the maximum width
Coordinate Y1 with the maximum width	MAXY1	Y coordinate Y1 with the maximum width
Coordinate X2 with the maximum width	MAXX2	X coordinate X2 with the maximum width
Coordinate Y2 with the maximum width	MAXY2	Y coordinate Y2 with the maximum width
Coordinate X1 of gap width	GAPX1	X coordinate X1 of gap width
Coordinate Y1 of gap width	GAPY1	Y coordinate Y1 of gap width
Coordinate X2 of gap width	GAPX2	X coordinate X2 of gap width
Coordinate Y2 of gap width	GAPY2	Y coordinate Y2 of gap width

External Reference Tables (Glue Bead Inspection)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Status of measure result	Get only	-
6	Min. width of measure result	Get only	-
7	Max. width of measure result	Get only	-
8	Average width of measure result	Get only	-
9	Lack width of measure result	Get only	-
10	Route len. (Long)	Get only	-
11	Route len. (Short)	Get only	-
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Register the max. color hue	Set/Get	0 to 359
121	Register the min. color hue	Set/Get	0 to 359
122	Register the max. color saturation	Set/Get	0 to 255
123	Register the min. color saturation	Set/Get	0 to 255
124	Register the max. color brightness	Set/Get	0 to 255
125	Register the min. color brightness	Set/Get	0 to 255
126	Extract image	Set/Get	0: OFF 1: ON
127	Background color	Set/Get	0: Black 1 : White 2: Red 3: Green 4: Blue
128	With/without fill profile	Set/Get	0: OFF 1: Fill profile 2: Filling up holes
129	Inverse area presence	Set/Get	0: OFF 1: ON
130	With/without noise removal	Set/Get	0: OFF 1: ON
131	Allowable path width	Set/Get	2 to 100
132	Upper limit of the minimum width	Set/Get	0.0000 to 99999.9999
133	Lower limit of the minimum width	Set/Get	0.0000 to 99999.9999

No.	Data name	Set/Get	Data range
134	Upper limit of the maximum width	Set/Get	0.0000 to 99999.9999
135	Lower limit of the maximum width	Set/Get	0.0000 to 99999.9999
136	Upper limit of average width	Set/Get	0.0000 to 99999.9999
137	Lower limit of Average width	Set/Get	0.0000 to 99999.9999
138	Upper limit of gap width	Set/Get	0.0000 to 99999.9999
139	Lower limit of gap width	Set/Get	0.0000 to 99999.9999
142	Upper limit of the binary level	Set/Get	0 to 255
143	Lower limit of the binary level	Set/Get	0 to 255
144	Binary image	Set/Get	0: OFF 1: ON
145	Scanning direction for line 0	Set/Get	0: Clockwise 1: Counterclockwise
146	Scanning direction for line 1	Set/Get	0: Clockwise 1: Counterclockwise
147	Upper limit of the Route len. (Long)	Set/Get	0.0000 to 99999.9999
148	Lower limit of the Route len. (Long)	Set/Get	0.0000 to 99999.9999
149	Upper limit of the Route len. (Short)	Set/Get	0.0000 to 99999.9999
150	Lower limit of the Route len. (Short)	Set/Get	0.0000 to 99999.9999
151	Multiple selections	Set/Get	0: Multiselect NG 1: MultiSelect OK
152	Display image type	Set/Get	0: Measurement image 1: All color image 2: Color selected image 3: Binary image
153	Upper limit of the object area range	Set/Get	0 to 999999999
154	Lower limit of the object area range	Set/Get	0 to 999999999
155	Labeling	Set/Get	0: OFF 1: ON
156	Inspection kind	Set/Get	0: Width's inspection only 1: Route's inspection only 2: Width and route's inspection
160 + N × 10 (N = 0 to 7)	Flag N used for registered color	Set/Get	0: OFF 1: ON
161 + N × 10 (N = 0 to 7)	Flag N for registered color OR/NOT	Set/Get	0: OR 1: NOT
162 + N × 10 (N = 0 to 7)	Register the max. color hue N	Set/Get	0 to 359
163 + N × 10 (N = 0 to 7)	Register the min. color hue N	Set/Get	0 to 359
164 + N × 10 (N = 0 to 7)	Register the max. color saturation N	Set/Get	0 to 255

No.	Data name	Set/Get	Data range
165 + N × 10 (N = 0 to 7)	Register the min. color saturation N	Set/Get	0 to 255
166 + N × 10 (N = 0 to 7)	Register the max. color brightness N	Set/Get	0 to 255
167 + N × 10 (N = 0 to 7)	Register the min. color brightness N	Set/Get	0 to 255
168 + N × 10 (N = 0 to 7)	Background color N	Set/Get	0: Black 1: White 2: Red 3: Green 4: Blue
1000 + N × 2 (N = 0 to 1)	Min. width XN	Get only	-
1001 + N × 2 (N = 0 to 1)	Min. width YN	Get only	-
1004 + N × 2 (N = 0 to 1)	Max. width XN	Get only	-
1005 + N × 2 (N = 0 to 1)	Max width YN	Get only	-
1008 + N × 2 (N = 0 to 1)	Gap pos. XN	Get only	-
1009 + N × 2 (N = 0 to 1)	Gap pos. YN	Get only	-

MEMO

Compensate image

This chapter describes how to apply positional compensation for measurement objects in the input image in order to measure accurately.

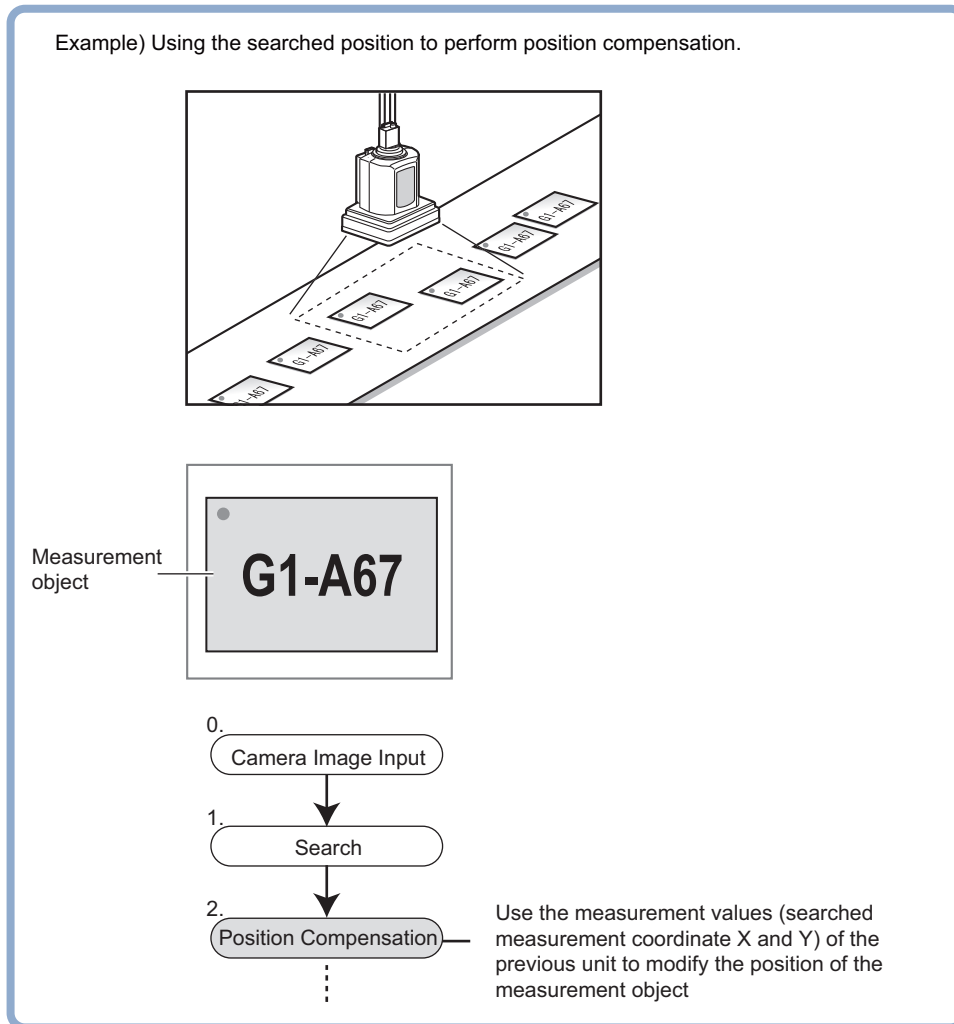
Position Compensation	420
Filtering	425
Background Suppression	429
Brightness Correct Filter	432
Color Gray Filter	435
Extract Color Filter	438
Anti Color Shading	443
Stripes Removal Filter II.....	446
Polar Transformation	451
Trapezoidal Correction.....	454
Machine Simulator.....	461
Image Subtraction	467
Advanced filter.....	474
Panorama	507

Position Compensation

The positional deviation of measurement objects can be corrected using measured values saved by other processing units. Compare the measured coordinates with the reference coordinates of the applicable processing unit, and move the image by the amount of the difference.

Used in the Following Case

- Even with different positions for the same measurement object, correct measurement can still be performed by correcting the position of the input image. There is no need to reposition the measurement object itself.



Processing Units That Can Be Combined with Position Compensation

Position compensation corrects positions according to measured values (coordinates) from the immediately preceding processing unit. Combining the following processing units with position compensation is effective.

Processing unit type	Processing item name
Processing unit that performs search or matching (called "Search processing unit" hereafter.)	Reference: ▶ Search (p.68) Reference: ▶ Flexible Search (p.82) Reference: ▶ ECM Search (p.104) Reference: ▶ Circle Angle (p.401)

Processing unit type	Processing item name
Processing unit that detects edge positions (called "Edge position processing unit" hereafter.)	Reference: ▶ Edge Position (p.191) Reference: ▶ Scan Edge Position (p.210)
Processing unit to detect the center of gravity (called "processing unit for gravity center detection".)	Reference: ▶ Gravity and Area (p.284) Reference: ▶ Labeling (p.298)

Important

- When the position compensation method ([Method]) is set to [1 unit scroll] or [2 unit scroll], position compensation will not be performed correctly if units other than the above unit(s) are present immediately before the [Position Compensation] unit within the scene.
- For processing units that are used in combination with position compensation, set [Calibration] to "OFF" in [Output parameter].
- The position compensation method causes some processing items to be NG when areas outside the image are included within the region. (Edge position/number of edge pins/fine matching/defects and contamination/ high-precision defects and contamination detection/area gravity center/labeling/sophisticated labeling+/color average and deviation/scan edge position/scan edge width/circular shape angle acquisition)

Region Compensation (Position Compensation)

When position compensation is set, the position is shifted by exactly the amount of the compensation, then measurement is performed. Restricting the region in which the image is moved can shorten the processing time.

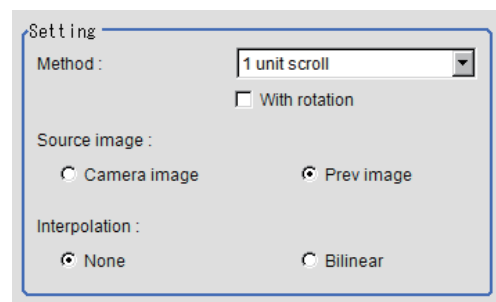
- 1 In the Item Tab area, click [Region setting].**
- 2 Use the Drawing tools to specify the measurement region.**
- 3 In the figure setting area, click [OK].**

The range in which to perform position compensation is registered.

Scroll Method (Position Compensation)

Set the compensation method for position compensation.

- 1 In the Item Tab area, click [Scroll method].**
- 2 Set the parameters.**



Setting item	Set value [Factory default]	Description
Method	[1 unit scroll]	This performs a position compensation by referring to the coordinates measured with the search processing unit or edge position processing unit [Note 1] immediately before the [Position Compensation] (automatic processing unit). This moves the image by the difference between the measured coordinates and the reference coordinates of the referring search processing unit or edge position processing unit.
	2 unit scroll	This performs a position compensation by referring to the coordinates measured with the search processing unit or edge position processing unit [Note 1] immediately before or two units before the [Position Compensation] (automatic processing unit).
	Calculation	Set whichever position compensation you prefer. Set the reference coordinates and measurement coordinates.
	Reset scroll	The image for the immediately preceding image input (Camera image input/Camera switching) is displayed. When position compensation has been performed, the status returns to that from before position compensation. If Filtering or Color Gray Filter had been performed, the original image with Filtering or Color Gray Filter released is displayed.
With rotation	<ul style="list-style-type: none"> • Checked • [Unchecked] 	When "1 unit scroll" or "2 unit scroll" is selected as the setting method, place a check for executing position compensation in the rotation direction in addition to the XY directions.
Source image	Camera image	The camera input image that has not been subject to filtering is subject to compensation as is.
	[Prev image]	Images to which filtering and position compensation processing are applied in units even before the "Position Compensation" being set are the targets.
Interpolation	[None]	Position compensation is performed in units of pixels.
	Bilinear	This option joins more than one point with a line in order to find a desired approximate value. The image will become smoother.

[Note 1]Reference: ▶ Processing Units That Can Be Combined with Position Compensation (p.420)

When you choose the "Calculation" option

3 Using expressions, specify the "Reference" and "Position" which are used to determine the position compensation.

Differences between the respective values in the "Reference" and "Position" areas give the amount of position compensation to be performed.

Reference: ▶ Layout of Setting Expression Window (p.535)

Key Points for Test Measurement and Adjustment (Position Compensation)

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number.	Explanation of image to be displayed
0	After compensation
1	Before compensation

Measurement Results for Which Output Is Possible (Position Compensation)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Scroll X	DX	Scroll X
Scroll Y	DY	Scroll Y
Scroll θ	DT	Scroll θ
Measurement coordinate X	X	Measured value X coordinate
Measurement coordinate Y	Y	Measured value Y coordinate
Measurement angle θ	TH	Measure angle θ
Reference position X	SX	Reference X coordinate
Reference position Y	SY	Reference Y coordinate
Reference angle θ	ST	Reference angle θ

External Reference Tables (Position Compensation)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Scroll X	Get only	-99999.9999 to 99999.9999
6	Scroll Y	Get only	-99999.9999 to 99999.9999
7	Scroll θ	Get only	-999.9999 to 999.9999
8	Position X	Get only	0 to 99999.9999
9	Position Y	Get only	0 to 99999.9999
10	Measurement θ	Get only	-360 to 360
11	Reference X	Get only	-99999.9999 to 99999.9999
12	Reference Y	Get only	-99999.9999 to 99999.9999
13	Reference θ	Get only	-999.9999 to 999.9999
120	Interpolation	Set/Get	0: None 1: Bilinear
121	Method	Set/Get	0: 1 unit scroll 1: 2 unit scroll 2: Expression 3: Reset scroll
122	Scroll target	Set/Get	0: Camera image 1: Prev. unit image

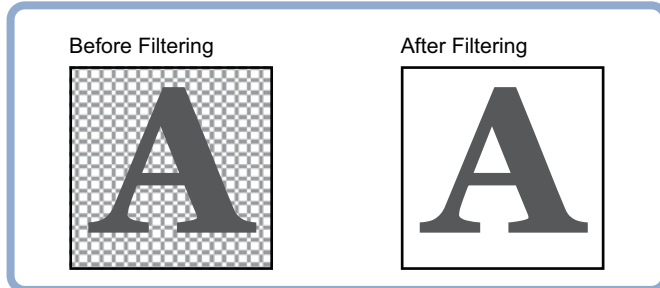
No.	Data name	Set/Get	Data range
123	With rotation	Set/Get	0: OFF 1: ON
124	Reference position X	Set/Get	Exp. character string
125	Reference position Y	Set/Get	Exp. character string
126	Reference angle	Set/Get	Exp. character string
127	Measurement position X	Set/Get	Exp. character string
128	Measurement position Y	Set/Get	Exp. character string
129	Measurement angle	Set/Get	Exp. character string

Filtering

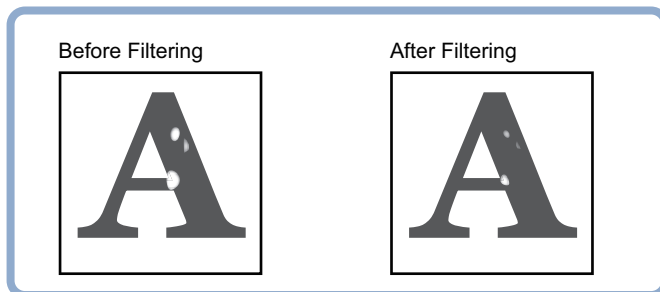
Process the images acquired from cameras in order to make them easier to measure.

Used in the Following Case

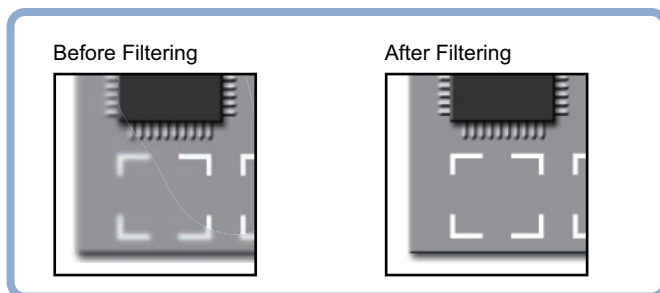
- Cutting out unnecessary background images to exclude them from the measurement region



- When noise is to be removed



- When the edges of marks you want to find cannot be found even though other edges have been extracted.



Filtering Parameters (Filtering)

Treat the images loaded from the camera in order to make them easier to measure.

You can select from 10 filtering methods to match the image state.

- 1 In the Item Tab area, click [Filter parameter].
- 2 Set each item while checking the image.

Setting item	Set value [Factory default]	Description
Display	Through image display	The latest image is always input from the camera and displayed.
	[Freeze image display]	The image that was scanned in the immediately preceding measurement is displayed. Images can be updated at any time during measurement.

Setting item	Set value [Factory default]	Description
Target for filtering	[Camera image]	Filtering is applied to the images input from the camera that is set before this unit ([Filtering]) in the scene. Filtering is not performed.
	Previous image	Filtering is applied to the images which have been processed by the [Position Compensation] and [Filtering] units that are set before this unit ([Filtering]) in the scene.
Order of filtering	<ul style="list-style-type: none"> • [Filtering → BGS] • BGS → Filtering 	Select the sequence of background suppression/filtering.
Filtering	<ul style="list-style-type: none"> • [OFF] • Weak smoothing • Strong smoothing • Dilate • Erosion • Median • Extract edges • Extract horizontal edges • Extract vertical edges • Enhance edges 	Select the type of filtering. Reference: ▶ Filtering Options and Examples (p.426)
Filter size	<ul style="list-style-type: none"> • [3 × 3] • 5 × 5 	Select whether to use information from several surrounding pixels. With mask size, the larger the setting value, the more of the surrounding pixel variation that can be assimilated.
BGS level	[0] to [255]	While looking at your image, specify the upper and lower limits for RGB to suppress as the background. Reference: ▶ Background Suppression Level (p.427)

Filtering Options and Examples

Treat the images loaded from the camera in order to make them easier to measure.

Types of filtering	The problems to be treated	Filtering description	Example
Weak smoothing Strong smoothing	Small flecks on the measurement object	Makes flecks less visible.	Makes stable searching possible and stable area measurement possible.
Dilate	Dark noise exists	This filtering removes dark noise by enlarging brighter areas.	Removing noise from measurement objects
Erosion	Brighter noise exists	This filtering removes brighter noise by shrinking brighter areas.	
Median	Small flecks on the measurement object	This filtering keep the profile and weaken flecks.	Edge positioning (Accuracy is not reduced)
Extract edges	Due to a comparatively lower image contrast, defects are difficult to extract	Extracts the boundary lines of the image (light and shade).	Defect inspection
Extract horizontal edges	Due to a comparatively lower image contrast, defects are difficult to extract	Extracts the boundary lines horizontal to the image (light and shade).	
Extract vertical edges	Due to a comparatively lower image contrast, defects are difficult to extract	Extracts the boundary lines vertical to the image (light and shade).	
Enhance edges	The measurement object is blurry (due to changes such as lighting fluctuation).	Clearly delineates the boundary lines between the light and dark in the image.	Edge positioning

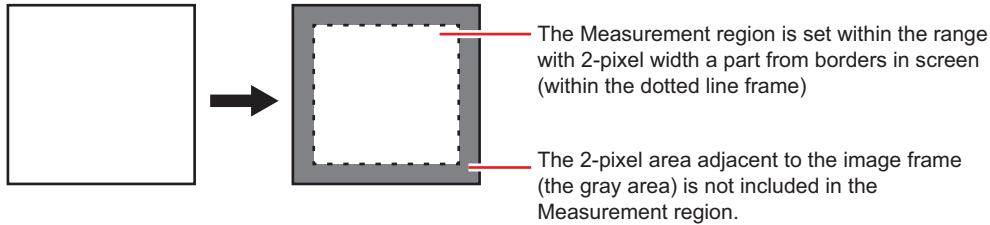
Notes on Filtering Setting

If filtering is applied to the image, the area around the image frame will become unstable. When a [Filtering] processing item has been set in the scene, ensure that measurement ranges, etc. set for other processing items are not included in the area around the image frame.

The width not included in the measurement range will vary depending on the mask size settings.

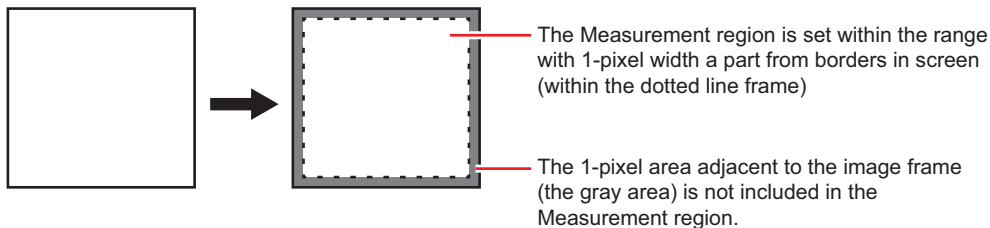
- **Filter size: 5 × 5**

Make settings so that a width around the image frame equal to 2 pixels is not included in the measurement range.



- **Filter size: 3 × 3**

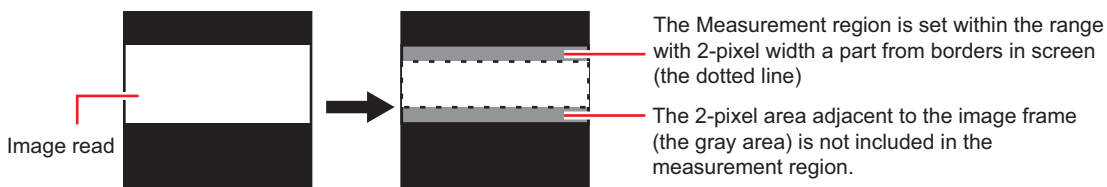
Make settings so that a width around the image frame equal to 1 pixels is not included in the measurement range.



When a partial scan is used to limit the load range

Set so as to not include the image loading range surroundings.

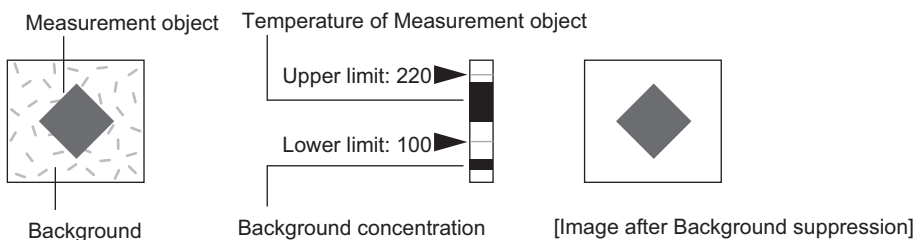
The width that will not be included in the measurement range is the same as the above. (In the following figure, filter size: 5 × 5).



Background Suppression Level

The images below the lower limit and above the upper limit will be set to the lower and upper limits of brightness, respectively.

Example) lower limit: 100 upper limit: 220



Only images with a density of 100 to 220 can be measurement objects.

Region Setting (Filtering)

It is possible to target the entire screen, but restricting the range can shorten the processing time.

- 1** In the Item Tab area, click [Region setting].
- 2** Use the Drawing tools to specify the measurement region.
- 3** In the figure setting area, click [OK].

The area in which to perform filtering is registered.

External Reference Tables (Filtering)

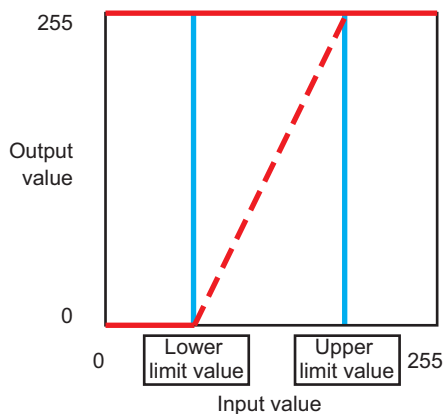
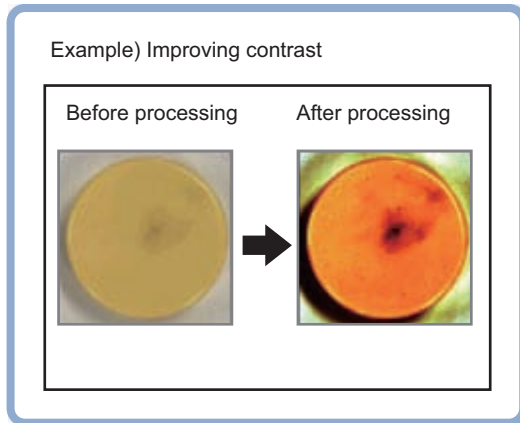
No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
120	Target	Set/Get	0: Camera image 1: Prev. unit image
121	Filtering	Set/Get	0: OFF 1: Weak smoothing 2: Strong smoothing 3: Dilation 4: Erosion 5: Median 6: Extract vertical edges 7: Extract horizontal edges 8: Extract edges 9: Enhance edges
122	Filtering order	Set/Get	0: Filtering to BGS 1: BGS to Filtering
123	Filter size	Set/Get	0: 3 * 3 1: 5 * 5
124	Lower limit for BGS levels	Set/Get	0 to 255
125	Upper limit for BGS levels	Set/Get	0 to 255

Background Suppression

Specifying a brightness range to use for measurement eliminates the section outside that range as background. In addition, the extracted range is converted into values of 0 to 255, so the contrast can be emphasized.

Used in the Following Case

- By extracting a specific brightness range, the contrast on the image can be improved, unnecessary background eliminated, etc.



Basic concept of background suppression

Because input values from 0 to [Lower] are converted to level 0 and values from [Upper] to 255 are converted to level 255, the background in this range is eliminated.

Together with this, only [Lower] to [Upper] from the input values 0 to 255 are taken and those are converted to output values of 0 to 255, so the contrast within this range is emphasized.

Filter Setting (Background Suppression)

This item sets the filter.

- 1 In the Item Tab area, click [Filter Setting].
- 2 In the "Display" area, click [Change display] to switch between camera image types.

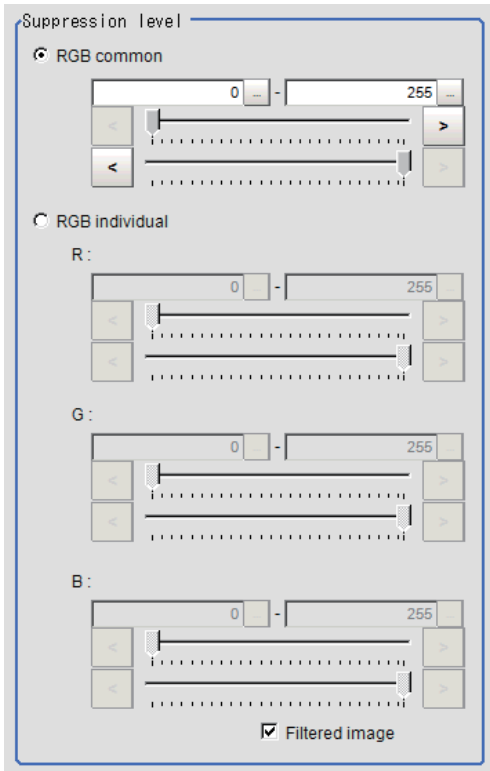
The displayed contents of the Image Display area will be switched.

Setting item	Set value [Factory default]	Description
Display	Through image display	The latest image is always input from the camera and displayed.
	[Freeze image display]	The image that was scanned in the immediately preceding measurement is displayed.

3 Set the background suppression level.

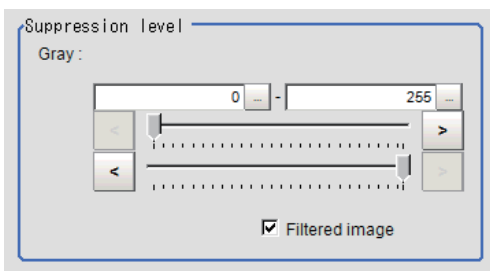
There are two setting methods: specifying the section in the image whose contrast is to be emphasized or specifying the extraction range with numeric values.

For color cameras:



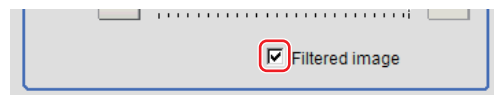
Item	Set value [Factory default]	Description
Suppression level	RGB common 0 to 255	The upper and lower limits for the background suppression level are set in common for RGB. The range from the set minimum to the set maximum is converted to 0 to 255.
	RGB individual 0 to 255	The maximum and minimum for the background suppression level are independently for RGB. The range from the set minimum to the set maximum is converted to 0 to 255.

For monochrome cameras:



Setting item	Set value [Factory default]	Description
Gray	0 to 255	The set range is converted to 0 to 255.

4 As necessary, set the display image.



Region Setting (Background Suppression)

It is possible to target the entire screen, but restricting the range can shorten the processing time.

- 1** In the Item Tab area, click [Region setting].
- 2** Use the Drawing tools to specify the measurement region.
- 3** In the figure setting area, click [OK].

The area in which to perform filtering is registered.

Measurement Results for Which Output Is Possible (Background Suppression)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Background Suppression)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
121	Color setting mode	Set/Get	0: RGB common 1: RGB individual
122	Lower limit for common colors	Set/Get	0 to 255
123	Upper limit for common colors	Set/Get	0 to 255
124	MIN R	Set/Get	0 to 255
125	MAX R	Set/Get	0 to 255
126	MIN G	Set/Get	0 to 255
127	MAX G	Set/Get	0 to 255
128	MIN B	Set/Get	0 to 255
129	MAX B	Set/Get	0 to 255
130	Lower limit for shading	Set/Get	0 to 255
131	Upper limit for shading	Set/Get	0 to 255
132	Filtered image	Set/Get	0: Image prior to transfer 1: Image after transfer
200	Transfer source image number	Set/Get	0 to 9
201	Transfer destination image number	Set/Get	0 to 9

Brightness Correct Filter

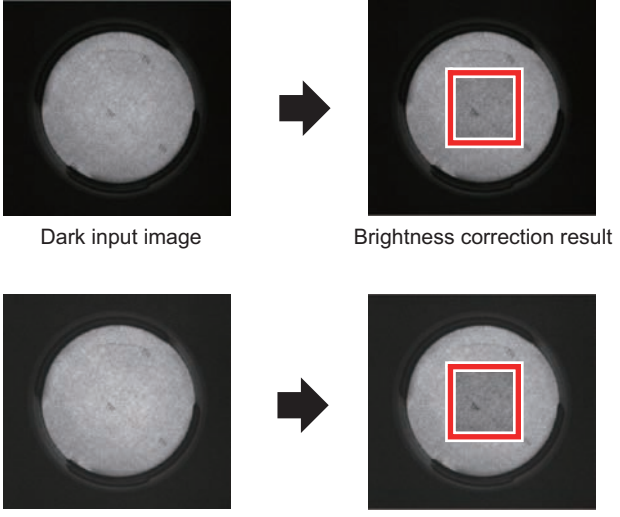
The filter can be used to correct the effect of the material and shape of the lighting and the measurement object.

Used in the Following Case

- This is used when the image is non-uniform due to the effect of the material and shape of the lighting and the measurement object.

• Brightness correction

Even if the brightness of the measurement object changes due to the impact of the surrounding environment, consistent measurement results can be obtained by applying correction to a certain brightness.



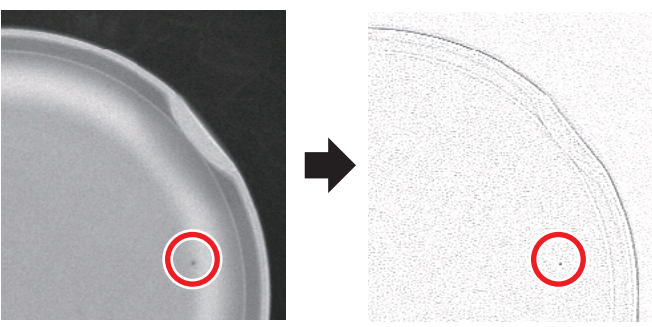
Dark input image → Brightness correction result

Bright input image → Brightness correction result

■ Setting region

• Unevenness removal

If the image is uneven due to the influence of the shape, material, or the like of the measurement object, this function can be used to remove the unevenness and make defects easier to detect.



Input image → Unevenness removal

Important

- This processing item is for monochrome only. When using a color camera, insert a color gray filter before this processing item. If a color image is input, it is NG (incompatible image).

Filter Setting (Brightness Correct Filter)

This item sets the filter.

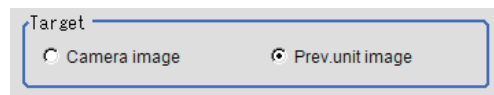
- 1 In the "Item Tab" area, click [Filter setting].
- 2 In the "Display" area, click [Change display] to switch between camera image types.

The displayed contents of the image display area will be switched.



Setting item	Setting value [Factory default]	Description
Display	Through image display	The latest image is always input from the camera and displayed.
	[Freeze image display]	The image that was scanned in the immediately preceding measurement is displayed.
Filtered image	<ul style="list-style-type: none"> • [Checked] • Unchecked 	To display the original image, uncheck here.

- 3 Set the target image.



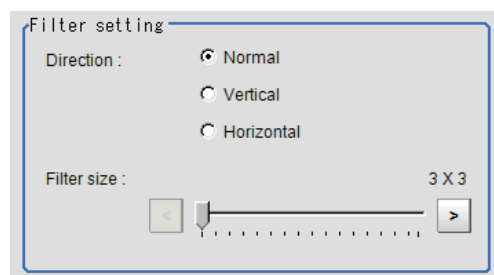
Setting item	Setting value [Factory default]	Description
Target	Camera image	The camera input image that has not been subject to filtering is subject to compensation as is.
	[Prev. unit image]	Images to which processing is applied in units even before the "Brightness correction" being set are the targets.

- 4 Set the correction method.



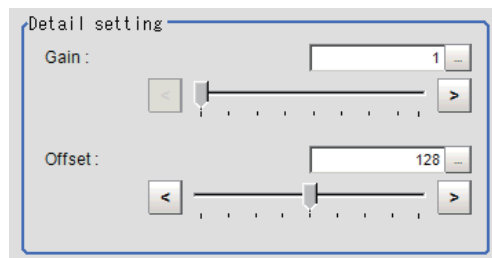
Setting item	Setting value [Factory default]	Description
Uneven removal	<ul style="list-style-type: none"> • Checked • [Unchecked] 	When this is checked, unevenness removal is performed in addition to brightness correction.

- 5 Specify the filtering setting (only for "Uneven removal").



Setting item	Setting value [Factory default]	Description
Direction	<ul style="list-style-type: none"> • [Normal] • Vertical • Horizontal 	Usually, set this to "Normal". If the direction of change of the unevenness is one direction, select the setting that is perpendicular to the direction of change of the unevenness.
Filter Size	3 to 255 [3]	Specify a larger value to match the size of the defects to be extracted. Only an odd number value can be specified.

6 Set the details.



Setting item	Setting value [Factory default]	Description
Gain	1 to 63 [1]	Adjust the contrast of an image after the correction. Specifying a larger value emphasizes the density differences within the image.
Offset	0 to 255 [128]	Adjust the brightness of an image after the correction. Specifying a larger value increases the brightness of the image.

Region Setting (Brightness Correct Filter)

It is possible to target the entire screen, but restricting the range can shorten the processing time.

- 1** In the Item Tab area, click [Region setting].
- 2** Use the drawing tools to specify the measurement region.
- 3** In the figure setting area, click [OK].

The area in which to perform filtering is registered.

External Reference Tables (Brightness Correct Filter)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (not yet measured) 1: Judgement result OK -1: Judgement result NG
120	Unevenness removal (correction method)	Set/Get	0: Do not perform unevenness removal. (Perform brightness correction.) 1: Perform unevenness removal.
121	Direction	Set/Get	0: Vertical and horizontal 1: Horizontal 2: Vertical
122	Filter Size	Set/Get	3 to 255
123	Gain	Set/Get	1 to 63
124	Offset	Set/Get	0 to 255
200	Transfer source image number	Set/Get	0 to 9
201	Image number after transfer	Set/Get	0 to 9
202	Target image	Set/Get	0: Camera input image 1: Previous unit image
203	Display image	Set/Get	0: Display the image before processed. 1: Display the image after processed.

Color Gray Filter

This processing item converts a color image input from a color camera into a monochrome image. The available filters are "Primary color filter (RGB)", "Complementary color filter (CMY)", "Brightness filter", and "HSV filter".

This processing item cannot be used with monochrome images. Such use causes a judgement of NG (incompatible image).

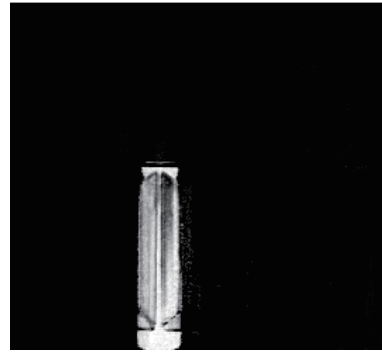
Note

- The processing items after Color Gray Filter are the same as when a monochrome camera is connected.

Used in the Following Case

- To convert a color image to a monochrome image with a specific color enhanced

Example) To obtain a monochrome image with the dark red area enhanced



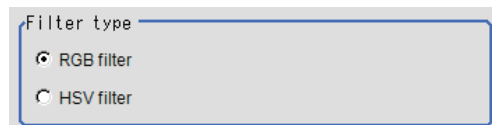
Filter Setting (Color Gray Filter)

This item sets the filter.

- In the Item Tab area, click [Filter Setting].
- In the "Display mode" area, click [Change display] to switch between camera image types. The displayed contents of the Image Display area will be switched.

Setting item	Set value [Factory default]	Description
Display mode	Through image display	The latest image is always input from the camera and displayed.
	[Freeze image display]	The image that was scanned in the immediately preceding measurement is displayed.

- Select the type of filter in the "Filter type" area.

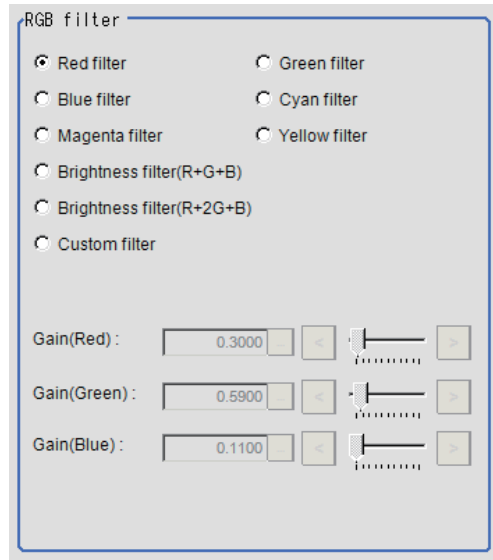


Setting item	Set value [Factory default]	Description
Filter type	[RGB filter]	Specify the color extraction range with R, G, and B.
	HSV filter	Specify the color extraction range with hue and color chroma.

When RGB is selected

4 Select the type of color filter in the "RGB filter" area.

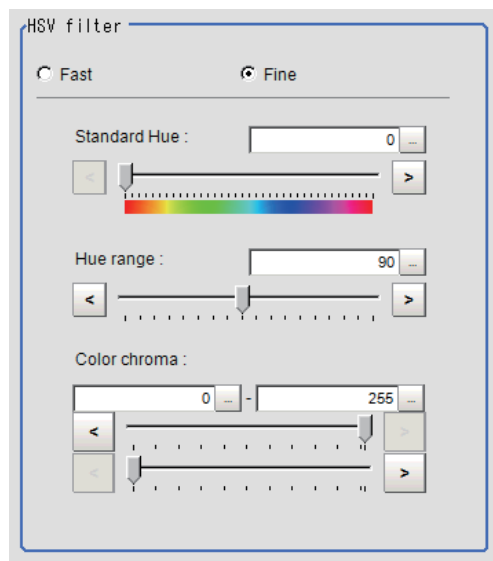
If "Custom filter" is selected, set the "Gain (Red)", "Gain (Green)", and "Gain (Blue)" as necessary.



Setting item	Set value [Factory default]	Description
RGB Filter	<ul style="list-style-type: none"> • [Red filter] • Green filter • Blue filter • Cyan filter • Magenta filter • Yellow filter • Brightness filter(R+G+B) • Brightness filter (R+2G+B) • Custom filter 	This item produces the same effects as using the selected optical filters.
Gain (Red)	0.0001 to 9.9999 [0.3]	RGB gain values when processing with a custom filter. The density of the color component increases as the value increases. This can be set only when "Custom filter" is selected for RGB filter.
Gain (Green)	0.0001 to 9.9999 [0.59]	
Gain (Blue)	0.0001 to 9.9999 [0.11]	

When you choose the HSV option

5 Select the type of filter in the "HSV filter" area.



Setting item	Set value [Factory default]	Description
HSV filter	<ul style="list-style-type: none"> • Fast • [Fine] 	"Fast": The color extraction range is set only by hue. "Fine": Extraction is set by standard hue, hue range, and color chroma.
Standard Hue	[0] to 359	Specify the standard hue (tone) for the HSV filter. The density decreases as the difference in hue from the standard hue (difference in tone) increases.
Hue range	10 to 180 [90]	Specify the hue range (difference in tone) of the HSV filter. The hue difference is obtained by dividing the specified hue range into 255 subranges with the standard hue as the center subrange. The density of the hue outside the hue range is 0. This can only be set when "Fine" is selected.
Color chroma	[0] to [255]	Specify the upper and lower limits for saturation (vividness). This can only be set when "Fine" is selected.

External Reference Tables (Color Gray Filter)

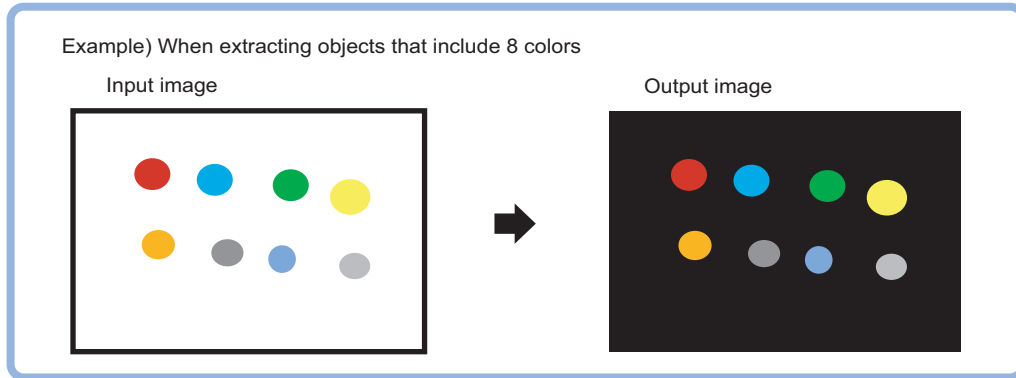
No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgment (unmeasured) 1: Judgment result OK -1: Judgment result NG
100	Filter kind	Set/Get	0: RGB filter 1: HSV filter
101	RGB filter kind	Set/Get	0: Red filter 1: Green filter 2: Blue filter 3: Cyan filter 4: Magenta filter 5: Yellow filter 6: Brightness filter (R+G+B) 7: Brightness filter (R+2G+B) 8: Custom filter
102	Gain (Red)	Set/Get	0.0001 to 9.9999
103	Gain (Green)	Set/Get	0.0001 to 9.9999
104	Gain (Blue)	Set/Get	0.0001 to 9.9999
105	HSV system filter kind	Set/Get	0: Fast 1: Fine
106	Standard Hue	Set/Get	0 to 359
107	Hue range	Set/Get	10 to 180
108	Upper Limit for Saturation	Set/Get	0 to 255
109	Lower Limit for Saturation	Set/Get	0 to 255
200	Transfer source image number	Set/Get	0 to 9
201	Transfer destination image number	Set/Get	0 to 9

Extract Color Filter

The color image is extracted by color. Up to 8 ranges can be set. However, this processing item cannot be used with monochrome images.

Used in the Following Case

- To extract an object of different color.



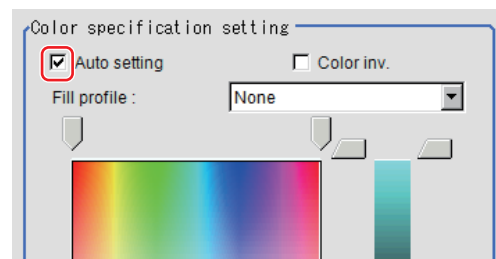
Color Specification (Extract Color Filter)

When connecting a color camera, specify the color to be measured. There are two specification methods: specifying the color to be extracted in the image or specifying the color with the hue, saturation, and brightness values.



This section describes how to specify colors in an image and gives an example of the procedure for finely adjusting with numeric input afterwards.

- 1** In the Item Tab area, click [Color setting].
- 2** Place a check at [Auto setting].
- 3** In the Image Display area, specify the color range you want to detect by dragging the cursor from the upper left corner to the lower right corner of that area.

The color of the specified area is automatically set.



4 As necessary, select Fill profile.

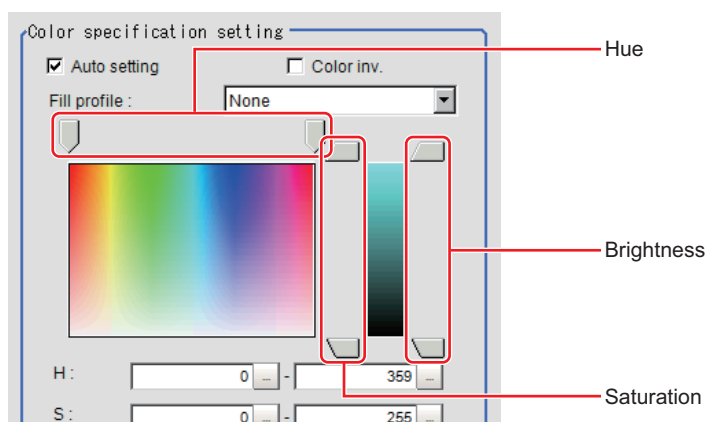
Item	Set value [Factory default]	Description
Fill profile	[None]	The empty section in the center is not filled in.
	Fill outline	<p>In the measurement region, the part between the extracted-color start point and end point in the X-axis direction is measured as having the extracted color. Since filling is applied only to the X-axis direction, the processing is faster than filling up holes.</p> <p>Input image File profile image</p> 
	Filling up holes	<p>The part surrounded by the extracted color, like a doughnut hole, is filled with the extracted color.</p> <p>Input image Image after filling up hole</p> 

5 Finely adjust the hue, saturation, and brightness if necessary.

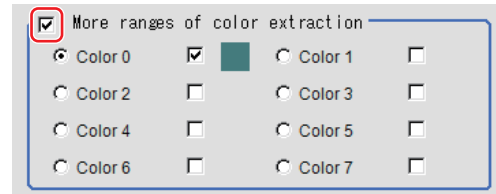
Adjust either by adjusting on the color chart or by inputting numbers.

Item	Set value [Factory default]	Description
H	0 to 359	Specify the color phase (difference of color hues).
S	0 to 255	Specify color saturation (difference of color saturation).
V	0 to 255	Specify the brightness (difference of brightness).
Auto setting	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Specifying the color to be measured on the image automatically sets the hue, saturation, and brightness.
Color inv.	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Everything other than the specified color becomes the measurement target.

About color charts

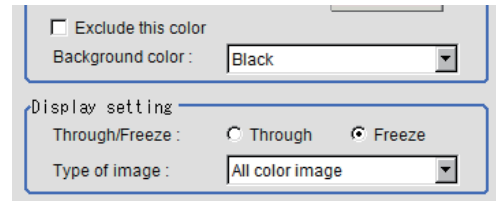


6 To specify multiple colors, place a check at "More ranges of color extraction".



Setting item	Set value [Factory default]	Description
More ranges of color extraction	<ul style="list-style-type: none"> • Checked • [Unchecked] 	If you place a check at this option, you can set up to 8 colors.

7 If necessary, set the display conditions for displayed images.



Setting item	Set value [Factory default]	Description
Exclude this color	<ul style="list-style-type: none"> • Checked • [Unchecked] 	If you place a check at this option, pixels within the HSV range are excluded from color extraction. The priority order for exclusion is that the higher color extraction range numbers are given priority. This setting is disabled if "More ranges of color extraction" is unchecked.
Background color	<ul style="list-style-type: none"> • [Black] • White • Red • Green • Blue 	The background section outside the extracted image is filled with the specified colors. The background colors that can be set depend on the display settings. When "Color selected image" is selected, the background color can be set for each selected color. When All color image is selected, the background color for color extraction range 0 is used.
Through/Freeze	<ul style="list-style-type: none"> • Through • [Freeze] 	For Through, the latest image from the camera is always displayed; for Freeze, the image that was scanned in the immediately preceding measurement is displayed.
Type of image	<ul style="list-style-type: none"> • Measurement image • [All color image] • Color selected image • Binary image 	This sets the state of the image to display.

Region Setting (Extract Color Filter)

Use a rectangle to specify the area where the model is searched.

Instead of measuring the entire input image, narrowing the measurement area shortens the processing time.

1 In the Item Tab area, click [Region setting].

2 Click [Edit].

The figure setting area is displayed.

3 Specify the area in which to search for the model.

The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.

4 Click [OK].

The area to measure is registered.

Output Image (Extract Color Filter)

Setting item	Set value [Factory default]	Description
Output image setting	<ul style="list-style-type: none"> • [Binary image] • All color image 	This sets the state of the image output.

Key Points for Test Measurement and Adjustment (Color Extraction Filter)

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number.	Explanation of image to be displayed
0	Color extraction image
1	Measurement image

Measurement Results for Which Output Is Possible (Extract Color Filter)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Extract Color Filter)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
120	Fill profile	Set/Get	0: OFF 1: Fill profile 2: Filling up holes
121	Inverse area presence	Set/Get	0: OFF 1: ON
122	Image kind	Set/Get	0: Measurement image 1: All color image 2: Selection color image 3: Binary image
123	Multiple selections	Set/Get	0: Multiple selections disabled 1: Multiple selections enabled
124	Output image	Set/Get	0: Binary image 1: All color image
130 + 10 × N (N = 0 to 7)	Usage flag [N] (N = 0 to 7)	Set/Get	0: Not used 1 : Used Default value 1 only for [0] Default value 0 for all others
131 + 10 × N (N = 0 to 7)	OR/NOT setting [N] (N = 0 to 7)	Set/Get	0: OR 1: NOT
132 + 10 × N (N = 0 to 7)	Register the max. color hue [N] (N = 0 to 7)	Set/Get	0 to 359

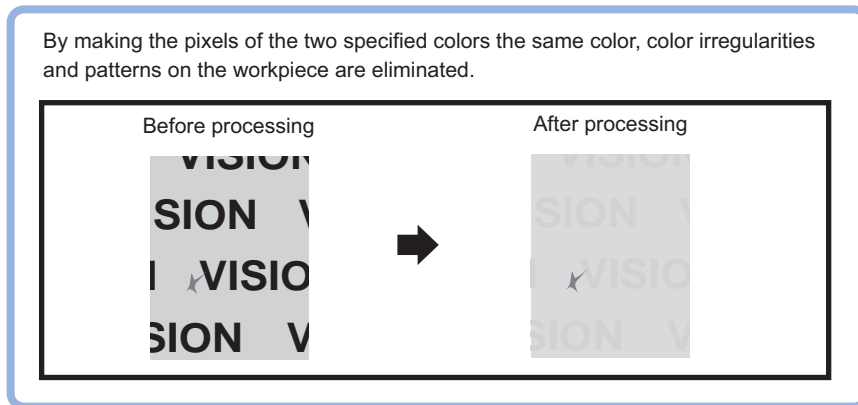
No.	Data name	Set/Get	Data range
133 + 10 × N (N = 0 to 7)	Register the min. color hue [N] (N = 0 to 7)	Set/Get	0 to 359
134 + 10 × N (N = 0 to 7)	Register the max. color saturation [N] (N = 0 to 7)	Set/Get	0 to 255
135 + 10 × N (N = 0 to 7)	Register the min. color saturation [N] (N = 0 to 7)	Set/Get	0 to 255
136 + 10 × N (N = 0 to 7)	Register the max. color brightness [N] (N = 0 to 7)	Set/Get	0 to 255
137 + 10 × N (N = 0 to 7)	Register the min. color brightness [N] (N = 0 to 7)	Set/Get	0 to 255
138 + 10 × N (N = 0 to 7)	Register the BG color [N] (N = 0 to 7)	Set/Get	0: Black 1 : White 2: Red 3: Green 4: Blue
5000	RGB value pixel density data	Set/Get	Characteristic application The RGB value for the coordinate specified during set up is saved in measurement data. When acquiring, the data saved in measurement data is returned.
5001	Selected color extraction range	Set/Get	Characteristic application The color extraction range number selected during set up is saved in measurement data. When acquiring, the data saved in measurement data is returned.

Anti Color Shading

This filter eliminates color unevenness in the image. Unevenness is eliminated either by converting the two specified colors toward the color midway between them or by converting one of the two specified colors to approach the other. However, this processing item cannot be used with monochrome images.

Used in the Following Case

- This is used when a work that would be expected to have uniform color has a non-uniform image due to the effect of tilting, uneven paint, or the like.



Filter Setting (Anti Color Shading)

This item sets the filter.

- 1 In the Item Tab area, click [Filter setting].
- 2 In the "Display" area, click [Change display] to switch between camera image types.

The displayed contents of the Image Display area will be switched.

Setting item	Set value [Factory default]	Description
Display	Through image display	The latest image is always input from the camera and displayed.
	[Freeze image display]	The image that was scanned in the immediately preceding measurement is displayed.

- 3 The section with color contrast on the image is enclosed.

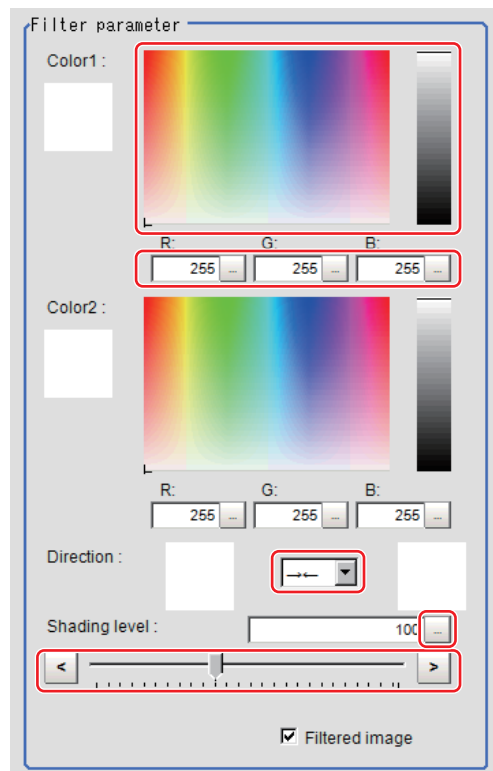
The image with the contrast suppressed is displayed.



4 Adjust the color, conversion direction, and Anti Color Shading level as necessary.

The picked up 2 colors are displayed at Color 1 and Color 2.

Fine adjustments can also be made to the R, G, and B values and on the color chart.



Setting item	Set value [Factory default]	Description
Color1	<ul style="list-style-type: none"> • R 0 to [255] • G 0 to [255] • B 0 to [255] 	The most separate two colors are picked up from the specified region.
Color2	<ul style="list-style-type: none"> • R 0 to [255] • G 0 to [255] • B 0 to [255] 	The sections corresponding to these colors in the region are converted to the color midway between the two.
Direction	<ul style="list-style-type: none"> • [→←] ∞→ ∞← 	Select the conversion method for the set Color 1 and Color 2. →←: Color 1 and Color 2 are converted to the color midway between the two. →: Color 1 is converted to Color 2. ←: Color 2 is converted to Color 1.
Shading level	0 to 255 [100]	Set the level for suppressing color contrast. The larger this value, the less the color contrast.

5 As necessary, set the display image.



Setting item	Set value [Factory default]	Description
Filtered image	<ul style="list-style-type: none"> • [Checked] • Unchecked 	To display the original image, uncheck here.

Region Setting (Anti Color Shading)

It is possible to target the entire screen, but restricting the range can shorten the processing time.

- 1** In the Item Tab area, click [Region setting].
- 2** Use the Drawing tools to specify the measurement region.
- 3** In the figure setting area, click [OK].

The area in which to perform filtering is registered.

Key Points for Test Measurement and Adjustment (Anti Color Shading)

The following content is displayed in the "Detail result" area as text.

Displayed item	Description
Judge	Judgement result

Measurement Results for Which Output Is Possible (Anti Color Shading)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Anti Color Shading)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
100	Specified color R1	Set/Get	0 to 255
101	Specified color G1	Set/Get	0 to 255
102	Specified color B1	Set/Get	0 to 255
103	Specified color R2	Set/Get	0 to 255
104	Specified color G2	Set/Get	0 to 255
105	Specified color B2	Set/Get	0 to 255
106	Direction	Set/Get	0: Color 1→←Color 2 1: Color 1→Color 2 2: Color 1←Color 2
107	Shading level	Set/Get	0 to 255
108	Filtered image	Set/Get	0: OFF 1: ON

Stripes Removal Filter II

Eliminating a striped pattern or other background makes it possible to stably extract just the defect without it being affected by the background.

Used in the Following Case

- To eliminate vertical stripes, or horizontal stripes from the target.

• Thin stripe pattern suppression filter

○ When the filter size is larger than the stripes and the defects are larger than the filter size, vertical filter stripes can be removed.

✕ If the filter size is smaller than the stripes, the stripes cannot be removed.

Filter shape (size) Defect

• Thick stripe pattern suppression filter

○ If defects are larger than the filter size and smaller than the stripe width, the stripes can be removed.

✕ If the filter size is larger than the stripe width, the stripes cannot be removed.

Filter shape (size) Defect

Important

- This processing item is for monochrome only. When using a color camera, insert a color gray filter before this processing item. If a color image is input, it is NG (incompatible image).

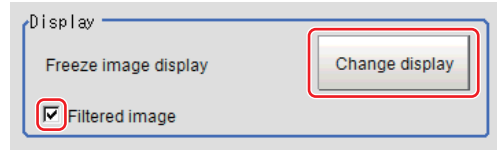
Filter Setting (Stripes Removal Filter II)

This item sets the filter.

1 In the "Item Tab" area, click [Filter Setting].

2 In the "Display" area, click [Change display] to switch between camera image types.

The displayed contents of the image display area will be switched.



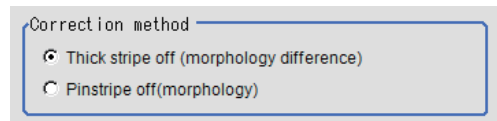
Setting item	Setting value [Factory default]	Description
Display	Through image display	The latest image is always input from the camera and displayed.
	[Freeze image display]	The image that was scanned in the immediately preceding measurement is displayed.
Filtered image	<ul style="list-style-type: none"> • [Checked] • Unchecked 	To display the original image, uncheck here.

3 Set the target image.



Setting item	Setting value [Factory default]	Description
Target	Camera image	The camera input image that has not been subject to filtering is subject to compensation as is.
	[Prev. unit image]	Images to which processing is applied in units even before the "Stripes Removal Filter II" being set are the targets.

4 Set the correction method.

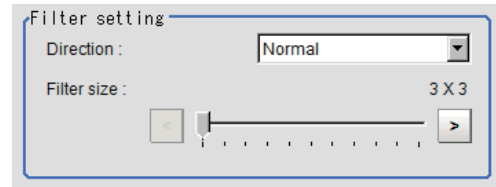


Setting item	Setting value [Factory default]	Description
Correction method	[Thick stripe off]	This item sets the filter size based on the size of the expected defect and removes the striped pattern.
	Pinstripe off	This item sets the filter size based on the width of the stripes and removes the striped pattern.

Important

- When this setting is changed, the filter setting and the detail setting will be reset to the factory default values.

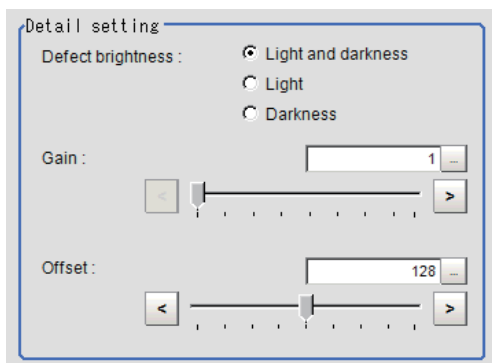
5 This sets the filter settings.



Setting item	Setting value [Factory default]	Description
Direction	<ul style="list-style-type: none"> • [Normal] • Vertical • Horizontal • Upper right • Lower right 	Specify the filter direction.
Filter Size	3 to 63 [3]	<p>The value is set based on the size of the defect to be extracted or the size of the stripes. Only an odd number value can be specified.</p> <p>For "Pinstripe off": Select a filter size larger than the width of the striped pattern.</p> <p>For "Thick stripe off": Select a filter size larger than the size of the defect to be detected.</p>

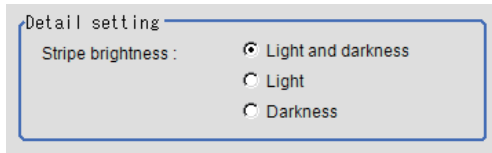
6 Set the details.

Correction method: For "Thick stripe off"



Setting item	Setting value [Factory default]	Description
Defect brightness	<ul style="list-style-type: none"> • [Light and darkness] • Light • Darkness 	Set the brightness of defects to be extracted from the background. To detect both white defects and black defects, select "Light and darkness".
Gain	1 to 63 [1]	Adjust the contrast of an image after the pattern suppression. Specifying a larger value emphasizes the density differences within the image.
Offset	0 to 255 [128]	Adjust the brightness of an image after the pattern suppression. Specifying a larger value increases the brightness of the image.

Correction method: For "Pinstripe off"



Setting item	Setting value [Factory default]	Description
Stripe brightness	<ul style="list-style-type: none"> • [Light and darkness] • Light • Darkness 	This item selects the color of the stripes to be deleted.

Region Setting (Stripes Removal Filter II)

It is possible to target the entire screen, but restricting the range can shorten the processing time.

- 1** In the Item Tab area, click [Region setting].
- 2** Use the drawing tools to specify the measurement region.
- 3** In the figure setting area, click [OK].

The area in which to perform filtering is registered.

Test Measurement (Stripes Removal Filter II)

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image No.	Explanation of image to be displayed
0	Filtered image

External Reference Tables (Stripes Removal Filter II)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (not yet measured) 1: Judgement result OK -1: Judgement result NG
120	Correction method	Set/Get	0: Thick striped pattern suppression 1: Thin striped pattern suppression
121	Direction	Set/Get	0: Vertical and horizontal 1: Horizontal 2: Vertical 3: Slant (upper right) 4: Slant (lower right)
122	Filter Size	Set/Get	3 to 63
123	Defect brightness	Set/Get	0: Light and dark 1: Light 2: Dark
124	Gain	Set/Get	1 to 63
125	Offset	Set/Get	0 to 255
200	Transfer source image number	Set/Get	0 to 9
201	Image number after transfer	Set/Get	0 to 9

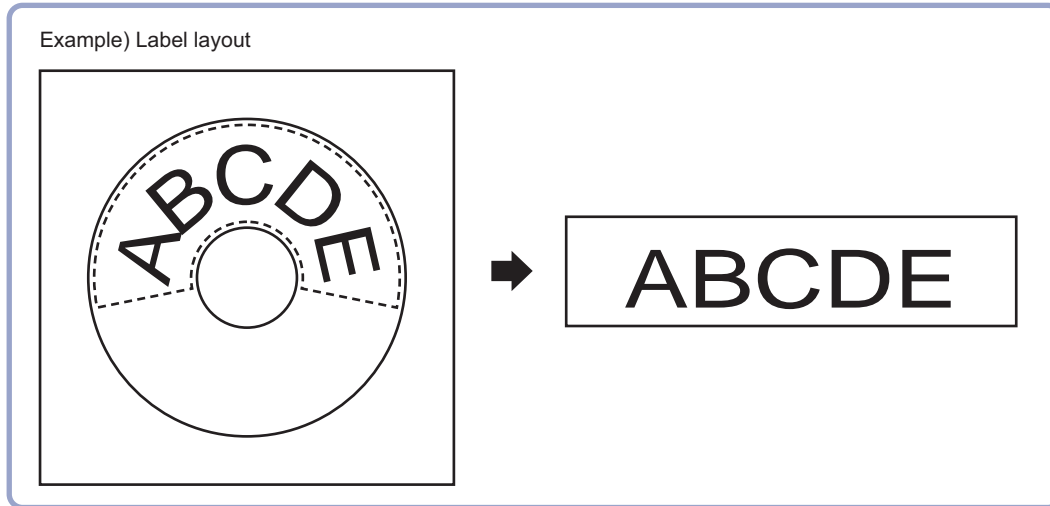
No.	Data name	Set/Get	Data range
202	Target image	Set/Get	0: Camera input image 1: Previous. unit image
203	Display image	Set/Get	0: Display the image before processed. 1: Display the image after processed.

Polar Transformation

Wide circle and fan shape images are transformed in polar coordinates and converted into orthogonal coordinate images. The converted image is a measurement object for processing units in later stages.

Used in the Following Case

- This is used for judging characters printed around the circumference of caps and the like.



Important

- When using polar transformation and a position list, display with [Polar Transformation].
If the image is displayed with [Camera Image Input] or the like before the [Polar Transformation], the graphic is not displayed correctly.

Region Setting (Polar Transformation)

Set a region enclosing the character string that is lined up along a circle.

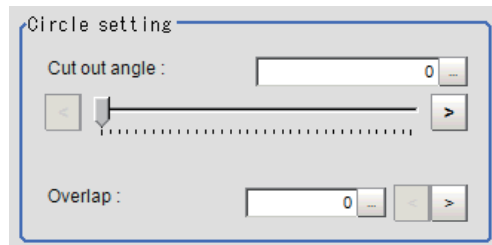
- 1** Use the Drawing tools to specify the measurement region.
- 2** Enclose the characters in the image.



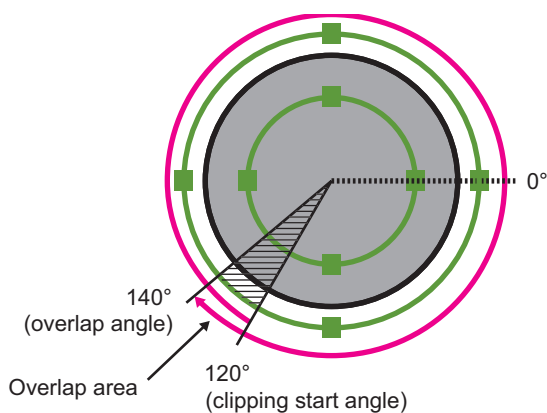
- 3** In the figure setting area, click [OK].

The measurement region is registered and displayed in the Image Display area.

4 As necessary, set the items in the "Circle setting" area.



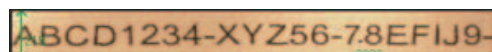
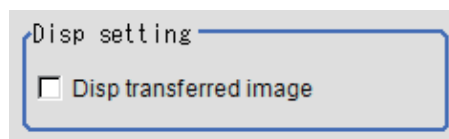
Setting item	Set value [Factory default]	Description
Cut out angle	[0] to 359	Set the angle for starting extraction when the figure is a wide circle.
Overlap	[0] to 180	Set the angle for overlap when the figure is a wide circle. The overlap angle indicates the end angle of the measurement range. This is set to measure extra overlapping from the start angle. Basically, set this larger than the extraction angle.



5 Place a check at [Disp transferred image].

Displays the polar transformed image in the image window.

The vertical and horizontal image sizes (in pixels) are displayed overlapped.



Key Points for Test Measurement and Adjustment (Polar Transformation)

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number	Explanation of image to be displayed
0	Post-conversion image
1	Measurement image

Measurement Results for Which Output Is Possible (Polar Transformation)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Polar Transformation)

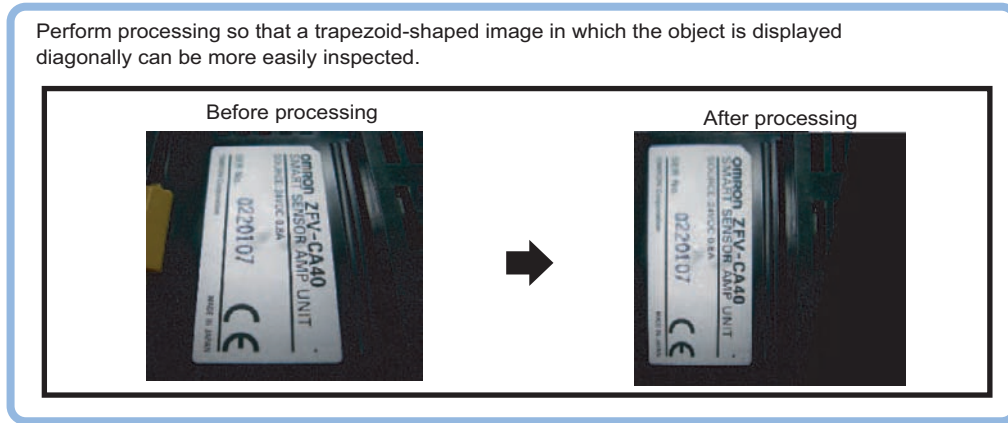
No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
120	Cut out angle	Set/Get	0 to 359
122	Overlap	Set/Get	0 to 360
123	Disp transferred image	Set/Get	0: Image prior to transfer 1: Image after transfer

Trapezoidal Correction

If measurement is performed with the measurement object tilted or the camera tilted, the input image is converted to orthogonal coordinates.

Used in the Following Case

- Processing a trapezoidal image shot tilted to make it easier to inspect



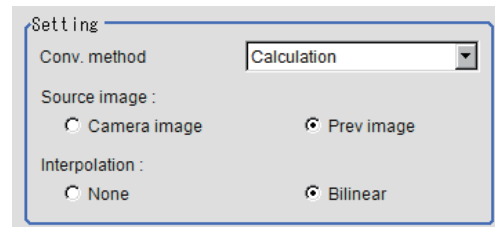
Conversion Method (Trapezoidal Correction)

Set the input image conversion method.

- 1 In the Item Tab area, click [Conv. method].

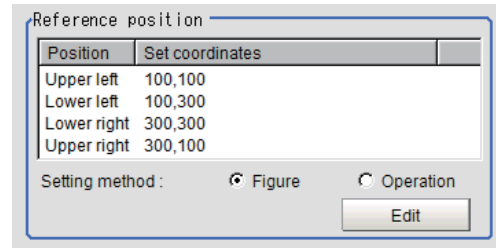
When making a new setting, you do not need to click [Conv. method].

- 2 As necessary, set the parameters.



Setting item	Set value [Factory default]	Description
Conv. method	<ul style="list-style-type: none"> • 4 unit reference • [Calculation] 	<p>Set the expression used for image conversion</p> <p>4-unit reference: The parameters are set referencing the reference coordinates and measurement coordinates for the immediately preceding 4 units.</p> <p>Confirm that the units are arranged according to the upper left coordinate, lower left coordinate, lower right coordinate and upper right coordinate. To modify the expression for the reference position and measurement position set with 4-unit reference, select the Expression.</p>
Source image	<ul style="list-style-type: none"> • Camera image • [Prev image] 	Set the image to be compensated.
Interpolation	<ul style="list-style-type: none"> • None • [Bilinear] 	Set the interpolation between pixels for image conversion. To reduce conversion time more than raise compensation precision, set "None".

3 Set the reference position.



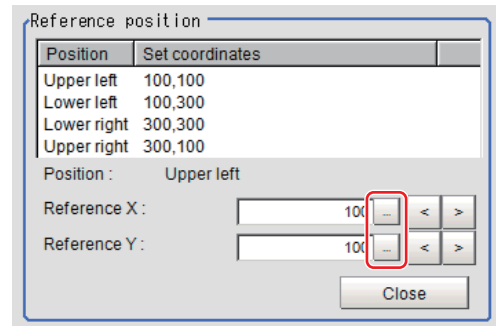
Setting item	Set value [Factory default]	Description
Setting method	<ul style="list-style-type: none"> • [Figure] • Operation 	<p>Set the method for setting the reference position.</p> <p>When fixed value is selected, specify the vertex position on the image.</p> <p>After setting with an expression, if the setting is changed to a fixed value, the result of the expression is reflected as a fixed value.</p>

When Operation is chosen

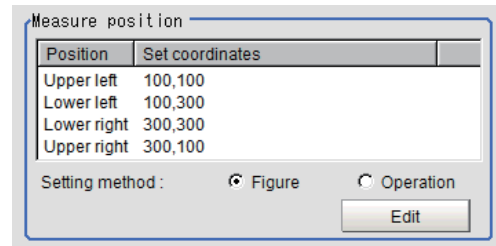
Click [Edit].

Click [...] and set the expression.

Reference: ▶ Layout of Setting Expression Window (p.535)

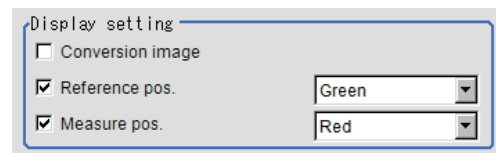


4 Set the measure position.



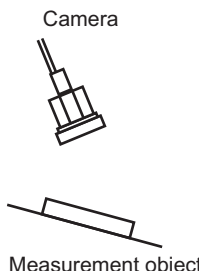
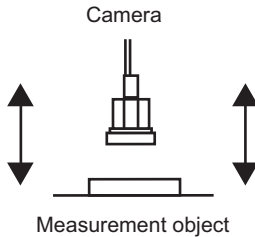
Setting item	Set value [Factory default]	Description
Setting method	<ul style="list-style-type: none"> • [Figure] • Operation 	<p>Set the method for setting the measurement position.</p> <p>When fixed value is selected, specify the vertex position on the image.</p> <p>After setting with an expression, if the setting is changed to a fixed value, the result of the expression is reflected as a fixed value.</p>

5 Set the display settings as necessary.



Example of Setting

The setting examples for the reference position and measurement position.

	Pattern 1	Pattern 2
Setting item	Camera: Fixed tilt Work: No chatter 	Camera: Fixed vertical Work: Chatter 
Reference position	Figure	Figure
Measure position	Figure	Operation

Pattern 1:

When the camera is installed tilted and there is no chatter in the work

- See the Reference: ► **Setting Example for when There Is No Chatter in the Work (p.456) for when there is no chatter in the work.**

Pattern 2:

When the camera is installed vertical and there is chatter in the work

- See the Reference: ► **Setting Example for when There Is Chatter in the Work (p.457) for when there is chatter in the work.**

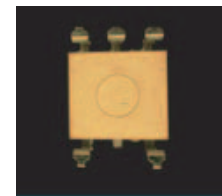
Setting Example for when There Is No Chatter in the Work

Even when there is a mechanical structure and the camera cannot be installed from the front, 4-point position information can be used to compensate for distortion in the image.

When you specify the four points used for distortion compensation and specify the positions where those four points should be as reference positions, the parameters for distortion compensation are set automatically. Each time a measurement is made, the distortion is automatically compensated for using these parameters.

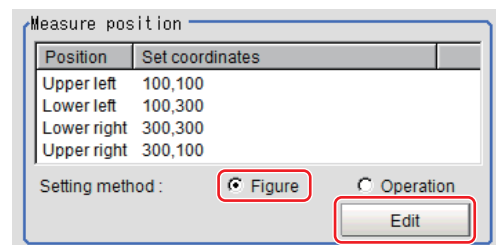


Crooked image



After revision

- 1 Select "Figure" for the measure position and click Edit.



- 2** Specify on the image which four points whose information to use for distortion compensation.



- 3** Select "Figure" for the reference position and click Edit.

Position	Set coordinates
Upper left	100,100
Lower left	100,300
Lower right	300,300
Upper right	300,100

Setting method : Figure Operation

- 4** On the image, specify which information for the positions where the four specified points should be to use for distortion compensation.

When concrete coordinate positions are known or to measure them and find accurate positions, it is possible to set "Expression" and substitute measurement values from other processing units.



- 5** Place a check at "Conversion image" in the display settings and check the image in which the distortion has been compensated for.

Display setting

Conversion image

Reference pos. Green

Measure pos. Red

Setting Example for when There Is Chatter in the Work

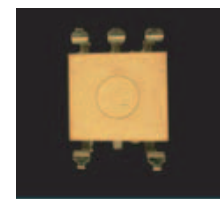
Even when there is chatter in the work during transport and error is generated in the distance to the camera, 4-point position information can be used to compensate for distortion in the image.

Preset in other units so that when you specify the positions where the four points used for distortion compensation should be as reference positions, the 4-point position information can be acquired.

Compensate for the distortion in the image so that the position information for the four points aligns with the reference positions when measurements are made. With this setting, 3D position deviation can be compensated for.



Crooked image



After revision

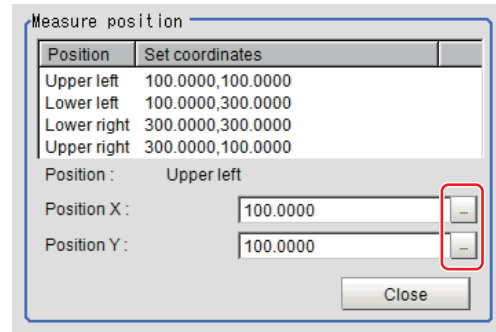
- 1** Select "Operation" for the measure position and click Edit.

Position	Set coordinates
Upper left	100.0000,100.0000
Lower left	100.0000,300.0000
Lower right	300.0000,300.0000
Upper right	300.0000,100.0000

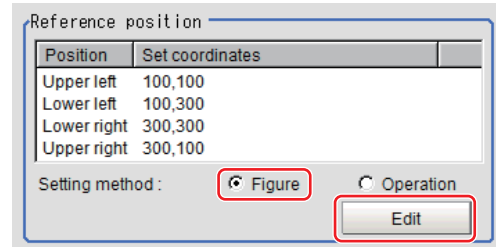
Setting method : Figure Operation

2 Specify with the expression which four points to use the information of for compensation.

Set the processing unit for acquiring the positions before the processing unit for trapezoidal distortion compensation.



3 Select "Figure" for the reference position and click Edit.

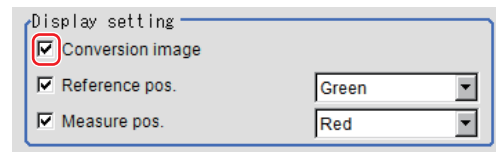


4 On the image, specify which information for the positions where the four specified points should be to use for distortion compensation.

When concrete coordinate positions are known or to measure them and find accurate positions, it is possible to set "Operation" and substitute measurement values from other processing units.



5 Place a check at "Conversion image" in the display settings and check the image in which the distortion has been compensated for.



Region Setting (Trapezoidal Correction)

Specify as a rectangle the range for compensating in the image.

Narrowing the compensation range instead of measuring the entire input image shortens the processing time.

1 In the Item Tab area, click [Region setting].

2 Click [Edit].

The figure setting area is displayed.

3 Specify the area in which to search for the model.

The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.

4 Click [OK].

The area to measure is registered.

Key Points for Test Measurement and Adjustment (Trapezoidal Correction)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number	Explanation of image to be displayed
0	Post-conversion image

Measurement Results for Which Output Is Possible (Trapezoidal Correction)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Trapezoidal Correction)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
120	Interpolation mode	Set/Get	0: None 1: Linear interpolation
121	Method	Set/Get	0: See unit 4 1: Expression
122	Input image	Set/Get	0: Camera image 1: Prev image
123	Reference position setting method	Set/Get	0: Figure 1: Expression
124	Measurement position setting method	Set/Get	0: Figure 1: Expression
125	Reference coordinate display	Set/Get	0 : Not displayed 1 : Displayed
126	Reference coordinate display color	Set/Get	0: Black 1 : White 2: Red 3: Green 4: Blue
127	Measurement coordinate display	Set/Get	0 : Not displayed 1 : Displayed
128	Measurement coordinate display color	Set/Get	0: Black 1 : White 2: Red 3: Green 4: Blue
129	Filtered image	Set/Get	0: Disp input image 1: Filtered image

No.	Data name	Set/Get	Data range
200 + N (N = 0 to 3)	X coordinate of the reference coordinate N	Set/Get	Character string for expression (*)
300 + N (N=0 to 3)	Y coordinate of the reference coordinate N	Set/Get	Character string for expression (*)
400 + N (N = 0 to 3)	X coordinate of the measurement coordinate N	Set/Get	Character string for expression (*)
500 + N (N = 0 to 3)	Y coordinate of the measurement coordinate N	Set/Get	Character string for expression (*)

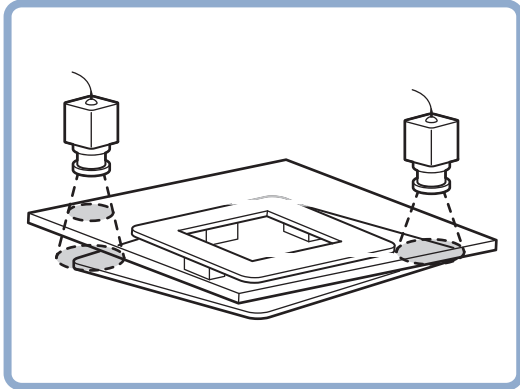
* Numerical data can also be set in the data setting processing items for the processing unit, etc.

Machine Simulator

You can simulate the movement of an alignment mark and verify the operation of alignment-related processing items without an actual stage or robot. Actual coordinate system conditions (origin position, magnification, axis angle) can be set as desired in this processing item group. For the origin position, set the rotating center of the stage.

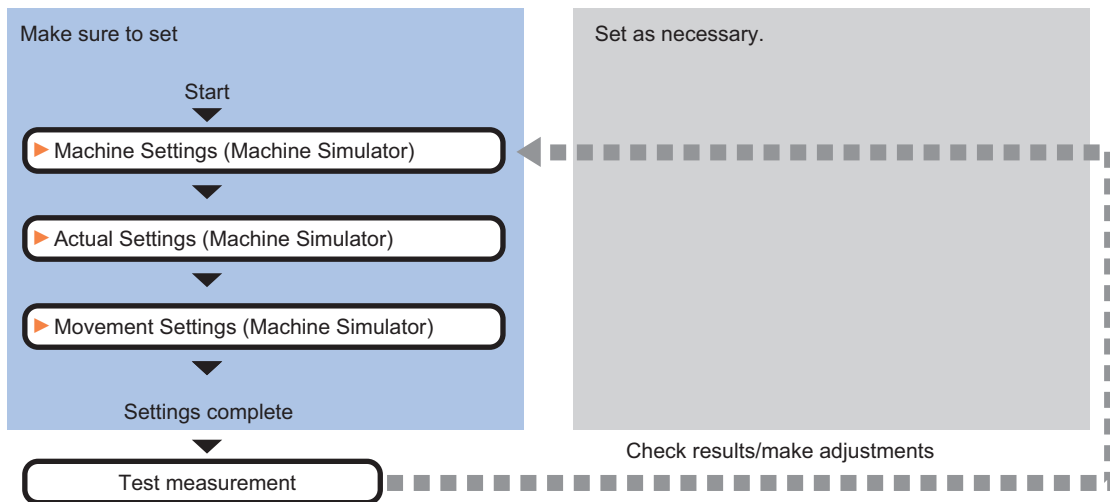
Used in the Following Case

- Check alignment operations before connecting the stage
- Create scene data before connecting the stage



Settings Flow (Machine Simulator)

Set up the machine simulator with the following steps.



List of Machine Simulator Items

Item name	Description
Machine setting	Select a processing item (stage data or robot data) under which external device information needed for calculation of travel distance of the actuator is held. Reference: ▶ Machine Setting (Machine Simulator) (p.462)
Actual setting	Set the origin position, magnification and the axis angle of the real coordination system. Set the conditions for the coordinate system of the stage or robot used. Reference: ▶ Actual Setting (Machine Simulator) (p.463)
Movement setting	Set the movement amount of each axis needed to move the image. When simulating a movement from other than the origin return position, also set the current axis position. Reference: ▶ Movement Setting (Machine Simulator) (p.464)

Machine Setting (Machine Simulator)

Select a processing item (stage data or robot data) under which external device information needed for calculation of travel distance of the actuator is held.

1 In the Item Tab area, click [Machine setting].

2 Select a processing unit holding external device information.

Information of the selected processing unit is displayed in the reference data display area.

Machine setting data

Reference scene No. : Present scene

Reference unit No. : 1.Stage data

Setting item	Setting value [Factory default]	Description
Reference scene No.	[Present scene] Scenes 0 to 127	Select a scene number (stage data or robot data) under which external device information needed for calculation of travel distance of the actuator is held.
Reference unit No.	-	From among the referenced scene numbers, select a processing item (stage data or robot data) under which external device information needed for calculation of travel distance of the actuator is held.

Note

- If the number of scenes is increased using the scene group conversion tool, the maximum value that can be selected in "Reference scene No." changes.

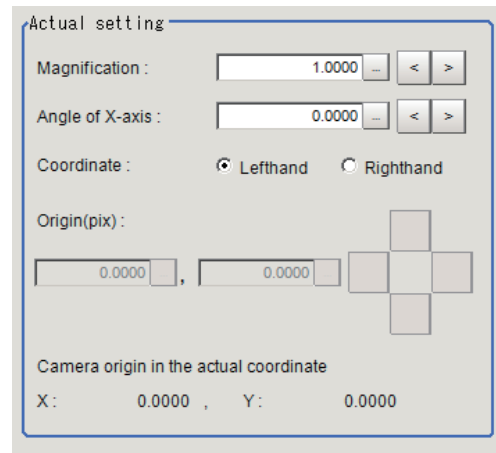
Actual Setting (Machine Simulator)

Set the conditions for the actual coordinate system (origin position, magnification, axis angle). Set the conditions for the coordinate system of the stage or robot used.

1 In the Item Tab area, click [Actual setting].

2 In the "Actual setting" area, set the conditions for the actual coordinate system.

When a setting is changed, a correction result is displayed in the Image Display area and the origin position (unit: mm) of actual coordinates is updated.



Setting item	Setting value [Factory default]	Description
Magnification	0.0001 to 9.9999 [1.0000]	Specify the ratio of 1 pixel to the actual dimensions.
Angle of X-axis	-180.0000 to 180.0000 [0.0000]	If the movement amount of each axis is 0, set the X axis angle in the actual coordinate system of the camera.
Coordinate	<ul style="list-style-type: none"> [Lefthand] [Righthand] 	Select the coordinate system to be used. Lefthand: Clockwise is forward when specifying the angles. Righthand: Counter-clockwise is forward when specifying the angles.
Origin(pix)	-99999.9999 to 99999.9999 [0.0000]	Set the origin position of actual coordinate as camera coordinates (pix). For the origin position, set the rotating center position of the stage.

Movement Setting (Machine Simulator)

Set the movement amount of each axis needed to move the image. When simulating a movement from other than the origin return position, also set the current axis position.

1 In the Item Tab area, click [Movement setting].

2 Select the target image to move in the "Source image" area.

Setting item	Setting value [Factory default]	Description
Source image	Camera image	The unfiltered input image from the camera directly becomes the target image to move.
	[Previous image]	The image filtered by a processing item before the "External device simulator" currently set before this item.

3 Set the current position of each axis in the "Current setting" area.

The setting items vary depending on the type of stage or robot.

Setting item	Setting value [Factory default]	Description
X-axis	-99999.9999 to 99999.9999 [0.0000]	Set the current position of each stage/robot axis.
Y-axis	-99999.9999 to 99999.9999 [0.0000]	
theta-axis	-180.0000 to 180.0000 [0.0000]	

4 In the "Axis movement" area, set the movement amount of each axis.

The setting items vary depending on the type of stage or robot.

Setting item	Setting value [Factory default]	Description
X-axis movement	-99999.9999 to 99999.9999 [0.0000]	Set the movement amount of each stage/robot axis.
Y-axis movement	-99999.9999 to 99999.9999 [0.0000]	
theta-axis movement	-180.0000 to 180.0000 [0.0000]	

Key Points for Test Measurement and Adjustment (Machine Simulator)

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image.	Explanation of image to be displayed
0, 2 to 31	Measurement image (Same when a list of positions is displayed)
1	Input image

Key Points for Adjustment

Adjust the setting parameters referring to the following points.

The image is not compensated correctly

State	Parameter to be adjusted	Troubleshooting
The corrected image is completely different	Actual setting	The conditions for the actual coordinate system (origin position, magnification, axis angle) may not be set correctly. Check for input errors. In factory default, the real coordination system is same as the camera coordination.
The corrected image is slightly different	Movement setting	The current axis position may not be set correctly. Set this condition when simulating a movement from other than the origin return position. The current axis position is a parameter required for accurate calculation of the travel distance of the actuator.

Other

State	Parameter to be adjusted	Troubleshooting
The reference unit number is <"None"> and cannot be selected.	Machine setting	Check if the reference scene number is selected correctly. Check if stage data processing items or robot data processing items are registered in the selected reference scene.
The reference unit number does not change during flow editing.	Machine setting	The system is designed this way. While a scene other than the current scene is referenced, the reference unit number does not change according to the editing of the flow. Change the flow so that the current scene will be referenced, or set the reference unit number again.

Measurement Results for Which Output Is Possible (Machine Simulator)

The following values can be output using processing items related to results output. It is also possible to refer to measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Machine Simulator)

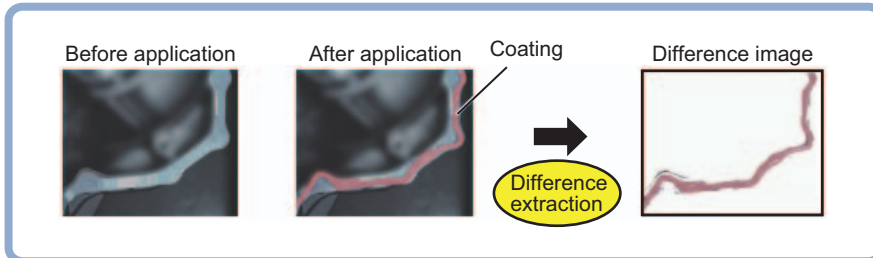
No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
120	Scene No.	Set/Get	-1: Current scene referred 0 to 9999: Pointed scene referred
121	Unit No.	Set/Get	-1: No reference 0 to 9999: Pointed unit referred
122	Magnification	Set/Get	0.0001 to 9.9999
123	Angle of X-axis	Set/Get	-180.0000 to 180.0000
124	Coordinate	Set/Get	0: Lefthand 1: Righthand
125	Origin X (pix)	Set/Get	-99999.9999 to 99999.9999
126	Origin Y (pix)	Set/Get	-99999.9999 to 99999.9999
127	Source image	Set/Get	0: Camera image 1: Previous image
128	X-axis movement	Set/Get	-99999.9999 to 99999.9999
129	Y-axis movement	Set/Get	-99999.9999 to 99999.9999
130	θ -axis movement	Set/Get	-180.0000 to 180.0000
131	θ -axis (linear drive)	Set/Get	-99999.9999 to 99999.9999
132	U-axis movement	Set/Get	-99999.9999 to 99999.9999
133	V-axis movement	Set/Get	-99999.9999 to 99999.9999
134	W-axis movement	Set/Get	-99999.9999 to 99999.9999
135	R-axis movement	Set/Get	-99999.9999 to 99999.9999
136	Current X-axis movement	Set/Get	-99999.9999 to 99999.9999
137	Current Y-axis movement	Set/Get	-99999.9999 to 99999.9999
138	Current θ -axis movement	Set/Get	-180.0000 to 180.0000
139	Current θ -axis	Set/Get	-99999.9999 to 99999.9999
140	Current U-axis movement	Set/Get	-99999.9999 to 99999.9999
141	Current V-axis movement	Set/Get	-99999.9999 to 99999.9999
142	Current W-axis movement	Set/Get	-99999.9999 to 99999.9999
143	Current R-axis movement	Set/Get	-99999.9999 to 99999.9999
144	Origin X in the actual coordinate	Set/Get	-
145	Origin Y in the actual coordinate	Set/Get	-

Image Subtraction

The registered model image and measurement image are compared and only the different pixels are extracted and converted to an image.

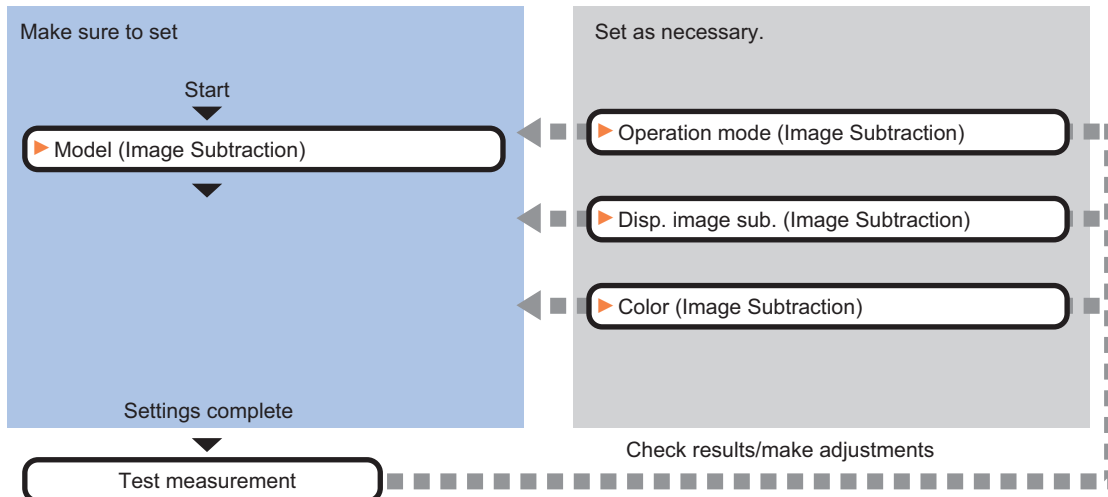
Used in the Following Case

- When you want to extract from the image only the parts that are to be inspected



Settings Flow (Image Subtraction)

Follow the steps below to set up difference extraction.



List of Image Subtraction Items

Item name	Description
Operation mode	This item sets the operation mode during measurement. Reference: ▶ Operation Mode (Image Subtraction) (p.468)
Model	This item registers model images. Reference: ▶ Model (Image Subtraction) (p.469)
Disp. image sub.	This item sets the method for extracting the difference images. Reference: ▶ Disp. Image Sub. (Image Subtraction) (p.470)
Color	This item sets the background color of the difference images. Reference: ▶ Color (Image Subtraction) (p.471)

Operation Mode (Image Subtraction)

Set how to switch model registration and difference extraction at the time of measurement.

- 1 In the Item Tab area, click [Operation mode].
- 2 Set each item in the "Operation mode" area.

Setting item	Setting value [Factory default]	Description
Subtraction mode	[Subtract only]	Always use the initially registered model image to perform difference extraction processing. The model is registered in the setting mode and difference extraction processing is always performed with respect to the captured measurement target image in the operation mode.
	DI Register	Check the DI input (4 to 0) during measurement processing and register the model only when the signal input corresponds to the pattern set under "Input DI Code". In all other cases, difference extraction processing is performed. A model image is captured and registered during operation, after which difference processing is performed.
	Subt./Reg.	Execution of model registration - difference extraction processing is switched every time measurement is performed. Select this option when performing second measurement using the logging image. The model image and measurement image can be read alternately, meaning that model registration - measurement can be performed offline.
Input DI Code	00000 to 11111 (binary numbers) [00000]	Set the DI input pattern you want to use for model registration. This option can be set only when "Subtraction mode" is set to "DI Register".
Subt./Reg. Set	<ul style="list-style-type: none"> • [Register model] • Subtract 	Select whether to perform model registration or difference extraction when measurement is performed next time. This option can be set only when "Subtraction mode" is set to "Subt./Reg.".

Important

- When the operation mode is Single-line High-speed mode or Non-stop Adjustment mode, "Subtraction mode: Subt./Reg." cannot be used.

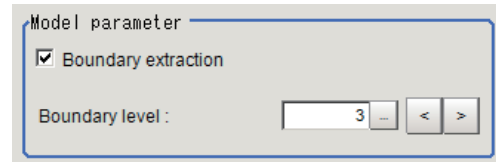
- 3 Click [OK].

Model (Image Subtraction)

Register the region you want to compare, as a model.

Normally the background image (image not showing what you want to extract at the time of measurement) is registered as a model.

- 1** In the Item Tab area, click [Model].
- 2** In the "Model parameter" area, set model parameters.



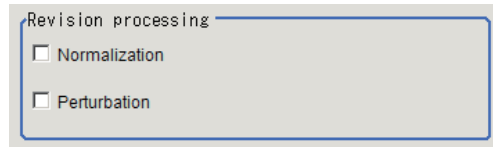
Setting item	Setting value [Factory default]	Description
Boundary extraction	[Checked]	Under this method, the difference image is used directly. If the registered model and coated object can be captured at the exact same position, there is no offsetting of images and therefore noises will not generate due to difference extraction. In this case, more accurate measurement is possible when the difference image is used directly.
	Unchecked	Under this method, pixels corresponding to specified values are deleted from the outline of the extracted difference image. This option is set to remove noises resulting from offset images when the inspection object or camera has moved slightly. Since information of several pixels are deleted from the difference image, the measured coating width becomes smaller than the actual width.
Boundary level	0 to 9 [3]	Set the degree of assimilation of variations around boundaries. Depending on the "Boundary inspection" value, the meaning is different.

- 3** Click [Edit].
- 4** Use the Drawing tools to set the model registration range.
- 5** Click [OK].

Disp. Image Sub. (Image Subtraction)

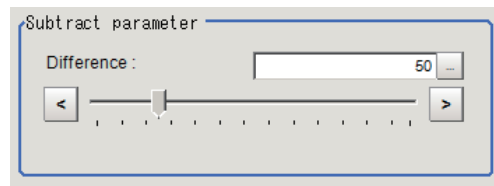
Set the method for extracting the difference images. Set this option when the difference cannot be extracted correctly such as when there are a lot of noises.

- 1 In the Item Tab area, click [Disp. image sub.].
- 2 Set each item in the "Revision processing" area.



Setting item	Setting value [Factory default]	Description
Normalization	<ul style="list-style-type: none"> • Checked • [Unchecked] 	<p>Select whether to perform normalization based on the brightness in the registered model.</p> <p>When "Checked" is selected, the density is adjusted before difference extraction, so that the difference extraction is not affected by changes in the total image brightness or the lighting fluctuations.</p> <p>When normalization is performed on the measured objects without patterns, the total image brightness is changed and the extraction does not work correctly.</p>
Perturbation	<ul style="list-style-type: none"> • Checked • [Unchecked] 	<p>If you place a check here, in order to prevent mistaken detection of slight positional deviation of measurement objects as differences, corrections are made before difference extraction.</p> <p>However, this requires more processing time.</p>

- 3 Set the difference judgement value in the "Subtract parameter" area.

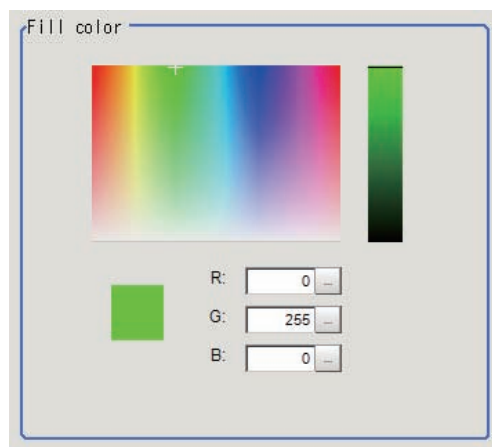


Setting item	Setting value [Factory default]	Description
Difference	0 to 255 [50]	<p>This sets the reference grayscale used when calculating differences between the model and the inspected object image.</p> <p>Pixels with a difference equal to or greater than Difference are converted to white and other pixels are converted to black, so that only defects are converted to white and measured.</p>

Color (Image Subtraction)

Set the background color of the difference image (color of the parts not recognized as differences).
Set this option if necessary, such as when the background color is similar to the color of the extraction object and the object is difficult to see.

- 1** In the Item Tab area, click [Color].
- 2** Specify the desired background color on the color chart.



- 3** Finely adjust the R, G and B if necessary.

Adjust either by adjusting on the color chart or by inputting numbers.

Setting item	Setting value [Factory default]	Description
R	0 to 255 [0]	Set a value for R (red).
G	0 to 255 [255]	Set a value for G (green).
B	0 to 255 [0]	Set a value for B (blue).

Key Points for Adjustment (Image Subtraction)

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the extraction is unstable

State	Parameter to be adjusted	Troubleshooting
Affected by lighting change	Disp. image sub.	Turn ON the normalization. The density is adjusted before difference extraction, so that the extraction is not affected by changes in the total image brightness or the lighting fluctuations.

When the processing speed is slow

Parameter to be adjusted	Troubleshooting
Model	Make the area to register as the model as small as possible.
Disp. image sub.	Turn OFF the perturbation processing.

When judgement is NG

State	Parameter to be adjusted	Troubleshooting
The judgement is NG (insufficient memory)	Model	Make the area to register as the model as small as possible.

Measurement Results for Which Output Is Possible (Image Subtraction)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Image Subtraction)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
120	Boundary inspection	Set/Get	0: OFF 1: ON
121	Boundary level	Set/Get	0 to 9
122	Normalization	Set/Get	0: OFF 1: ON
123	Perturbation processing	Set/Get	0: OFF 1: ON
124	Difference	Set/Get	0 to 255
125	Model register	Get only	0: Not registered 1: Registered
126	Fill profile color R	Set/Get	0 to 255
127	Fill profile color G	Set/Get	0 to 255
128	Fill profile color B	Set/Get	0 to 255
129	Extract image	Set/Get	0: OFF 1: ON
130	Operation mode	Set/Get	0: Always extract differences 1: Register at DI input 2: Switch at every measurement
131	Model registration DI input	Set/Get	0 to 31
132	Next measurement processing	Set/Get	0: Model 1: Difference extraction

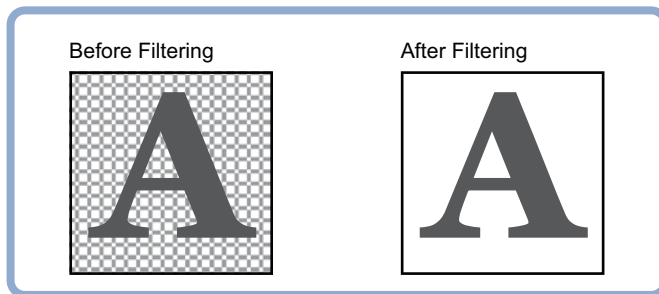
Advanced filter

Process the images acquired from cameras in order to make them easier to measure. This processing item consolidates existing image conversion filtering into one processing item and adds extra functions.

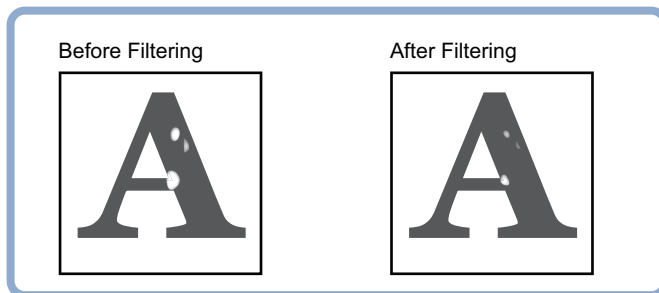
Up to 16 filtering processes can be performed under this processing item. You can also select and save four filtered images from among those undergoing the 16 filtering processes.

Used in the Following Case

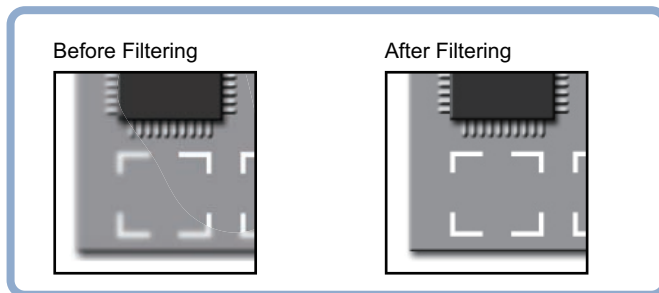
- **Cutting out unnecessary background images to exclude them from the measurement region**



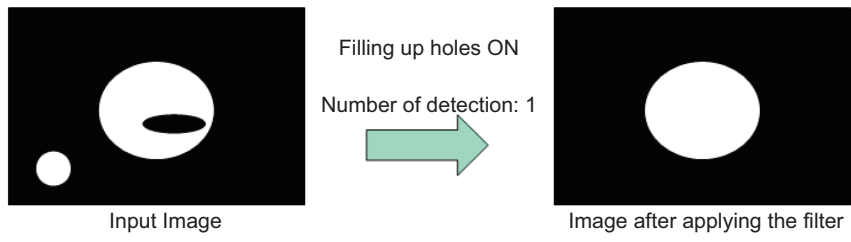
- **When noise is to be removed**



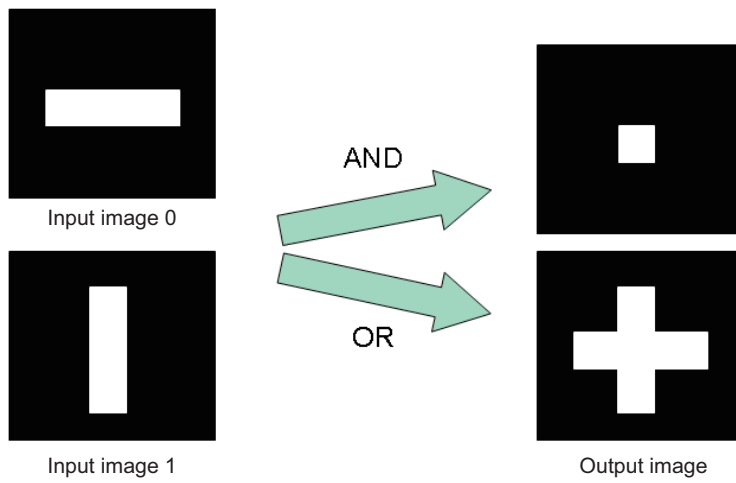
- **When the edges of marks you want to find cannot be found even though other edges have been extracted.**



- When labeling processing is applied to extract labels matching specific conditions



- When calculation processing is performed on multiple images

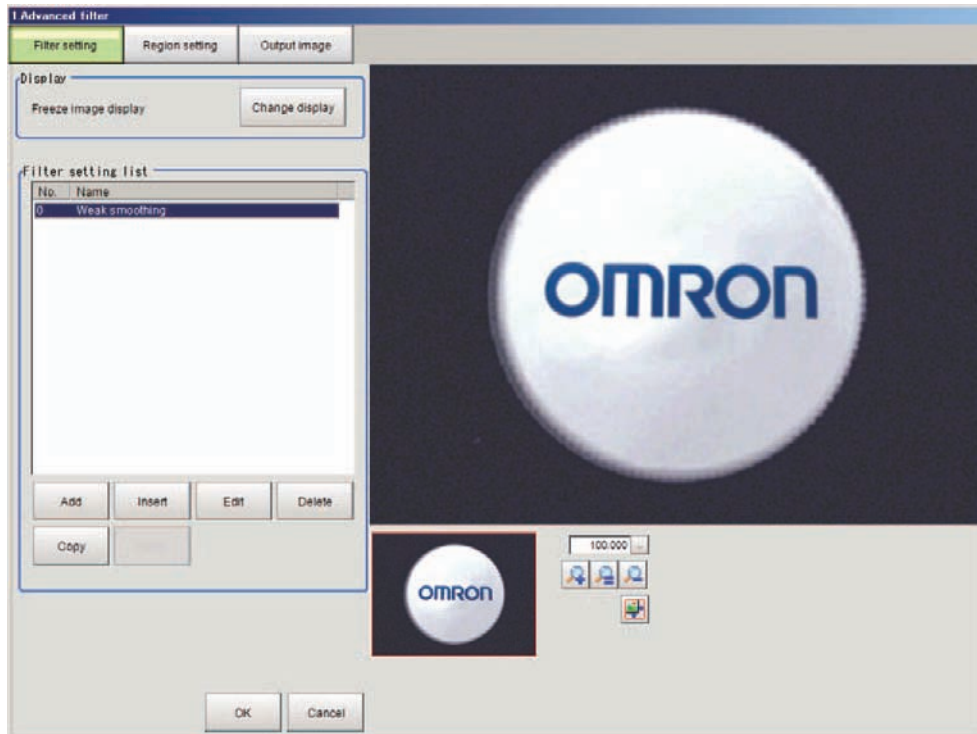


Filtering Setting Screen

Add, edit or delete filters used for filtering.

16 filtering processes can be performed within this processing item.

24 types of filtering are available, so set each applicable type.



Set each item according to the condition of the image.

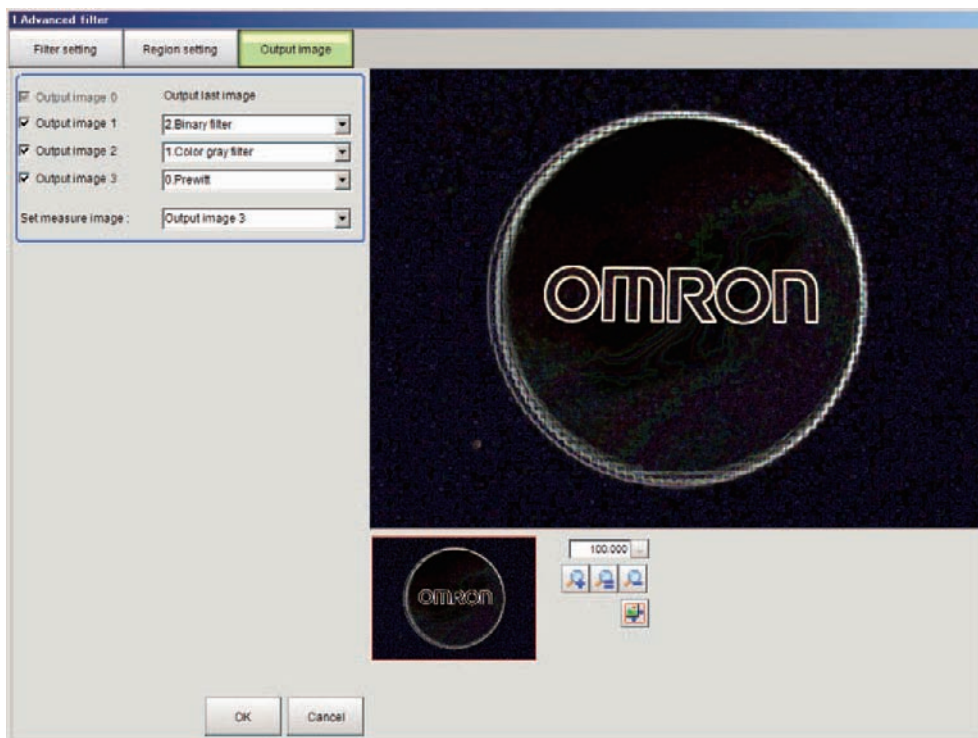
- 1** In the Item Tab area, click [Filter setting].
- 2** Click [Change display] in the "Display" area to switch the display mode.
- 3** A list of filters currently set is displayed in the "Filter setting list" area. Up to 16 filters can be added.
- 4** Click [Add], [Insert], [Edit], [Delete] or [Copy] in the "Filter setting list" area to add, insert, edit, delete or copy filters.
- 5** The displayed screen changes according to the selected state or clicking of each button in the "Filter setting list" area.

Setting item	Setting value [Factory default]	Description
Change display	<ul style="list-style-type: none"> • [Freeze image display] • Through image display 	The image displayed in the Image Display area is changed. <ul style="list-style-type: none"> • Freeze image display: The image that was input in the immediately preceding measurement is displayed. • Through image display: The latest image is always input from the camera and displayed.
Add	-	Add the filter. Clicking this button displays the filter details selection screen. The added filter is registered at the very end.
Insert	-	Insert the filter. Clicking this button displays the filter details selection screen. The inserted filter is registered at the selected location and the subsequent filters move one position down, respectively.

Setting item	Setting value [Factory default]	Description
Edit	-	Open the Edit Filter screen. The setting screens are different depending on the filter type.
Delete	-	Delete the filter. Clicking this button displays the deletion confirmation screen.
Copy	-	Copy the filter. Clicking this button selects the filter to copy from. When copy is performed, the Paste button becomes enabled.
Paste	-	Paste the copied filter. The filter is pasted at the selected location and the subsequent filters move one position down, respectively.

6 After setting a filter, specify the region to apply the filter to in [Region Setting] in the Item Tab area.

7 After setting a region, set the image to be output in [Output image] in the Item Tab area.

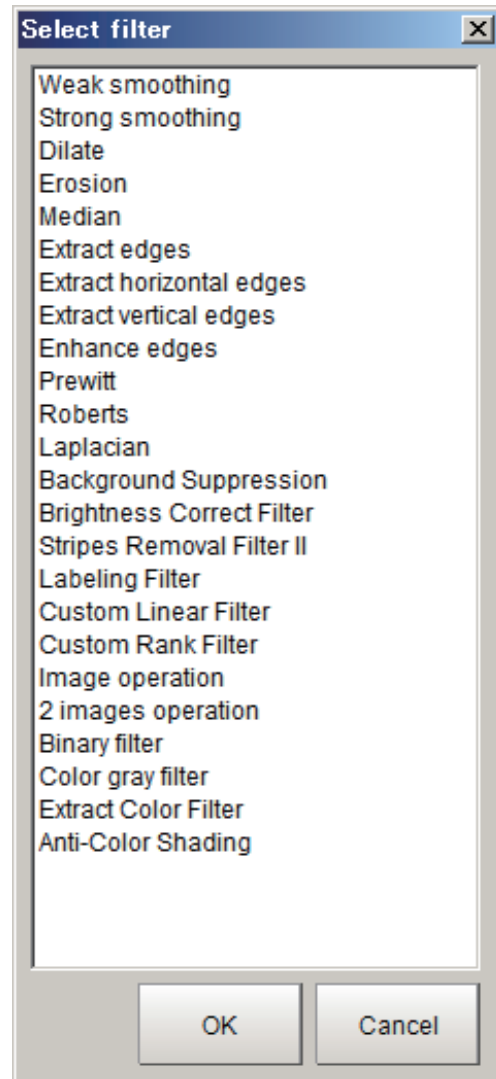


Setting item	Setting value [Factory default]	Description
Output image 0	Enabled (fixed)	Display the last image. (Fixed)
Output images 1 to 3 check boxes	<ul style="list-style-type: none"> • [Disabled] • Enabled 	Set whether to enable or disable the images displayed under Output images 1 to 3.
Output images 1 to 3	<ul style="list-style-type: none"> • [None] 	Set the filtered images to be displayed under Output images 1 to 3. Select an image from the list of filter settings currently registered.
Set measure image	Output image 0 to 3 [Output image 0]	Set the image to be displayed as the measurement image. Select one of Output images 0 to 3.

Filter Details Selection Screen

A specific filter is selected here.

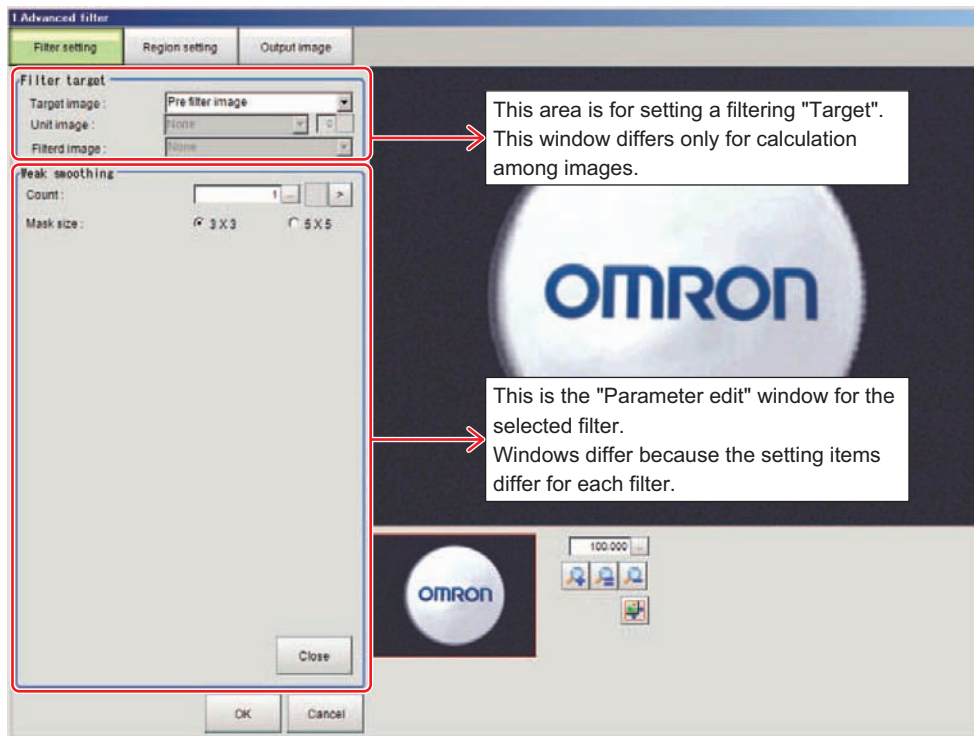
The Filter Edit screen changes according to the selected filter.



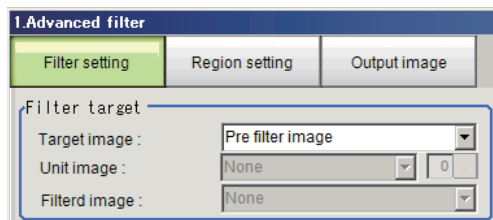
- 1** Clicking [Add] or [Insert] in the "Filter setting list" area displays the filter details selection screen.
- 2** The displayed screen changes according to the selected details of the filter.

Filter Edit Screen

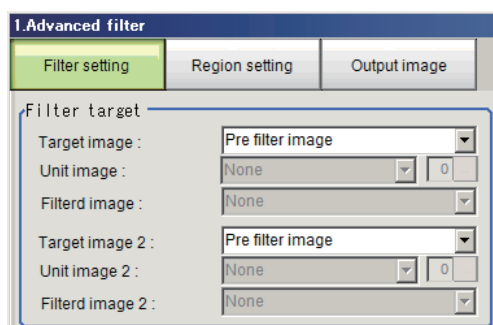
The image to be filtered are selected and filter parameters are set here.



■ "Filter target" area for other than by calculation between images



■ "Filter target" area for calculation between images

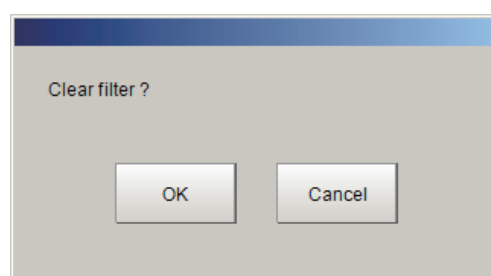


- 1** Select the image to be filtered from among the target images in the "Filter target" area. Display of the following items relating to processing unit images and filtered images is enabled depending on the selected image.
- 2** Select the processing unit from among the processing unit images in the "Filter target" area. The processing unit image number part is enabled depending on the selected processing unit.
- 3** Select the filtered image to be filtered from among the filtered images in the "Filter target" area.

Setting item	Setting value [Factory default]	Description
Target image	<ul style="list-style-type: none"> • Measure image • [Pre filter image] • Other unit image • Filtered image 	<p>Display and select the type of target image to be filtered.</p> <ul style="list-style-type: none"> • Measure image : Process the measurement images for the processing unit. • Pre filter image : The last filtered image is filtered. Filter 0 represents the measurement image. : Filter 1 or subsequent number represents the image completing the filtering immediately before it. • Other unit image : The image of the specified processing unit is filtered. : When this type is selected, setting items relating to processing unit images are enabled. • Filtered image : The specified filtered image is filtered.
Unit image	<ul style="list-style-type: none"> • [OFF] • Unit 	<p>Select the processing unit associated with the target image to be filtered. This option is enabled only when "Target image" is "Other unit image". Selectable processing units include "Image input related" and "Image conversion related" processing items. If the selected processing unit has no image, a black, invalid screen is displayed.</p>
Processing unit image No.	<ul style="list-style-type: none"> • [0] • Image number 	<p>Specify the image number under the processing unit associated with the target image to be filtered. This option is enabled only when "Target image" is "Processing unit image". If the processing unit does not have the image of the specified number, a black, invalid screen is displayed.</p>
Filtered image	<ul style="list-style-type: none"> • [OFF] • Filtered image 	<p>Select the filtered image to be filtered. This option is enabled only when "Target image" is "Filtered image". Only an image filtered before this processing item can be selected.</p>
Target image 2	<ul style="list-style-type: none"> • Measurement image • [Prev. unit image] • Processing unit image • Filtered image 	<p>Same as the target image. This option can be selected only when calculation between images is set.</p>
Unit image 2	<ul style="list-style-type: none"> • [OFF] • Unit 	<p>Same as the processing unit image. This option can be selected only when calculation between images is set.</p>
Processing unit image No. 2	<ul style="list-style-type: none"> • [0] • Image number 	<p>Same as the processing unit image No. This option can be selected only when calculation between images is set.</p>
Filtered image 2	<ul style="list-style-type: none"> • [OFF] • Filtered image 	<p>Same as the filtered image. This option can be selected only when calculation between images is set.</p>

Deletion Confirmation Screen

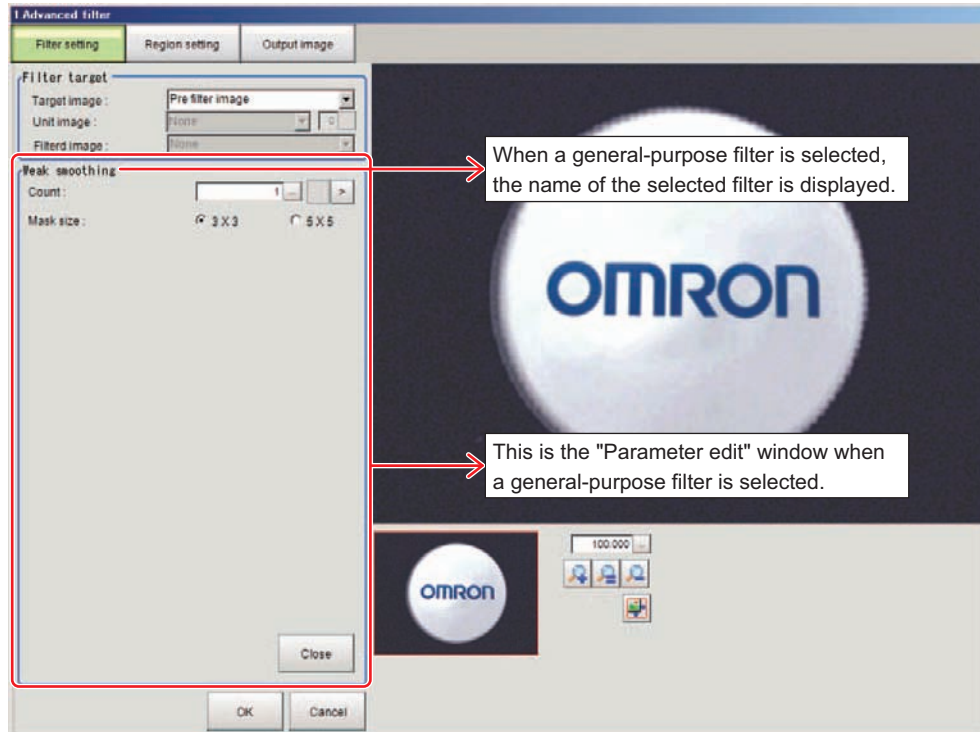
This confirmation screen appears before the selected filter is deleted.



Setting of General-purpose Filter

- 1 Selecting one of the following general-purpose filters on the filter details selection screen displays the "Parameter edit" area for the selected filter.

General-purpose filters include "Weak smoothing", "Strong smoothing", "Dilate", "Erosion", "Median", "Extract edges", "Extract horizontal edges", "Extract vertical edges" and "Enhance edges".



- 2 For the setting details, refer to the applicable filtering provided as an existing processing item.

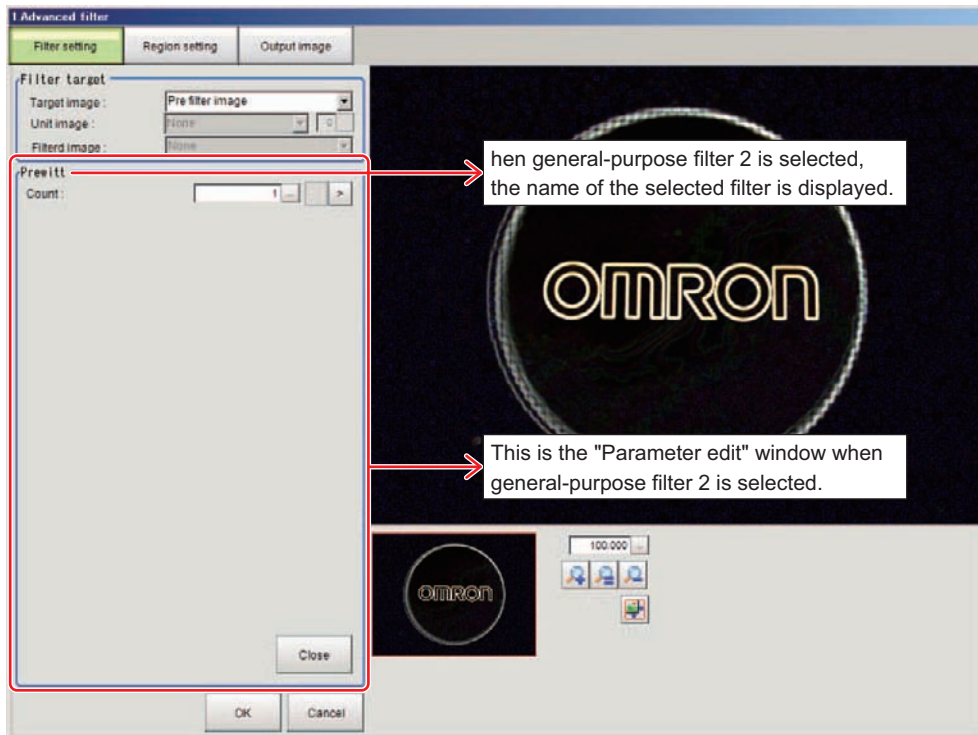
The specifics are the same, except that setting of background suppression level is not available.

Setting item	Setting value [Factory default]	Description
Count	• 1 to 9 [1]	Select the number of times the filter will be applied.
Mask size	• [3 × 3] • 5 × 5	Select the filter size to be applied to the filter. Increasing the filter size absorbs the negative effects of more pixels nearby.

Setting of General-purpose Filter 2

- 1 Selecting one of the following general-purpose filters 2 on the filter details selection screen displays the "Parameter edit" area for the selected filter.

General-purpose filters 2 include "Prewitt," "Roberts" and "Laplacian".



- 2 Select the number of times the filter will be applied.

Setting item	Setting value [Factory default]	Description
Count	• 1 to 9 [1]	Select the number of times the filter will be applied.

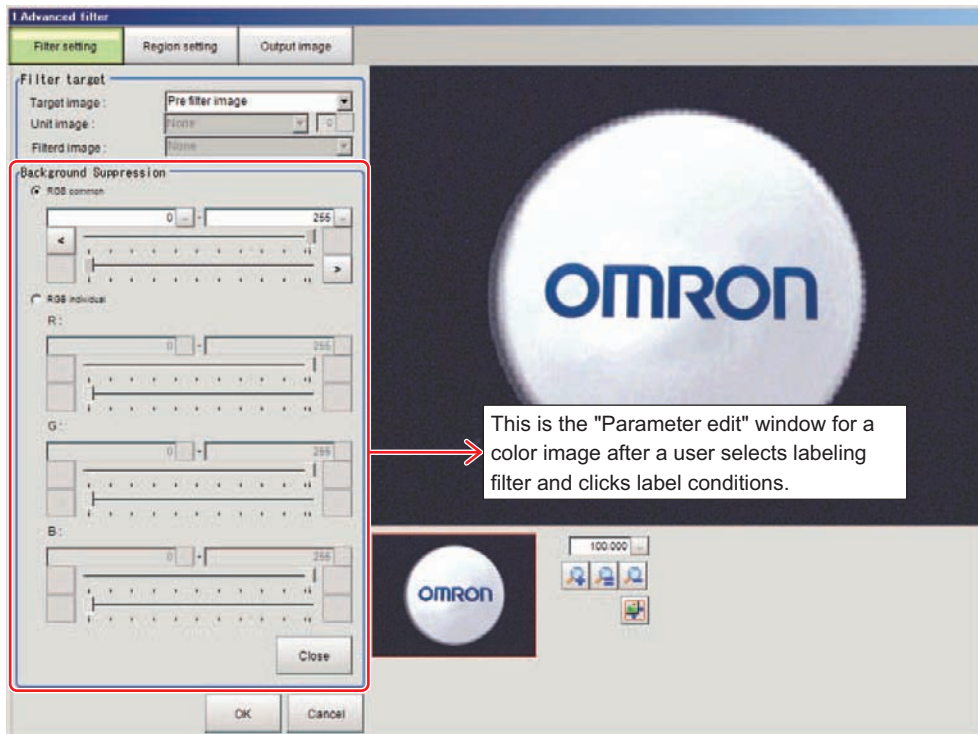
Filter options and examples

Types of filtering	Filtering description	Example
Prewitt	Image boundaries (bright/dark) are extracted by suppressing noises.	Defect inspection
Roberts	Suppresses noise and extracts the boundary lines of the image (light and shade). This type of filtering is effective for diagonal boundary lines.	Defect inspection
Laplacian	Extracts the boundary lines of the image (light and shade). This type of filtering is effective for consistent extraction of boundary lines.	Defect inspection Edge positioning

Background Suppression Setting (Color Image)

- 1 Selecting "Background Suppression" on the filter details selection screen displays the "Parameter edit" area for the selected filter.

■ Color image



- 2 Select whether to set an adjustment of background suppression level that applies commonly to R/G/B or set an adjustment that applies individually to R/G/B, and make adjustment.
- 3 For the setting details, refer to the applicable background suppression provided as an existing processing item.

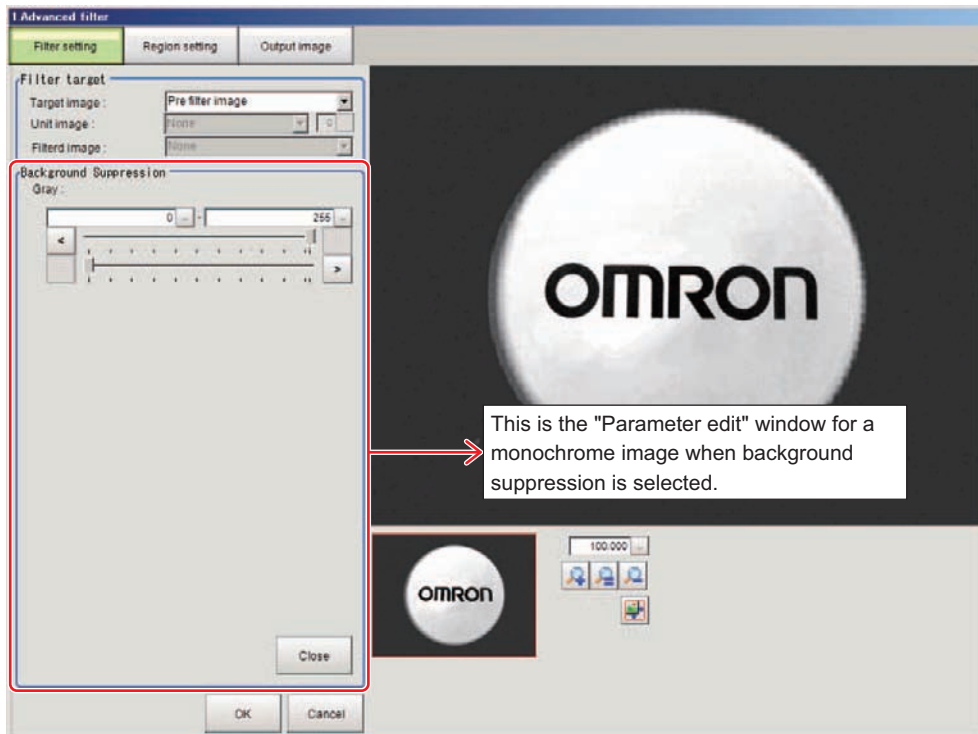
Setting item	Setting value [Factory default]	Description
RGB common/ RGB individual	<ul style="list-style-type: none"> • [RGB common] • RGB individual 	<p>Select how to adjust the background suppression level. Selecting a given method enables/disables each item on the parameter edit screen.</p> <ul style="list-style-type: none"> • RGB common : When "RGB common" is selected, the upper/lower limits set in the RGB common setting area are enabled. • RGB individual : When "RGB individual" is selected, the upper/lower limits set individually for R/G/B in the RGB individual setting area are enabled.
RGB common lower limit/ upper limit	[0] to [255]	<p>The upper/lower limits for the background suppression level that apply commonly to RGB are set. A value between 0 and 255 can be set for each level. These items are enabled only when "RGB common" is selected.</p>
RGB individual R individual lower limit/ upper limit	[0] to [255]	<p>The upper/lower limits for the background suppression level that apply individually to R are set. A value between 0 and 255 can be set for each level. These items are enabled only when "RGB individual" is selected.</p>

Setting item	Setting value [Factory default]	Description
RGB individual G individual lower limit/upper limit	[0] to [255]	The upper/lower limits for the background suppression level that apply individually to G are set. A value between 0 and 255 can be set for each level. These items are enabled only when "RGB individual" is selected.
RGB individual B individual lower limit/upper limit	[0] to [255]	The upper/lower limits for the background suppression level that apply individually to B are set. A value between 0 and 255 can be set for each level. These items are enabled only when "RGB individual" is selected.

Background Suppression Setting (Monochrome Image)

- 1 Selecting "Background Suppression" on the filter details selection screen displays the "Parameter edit" area for the selected filter.

■ Monochrome image



- 2 Adjust the background suppression level.
- 3 For the setting details, refer to the applicable background suppression provided as an existing processing item.

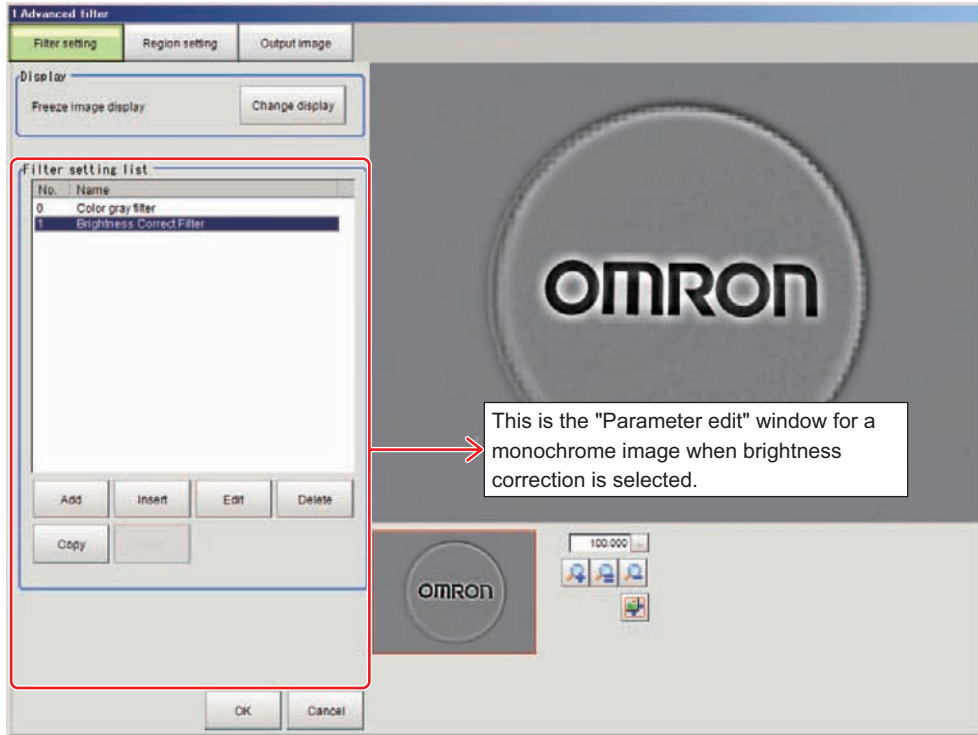
Setting item	Setting value [Factory default]	Description
Gray	[0] to [255]	The upper and lower limits for the background suppression level are set. A value between 0 and 255 can be set for each level.

Brightness Correct Filter Setting (Monochrome Image)

This filter is applied only to monochrome images.

- 1 Selecting "Brightness Correct Filter" on the filter details selection screen displays the "Parameter edit" area for the selected filter.

■ Monochrome image



- 2 For the setting details, refer to the applicable Brightness Correct Filter provided as an existing processing item.

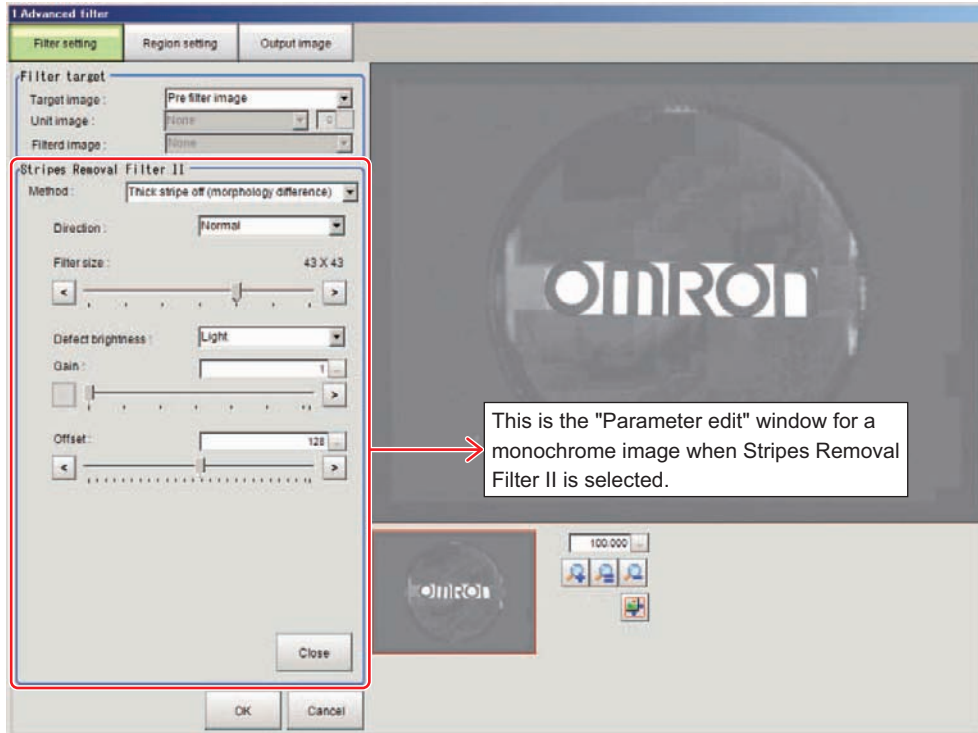
Setting item	Setting value [Factory default]	Description
Uneven removal	<ul style="list-style-type: none"> • [Uneven removal OFF] • Uneven removal ON 	Select whether to enable/disable uneven removal processing. <ul style="list-style-type: none"> • Uneven removal OFF • Uneven removal ON : When "Uneven removal ON" is selected, the filter direction and filter size settings are enabled.
Direction	<ul style="list-style-type: none"> • [Normal] • Horizontal • Vertical 	Make selection according to the direction in which to remove unevenness. Select the direction vertical to the direction in which unevenness changes. This option is enabled when "Uneven removal ON" is selected.
Filter size	3 to 255 [3]	Set the filter size. Specify a larger value to match the size of the unevenness. An odd number value can be specified. This option is enabled when "Uneven removal ON" is selected.
Gain	1 to 63 [1]	Adjust the contrast of an image after the correction. Specifying a larger value emphasizes the density differences within the image.
Offset	0 to 255 [128]	Adjust the brightness of an image after the correction. Specifying a larger value increases the brightness of the image.

Stripes Removal Filter II Setting (Monochrome Image)

This filter is applied only to monochrome images.

- 1 Selecting "Stripes Removal Filter II" on the filter details selection screen displays the "Parameter edit" area for the selected filter.

■ Monochrome image



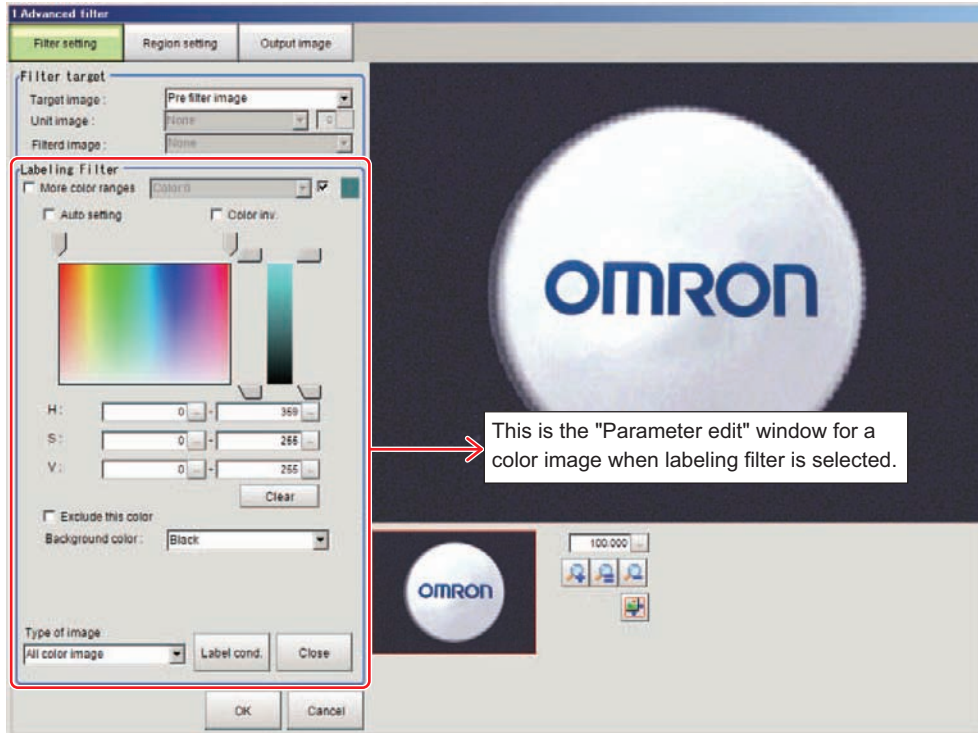
- 2 For the setting details, refer to applicable Stripes Removal Filter II provided as an existing processing item.

Setting item	Setting value [Factory default]	Description
Method	<ul style="list-style-type: none"> [Thick stripe off (morphology difference)] Pinstripe off (morphology) 	Select the correction method. <ul style="list-style-type: none"> Thick stripes removal filter (Morphology difference) : Set the filter size based on the size of the expected defect and removes the striped pattern. Thin stripes removal filter (Morphology) : Set the filter size based on the width of the stripes and cuts the striped pattern.
Direction	<ul style="list-style-type: none"> [Normal] Vertical Horizontal Upper right Lower right 	Make selection according to the direction in which to remove stripes. Select the direction vertical to the direction in which stripes change.
Filter size	3 to 63 [3]	Set the filter size. Specify a larger value to match the size of the stripes. An odd number value can be specified.
Gain	1 to 63 [3]	Adjust the contrast of an image after the correction. Specifying a larger value emphasizes the density differences within the image.
Offset	0 to 255 [128]	Adjust the brightness of an image after the correction. Specifying a larger value increases the brightness of the image.

Labeling Filter Setting (Color Extraction)

- 1 Selecting "Labeling filter" on the filter details selection screen displays the "Parameter edit" area for the selected filter.

■ Color image

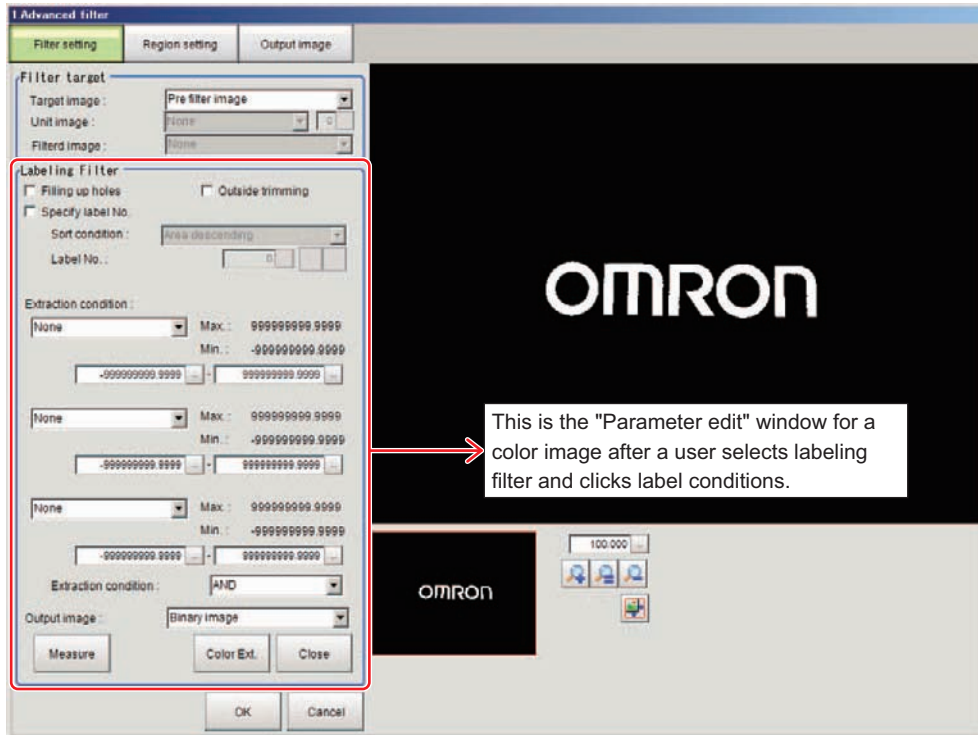


- 2 For the setting details, refer to the applicable labeling provided as an existing processing item.

Setting item	Setting value [Factory default]	Description
More color ranges	<ul style="list-style-type: none"> • [Single selection] • Multiple selections 	Select whether or not to register multiple colors as the setting range for color extraction. Placing a check here permits registration of multiple colors and enables setting of color extraction range.
Color extraction range	Color 0 to 7 [Color 0]	Select the color extraction range currently set as the target. This option is enabled when a check is placed at "More ranges of color extraction".
Color extraction range enabled/disabled	<ul style="list-style-type: none"> • Initial value of color 0 : Enabled • Initial value of color 1 to 7 : Disabled 	Select whether or not to enable the range selected under "Color extraction range". Placing a check here enables the range selected under "Color extraction range".
Extraction color panel	-	Extraction colors in the range selected under "Color extraction range" are displayed. This panel is displayed only when "Color extraction range enabled/disabled" is set to "Enabled".

Setting item	Setting value [Factory default]	Description
Auto setting	<ul style="list-style-type: none"> • [Disabled] • Enabled 	<p>Select whether or not to permit automatic reflection in the setting of the color extraction result by dragging from the extraction color panel image window.</p> <p>When [Enabled] is selected, the extraction colors are plotted on the HSV control and the values are also reflected.</p> <p>When [Disabled] is selected, only the extraction colors are plotted.</p>
Color inv.	<ul style="list-style-type: none"> • [No reverse] • Reverse 	Select the reverse color of the extraction image. Everything other than the selected color becomes the measurement target.
HSV range	<ul style="list-style-type: none"> • H : [0] to [359] • S : [0] to [255] • V : [0] to [255] 	Set the color to be extracted based on HSV (hue, saturation, value).
Clear	---	<p>Clear the value in the HSV range.</p> <p>Once the settings have been cleared, the default values become effective again.</p>
Exclude this color	<ul style="list-style-type: none"> • [Do not exclude] • Exclude 	<p>Specify exclusion of the range specified under "Color extraction range".</p> <p>Placing a check here specifies exclusion of the specified range.</p> <p>The range specified for exclusion will be registered as a non-extraction range.</p>
Background color	<ul style="list-style-type: none"> • [Black] • White • Red • Green • Blue 	Select the background color of the non-extraction range.
Type of image	<ul style="list-style-type: none"> • Measure image • [All color image] • Color selected image • Binary image 	Select the image to be displayed in the image window.
Label cond.	---	The label condition panel appears.

3 Set the filter parameters, and then set the label conditions.



Setting item	Setting value [Factory default]	Description
Filling up holes	<ul style="list-style-type: none"> • [Filling up holes OFF] • Filling up holes ON 	Select whether to enable or disable filling up hole processing. Set how to process parts surrounded by the specified color. Placing a check here enables filling up hole processing.
Outside trimming	<ul style="list-style-type: none"> • [Outside trimming OFF] • Outside trimming ON 	Select whether to enable or disable outside trimming processing. Outside trimming processing, which changes all areas outside the measurement region to the measurement target color, is performed. Placing a check here enables outside trimming processing.
Specify label No.	<ul style="list-style-type: none"> • [All labels] • Specified label 	Select whether to target all labels or specify a number. Placing a check here enables label number specification processing. If "Specify label number" is enabled, the sorting method is enabled.

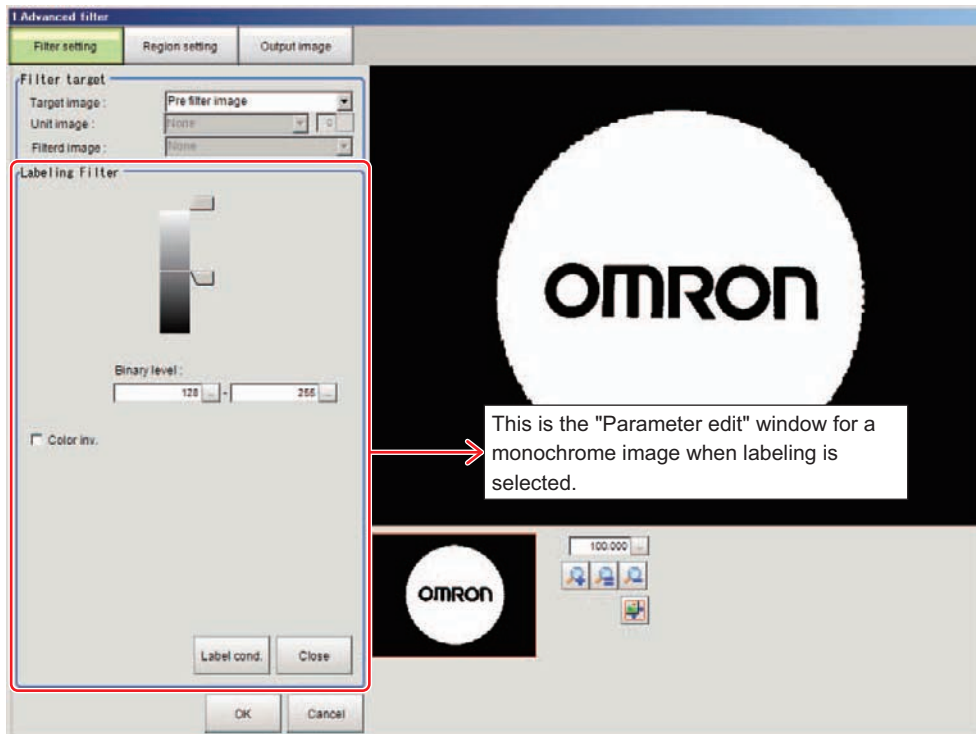
Setting item	Setting value [Factory default]	Description
Sort condition	Area ascending [Area descending] X ascending X descending Y ascending Y descending Elliptic major axis ascending Elliptic major axis descending Elliptic minor axis ascending Elliptic minor axis descending Elliptic ratio ascending Elliptic ratio descending Rectangle width ascending Rectangle width descending Rectangle height ascending Rectangle height descending Rectangle X1 ascending Rectangle X1 descending Rectangle Y1 ascending Rectangle Y1 descending Perimeter ascending Perimeter descending CircularityAsc ascending CircularityAsc descending Fit rect major axis ascending Fit rect major axis descending Fit rect minor axis ascending Fit rect minor axis descending Fit rect ratio ascending Fit rect ratio descending Inscribed circle X ascending Inscribed circle X descending Inscribed circle Y ascending Inscribed circle Y descending Inscribed circle R ascending Inscribed circle R descending Circum. circle X ascending Circum. circle X descending Circum. circle Y ascending Circum. circle Y descending Circum. circle R ascending Circum. circle R descending Number of holes ascending Number of holes descending	Select the sort method of labels. This option is enabled only when "Specify label number" is set to "Specified label".
Label No.	0 to 2499 [0]	Set the label No. to be output. This option is enabled only when "Specify label number" is set.

Setting item	Setting value [Factory default]	Description
Extraction condition 0 to 2	[None] Area X Y Elliptic major axis Elliptic minor axis Elliptic ratio Rectangle width Rectangle height Rectangle X1 Rectangle Y1 Perimeter CircularityAsc Fit rect major axis Fit rect minor axis Inscribed circle R Circum. circle R Number of holes	Select the conditions for extracting a label. Three conditions can be selected.
Extraction condition upper/ lower limit 0 to 2	[-999999999.9999] to [999999999.9999]	Set the upper limit and lower limit for extracting a label.
Display maximum /minimum measured values 0 to 2	---	The maximum and minimum values under extraction condition 0 to 2 as currently set are displayed. These values are updated only when the measurement button is clicked.
Extraction condition setting	<ul style="list-style-type: none"> • [AND] • OR 	Select the combination of extraction conditions. When AND is selected, labels meeting all of extraction conditions 0 to 2 are extracted. When OR is selected, labels meeting any one of extraction conditions 0 to 2 are extracted.
Output image	<ul style="list-style-type: none"> • [Binary image] • All color image 	Select images to be output.
Measurement	---	Execute test measurement processing. The displayed maximum and minimum measured values 0 to 2 are updated.
Color extraction/ binarization	---	The color extraction screen or binary screen appears.

Labeling Filter Setting (Binary)

- 1 Selecting "Labeling Filter" on the filter details selection screen displays the "Parameter edit" area for the selected filter.

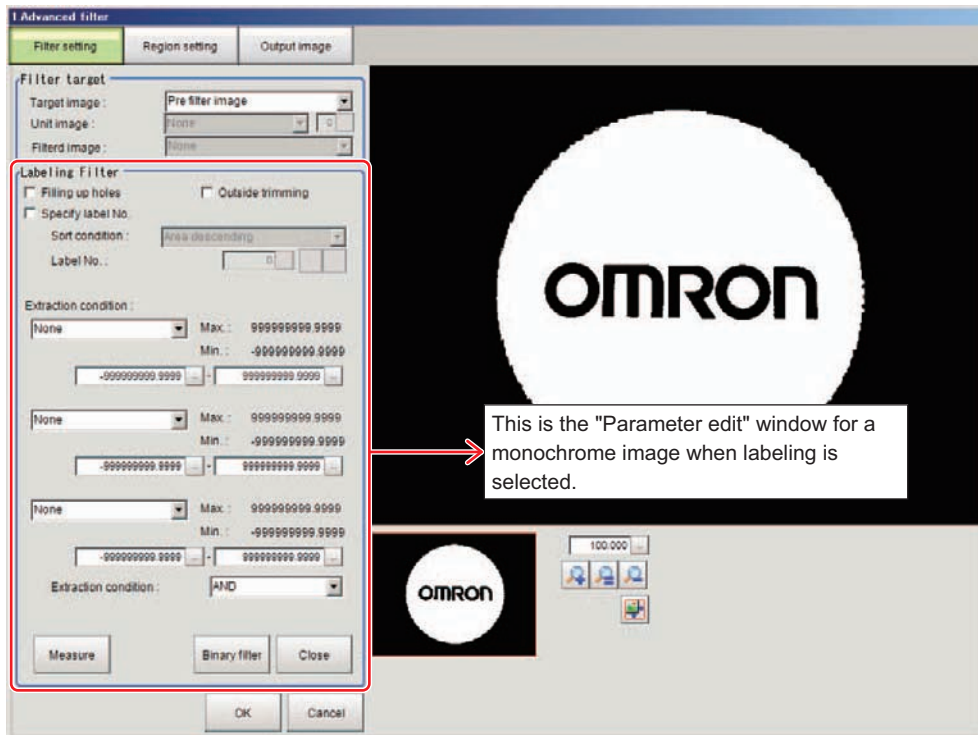
■ Monochrome image



- 2 For the setting details, refer to the applicable labeling provided as an existing processing item.

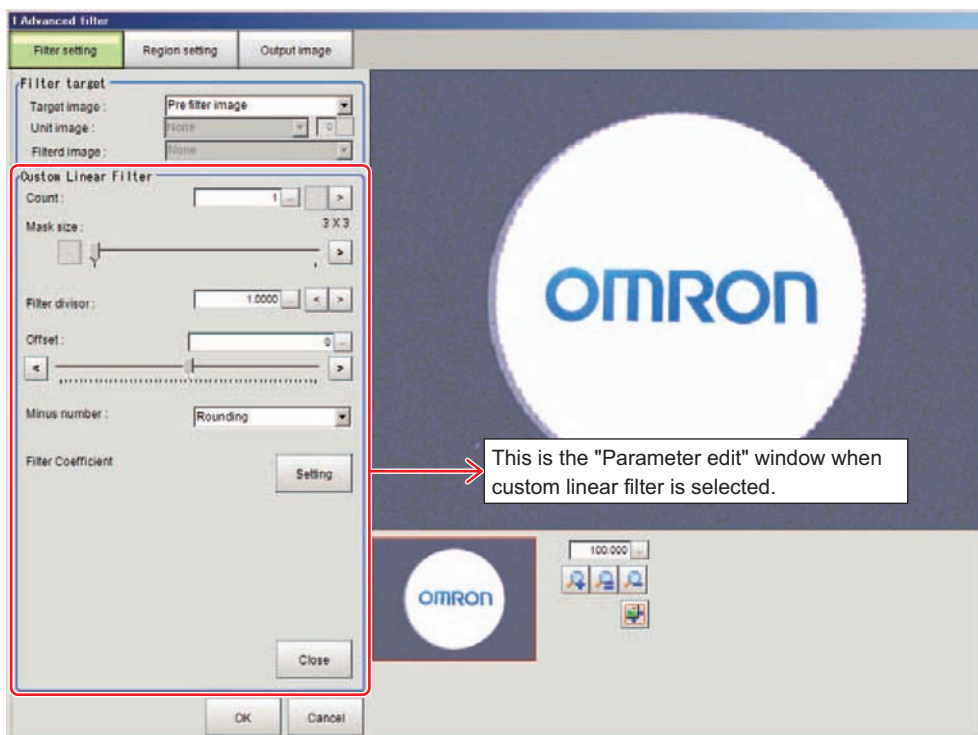
Setting item	Setting value [Factory default]	Description
Binary level	Lower limit: 0 to 255 [255] Upper limit: 0 to 255 [128]	Set the binary level. Monochrome images only
Color inv.	<ul style="list-style-type: none"> • [No reverse] • Reverse 	Select the binary inversion. The level set under "Binary level" is reversed. Everything other than the set level becomes the measurement target. Placing a check here enables binary inversion.
Label cond.	---	The label condition panel appears.

- 3 Set the filter parameters, and then set the label conditions. (The specific settings are the same as those of the label conditions for color images, except that there are no setting items for output images.)



Custom Linear Filter Setting

- 1 Selecting "Custom Linear Filter" on the filter details selection screen displays the "Parameter edit" area for the selected filter, where you can set the necessary items.

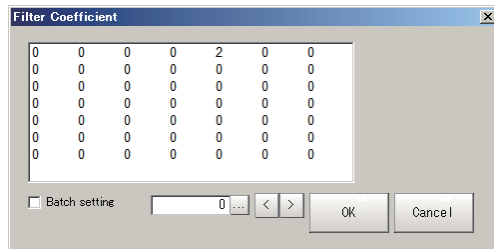


Setting item	Setting value [Factory default]	Description
Count	1 to 9 [1]	Set the number of times the custom linear filter will be applied.
Mask size	<ul style="list-style-type: none"> • Setting value : 3×3 : 5×5 : 7×7 : 9×9 : 11×11 : 13×13 : 15×15 : 17×17 : 19×19 : 21×21 	Select the filter size for the custom linear filter.
Filter divisor	0.0001 to 99999.9999 [1.0000]	Set the filter divisor to be used with the custom linear filter.
Offset	<ul style="list-style-type: none"> • Setting range : -255 to 255 : [0] 	Set the offset value to be used with the custom linear filter.
Minus number	<ul style="list-style-type: none"> • [Rounding] • Absolute 	Select the negative number processing to be used with the custom linear filter. When "Rounding" is selected, density is rounded to 1. When "Absolute value" is selected, the absolute value is set as the density.
Filter Coefficient	---	The filter parameter setting screen appears.

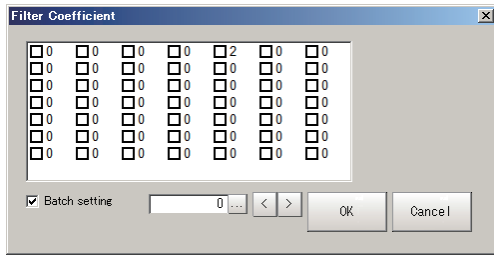
2 Thereafter, click [Filter Coefficient] to switch to the filter parameter setting screen and set the filter parameters.

3 The layout of the filter parameter screen varies depending on the filter size of the filter (3×3 to 21×21). (7×7 in the example below)

■ No batch setting



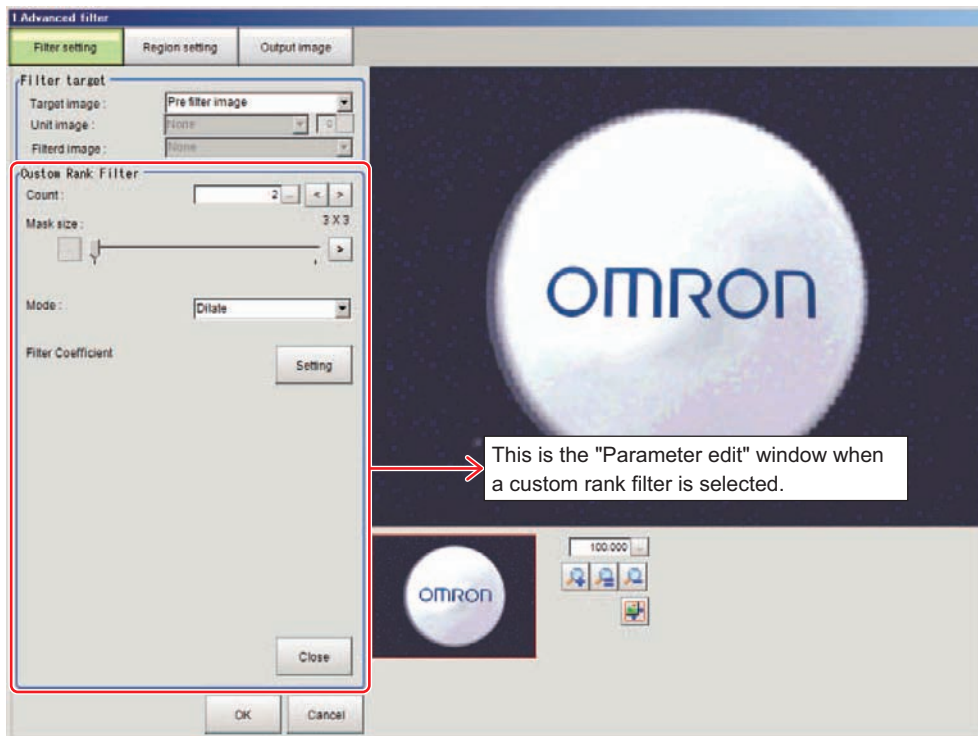
■ Batch setting



Setting item	Setting value [Factory default]	Description
Filter parameter 0 to 440	---	Filter parameters for the filter sizes of 3×3 to 21×21 are displayed. You can only make selections from this list and cannot change the values directly.
Batch setting	<ul style="list-style-type: none"> • [No batch setting] • Batch setting 	Select whether or not to set filter parameters for the filter sizes of 3×3 to 21×21 in batch. Placing a check here enables batch setting. When "Batch setting" is selected, a check box appears next to each filter parameter item.
Filter value	-127 to 128 [0]	Set the filter value. If "No batch setting" has been selected, the parameter currently selected in the list is changed. If "Batch setting" has been selected, the parameters where a check is placed are changed.
OK	---	The dialog box closes after applying the filter parameters.
Cancel	---	The dialog box closes without applying the filter parameters.

Custom Rank Filter Setting

- 1 Selecting "Custom Rank Filter" on the filter details selection screen displays the "Parameter edit" area for the selected filter, where you can set the necessary items.

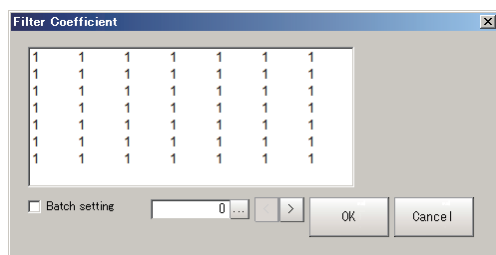


Setting item	Setting value [Factory default]	Description
Count	1 to 9 [1]	Set the number of times the custom rank filter will be applied.
Mask size	<ul style="list-style-type: none"> • Setting value : [3 × 3] : 5 × 5 : 7 × 7 : 9 × 9 : 11 × 11 : 13 × 13 : 15 × 15 : 17 × 17 : 19 × 19 : 21 × 21 	Set the filter size for the custom rank filter.
Mode	<ul style="list-style-type: none"> • [Dilate] • Erosion 	Select the negative number processing to be used with the custom rank filter.
Filter Coefficient	---	The filter parameter setting screen appears.

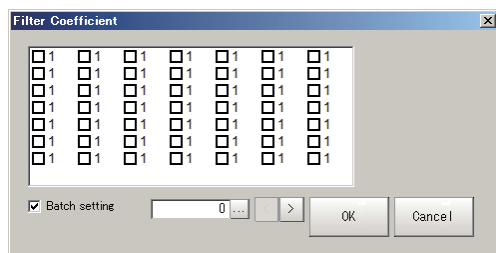
- 2 Thereafter, click [Filter Coefficient] to switch to the filter parameter setting screen and set the filter parameters.

3 The layout of the filter parameter screen varies depending on the filter size of the filter (3 × 3 to 21 × 21). (7 × 7 in the example below)

■ No batch setting



■ Batch setting



Setting item	Setting value [Factory default]	Description
Filter parameter 0 to 440	---	Filter parameters for the filter sizes of 3 × 3 to 21 × 21 are displayed. You can only make selections from this list and cannot change the values directly.
Batch setting	<ul style="list-style-type: none"> • [No batch setting] • Batch setting 	Select whether or not to set filter parameters for the filter sizes of 3 × 3 to 21 × 21 in batch. Placing a check here enables batch setting. When "Batch setting" is selected, a check box appears next to each filter parameter item.
Filter value	0 to 1 [1]	Set the filter value. If "No batch setting" has been selected, the parameter currently selected in the list is changed. If "Batch setting" has been selected, the parameters where a check is placed are changed.
OK	---	The dialog box closes after applying the filter parameters.
Cancel	---	The dialog box closes without applying the filter parameters.

Image Operation Setting

- 1 Selecting "Image operation" on the filter details selection screen displays the "Parameter edit" area for the selected filter.
- 2 The parameters that can be set vary depending on the calculation type selected in the image calculation area.
- 3 Four Arithmetic operation

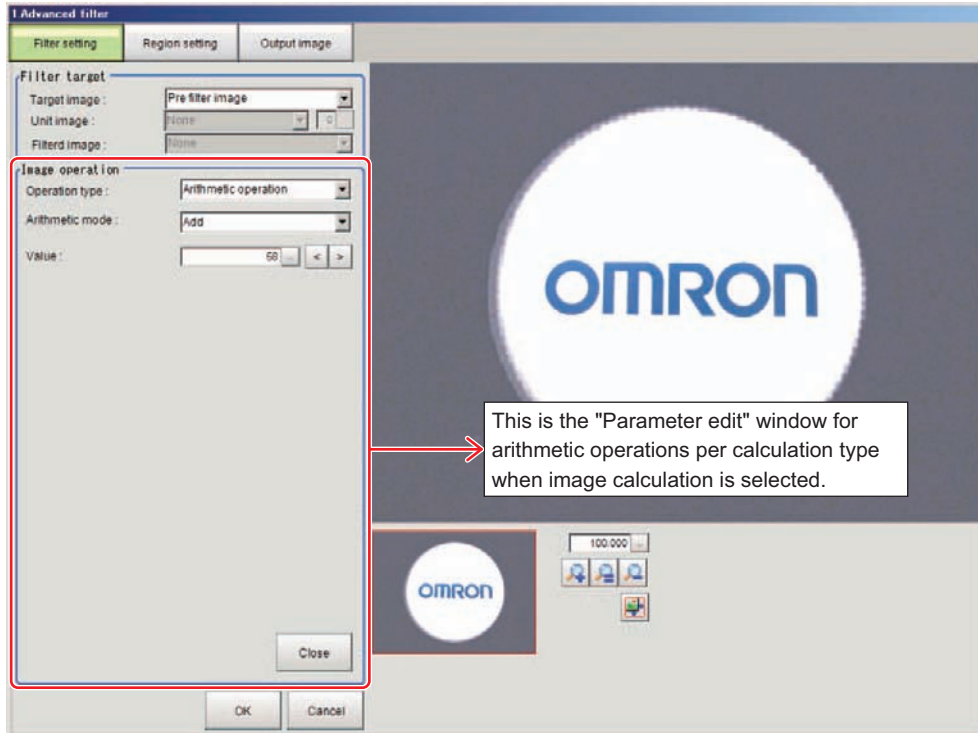


Image calculation (four arithmetic calculations) is a filter that performs calculation on the original image using the set calculation value to convert pixel values.

Addition

230	20	100
64	128	196
150	50	1

+50 →

255	70	150
114	178	246
200	100	51

Outputs 255 if over 255

Subtraction

230	20	100
64	128	196
150	50	1

-50 →

180	1	50
14	78	146
100	1	1

Outputs 1 if less than one

Subtraction (absolute value)

230	20	100
64	128	196
150	50	1

-50 →

180	30	50
14	78	146
100	1	49

Outputs absolute value when less than 0

Multiplication

230	20	100
64	128	196
150	50	1

X2.000 →

255	40	200
128	255	255
255	100	2

Outputs 255 if over 255

Setting item	Setting value [Factory default]	Description
Operation type	<ul style="list-style-type: none"> • [Arithmetic operation] • Bit operation • Bit shift • Change pixel value 	Select the calculation type of image calculation to be performed.
Arithmetic mode	<ul style="list-style-type: none"> • [Add] • Subtraction • Subtraction (absolute) • Multiplication 	Select one of four arithmetic calculation methods.
Value	0 to 255 [0]	Set the value used for the arithmetic calculation.

4 Bit operation

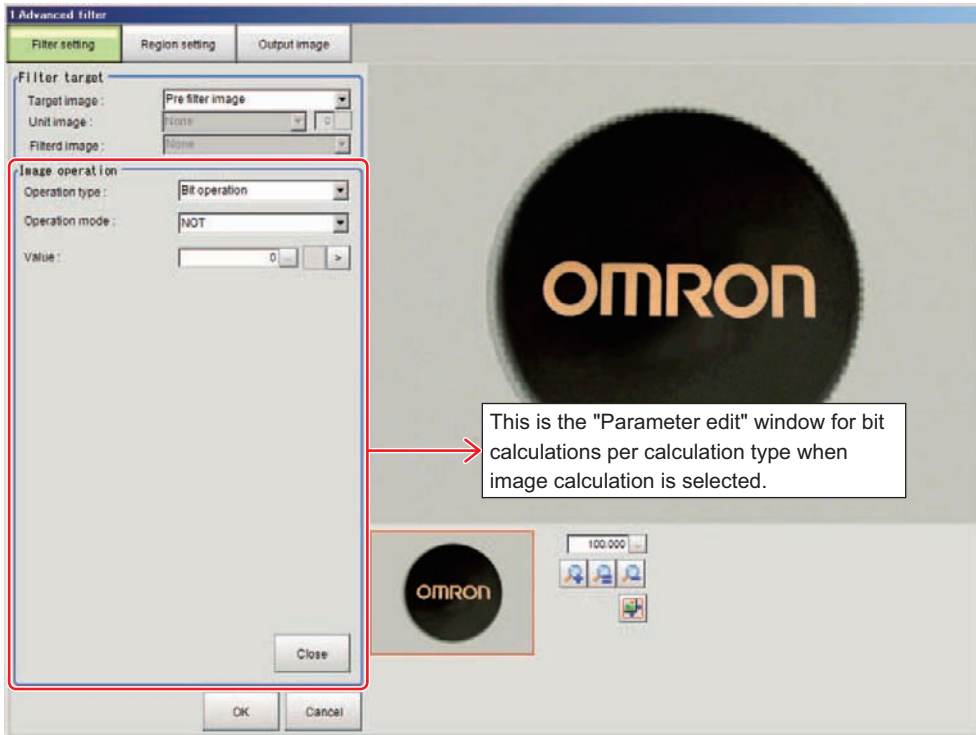
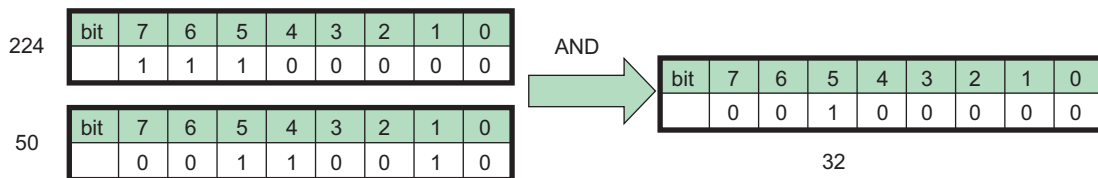


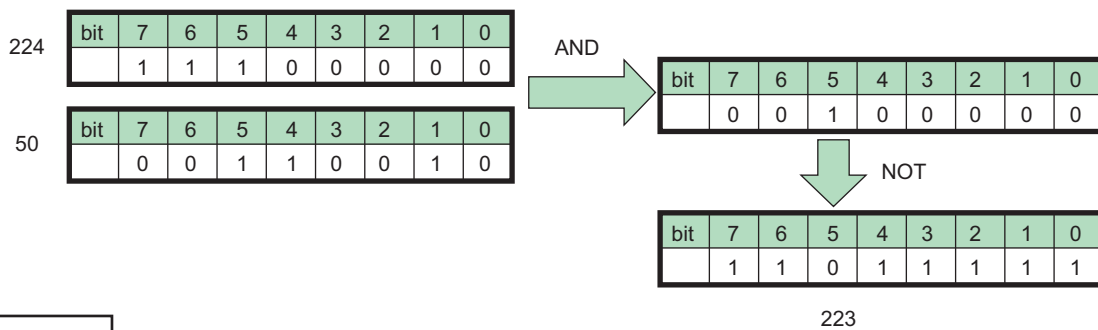
Image calculation (bit calculation) is a filter that performs bit calculation on the original image using the set calculation value to convert pixel values.

AND



NAND

$$\text{NAND}(A, B) = \text{NOT}(\text{AND}(A, B))$$



NOR

$$\text{NOR}(A, B) = \text{NOT}(\text{OR}(A, B))$$

XNOR

$$\text{XNOR}(A, B) = \text{NOT}(\text{XOR}(A, B))$$

Setting item	Setting value [Factory default]	Description
Operation type	<ul style="list-style-type: none"> • [Arithmetic operation] • Bit operation • Bit shift • Change pixel value 	Select the calculation type of image calculation to be performed.
Operation mode	<ul style="list-style-type: none"> • [NOT] • AND • OR • XOR • NAND • NOR • XNOR 	Select the bit calculation method.
Value	0 to 255 [0]	Set the value used for bit calculation.

5 Bit shift

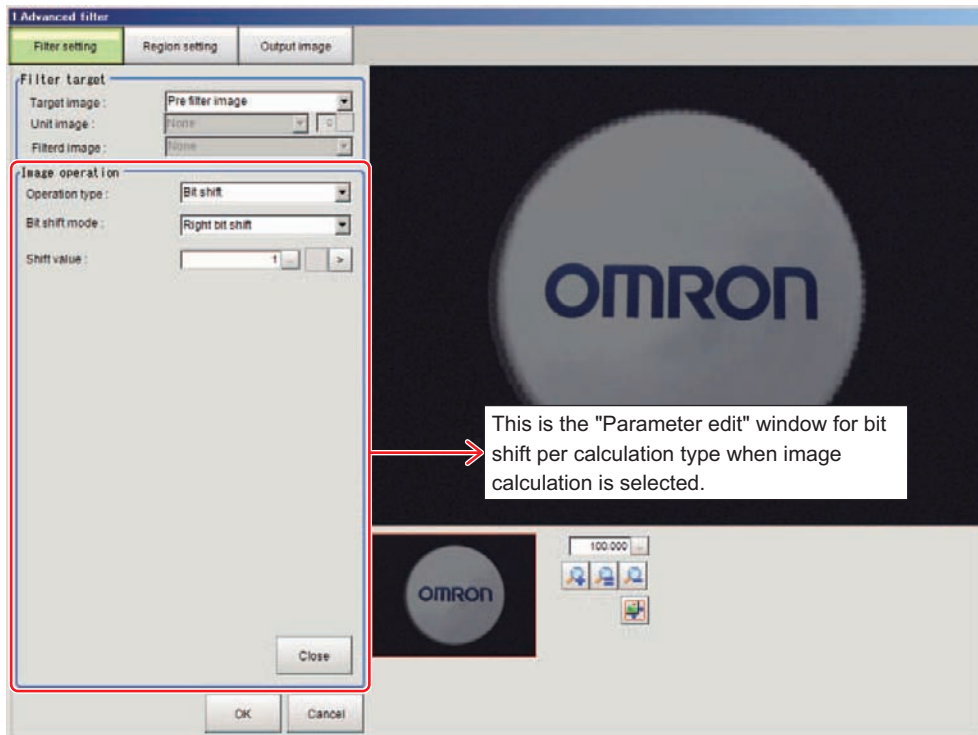


Image calculation (bit shift) is a filter that performs bit shift calculation on the original image using the set calculation value to convert pixel values.

bit	7	6	5	4	3	2	1	0
	1	0	0	0	0	0	0	0



1 bit shift to the right

bit	7	6	5	4	3	2	1	0
	0	1	0	0	0	0	0	0

Setting item	Setting value [Factory default]	Description
Operation type	<ul style="list-style-type: none"> • [Arithmetic operation] • Bit operation • Bit shift • Change pixel value 	Select the calculation type of image calculation to be performed.
Bit shift mode	<ul style="list-style-type: none"> • [Right bit shift] • Left bit shift 	Select the bit shift calculation method. <ul style="list-style-type: none"> • Right bit shift: The image becomes darker. • Left bit shift: The image becomes brighter.
Shift value	0 to 8 [0]	Set the value used for bit shift calculation.

6 Change pixel value

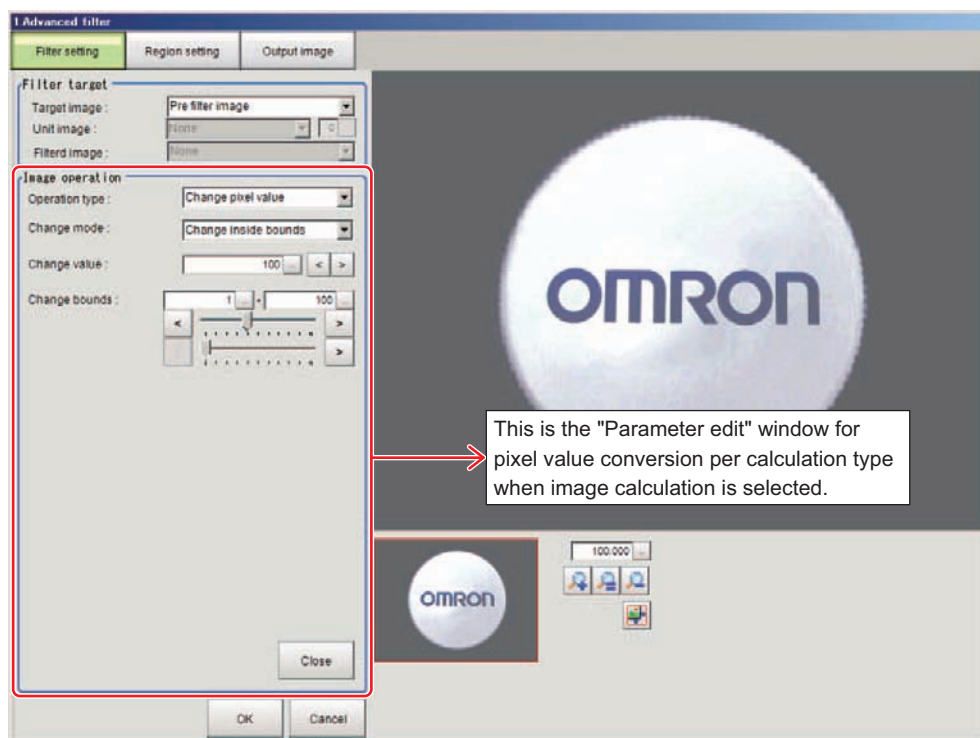
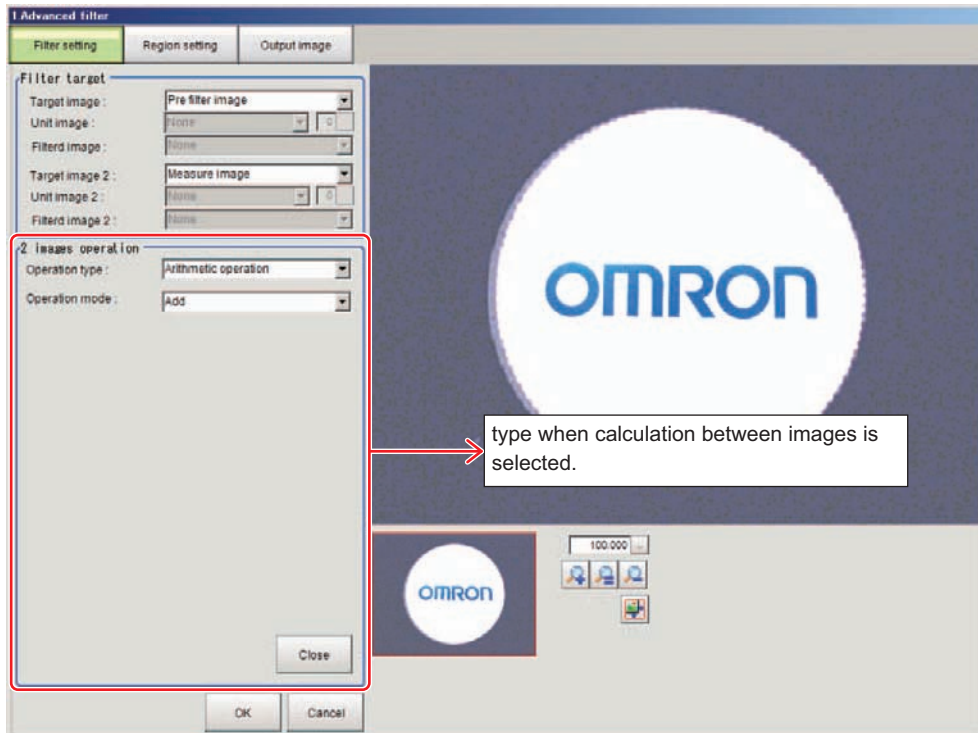


Image calculation (pixel value conversion) replaces values inside (or outside) the set pixel value range of the original image with a desired pixel value. This filter performs bit shift calculation on the original image using the set calculation value to convert pixel values.

Setting item	Setting value [Factory default]	Description
Operation type	<ul style="list-style-type: none"> • [Arithmetic operation] • Bit operation • Bit shift • Change pixel value 	Select the calculation type of image calculation to be performed.
Change mode	<ul style="list-style-type: none"> • Change inside bounds • Change outside bounds 	Select the method of pixel value conversion calculation. <ul style="list-style-type: none"> • Right bit shift: The image becomes darker. • Left bit shift: The image becomes brighter.
Change value	1 to 255 [128]	Set the value used for pixel value conversion.
Change bounds	[1] to [255]	Set the upper/lower limits to be converted.

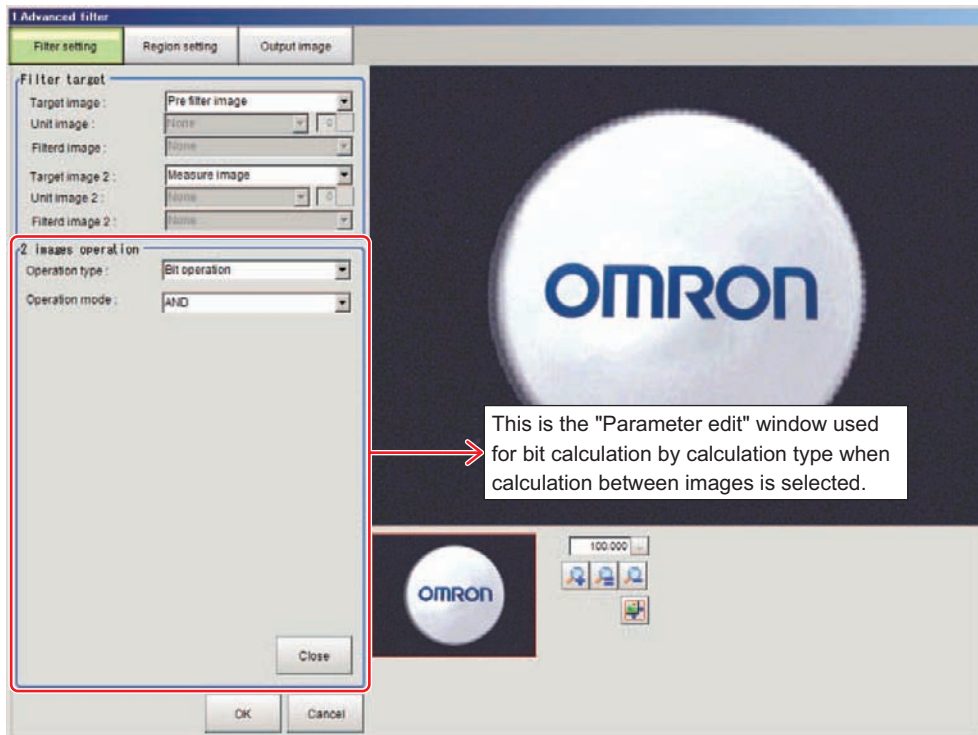
Setting of 2 images operation

- 1 Selecting "2 images operation" on the filter details selection screen displays the "Parameter edit" area for the selected filter.
- 2 The parameters that can be set vary depending on the calculation type selected in the image calculation area.
- 3 When "Calculation type" is "Arithmetic operation".



Setting item	Setting value [Factory default]	Description
Operation type	<ul style="list-style-type: none"> • [Arithmetic operation] • Bit operation 	Select the calculation type to be used for calculation between images.
Operation mode	<ul style="list-style-type: none"> • [Add] • Subtraction • Subtraction (Absolute) • Multiplication • Multiplication (Normalization) • Average • Maximum • Minimum 	Select the calculation mode.

4 When "Calculation type" is "Bit operation".



Setting item	Setting value [Factory default]	Description
Operation type	<ul style="list-style-type: none"> • [Arithmetic operation] • Bit operation 	Select the calculation type to be used for calculation between images.
Operation mode	<ul style="list-style-type: none"> • [AND] • OR • XOR • NAND • NOR • XNOR 	Select the bit calculation mode.

External Reference Tables (Advanced filter)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG

Panorama

Images from multiple cameras are combined into one image.

Pay attention to the characteristics of images to compensate the image positions and angles when combining them. Therefore, users can acquire precise combined images without strictly designing the camera placing positions.

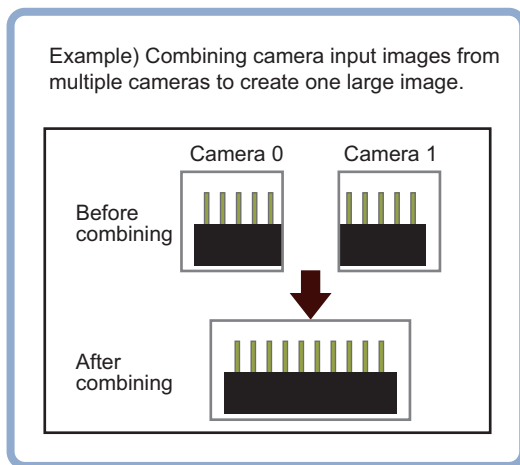
Intelligent compact camera, FZ-SQxxxx cannot be used.

If the FH Sensor Controller is connected to the FH-Sx02/Sx04 digital camera with two camera cables, panorama is not available.

With panorama, only camera images of the same type can be input.

Used in the Following Case

- To combine the input images from multiple cameras



Important

- The first processing after the sensor controller is started may take longer than the second and subsequent processing even though the same image is measured.
- To save an image converted into a panorama, use the image convert logging processing item.

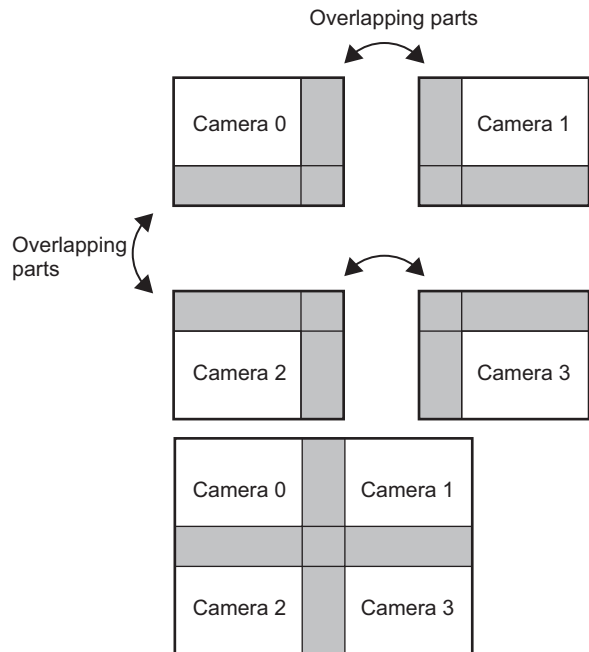
Camera Placement and Image Combination Method

Place the cameras so that the field of vision of each camera overlaps at least 1/4 for stable image combination. For this setting, do not use a plain, featureless image or an image with a lattice or other repetitive pattern. The image combination may not be set correctly. In measurement after the setting has been made, panoramic combination is possible even for plain and lattice-pattern images.

For 2 × 2 camera placement

1 Set the camera placement.

Adjust the camera placement so that the fields of vision overlap at least 1/4 for cameras 0 and 1, 1 and 2, and 2 and 3.



2 Set the image combination method.

Use the Offset X, Y buttons on the setting screen to adjust so that the overlapping sections of neighboring images match.

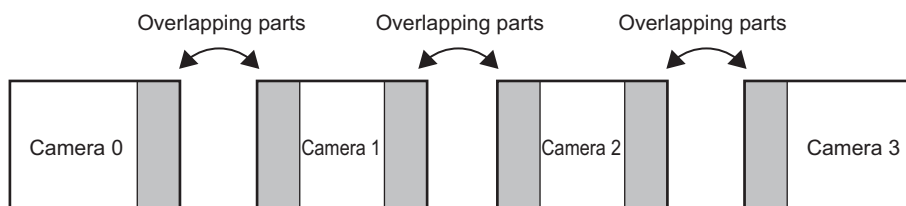
3 Combine the image.

Click the Combine button on the setting screen.

For 1 × 4 camera placement

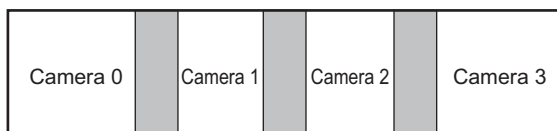
1 Set the camera placement.

Adjust the camera placement so that the fields of vision overlap at least 1/4 for cameras 0 and 1, 1 and 2, and 2 and 3.



2 Set the image combination method.

Use the Offset X, Y buttons on the setting screen to adjust so that the overlapping sections of neighboring images match.



3 Combine the image.

Click the Combine button on the setting screen.

Camera Placement (Panorama)

Set the camera placement.

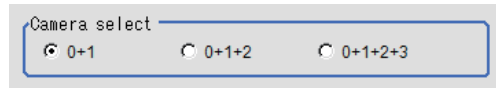
1 In the Item Tab area, click [Arrangement].

2 In the "Display" area, click [Change display] to switch between camera image types.

The displayed contents of the Image Display area will be switched.

Setting item	Set value [Factory default]	Description
Display	Through	The latest image is always input from the camera and displayed.
	[Freeze]	The image that was scanned in the immediately preceding measurement is displayed.

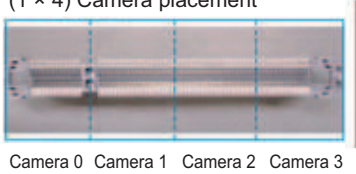
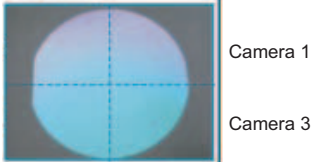
3 Set the camera settings.



Setting item	Set value [Factory default]	Description
Camera select	<ul style="list-style-type: none"> • [0+1] • 0+1+2 • 0+1+2+3 	Select the combination of cameras to combine the images from. 0+1: Combine the images from Camera0 and Camera1. 0+1+2: Combine the images from Camera0, Camera1, and Camera2. 0+1+2+3: Combine the images from Camera0, Camera1, Camera2, and Camera3.

4 Set the camera placement.



Setting item	Set value [Factory default]	Description
Arrangement	<ul style="list-style-type: none"> • [One line] • Two line 	Set the camera image placement. (1 × 4) Camera placement  Camera 0 Camera 1 Camera 2 Camera 3 (2 × 2) Camera placement  Camera 0 Camera 1 Camera 2 Camera 3

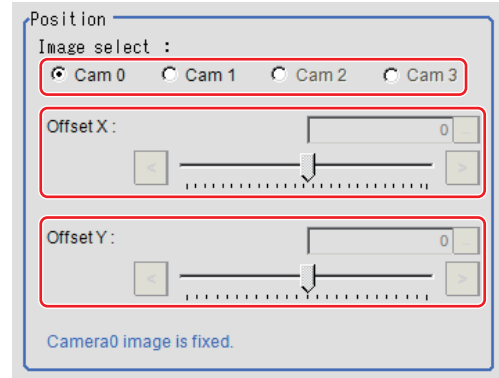
Important

- If the configuration of the connected camera is changed, the measurement result is NG (incompatible image). Press the initialize button and re-do the settings.
- Do not set [Camera Image Input] or [Camera Image Input HDR] after [Panorama].

Image Combination (Panorama)

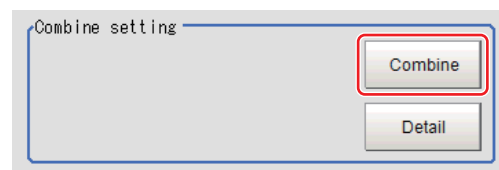
Set the image combination method.

- 1 In the "Item Tab" area, click [Combine].
- 2 Set each item in the "Position" area.



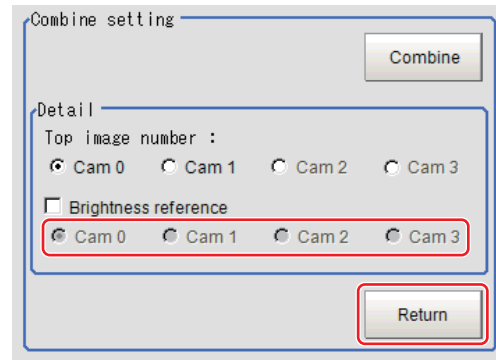
Setting item	Set value [Factory default]	Description
Image select	<ul style="list-style-type: none"> • [Cam 0] • Cam 1 • Cam 2 • Cam 3 	Select the camera image for adjusting the combination position. Camera0 is fixed. Adjust the combination position to the position where you want to add in Camera1 and higher.
Offset X	0.3 megapixel CCD cameras: -640 to 640 [0] 2 megapixel CCD cameras: -1600 to 1600 [0] 5 megapixel CCD cameras: -2448 to 2448 [0] 0.3 megapixel CMOS cameras: -640 to 640 [0] 2 megapixel CMOS cameras: -2040 to 2040 [0] 4 megapixel CMOS cameras: -2040 to 2040 [0]	Adjust the selected camera image in the X direction.
Offset Y	0.3 megapixel CCD cameras: -480 to 480 [0] 2 megapixel CCD cameras: -1200 to 1200 [0] 5 megapixel CCD cameras: -2048 to 2048 [0] 0.3 megapixel CMOS cameras: -480 to 480 [0] 2 megapixel CMOS cameras: -1088 to 1088 [0] 4 megapixel CMOS cameras: -2048 to 2048 [0]	Adjust the selected camera image in the Y direction.

- 3 In the "Combine setting" area, set the combination method.



Setting item	Description
Combine	This option combines images panoramically so that the detected feature points (same location on the object as positioned differently on the different images) line up with each other in the combined image.

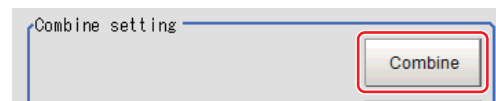
4 Set details as necessary.



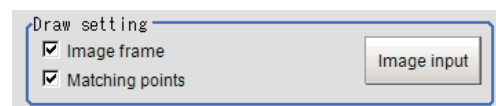
Setting item	Set value [Factory default]	Description
Top image number	<ul style="list-style-type: none"> • [Cam 0] • Cam 1 • Cam 2 • Cam 3 	Select the number of the camera image to be displayed on top. The selected number order changes the order of the images.
Brightness reference	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check here where there is brightness variation among the camera images.
	[Cam 0] Cam 1 Cam 2 Cam 3	Set the number of the camera to be used as reference for brightness compensation. The brightness of the selected camera image is used as reference to adjust the brightness of the other cameras.

Restoring settings to their initial states

Clicking [Initialize] restores settings to their initial states.



5 Make the drawing settings as necessary.



Setting item	Set value [Factory default]	Description
Image frame	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Set whether to display the image frame.
Matching points	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Set whether to display feature points.

Key Points for Test Measurement and Adjustment (Panorama)

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number	Explanation of image to be displayed
0	Post-combination image

Key Points for Adjustment

Select the adjustment method referring to the following points.

If grid point combination fails

State	Parameter to be adjusted	Troubleshooting
The width of the overlapping portion of images is small	Offset X, Offset Y	Set the offset so that one-fourth of each image overlaps with each other. Set the camera so that the one-fourth of the field of views between cameras overlaps with each other.
Overlapping part of images has no characteristics	Input image	Use characteristic images when setting it.

Measurement Results for Which Output Is Possible (Panorama)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Panorama)

No.	Data name	Set/Get	Data range
0	Judge	Get	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
100	Select camera	Set/Get	0: Camera 0 + 1 1: Camera 0 + 1 + 2 2: Camera 0 + 1 + 2 + 3
101	Arrangement	Set/Get	0: (1 × 4) placement 1: (2 × 2) placement
102	Select Image	Set/Get	0 to 3
103	Amount of parallel movement X	Set/Get	0.3 megapixel CCD cameras: -640 to 640 2 megapixel CCD cameras: -1600 to 1600 5 megapixel CCD cameras: -2448 to 2448 0.3 megapixel CMOS cameras: -640 to 640 2 megapixel CMOS cameras: -2040 to 2040 4 megapixel CMOS cameras: -2040 to 2040

No.	Data name	Set/Get	Data range
104	Amount of parallel movement Y	Set/Get	0.3 megapixel CCD cameras: -480 to 480 2 megapixel CCD cameras: -1200 to 1200 5 megapixel CCD cameras: -2044 to 2044 0.3 megapixel CMOS cameras: -480 to 480 2 megapixel CMOS cameras: -1088 to 1088 4 megapixel CMOS cameras: -2048 to 2048
107	Flag for drawing image frame	Set/Get	0: Not drawn 1 : Drawn
108	Flag for drawing characteristic points	Set/Get	0: Not drawn 1 : Drawn
109	Flag for executing brightness correction	Set/Get	0: Not executed 1 : Executed
110	Brightness correction reference image No.	Set/Get	0 to 3
112	Number of valid images	Set/Get	0 to 4
200	Foremost window image	Get	0 to 3

MEMO

Support Inspection and Measurement

This chapter explains how to set calculations and how to get or view data.

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Macro

User's original measurement processing can be performed.

Macros are convenient if you want to build a new measurement processing by combining filters and measurement processing's, create a complex display that cannot be realized with the result display processing items, or write original text in the detail text display.

Used in the Following Case

- **Processing performed by multiple processing items such as looping and branching can be consolidated into one.**

Example) Perform search processing after carrying out filter processing multiple times

- Using a flow: Combine filtering, calculation, Set Unit Data and search.
- Using macros: Add filtering and search to a flow and define a processing where search measurement processing is performed after carrying out filter processing multiple times.

A flow can be made simpler using macros.

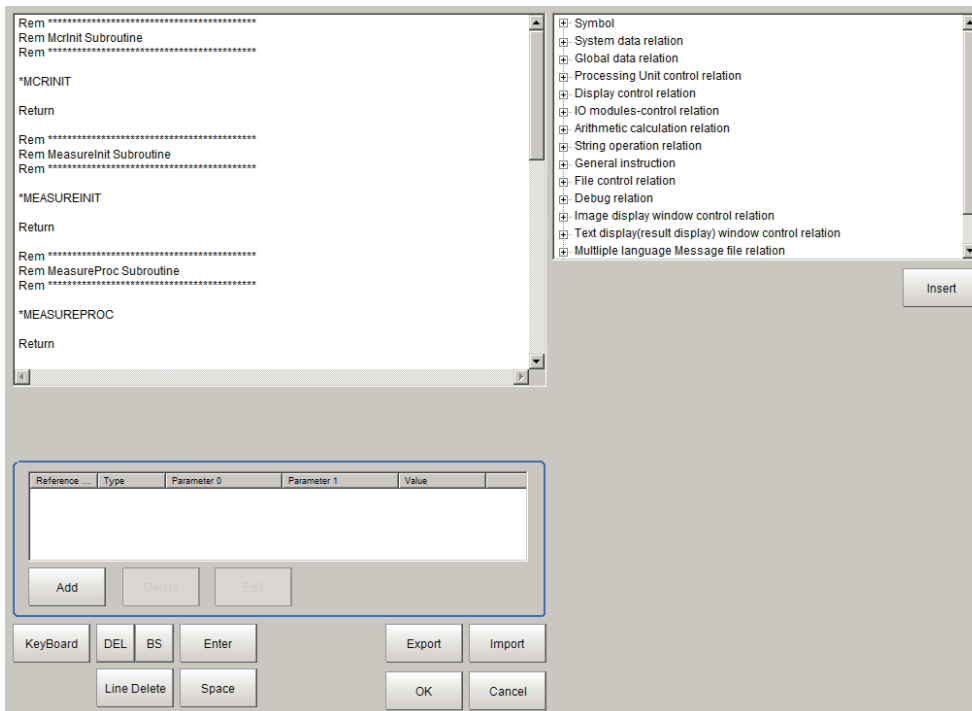
Important

- Macros cannot be edited by remote operation.

Description Method

When a macro processing item is added to a flow, you'll find that specific subroutines have been written in advance to the minimum extent not affecting the operation. Write the processing details in the subroutine you will use.

The subroutine whose processing details have been written will be automatically called and executed at the defined timing.



Program structure

Name of pre-defined subroutine	Processing detail	
*MCRINIT	Initial processing	Processing performed immediately after macro program load
*MEASUREINIT	Measurement initialization processing	Processing performed at the start of measurements
*MEASUREPROC	Measurement processing	Processing performed when measurement processing is executed
*MEASUREDISPI	Display processing	Image display
*MEASUREDISPT	Display processing	Text display
*MEASUREDISPG	Display processing	Graphics display (other than images and text on the setting screen, etc.)
*RENUMPROC	Number reference processing	Processing performed when the processing unit reference number is updated
*CLEARMEASUREDATA	Measurement results initialization processing	Initialization processing for processing unit measurement results

Note

- MEASUREDISPG" is executed when "Positions" is ON, but "*MEASUREDISPI" is not executed when "Positions" is ON.

The following functions are written in each subroutine.

Function types

Symbol, system data related, global data related, processing unit control related, measurement control related, display control related,
input/output (I/O module control) related, numerical calculations, string calculations, general commands, file control related, debugging related, other,
image display window control related, text display (detail result display) window control related

For the details of functions, refer to "Appendixes About Macro Functions Macro Command Reference" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Details of each subroutine

*MCRINIT

Processing performed immediately after macro program load

*McrInit is launched immediately after the macro program is loaded.

You can use this subroutine to declare an arrangement variable, or write processing such as setting the initial value of a variable.

Example of code: Initialize all elements of an arrangement variable to -1 when the macro program is loaded

```
*MCRINIT
  MAX& = 5
  Dim WRKCR#(MAX&)
  For LP& = 0 To MAX& - 1
    WRKCR#(LP&) = -1
  Next
Return
```

*MEASUREINIT

Processing Performed at the Start of Measurements

This subroutine performs processing at the start of measurements, e.g., when the system is started or when moving to the Main Window.

The processing at the start of measurements makes settings to prepare for measurements.

Example of code: Search for a processing unit to access during measurement processing at the start of measurements and retain the unit number.

```
*MEASUREINIT
UNITNUM& = -1
For I& = 0 To 999
  If UnitTitle$(I&) = "Camera0Search" Then
    UNITNUM& = I&
  Exit For
EndIf
Next
Return
```

*MEASUREPROC

Processing performed when measurement processing is executed

This subroutine is called when measurement processing of the applicable macro unit is performed.

You can use it to define operations such as obtaining data from other processing units, calculation, and result output.

Example of code:

Store measurement result of ECM search every time measurement processing is performed, and obtain an average/dispersion/standard deviation of measured XY

```
*MEASUREPROC
GetUnitData ECMSEARCHUNITNO&, "X", POSITIONX#(COUNT&)
GetUnitData ECMSEARCHUNITNO&, "Y", POSITIONY#(COUNT&)
AVERAGEXCNT# = AVERAGEXCNT# + POSITIONX#(COUNT&)
AVERAGEYCNT# = AVERAGEYCNT# + POSITIONY#(COUNT&)
AVERAGEX# = AVERAGEXCNT# / (COUNT& + 1)
AVERAGEY# = AVERAGEYCNT# / (COUNT& + 1)
For CNT& = 0 To COUNT& Step 1
  VARIANCEX# = VARIANCEX# + ((POSITIONX#(CNT&) - AVERAGEX#) * (POSITIONX#(CNT&) - AVERAGEX#))
  VARIANCEY# = VARIANCEY# + ((POSITIONY#(CNT&) - AVERAGEY#) * (POSITIONY#(CNT&) - AVERAGEY#))
Next
VARIANCEX# = VARIANCEX# / (COUNT& + 1)
VARIANCEY# = VARIANCEY# / (COUNT& + 1)
SDEVX# = Sqr(Abs(VARIANCEX#))
SDEVY# = Sqr(Abs(VARIANCEY#))
COUNT& = COUNT& + 1
Return
```

*MEASUREDISPI

Measurement result display processing (image display)

If this macro unit is selected in the image display window, this processing is called when measurement result display processing is performed. You can use this subroutine to draw an image in the image display window.

You can also call measurement result display processing of other unit.

Example of code: Display measurement image 0 in the image display window through measurement result display processing.

```
*MEASUREDISPI
  DrawMeasureImage 0
Return
```

*MEASUREDISPT

Measurement result display processing (text display)

If this macro unit is selected in the text display window, this processing is called when measurement result display processing is performed. Text is displayed in the text display window.

Example of code:

Display, through measurement result display processing, the processing unit name, measured coordinate X and measured coordinate Y line by line in the OK color in the text display window.

```
*MEASUREDISPT
  DrawText "Processing Item : " + UNITNAME$, JUDGE_OK, 1 '(3)
  If RESULTUNIT& >= 0 Then
    DrawText "Position X : " + Str$(POSITIONX#), JUDGE_OK, 1
    DrawText "Position Y : " + Str$(POSITIONY#), JUDGE_OK, 1
  EndIf
Return
```

*MEASUREDISPG

Measurement result display processing (graphic display)

If this macro unit is selected in the image display window, this processing is called when measurement result display processing is performed. You can use this subroutine to draw a graphic or image in the image display window. You can also call measurement result display processing of other unit.

Example of code: Display, through measurement result display processing, a line graphic based on the reference position SX, SY in the image display window.

```
*MEASUREDISPG
  MeasureDispG 1,0
  MYUNIT& = UnitNo
  SX& = UnitData(MYUNIT& - 1,"SX")
  SY& = UnitData(MYUNIT& - 1,"SY")
  SetDrawStyle PS_SOLID, 3, JUDGE_NG
  DrawLine SX&, SY& - 10, SX&, SY& + 10, 0
  DrawLine SX& - 10, SY&, SX& + 10, SY&, 0
Return
```


RENUMPROC*Processing performed when the processing unit reference number is updated**

This processing is called immediately after a unit has been added or deleted to/from the flow.
If the target unit number of processing is held in a variable, RenumUnitNo can be called in this processing to update the unit number.

Example of code: Update the unit number being held when a unit is added or deleted to/from the flow

```
*RENUMPROC
  UNITNO& = RenumUnitNo(UNITNO&)
Return
```

CLEARMEASUREDATA*Initialization Processing for Processing Unit Measurement Results**

This subroutine is called when measurement results are cleared.
You can use it to initialize the judgement for a Macro processing unit to [No judgement (unmeasured)].

Example of code: Initialize the COUNT& integer variable that is defined in the Macro processing item to 0 when measurement results are cleared.

```
*CLEARMEASUREDATA
  SetUnitJudge UnitNo, JUDGE_NC
  COUNT& = 0
Return
```

Image data

Up to 32 image data can be held per macro processing unit.
An image to be held can be specified using the CopyMeasureImage command.
An image being held can be displayed on the screen using the DrawMeasureImage command or passed as a measurement image of the subsequent unit using the SetMeasureImage command.

External reference data

By setting a variable name as an identification name of external reference data, the content of the applicable variable can be updated/referenced using a macro program, non-procedure command, CoreRA API, etc., of other unit. For example, you can specify "AA&" as an identification name of external reference data to set/obtain the content of the variable AA& from outside the processing unit.
You can also specify an operation using any of the following identification names via the external reference data setting I/F.

Identification name	Operation
direct	You can specify a command line string as setting data to directly execute the processing in the command line.
gosub	You can specify a label name string as setting data to execute the subroutine processing of the specified label.
load	You can specify a file name as setting data to load a program from the specified file.
save	You can specify a file name as setting data to save a program to the specified file.

Example of use of the non-procedure command UnitData**Command example 1:**

The processing AA&=100 (assign the value 100 to the integer variable AA&) is executed.
UnitData <Processing unit No.> direct AA&=100

Command example 2:

The subroutine processing *SUB0000 is executed.

UnitData <Processing unit No.> gosub *SUB0000

Command example 3:

A program is loaded from the file C:\Program.mcr.

UnitData <Processing unit No.> load C:\Program.mcr

Command example 4:

A program is saved to the file C:\Program.mcr.

UnitData <Processing unit No.> save C:\Program.mcr

Important

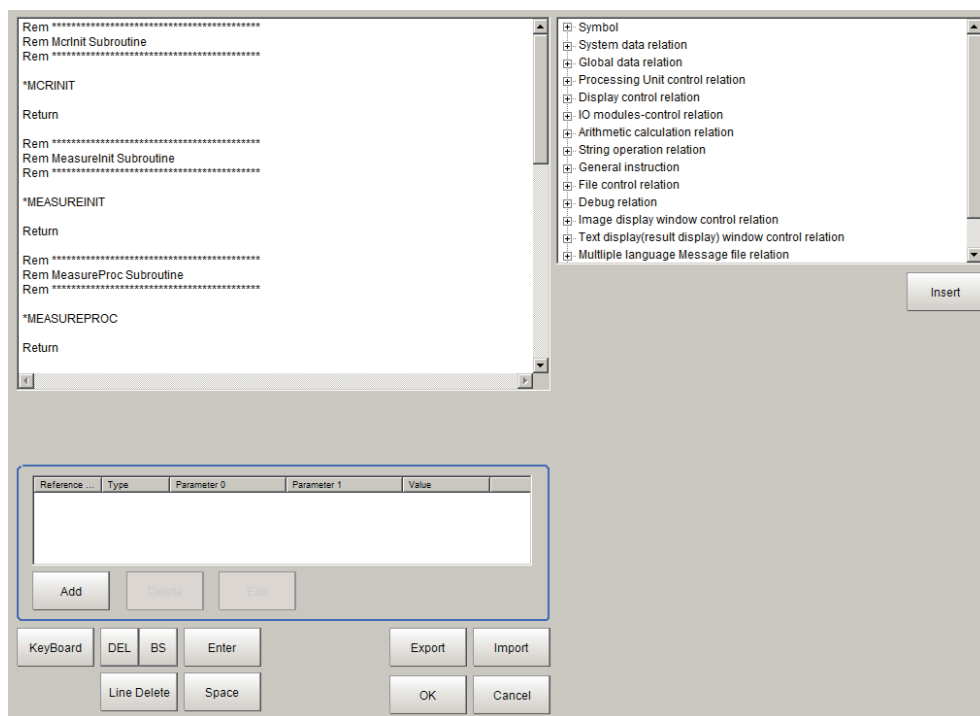
- The values of macro variables will not change even after "Clear measurement" is executed.

Setting Macro Code (Macro)

Define the processing to be executed at each timing of measurement processing.

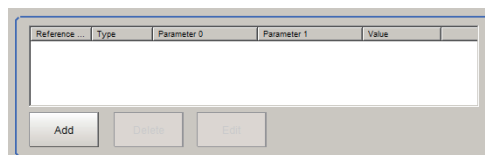
1 Click the [Macro] icon on the Main screen or Edit Flow window.

The setting window is displayed.



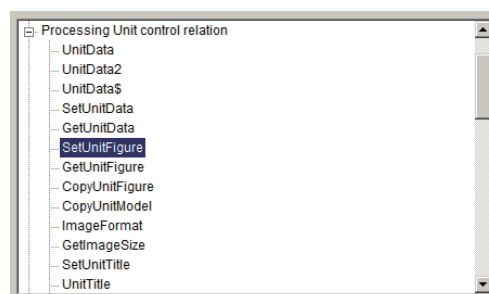
2 Set the reference variable.

Reference: ▶ Setting Reference Variable (Macro) (p.524)

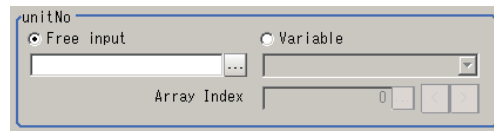


3 From the function list, select the function to be inserted.

When the function is selected, an operand list appears below the function list.



4 Set the operand.



Setting item	Setting value [Factory default]	Description
Operand input method	• [Free input]	Select this option if you want to enter an operand freely. Click [...] to set the operand.
	• Variable	Select this option if you want to select an operand from variables. Click [▼] to select the variable. You can select any variable or reference variable currently defined in the macro code.
Array Index	0 to number of arrangements [0]	If the selected variable is an arrangement variable, set the arrangement number to be used as an operand.

5 Click [Insert].

The set function is registered and appears in the code edit window in the top left-hand corner.



6 Repeat steps 2 to 5, and set the macro code.

7 When the setting of macro code is complete, click [OK].

Important

Do not access other unit or system data in the display event processing.

- Display processing may operate in parallel with measurement processing, etc. This gives rise to the possibility of a data access error. Make sure a value is assigned to a local variable in the measurement processing beforehand, so that the value-assigned local variable can be accessed in display processing.

Console display on FZ5-3xx and FZ5-6xx sensor controllers

- When a macro error occurs, the console is displayed in the full-screen mode. Do not close the console, but connect a USB keyboard and press [Ctrl]+[Alt] to switch the screen instead. If the console is closed, the sensor controller may no longer operate properly.

Loading Macro Code (Macro)

The macro code output by [Macro] is loaded.

1 Click [Load] on the macro code setting screen.

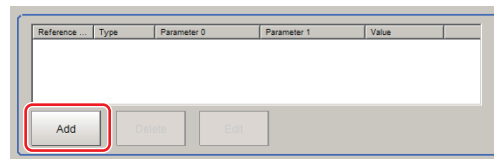
2 Select the file (.mcr) in which the macro code you would like to load has been saved, and then click [OK].

Setting Reference Variable (Macro)

Set up the reference variables used for function.

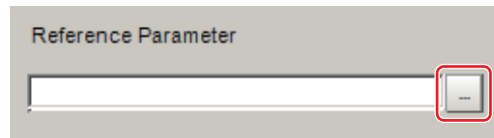
- 1 Click [Add] in the reference variable list on the macro setting screen.

A reference variable window is displayed.

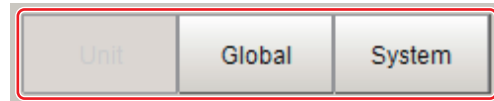


- 2 Click [...] to set the variable name.

The variable name must consist of alphanumeric characters beginning with a capital letter.

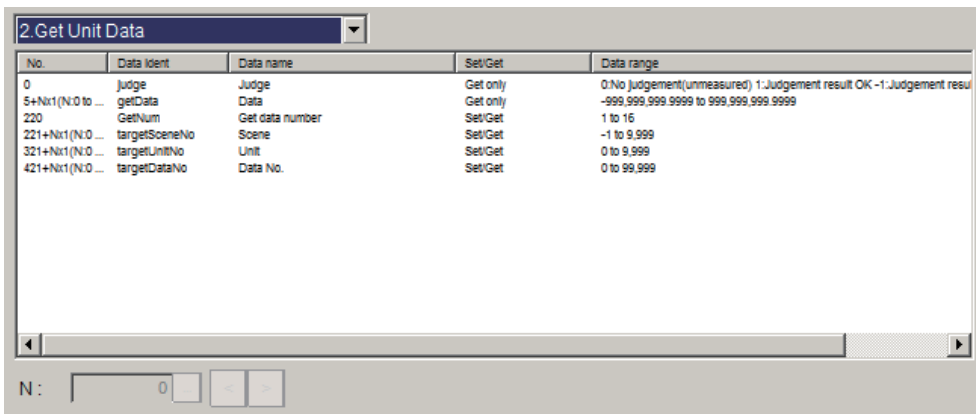


- 3 Set the variable to be referenced.



If Unit is selected

Select the processing item to be referenced, and then select the data to be referenced from the list.



If Global is selected

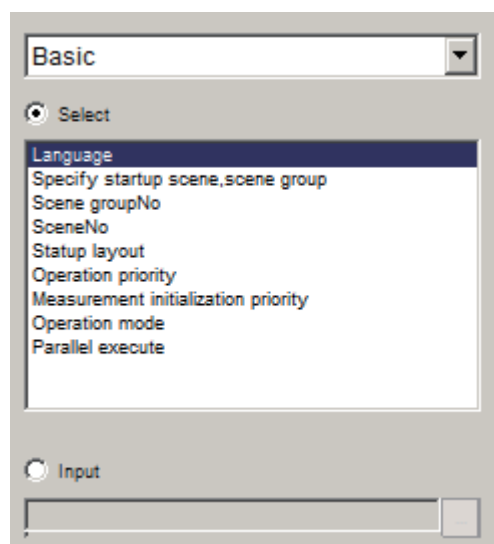
Click [...] to set the variable value.



If System is selected

Place a check at applicable [Select] to select the type of system variable, and then select the variable to be referenced from the list.

To set a variable value, place a check at [Enter] and then click [...] to set the variable value.



- 4 Click [OK].

Key Points for Test Measurement and Adjustment (Macro)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image.	Explanation of image to be displayed
0	Measurement image

Key Points for Adjustment

Select the adjustment method referring to the following points.

An error message appears on the console

Parameter to be adjusted	Troubleshooting
-	Refer to the error messages list. Reference: ▶ "Appendixes About Macro Functions List of Macro Error Messages" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Nothing happens when [DEL], [BS], [Enter], etc., is clicked

Parameter to be adjusted	Troubleshooting
-	Nothing happens while the focus is not on the code window (key entry cursor is not displayed). Click the position you want to operate, and then click the button.

Want to include a line feed code in a string

Parameter to be adjusted	Troubleshooting
Macro code	Add (+) CR → Chr\$(13) LF → Chr\$(10) to the string.

The "Positions" display is not as desired

Parameter to be adjusted	Troubleshooting
Macro code	When "Positions" is OFF, the display processing written in "**MEASUREDISPT" and "**MEASUREDISPG" is executed. When "Positions" is ON, only what is written in "**MEASUREDISPG" is displayed.

Data acquisition sometimes fails during measurement

Parameter to be adjusted	Troubleshooting
Macro code	Data may be stolen by the applicable communication processing unless the communication processing is stopped using the SetPollingState function. (Example) Receive data without TCP procedure Write the processing in the following sequence. <ul style="list-style-type: none"> • SetPollingState "TcpNormal", false • Data receive processing • SetPollingState "TcpNormal", true

Macro Calculation

You can perform calculations, as well as setting/acquiring.

This function is convenient when the user wants to calculate a value using an original calculation formula or change the set value or system data of a processing item.

Used in the Following Case

- **Calculations that use multiple processing items including looping and conditional branch can be consolidated into one.**

Example) When you want to use a different calculation formula depending on the condition

- Using a flow: Realized by combining Conditional Branch and Calculation.
- Using macro calculation: Define in a macro calculation processing item a calculation processing that uses a calculation formula appropriate for each condition.

A flow can be made simpler using macro calculation.

- **A set of multiple processing items can be consolidated into one processing when, for example, changing the settings of multiple processing depending on the condition.**

Example) When you want to change the labeling extraction condition depending on the sorting result

- Using a flow: Realized by combining Conditional Branch, Calculation and Set Unit Data.
- Using macro calculation: Register a reference variable representing the labeling extraction conditions and define a processing that assigns a value to the variable according to each condition.

A flow can be made simpler using macro calculation.

Setting Calculation Processing (Macro Calculation)

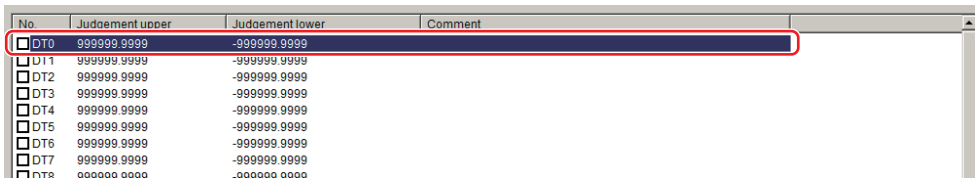
32 calculation processes from "DT0" to "DT31" can be set per unit.

Note

- Calculation results cannot be output to external devices when you only set up macro calculations. When calculation results are output to external devices, set processing items related to results output in units after "Macro calculation" with flow editing.

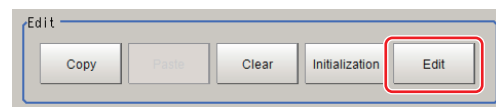
Reference: ▶ Output result (p.749)

1 From the list, click the operator of the calculation processing to be set.

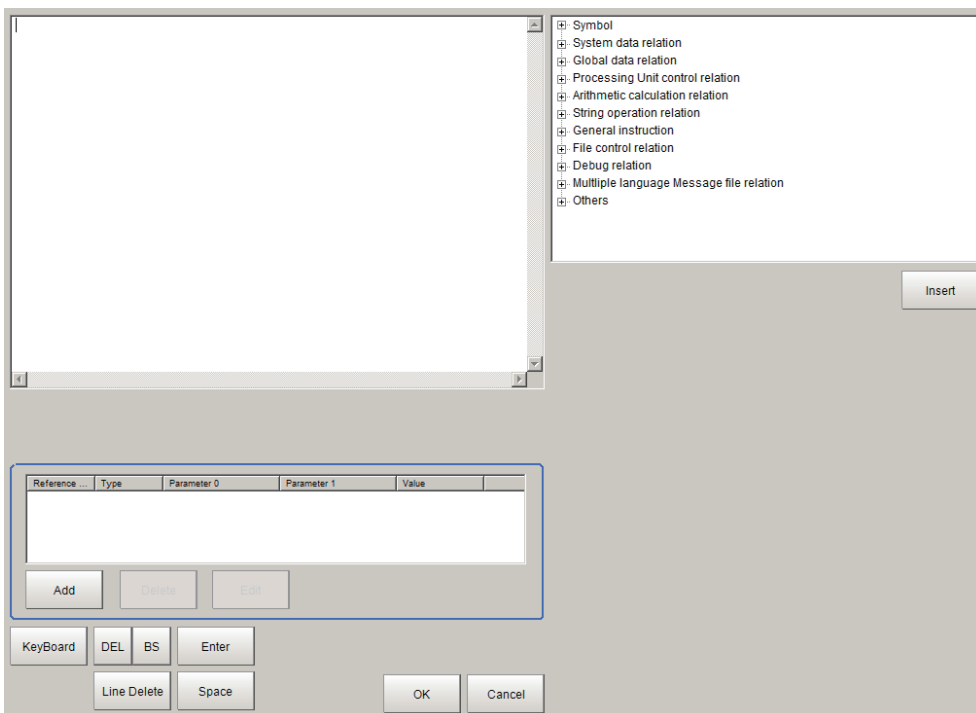


No.	Judgement upper	Judgement lower	Comment
<input checked="" type="checkbox"/> DT0	999999.9999	-999999.9999	
<input type="checkbox"/> DT1	999999.9999	-999999.9999	
<input type="checkbox"/> DT2	999999.9999	-999999.9999	
<input type="checkbox"/> DT3	999999.9999	-999999.9999	
<input type="checkbox"/> DT4	999999.9999	-999999.9999	
<input type="checkbox"/> DT5	999999.9999	-999999.9999	
<input type="checkbox"/> DT6	999999.9999	-999999.9999	
<input type="checkbox"/> DT7	999999.9999	-999999.9999	
<input type="checkbox"/> DT8	999999.9999	-999999.9999	

2 In the Edit area, click [Edit].

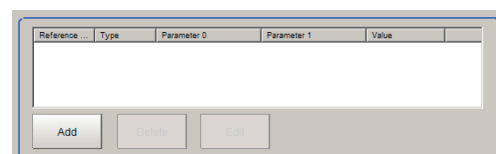


The macro calculation setting window is displayed.



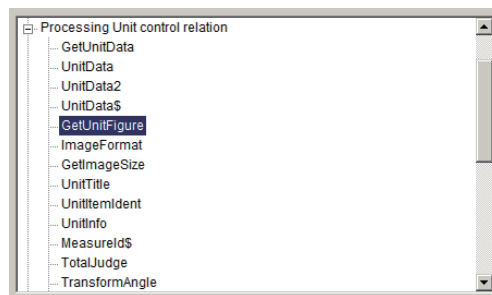
3 Set the reference variable.

Reference: ▶ Setting Reference Variable (Macro Calculation) (p.530)

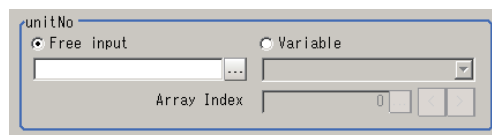


4 From the function list, select the function to be inserted.

When the function is selected, an operand list appears below the function list.



5 Set the operand.



Setting item	Setting value [Factory default]	Description
Operand input method	[Free input]	Select this option if you want to enter an operand freely. Click [...] to set the operand.
	Variable	Select this option if you want to select an operand from variables. Click [▼] to select the variable. You can select any variable or reference variable currently defined in the macro code.
Array Index	0 to number of arrangements [0]	If the selected variable is an arrangement variable, set the arrangement number to be used as an operand.

6 Click [Insert].

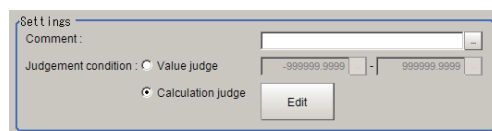
The set function is registered and appears in the code edit window in the top left-hand corner.



7 Repeat steps 3 to 6, and set the calculation processing.

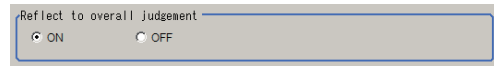
8 When the setting of calculation processing is complete, click [OK].

9 Set judgement conditions in the "Settings" area.



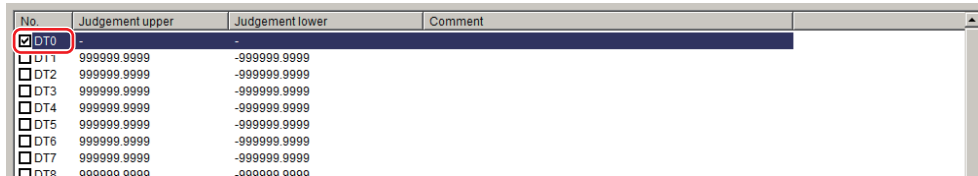
Setting item	Setting value [Factory default]	Description
Comment	-	Enter a comment on the calculation processing you have selected from the list.
Judgement condition	<ul style="list-style-type: none"> • [Value judge] • Calculation judge 	Select whether to use a figure or macro judgement for the calculation result. If figure judgement selected, set the upper/lower limits of OK judgement. If macro judgement is selected, click [Edit] and define the calculation processing to be performed on the calculated value.

- 10** Select whether or not to reflect the judgement result in the scene overall judgement in "Reflect to overall judgement" area.



Setting item	Setting value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • [OFF] 	Specify whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

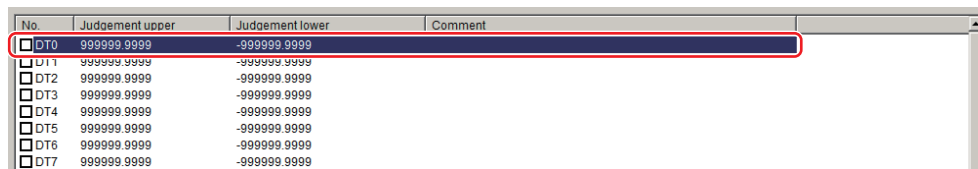
- 11** Place a check at the operator to use to perform the calculation processing.



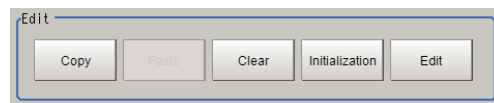
Editing Operator (Macro Calculation)

The calculation processing you have set can be copied or cleared.

- 1** From the list, click the operator of the calculation processing whose setting is to be edited.



- 2** Select each operation in the "Edit" area.

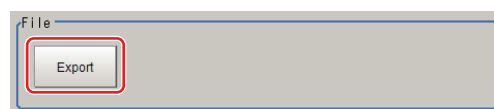


Item	Description
Copy	Copy the setting of the operator you have selected from the list. The copied setting can be pasted to other operator via [Paste].
Paste	Paste the copied set value to the operator selected from the list. Data that can be pasted includes valid/invalid flags, calculation macro codes, comments, judgement flags, upper/lower limits of figure judgement and judgement macro codes.
Clear	Initialize the setting of the operator you have selected from the list. Data to be initialized includes valid/invalid flags, calculation macro codes, comments, judgement flags, upper/lower limits of figure judgement and judgement macro codes.
Initialization	Initialize the settings of all operators.
Edit	Edit the setting of the operator you have selected from the list. Reference: ▶ Setting Calculation Processing (Macro Calculation) (p.527)

Outputting Macro Code (Macro Calculation)

Export the set calculation processing to a file.

- 1** Click [Export] in the "File" area.



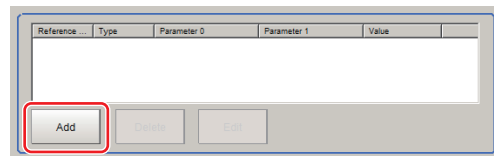
- 2** Specify the folder and file name, and then click [OK].

Setting Reference Variable (Macro Calculation)

Set up the reference variables used for function.

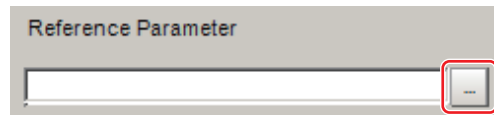
- 1 On the macro calculation setting screen, click [Add] in the reference variable list.

A reference variable window is displayed.

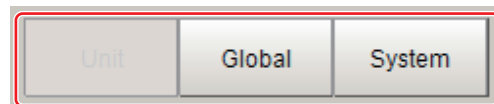


- 2 Click [...] to set the variable name.

The reference variable name must consist of alphanumeric characters beginning with a capital letter.



- 3 Set the variable to be referenced.



If Unit is selected

Select the processing item to be referenced, and then select the data to be referenced from the list.

No.	Data Ident	Data name	Set/Get	Data range
0	Judge	Judge	Get only	0:No judgement(unmeasured) 1:Judgement result OK -1:Judgement resu
5+Nxt1(N:0 to ...	getData	Data	Get only	-999,999,999,9999 to 999,999,999,9999
220	getNum	Get data number	Set/Get	1 to 16
221+Nxt1(N:0 ...	targetSceneNo	Scene	Set/Get	-1 to 9,999
321+Nxt1(N:0 ...	targetUnitNo	Unit	Set/Get	0 to 9,999
421+Nxt1(N:0 ...	targetDataNo	Data No.	Set/Get	0 to 99,999

If Global is selected

Click [...] to set the variable value.

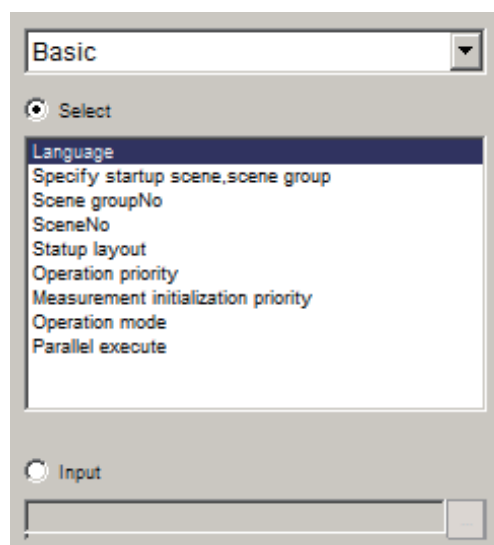


If System is selected

Place a check at applicable [Select] to select the type of system variable, and then select the variable to be referenced from the list.

To enter a variable value, place a check at [Input] and then click [...] to set the variable value.

- 4 Click [OK].



Key Points for Test Measurement and Adjustment (Macro Calculation)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Calculation 0 comment	Calculation 0 value
Calculation 1 comment	Calculation 1 value
:	:
Calculation 31 comment	Calculation 31 value

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image.	Explanation of image to be displayed
0	Measurement image

Key Points for Adjustment

Select the adjustment method referring to the following points.

An error message appears on the console

Parameter to be adjusted	Troubleshooting
-	Refer to the error messages list. Reference: ► "Appendixes About Macro Functions List of Macro Error Messages" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Nothing happens when [DEL], [BS], [Enter], etc., is clicked

Parameter to be adjusted	Troubleshooting
-	Nothing happens while the focus is not on the code window (key entry cursor is not displayed). Click the position you want to operate, and then click the button.

Want to include a line feed code in a string

Parameter to be adjusted	Troubleshooting
Macro code	Add (+) CR → Chr\$(13) LF → Chr\$(10) to the string.

Calculation result is indicated as "Unmeasured"

Parameter to be adjusted	Troubleshooting
Enabled/disabled	Place a check to enable the operator.
Calculation judgement	The judgement result may not be set correctly in calculation judgement.

Measurement Results for Which Output Is Possible (Macro Calculation)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Calculation result 0	DT00	Calculation result 0
Judgement result 0	JG00	Judgement result 0
:		
Calculation result 31	DT31	Calculation result 31
Judgement result 31	JG31	Judgement result 31

External Reference Tables (Macro Calculation)

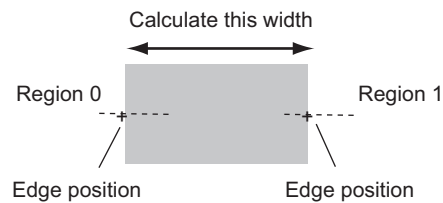
No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5 + N × 1 (N = 0 to 31)	Calculation result N (N = 0 to 31)	Set/Get	-99999.9999 to 99999.9999
37 + N × 1 (N = 0 to 31)	Judgement result N (N = 0 to 31)	Get only	-99999.9999 to 99999.9999

Calculation

Used in the Following Case

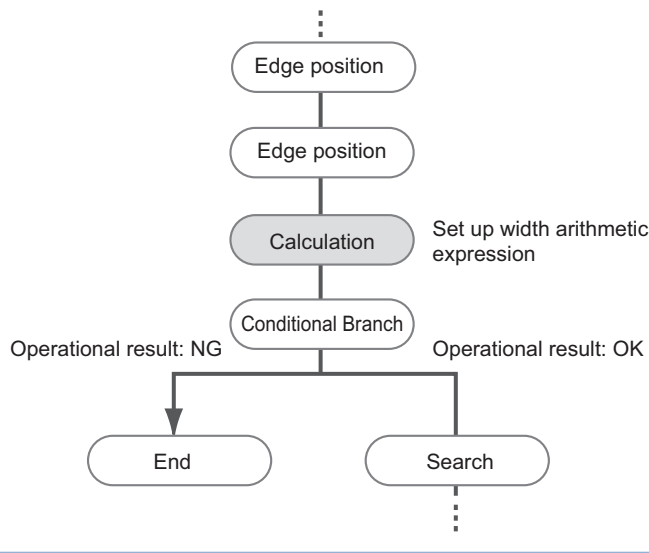
- When changing the inspection details through use of calculation results

Example) Calculating the width of the measurement object Width calculation can be performed by first calculating two edge positions and setting up the arithmetic expression which is used to calculate the edge position difference.



Width = the edge position of Area 0 – the edge position of Area 1

By combining Calculation and Conditional Branch, the following measurement contents can be changed based on the operational result.



- When performing calculation by using the calculation results of other processing units.

Settings (Calculation)

Up to 8 expressions "Calculation 0" to "Calculation 7" can be set up in one single unit.

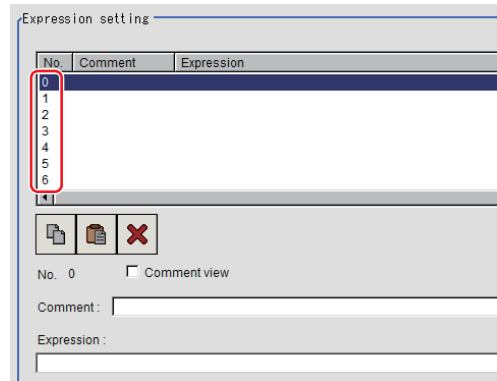
Note

- Calculation results cannot be output to external devices when you only set up expressions. When calculation results are output to external devices, set processing items related to results output in units after "Expression" with flow editing. Reference: ▶ Output result (p.749)

1 In the Item Tab area, click [Setting].

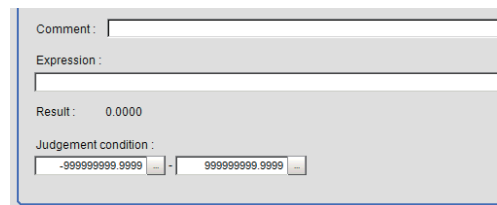
2 Click the "No." for setting up the expression from the list in the "Expression setting" area

The number selected will be displayed below the list.



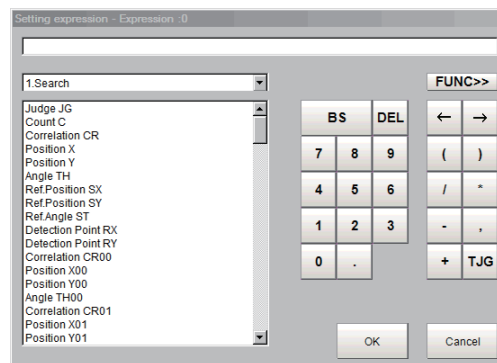
3 Click [...] for the Expression.

The Setting Expression window is displayed.



4 Set up the expression.

Sub-menus that can be set in expressions depending on the processing unit are displayed. When the sub-menu is clicked, it is added to the Expression.



Reference: ▶ Layout of Setting Expression Window (p.535)

5 After setting up the expression, click [OK].

The expression is confirmed.

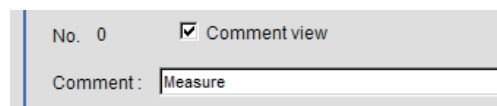
Note

If an error message is displayed, please check the following points.

- Unit value, numbers, function or TJK settings should be just before or just behind operator.
- Operators and commas "," should not be placed at the start or end of an expression.
- Operators cannot be input continuously.
- TJK/Unit value/Functions cannot be input continuously.
- The left and right parentheses "(") should be used together.
- Please ensure that the function argument is set.

6 Click [...] for "Comment" and input an explanation of the expression as necessary.

7 To display comments in the "Detail result display" area, check "Comment view".



8 Set up the judgement upper limit and the judgement lower limit for "Judgement condition".

Setting item	Set value	Description
Judgement condition	-999999999.9999 to 999999999.9999	This is a judgement condition for the expression. Set upper and lower limits for judging as OK.

9 Repeat the Steps Reference: ▶ 2 (p.534) to Reference: ▶ 8 (p.535) and set up the expression.

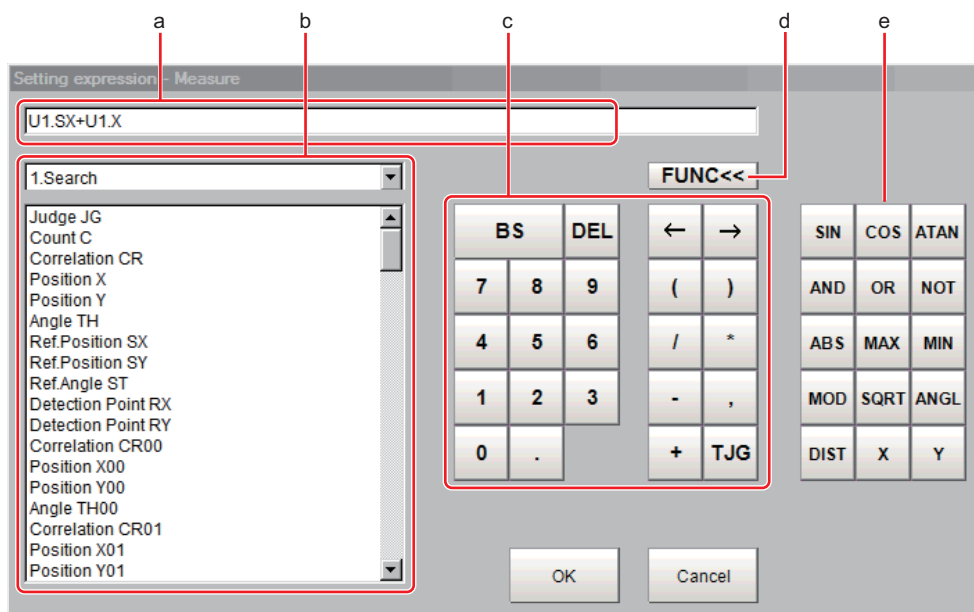
Output Parameters (Calculation)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Choose whether or not to reflect this in the scene overall judgement in "Reflect to overall judgement" area.

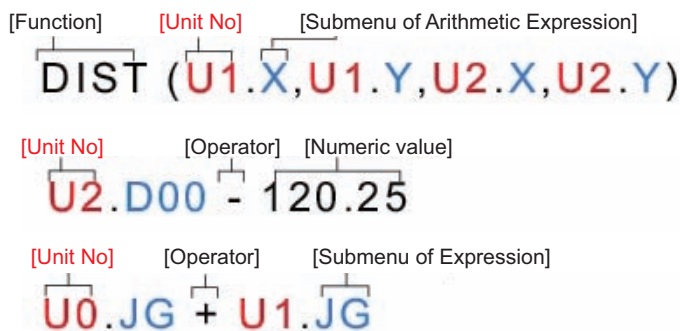
Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Layout of Setting Expression Window



a Expression Display Area

This area is for setting expressions. The expressions are displayed in the following manner.



b Unit Area

This area is where processing item values set in unit are selected. Clicking [▼] displays the unit number and unit name that have been set up in the currently displayed scene. Select the unit and then select items from sub-menus displayed for use in calculation.

Reference: Each processing item "Measurement Results for Which Output Is Possible"

3 General Button Area

These common buttons are required for editing expressions. Numbers and operators can be input here.

Button	Type	Description
BS	-	Deletes the item directly in the front of the cursor in the expression display area.
DEL	-	Deletes the item directly behind the cursor in the expression display area.
0 to 9	Numerical number	Numbers will be displayed at the cursor position in the expression display area. The number range that can be set up is from -999999999.9999 to 999999999.9999.
.	Symbol	A dot "." will be displayed at the cursor position in the expression display area.
←	Movement	The cursor in the expression display area moves one space to the left.
→	Movement	The cursor in the expression display area moves one space to the right.
(Symbol	Used to set off the numerical expression. Used in pairs with ")".
)	Symbol	Used to set off the numerical expression. Used in pairs with "(".
/	Operator	Indicates division for real numbers.
*	Operator	Indicates multiplication.
-	Operator	Indicates subtraction.
,	Symbol	A comma "," will be displayed at the cursor position in the expression display area.
+	Operator	Indicates addition.
TJG	-	Acquires the overall judgement result for all units ahead of the unit number in which an expression has been set. Reference: ► Conditional Branch Settings Examples (p.726)

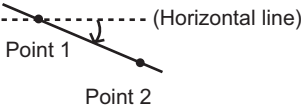
d [FUNC]

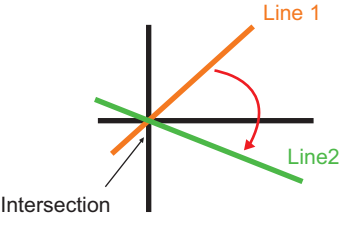
Display/Hide the function button area.

e Function Button Area

Buttons for inputting functions.

Function	Description
SIN (equation)	Calculates the sine. The result will be returned within the range of -1 to 1. Indicates the angle designated in the numerical expression in degrees.
COS (equation)	Calculates the cosine. The result will be returned within the range of -1 to 1. Indicates the angle designated in the numerical expression in degrees.
ATAN (Y-axis component, X-axis component)	Calculates the arc tangent of the Y-axis component/X-axis component. The result will be returned in radians within the range of $-\pi$ and π . (Example) For calculation of the angle between the straight line that connects the centers of gravity of area 0 and area 1 and a horizontal line ATAN (R1.Y-R0.Y, R1.X-R0.X) When both operands equal 0, calculation will return a result of 0 and OK will display.
AND (operand 1, operand 2)	Calculates the logical product. When one of two operands is 0, calculation will return a result of 0, and for all other cases, will return a result of -1.

Function	Description
OR (operand 1, operand 2)	Calculates the logical sum. When both operands are 0, calculation will return a result of 0 and for all other cases, will return a result of -1.
NOT (operand)	Calculates the logical NOT. When the operands equal 0, calculation will return a result of -1 and for all other cases, will return a result of 0 be returned.
ABS (operand)	Calculates the absolute value.
MAX (operand 1, operand 2)	The larger of 2 operands will be returned.
MIN (operand 1, operand 2)	The smaller of 2 operands will be returned.
MOD (dividend, divisor)	Calculates the remainder when dividing the dividend with the divisor. To calculate the remainder, if the number being used is a real number, round off the portion after the decimal point of the real number and then execute the calculation. The result is the remainder after division of the integer. (Example) MOD (13.4) Result: 1 (the remainder when dividing 13 by 4) MOD (25.68,6.99) Result: 5 (the remainder when dividing 26 by 7)
SQRT (operand)	Calculates the square root. When the operand is a negative number, calculation will return a result of 0. Judgement will be NG.
ANGL (Y-axis component, X-axis component)	Calculates the angle made by straight line that connects 2 points (center of gravity/center of model). Calculates the angle relative to the horizontal line. The result will be returned within the range of -180 to 180. (Example) When calculating the angle produced by the straight lines that join the gravity of Area 0 and that Area 1 ANGL (R1.Y-R0.Y, R1.X-R0.X)  When both the two operands are equal to 0, "0" will be returned, and the judge will become NG.
ANGL (first linear coefficient A, first linear coefficient B, first linear coefficient C, second linear coefficient A, second linear coefficient B, second linear coefficient C)	Calculate the angle of Line 1 and Line 2 in the part that does not go across the Y axis. The same angle can be obtained from both Line 1 and Line 2. (Example) Use line data at scan edge position 1 and scan edge position 2 to obtain the angle formed by the two lines ANGL (U1.A, U1.B, U1.C, U2.A, U2.B,U2.C)
DIST (X-coordinate of first point, Y-coordinate of first point, X-coordinate of second point, Y-coordinate of second point)	Calculates the distance between 2 points (center of gravity/center of model). (Example) When calculating the distance between the gravity of Area 0 and that of Area 1. DIST (R0.X,R0.Y,R1.X,R1.Y) The following calculation will be performed internally. $\sqrt{(R1.X-R0.X)^2 + (R1.Y-R0.Y)^2}$

Function	Description
DIST (Linear coefficient A, linear coefficient B, linear coefficient C, X coordinate, Y coordinate)	<p>A line and a point are specified to obtain the vertical distance between the line and point.</p>  <p>(Example) Obtain the distance between the linear regression at scan edge position 1 and edge position 2 DIST (U1.A, U1.B, U1.C, U2.X, U2.Y)</p>
X (first linear coefficient A, first linear coefficient B, first linear coefficient C, second linear coefficient A, second linear coefficient B, second linear coefficient C)	<p>Calculates intersection (X coordinate) of data for 2 lines (Example) Obtain the X coordinate of the intersection between the lines at scan edge position 1 and scan edge position 2 X (U1.A,U1.B,U1.C,U2.A,U2.B,U2.C)</p>
Y (first linear coefficient A, first linear coefficient B, first linear coefficient C, second linear coefficient A, second linear coefficient B, second linear coefficient C)	<p>Calculates intersection (Y coordinate) of data for 2 lines (Example) Obtain the Y coordinate of the intersection between the lines at scan edge position 1 and scan edge position 2 Y (U1.A,U1.B,U1.C,U2.A,U2.B,U2.C)</p>

Expression Usage Examples

Perform Judgement by Combining Unit Judgement Results

Example 2: Perform judgement by combining the judgement results of unit 0 and unit 1

If a judgement of OK for both unit 0 and unit 1 is achieved, a judgement of OK for the calculation will be achieved.

Expression setting

No.	Comment	Expression
0	Measure	U0.JG+U1.JG
1		
2		
3		
4		
5		
6		

No. 0 Comment view

Comment: Measure

Expression:
U0.JG+U1.JG

Result: 0.0000

Judgement condition:
-99999999.9999 - 99999999.9999

Step1: The sum of the judgement results (U0.JG, U1.JG) for unit 0 and unit 1 is set up in the expression. The sum of adding the judgement value (1: OK/-1: NG) based on the unit 0 judgement conditions and the

judgement value (1: OK/-1: NG) based on the unit 1 judgement conditions is displayed in "Result".

Step2: The expression result of step 1 is judged based on judgement upper and lower limits.

When "2" is set for both the judgement upper and lower limits, the calculation judgement of OK is achieved when both units 0 and 1 are judged as OK.

Judgement results of unit 0 (Judgement value)	Judgement results of unit 1 (Judgement value)	Expression result (Summation results of judgement values for units 0 and 1)	Judgement result of expression
OK (1)	OK (1)	2	OK
NG (-1)	OK (1)	0	NG
OK (1)	NG (-1)	0	NG
NG (-1)	NG (-1)		NG





Using Values of Other Expressions

Up to 8 expressions can be set in 1 expression unit.

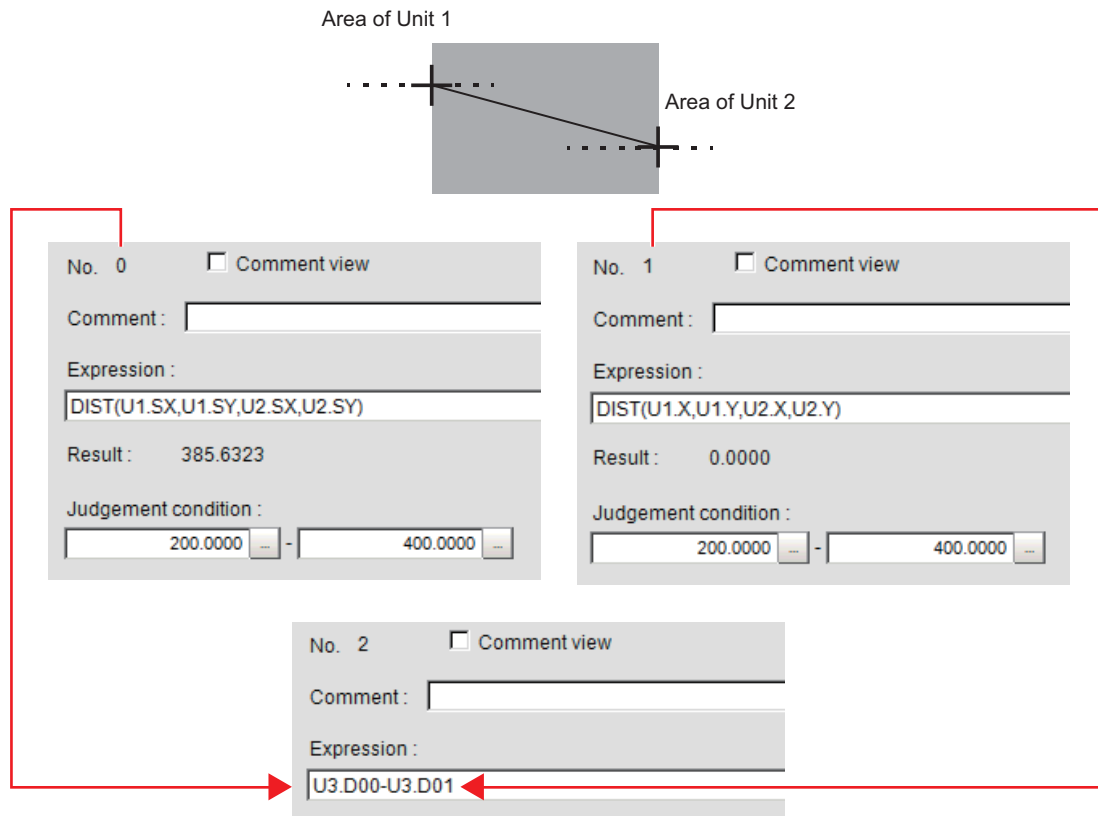
The value of other expressions set within the same unit can also be used.

Since expression results obtained by the expression are displayed as D00 to D07 and judgement results of expression are displayed as J00 to J07, this is set to "U3.D00" (results of expression 0 set for processing item [Calculation] of unit number "3") using "unit number calculation results".

For the following scene settings:

	0.Camera Image Input FH
	1.Edge Position
	2.Edge Position
	3.Calculation

Example 1: Calculate the reference position distance and measurement results distance for the edge position and output the difference between the two.



The diagram illustrates the setup for calculating the distance between two units. At the top, a grey rectangle represents 'Area of Unit 1' and a white rectangle represents 'Area of Unit 2'. A dashed line indicates the reference position of Unit 1, and a solid line indicates the measurement position of Unit 2. Below this, three expression settings are shown:

- No. 0:** Expression: `DIST(U1.SX,U1.SY,U2.SX,U2.SY)`. Result: 385.6323. Judgement condition: 200.0000 - 400.0000.
- No. 1:** Expression: `DIST(U1.X,U1.Y,U2.X,U2.Y)`. Result: 0.0000. Judgement condition: 200.0000 - 400.0000.
- No. 2:** Expression: `U3.D00-U3.D01`.

Red arrows indicate that the results of Expression 0 (D00) and Expression 1 (D01) are substituted into Expression 2 to calculate the difference.

Substitute the operational results of Expression 0 (D00) and Expression 1 (D01)

Set expressions in the following manner.

- **Calculation 0: DIST (U1.SX, U1.SY, U2.SX, U2.SY)**

This expression is used to calculate the distance between the reference positions of unit 1 and unit 2. The function "DIST" calculates the distance between 2 points.

- **Calculation 1: DIST (U1.X,U1.Y,U2.X,U2.Y)**

This expression is used to calculate the distance between the measurement positions of unit 1 and unit 2. The function "DIST" calculates the distance between 2 points.

• **Calculation 2: U3.D01-U3.D00**

(Unit 3: Calculation [Calculation 1] - Unit 3: Calculation [Calculation 0])

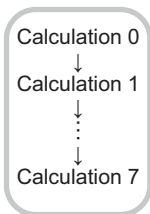
This equation is used to calculate the difference between results of Calculation 1 and Calculation 0 in unit 3 (in this example, Operation).

Note

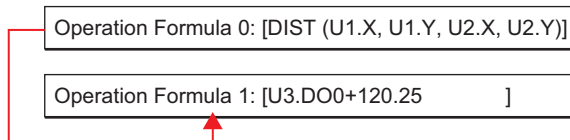
Calculating order of expressions

- Express that use the express results of other expressions must be set with an expression number that is higher than that of the substituted expression. If it is set with a number smaller than the number of the substituted expression, previous expression results of the substituted expression will be inserted.

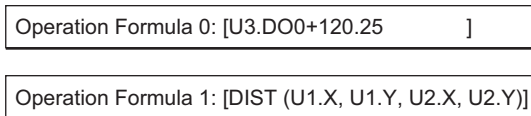
Calculating order



Calculate the distance between the two points in the inspection region in



When you substitute these equations with each other



Since the calculation of operation formula 0 is earlier than operation formula 1, the last operation result of operation formula 1 will be substituted into U3 D01

Counting Number of Measurements

No. 0 Comment view

Comment :

Expression :

The measurement count is counted by adding "1" to each calculation number 0.

Note

- When expression results are cleared or the power is turned off, U3.D00 will return to "0" and the measurement counts will also be reset.

Key Points for Test Measurement and Adjustment (Calculation)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Expression0	Expression result of Expression 0
Expression1	Expression result of Expression 1
Expression2	Expression result of Expression 2
Expression3	Expression result of Expression 3
Expression4	Expression result of Expression 4
Expression5	Expression result of Expression 5
Expression6	Expression result of Expression 6
Expression7	Expression result of Expression 7

Measurement Results for Which Output Is Possible (Calculation)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judgement result
Data 0	D00	Expression result of expression 0
Data 1	D01	Expression result of expression 1
Data 2	D02	Expression result of expression 2
Data 3	D03	Expression result of expression 3
Data 4	D04	Expression result of expression 4
Data 5	D05	Expression result of expression 5
Data 6	D06	Expression result of expression 6
Data 7	D07	Expression result of expression 7
Judge 0	J00	Judgement result of expression 0
Judge 1	J01	Judgement result of expression 1
Judge 2	J02	Judgement result of expression 2
Judge 3	J03	Judgement result of expression 3
Judge 4	J04	Judgement result of expression 4
Judge 5	J05	Judgement result of expression 5
Judge 6	J06	Judgement result of expression 6
Judge 7	J07	Judgement result of expression 7

External Reference Tables (Calculation)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5 to 12	Expression result of Expression 0 - Expression result of Expression 7	Set/Get	-999999999.9999 to 999999999.9999
13 to 20	Judgement result of Expression 0 - Judgement result of Expression 7	Get only	0: Unmeasured, 1: OK, -1: NG
103	Reflect to overall judgement	Set/Get	0: ON, 1: OFF
120	Upper limit 0 for judgement	Set/Get	-999999999.9999 to 999999999.9999
121	Lower limit 0 for judgement	Set/Get	-999999999.9999 to 999999999.9999
122	Upper limit 1 for judgement	Set/Get	-999999999.9999 to 999999999.9999
123	Lower limit 1 for judgement	Set/Get	-999999999.9999 to 999999999.9999
124	Upper limit 2 for judgement	Set/Get	-999999999.9999 to 999999999.9999
125	Lower limit 2 for judgement	Set/Get	-999999999.9999 to 999999999.9999
126	Upper limit 3 for judgement	Set/Get	-999999999.9999 to 999999999.9999
127	Lower limit 3 for judgement	Set/Get	-999999999.9999 to 999999999.9999
128	Upper limit 4 for judgement	Set/Get	-999999999.9999 to 999999999.9999
129	Lower limit 4 for judgement	Set/Get	-999999999.9999 to 999999999.9999
130	Upper limit 5 for judgement	Set/Get	-999999999.9999 to 999999999.9999
131	Lower limit 5 for judgement	Set/Get	-999999999.9999 to 999999999.9999
132	Upper limit 6 for judgement	Set/Get	-999999999.9999 to 999999999.9999
133	Lower limit 6 for judgement	Set/Get	-999999999.9999 to 999999999.9999
134	Upper limit 7 for judgement	Set/Get	-999999999.9999 to 999999999.9999
135	Lower limit 7 for judgement	Set/Get	-999999999.9999 to 999999999.9999

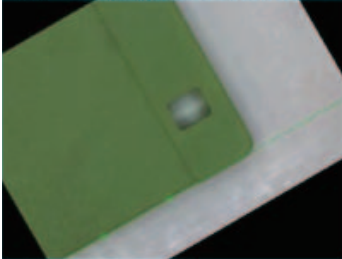
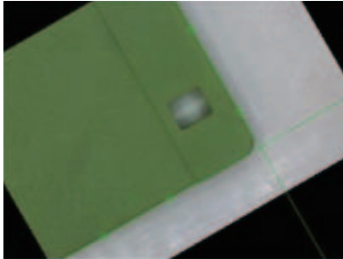
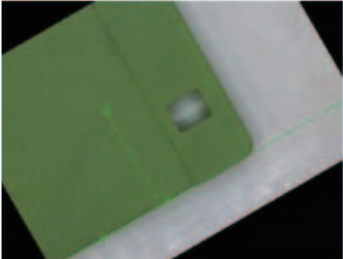
Line Regression

Calculates the line that generates the shortest total distance from multiple measurement coordinates (Line Regression).

It can also calculate the intersection and angle between two lines and the distance between a line and a point.

Used in the Following Case

- For computing a line and for calculating the intersection and distance of lines

<ul style="list-style-type: none"> • Approximate multiple measurement coordinates with a straight line 	<ul style="list-style-type: none"> • Calculate the intersection and angles of two lines. 	<ul style="list-style-type: none"> • Calculate the distance from the line to the point 
---	---	--

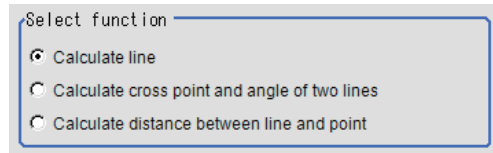
Important

- Do not set processing units that perform affine transformations such as position compensation between Line Regression and a unit that inputs for Line Regression.

Function Selection (Line Regression)

Functions are selected depending on application.

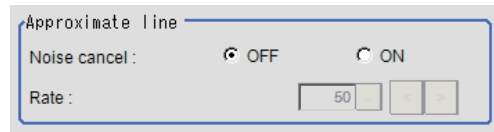
- 1 In the Item Tab area, click [Select function].
- 2 Select a function in the "Select function" area.



Setting item	Set value [Factory default]	Description
Select function	<ul style="list-style-type: none"> • [Calculate line] 	Calculates a straight line providing the shortest distance from multiple points (Line Regression). Set the Line 0 tab.
	<ul style="list-style-type: none"> • Calculate cross point and angle of two lines 	Calculates the intersection and angle between 2 Line Regressions. Set the Line 0 tab and Line 1 tab. The angle is measured from Line 0 to Line 1 in clockwise order.
	<ul style="list-style-type: none"> • Calculate distance between line and point 	Calculates the distance between a Line Regression and a point. Set the Line 0 and Point tab.

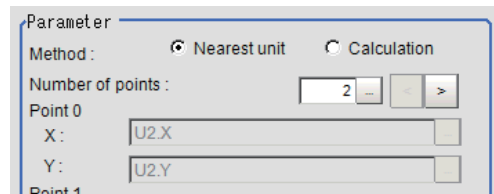
Line 0 (Line Regression)

- 1 In the Item Tab area, click [Line 0].
- 2 Set it to remove noise points when calculating lines.



Setting item	Set value [Factory default]	Description
Noise cancel	<ul style="list-style-type: none"> • [OFF] • ON 	When a check is placed at [ON], an approximate line is found by excluding the points with large deviation among the measured points.
Rate	0 to 100 [50]	Specify the ratio (%) of the points that are removed as noise.

- 3 Set each item in the "Parameter" area.



Setting item	Set value [Factory default]	Description
Method	<ul style="list-style-type: none"> • [Nearest unit] • Calculation 	<p>Nearest unit: Calculated from data of several continuous coordinate measurement units that were just performed. The number of units referenced is indicated by the Number of points. If a unit where coordinate measurement is not performed is included in Nearest unit, calculation will not be performed properly and measurement will be NG.</p> <p>Calculation: Calculated from expression set up.</p> <p>Reference: ► When Calculation is Selected (p.545)</p>
Number of points	[2] to 8	Set up the number of coordinate points used for calculation.

- 4 Click [OK].

When Calculation is Selected

- 1 Click [...] for the expression and set the expression.

The Setting Expression window is displayed.

Reference: ► Layout of Setting Expression Window (p.535)

- 2 After setting up the expression, click [OK].

The expression is confirmed.



Line 1 (Line Regression)

"Line 1" is only valid if "Calculate cross point and angle of two lines" is selected in Select function.

- The set up method is the same as for [Line 0].
- Reference: ► Line 0 (Line Regression) (p.545)

Point (Line Regression)

"Point" is only valid if "Calculate distance between line and point" is selected in "Select function".

- 1** Click [Point] in the Item Tab area.
- 2** Click [...] for the expression and set the expression.

The Setting Expression window is displayed.

- 3** After setting up the expression, click [OK].

The expression is confirmed.

Key Points for Test Measurement and Adjustment (Line Regression)

The following content can be confirmed in the "Detail result" area using text.

Displayed items	Description
Judge	Judgement result
Line parameter 0 A	Parameter A of line 0
Line parameter 0 B	Parameter B of line 0
Line parameter 0 C	Parameter C of line 0
Line parameter 1 A	Parameter A of line 1 (only displayed when calculating the intersection of 2 lines)
Line parameter 1 B	Parameter B of line 1 (only displayed when calculating the intersection of 2 lines)
Line parameter 1 C	Parameter C of line 1 (only displayed when calculating the intersection of two lines)
Cross point X	X coordinate of intersection (only displayed when calculating the intersection of two lines or calculating the distance between a line and a point)
Cross point Y	Y coordinate of intersection (only displayed when calculating the intersection of two lines or calculating the distance between a line and a point)
Angle	Angle between two lines (only displayed when calculating the intersection of two lines)
Point X	X coordinate of input point (only displayed when calculating the distance between a line and a point)
Point Y	Y coordinate of input point (only displayed when calculating the distance between a line and a point)
Distance	Distance between line 0 and an input point (only displayed when calculating the distance between a line and a point)

Measurement Results for Which Output Is Possible (Line Regression)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judge
Line Param. 0	A	Parameter A of line 0
Line Param. 0	B	Parameter B of line 0
Line Param. 0	C	Parameter C of line 0
Line Param. 1	A1	Parameter A of line 1
Line Param. 1	B1	Parameter B of line 1
Line Param. 1	C1	Parameter C of line 1
Cross point X	CX	X coordinate of intersection
Cross point Y	CY	Y coordinate of intersection
Angle	TH	Angle between two lines
Point X	PX	X coordinate of input point
Point Y	PY	Y coordinate of input point
Distance	DS	Distance between line 0 and input point

External Reference Tables (Line Regression)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Line Param. 0 A	Get only	-99999.9999 to 99999.9999
6	Line Param. 0 B	Get only	-99999.9999 to 99999.9999
7	Line Param. 0 C	Get only	-99999.9999 to 99999.9999
8	Line Param. 1 A	Get only	-99999.9999 to 99999.9999
9	Line Param. 1 B	Get only	-99999.9999 to 99999.9999
10	Line Param. 1 C	Get only	-99999.9999 to 99999.9999
11	Cross point X	Get only	-99999.9999 to 99999.9999
12	Cross point Y	Get only	-99999.9999 to 99999.9999
13	Angle	Get only	0.0000 to 180.0000
14	Point X	Get only	-99999.9999 to 99999.9999
15	Point Y	Get only	-99999.9999 to 99999.9999
16	Distance	Get only	0.0000 to 99999.9999
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
120	Function type	Set/Get	0: Calculate line 1: Calculate cross point and angle of two lines 2: Calculate distance between line and point

No.	Data name	Set/Get	Data range
121	Noise cancel 0	Set/Get	0: Noise cancel OFF 1: Noise cancel ON
122	Noise cancel 1	Set/Get	0: Noise cancel OFF 1: Noise cancel ON
123	Number of points 0	Set/Get	2 to 8
124	Number of points 1	Set/Get	2 to 8
125	Method 0	Set/Get	0: Nearest unit 1: Expression
126	Method 1	Set/Get	0: Nearest unit 1: Expression
130	Expressions (Line 0 Point 0 coordinate X)	Set/Get	Exp. character string
131	Expressions (Line 0 Point 0 coordinate Y)	Set/Get	Exp. character string
132	Expressions (Line 0 Point 1 coordinate X)	Set/Get	Exp. character string
133	Expressions (Line 0 Point 1 coordinate Y)	Set/Get	Exp. character string
134	Expressions (Line 0 Point 2 coordinate X)	Set/Get	Exp. character string
135	Expressions (Line 0 Point 2 coordinate Y)	Set/Get	Exp. character string
136	Expressions (Line 0 Point 3 coordinate X)	Set/Get	Exp. character string
137	Expressions (Line 0 Point 3 coordinate Y)	Set/Get	Exp. character string
138	Expressions (Line 0 Point 4 coordinate X)	Set/Get	Exp. character string
139	Expressions (Line 0 Point 4 coordinate Y)	Set/Get	Exp. character string
140	Expressions (Line 0 Point 5 coordinate X)	Set/Get	Exp. character string
141	Expressions (Line 0 Point 5 coordinate Y)	Set/Get	Exp. character string
142	Expressions (Line 0 Point 6 coordinate X)	Set/Get	Exp. character string
143	Expressions (Line 0 Point 6 coordinate Y)	Set/Get	Exp. character string
144	Expressions (Line 0 Point 7 coordinate X)	Set/Get	Exp. character string
145	Expressions (Line 0 Point 7 coordinate Y)	Set/Get	Exp. character string
146	Expressions (Line 1 Point 0 coordinate X)	Set/Get	Exp. character string
147	Expressions (Line 1 Point 0 coordinate Y)	Set/Get	Exp. character string
148	Expressions (Line 1 Point 1 coordinate X)	Set/Get	Exp. character string

No.	Data name	Set/Get	Data range
149	Expressions (Line 1 Point 1 coordinate Y)	Set/Get	Exp. character string
150	Expressions (Line 1 Point 2 coordinate X)	Set/Get	Exp. character string
151	Expressions (Line 1 Point 2 coordinate Y)	Set/Get	Exp. character string
152	Expressions (Line 1 Point 3 coordinate X)	Set/Get	Exp. character string
153	Expressions (Line 1 Point 3 coordinate Y)	Set/Get	Exp. character string
154	Expressions (Line 1 Point 4 coordinate X)	Set/Get	Exp. character string
155	Expressions (Line 1 Point 4 coordinate Y)	Set/Get	Exp. character string
156	Expressions (Line 1 Point 5 coordinate X)	Set/Get	Exp. character string
157	Expressions (Line 1 Point 5 coordinate Y)	Set/Get	Exp. character string
158	Expressions (Line 1 Point 6 coordinate X)	Set/Get	Exp. character string
159	Expressions (Line 1 Point 6 coordinate Y)	Set/Get	Exp. character string
160	Expressions (Line 1 Point 7 coordinate X)	Set/Get	Exp. character string
161	Expressions (Line 1 Point 7 coordinate Y)	Set/Get	Exp. character string
162	Expressions(Point coordinateX)	Set/Get	Exp. character string
163	Expressions(Point coordinateY)	Set/Get	Exp. character string
164	Rate 0	Set/Get	0 to 100
165	Rate 0	Set/Get	0 to 100

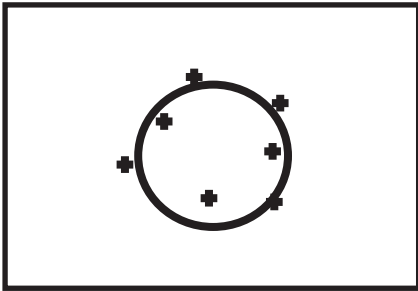
Circle Regression

Calculates the circle that generates the shortest total distance from multiple measurement coordinates (Circle Regression).

Used in the Following Case

- This is used when calculating the center and radius of a circle.

Use in cases in which an approximate circle is to be calculated from multiple measurement coordinates.

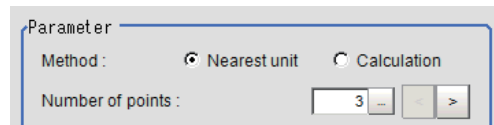


Important

- Do not set processing units that perform affine transformations such as position compensation between Circle Regression and a unit that inputs for Circle Regression.

Parameter Settings (Circle Regression)

- 1 Set each item in the "Parameter" area.



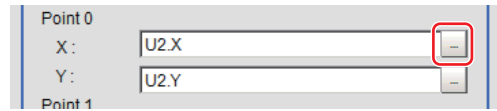
Setting item	Set value [Factory default]	Description
Method	<ul style="list-style-type: none"> • [Nearest unit] • Calculation 	<p>Nearest unit: calculated from the unit data of several continuous coordinates that were just measured. The number of units referenced is indicated by the Number of points. If a unit where coordinate measurement is not performed is included in Nearest unit, calculation will not be performed properly and measurement will be NG.</p> <p>Calculation: Calculated from expression set up.</p> <p>Reference: ▶ When Calculation is Selected (p.545)</p>
Number of points	[3] to 8	Set up the number of coordinate points used for calculation.

- 2 Click [OK].

When Calculation is Selected

- 1 Click [...] for the expression and set the expression.

The Setting Expression window is displayed.



- 2 After setting up the expression, click [OK].

The expression is confirmed.

Key Points for Test Measurement and Adjustment (Circle Regression)

The following content can be confirmed in the "Detail result" area using text.

Displayed items	Description
Judge	Judgement result
Central X	Central X
Central Y	Central Y
Radius R	Radius

Measurement Results for Which Output Is Possible (Circle Regression)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judgement	JG	Judge
Center Axis	X	Center Axis X
Center Axis	Y	Center Axis Y
Radius	R	Radius

External Reference Tables (Circle Regression)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Central X	Get only	-99999.9999 to 99999.9999
6	Central Y	Get only	-99999.9999 to 99999.9999
7	Radius	Get only	0 to 99999.9999
101	Output Coordinates	Set/Get	0: After scroll 1: Before scroll
102	Calibration	Set/Get	0: OFF 1: ON
121	Number of points	Set/Get	3 to 8
122	Method	Set/Get	0: Nearest unit 1: Expression
130	Expressions (Point0 coordinate X)	Set/Get	Exp. character string

No.	Data name	Set/Get	Data range
131	Expressions (Point0 coordinate Y)	Set/Get	Exp. character string
132	Expressions (Point 1 coordinate Y)	Set/Get	Exp. character string
133	Expressions (Point 1 coordinate Y)	Set/Get	Exp. character string
134	Expressions (Point 2 coordinate X)	Set/Get	Exp. character string
135	Expressions (Point 2 coordinate Y)	Set/Get	Exp. character string
136	Expressions (Point 3 coordinate X)	Set/Get	Exp. character string
137	Expressions (Point 3 coordinate Y)	Set/Get	Exp. character string
138	Expressions (Point 4 coordinate X)	Set/Get	Exp. character string
139	Expressions (Point 4 coordinate Y)	Set/Get	Exp. character string
140	Expressions (Point 5 coordinate X)	Set/Get	Exp. character string
141	Expressions (Point 5 coordinate Y)	Set/Get	Exp. character string
142	Expressions (Point 6 coordinate X)	Set/Get	Exp. character string
143	Expressions (Point 6 coordinate Y)	Set/Get	Exp. character string
144	Expressions (Point 7 coordinate X)	Set/Get	Exp. character string
145	Expressions (Point 7 coordinate Y)	Set/Get	Exp. character string

Precise Calibration

This corrects for camera tilt, and also corrects image distortion caused by the camera lens. Also, by setting the calibration, the measurement result can be converted and output as actual dimensions.

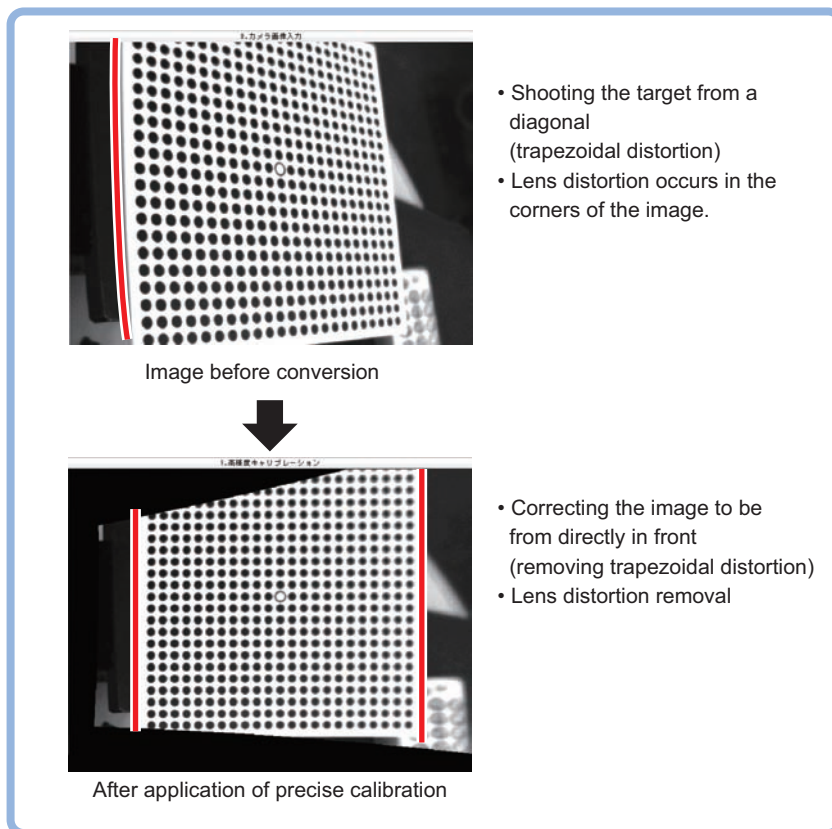
A calibration parameter that corrects coordinate values is generated in this processing item. There is no correction for area and other feature quantities.

Four actual coordinates must be indicated in order to perform a calibration.

Calibration is also available for camera image input and the calibration data from just prior to the unit referencing calibration data becomes effective.

Used in the Following Case

- Processing a trapezoidal image shot tilted to make it easier to inspect
- Processing an image that has lens distortion to make it easier to inspect
- Setting calibration for an image in which there is lens distortion or trapezoidal distortion



Important

- If these processing items are performed for an image for which other processing items are also being performed, the correction may not be performed correctly. Always perform these processing items immediately after image input from the camera.
- Please make sure the points taught for calibration are distributed evenly on the screen. If they are distributed unevenly, the correction may not be performed properly.
- About limits on the number of precise calibration used
The sensor controller and the camera place restrictions on the number of precise calibration processing items that can be used in the same scene group. Do not exceed these restrictions.

Type of sensor controller	0.3 megapixel camera	Intelligent compact camera	2 megapixel camera	5 megapixel camera	0.3 megapixel camera (FH)	2 megapixel camera (FH)	4 megapixel camera (FH)
FZ5-L35x FZ5-6xx	30	28	7	2	30	6	3
FZ5-11xx	150	140	40	15	150	35	20
FH-1xxx FH-3xxx	150	140	40	15	150	35	20

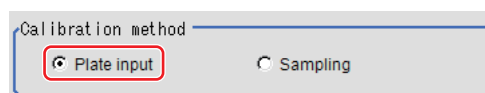
Calibration (Precise Calibration)

Set the input image conversion method (calibration parameters). This only calculates the parameters used in calibration. The actual correction is performed from the image correction tab.

Setting with the Pattern Plate

The parameters are calculated automatically by shooting the Omron pattern plate (FZD-CAL 3D Calibration tool).

- 1 In the Item Tab area, click [Calibration settings].
- 2 In the "Calibration method" area, select "Plate input".



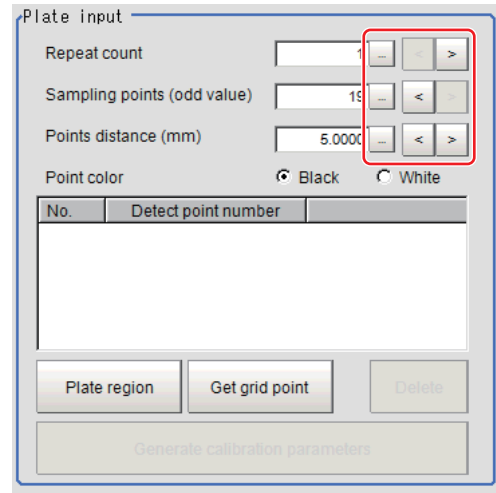
Setting item	Set value [Factory default]	Description
Calibration method	<ul style="list-style-type: none"> • [Plate input] • Sampling 	Set the calibration parameter setting method.

- 3 In the "Display" area, click [Change display] to switch between camera image types.

The displayed contents of the image display area will be switched.

Setting item	Set value [Factory default]	Description
Display	Through image display	The latest image is always input from the camera and displayed.
	[Freeze image]	The image that was scanned in the immediately preceding measurement is displayed.

4 Shoot the pattern plate and set each item.



Setting item	Set value [Factory default]	Description
Repeat count	1 to 10 [1]	Shooting the plate multiple times enables detection with grid points stabilized even for images with high noise levels. Input the number of repetitions.
Sampling points	5 to 19 [19]	Input the point string count for the pattern plate.
Points distance	1 to 1000 [5]	Input the point interval for the pattern plate. Input in millimeters (mm).

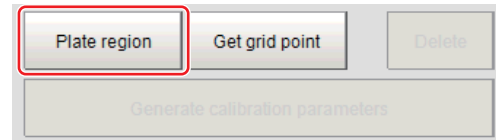
5 Set the plate region as necessary.

The default value setting is for the entire screen.

Note

- If anything other than the pattern plate is shot in the image, grid point extraction may fail. In this case, it is necessary to set the plate region.

Click [Plate region].

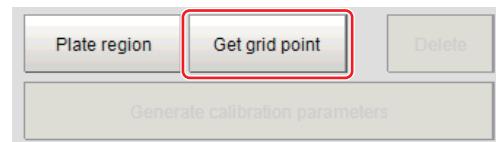


Use the drawing tools to specify the pattern plate range. In the figure setting area, click [OK].

The pattern plate range is registered.

6 Click [Get grid point].

The grid points gotten are listed in the Plate input area.



Note

- When the plate is small relative to the field of view, the plate is moved and the grid point is extracted multiple times. By selecting a through image and repeating Operations 4-6, the information can be scanned in for plates laid out at different positions.

7 Delete grid points as necessary.

Important

- After generating calibration parameters, if you delete grid points or change settings, the calibration parameters are deleted. In this case, it is necessary to generate new calibration parameters.
- The deleted grid points are deleted from the list.

Set the grid points to be deleted from the list.
Click [Delete].

No.	Detect point number
0	(361)

8 Click [Generate calibration parameters].

The calibration parameters will be generated.

Calibration status

Calibration parameters have been updated

Precision error	X max. (mm)	0.0973
	Y max. (mm)	0.0463

Setting Calibration through Sampling Measurement (Sampling)

This is a method for setting calibration based on measurement results.

Calibration parameters are calculated automatically when a registered model is searched and the actual coordinates for that position entered.

For actual coordinate input, input as at least two straight lines that make up straight lines parallel with the X and Y coordinates. Also, input at least 3 points for each straight line.

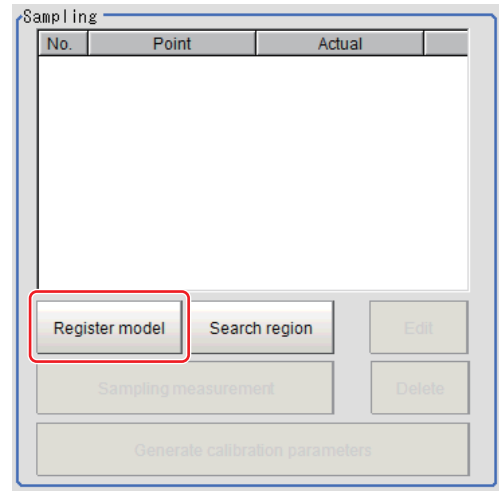
1 In the Item Tab area, click [Calibration settings].

2 In the "Calibration method" area, select "Sampling".

Calibration method

Plate input Sampling

- 3** In the "Sampling" area, click [Register model].



- 4** Use the Drawing tools to register the model.

- 5** Adjust the search region as necessary.

The default value setting is for the entire screen.

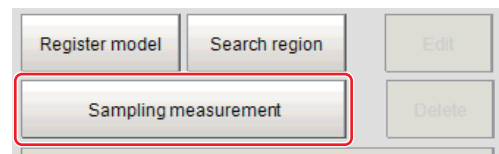
Click [Search region].

Use the drawing tools to specify the measurement region.

In the figure setting area, click [OK].

The area in which to perform filtering is registered.

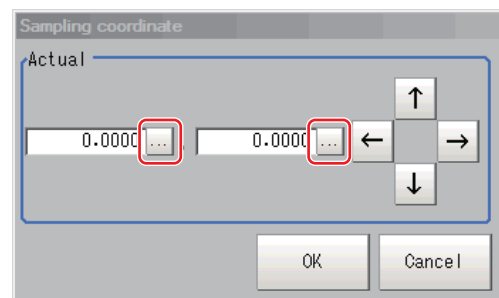
- 6** Click [Sampling measurement].



Measurement is performed.

The search result (cross-shaped cursor) is displayed in the image display area, and the Sampling Coordinate window is displayed.

- 7** In the sampling coordinate window, enter the X and Y values.



- 8** Click [OK].

Point coordinates and actual coordinates are registered in the "Sampling" area.

- 9** Move the measurement object and repeat the Steps Reference: ▶ 3 (p.557) to Reference: ▶ 8 (p.557).

- 10** Edit or delete coordinates as necessary.

Important

- After generating calibration parameters, if you edit or delete coordinates, the calibration parameters are updated.
- The deleted coordinates are deleted from the list.

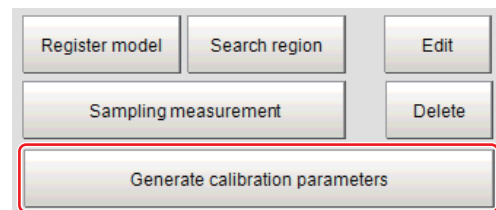
Set the grid points to be edited or deleted from the list.

Click [Edit] or [Delete].

No.	Point	Actual
0	(153,29)	(0,0)
1	(509,404)	(500,400)
2	(273,253)	(200,300)
3	(426,363)	(450,360)

If you clicked [Edit], execute StepReference: ▶ 7. (p.557)

11 Click [Generate calibration parameters].



The calibration parameters will be generated.

Calibration status		
Calibration parameters are generated		
Precision error	X max. (mm)	0.0110
	Y max. (mm)	0.0100

Note

- If the precision of input grid points is poor, parameter generation may fail. Set again so that the grid points are shown clearly.
- The precision error is a yardstick for calibration, not a guarantee of actual precision.

Height Adjustment (Precise Calibration)

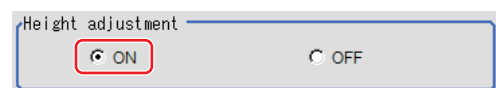
Even if the plane height is different for calibration and for measurement, adjust so that the correct coordinates can be corrected for.

Important

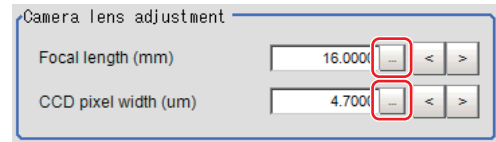
- The height adjustment is only valid when the camera is facing the measurement object level. If the camera is tilted, it may be impossible to correct the image accurately.
- The results of height adjustment are not applied to image correction.

1 In the Item Tab area, click [Height adjustment].

2 Select "ON" in the Height adjustment area.

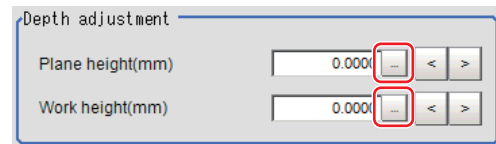


3 Input the numeric values in the Camera lens adjustment area.



Setting item	Set value [Factory default]	Description
Focal length	5 to 100 [16]	Input the focal distance of the camera used for shooting in mm.
CCD pixel width	3 to 8 [4.7]	Set the camera pixel size. Input in μm .

4 Input the numeric values in the Depth adjustment area.



Setting item	Set value [Factory default]	Description
Plane height	-100 to 100 [0]	Input the plate height in mm.
Work height	-100 to 100 [0]	Input the measurement object height in mm.

Important

- For the depth adjustment, input the height from the reference surface where the work is placed. Set the plate height and the work height from the reference surface.

Image Correction (Precise Calibration)

Execute actual image correction based on the parameters generated with the [Calibration settings] tab.

- 1 In the Item Tab area, click [Image correction].
- 2 Select "ON" in the Correction settings area.

When the calibration parameters generation is complete, the corrected image is displayed according to the settings.



Important

- If the grid points were distributed unevenly when the parameters were created, the image may not be corrected properly.
- When the image correction function is ON, only the left-hand coordinate system is supported when entering X and Y on the Sampling Coordinate window. If X and Y are entered in the right-hand coordinate system, the image is not converted normally.

Measurement Results for Which Output Is Possible (Precise Calibration)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Precise Calibration)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (not yet measured) 1: Judgement result OK -1: Judgement result NG
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Coordinate indication method	Set/Get	Select the grid point detection method. 0: Sampling 1: Pattern plate
121	Correction settings	Set/Get	0: Corrected image not output 1: Corrected image output
180	Sampling point line	Set/Get	Specify the extraction point count for the plate input.
181	Sampling point string	Set/Get	Specify the extraction point count for the plate input.
182	Sampling point interval	Set/Get	Specify the plate point interval for the plate input.
183	Grid point average repetition count	Set/Get	1 to 10
240	Focal distance of lens [mm]	Set/Get	5.0000 to 100.0000
241	CCD1 pixel size [μm]	Set/Get	3.4500 to 7.4000
242	Plate height [mm]	Set/Get	-100.0000 to 100.0000
243	Workpiece height [mm]	Set/Get	-100.0000 to 100.0000
244	Depth settings	Set/Get	0: Off 1: On
260	Margin/X maximum	Get only	-1.0000 to -1.0000
261	Margin/Y maximum	Get only	-1.0000 to -1.0000

User Data

User data consists of 100 counts of data that can be shared within the sensor controller. Once the user data is set, the values can be used by each of the processing units.

Used in the Following Case

- To share data that is arbitrarily set among multiple other units
- To share data across a scene or a scene group (In the multi-line random trigger operation mode, however, data cannot be shared beyond the lines.)
- To perform a measurement with the initial value set
- To save a measurement result and continue to perform another measurement process (User data can be saved via "Data save" even if the system is shut down.)
- To temporarily save data to a safe location as part of a processing flow

Setting (User Data)

User data can be modified on this processing unit. Data modified on the processing unit after this unit can be referenced.

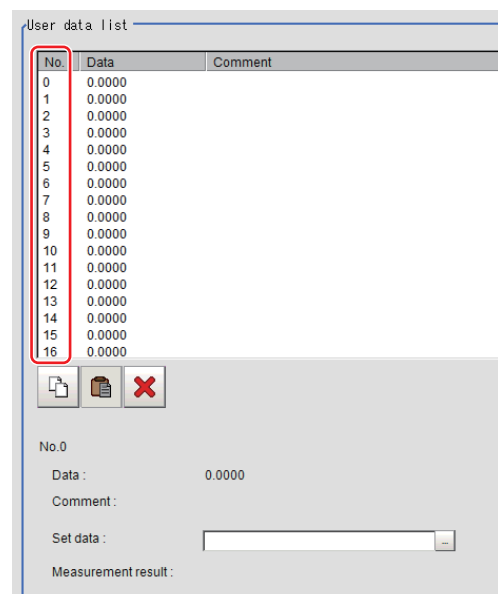
To set the initial value or a comment, select the [Tool] menu - [User data tool] from the Main screen.

Reference: ▶ "Chapter 4 Using Tool Using User Data Tool [Setting Methods of User Data]" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Note

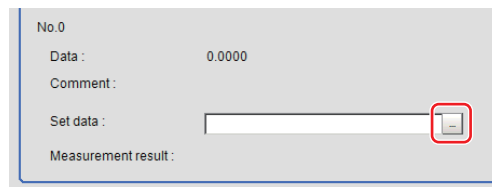
- If any error is detected in expressions in the set data while starting up the setting window, E indicating error appears in the error check column and the message saying "Invalid set data" is displayed. Correct the expression indicated by E. If there is any E error sign, the error message remains on the screen.

- 1 In the Item Tab area, click [Setting].**
- 2 Click the "No." for setting up the user data in the User data list area.**
The number selected will be displayed below the list.



- 3** In the "User data list" area, click [...] for "Set data" and set the expression to update the user data.

The Set data window is displayed.



- 4** After setting up the expression, click [OK].

The expression to update the user data is confirmed.

Note

If an error message is displayed, please check the following points.

- Unit value, numbers, function or TJG settings should be just before or just behind operator.
- Operators and commas "," should not be placed at the start or end of an expression.
- Operators cannot be input continuously.
- TJG/Unit value/Functions cannot be input continuously.
- The left and right parentheses "(")" should be used together.
- Please ensure that the function argument is set.

- 5** Repeat steps Reference: ▶ 2 (p.561) to Reference: ▶ 4 (p.562) and set the expressions

- 6** Click [Measure] to check the measurement results for the data.

Key Points for Test Measurement and Adjustment (User Data)

The following content can be confirmed in the "Detail result" area using text.

Displayed item	Description
Judge	Judgement result

Measurement Results for Which Output Is Possible (User Data)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
A value between set data 00 and set data 99	DT00 to DT99	A value between set data 00 and set data 99

External Reference Tables (User Data)

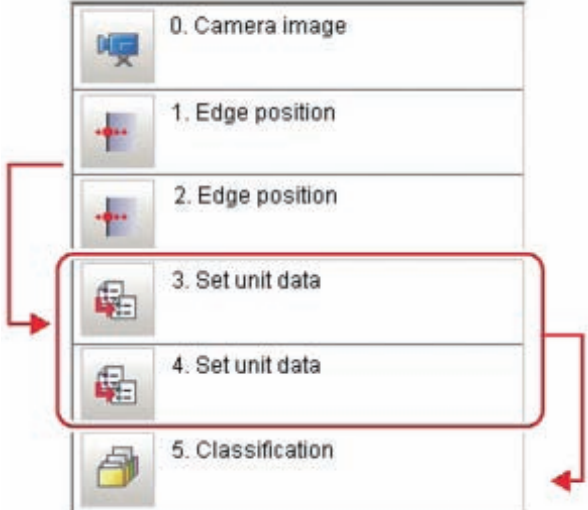
No.	Data name	Set/Get	Data range
0	Judgement result	Get only	0: No judgement (not yet measured) 1: Judgement result OK -1: Judgement result NG
200 + N (N = 0 to 99)	Data	Set/Get	Expression character string
1000 to 1099	Calculation result	Get only	-999999999.9999 to 999999999.9999

Set Unit Data

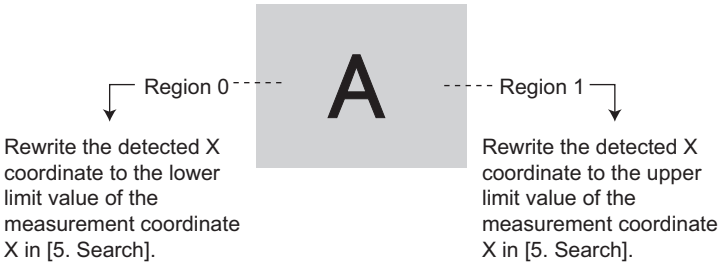
Used in the Following Case

- When you want to overwrite processing unit data while measuring

Example) Adjust the search range based on the size of measurement object.



- Measurement the width of the measurement object by "1 Edge position" and "2 Edge position"
- Adjust the judgement condition of the measurement coordinate X in [5. Search] based on the result.



Region 0

Region 1

Rewrite the detected X coordinate to the lower limit value of the measurement coordinate X in [5. Search].

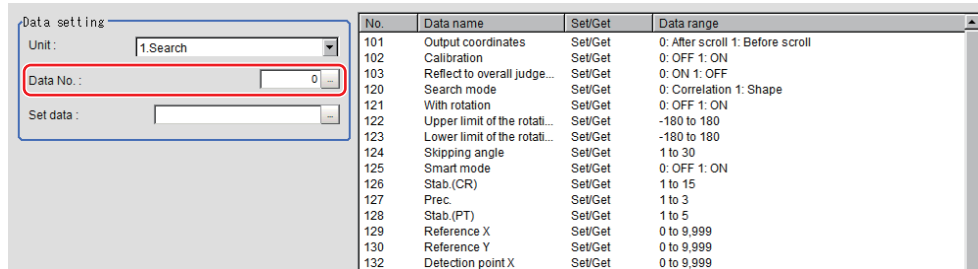
Rewrite the detected X coordinate to the upper limit value of the measurement coordinate X in [5. Search].

Parameter Settings (Set Unit Data)

1 In the "Data setting" area, select the target unit to overwrite.

The data number, data name, and data range that can be used in the target units are displayed on the right side.

2 Click [...] for "Data No." and set the target data number.



The designated data No. will be different depending on the processing item.

► For more details, refer to External Reference Table for each processing item.

Important

- Only numeric data can be used for the processing unit data setting.
- To set character string data, use macro processing items.
- Those items whose data range are described as "Character String" in the external reference data list are character string data.

3 In the "Data setting" area, overwrite details are set up using an expression.

Reference: ► Layout of Setting Expression Window (p.535)

4 Click [OK].

The settings are finalized.

Measurement Results for Which Output Is Possible (Set Unit Data)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Latest processing unit judgement result
Data	DT	Calculation result of setup data (formula)

External Reference Tables (Set Unit Data)

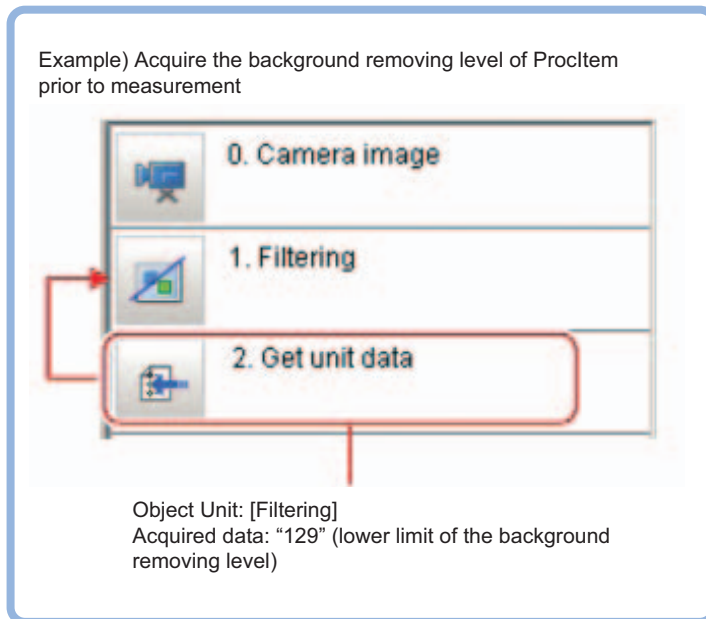
No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgment (unmeasured) 1: Judgment result OK -1: Judgment result NG
5	Data	Get only	-999999999.9999 to 999999999.9999
120	Unit	Set/Get	0 to 9999
121	Data No.	Set/Get	0 to 99999
122	Expressions	Set/Get	Expression character string

Get Unit Data

Used in the Following Case

- When you want to acquire processing unit data while measuring

Example) Acquire the background removing level of Procltem prior to measurement



Object Unit: [Filtering]
Acquired data: "129" (lower limit of the background removing level)

Parameter Settings (Get Unit Data)

- 1** In the "Data setting" area, click the "Get data number" [...] or [>] to set the number of target data.

The data number, data name, and data range that can be used in the target units are displayed on the right side.

- 2** From the list, click the "No." of the data for which you are setting the acquisition target.

The No. selected will be displayed below the list.

- 3** Click [▼] for "Scene" and specify the scene number of the desired processing unit.

For more details, refer to External Reference Tables for each processing item.

- 4** Click [▼] for "Unit" and specify the desired unit.

Get data number : [<] [>]

No.	Scene	Unit	Data No.
0	Current scene	0.Camera Image I...	0

No.	Scene	Unit	Data No.
0	Current scene	0.Camera Image I...	0
1	Current scene	0.Camera Image I...	0
2	Current scene	0.Camera Image I...	0

Scene : [▼]
Unit : [▼]
Data No. : [<] [>]

5 Click [...] for "Data No." and specify the desired data No.

The designated data No. will be different depending on the processing item.

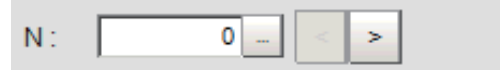
For more details, refer to External Reference Tables for each processing item.

Important

- Only numeric data can be obtained for the processing unit data acquisition.
- To get character string data, use macro processing items.
- Those items whose data range are described as "Character String" in the external reference data list are character string data.

Note

- Clicking the desired data on the list enters the "Data No." of the clicked position.
- If ">" of "N" at the bottom of the list is clicked, the "Data No." with the N value of the number taken into account can be set.



6 Click [OK].

The settings are finalized.

Measurement Results for Which Output Is Possible (Get Unit Data)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Data 00 to 15	DT00 to DT15	The values in the data 00 to 15

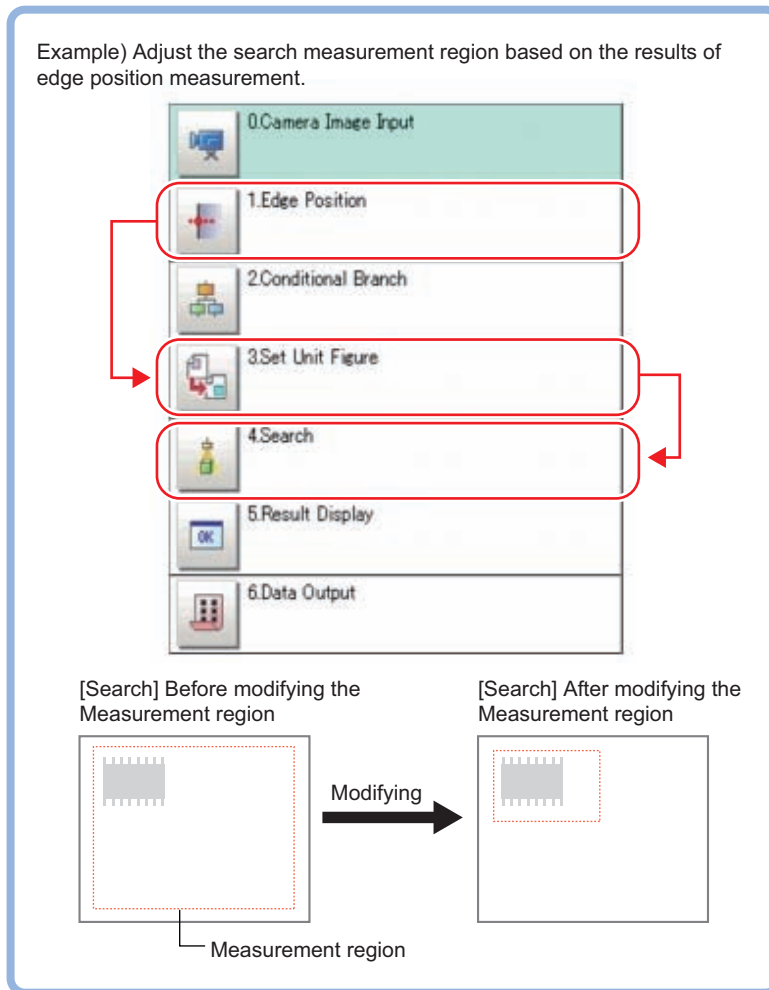
External Reference Tables (Get Unit Data)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgment (unmeasured) 1: Judgement result OK -1: Judgement result NG
5 + N (N = 0 to 15)	Data	Get only	-999,999,999.9999 to +999,999,999.9999
220	Number of acquired data	Set/Get	1 to 16
221 + N (N = 0 to 15)	Scene	Set/Get	-1 to 9,999 If it is -1, refers to the current scene.
321 + N (N = 0 to 15)	Unit	Set/Get	0 to 9,999
421 + N (N = 0 to 15)	Data No.	Set/Get	0 to 99,999

Set Unit Figure

Used in the Following Case

- When changing the measurement area based on the measurement results



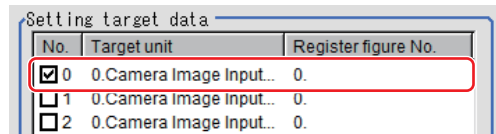
Important

- Do not insert " Input image" processing items or " Compensate image" processing items between the " Set Unit Figure" and the target processing unit. The processing unit figure may go out. The processing unit figure may go out.
Reference: ▶ Input image (p.17)
Reference: ▶ Compensate image (p.419)

Parameter Settings (Set Unit Figure)

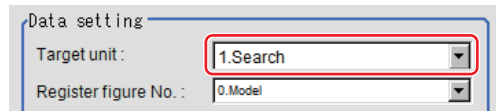
Up to 8 figures can be set for each set unit figure.
To set multiple figures for one target unit,
set different register figure Nos.

1 Click the target unit in the "Setting target data" area and check the No. column.



2 In the "Data setting" area, click the [Target unit] [▼] to select the target unit.

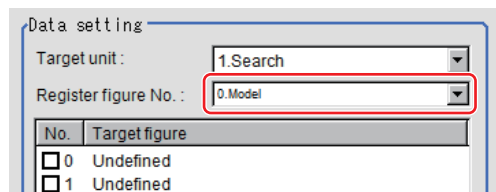
The target unit name in the "Setting target data" area is also reflected automatically.



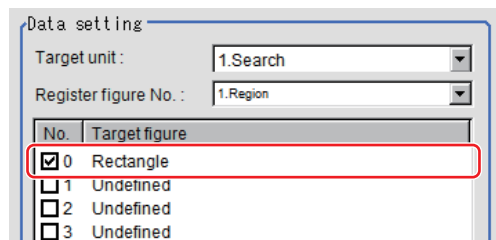
3 In the "Data setting" area, click the [Register figure No.] [▼] to select the figure to be registered.

Target figures included in the selected figure are displayed.

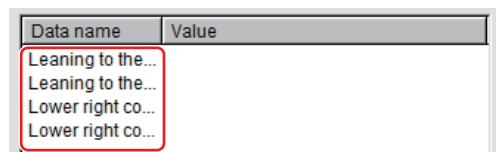
The registered figure name in the "Setting target data" area is also reflected automatically.



4 Click the target figure whose data you want to set and check the No. column.



5 Click the name of the data that you want to rewrite.



6 Click [Edit] to set up the overwrite details using an expression.

Reference: ▶ Layout of Setting Expression Window (p.535)



7 Click [OK].

An area is displayed on the image based on settings.

Key Points for Test Measurement and Adjustment (Set Unit Figure)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Target unit	Unit for setting up figures
Register figure No.	Registered figure number
Target figure No.	Target figure number

Key Points for Adjustment

Select the adjustment method referring to the following point.

Judgement will be NG.

Parameter to be adjusted	Troubleshooting
Setting parameters for figures	<ul style="list-style-type: none">• Check if the values entered for the setting figure are correct. If the setting figure is a rectangle, check that coordinates are specified in the order from top-left (X, Y) to bottom-right (X, Y). To refer to the measurement coordinates X and Y from other units, the set order may be the top-right coordinates (X, Y) to bottom-left coordinates (X, Y). If the setting figure is a circle, check that no negative value is specified as the radius.• Check that anything other than images are not included in the set figure.• Check that figure size limit of the setting target is not exceeded.

Measurement Results for Which Output Is Possible (Set Unit Figure)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	The latest processing unit judgement result
Number of data items	DNO	Number of data items setup
Data 0	DT0	Calculation result of setup data 0
Data 1	DT1	Calculation result of setup data 1
Data 2	DT2	Calculation result of setup data 2
Data 3	DT3	Calculation result of setup data 3
Data 4	DT4	Calculation result of setup data 4
Data 5	DT5	Calculation result of setup data 5
Data 6	DT6	Calculation result of setup data 6
Data 7	DT7	Calculation result of setup data 7
Data 8	DT8	Calculation result of setup data 8
Data 9	DT9	Calculation result of setup data 9
Data 10	DT10	Calculation result of setup data 10
Data 11	DT11	Calculation result of setup data 11
Data 12	DT12	Calculation result of setup data 12
Data 13	DT13	Calculation result of setup data 13
Data 14	DT14	Calculation result of setup data 14
Data 15	DT15	Calculation result of setup data 15
Data 16	DT16	Calculation result of setup data 16
Data 17	DT17	Calculation result of setup data 17
Data 18	DT18	Calculation result of setup data 18
Data 19	DT19	Calculation result of setup data 19

External Reference Tables (Set Unit Figure)

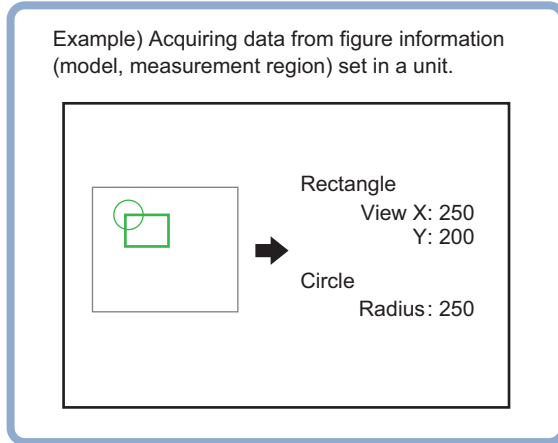
No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (un measured) 1: Judgement result OK -1: Judgement result NG
5 to 24	Data 0 to 19	Get only	-999999999.9999 to 999999999.9999
120	Target unit	Set/Get	0 to 9999
121	Register figure No.	Set/Get	0 to 999
122	Target figure No.	Set/Get	0 to 7
123	Number of setting data items	Get only	0 to 20

Get Unit Figure

Acquires and displays figures drawn by other processing units.

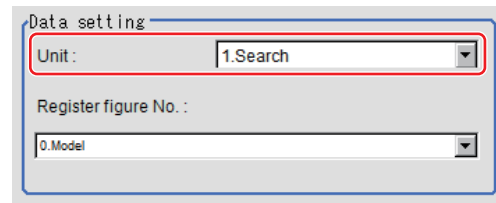
Used in the Following Case

- When you want to acquire data such as coordinates from figure information



Parameter Settings (Get Unit Figure)

- 1 In the "Data setting" area, click the [Unit] [▼] to set the number of the registered figure you want to acquire.



- 2 Click [▼] for [Resister figure No.] and specify Register figure No. you would like to acquire.

Key Points for Test Measurement and Adjustment (Get Unit Figure)

The following content can be confirmed in the "Detail result" area using text.

Displayed items	Description
Judge	Judgement result
Target unit	Target unit which acquired figure
Register figure No.	Acquired figure number

Measurement Results for Which Output Is Possible (Get Unit Figure)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	The latest processing unit judgement result
Number of figures	NUM	Number of figures acquired
Size of figures	SIZ	Size of figures acquired (number of bytes)
Figure N type (N = 0 to 9)	FNT	Type of figure N 0x0000→Undefined 0x0001→Point 0x0002→Line 0x0004→Wide line 0x0008→Rectangle 0x0010→Ellipse 0x0020→Circle 0x0040→Wide circle 0x0080→Arc 0x0100→Wide arc 0x0200→Polygon Set to 0 if no figures are acquired.
Figure N mode (N = 0 to 9)	FNM	Figure N drawing mode 0: OR 1: NOT Set to 0 if no figures are acquired.
Figure N data 00 to 20 (N = 0 to 9)	FND 00 to FND 20	Data 0 to 20 of figure N <ul style="list-style-type: none"> • For points <ul style="list-style-type: none"> 0: X coordinate 1: Y coordinate • For lines <ul style="list-style-type: none"> 0: X coordinate for first point 1: Y coordinate for first point 2: X coordinate for second point 3: Y coordinate for second point • For wide lines <ul style="list-style-type: none"> 0: X coordinate for first point 1: Y coordinate for first point 2: X coordinate for second point 3: Y coordinate for second point 4: Width • For rectangles <ul style="list-style-type: none"> 0: X coordinate for upper left point 1: Y coordinate for upper left point 2: X coordinate for lower right point 3: Y coordinate for lower right point

Measurement items	Character string	Description
Figure N data 00 to 20 (N = 0 to 9)	FND 00 to FND 20	<ul style="list-style-type: none"> • For ellipses <ul style="list-style-type: none"> 0: X coordinate for center point 1: Y coordinate for center point 2: Radius in X direction 3: Radius in Y direction • For circles <ul style="list-style-type: none"> 0: X coordinate for center point 1: Y coordinate for center point 2: Radius • For wide circles <ul style="list-style-type: none"> 0: X coordinate for center point 1: Y coordinate for center point 2: Radius 3: Width • For arcs <ul style="list-style-type: none"> 0: X coordinate for center point 1: Y coordinate for center point 2: Radius 3: Start angle of arc 4: End angle of arc • For wide arcs <ul style="list-style-type: none"> 0: X coordinate for center point 1: Y coordinate for center point 2: Radius 3: Start angle of arc 4: End angle of arc 5: Width • For polygons <ul style="list-style-type: none"> 0: Number of vertexes 1: X coordinate for vertex 0 2: Y coordinate for vertex 0 3: X coordinate for vertex 1 4: Y coordinate for vertex 1 5: X coordinate for vertex 2 6: Y coordinate for vertex 2 : : 19: X coordinate for vertex 9 20: Y coordinate for vertex 9 <p>Set to 0 if disabled or no figures are acquired.</p>

External Reference Tables (Get Unit Figure)

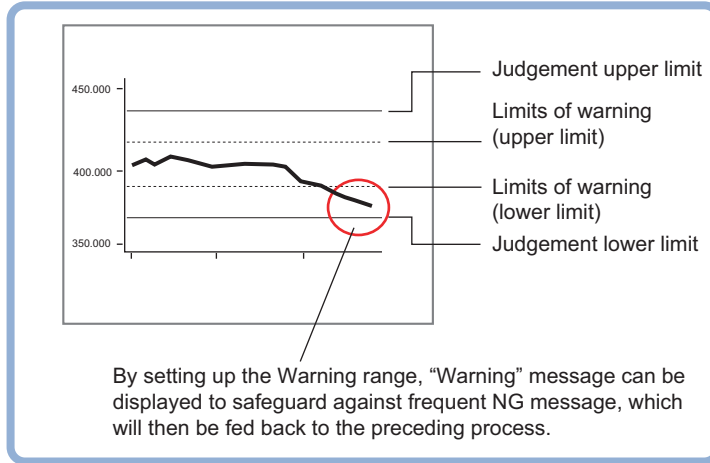
No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
1	Number of figures	Get only	Number of figures acquired
2	Size of figures	Get only	Size of figures acquired
120	Target processing unit No.	Set/Get	0 to 9999
121	Target figure No.	Set/Get	0 to 999
1000 + 100 × N (N = 0 to 9)	Figure N type (N = 0 to 9)	Get only	Figure 0 type 0x0000→Undefined 0x0001→Point 0x0002→Line 0x0004→Wide line 0x0008→Rectangle 0x0010→Ellipse 0x0020→Circle 0x0040→Wide circle 0x0080→Arc 0x0100→Wide arc 0x0200→Polygon Set to 0 if no figures are acquired.
1001 + 100 × N (N = 0 to 9)	Figure N drawing mode (N = 0 to 9)	Get only	Figure N drawing mode
1002 + 100 × N to 1022 + 100 × N (N = 0 to 9)	Figure N data 00 to figure N data 20 (N = 0 to 9)	Get only	Figure N data 0 to 20 The amount of valid data differs with data type. Set to 0 if disabled or no figures are acquired.

Trend Monitor

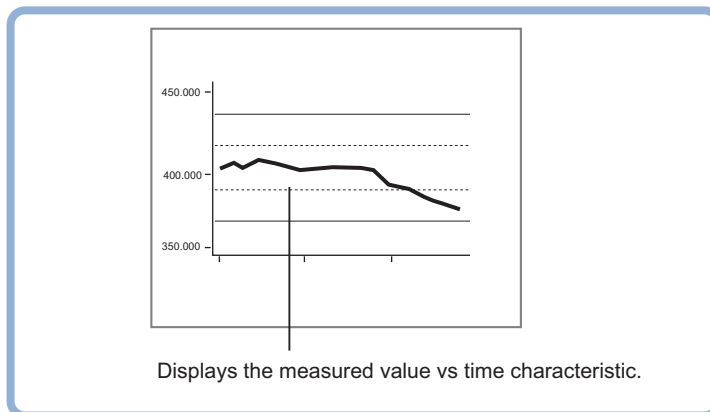
Enables the history of the measurement results to be displayed on the monitor.

Used in the Following Case

- When you want to prevent repeated occurrences of failed product



- When you want to analyze the cause of NG



List of Trend Monitor Items

Item name	Description
Measurement	Select the measurement value to be displayed on the trend monitor. Reference: ▶ Measurement Value (Trend Monitor) (p.576)
Display range	Specify the display range. You can scroll the display range of a graph up and down or zoom in/out. Reference: ▶ Display Range (Trend Monitor) (p.577)
Judgement	Set the conditions for deciding when measurement results are judged as OK, and set the warning range for issuing a caution before there are many NG occurrences. Reference: ▶ Judgement Conditions (Trend Monitor) (p.579)
History display	Display measurement history. Reference: ▶ Measurement History Display (Trend Monitor) (p.580)
Data save	Save the measurement results recorded in the trend monitor to USB memory. Reference: ▶ Data Save (Trend Monitor) (p.582)

Item name	Description
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Specify whether to reflect the judgement result to the overall judgement of the scene. Reference: ▶ Output Parameters (Trend Monitor) (p.583)

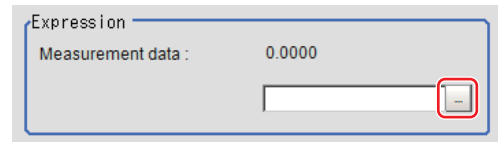
Measurement Value (Trend Monitor)

Select the measurement value to be viewed on the trend monitor.

One item can be displayed for each trend monitor unit.

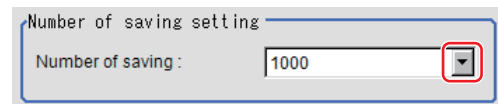
1 Click [Measurement] in the Item Tab area.

2 In the "Expression" area, click [...] in "Measurement data", and measurement values to be monitored are set up using an expression.



The Setting Expression window is displayed. Select a unit number processed before [Trend Monitor]. Even if the unit number after [Trend Monitor] is selected, the graph will not display.

3 Set up number of items to save as necessary.



Setting item	Set value	Description
Number of saving	<ul style="list-style-type: none"> • [1000] • 5000 • 10000 • 50000 • 100000 	Set the number of measurement values to save. A maximum of 5000 items can be displayed on the main screen. Measurements that exceed 5000 items are displayed using toggling of pages.

Important

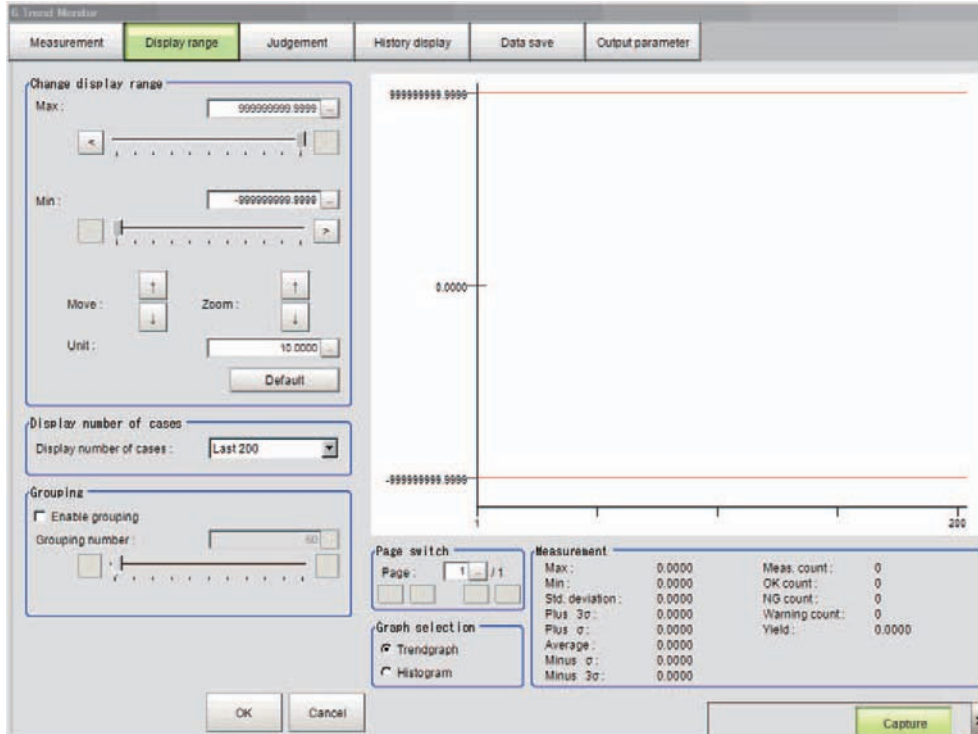
- Trade offs between number of items saved and the sensor controller performance include the following.
 - Increasing the number of items saved delays display processing and affects measurement interval. Please confirm measurement interval prior to performing set up.
 - There is a difference in amount of memory used of approximately 2 MB between 1000 items and 100000 items. Please confirm the amount of memory remaining prior to performing set up.

Display Range (Trend Monitor)

If what you want to see is not on the screen, scroll the graph up and down or zoom in/out. Also, items displayed horizontally can be toggled.

1 In the Item Tab area, click [Display range].

A graph is displayed in the "Image Display" area.



Note

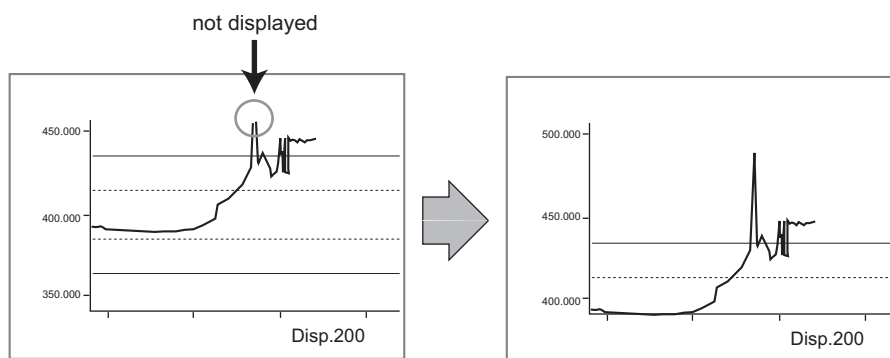
- If the window is entered after measurement is performed a few times and [Default] is clicked on, a display range suitable for these measurement values is automatically set.



Setting item	Set value [Factory default]	Description	
Change display range	Max	-999999999.9999 to 999999999.9999	
	Min		
	Move	<ul style="list-style-type: none"> • ↑ • ↓ 	Moves up and down the graph itself.
	Zoom	<ul style="list-style-type: none"> • ↑ • ↓ 	Zooms the graph itself in and out.
	Unit	1 to 1000000.0000	Sets the amount of variation generated when the up/down buttons for moving or zooming in/out are pushed.
	Default	-	If several measurements have already been made, an optimal display range is automatically set based on the measurement results.

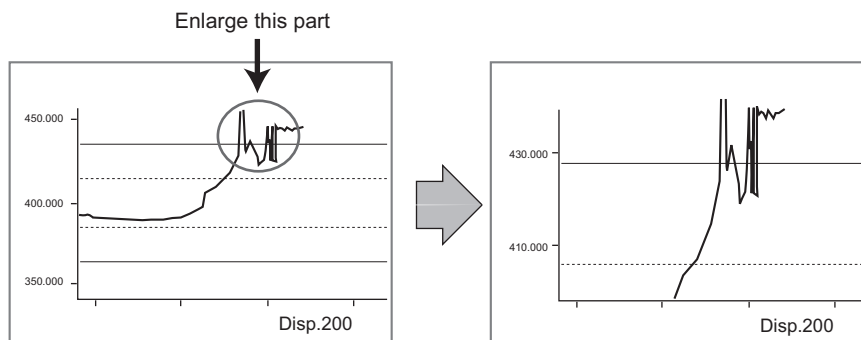
Setting item	Set value [Factory default]	Description
Display number of cases	<ul style="list-style-type: none"> • [Last 200] • Last 1000 • Last 5000 • Last 10000 • Last 50000 • Last 100000 	Select the number of items displayed in the horizontal direction on the graph.
Enable grouping	<ul style="list-style-type: none"> • [Checked] • Unchecked 	<p>Draws a rectangle that shows the maximum and minimum of measurement data for every set number of items.</p> <p>This enables viewing the maximum and minimum in a section at a glance.</p>
	0 to 5000 [50]	Sets the number of items that can be grouped.

Move

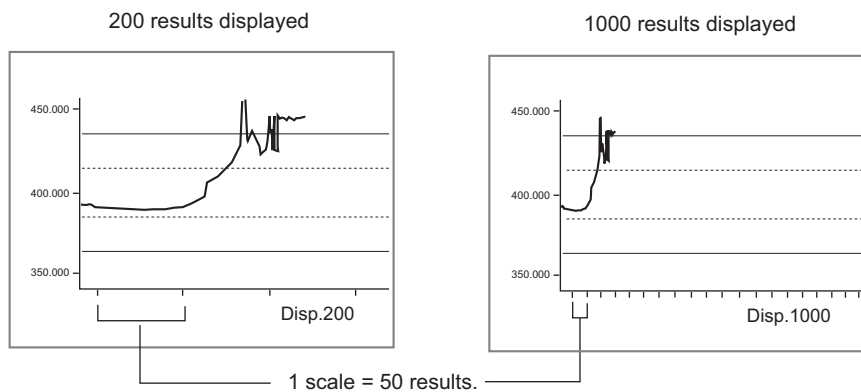


Zoom

Example: Enlarging a part where measurement results were unstable

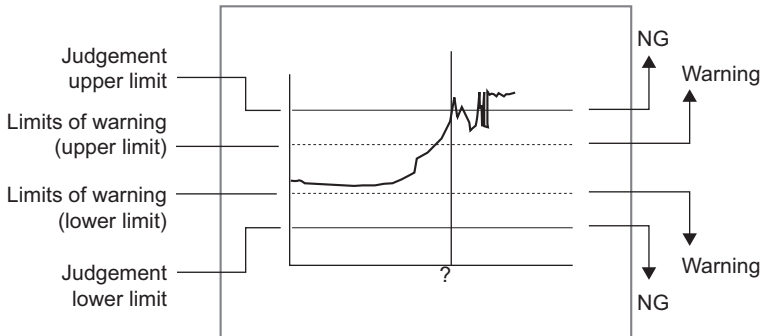


Horizontal



Judgement Conditions (Trend Monitor)

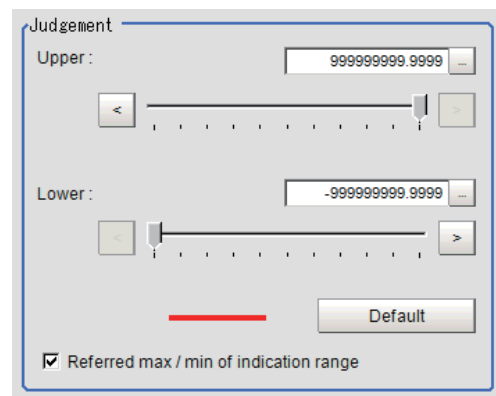
Sets the warning range for prompting caution before large numbers of NGs occur as well as OK/NG judgement conditions.



Note

- When a warning occurs, the message "Limits of Warning" is displayed on the screen. Notification that an alarm has occurred can also be output to external devices if output-related processing units such as "Parallel Judgement Output" are used to set an arithmetic expression to output measurement results (warnings) from the trend monitor.

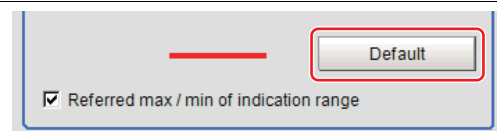
- In the Item Tab area, click [Judgement].
- Set up the judgement condition.



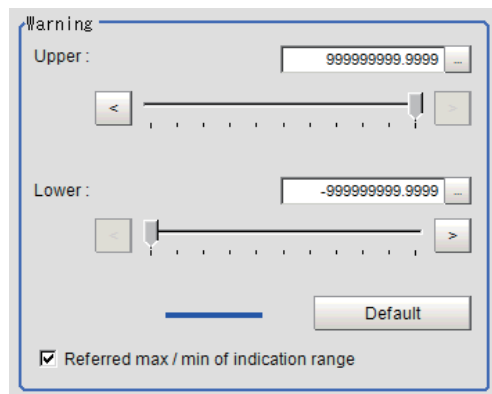
Setting item	Set value [Factory default]	Description
Upper	-999999999.9999 to 999999999.9999	Specify the range where the measurement result is judged to be OK.
Lower	-999999999.9999 to 999999999.9999	
Referred max / min of indication range	<ul style="list-style-type: none"> [Checked] Unchecked 	When checked, the judgement range that can be set with the upper and lower values becomes the same as the max. and min. values set in [Display range].

Note

- If the window is entered after measurement is performed a few times and [Default] is clicked on, optimal judgement conditions including maximum and minimum measurement values are automatically set.



3 In the "Warning" area, specify values for "Upper" and "Lower".



The setup method is the same as the setup method for the "Judgement" area.

Setting item	Set value [Factory default]	Description
Upper	-99999999.9999 to [99999999.9999]	Specify the warning range for encouraging caution before frequent occurrence of NGs.
Lower	[-99999999.9999] to 99999999.9999	
Referred max / min of indication range	<ul style="list-style-type: none"> • [Checked] • Unchecked 	When checked, the judgement range that can be set with the upper and lower values becomes the same as the max. and min. values set in [Display range].

Measurement History Display (Trend Monitor)

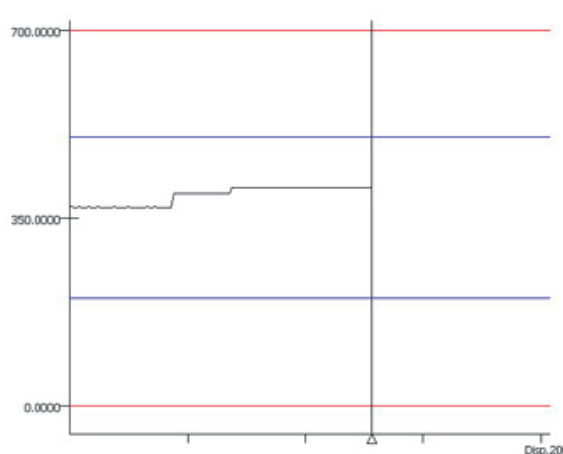
Displays measurement history.

- 1** Click [History display] in the Item Tab area.
- 2** Click judgement displayed in the "Measurement history" area.

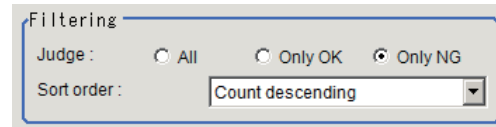
Judge	Count	Value	Time
OK	761	320.0000	18:28:57
OK	760	321.0000	18:28:57
OK	759	321.0000	18:28:57
OK	758	321.0000	18:28:57
OK	757	321.0000	18:28:57
OK	756	316.0000	18:28:57
OK	755	320.0000	18:28:56
OK	754	320.0000	18:28:56
OK	753	321.0000	18:28:56
OK	752	321.0000	18:28:56
OK	751	320.0000	18:28:56
OK	750	321.0000	18:28:56
OK	749	321.0000	18:28:56
OK	748	320.0000	18:28:56
OK	747	321.0000	18:28:56

The measurement values and time are displayed.

In the Image Display area, longitudinal lines displayed at NG positions in the graph show where NG have occurred.

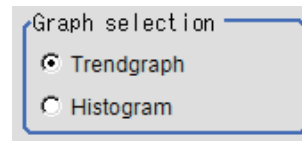


3 Set up a filter as necessary.



Setting item	Set value [Factory default]	Description
Judge	<ul style="list-style-type: none"> • All • Only OK • [Only NG] 	Sets the judgement results that are displayed.
Sort order	<ul style="list-style-type: none"> • Count ascending • [Count descending] • Value ascending • Value descending 	Sets the sort order for the judgement results to display.

4 Sets up a display graph as necessary.



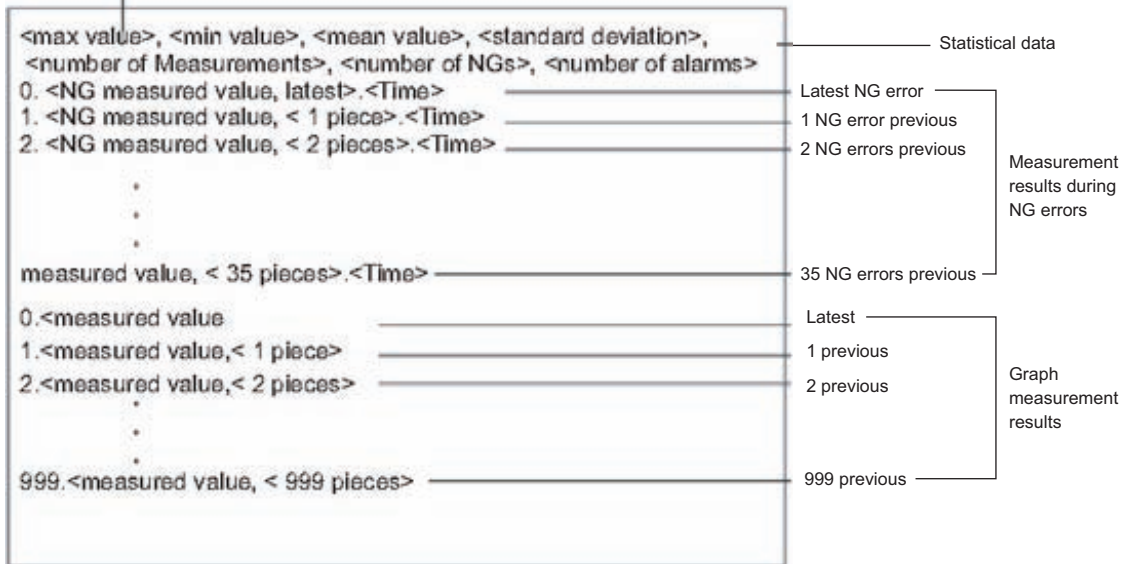
Setting item	Set value [Factory default]	Description
Graph selection	<ul style="list-style-type: none"> • [Trendgraph] 	<p>The vertical direction shows measurement values and horizontal direction shows number of items. This is convenient for showing time elapse and changes in measurement.</p>
	<ul style="list-style-type: none"> • Histogram 	<p>The vertical direction shows number of items and horizontal direction shows measurement values. This is convenient for showing distribution.</p>

Data Save (Trend Monitor)

The measurement results recorded in the trend monitor can be saved in a USB memory stick or SD card (for FH series). Since the data is saved in CSV format, it can be edited on the PC.

The data to be saved includes all the statistical data, the value and time stamp when NG occurs (up to 36 items) and the measurement result on the graph (up to 1000 items). Up to 100000 items of measurement results can be saved in extended format. The format is as follows.

Data is partitioned using commas.



Important

- Insert a USB memory stick or SD card before saving data.
For information on the position of the USB connector and SD card slot, refer to the User's Manual.

1 In the Item Tab area, click [Data save].

2 Specify format in the "Save setting" area.

Standard format

Line	Text	Description	
1	<Maximum>, <Minimum>, <Average>, <Deviation>, <Count>, <NG count>, <Warning count>	Statistical data	
2			
3	0, <NG measured value, latest>, <Time>	Last NG	Measurement results when NG occurs (Max: 36 items)
4	1, <Last 1 NG measurement>, <Time>	Last 1 NG	
5	2, <Last 2 NG measurement>, <Time>	Last 2 NG	
:	:	:	
38	35, <Last 35 NG measurement>, <Time>	Last 35 NG	
39			
40	0, <measured value, latest>	Last	Measurement result (Max: 1000 items)
41	1, <Last 1 measurement>	Last 1	
42	2, <Last 2 measurement>	Last 2	
:	:	:	
1039	999, <Last 999 measurement>	Last 999	

Extended format

Line	Text	Description	
1	<Maximum>, <Minimum>, <Deviation>, <Plus 3σ>, <Plus σ>, <Average>, <Minus σ>, <Minus 3σ>, <Count>, <OK count>, <NG count>, <Warning count>, <Yield>	Statistical data	
2			
3	0, <judgement result, latest>, <measured value, latest>, <Time>	Last	Measurement result (Max: 100000 items)
4	1, <Last 1 judgement result>, <Last 1 Measurement>, <Time>	Last 1	
5	2, <Last 2 judgement result>, <Last 2 Measurement>, <Time>	Last 2	
:	:	:	
100002	99999, <Last 99999 judgement result>, <Last 99999 Measurement>, <Time>	Last 99999	

Note

- The default for the file name is the data save date (example: 0410.csv). If it is half-width alphanumeric characters, it can be changed arbitrarily.

3 In the "Save setting" area, click [Save].

Data is saved to a USB memory stick or SD card.

4

Support Inspection and Measurement

Output Parameters (Trend Monitor)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- Click [Output parameter] in the Item Tab area.
- Choose whether or not to reflect this in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> [ON] OFF 	Enables choosing whether or not the judgment results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Trend Monitor)

The following content can be confirmed in the "Detail result" area using text.

Displayed items	Description
Judge	Judgement result
Measurement	Latest measured value
Max	Max. measurement value during recording period
Mini	Min. measurement value during recording period
Standard deviation	Standard deviation for measurement values during recording period
Plus 3σ	Average of measurement values during period recorded + standard deviation of the measurement values × 3
Plus σ	Average of measurement values during period recorded + standard deviation of the measurement values
Average	Average value for measurement values during recording period

Displayed items	Description
Minus σ	Average of measurement values during period recorded - standard deviation of the measurement values
Minus 3σ	Average of measurement values during period recorded - standard deviation of the measurement values $\times 3$
Measurement count	Measure count since the beginning of measurement
OK count	Number of measurements since starting to make measurements - NG count in number of measurements
NG count	Number of NG occurrences within the measurement count
Warning count	Warning count within the measurement count
Yield	OK count in number of measurements / Number of measurements since starting to make measurements

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number	Explanation of image to be displayed
0	Trend graph
1	Histogram

Measurement Results for Which Output Is Possible (Trend Monitor)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Measurement	DT	Latest measured value
Warning	WN	Existence of warning occurrence
Maximum	MX	Max. measurement value during recording period
Minimum	MN	Min. measurement value during recording period
Deviation	DV	Standard deviation for measurement values during recording period
Plus 3σ	AP3	Average of measurement values during period recorded + standard deviation of the measurement values $\times 3$
Plus σ	AP1	Average of measurement values during period recorded + standard deviation of the measurement values
Average	AV	Average value for measurement values during recording period
Minus σ	AM1	Average of measurement values during period recorded - standard deviation of the measurement values
Minus 3σ	AM3	Average of measurement values during period recorded - standard deviation of the measurement values $\times 3$
Measurement count	MC	Measure count since the beginning of measurement
OK count	OC	Number of measurements since starting to make measurements - NG count in number of measurements
NG count	NC	Number of NG occurrences within the measurement count
Warning count	WC	Warning count within the measurement count
Yield	YD	OK count in number of measurements / Number of measurements since starting to make measurements

Important

- If the total measurement value data exceeds -1.0×10^{11} to 1.0×10^{11} , the measurement will be disabled (NG). Regularly clear the measurement values so that the total measurement value data stays within the range.

External Reference Tables (Trend Monitor)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Measurement	Get only	-999999999.9999 to 999999999.9999
6	Warning	Get only	0: OFF 1: ON
7	Maximum	Get only	-999999999.9999 to 999999999.9999
8	Minimum	Get only	-999999999.9999 to 999999999.9999
9	Average	Get only	-999999999.9999 to 999999999.9999
10	Deviation	Get only	-999999999.9999 to 999999999.9999
11	Count	Get only	0 to 999999999
12	NG count	Get only	0 to 999999999
13	Warning count	Get only	0 to 999999999
14	Measurement value average plus 3σ	Get only	-999999999.9999 to 999999999.9999
15	Measurement value average plus σ	Get only	-999999999.9999 to 999999999.9999
16	Measurement value average minus σ	Get only	-999999999.9999 to 999999999.9999
17	Measurement value average minus 3σ	Get only	-999999999.9999 to 999999999.9999
18	OK count	Get only	0 to 999999999
19	Yield	Get only	0 to 1
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
121	Upper limit of the judgement	Set/Get	-999999999.9999 to 999999999.9999
122	Lower limit of the judgement	Set/Get	-999999999.9999 to 999999999.9999
123	Warning upper limit	Set/Get	-999999999.9999 to 999999999.9999
124	Warning lower limit	Set/Get	-999999999.9999 to 999999999.9999
125	Upper limit of the display range	Set/Get	-999999999.9999 to 999999999.9999
126	Lower limit of the display range	Set/Get	-999999999.9999 to 999999999.9999
127	Amount of change to display range	Set/Get	1 to 1000000
128	Horizontal	Set/Get	0: Display 200 results 1: Display 1000 results

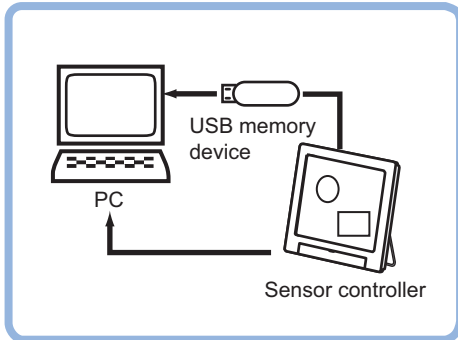
No.	Data name	Set/Get	Data range
129	Grouping flag	Set/Get	0: OFF 1: ON
130	Grouping count	Set/Get	-999999999.9999 to 100000
131	Number saved	Set/Get	0: 1,000 1: 5,000 2: 10,000 3: 50,000 4: 100,000
132	Save format	Set/Get	0: Standard format 1: Extended format

Image Logging

This is used when saving measurement images to on-board memory, RAMDisk or USB memory. This enables preparation of logging conditions using an expression and is more flexible than the system image logging conditions settings. However, the settings of this unit are enabled if "None" is set on the [Logging setting] of [System] menu. If settings that perform image logging for multiple units during measurement are executed, the last settings executed are enabled.

Used in the Following Case

- This is used when saving logging images under specific conditions.



Important

- If several image logging units are set in the flow, saving is performed based on the last image logging conditions executed.

Logging Conditions (Image Logging)

Indicate the image to perform logging for. If 4 cameras are connected, image logging is performed for 4 cameras each time.

- 1 Click [Logging condition] in the Item Tab area.
- 2 Set the logging conditions.

The screenshot shows the 'Logging condition' settings. The 'Condition' is set to 'None'. The 'Arithmetic expression' is empty, and the 'Arithmetic result' is 0.0000. The 'Judgement condition' is set to a range from -99999999.9999 to 99999999.9999.

Setting item	Set value [Factory default]	Description
Condition	• [None]	No images are saved.
	• Only NG	Saves images only if an NG occurs. If an NG occurs downstream from the image logging processing unit, image logging is not performed. Insert image logging as close to the end of the scene as possible
	• All	All measured images are saved.

3 When "Only NG" is selected, click [...] to set up the expression.

The Setting Expression window is displayed.

4 After setting up the expression, click [OK].

The expression is confirmed.

5 Set up the judgement upper limit and the judgement lower limit for "Judgement condition".

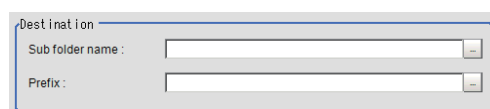
Setting item	Set value [Factory default]	Description
Judgement condition	-999999999.9999 to 999999999.9999	This is a judgement condition for the expression. Set upper and lower limits for judging as OK.

Save Destination (Image Logging)

1 Click [Destination] in the Item Tab area.

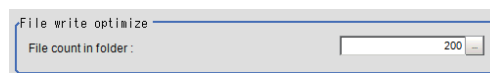
2 Set the logging images save destination.

Enabled when "Save to memory + file" is selected as the save destination in the system image logging settings.



Setting item	Set value [Factory default]	Description
Sub folder name	-	Designates sub folder names. Creates a sub folder in the save destination in system logging settings. (Max: 32 characters) The following characters cannot be set. \\ : * ? " < >
Prefix	-	Sets the prefix for the save file name. (Max: 32 characters) The set character string is added at the beginning of the name of the save file. If the system logging settings designate a prefix, the file name is set to [prefix designated by image logging] + [prefix designated by system logging settings] + image logging file name.

3 Set the File count in folder, if necessary.



Setting item	Set value [Factory default]	Description
File count in folder	0 to 999 [200]	Set the maximum number of files that can be saved in 1 folder. The name of the folder to be automatically generated will be the same as that of the first image logging file to be stored in that folder. Furthermore, if 0 is specified, folders are not automatically generated.

Note

- If too many files are saved in 1 folder, performance may drop. Performance drop can be prevented by setting [File count in folder].

Important

- If conditional branching is used, the number of files saved may vary from the specified number.
- If the operation mode is [Single-line High-speed mode], images taken by odd-numbered measurements are stored in a file different from one containing images taken by even-numbered measurements.
- If the operation mode is [Non-stop adjustment mode], the number of files in the folder may vary from the specified number before and after non-stop adjustment.

Key Points for Test Measurement and Adjustment (Image Logging)

The following content can be confirmed in the "Detail result" area using text.

Displayed items	Description
Judge	Judgement result
Expression	Calculation result of conditional expression

Measurement Results for Which Output Is Possible (Image Logging)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Data	D00	Conditional expression data
Judge	J00	Conditional expression judgement

External Reference Tables (Image Logging)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Calculation result	Get only	-99999.9999 to 99999.9999
6	Judgement result	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
120	Logging condition	Set/Get	0: None 1: Only NG 2: All
121	Judge expression	Set/Get	Expression character string
122 to 123	Upper limit of conditions calculation	Set/Get	-99999.9999 to 99999.9999
	Lower limit of conditions calculation	Set/Get	-99999.9999 to 99999.9999
124	Sub directory name	Set/Get	Character string
125	Prefix	Set/Get	Character string

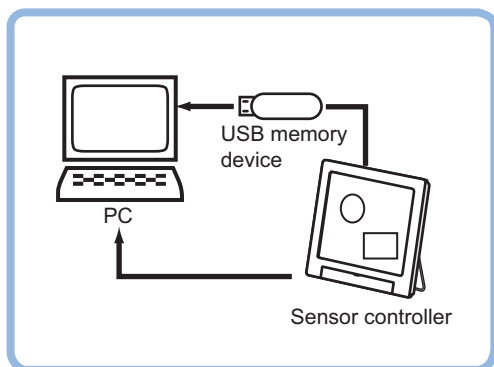
Image Conversion Logging

This processing item is used to save a measurement processing image in RAM Disk or USB memory. This enables preparation of logging conditions using an expression and is more flexible than the system image logging conditions settings. The save range within the image can be specified in rectangle and the image save format (BMP or JPG) can be specified.

Used in the Following Case

- **This is used when saving measurement images under specific conditions.**

The measurement image is saved when Image conversion logging is registered in the flow. Filtering and position compensation are also reflected.



Save Condition (Image Conversion Logging)

Indicate the image to perform logging for.

Important

- Only one image per processing unit can be saved in image conversion logging. Note, however, that multiple images can be saved if more than one processing unit is set up in the flow.

- 1 Click [Save condition] in the Item Tab area.
- 2 Set save conditions.

The screenshot shows the 'Save condition' dialog box with the following fields and options:

- Condition: None Only NG All
- Arithmetic expression: [Empty text box]
- Arithmetic result: 0.0000
- Judgement condition: [-999999999.9999] - [999999999.9999]

Setting item	Set value [Factory default]	Description
Condition	• [None]	No images are saved.
	• Only NG	Saves the images only if an NG occurs. If an NG occurs downstream from the image conversion logging processing unit, image conversion logging is not performed. Judgement uses the measurement value at the point in time when measurement processing is executed for image convert logging.
	• All	All measured images are saved.

3 When "Only NG" is selected, click [...] to set up the expression.

The Setting Expression window is displayed.

4 Logging conditions are set using an expression.

Reference: ▶ Layout of Setting Expression Window (p.535)

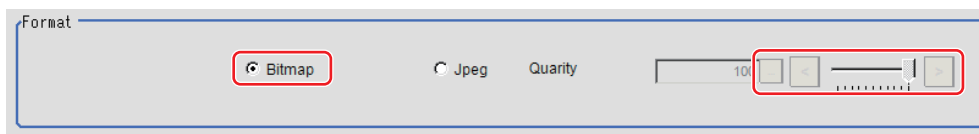
5 After setting up the expression, click [OK].

The expression is confirmed.

6 Set up the judgement upper limit and the judgement lower limit for "Judgement".

Setting item	Set value [Factory default]	Description
Judgement condition	-999999999.9999 to 999999999.9999	This is a judgement condition for the expression. Set upper and lower limits for judging as OK.

7 In the Format area, set save format.



Setting item	Set value [Factory default]	Description
Format	<ul style="list-style-type: none"> • [Bitmap] • Jpeg 	Select the image format to be saved.
Quality	0 to 100 [100]	Specify the quality of the Jpeg image to be saved.

Destination (Image Conversion Logging)

Note

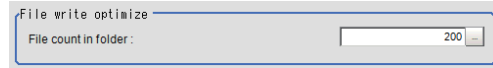
- The save file name is the prefix, measurement ID and extension.

1 Set the logging images save destination.



Setting item	Set value [Factory default]	Description
Folder name	-	Specify the name of the folder to which the image is to be saved. (Max: 32 characters) The following characters cannot be set. \\ / : * ? " < >
Prefix	-	Sets the prefix for the save file name. (Max: 32 characters) The set character string is added at the beginning of the name of the save file. Any prefix specified in the system's logging setting will be ignored.

2 Set the number of files in the folder, if necessary.



Setting item	Set value [Factory default]	Description
File count in folder	0 to 999 [200]	Set the maximum number of files that can be saved in 1 folder. The name of the folder to be automatically generated will be the same as that of the first image logging file to be stored in that folder. Furthermore, if 0 is specified, folders are not automatically generated.

Note

- If too many files are saved in 1 folder, performance may drop. Performance drop can be prevented by setting [File count in folder].

Important

- If the operation mode is [Single-line High-speed mode], images taken by odd-numbered measurements are stored in a file different from one containing images taken by even-numbered measurements.
- If the operation mode is [Non-stop adjustment mode], the number of files in the folder may vary from the specified number before and after non-stop adjustment.

Area Setting (Image Conversion Logging)

Specify the range of images to be logged.

- 1 In the Item Tab area, click [Area Setting].
- 2 Use the drawing tools to specify the Image Conversion Logging range.
- 3 In the figure setting area, click [OK].

The range in which to perform logging is registered.

Key Points for Test Measurement and Adjustment (Image Conversion Logging)

The following content can be confirmed in the "Detail result" area using text.

Displayed item	Description
Judge	Judgement result
Expression	Calculation result of conditional expression

Measurement Results for Which Output Is Possible (Image Conversion Logging)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Data	D00	Conditional expression data
Judge	J00	Conditional expression judgement

External Reference Tables (Image Conversion Logging)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (not yet measured) 1: Judgement result OK -1: Judgement result NG
5	Calculation result	Get only	-99999.9999 to 99999.9999
6	Judgement result	Get only	0: No judgement (not yet measured) 1: Judgement result OK -1: Judgement result NG
120	Save Condition	Set/Get	0: None 1: Only NG 2: All
122 to 123	Upper limit of conditions calculation	Set/Get	-99999.9999 to 99999.9999
	Lower limit of conditions calculation	Set/Get	-99999.9999 to 99999.9999
130	File count in folder	Set/Get	0 to 999
131	Image saving format	Set/Get	0: Bitmap 1: Jpeg
132	Jpeg quality	Set/Get	0 to 100

Data Logging

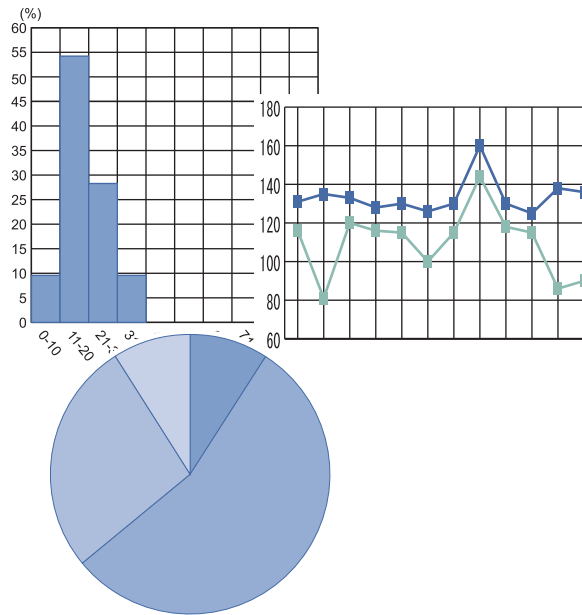
This is used to save measurement data in storage or USB memory.

Used in the Following Case

- When performing analysis using measurement data

Logging is performed for measurement results and these are read into an external device such as a PC.

Example: Analysis using Excel statistical processing



Important

- Insert data logging as close to the end of the flow as possible. If "Only NG" is selected in logging timing conditions and an NG occurs after the data logging processing unit, it will not be logged.
- Setting data logging settings to save [Image logging] makes simultaneous confirmation of measurement data and image data convenient.

Reference: ▶ "Chapter 3 Performing Test Measurement/Starting Operation Useful Functions for Operation Logging Measurement Values and Measurement Images Setting Logging Conditions [Logging Setting]" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Settings (Data Logging)

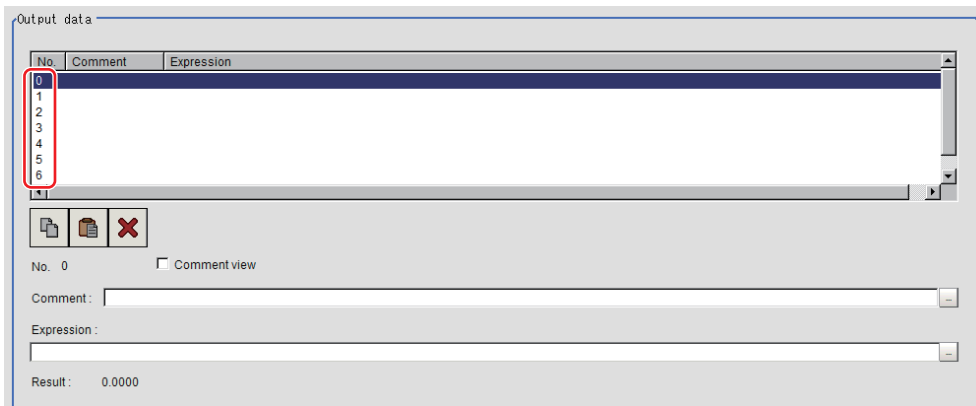
Indicate the data to perform logging for. Logging can be performed for up to 8 data using one "Data logging" processing item.

Note

- If you want to perform logging for 9 or more data using one record
Reference: ▶ Additional Explanation (Data Logging) (p.598)

1 In the Item Tab area, click [Setting].

2 In the list, click the output No. for which the expression is to be set.



The selected output No. is displayed under the list.

3 Click [...] for the expression and set the data to be logged with the expression.

The Setting Expression window is displayed.

4 Input "Comment" as necessary.

5 To display comments in the "Detail result display" area, check "Comment view".

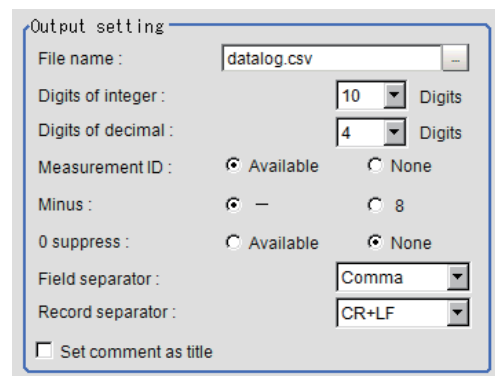
6 Repeat steps Reference: ▶ 2 (p.595) to Reference: ▶ 5 (p.595) and set up the output contents for each output number.

Output Format (Data Logging)

Sets the output format for logging data.

1 In the Item Tab area, click [Output format].

2 Set up each item as necessary.



Setting item	Set value [Factory default]	Description
File name	datalog.csv	Half-width alphanumeric characters are used for File name. (Max: 128 characters) Set the folder name and file name such that they are no more than 255 characters combined.
Digits of Integer	1 to [10]	Specify the digits of the integer part including the sign. For positive numbers, the plus sign is not output. Example Setting: 4 digits, Data: -5619 -999 is output.
Digits of Decimal	0 to [4]	Specify the number of output digits in the decimal part. Decimals are rounded up and output. When 0 is selected, the decimal digits will be rounded off.

Setting item	Set value [Factory default]	Description
Measurement ID	<ul style="list-style-type: none"> • [Available] • None 	<p>Select whether to output the measurement ID at the head of the output data.</p> <p>Measurement ID : measurement time YYYY-MM-DD_HH-MM-SS-MS (YYYY: Calendar, MM: Month, DD: Day, HH: Hour, MM: Minute, SS: Second, MS: millisecond)</p> <p>Example Measurement time: 11:10:25.500 AM, December 24, 2007, the measurement ID is "2007-12-24_11-10-25-500".</p> <p>Since the file name of the logging image also includes the same measurement ID, confirmation of the measurement data and image data can be performed with the measurement ID.</p>
Minus	<ul style="list-style-type: none"> • [-] • 8 	Select what is displayed in the sign column for a negative number.
0 suppress	<ul style="list-style-type: none"> • Available • [None] 	<p>Select the method for adjusting when there is a blank to the left of the output data.</p> <p>Available: Insert 0 into the blank digit space. None: Insert a space in the location with no character.</p> <p>Example When integer section setting: 5 digits, decimal section setting: 3 digits, data is 100.000 Available: 00100.000 None: _100.000 (_ represents a space)</p>
Field separator	<ul style="list-style-type: none"> • OFF • [Comma] • Tab • Space • CR+LF 	Select the separator for output data.
Record separator	<ul style="list-style-type: none"> • OFF • Comma • Tab • Space • [CR+LF] 	Select the separator each time data is output.
Set comment as title	<ul style="list-style-type: none"> • [Unchecked] • Checked 	Place a check here to output comments as the titles on the first line of the data logging file.

3 If necessary, set the save destination of the logging data.

Setting item	Setting value [Factory default]	Description
Destination setting	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Place a check here to set the destination and prefix.
Sub folder name	-	<p>Sets sub folder names. Creates a sub folder in the save destination in system logging settings. (Max: 32 characters)</p> <p>The following characters cannot be set. \\ / : * ? " < > ?</p>

Setting item	Setting value [Factory default]	Description
Prefix	-	Sets the prefix for the save file name. (Max: 32 characters) The set character string is added at the beginning of the name of the save file. The following characters cannot be set. \\ : * ? " < > ?

Note

- The actual data output is in the ASCII format with the following type of header added.

Measurement ID, Data1 Data N + delimiter

|

Measurement time: YYYY-MM-DD_HH-MM-SS-

(YYYY: Calendar, MM: Month, DD: Day, HH: Hour, MM: Minute, SS: Second, MS: millisecond)

Example)

Measurement time: 11:10:25.500 AM, December 24, 2007

Measurement ID is "2007-12-24_11-10-25-500".

- Logging timing and saving destination

Reference: ▶ "Chapter 3 Performing Test Measurement/Starting Operation Useful Functions for Operation Logging Measurement Values and Measurement Images" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

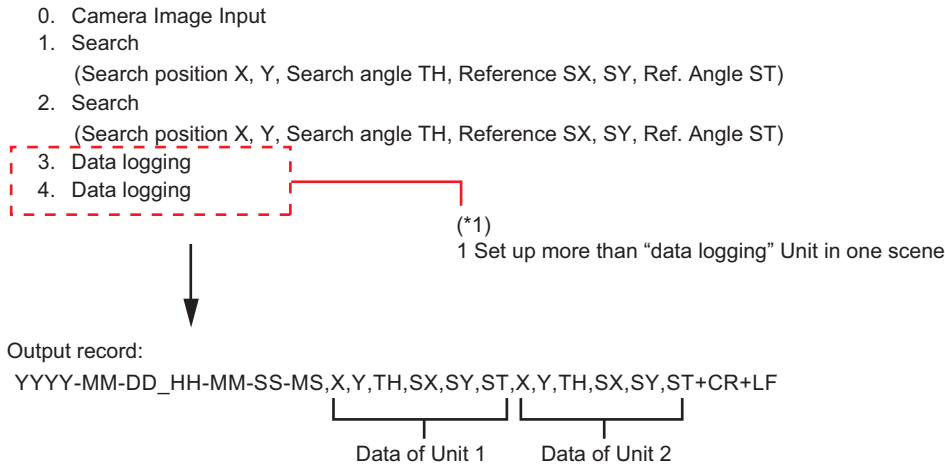
Additional Explanation (Data Logging)

When 9 or More Data Items Are Output as One Record

Up to 8 Value can be output with one [Data Logging] Processing Item. When 9 or more data items are to be output as 1 record, perform settings in the following manner.

- Registers two or more [Data Logging] units in one scene. (*1)
- Set [File name] of [Data Logging] so that it is identical. (*2)
- This prepares set up to attach "Record separator (CR+LF)" to the end of all data output. (*3)

Example) When outputting the coordinate data for 12 points acquired in two "Search" of measurements performed on substrate arrangement in 1 record.



Unit 3 [Data logging] setting details		Unit 4 [Data logging] setting details		Remarks
<Condition setting>		<Condition setting>		
Output Destination (File name)	datalog.csv	Output Destination (File name)	datalog.csv	(*2) Make the path and file name the same.
Integer	8	Integer	8	
Decimal	3	Decimal	3	
Measurement ID	ON	Measurement ID	OFF	
Minus	-	Minus	-	
0 suppress	OFF	0 suppress	OFF	
Field separator	Comma	Field separator	Comma	
Record separator	Comma	Record separator	CR+LF	(*3) Set "Record separator (CR+LF)" in unit 4 which contains the last data
<Output data>		<Output data>		
Calculation 0. U1.X (Search position X) Calculation 1. U1.Y (Search position Y) Calculation 2. U1.TH (Angle θ) Calculation 3. U1.SX (reference X) Calculation 4. U1.SY (reference Y) Calculation 5. U1.ST (Reference angle θ) Calculation 6. U2.X (Search position X) Calculation 7. U2.Y (Search position Y)		Calculation 0. U2.TH (Search angle θ) Calculation 1. U2.SX (reference X) Calculation 2. U2.SY (reference Y) Calculation 3. U2.ST (Reference angle θ)		The data not included in Unit 3 will be output as Calculation 0 to 3 in Unit 4

Unit 3 [Data logging] setting details	Unit 4 [Data logging] setting details	Remarks
127 + N (N = 0 to 7)	Comment	Character string
135 + N (N = 0 to 7)	Expression	Expression character string
143	Output destination file name	Character string
144	Sub folder name	Character string
145	Prefix	Character string
146	Specifying destination	0: Not specified 1: Specified

Measurement Results for Which Output Is Possible (Data Logging)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement item	Character string	Description
Judge	JG	Judgement result
Result of Expression 0 - Result of Expression 7	D00 to D07	Expression result of expression 0 to Expression result of expression 7

External Reference Tables (Data Logging)

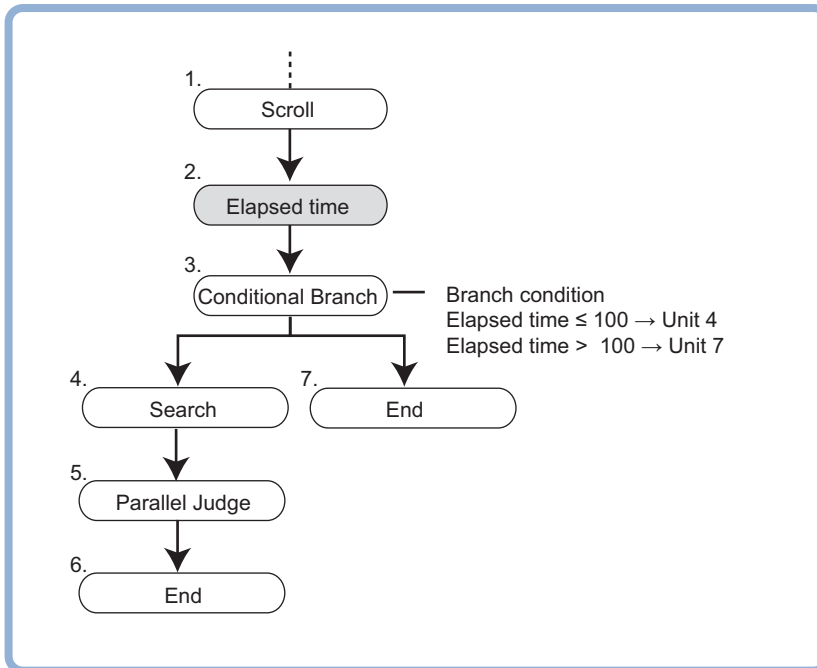
No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5 to 12	Result of Expression 0 - Result of Expression 7	Get only	Calculation results of expressions
120	Measurement ID	Set/Get	0: OFF, 1: ON
121	Integer	Set/Get	1 to 10
122	Decimal	Set/Get	0: 0 to 4: 4
123	Minus	Set/Get	0: -, 1:8
124	Field separator	Set/Get	0: OFF, 1: Comma, 2: Tab, 3: Space, 4: CR+LF
125	Record separator	Set/Get	0: OFF 1: Comma, 2: Tab, 3: Space, 4: CR+LF
126	0 suppress	Set/Get	0: OFF, 1: ON
127 + N (N = 0 to 7)	Comment	Set/Get	Character string
135 + N (N = 0 to 7)	Expressions	Set/Get	Exp. character string
143	File name	Set/Get	Character string
144	Sub directory name	Set/Get	Character string
145	Prefix	Set/Get	Character string
146	Destination setting	Set/Get	0: Not setting 1: Setting

Elapsed Time

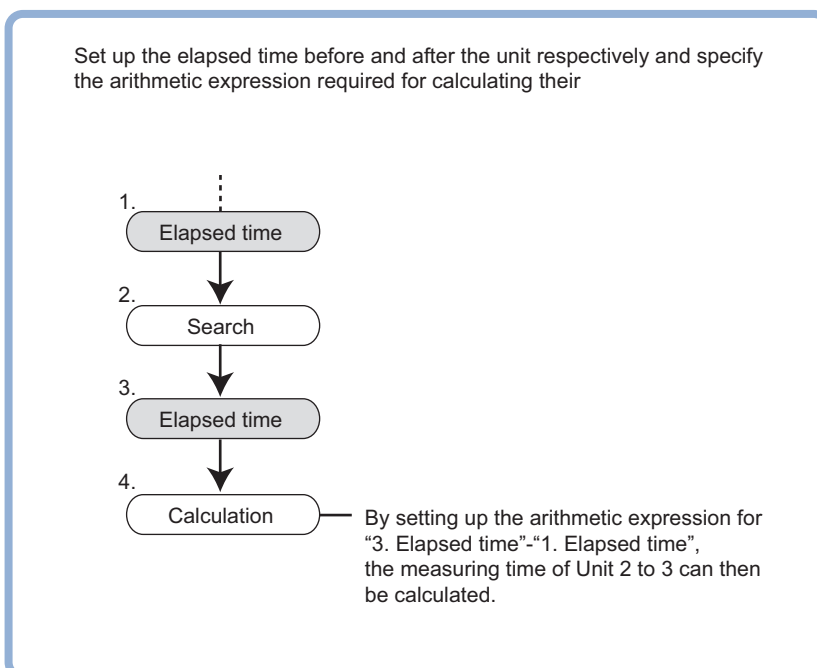
Calculate the elapsed time in milliseconds after the measurement starts. You can add this processing item to a scene and setup is not required.

Used in the Following Case

- When combining with the conditional branch for stopping measurement after the specified processing time has elapsed.



- When calculating the processing execution time of a unit



Note

- Time elapse can be confirmed on the main screen "Detail result" area.

```
[11.Elapsed Time]
Judge : OK
Elapsed time : 33ms
```

Measurement Results for Which Output Is Possible (Elapsed Time)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Latest processing unit judgement result
Elapsed Time	TM	Elapsed time from start of measurement (ms)

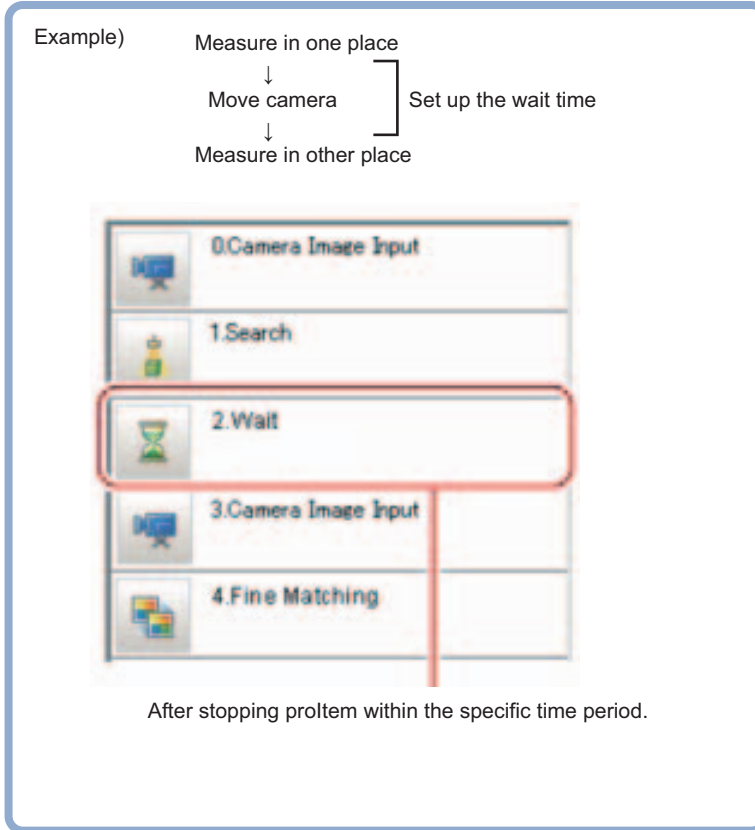
External Reference Tables (Elapsed Time)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Elapsed Time	Get only	0 to 999999

Wait

Used in the Following Case

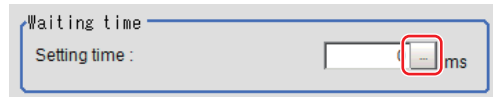
- When pausing the measurement flow and setting processing in standby for a specific period of time



Settings (Wait)

- 1 Set the temporary stop time for flow in the "Waiting time" area.**

Please specify the time in ms.
This can be set to a range of 0 to 9999.



- 2 Click [OK].**

The settings are finalized.

External Reference Tables (Wait)

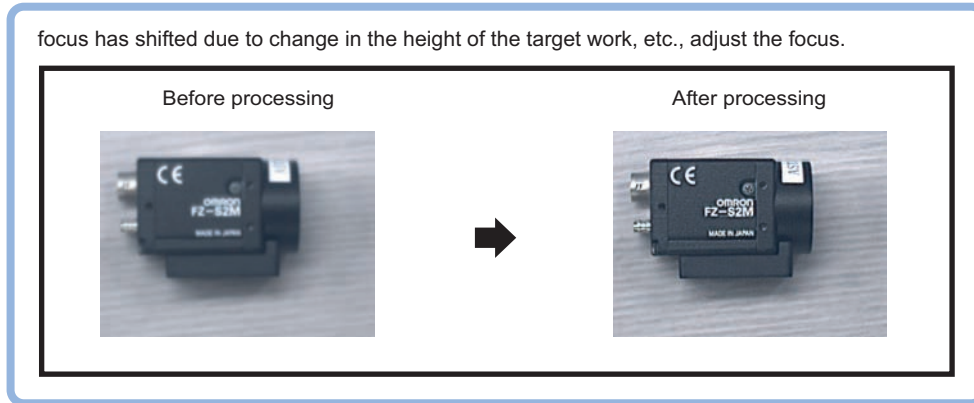
No.	Data name	Set/Get	Data range
120	Waiting time	Set/Get	0 to 9999 (ms)

Focus

This function helps you bring the camera into focus.

Used in the Following Case

- Use this function to make adjustments so as to facilitate inspection of input images that tend to become out of focus.



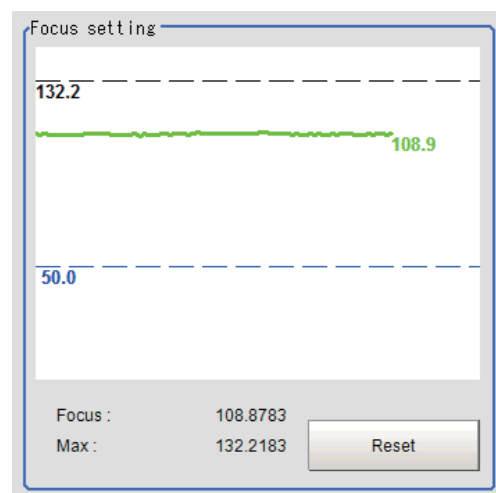
Measurement Parameters (Focus)

Measurement parameters can be changed as needed to address unstable focus values.

- 1 In the Item Tab area, click [Measurement].
- 2 In the "Display" area, click [Change display] to switch between camera image types.
(Re-measurement images are not shown on the setting window.)

Setting item	Set value	Description
ON	Through	The latest image is always input from the camera and displayed.
	Freeze	The image that was scanned in the immediately preceding measurement is displayed.

- 3 Set the focus value.
The focus value is displayed chronologically in real time in the graph area.



- 4 Set up the judgement condition.

Setting item	Set value [Factory default]	Description
Focus	0.0000 to 255.0000 [50.0000]	This item specifies the judgement value for focus.

Region Setting (Focus)

Set the range of focus adjustment.

- 1** In the Item Tab area, click [Region setting].
- 2** Click [Edit].
The figure setting area is displayed.
- 3** Specify the range of focus adjustment.
The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.
- 4** Click [OK].
The range to adjust is registered.

Output Parameters (Focus)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- 1** Click [Output parameter] in the Item Tab area.
- 2** Choose whether or not to reflect this in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgment results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Focus)

Displayed items	Description
Judge	Judgement result
Focus	Focus value

External Reference Tables (Focus)

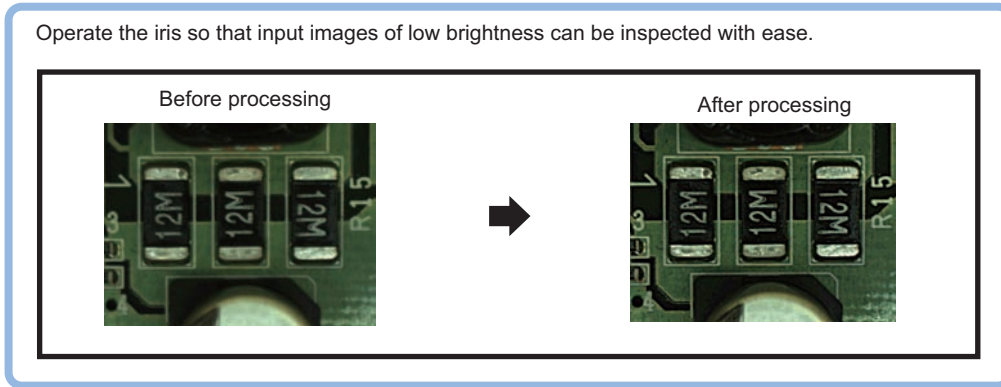
No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
1	Measurement data Focus value	Get only	0 to 255
2	Focus maximum value	Get only	0 to 255
3	Last focus value	Get only	0 to 255
103	Setting data Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Setting data Focus value Lower limit	Set/Get	0 to 255

Iris

This function assists the aperture operation to adjust the amount of light taken in by the camera according to the change in illumination intensity.

Used in the Following Case

- When brightness at the measurement site changes:



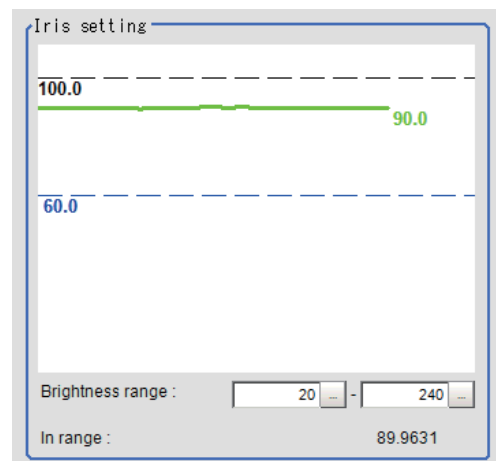
Measurement Parameters (Iris)

Adjust the amount of light taken in through the lens. Change the measurement parameter as necessary.

- 1 In the Item Tab area, click [Measurement].
- 2 In the "Display" area, click [Change display] to switch between camera image types.
(Re-measurement images are not shown on the setting window.)

Setting item	Set value	Description
Display	Through	The latest image is always input from the camera and displayed.
	Freeze	The image that was scanned in the immediately preceding measurement is displayed.

- 3 Set the valid brightness range.
The valid pixels are displayed chronologically in real time in the graph area.



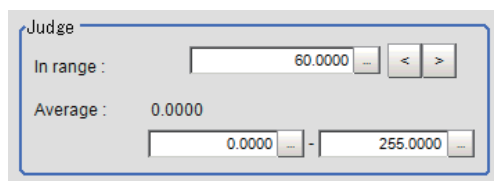
Setting item	Set value [Factory default]	Description
Brightness range	Upper limit 0 to 255 [240]	Set the range used to determine whether or not the brightness of pixels is valid.
	Lower limit 0 to 255 [20]	

4 Set up the judgement condition.

For color cameras:

Setting item		Set value [Factory default]	Description
In range		0.0000 to 100.0000 [60.0000]	Set the minimum number of pixels to be made valid. Valid pixels indicate the percentage (%) of pixels inside the valid brightness range in the region.
R average	Upper limit	0 to 255 [255.000]	Set the R, G and B ranges to be made valid.
	Lower limit	0 to 255 [0.000]	
G average	Upper limit	0 to 255 [255.000]	
	Lower limit	0 to 255 [0.000]	
B average	Upper limit	0 to 255 [255.000]	
	Lower limit	0 to 255 [0.000]	

For monochrome cameras:



Setting item		Set value [Factory default]	Description
In range		0.0000 to 100.0000 [60.0000]	Set the minimum number of pixels to be made valid. Valid pixels indicate the percentage (%) of pixels inside the valid brightness range in the region.
Average	Upper limit	0 to 255 [255.000]	Set the average brightness range to be made valid.
	Lower limit	0 to 255 [0.000]	

Region Setting (Iris)

Set the range of iris adjustment.

- 1** In the Item Tab area, click [Region setting].
- 2** Click [Edit].
The figure setting area is displayed.
- 3** Specify the range of iris adjustment.
The rectangle covering the entire screen is set. Adjust the size and position of the rectangle.
- 4** Click [OK].
The range to adjust is registered.

Output Parameter (Iris)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Choose whether or not to reflect this in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Iris)

Displayed items	Description
Judge	Judgement result
In range	Percentage inside the valid brightness range
R average	R average in the region
G average	G average in the region
B average	B average in the region

External Reference Tables (Iris)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
1	Measurement data Valid pixel	Get only	0 to 100
2	Measurement data Average brightness	Get only	0 to 255
3	Measurement data R average	Get only	0 to 255
4	Measurement data G average	Get only	0 to 255
5	Measurement data B average	Get only	0 to 255
6	Last valid pixel	Get only	0 to 100
7	Last average brightness	Get only	0 to 255
8	Last average R component value	Get only	0 to 255
9	Last average G component value	Get only	0 to 255
10	Last average B component value	Get only	0 to 255
103	Setting data Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Setting data Valid brightness range Lower limit	Set/Get	0 to 255
121	Setting data Valid brightness range Upper limit	Set/Get	0 to 255
122	Setting data Valid pixel Lower limit	Set/Get	0 to 100
123	Setting data Average brightness Lower limit	Set/Get	0 to 255

No.	Data name	Set/Get	Data range
124	Setting data Average brightness Upper limit	Set/Get	0 to 255
125	Setting data R average Lower limit	Set/Get	0 to 255
126	Setting data R average Upper limit	Set/Get	0 to 255
127	Setting data G average Lower limit	Set/Get	0 to 255
128	Setting data G average Upper limit	Set/Get	0 to 255
129	Setting data B average Lower limit	Set/Get	0 to 255
130	Setting data B average Upper limit	Set/Get	0 to 255

Parallelize

This processing item is used exclusively for the FH/FZ5-11□□.

The measurement time can be reduced by dividing one part of the measurement flow to two or more tasks and doing each one in parallel.

Measurement processing of the processing unit can be done in parallel when the operation mode's parallel processing is ON. When parallel processing is OFF, measurement processing of the processing unit is processed in series according to the execution order of the measurement flow.

You can add this processing item to a scene and setup is not required. Place it at the beginning of the process that you want to run in parallel.

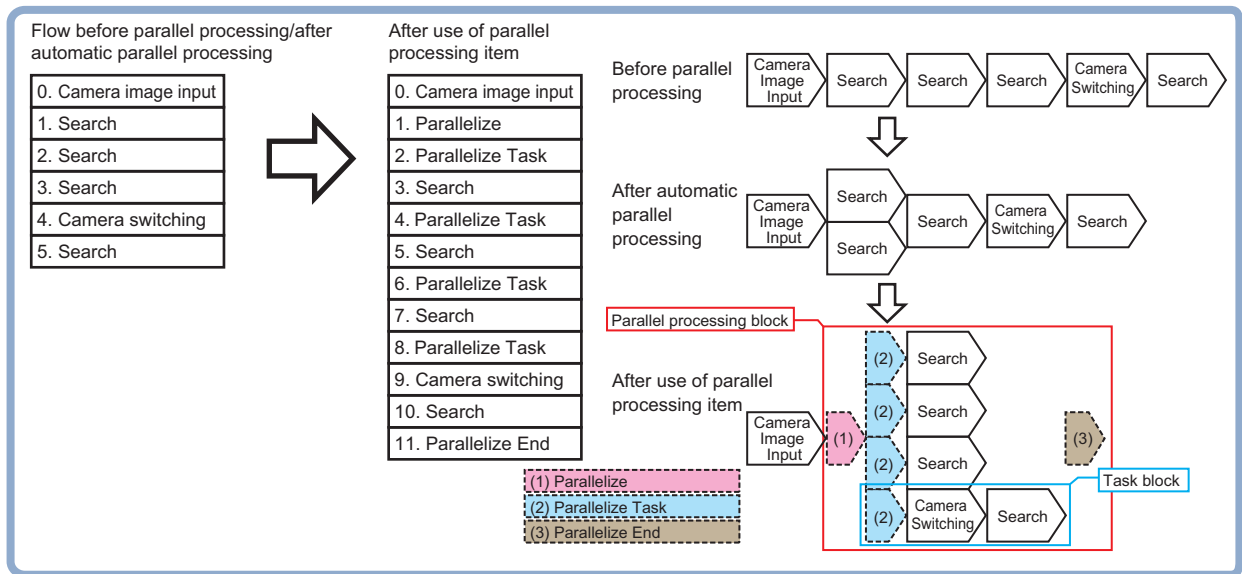
Parallel processing, parallel processing tasks, and parallel processing end cannot be used separately. Make sure to use them together as a set.

Reference: See ▶ "Parallel Processing" in "Chapter 6 Changing the System Environment" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Used in the Following Case

- When you want to reduce the overall processing time when there are multiple measurement processing items in the measurement flow

Example) Reducing the overall processing time, instead of performing series processing, by processing multiple searches in parallel.



Processing units can be executed in parallel by properly combining parallel processing, parallel processing tasks, and parallel processing end.

Parallelize Task

This processing item is used exclusively for the FH/FZ5-11□□.

The measurement time can be reduced by dividing one part of the measurement flow to two or more tasks and doing each one in parallel.

Measurement processing of the processing unit can be done in parallel when the operation mode's parallel processing is ON. When parallel processing is OFF, measurement processing of the processing unit is processed in series according to the execution order of the measurement flow.

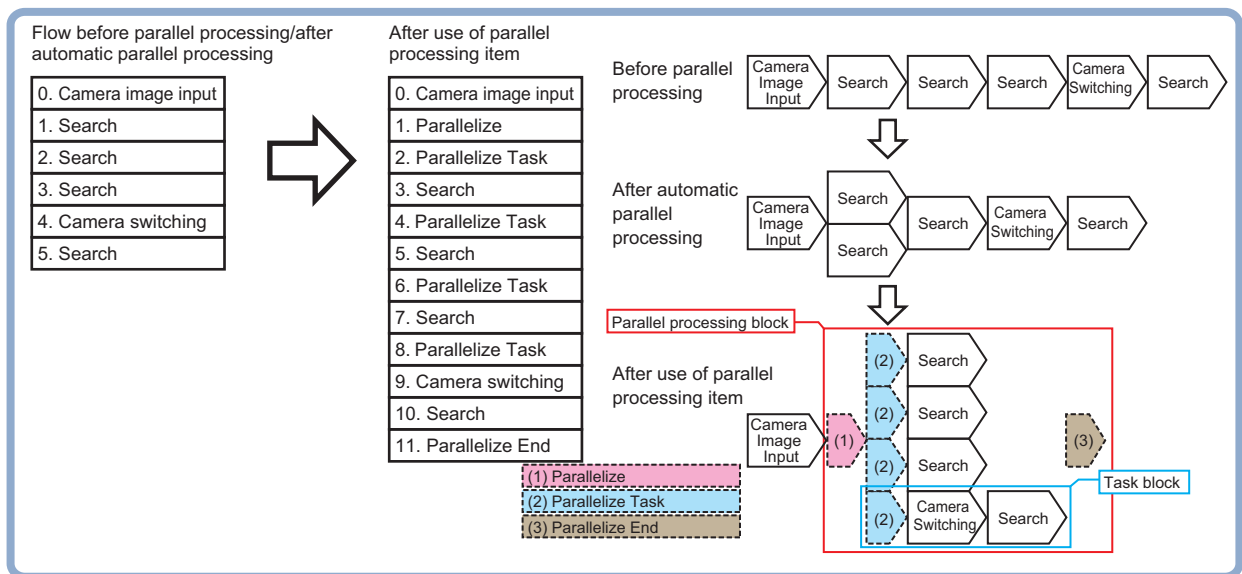
You can add this processing item to a scene and setup is not required. Place this right before the process you want to perform in parallel, between the parallel processing item and parallel processing end processing item. Parallel processing, parallel processing tasks, and parallel processing end cannot be used separately. Make sure to use them together as a set.

Reference: See ▶ "Parallel Processing" in "Chapter 6 Changing the System Environment" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Used in the Following Case

- **When you want to reduce the overall processing time when there are multiple measurement processing items in the measurement flow**

Example) Reducing the overall processing time, instead of performing series processing, by processing multiple searches in parallel.



Processing units can be executed in parallel by properly combining parallel processing, parallel processing tasks, and parallel processing end.

Statistics

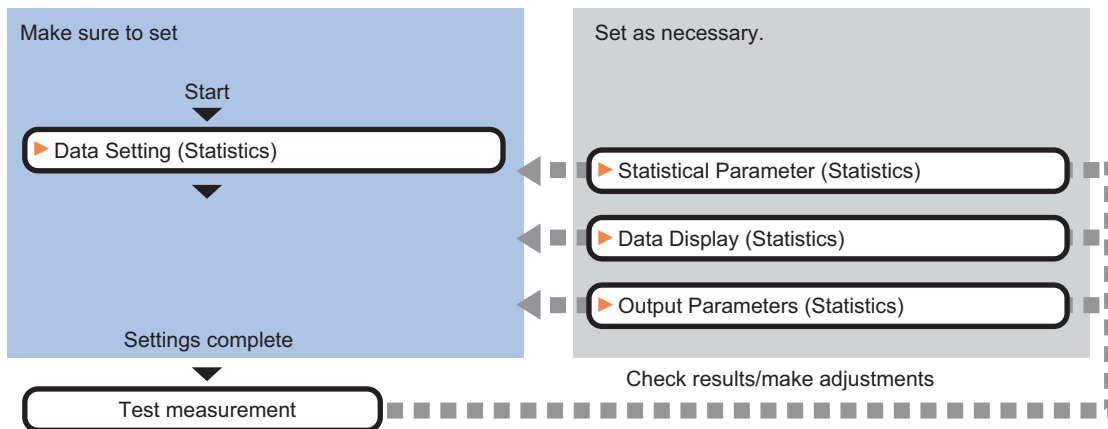
To reduce measurement variation of a given measurement processing item, multiple measurement results are stored in the processing item and statistical processing is performed at a specified timing. Up to 8 data can be set for statistical processing per processing item.

Used in the Following Case

- When you want to use an average of multiple measurement results as the measurement value because the work is vibrating

Settings Flow (Statistics)

Set up statistical processing according to the following flow.



List of Statistics Items

Item name	Description
Statistical parameter	Set the number of data to be stored as well as processing timing. Reference: ▶ Statistical Parameters (Statistics) (p.612)
Data setting	Set the data to be processed using a calculation formula. Reference: ▶ Data Setting (Statistics) (p.612)
Data display	Set up for checking of stored data using a graph. Reference: ▶ Data Display (Statistics) (p.613)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Reference: ▶ Output Parameters (Statistics) (p.614)

Statistical Parameters (Statistics)

Set the number of data to be stored as well as processing timing. The greater the number of data held, the less the measurement variation becomes.

1 Click [Statistical parameter] in the Item Tab area.

2 Set the maximum number of data to be saved in the "Max. data count" area.

Setting item	Setting value [Factory default]	Description
Max. data count	1 to 100 [10]	Set the maximum number of stored data to be saved to one processing target data.

3 Set the timing of statistical processing in the "Calculate timing" area.

Setting item	Setting value [Factory default]	Description
Calculate timing	<ul style="list-style-type: none"> • Every time • [Reach max. data count] 	Select the timing at which to perform statistical processing.

4 Click [OK].

Data Setting (Statistics)

Set the data to be processed using a calculation formula. Up to 8 data can be set.

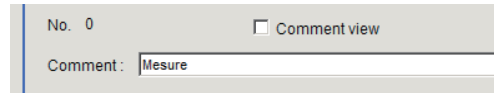
1 In the Item Tab area, click [Data setting].

2 In the "Data setting" area, specify each item.

Up to 8 data can be set.

Setting item	Setting value [Factory default]	Description
Comment	-	Set a comment explaining the expression to be applied to the data to be processed.
Expression	-	Set the expression to be applied to the data to be processed.

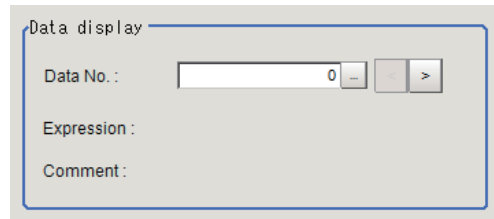
- 3 To display comments in the "Detail result display" area, check "Comment view".



Data Display (Statistics)

Set up for checking of stored data using a graph. Also, set the judgement range while checking the graph. Data outside the judgement range will not be processed.

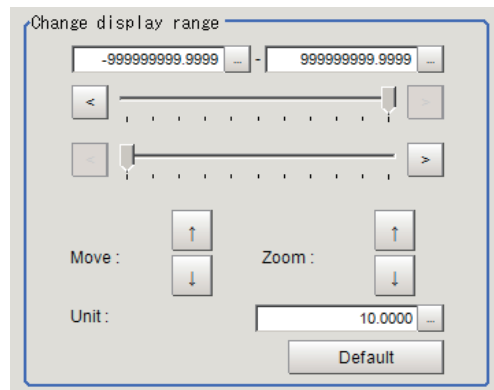
- 1 In the Item Tab area, click [Data display].
- 2 In the "Data display" area, set the data number to be used as the target of [Data setting].



Setting item	Setting value [Factory default]	Description
Data No.	0 to 7 [0]	Set the data number to be used as the target of data setting.
Expression	-	Set data of the expression corresponding to the data number is displayed.
Comment	-	Set data of the comment corresponding to the data number is displayed.

- 3 In the "Change display range" area, set the upper and lower limit values of graph display range.

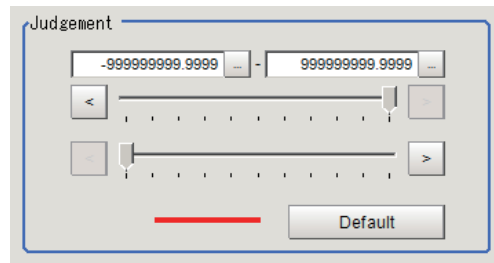
If the window is entered after measurement is performed a few times and [Default] is clicked, a display range suitable for these measurement values is automatically set.



Setting item	Setting value [Factory default]	Description
Upper and lower limit values of the graph display range	-999999999.9999 to 999999999.9999	Set the upper and lower limit values of the display range of the graph corresponding to the data number.
Unit	1.0000 to 1000000.0000 [10.0000]	Set how much the value will change when the Move or Zoom arrow button is clicked.

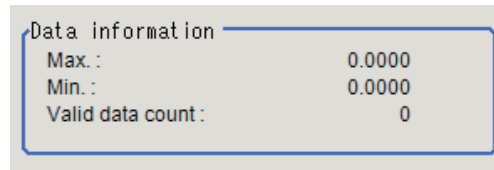
4 In the "Judgement" area, set the upper and lower limit values of set data judgement range.

If the window is entered after measurement is performed a few times and [Default] is clicked, a judgement range suitable for these measurement values is automatically set.



Setting item	Setting value [Factory default]	Description
Upper and lower limit values of the judgement range	-999999999.9999 to 999999999.9999	Set the upper and lower limit values of the judgement range corresponding to the data number.

5 The value reflecting the setting changes appears in the "Data information" area.



Output Parameters (Statistics)

Select how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Select the "Reflect to overall judgement".

Setting item	Setting value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Specify whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Statistics)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Calculated time	Number of measurements performed
Statistical result 0	Statistical processing result of data 0
Statistical result 1	Statistical processing result of data 1
Statistical result 2	Statistical processing result of data 2
Statistical result 3	Statistical processing result of data 3
Statistical result 4	Statistical processing result of data 4
Statistical result 5	Statistical processing result of data 5
Statistical result 6	Statistical processing result of data 6
Statistical result 7	Statistical processing result of data 7

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are false

State	Parameter to be adjusted	Troubleshooting
Not all data is included in the calculation	Data display	Data outside the judgement range will not be processed. If any necessary data is outside the judgement range, set the judgement range again.
The measurement result remains 0.0	Statistical parameter	If the calculation timing is "Only when the maximum number of data is reached," the measurement result remains 0.0 while the number of measurements is yet to reach the maximum number saved. Change the calculation timing on the statistical parameter tab to "Every time," and the measurement result will be calculated every time.

When the graph displays are false

State	Parameter to be adjusted	Troubleshooting
A graph showing a flat line appears even when the value is changing.	Data display	Change the graph display range to an appropriate range. If the initial values remain unchanged, the display range is too wide and the graph will show a flat line. Perform measurement at least twice, and then click the default range button on the data display tab.

Measurement Results for Which Output Is Possible (Statistics)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Calculated time	CT	Count
Statistic value N (N = 0 to 7)	DTN (N = 0 to 7)	Statistical processing result 0 to 7
Valid data N (N = 0 to 7)	OCN (N = 0 to 7)	Number of valid statistical processing data 0 to 7
Maximum N (N = 0 to 7)	MXN (N = 0 to 7)	Stored data maximum value 0 to 7
Minimum N (N = 0 to 7)	MNN (N = 0 to 7)	Stored data minimum value 0 to 7

External Reference Tables (Statistics)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Calculated time	Get only	0 to 100
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Maximum number of stored data	Set/Get	1 to 100
121	Data No.	Set/Get	0 to 7
122	Calculation timing	Set/Get	0 to 1
131 + N × 10 (N = 0 to 7)	Data expression N	Set/Get	Exp. character string
132 + N × 10 (N = 0 to 7)	Data N Upper limit of the judgement range	Set/Get	-999999999.9999 to 999999999.9999
133 + N × 10 (N = 0 to 7)	Data N Lower limit of the judgement range	Set/Get	-999999999.9999 to 999999999.9999
134 + N × 10 (N = 0 to 7)	Data N Upper limit of the display range	Set/Get	-999999999.9999 to 999999999.9999
135 + N × 10 (N = 0 to 7)	Data N Upper limit of the display range	Set/Get	-999999999.9999 to 999999999.9999
136 + N × 10 (N = 0 to 7)	Amount of change in data N display range	Set/Get	1 to 1000000
137 + N × 10 (N = 0 to 7)	Data N Measurement value	Set/Get	-999999999.9999 to 999999999.9999
138 + N × 10 (N = 0 to 7)	Expressions comment N	Set/Get	Character string
1000 + N × 10 (N = 0 to 7)	Measurement	Set/Get	-999999999.9999 to 999999999.9999
1001 + N × 10 (N = 0 to 7)	Statistical value	Set/Get	-999999999.9999 to 999999999.9999
1002 + N × 10 (N = 0 to 7)	Number of valid data	Set/Get	0 to 100
1003 + N × 10 (N = 0 to 7)	Maximum	Set/Get	-999999999.9999 to 999999999.9999
1004 + N × 10 (N = 0 to 7)	Minimum	Set/Get	-999999999.9999 to 999999999.9999
10000 + N × 1 (N = 0 to 99)	Stored data N of data 0	Get only	-999999999.9999 to 999999999.9999
11000 + N × 1 (N = 0 to 99)	Stored data N of data 1	Get only	-999999999.9999 to 999999999.9999
12000 + N × 1 (N = 0 to 99)	Stored data N of data 2	Get only	-999999999.9999 to 999999999.9999
13000 + N × 1 (N = 0 to 99)	Stored data N of data 3	Get only	-999999999.9999 to 999999999.9999
14000 + N × 1 (N = 0 to 99)	Stored data N of data 4	Get only	-999999999.9999 to 999999999.9999

No.	Data name	Set/Get	Data range
15000 + N × 1 (N = 0 to 99)	Stored data N of data 5	Get only	-999999999.9999 to 999999999.9999
16000 + N × 1 (N = 0 to 99)	Stored data N of data 6	Get only	-999999999.9999 to 999999999.9999
17000 + N × 1 (N = 0 to 99)	Stored data N of data 7	Get only	-999999999.9999 to 999999999.9999

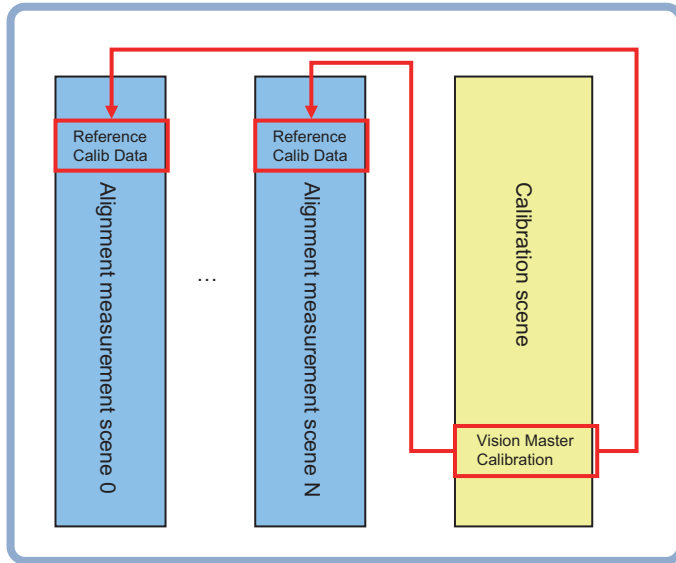
Reference Calib Data

Calibration data and distortion compensation data held under other processing items can be referenced. Referenced data will be used to perform coordinate conversion processing and distortion compensation processing on measurement results after this processing unit.

As for distortion compensation processing, you can select not only "Compensate measurement result," but also "Compensate measurement image".

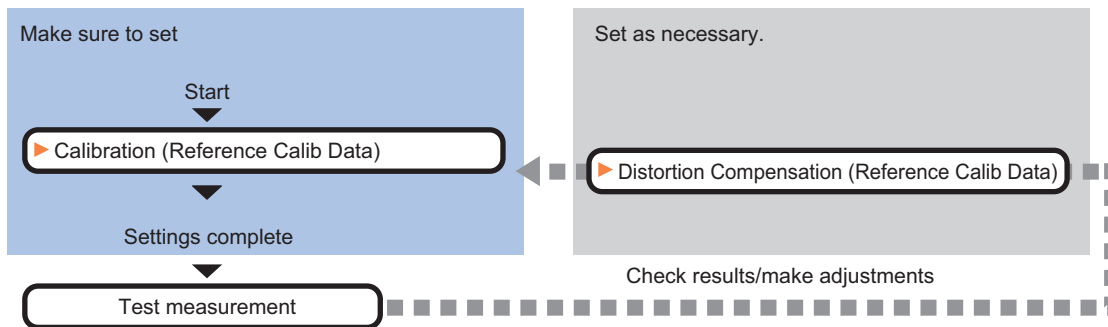
Used in the Following Case

- When you want to position the FPD panel



Settings Flow (Reference Calib Data)

Calibration reference can be set up as follows.



List of Reference Calib Data Items

Item name	Description
Calibration	Select the processing unit which holds calibration data. Data can be referenced not only from the current scene, but also from other scenes. Reference: ▶ Calibration (Reference Calib Data) (p.619)
Distortion correction	Select the processing unit in which the distortion compensation data to be referenced is held. Data can be referenced not only from the current scene, but also from other scenes. One of the two compensation methods, namely image correction and measurement value correction, can be selected. Reference: ▶ Distortion Correction (Reference Calib Data) (p.620)

Calibration (Reference Calib Data)

Select the processing unit in which the calibration data to be referenced is held.

- 1** In the Item Tab area, click [Calibration].
- 2** Select the reference scene No., reference unit No., and reference data No.

Item name	Description
Scene No.	Select the scene number to be referenced to obtain calibration data.
Unit No.	Select the unit number to be referenced to obtain calibration data. Units that can be referenced include camera image input, camera image input FH, camera image input HDR, camera image input HDR Lite, image master calibration, PLC master calibration, camera calibration and precise calibration.
Data No.	Select the position of the calibration data to be referenced among the data held in the unit to be referenced.
Reference data	Display the referenced calibration data. This display is updated when the reference scene number is changed, reference unit number is changed, or reference calibration data number is changed. If "None" is selected, the initial value is displayed. <ul style="list-style-type: none"> • Affine transformation parameter (A to F): Value (up to the sixth decimal place) • XY magnification: Value (up to the sixth decimal place) • Origin XY: Value (up to the sixth decimal place) • X axis angle, Y axis angle, XY angle: Value (up to the sixth decimal place)

Distortion Correction (Reference Calib Data)

Select the processing unit in which the distortion compensation data to be referenced is held.

1 In the Item Tab area, click [Distortion correction].

2 Place a check at [Distortion correction] and select the reference scene number and reference unit number.

Item name	Description
Distortion correction	Place a check at [Distortion correction] if one of the conditions below is met: <ul style="list-style-type: none"> • Vision master calibration was performed with "Trapezoidal distortion" or "Lens distortion" selected under [Distortion correction setting]. • Precise calibration was performed with the correction settings turned "ON" on the [Image correction] tab.
Scene No.	Select the number of the scene to be referenced to obtain distortion compensation data.
Unit No.	Select the number of the unit to be referenced to obtain distortion compensation data. A high-precision calibration unit or image master calibration unit can be referenced.
Data No.	0 to 7 This item can be specified only when an image master calibration unit is selected for reference.
Using referred data	Initial value Checked
Height adjustment	Select "ON" to perform height adjustment using the reference data. Initial value OFF
Image correction	Select "ON" to perform image correction. Initial value OFF

Important

- When image correction is OFF, coordinate distortion compensation process is executed only for coordinate values.
- Note that no distortion compensation process is executed for other feature quantities such as an area.

Key Points for Test Measurement and Adjustment (Reference Calib Data)

The following content is displayed in the "Detail result" area as text.

Setting item	Description
Judge	Judge
A	Affine transformation parameter A
B	Affine transformation parameter B
C	Affine transformation parameter C
D	Affine transformation parameter D
E	Affine transformation parameter E
F	Affine transformation parameter F
X magnification	X magnification.
Y magnification	Y magnification.
Origin X	Origin X.
Origin Y	Origin Y.
X axis angle	X axis angle.
Y axis angle	Y axis angle.
XY axis angle	XY axis angle.

Measurement Results for Which Output Is Possible (Reference Calib Data)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Setting item	Character string	Description
Judge	JG	Judge

External Reference Tables (Reference Calib Data)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	A	Get only	-
6	B	Get only	-
7	C	Get only	-
8	D	Get only	-
9	E	Get only	-
10	F	Get only	-
11	X magnification	Get only	-
12	Y magnification	Get only	-
13	Origin X	Get only	-
14	Origin Y	Get only	-
15	X axis angle	Get only	0.000000 to 360.000000
16	Y axis angle	Get only	0.000000 to 360.000000

No.	Data name	Set/Get	Data range
17	XY angle	Get only	0.000000 to 180.000000
18	Focal distance of lens [mm]	Get only	5.0000 to 100.0000
19	CCD pixel size [μm]	Get only	3.4500 to 7.4000
20	Plate height [mm]	Get only	-100.0000 to 100.0000
21	Depth settings	Get only	0: OFF 1: ON
22	Image correction	Get only	0: OFF 1: ON
23	Workpiece height	Get only	-100.0000 to 100.0000
120	Reference scene No. (Calibration)	Set/Get	-1: Current scene 0 to 9999
121	Reference unit No. (Calibration)	Set/Get	-1: No reference 0 to 9999
122	Reference data No. (Calibration)	Set/Get	0 to 7
123	Reference scene No. (Distortion compensation)	Set/Get	-1: Current scene 0 to 9999
124	Reference unit No. (Distortion compensation)	Set/Get	1: No reference 0 to 9999
125	Distortion compensation function	Set/Get	0: Not corrected 1: Corrected
126	Depth settings (resetting)	Set/Get	0: OFF 1: ON
127	Distortion compensation data reference setting	Set/Get	0: Not referenced 1: Referenced
128	Image correction (resetting)	Set/Get	0: OFF 1: ON
129	Workpiece height (resetting)	Set/Get	-100.0000 to 100.0000
130	Reference data No. (Distortion compensation)	Set/Get	0 to 7

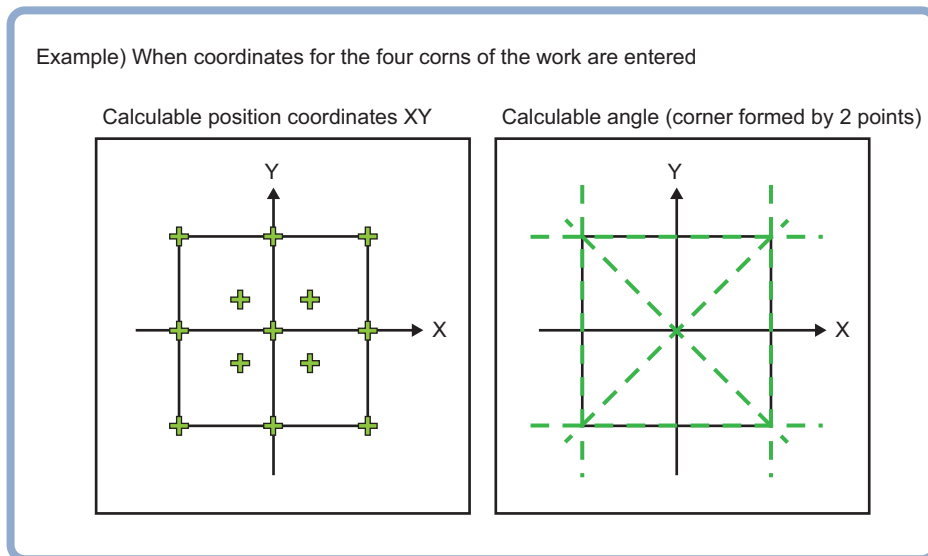
Position Data Calculation

Calculates position data and angle data used in the Position Data Calculation based on the measurement results of multiple processing items. Up to 4 measurement results can be used for the calculation.

It lets users easily calculate "The angle of a line between 2 points" and "the center point of two points" that are often used in alignment applications.

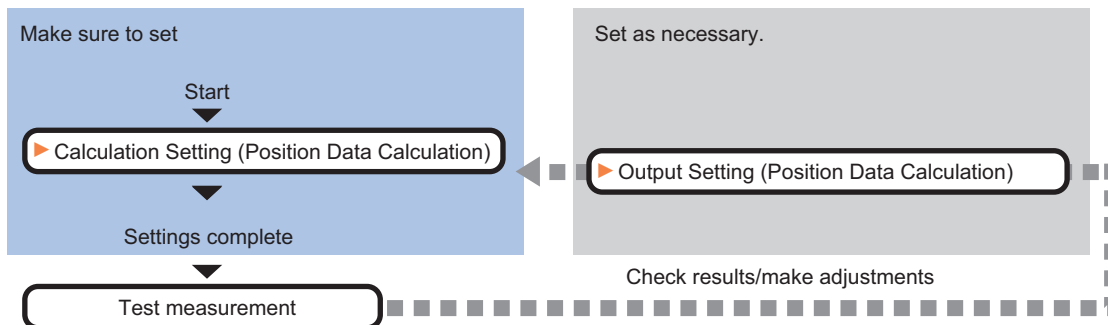
Used in the Following Case

- When you want to position the FPD panel



Settings Flow (Position Data Calculation)

The position/angle calculation should be set up with the following procedure.



List of Position Data Calculation Items

Item name	Description
Calculation setting	Set the data to be processed using a calculation formula. Up to 4 data can be set. The position data to be output is calculated by calculating the average of the position data of the points selected in "Calculation target position selection". The angle data to be output is calculated using the method selected in "Angle calculation method selection". Reference: ▶ Calculation Setting (Position Data Calculation) (p.624)
Output setting	This item can be changed if necessary. Normally, the factory default value will be used. Select whether to reflect the judgement result to the overall judgement of the scene. Reference: ▶ Output Setting (Position Data Calculation) (p.626)

Calculation Setting (Position Data Calculation)

Calculates position data and angle data used in the axis movement amount calculation based on the measurement results of multiple processing items.

1 In the Item Tab area, click [Calculation setting].

2 In the "Select calculation target position" area, select points to be used in the position calculation.

3 Select the angle calculation method in the "Select angle calculation method" area. Angle data is calculated using the selected method and the result is output.

Setting item	Setting value [Factory default]	Description
Select angle calculation method	<ul style="list-style-type: none"> • Points 0-3 • Line (point0-point1) • Line (point0-point2) • Line (point0-point3) • Line (point1-point0) • Line (point1-point2) • Line (point1-point3) • Line (point2-point0) • Line (point2-point1) • Line (point2-point3) • Line (point3-point0) • Line (point3-point1) • Line (point3-point2) 	Select the method for calculating the angle. Line (point0-point1) indicates an angle created by connecting Point 0 and Point 1.

Note

- As for the calculation of the angle formed by points, "Line (point0--point1)" and "Line (point1-point0)" output different angles. Use the suitable one.

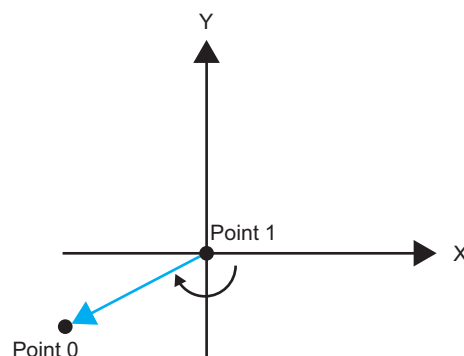
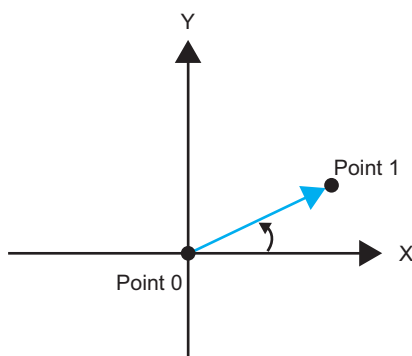


Fig. 1 angle of a side line formed by Point 0 – 1 Fig. 2 angle of a side line formed by Point 1 – 0

- As for data necessary for the calculation, the points X and Y for the points checked for position data calculation must not be empty. The angle data is as shown in the table in the next page.

Data necessary for angle data (○: data needed to be entered)								
Angle calculation method selection	Point 0		Point 1		Point 2		Point 3	
	Position XY	Angle	Position XY	Angle	Position XY	Angle	Position XY	Angle
Point 0		○						
Point 1				○				
Point 2						○		
Point 3								○
Side line formed by Points 0-1	○		○					
Side line formed by Points 0-2	○				○			
Side line formed by Points 0-3	○						○	
Side line formed by Points 1-0	○		○					
Side line formed by Points 1-2			○		○			
Side line formed by Points 1-3			○				○	
Side line formed by Points 2-0	○				○			
Side line formed by Points 2-1			○		○			
Side line formed by Points 2-3					○		○	
Side line formed by Points 3-0	○						○	
Side line formed by Points 3-1			○				○	
Side line formed by Points 3-2					○		○	

4 Set the position information of Points 0 to 3 as needed.

5 If the setting has been changed, click [Measure] to check the calculation result.

Test measuring of this item

Measure

6 Set up the judgement condition.

Setting item	Setting value [Factory default]	Description
Calculate position X	-99999.9999 to 99999.9999	Specify the range of X-axis calculation positions that is judged to be OK.
Calculate position Y	-99999.9999 to 99999.9999	Specify the range of Y-axis calculation positions that is judged to be OK.
Calculate angle	-180.0000 to 180.0000	Specify the range of calculation angles that is judged to be OK.

Output Setting (Position Data Calculation)

Specifies whether or not the judgement results of this processing unit is reflected in the overall judgement.

- 1** Click [Output setting] in the Item Tab area.
- 2** Choose whether or not to reflect the judgement result in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Setting value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Specify whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Position Data Calculation)

The following content is displayed in the "Detail result" area as text.

Setting item	Description
Judge	Judge
Calculation position X	Calculation position X
Calculation position Y	Calculation position Y
Calculation angle	Calculation angle

Measurement Results for Which Output Is Possible (Position Data Calculation)

The following values can be output using processing items related to the "output result" processing item. It is also possible to reference measurement values from expressions and other processing units.

Setting item	Character string	Description
Judge	JG	Judge
Calculation position X	X	Calculation position X
Calculation position Y	Y	Calculation position Y
Calculation angle	TH	Calculation angle
Calculation angle (Point 0)	TH0	Calculation angle for Point 0
Calculation angle (Point 1)	TH1	Calculation angle for Point 1
Calculation angle (Point 2)	TH2	Calculation angle for Point 2
Calculation angle (Point 3)	TH3	Calculation angle for Point 3
Calculation angle (Point 0-1)	TH01	Angle created by connecting Point 0-1.
Calculation angle (Point 0-2)	TH02	Angle created by connecting Point 0-2.
Calculation angle (Point 0-3)	TH03	Angle created by connecting Point 0-3.
Calculation angle (Point 1-0)	TH10	Angle created by connecting Point 1-0.
Calculation angle (Point 1-2)	TH12	Angle created by connecting Point 1-2.
Calculation angle (Point 1-3)	TH13	Angle created by connecting Point 1-3.
Calculation angle (Point 2-0)	TH20	Angle created by connecting Point 2-0.
Calculation angle (Point 2-1)	TH21	Angle created by connecting Point 2-1.
Calculation angle (Point 2-3)	TH23	Angle created by connecting Point 2-3.
Calculation angle (Point 3-0)	TH30	Angle created by connecting Point 3-0.

Setting item	Character string	Description
Calculation angle (Point 3-1)	TH31	Angle created by connecting Point 3-1.
Calculation angle (Point 3-2)	TH32	Angle created by connecting Point 3-2.

External Reference Tables (Position Data Calculation)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Calculation position X	Get only	-999999999.9999 to 999999999.9999
6	Calculation position Y	Get only	-999999999.9999 to 999999999.9999
7	Calculation angle	Get only	-180.0000 to 180.0000
8	Calculation angle (Point 0)	Get only	-180.0000 to 180.0000
9	Calculation angle (Point 1)	Get only	-180.0000 to 180.0000
10	Calculation angle (Point 2)	Get only	-180.0000 to 180.0000
11	Calculation angle (Point 3)	Get only	-180.0000 to 180.0000
12	Calculation angle (Point 0-1)	Get only	-180.0000 to 180.0000
13	Calculation angle (Point 0-2)	Get only	-180.0000 to 180.0000
14	Calculation angle (Point 0-3)	Get only	-180.0000 to 180.0000
15	Calculation angle (Point 1-0)	Get only	-180.0000 to 180.0000
16	Calculation angle (Point 1-2)	Get only	-180.0000 to 180.0000
17	Calculation angle (Point 1-3)	Get only	-180.0000 to 180.0000
18	Calculation angle (Point 2-0)	Get only	-180.0000 to 180.0000
19	Calculation angle (Point 2-1)	Get only	-180.0000 to 180.0000
20	Calculation angle (Point 2-3)	Get only	-180.0000 to 180.0000
21	Calculation angle (Point 3-0)	Get only	-180.0000 to 180.0000
22	Calculation angle (Point 3-1)	Get only	-180.0000 to 180.0000
23	Calculation angle (Point 3-2)	Get only	-180.0000 to 180.0000
103	Reflecting in the overall judgement	Set/Get	0: ON 1: OFF
120	Use the position of Point 0 for the calculation	Set/Get	0: Not used 1 : Used
121	Use the position of Point 1 for the calculation	Set/Get	0: Not used 1 : Used
122	Use the position of Point 2 for the calculation	Set/Get	0: Not used 1 : Used
123	Use the position of Point 3 for the calculation	Set/Get	0: Not used 1 : Used

No.	Data name	Set/Get	Data range
124	Angle calculation method selection	Set/Get	0 : Point 0 1 : Point 1 2 : Point 2 3 : Point 3 4 : Side line formed by Point 0-1 5 : Side line formed by Point 0-2 6 : Side line formed by Point 0-3 7 : Side line formed by Point 1-0 8 : Side line formed by Point 1-2 9 : Side line formed by Point 1-3 10 : Side line formed by Point 2-0 11 : Side line formed by Point 2-1 12 : Side line formed by Point 2-3 13 : Side line formed by Point 3-0 14 : Side line formed by Point 3-1 15 : Side line formed by Point 3-2
125	Upper limit value for the judgement position X	Set/Get	-999999999.9999 to 999999999.9999
126	Lower limit value for the judgement position X	Set/Get	-999999999.9999 to 999999999.9999
127	Upper limit value for the judgement position Y	Set/Get	-999999999.9999 to 999999999.9999
128	Lower limit value for the judgement position Y	Set/Get	-999999999.9999 to 999999999.9999
129	Upper limit value for the judgement angle	Set/Get	-180.0000 to 180.0000
130	Lower limit value for the judgement angle	Set/Get	-180.0000 to 180.0000
131	Point 0:X	Set/Get	Exp. character string
132	Point 0:Y	Set/Get	Exp. character string
133	Point 0:Angle	Set/Get	Exp. character string
141	Point 1:X	Set/Get	Exp. character string
142	Point 1:Y	Set/Get	Exp. character string
143	Point 1:Angle	Set/Get	Exp. character string
151	Point 2:X	Set/Get	Exp. character string
152	Point 2:Y	Set/Get	Exp. character string
153	Point 2:Angle	Set/Get	Exp. character string
161	Point 3:X	Set/Get	Exp. character string
162	Point 3:Y	Set/Get	Exp. character string
163	Point 3:Angle	Set/Get	Exp. character string

Stage Data

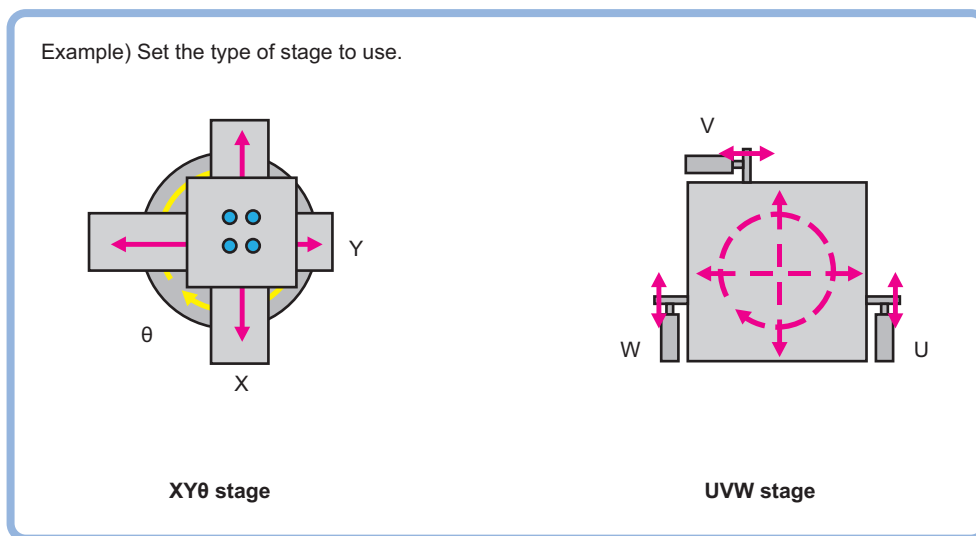
Stage data is a processing item that sets and preserves the data related to the stage of connecting to the Sensor controller. Set the data based on the specifications of the stage you are going to use.

When using a processing item which operates stages like the ones below, or which uses stage data, refer to this processing item.

- Vision master calibration
- PLC master calibration
- Reference calibration data
- Convert position data
- Movement single position
- Movement multi points

Used in the Following Case

- When setting parameters for the stage type and the rotation polarity



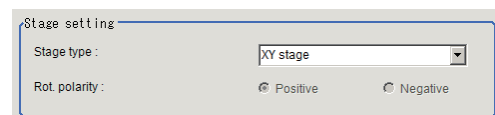
Data Setting (Stage Data)

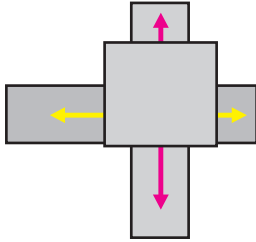
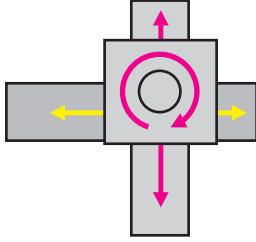
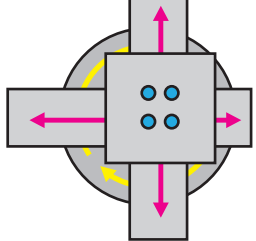
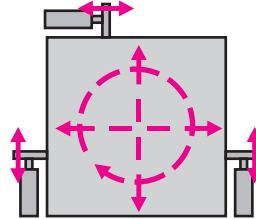
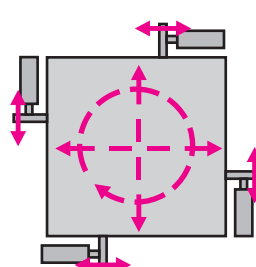
This item sets the stage type to be used and parameters. Select the stage you want to use and set the parameters according to the selected stage.

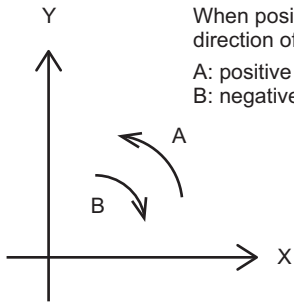
When operating a stage or using stage data, refer to this processing item from among the processing items.

Selecting a Stage Type (Stage Data)

- 1** In the "Stage setting" area, click [▼] in the [Stage type], and select your desired stage. Stages that can be used with this device are displayed.
- 2** If you select XYθ stage or θXY stage, the rotation polarity becomes selectable. Select the appropriate polarity.

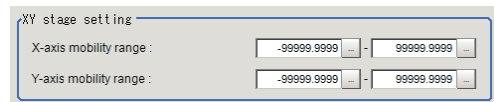


Setting item	Setting value [Factory default]	Description
Stage type	<ul style="list-style-type: none"> • [XY stage] • XYθ stage • θXY stage • UVW stage • UVWR stage 	<p>Usable "Stage types" are displayed. Select a stage. Usable "Stage types" are as follows:</p> <p>XY stage</p>  <p>XYθ stage</p>  <p>θXY stage</p>  <p>UVW stage</p>  <p>UVWR stage</p>  <p>When XY stage, UVW stage, or UVRW stage is selected, the rotation polarity selection becomes disabled.</p>

Setting item	Setting value [Factory default]	Description
Rot. polarity	<ul style="list-style-type: none"> • [Positive] • Negative 	<p>Select the rotation direction defined in the equipment is positive or negative compared to the rotation direction in the stage coordinate system.</p> <p>Polarities are as follows: Positive polarity/negative polarity</p>  <p>When positive rotation direction of the device is A: positive polarity B: negative polarity</p> <p>Stage coordinate system</p>

Setting the Data for Each Stage (XY Stage)

- 1 If XY stage is selected, the "XY stage setting" area is displayed.



- 2 Click [...] in [X-axis mobility range] in the "XY stage setting" area to set the upper and lower limit values.
- 3 Likewise click [...] in [Y-axis mobility range] to set the upper and lower limit values.

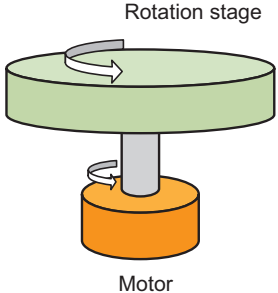
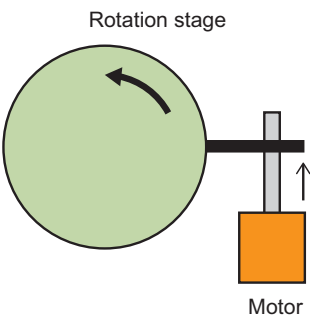
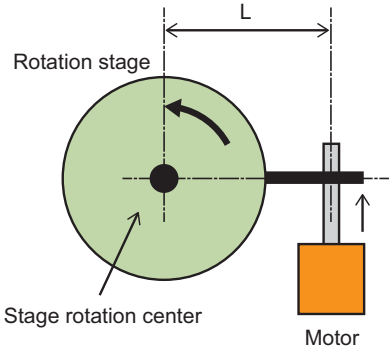
Setting item	Setting value [Factory default]	Description
X-axis mobility range	99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Set the upper and lower limit values for the X axis movement range of the XY stage. Units of the coordinate system set in calibration is used.
Y-axis mobility range	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Set the upper and lower limit values for the Y axis movement range of the XY stage. Units of the coordinate system set in calibration is used.

Setting the Data for Each Stage (XY θ Stage and θ XY Stage)

- 1 If XY θ stage or θ XY stage is selected, the "XY θ stage setting" area is displayed.

- 2 Click [...] in "X-axis mobility range" in the "XY θ stage setting" area to set the upper and lower limit values.
- 3 Likewise click [...] in [Y-axis mobility range] to set the upper and lower limit values.
- 4 Likewise click [...] in [θ -axis mobility range] to set the upper and lower limit values.
- 5 Select the θ axis drive system from the [θ -axis type].
- 6 If linear drive is selected in the θ axis type, [Distance from rotation center to θ -axis axis] can be set. Click [...] and set a numeric value.
- 7 If the camera is moved, select the axis to which the camera is attached from [Camera move axis].

Setting item	Setting value [Factory default]	Description
X-axis mobility range	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Set the upper and lower limit values for the X axis movement range of the XY θ stage. Units of the coordinate system set in calibration is used.
Y-axis mobility range	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Set the upper and lower limit values for the Y axis movement range of the XY θ stage. Units of the coordinate system set in calibration is used.
θ -axis mobility range	-180.0000 to 180.0000 [-180.0000] to [180.0000]	Set the upper and lower limit values for the θ axis angle movement range of the XY θ stage. The unit is degree.

Setting item	Setting value [Factory default]	Description
θ axis type	<ul style="list-style-type: none"> • [Direct drive] • Linear drive 	<p>Select the θ axis drive type.</p> <p>Direct drive: A drive system which matches the θ axis rotation with the motor's axis of rotation.</p>  <p>Linear drive: A system which controls the θ axis rotation by linear movement.</p> 
Distance from rotation center to θ-axis	0.0000 to 99999.9999 [0.0000]	<p>For the linear drive system, set the distance (L) from the stage rotation center to the linear axis.</p> 
Camera move axis		
X-axis	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Enable this setting if the camera moves instead of the stage axis.
Y-axis	<ul style="list-style-type: none"> • Checked • [Unchecked] 	If this is disabled, calculation for movement amount and so on is performed on the premises that the stage moves.

Setting the Data for Each Stage (UVW Stage and UVWR Stage)

- 1 If UVW stage or UVWR stage is selected, the "UVW or UVWR stage specific settings" area is displayed.

UVWR stage setting

Fulcrum type: Linear Rotation

U-axis: U-axis mobility range:

V-axis: V-axis mobility range:

W-axis: W-axis mobility range:

R-axis: R-axis mobility range:

Axis parameter setting: Setting by coordinate Setting by angle and pos.

Setting by coordinate

UX: UY:

VX: VY:

WX: WY:

RX: RY:

Rot. center X: Rot. center Y:

Setting by angle and pos.

R1: θ1:

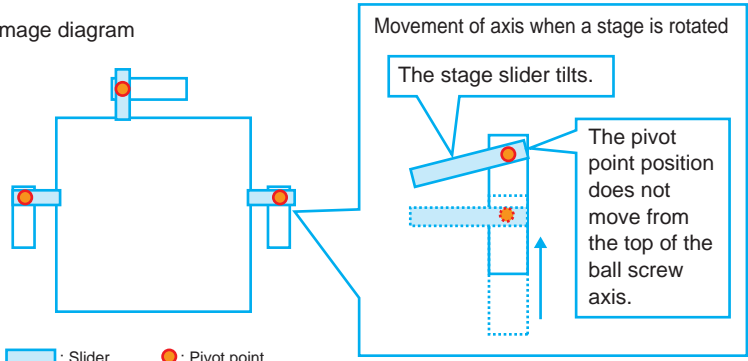
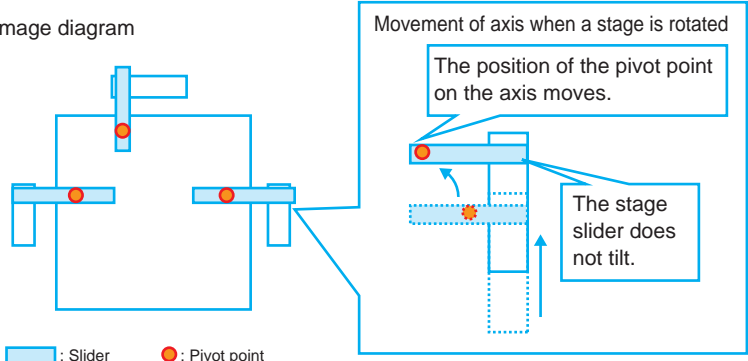
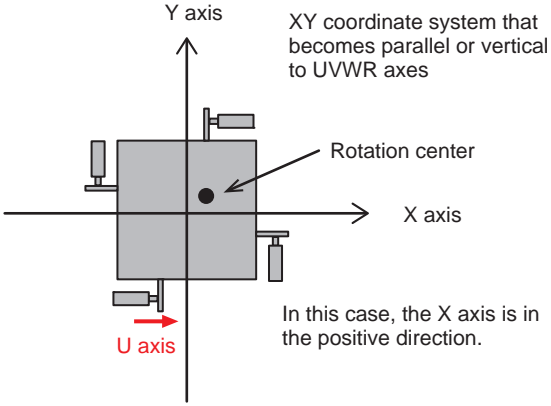
R2: θ2:

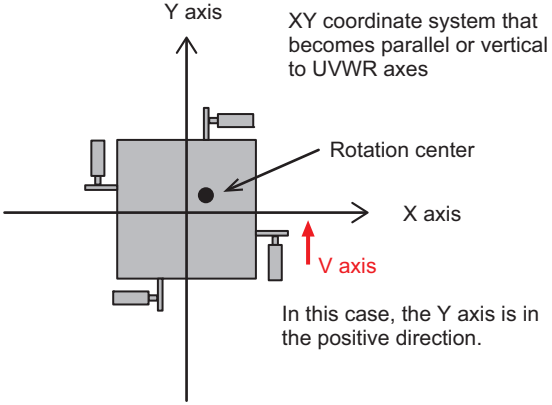
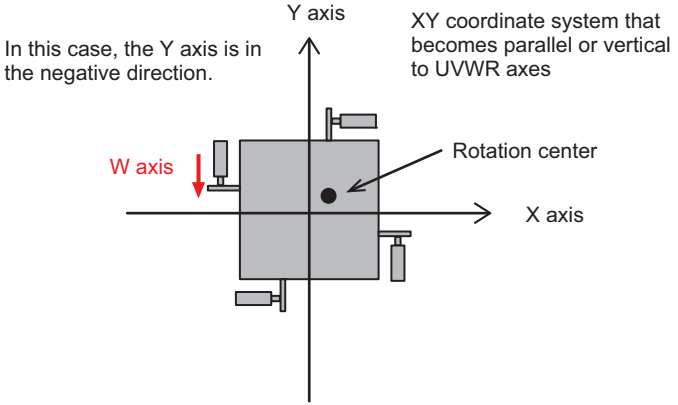
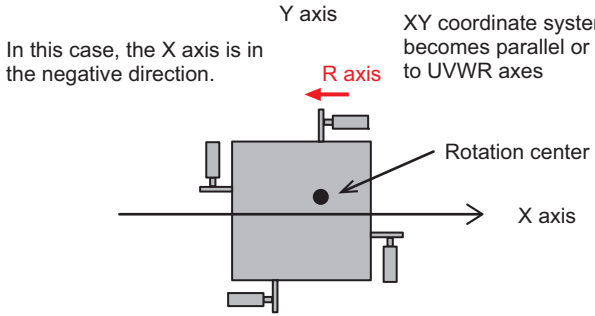
R3: θ3:

R4: θ4:

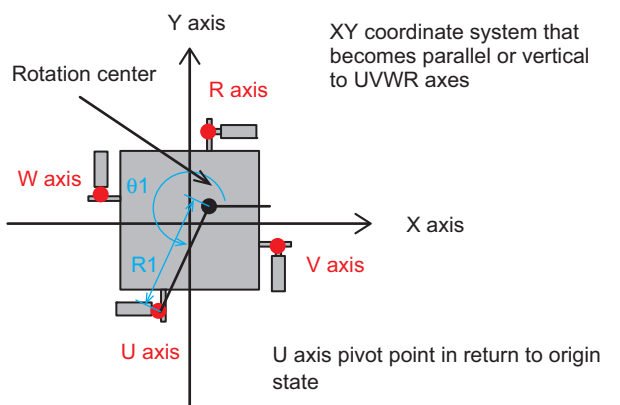
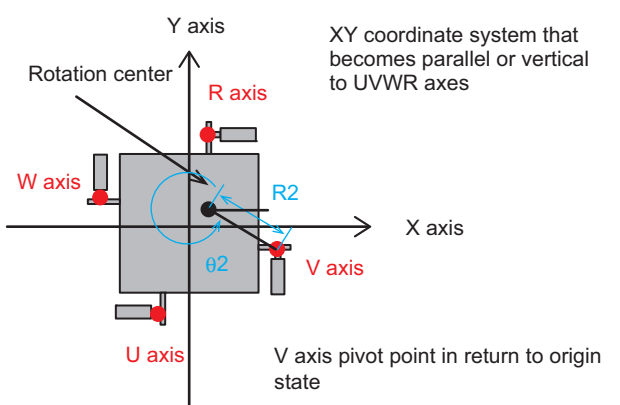
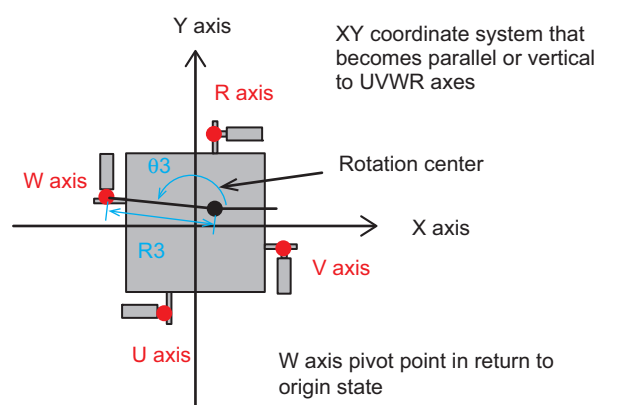
- 2 Select the slider type from the [Fulcrum type].
- 3 Click [▼] in [U-axis], and set the axis direction of the U axis to either forward or backward with respect to the X axis or Y axis direction in the XY coordinate system that is parallel or perpendicular to each UVWR axis.
- 4 Click [...] in [U-axis mobility range] to set the upper and lower limit values.
- 5 Likewise, click [▼] in [V-axis], and set the axis direction of the V axis to either forward or backward with respect to the X axis or Y axis direction in the XY coordinate system that is parallel or perpendicular to each UVWR axis.
- 6 Click [...] in [V-axis mobility range] to set the upper and lower limit values.
- 7 Likewise, click [▼] in [W-axis], and set the axis direction of the W axis to either forward or backward with respect to the X axis or Y axis direction in the XY coordinate system that is parallel or perpendicular to each UVWR axis.
- 8 Click [...] in [W-axis mobility range] to set the upper and lower limit values.
- 9 Likewise, click [▼] in [R-axis], and set the axis direction of the R axis to either forward or backward with respect to the X axis or Y axis direction in the XY coordinate system that is parallel or perpendicular to each UVWR axis.
- 10 Click [...] in [R-axis mobility range] to set the upper and lower limit values.
- 11 From the [Axis parameter setting], set the pivot point parameter of each UVWR axis either by coordinate setting or direct setting.
- 12 The "Setting by coordinate" area is enabled if "Setting by coordinate" is selected in [Axis parameter setting].
- 13 Click [...] in [UX] in the "Setting by coordinate" area to set a value.
- 14 Likewise, click [...] in [UY] in the "Setting by coordinate" area to set a value for the U axis pivot point's Y coordinate in the return to origin status.
- 15 Likewise, click [...] in [VY] in the "Setting by coordinate" area to set a value for the V axis pivot point's X coordinate in the return to origin status.

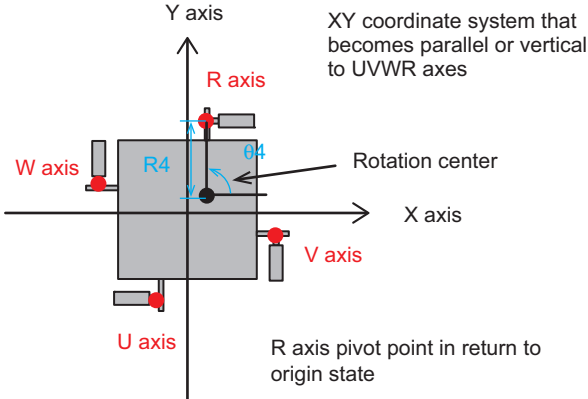
- 16** Likewise, click [...] in [VY] in the "Setting by coordinate" area to set a value for the V axis pivot point's Y coordinate in the return to origin status.
- 17** Likewise, click [...] in [WY] in the "Setting by coordinate" area to set a value for the W axis pivot point's X coordinate in the return to origin status.
- 18** Likewise, click [...] in [WY] in the "Setting by coordinate" area to set a value for the W axis pivot point's Y coordinate in the return to origin status.
- 19** Likewise, click [...] in [RX] in the "Setting by coordinate" area to set a value for the R axis pivot point's X coordinate in the return to origin status.
- 20** Likewise, click [...] in [RY] in the "Setting by coordinate" area to set a value for the R axis pivot point's Y coordinate in the return to origin status.
- 21** Likewise, click [...] in [Rot. center X] in the "Setting by coordinate" area to set a value for the rotation center's X coordinate in the return to origin status.
- 22** Likewise, click [...] in [Rot. center Y] in the "Setting by coordinate" area to set a value for the rotation center's Y coordinate in the return to origin status.
- 23** The "Setting by angle and pos." area is enabled if "Setting by angle and pos." is selected in [Axis parameter setting].
- 24** Click [...] in [R1] in the "Setting by angle and pos." area to set the distance between the U axis pivot point and rotation center in the return to origin status.
- 25** Likewise, click [...] in [R2] in the "Setting by angle and pos." area to set the distance between the V axis pivot point and rotation center in the return to origin status.
- 26** Likewise, click [...] in [R3] in the "Setting by angle and pos." area to set the distance between the W axis pivot point and rotation center in the return to origin status.
- 27** Likewise, click [...] in [R4] in the "Setting by angle and pos." area to set the distance between the R axis pivot point and rotation center in the return to origin status.
- 28** Likewise, click [...] in [$\theta 1$] in the "Setting by angle and pos." area to set a value.
- 29** Likewise, click [...] in [$\theta 2$] in the "Setting by angle and pos." area to set a value.
- 30** Likewise, click [...] in [$\theta 3$] in the "Setting by angle and pos." area to set a value.
- 31** Likewise, click [...] in [$\theta 4$] in the "Setting by angle and pos." area to set a value.

Setting item	Setting value [Factory default]	Description
Fulcrum type	<ul style="list-style-type: none"> • Linear • [Rotation] 	<p>Select the slider operation type when the stage is rotated.</p> <p>Linear</p> <p>Image diagram</p>  <p>Movement of axis when a stage is rotated</p> <p>The stage slider tilts.</p> <p>The pivot point position does not move from the top of the ball screw axis.</p> <p>Legend: ▬ : Slider ● : Pivot point</p> <p>Rotation</p> <p>Image diagram</p>  <p>Movement of axis when a stage is rotated</p> <p>The position of the pivot point on the axis moves.</p> <p>The stage slider does not tilt.</p> <p>Legend: ▬ : Slider ● : Pivot point</p>
U-axis	<ul style="list-style-type: none"> • [X-axis positive] • X-axis negative • Y-axis positive • Y-axis negative 	<p>For the axis direction of the U axis, set the rotation center to the point of origin then set it to either forward or backward with respect to the X axis or Y axis direction in the XY coordinate system that is parallel or perpendicular to each UVWR axis.</p>  <p>Y axis</p> <p>XY coordinate system that becomes parallel or vertical to UVWR axes</p> <p>Rotation center</p> <p>X axis</p> <p>In this case, the X axis is in the positive direction.</p>
U-axis mobility range	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	<p>Set the upper and lower limit values for the U axis movement range. Units of the coordinate system set in calibration is used.</p>

Setting item	Setting value [Factory default]	Description
V-axis	<ul style="list-style-type: none"> • [X-axis positive] • X-axis negative • Y-axis positive • Y-axis negative 	<p>Set the axis direction of the V axis to either forward or backward with respect to the X axis or Y axis direction in the XY coordinate system that is parallel or perpendicular to each UVWR axis.</p> 
V-axis mobility range	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	<p>Set the upper and lower limit values for the V axis movement range. Units of the coordinate system set in calibration is used.</p>
W-axis	<ul style="list-style-type: none"> • [X-axis positive] • X-axis negative • Y-axis positive • Y-axis negative 	<p>Set the axis direction of the W axis to either forward or backward with respect to the X axis or Y axis direction in the XY coordinate system that is parallel or perpendicular to each UVWR axis.</p> 
W-axis mobility range	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	<p>Set the upper and lower limit values for the W axis movement range. Units of the coordinate system set in calibration is used.</p>
R-axis	<ul style="list-style-type: none"> • [X-axis positive] • X-axis negative • Y-axis positive • Y-axis negative 	<p>Set the axis direction of the R axis to either forward or backward with respect to the X axis or Y axis direction in the XY coordinate system that is parallel or perpendicular to each UVWR axis.</p> 

Setting item	Setting value [Factory default]	Description
R-axis mobility range	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Set the upper and lower limit values for the R axis movement range. Units of the coordinate system set in calibration is used.
Axis parameter setting	<ul style="list-style-type: none"> • [Setting by coordinate] • Setting by angle and pos. 	Select the pivot point parameter of each UVWR axis either by coordinate setting or direct setting.
UX	-99999.999999 to 99999.999999	<p>Set the X coordinate value of the U axis pivot point in the return to origin status.</p> <p>XY coordinate system that becomes parallel or vertical to UVWR axes</p> <p>Rotation center (Rotation center X, rotation center Y)</p> <p>UVWR axis pivot points in return to origin state</p>
UY	-99999.999999 to 99999.999999 [0.000000]	Set the Y coordinate value of the U axis pivot point in the return to origin status.
VX	-99999.999999 to 99999.999999 [0.000000]	Set the X coordinate value of the V axis pivot point in the return to origin status.
VY	-99999.999999 to 99999.999999 [0.000000]	Set the Y coordinate value of the V axis pivot point in the return to origin status.
WX	-99999.999999 to 99999.999999 [0.000000]	Set the X coordinate value of the W axis pivot point in the return to origin status.
WY	-99999.999999 to 99999.999999 [0.000000]	Set the Y coordinate value of the W axis pivot point in the return to origin status.
RX	-99999.999999 to 99999.999999 [0.000000]	Set the X coordinate value of the R axis pivot point in the return to origin status.
RY	-99999.999999 to 99999.999999 [0.000000]	Set the Y coordinate value of the R axis pivot point in the return to origin status.
Rot. center X	-99999.999999 to 99999.999999 [0.000000]	Set the X coordinate value of the rotation center in the return to origin status.
Rot. center Y	-99999.999999 to 99999.999999 [0.000000]	Set the Y coordinate value of the rotation center in the return to origin status.

Setting item	Setting value [Factory default]	Description
R1	0.000000 to 99999.999999 [0.000000]	<p>Set the length of line segment connecting the stage rotation center and U axis pivot point in the return to origin (each axis' movement amount is 0) status.</p> 
theta1	-360.000000 to 360.000000 [0.000000]	<p>Set the angle from the X axis of the line segment connecting the stage rotation center and U axis pivot point in the return to origin (each axis' movement amount is 0) status. As for the angle, the X axis is set to 0° and the direction from X axis forward to Y axis forward is set to +.</p>
R2	0.000000 to 99999.999999 [0.000000]	<p>Set the length of line segment connecting the stage rotation center and V axis pivot point in the return to origin (each axis' movement amount is 0) status.</p> 
theta2	-360.000000 to 360.000000 [0.000000]	<p>Set the angle from the X axis of the line segment connecting the stage rotation center and V axis pivot point in the return to origin (each axis' movement amount is 0) status. As for the angle, the X axis is set to 0° and the direction from X axis forward to Y axis forward is set to +.</p>
R3	0.000000 to 99999.999999 [0.000000]	<p>Set the length of line segment connecting the stage rotation center and W axis pivot point in the return to origin (each axis' movement amount is 0) status.</p> 

Setting item	Setting value [Factory default]	Description
θ3	-360.000000 to 360.000000 [0.000000]	Set the angle from the X axis of the line segment connecting the stage rotation center and W axis pivot point in the return to origin (each axis' movement amount is 0) status. As for the angle, the X axis is set to 0° and the direction from X axis forward to Y axis forward is set to +.
R4	0.000000 to 99999.999999 [0.000000]	Set the length of line segment connecting the stage rotation center and R axis pivot point in the return to origin (each axis' movement amount is 0) status. 
θ4	-360.000000 to 360.000000 [0.000000]	Set the angle from the X axis of the line segment connecting the stage rotation center and R axis pivot point in the return to origin (each axis' movement amount is 0) status. As for the angle, the X axis is set to 0° and the direction from X axis forward to Y axis forward is set to +.

Measurement Results for Which Output Is Possible (Stage Data)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Stage Data)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (Unmeasured: Specifically right after startup, scene switch, or after leaving the settings screen) 1: Judgement result OK (No errors)
120	Stage type	Set/Get	0: XY stage 1: XYθ stage 2: θXY stage 3: UVW stage 4: UVWR stage
121	Rotation polarity	Set/Get	-1: Negative (from the Y axis to X axis) 1: Positive (from the X axis to Y axis)
122	Distance from the rotation center to the linear axis	Set/Get	0.000000 to 99999.999999

No.	Data name	Set/Get	Data range
123	UVWR axis parameter setting method	Set/Get	0: Coordinate setting 1: Direct setting
124	Stage rotation center X	Set/Get	-99999.999999 to 99999.999999
125	Stage rotation center Y	Set/Get	-99999.999999 to 99999.999999
126	UVW/UVWR stage slider type	Set/Get	0: Rotation 1: Linear
127	Pivot point type	Set/Get	0: Direct drive 1: Linear drive
128	Camera movement axis X	Set/Get	0: Disabled 1: Enabled
129	Camera movement axis Y	Set/Get	0: Disabled 1: Enabled
130	U axis distance	Set/Get	0.000000 to 99999.999999
131	U axis angle	Set/Get	-360.000000 to 360.000000
132	V axis distance	Set/Get	0.000000 to 99999.999999
133	V axis angle	Set/Get	-360.000000 to 360.000000
134	W axis distance	Set/Get	0.000000 to 99999.999999
135	W axis angle	Set/Get	-360.000000 to 360.000000
136	R axis distance	Set/Get	0.000000 to 99999.999999
137	R axis angle	Set/Get	-360.000000 to 360.000000
150	U axis pivot point coordinate X	Set/Get	-99999.999999 to 99999.999999
151	U axis pivot point coordinate Y	Set/Get	-99999.999999 to 99999.999999
152	V axis pivot point coordinate X	Set/Get	-99999.999999 to 99999.999999
153	V axis pivot point coordinate Y	Set/Get	-99999.999999 to 99999.999999
154	W axis pivot point coordinate X	Set/Get	-99999.999999 to 99999.999999
155	W axis pivot point coordinate Y	Set/Get	-99999.999999 to 99999.999999
156	R axis pivot point coordinate X	Set/Get	-99999.999999 to 99999.999999
157	R axis pivot point coordinate Y	Set/Get	-99999.999999 to 99999.999999
170	U axis polarity	Set/Get	0: X axis forward 1: X axis backward 2: Y axis forward 3: Y axis backward
171	V axis polarity	Set/Get	0: X axis forward 1: X axis backward 2: Y axis forward 3: Y axis backward
172	W axis polarity	Set/Get	0: X axis forward 1: X axis backward 2: Y axis forward 3: Y axis backward
173	R axis polarity	Set/Get	0: X axis forward 1: X axis backward 2: Y axis forward 3: Y axis backward
180	X axis movement lower limit	Set/Get	-99999.999999 to 99999.999999
181	X axis movement upper limit	Set/Get	-99999.999999 to 99999.999999
182	Y axis movement lower limit	Set/Get	-99999.999999 to 99999.999999

No.	Data name	Set/Get	Data range
183	Y axis movement upper limit	Set/Get	-99999.9999 to 99999.9999
184	θ axis angle movement lower limit	Set/Get	-180.0000 to 180.0000
185	θ axis angle movement upper limit	Set/Get	-180.0000 to 180.0000
186	θ axis linear movement lower limit	Set/Get	-99999.9999 to 99999.9999
187	θ axis linear movement upper limit	Set/Get	-99999.9999 to 99999.9999
190	U axis movement lower limit	Set/Get	-99999.9999 to 99999.9999
191	U axis movement upper limit	Set/Get	-99999.9999 to 99999.9999
192	V axis movement lower limit	Set/Get	-99999.9999 to 99999.9999
193	V axis movement upper limit	Set/Get	-99999.9999 to 99999.9999
194	W axis movement lower limit	Set/Get	-99999.9999 to 99999.9999
195	W axis movement upper limit	Set/Get	-99999.9999 to 99999.9999
196	R axis movement lower limit	Set/Get	-99999.9999 to 99999.9999
197	R axis movement upper limit	Set/Get	-99999.9999 to 99999.9999

Robot Data

Sets and stores data related to robots.

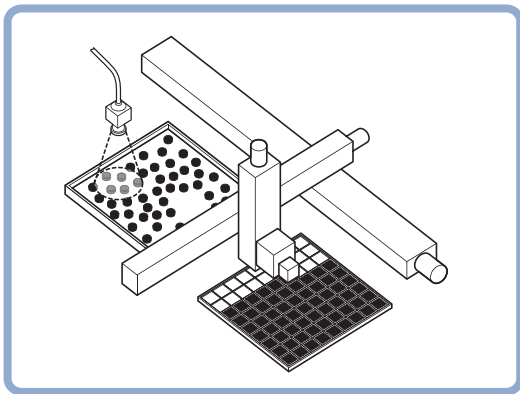
This processing item is required when using the following processing items in an equipment environment containing robots.

- Vision master calibration
- PLC master calibration
- Reference calibration data
- Convert position data
- Movement single position
- Movement multi points

Used in the Following Case

- **When setting parameters for robots to be used and the rotation polarity**

Example: palletizing of electronic parts

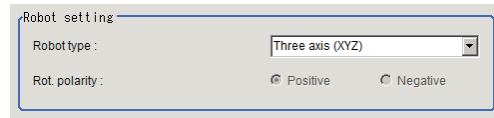


Data Setting (Robot Data)

Set data based on the specification of the robot.

- 1** In the Item Tab area, click [Data setting].
- 2** Select the type of the robot in the "Robot setting" area.

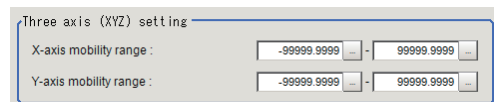
Selecting "four axis (XYZR) robot" will enable you to select the rotation polarity.



Setting item	Setting value [Factory default]	Description
Robot type	<ul style="list-style-type: none"> • [Three axis (XYZ)] • Four axis (XYZR) 	Select the type of the robot to be used.
Rot. polarity	<ul style="list-style-type: none"> • [Positive] • Negative 	<p>Select the rotation direction defined in the equipment is positive or negative compared to the rotation direction in the robot coordinate system.</p> <p>Positive: From the X axis to Y axis Negative: From the Y axis to X axis</p> <p>When positive rotation direction of the device is</p> <p>A: positive polarity B: negative polarity</p> <p>Stage coordinate system</p>

3-axis (XYZ) robot

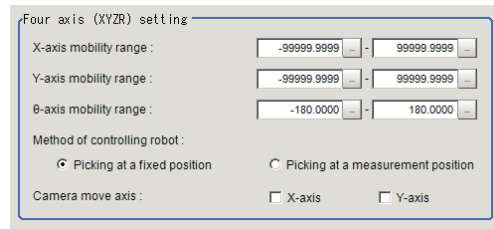
- 1** Selecting "Three axis (XYZ)" will display the "Three axis (XYZ) setting" area.
- 2** Click [...] in "X-axis mobility range" in the "Three axis (XYZ) setting" area to set the upper and lower limit values.
- 3** Likewise click [...] in "Y-axis mobility range" to set the upper and lower limit values.



Setting item	Setting value [Factory default]	Description
X-axis mobility range	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Set the upper and lower limit values for the X axis movement range. Units of the coordinate system set in calibration is used.
Y-axis mobility range	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Set the upper and lower limit values for the Y axis movement range. Units of the coordinate system set in calibration is used.

4-axis (XYZR) robot

1 Selecting "Four axis (XYZR)" will display the "Four axis (XYZR) setting" area.



2 Click [...] in "X-axis mobility range" in the "Four axis (XYZR) setting" area to set the upper and lower limit values.

3 Likewise click [...] in "Y-axis mobility range" to set the upper and lower limit values.

4 Likewise click [...] in "θ-axis mobility range" to set the upper and lower limit values.

5 Select the control method for the robot from the "Method of controlling robot".

6 If the camera is moved, select the axis to which the camera is attached from "Camera move axis".

Setting item	Setting value [Factory default]	Description
X-axis mobility range	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Set the upper and lower limit values for the X axis movement range. Units of the coordinate system set in calibration is used.
Y-axis mobility range	-99999.9999 to 99999.9999 [-99999.9999] to [99999.9999]	Set the upper and lower limit values for the Y axis movement range. Units of the coordinate system set in calibration is used.
θ-axis mobility range	-180.0000 to 180.0000 [-180.0000] to [180.0000]	Set the upper and lower limit values for the θ axis angle range. The unit is degree.
Method of controlling robot	<ul style="list-style-type: none"> • Picking at a fixed position • Picking at a measurement position 	<p>Select the robot control method. The robot control settings change depending on at which phase position alignment is performed from "the workpiece grasping phase" to "movement phase".</p> <p>(1) Go to a fixed position to pick up an object If the robot is controlled using the Sensor Controller measurement result, so that the robot can go to the same position every time during workpiece to pick up an object and place it on a specific position after grasping the object, select this. This is some kind of palletizing application. Specifically speaking, in this setting, the same calculation as the XYθ stage is used.</p> <p>(2) Go to the measurement position of workpiece to pick up an object If the robot is controlled so that the robot goes to grasp the workpiece and then places it on a specific position after grasping it using the measurement result of this vision sensor every time, select this. This is some kind of depalletizing application. Specifically speaking, in this setting, the same calculation as the θXY stage is used.</p>
Camera move axis		

Setting item		Setting value [Factory default]	Description
	X-axis	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Enable this setting if the camera moves instead of the robot axis.
	Y-axis	<ul style="list-style-type: none"> • Checked • [Unchecked] 	If this is disabled, calculation for movement amount and so on is performed on the premises that the stage moves.

Measurement Results for Which Output Is Possible (Robot Data)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Robot Data)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
120	Robot type	Set/Get	0: 3-axis (XYZ) robot 1: 4-axis (XYZR) robot
121	Rotation polarity	Set/Get	-1: Negative (from the Y axis to X axis) 1: Positive (from the X axis to Y axis)
122	Robot control method	Set/Get	0: Go to a fixed position to pick up an object 1: Go to the measurement position of workpiece to pick up an object
123	Camera movement axis X	Set/Get	0: Do not use the camera movement axis X 1: Use the camera movement axis X
124	Camera movement axis Y	Set/Get	0: Do not use the camera movement axis Y 1: Use the camera movement axis Y
130	X axis movement lower limit	Set/Get	-99999.9999 to 99999.9999
131	X axis movement upper limit	Set/Get	-99999.9999 to 99999.9999
132	Y axis movement lower limit	Set/Get	-99999.9999 to 99999.9999
133	Y axis movement upper limit	Set/Get	-99999.9999 to 99999.9999
134	θ axis angle lower limit	Set/Get	-180.0000 to 180.0000
135	θ axis angle upper limit	Set/Get	-180.0000 to 180.0000

Vision Master Calibration

This processing item is specifically provided for calibration between the camera coordination system and the control equipment coordinate system.

This processing item automatically calculates the entire axis movement amount of the control equipment necessary for calibration.

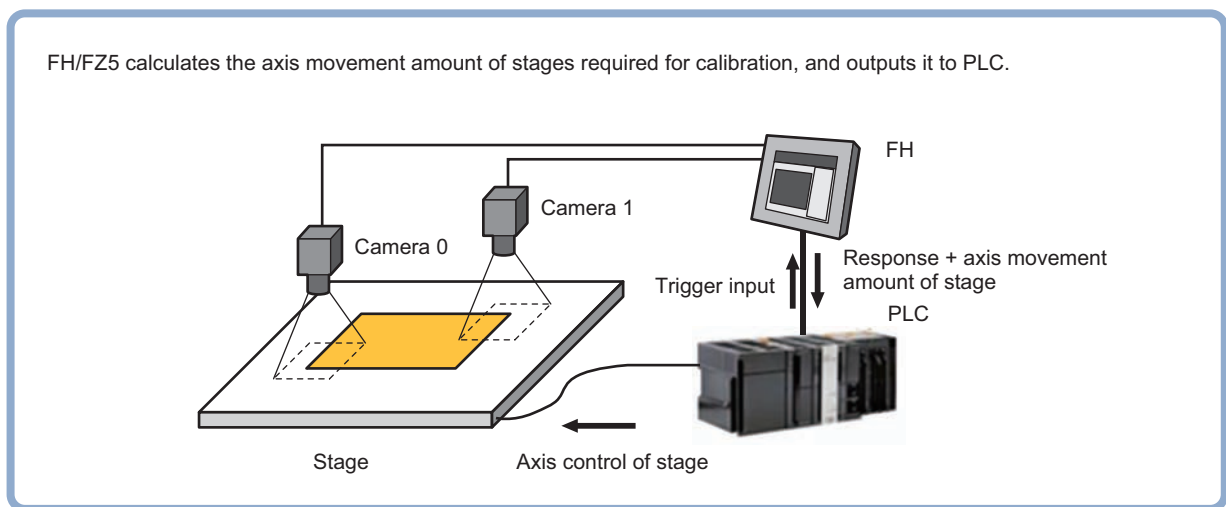
For that reason, it is possible to perform accurate calibration more easily than previously.

Important

- The calibration data created with this processing item is referred to using [Reference Calib Data]. Unlike other calibration-related processing items, note that this processing item cannot use the calibration data on its own.

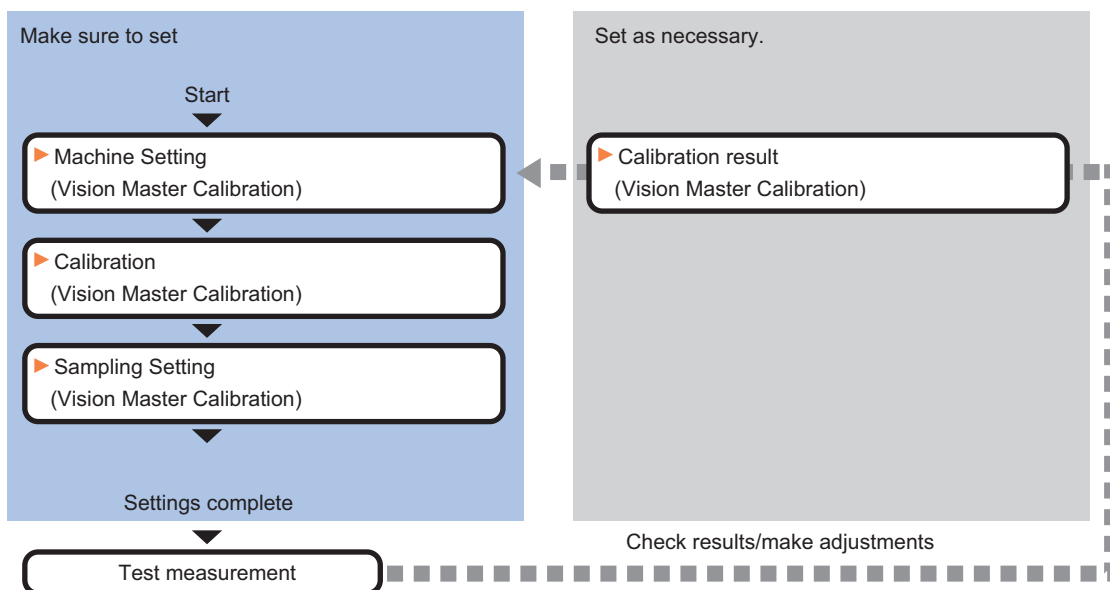
Used in the Following Case

- When you want to position the FPD panel



Settings Flow (Vision Master Calibration)

Set the image master calibration with the following steps.



List of Vision Master Calibration Items

Item name	Description
Machine setting	Select a processing item (stage data or robot data) under which external device information needed for calculation of axis movement amount is held. Reference: ▶ Machine Setting (Vision Master Calibration) (p.648)
Calibration	This item sets data related to calibration. Sets the number of calibration data to be created and the measurement processing items to be used for sampling in the arithmetic expression. Also sets the output method for the calculated axis movement amount. Reference: ▶ Calibration (Vision Master Calibration) (p.649)
Sampling setting	This item sets data related to sampling. Also makes the sampling settings for the initial calibration and this calibration. Reference: ▶ Sampling Setting (Vision Master Calibration) (p.651)
Calibration result	This item confirms the calibration data you created. The calibration data can be adjusted directly using the Edit function. It is also possible to confirm the sampling data used for the calculation. Reference: ▶ Calibration Result (Vision Master Calibration) (p.657)

Machine Setting (Vision Master Calibration)

Select a processing unit (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.

Important

- [Vision Master Calibration] refers to [Stage Data] or [Robot Data]. Be sure to register [Stage Data] or [Robot Data] with a given scene.

1 In the Item Tab area, click [Machine setting].

2 Select the processing unit that retains information on external device.

Information of the selected processing unit is displayed in the reference data display area.

Setting item	Setting value [Factory default]	Description
Scene No.	[Present scene] Scenes 0 to 127	Select a scene number (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.
Unit No.	-	From among the referenced scene numbers, select a processing item (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.

Note

- If the number of scenes is increased using the scene group conversion tool, the maximum value that can be selected in "Scene No." changes.

Calibration (Vision Master Calibration)

This item sets data related to calibration. Sets the number of calibration data to be created and the measurement processing items to be used for sampling in the arithmetic expression. Also sets the output method for the calculated axis movement amount.

- 1 In the Item Tab area, click [Calibration].
- 2 Check the calibration data items that you want to set.

Calibration data is created for the checked numbers.

No.	Input image unit	Position X	Position Y	Judge expression	Judge lower	Judge upper
<input checked="" type="checkbox"/> 0	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 1	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 2	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 3	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 4	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 5	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 6	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 7	<Nothing>			TJG	1.0000	1.0000

No. Input image unit: 0 <Nothing> Position X: Position Y: Judge expression: Judge condition: 1.0000

- 3 Select the line of the calibration data that you want to set.

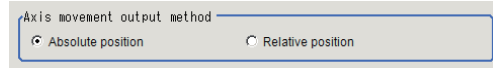
No.	Input image unit	Position X	Position Y	Judge expression	Judge lower	Judge upper
<input checked="" type="checkbox"/> 0	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 1	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 2	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 3	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 4	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 5	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 6	<Nothing>			TJG	1.0000	1.0000
<input type="checkbox"/> 7	<Nothing>			TJG	1.0000	1.0000

No. Input image unit: 0 <Nothing> Position X: Position Y: Judge expression: Judge condition: 1.0000

- 4 Set each item in the "Calibration target" area.

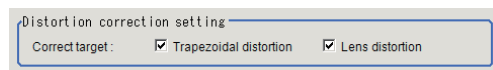
Setting item	Setting value [Factory default]	Description
Input image unit	[<Nothing>]	Select an image input unit to be used for sampling measurement.
Position X	-	Set the arithmetic expression that obtains camera coordinate X used for sampling.
Position Y	-	Set the arithmetic expression that obtains camera coordinate Y used for sampling.
Judge expression	-	Set the arithmetic expression to determine whether sampling was successful or not. If calibration fails during the initial value TJG, set the unit judgement JG of the processing unit from which positions X and Y are referred.
Judge condition	-999999999.9999 to 999999999.9999 [1.0000] to [1.0000]	Set the upper and lower limit values to determine whether sampling was successful or not. If TJG or JG is set to the judgement expression, use the initial values.

5 Select the output method for movement amount in the "Axis movement output method" area.



Setting item	Setting value [Factory default]	Description
Axis movement output method	<ul style="list-style-type: none"> • [Absolute position] • Relative position 	<p>Select the calculation method for the axis movement amount output to the external device next time.</p> <p>The movement amount output method affects the "Next movement amount" that can be obtained by calculation.</p> <p>The setting must be changed according to the specifications of the control equipment used.</p> <ul style="list-style-type: none"> • Absolute position It always outputs the axis movement amount from the origin return position (0 axis movement amount) to the next sampling position. • Relative position Outputs the axis movement amount from the current sampling position to the next sampling position.

6 Select whether or not to output distortion compensation parameters in the "Distortion correction setting" area.



Setting item	Setting value [Factory default]	Description
Trapezoidal distortion	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Select whether or not to output trapezoidal compensation parameters set for each data.
Lens distortion	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Select whether or not to output lens distortion compensation parameters set for each data.

Important

Limit on the number of calibration data when distortion compensation is turned on

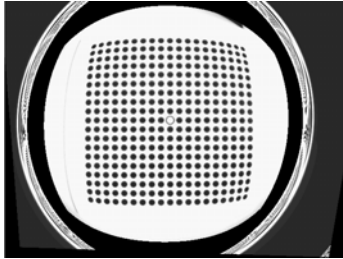
The number of distortion compensation calibration data (either the trapezoidal or lens compensation is checked) that can be used in the same scene group is limited by the controller or camera in use. Do not exceed these limits. Redoing calibration without checking both will delete the created distortion compensation data.

Type of controller	0.3 megapixel camera	Intelligent compact camera	2 megapixel camera	5 megapixel camera	0.3 megapixel camera (FH)	2 megapixel camera (FH)	4 megapixel camera (FH)
FZ5-L35x Or FZ5-6xx	30	28	7	2	30	6	3
FZ5-11xx	150	140	40	15	150	35	20
FH-1xxx FH-3xxx	150	140	40	15	150	35	20

Distortion compensation function

Because compensation is performed using the same algorithm with the high-precision calibration processing item in this processing item, sampling points are biased toward the center of the screen when the effective range of the field of view is extremely narrow and image compensation cannot be performed normally.

Widen the effective range of the field of view so that sampling points are located in the entire screen and perform calibration again.



If the effective range of the field of view is extremely narrow, a circular virtual image shown left may appear.

Sampling Setting (Vision Master Calibration)

This item sets data related to sampling.

Also makes the sampling settings for the initial calibration and this calibration.

- 1 In the Item Tab area, click [Sampling Setting].
- 2 In the "First calibration setting" area, specify each item.

First calibration setting

X-axis movement:

Y-axis movement:

Rotation start angle:

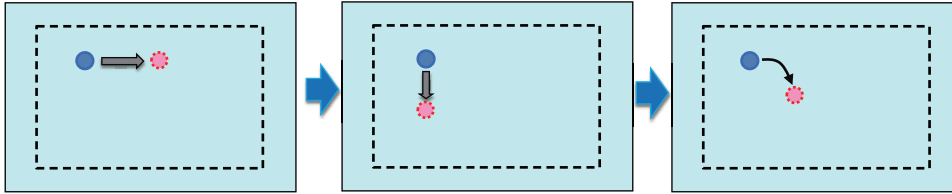
Setting item	Setting value [Factory default]	Description
X-axis movement	0 to 99999.9999 [10.0000]	Set the X axis movement amount in the initial calibration.
Y-axis movement	0 to 99999.9999 [10.0000]	Sets the Y axis movement amount in the initial calibration.
Rotation start angle	-180.0000 to 180.0000 [10.0000]	Set the rotation movement start angle in the initial calibration.

Note

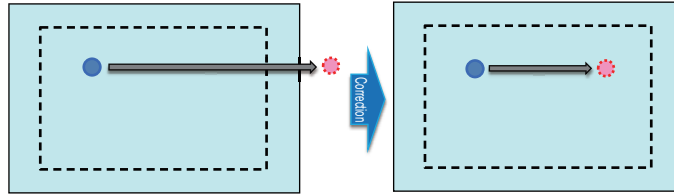
Rotation movement start angle

- If sampling fails in rotational sampling in the initial calibration, the movement angle is halved and rotational sampling is performed again.

Calculates calibration data used to perform high-precision calibration in the initial calibration.

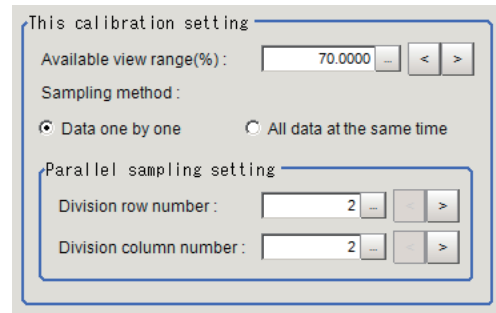


If the sample's amount of initial movement amount is too large and outside the range of the camera's field of view, the movement amount automatically corrects and the sample moves again.



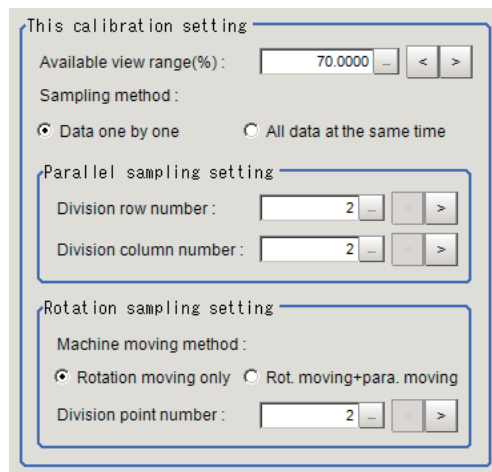
3 In this "This calibration setting" area, specify each item.

If the stage type of the reference data is the XYZ stage or the robot type is 3-axis robot



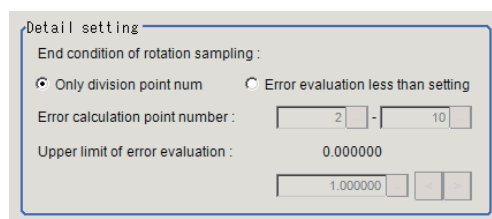
Setting item	Setting value [Factory default]	Description
Available view range(%)	1 to 100 [70.0000]	Set the effective range of the field of view for the image input unit.
Sampling method	<ul style="list-style-type: none"> [Data one by one] All data at the same time 	Select the sampling method for rotational movement in this calibration.
Parallel sampling setting	-	-
Division row number	2 to 10 [2]	Sets the number of lines divided during parallel movement sampling in this calibration.
Division column number	2 to 10 [2]	Set the number of columns divided during parallel movement sampling in this calibration.

If the stage type of the reference data is the XYθ stage, θXY stage, UVW stage or UVWR stage or the robot type is 4-axis robot



Setting item	Setting value [Factory default]	Description
Available view range(%)	1 to 100 [70.0000]	Set the effective range of the field of view for the image input unit.
Sampling method	<ul style="list-style-type: none"> • [Data one by one] • All data at the same time 	Select the sampling method for rotational movement in this calibration. When data are selected one by one, Measuring Processing Unit of data not targeted for sampling may be NG. In this case, normal calibration process becomes possible by setting the unit judgement JG of Measurement Processing Unit to the judgement expression on Calibration tab.
Parallel sampling setting	-	-
Division row number	2 to 10 [2]	Sets the number of lines divided during parallel movement sampling in this calibration.
Division column number	2 to 10 [2]	Set the number of columns divided during parallel movement sampling in this calibration. When data are selected one by one, Measuring Processing Unit of data not targeted for sampling may be NG.
Rotation sampling setting	-	-
Machine moving method	<ul style="list-style-type: none"> • [Rotation moving only] • Rot. moving+para. moving 	Set the external device movement method for rotational sampling in this calibration.
Division point number	2 to 100 [2]	Sets the number of division points for rotational sampling in this calibration.

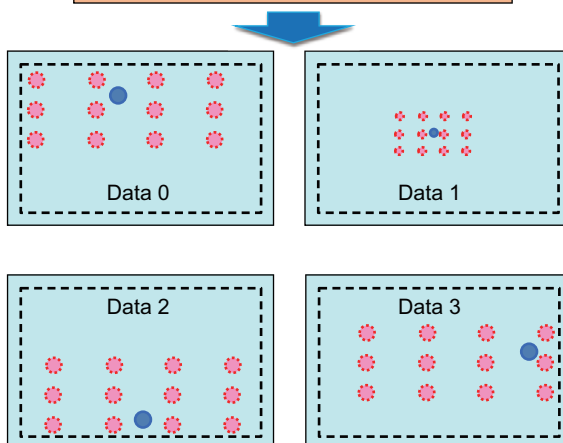
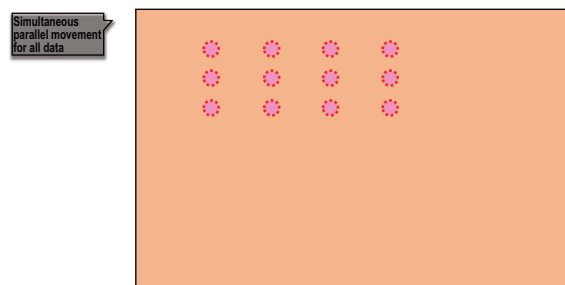
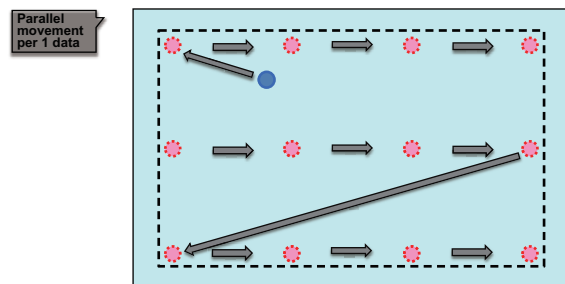
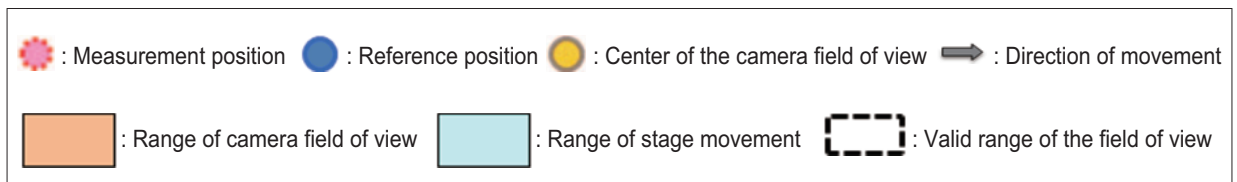
4 If necessary, set each item in the "Detail setting" area.



Setting item	Setting value [Factory default]	Description
End condition of rotation sampling	<ul style="list-style-type: none"> • [Only division point num] • Error evaluation less than setting 	Select the end condition for rotational movement in this calibration.
Error calculation point number	2 to 100 [2] to [10]	Set the range of error calculation points when "The error detection value is lower than the setting value" is selected.
Upper limit of error evaluation	0 to 99999.999999 [1.000000]	Specify the upper limit value for the error detection.

The movement amount necessary for sampling measurement

Movement amount necessary for sampling measurement is calculated using the number of divided lines (N) and the number divided lines (M).



Number of movement points = $N \times M$

Number of movement times = Number of data to be checked

It moves per data according to the resolution of the camera.

The movement positions of data to be checked are all the same.

The movement points are the maximum movement range within the effective range of the field of view of each camera in each data.

Number of movement points = $N \times M$

Number of movement times = 1

In the all data simultaneous movement, all data move once. As for the movement range, all movement points are within the effective range of the field of view of each camera.

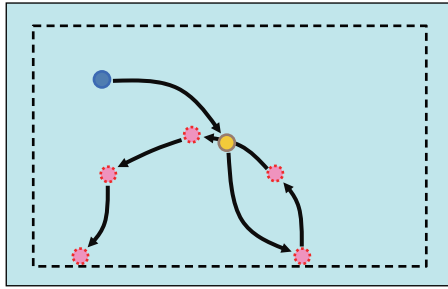
When simultaneous sampling for all data is set, sampling of all data is executed in one movement.

Movement range of sampling is automatically calculated to find a range that allows the largest movement within available view range of all data.

Movement order is determined based on the actual coordinate system.

The movement is different from the case when sampling is executed for each data one by one.

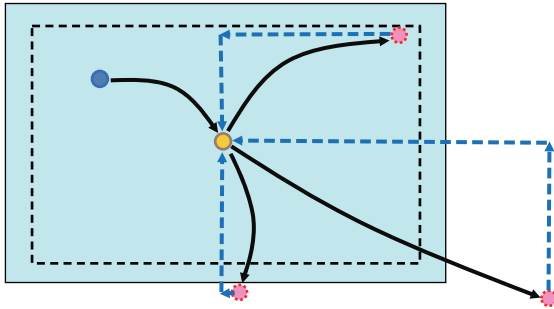
Rotational movement per 1 data rotation only



Number of movement points = Division points
 Number of movement times = Number of data to be checked

Because the precision in the center of the camera image is higher, rotational movement moves to the center of the field of view first.

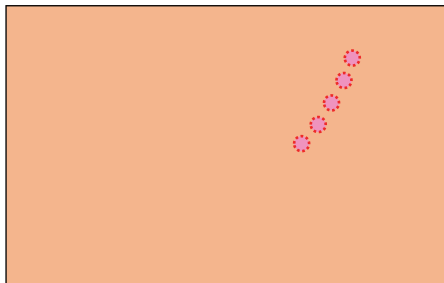
Rotational movement per 1 data rotation + parallel



Number of movement points = Division points
 Number of movement times = Number of data to be checked

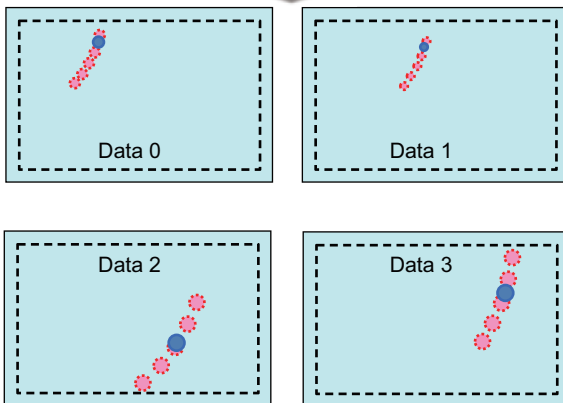
In "Rotational movement + Parallel movement," it moves back to the center of the field of view after the rotational movement.

Simultaneous parallel movement for all data. Rotation only is one method of rotational movement



Number of movement points = Division points
 Number of movement times = 1

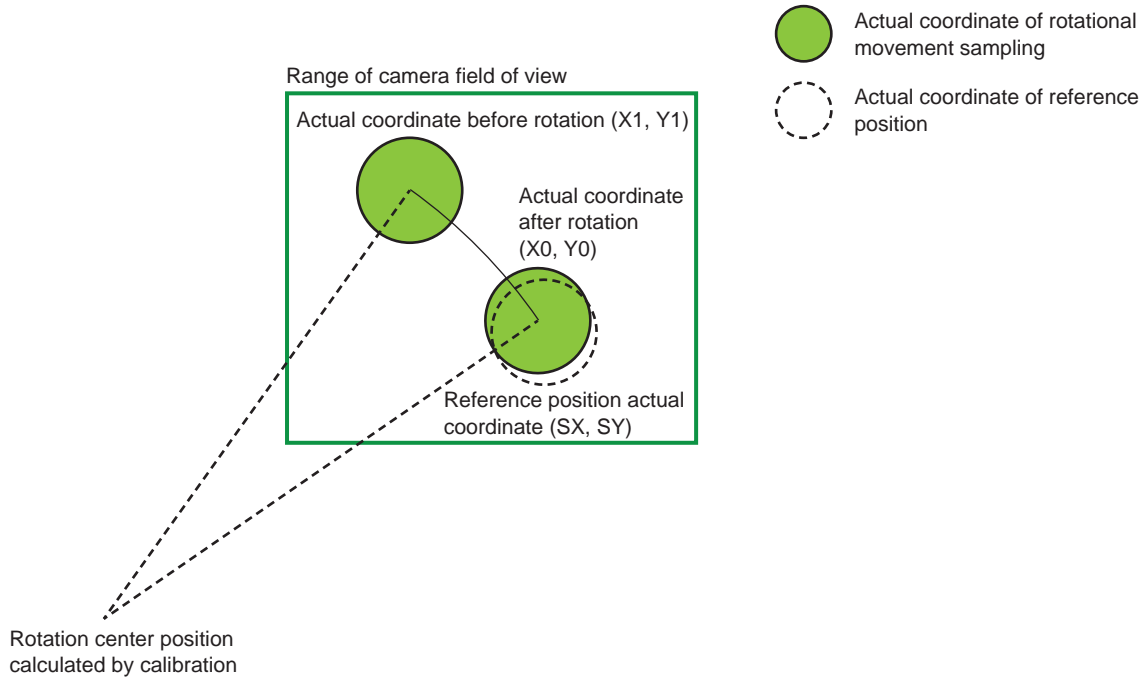
In the all data simultaneous movement, all data move once. As for the movement range, all movement points are within the effective range of the field of view of each camera.



Error detection values

Rotate the actual coordinate XY, which was acquired in the rotational movement sampling, for an amount of (rotational movement amount from the reference position) $\times (-1)$ to return to the reference position. The distance from the actual coordinate XY returned to the reference position and the actual coordination XY at the reference position is calculated for a number of rotation sampling points, and the average value is defined as an error detection value.

When there is a gap between "rotation center position calculated by calibration" and "rotation center position of actual external device", the error detection value increases.



5 In the "Calibration start axis position" area, specify the starting axis position of each axis with expressions.

The axis position setting menu changes depending on the settings of the processing unit selected in Unit No. in the "Machine setting data" area. If the workpiece used for sampling is not within the camera field of view in the return to origin position (all axes in 0,0 position), set the axis position after moving as the starting axis position.

Example: When XYθ stage is selected with the stage data

Calibration start axis position

X-axis :

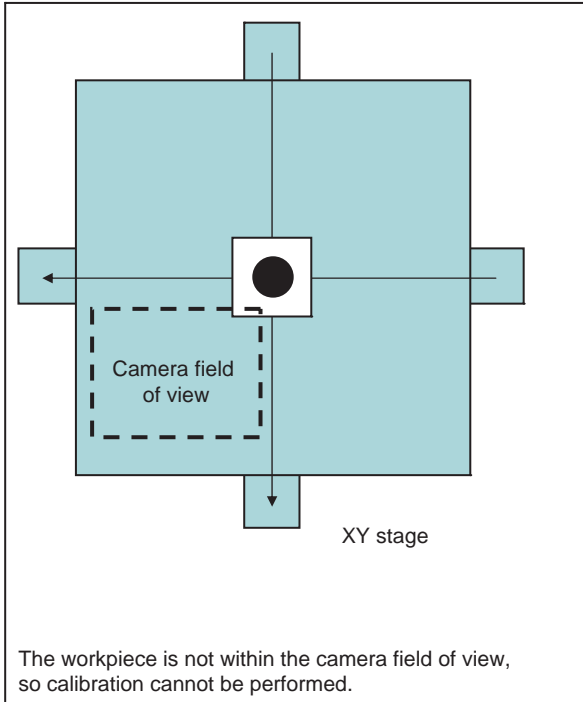
Y-axis :

θ-axis :

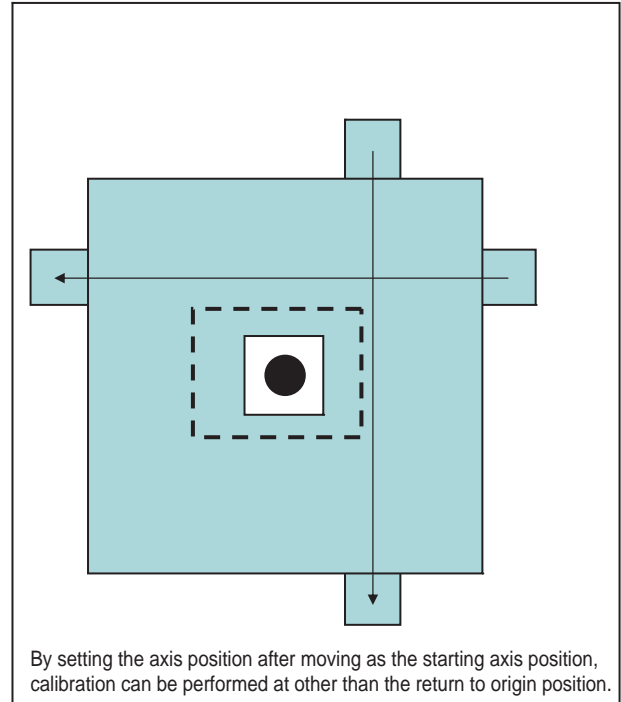
Usage example

When the workpiece used for sampling is not within the camera field of view in the return to origin position (axis movement amount 0)

Return to origin position



Move the stage to make the workpiece enter the camera field of view



Calibration Result (Vision Master Calibration)

This item confirms the calibration data you created. The calibration data can be adjusted directly using the Edit function.

It is also possible to confirm the sampling data used for the calculation.

- 1 In the Item Tab area, click [Calibration result].
- 2 This item confirms the calibration data you created.

Display setting

Data No.:

First calibration data				Calibration data			
A:	1.000000	D:	0.000000	A:	1.000000	D:	0.000000
B:	0.000000	E:	1.000000	B:	0.000000	E:	1.000000
C:	0.000000	F:	0.000000	C:	0.000000	F:	0.000000
X magnification:	1.000000	X-axis angle:	0.000000	X magnification:	1.000000	X-axis angle:	0.000000
Y magnification:	1.000000	Y-axis angle:	90.000000	Y magnification:	1.000000	Y-axis angle:	90.000000
Origin X:	0.000000	XY-axis angle:	90.000000	Origin X:	0.000000	XY-axis angle:	90.000000
Origin Y:	0.000000			Origin Y:	0.000000	Error evaluation	0.000000

Sampling data list

No.	Data type	X-axis movement	Y-axis movement	TH-axis movement	Camera X	Camera Y
0.	Standard position	0.0000	0.0000	0.0000	0.0000	0.0000
1.	First parallel position1	10.0000	0.0000	0.0000	0.0000	0.0000
2.	First parallel position2	0.0000	10.0000	0.0000	0.0000	0.0000
3.	First rotation position1	0.0000	0.0000	10.0000	0.0000	0.0000
4.	Standard position	0.0000	0.0000	0.0000	0.0000	0.0000
5.	Parallel position1	0.0000	0.0000	0.0000	0.0000	0.0000
6.	Parallel position2	0.0000	0.0000	0.0000	0.0000	0.0000
7.	Parallel position3	0.0000	0.0000	0.0000	0.0000	0.0000
8.	Parallel position4	0.0000	0.0000	0.0000	0.0000	0.0000
9.	Rotation position1	0.0000	0.0000	0.0000	0.0000	0.0000

Next measurement: Standard position

Item	Description
"Display setting" area	Sets the data number for which calculation results are displayed.
"First calibration data" area	Displays details about the initial calibration parameters.
"Calibration data" area	Displays details about the calibration parameters. Clicking [Edit enable] will let you change the numbers for A to F. If any number has been changed, the message "This data has been edited" appears at the left of [Edit enable].
"Sampling data list" area	Displays sampling data used for creating the calibration parameters. Reference position displays the movement amount from the origin return position (all axes at 0.0 position). Data other than the reference position displays the movement amount from the reference position.
[Clear step counter] button	Set back the reference position as the next measurement target and start over calibration.

Key Points for Test Measurement and Adjustment (Vision Master Calibration)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Next measurement	Next measurement target
NG cause	Displayed only when judgement is NG -1: Setting NG -2: Sequence NG -3: Operation range NG -4: Calibration calculation NG -5: Error detection value NG -6: Sampling NG -100: Other NG

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image.	Explanation of image to be displayed
0	Measurement image + calibration progress status display
1	Measurement image only

Key Points for Adjustment

Select the adjustment method referring to the following points.

While executing calibration

State	Parameter to be adjusted	Troubleshooting
Unit judgement NG occurred during calibration	Refer to the write sentence.	<p>Confirm the "NG cause" appears in the detail result display and perform appropriate countermeasures.</p> <p>Setting NG</p> <ul style="list-style-type: none"> The processing item setting is not correct. Check if the settings are correct including the processing items being referred to. <p>Sequence NG</p> <ul style="list-style-type: none"> Measurement is executed regardless of whether calibration has been completed. Be sure that no measurement is performed when the calibration completion flag is 1. <p>Movement range NG</p> <ul style="list-style-type: none"> The axis movement range is not correct. Check if the stage data being referred to and the movement range of the robot data are correct. <p>Calibration calculation NG</p> <ul style="list-style-type: none"> Calibration data calculation has failed. Check if the camera coordinates in the sampling data list in the Calculation Result Confirmation Tab are set correctly. If any data is set incorrectly, the processing items used in measurement may not be set properly. Check that the settings are correct. <p>Error detection value NG</p> <ul style="list-style-type: none"> If the end condition of the rotational sampling is "The error detection value is lower than the setting value," the error detection value is not lower than the setting value when the upper limit values for the number of measurement points are measured. Adjust the overall flow setting, for example, by using the average of multiple measurement results to improve the measurement accuracy. <p>Sampling NG</p> <ul style="list-style-type: none"> The sampling measurement has failed. Adjust the setting data so that the processing items used in the measurement is not NG. If it still continues to occur, the judgement formula and condition may not be set correctly. Check that the settings are correct.
To start all over again	Calculation result confirmation	Click [Clear next measurement target] or execute the measurement result clearing.

Other

State	Parameter to be adjusted	Troubleshooting
It cannot be selected because the reference unit No. is <none>.	Machine setting	Check if the reference scene number is selected correctly. Check if stage data processing items or robot data processing items are registered in the selected reference scene.
The reference unit number does not change during flow editing.	Machine setting	The system is designed this way. While a scene other than the current scene is referenced, the reference unit number does not change according to the editing of the flow. Change the flow so that the current scene will be referenced, or set the reference unit number again.

Measurement Results for Which Output Is Possible (Vision Master Calibration)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Origin return output flag	ORIF	Origin return output flag
Calibration end flag	ENDF	Calibration completion output flag
Error evaluation value X	EX	Error evaluation value X
Error detection value Y	EY	Error detection value Y
Next X axis movement	NMX	Next X axis movement amount
Next Y axis movement	NMY	Next Y axis movement amount
Next θ axis angle movement	NMT	Next θ axis angle movement amount
Next θ axis linear movement	NML	Next θ axis linear movement amount
Next U axis movement	NMU	Next U axis movement amount
Next V axis movement	NMV	Next V axis movement amount
Next W axis movement	NMW	Next W axis movement amount
Next R axis movement	NMR	Next R axis movement amount
NG cause	CNG	NG cause -1: Setting NG -2: Sequence NG -3: Operation range NG -4: Calibration calculation NG -5: Error detection value NG -6: Sampling NG -100: Other NG
Measurement execution flag	MF	Measurement execution flag

External Reference Tables (Vision Master Calibration)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
6	Origin return output flag	Get only	0: Do not return to the origin before moving to the next sampling position. 1: Return to the origin before moving to the next sampling position.
7	Calibration completion output flag	Get only	0: Calibration not completed (move to the next sampling position.) 1: Calibration completed.
8	Error evaluation value X	Get only	0 to 99999.9999
9	Error detection value Y	Get only	0 to 99999.9999
10	Next X axis movement amount	Get only	-
11	Next Y axis movement amount	Get only	-
12	Next θ axis angle movement amount	Get only	-
13	Next θ axis linear movement amount	Get only	-
14	Next U axis movement amount	Get only	-
15	Next V axis movement amount	Get only	-
16	Next W axis movement amount	Get only	-
17	Next R axis movement amount	Get only	-
18	Calibration progress type	Get only	-
19	Calibration progress number	Get only	-
20	NG cause	Get only	-1: Setting NG -2: Sequence NG -3: Operation range NG -4: Calibration calculation NG -5: Error detection value NG -6: Sampling NG -100: Other NG
21	Data No.	Get only	-
123	External device reference scene number	Set/Get	-1: Refer to the current scene 0 to 9999: Refer to the scene of the number
124	External device data reference unit number	Set/Get	-1: No reference 0 to 9999: Refer to the unit of the number
128	Movement amount output method	Set/Get	0: Absolute position 1: Relative position
137	Next calibration movement amount X	Set/Get	-99999.9999 to 99999.9999
138	Next calibration movement amount Y	Set/Get	-99999.9999 to 99999.9999
139	Initial calibration rotational movement Start angle	Set/Get	-180.0000 to 180.0000
140	Effective range of the field of view (%)	Set/Get	1 to 100
141	Sampling method for this calibration rotational movement	Set/Get	0: Per data 1: All data at once
142	The number of divided lines of parallel movement in this calibration	Set/Get	2 to 10

No.	Data name	Set/Get	Data range
143	The number of divided columns of parallel movement in this calibration	Set/Get	2 to 10
144	The number of division points in rotational movement in this calibration	Set/Get	2 to 100
145	External device movement method when performing rotational sampling in this calibration	Set/Get	0: Rotational movement only 1: Rotational movement + Parallel movement
150	X axis movement amount when calibration starts	Set/Get	Exp. character string
151	Y axis movement amount when calibration starts	Set/Get	Exp. character string
152	θ axis movement amount when calibration starts	Set/Get	Exp. character string
153	θ axis linear position when calibration starts	Set/Get	Exp. character string
154	U axis movement amount when calibration starts	Set/Get	Exp. character string
155	V axis movement amount when calibration starts	Set/Get	Exp. character string
156	W axis movement amount when calibration starts	Set/Get	Exp. character string
157	R axis movement amount when calibration starts	Set/Get	Exp. character string
158	Trapezoidal distortion compensation parameter creation flag	Set/Get	0: OFF 1: ON
159	Lens distortion compensation parameter creation flag	Set/Get	0: OFF 1: ON
160	Rotational sampling end conditions	Set/Get	0: Performed as many times as the number of division points 1: The error detection value is lower than the setting value.
161	Minimum number of points in error calculation	Set/Get	2 to 100
162	Maximum number of points in error calculation	Set/Get	2 to 100
163	Upper limit value of rotation center error detection	Set/Get	0.000000 to 99999.999999
200 + N \times 10 (N = 0 to 7)	Data N calibration execution flag	Set/Get	0: OFF 1: ON
201 + N \times 10 (N = 0 to 7)	Expression for camera coordinate X of data N	Set/Get	-
202 + N \times 10 (N = 0 to 7)	Expression for camera coordinate Y of data N	Set/Get	-
203 + N \times 10 (N = 0 to 7)	Expression that judges whether the sampling of data N was successful	Set/Get	-
204 + N \times 10 (N = 0 to 7)	The upper limit value for the calculation formula that judges whether the sampling of data N was successful	Set/Get	-999999999.9999 to 999999999.9999

No.	Data name	Set/Get	Data range
205 + N × 10 (N = 0 to 7)	The lower limit value for the calculation formula that judges whether the sampling of data N was successful	Set/Get	-999999999.9999 to 999999999.9999
206 + N × 10 (N = 0 to 7)	The number of the reference input image unit of data N	Set/Get	-1 to 9999
5009	Clear step counter	Set only	Clear the next measurement target data and return the measurement target to the reference position. 1: Clear
11301 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter A	Get only	-99999.999999 to 99999.999999
11302 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter B	Get only	-99999.999999 to 99999.999999
11303 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter C	Get only	-99999.999999 to 99999.999999
11304 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter D	Get only	-99999.999999 to 99999.999999
11305 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter E	Get only	-99999.999999 to 99999.999999
11306 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter F	Get only	-99999.999999 to 99999.999999
11307 + N × 10000 (N = 0 to 7)	Data N initial X magnification	Get only	-
11308 + N × 10000 (N = 0 to 7)	Data N initial Y magnification	Get only	-
11309 + N × 10000 (N = 0 to 7)	Data N initial origin X	Get only	-
11310 + N × 10000 (N = 0 to 7)	Data N initial origin Y	Get only	-
11311 + N × 10000 (N = 0 to 7)	Data N initial X axis angle	Get only	-
11312 + N × 10000 (N = 0 to 7)	Data N initial Y axis angle	Get only	-
11313 + N × 10000 (N = 0 to 7)	Data N initial XY axis angle	Get only	-
14000 + N × 10000 (N = 0 to 7)	Data N error value	Get only	-
14001 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter A	Set/Get	-99999.999999 to 99999.999999
14002 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter B	Set/Get	-99999.999999 to 99999.999999
14003 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter C	Set/Get	-99999.999999 to 99999.999999
14004 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter D	Set/Get	-99999.999999 to 99999.999999
14005 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter E	Set/Get	-99999.999999 to 99999.999999
14006 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter F	Set/Get	-99999.999999 to 99999.999999

No.	Data name	Set/Get	Data range
14007 + N × 10000 (N = 0 to 7)	Data N X magnification	Get only	-
14008 + N × 10000 (N = 0 to 7)	Data N Y magnification	Get only	-
14009 + N × 10000 (N = 0 to 7)	Data N origin X	Get only	-
14010 + N × 10000 (N = 0 to 7)	Data N origin Y	Get only	-
14011 + N × 10000 (N = 0 to 7)	Data N X axis angle	Get only	-
14012 + N × 10000 (N = 0 to 7)	Data N Y axis angle	Get only	-
14013 + N × 10000 (N = 0 to 7)	Data N XY angles	Get only	-

PLC Master Calibration

This processing item is specifically provided for calibration between the camera coordination system and the control equipment coordination system.

In this processing item, the axis movement amount of the control equipment necessary for calibration can be set freely.

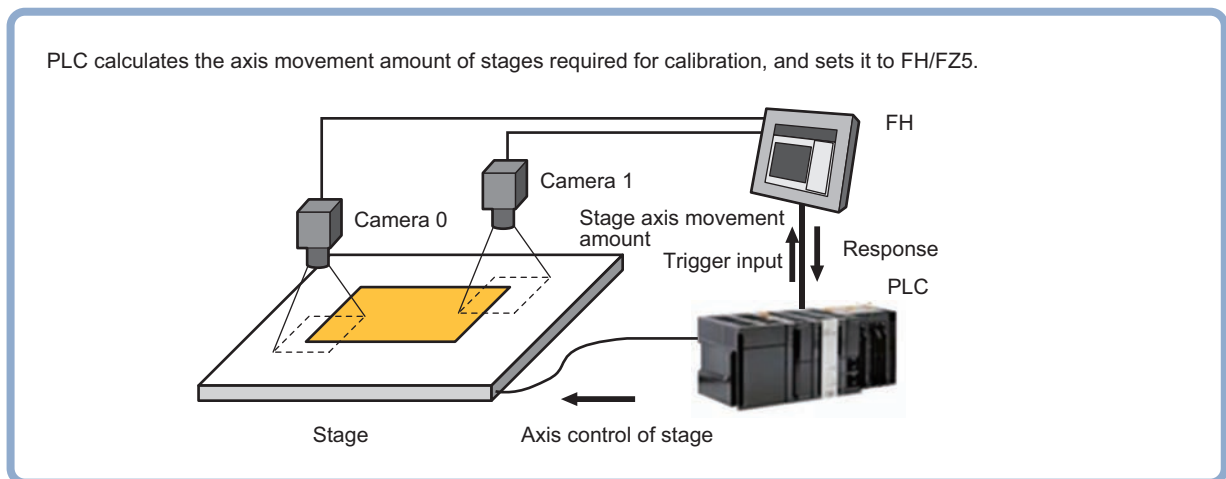
If how to move the calibration mark has already been determined and it cannot be changed, use this processing item. If it can be changed, we recommend you to use [Vision master calibration].

Important

- The calibration data created with this processing item can be referred from [Reference Calib Data]. Unlike other calibration-related processing items, note that this processing item cannot use the calibration data on its own.

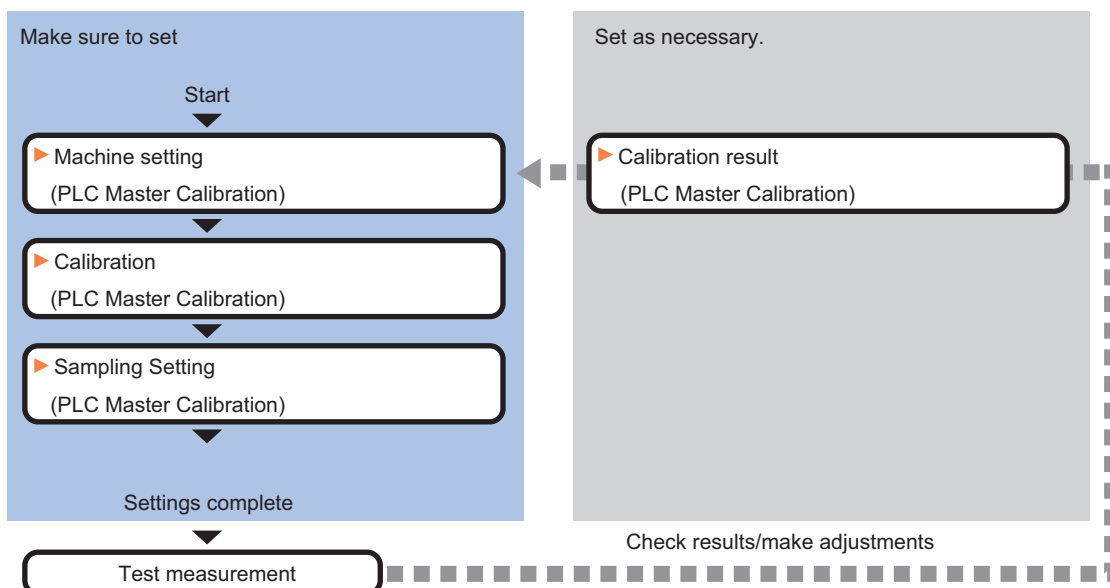
Used in the Following Case

- When you want to position the FPD panel



Settings Flow (PLC Master Calibration)

Set the PLC master calibration with the following steps.



List of PLC Master Calibration Items

Item name	Description
Machine setting	Select a processing item (stage data or robot data) under which external device information needed for calculation of axis movement amount is held. Reference: ▶ Machine Setting (PLC Master Calibration) (p.666)
Calibration	This item sets data related to calibration. Sets the number of calibration data to be created and the measurement processing items to be used for sampling in the arithmetic expression. Reference: ▶ Calibration (PLC Master Calibration) (p.667)
Sampling setting	This item sets data related to sampling. Set the number of samplings and the actual coordinate positions for each sampling. Reference: ▶ Sampling Setting (PLC Master Calibration) (p.668)
Calibration result	The created calibration data is displayed in this item. The calibration data can be adjusted directly using the Edit function. It is also possible to confirm the sampling data used for the calculation. Reference: ▶ Calibration Result (PLC Master Calibration) (p.669)

Machine Setting (PLC Master Calibration)

Select a processing item (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.

Important

- [PLC Master Calibration] refers to [Stage Data] or [Robot Data]. Be sure to register [Stage Data] or [Robot Data] with a given scene.

- 1 In the Item Tab area, click [Machine setting].**
- 2 Select the processing unit that retains information on external device.**

Information of the selected processing unit is displayed in the reference data display area.

Machine setting data

Scene No. : Present scene

Unit No. : 1.Stage data

Setting item	Setting value [Factory default]	Description
Scene No.	[Present scene] Scenes 0 to 127	Select a scene number (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.
Unit No.	-	From among the referenced scene numbers, select a processing item (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.

Note

- If the number of scenes is increased using the scene group conversion tool, the maximum value that can be selected in "Scene No." changes.

Calibration (PLC Master Calibration)

This item sets data related to calibration. Sets the number of calibration data to be created and the measurement processing items to be used for sampling in the arithmetic expression. Also sets the output method for the calculated axis movement amount.

1 In the Item Tab area, click [Calibration].

2 Select the calibration method in the "Calibration type" area.

Setting item	Setting value [Factory default]	Description
Calibration type	[Normal]	Perform calibration by combining the "measurement command" and "set unit data command" from the control equipment (PLC).
	Easy	Perform calibration by using the "measurement command" only.

3 Check the calibration data items that you want to set.

Calibration data is created for the checked numbers.

No.	Position X	Position Y	Judge expression	Judge lower	Judge upper
<input checked="" type="checkbox"/> 0.			TJG	1.0000	1.0000
<input type="checkbox"/> 1.			TJG	1.0000	1.0000
<input type="checkbox"/> 2.			TJG	1.0000	1.0000
<input type="checkbox"/> 3.			TJG	1.0000	1.0000
<input type="checkbox"/> 4.			TJG	1.0000	1.0000
<input type="checkbox"/> 5.			TJG	1.0000	1.0000
<input type="checkbox"/> 6.			TJG	1.0000	1.0000
<input type="checkbox"/> 7.			TJG	1.0000	1.0000

No. Position X: Position Y: Judge expression: Judge condition:

0. [] [] [] [] [] []

4 Select the line of the calibration data that you want to set.

No.	Position X	Position Y	Judge expression	Judge lower	Judge upper
<input checked="" type="checkbox"/> 0.			TJG	1.0000	1.0000
<input type="checkbox"/> 1.			TJG	1.0000	1.0000
<input type="checkbox"/> 2.			TJG	1.0000	1.0000
<input type="checkbox"/> 3.			TJG	1.0000	1.0000
<input type="checkbox"/> 4.			TJG	1.0000	1.0000
<input type="checkbox"/> 5.			TJG	1.0000	1.0000
<input type="checkbox"/> 6.			TJG	1.0000	1.0000
<input type="checkbox"/> 7.			TJG	1.0000	1.0000

No. Position X: Position Y: Judge expression: Judge condition:

0. [] [] [] [] [] []

5 Set each item in the "Calibration target" area.

Setting item	Setting value [Factory default]	Description
Position X	-	Set the arithmetic expression that obtains camera coordinate X used for sampling.
Position Y	-	Set the arithmetic expression that obtains camera coordinate Y used for sampling.
Judge expression	-	Set the arithmetic expression to determine whether sampling was successful or not. If calibration fails during the initial value TJG, set the unit judgement JG of the processing unit from which positions X and Y are referred.

Setting item	Setting value [Factory default]	Description
Judge condition	-999999999.9999 to 999999999.9999 [1.0000] to [1.0000]	Set the upper and lower limit values to determine whether sampling was successful or not. If TJG or JG is set to the judgement expression, use the initial values.

Sampling Setting (PLC Master Calibration)

This item sets data related to sampling.

Set the number of samplings and the actual coordinate positions for each sampling.

- 1** In the Item Tab area, click [Sampling setting].
- 2** Set each item in the "Measurement count" area.

Setting item	Setting value [Factory default]	Description
Parallel count	2 to 100 [2]	Set the number of samplings performed by moving the calibration work in parallel.
Rotation count	2 to 100 [2]	Set the number of samplings performed by rotating the calibration work.

- 3** Set the value for parallel or rotational movement in the "Movement setting" area.

Select the item you want to set in the list and set the movement amount from the reference position.

No.	Data type	X-axis movement	Y-axis movement	TH-axis movement
0	Standard position	0.0000	0.0000	0.0000
1.	Parallel position1	0.0000	0.0000	0.0000
2.	Parallel position2	0.0000	0.0000	0.0000
3.	Rotation position1	0.0000	0.0000	0.0000
4.	Rotation position2	0.0000	0.0000	0.0000

No. 1. X-axis movement: 0.0000 Y-axis movement: 0.0000 TH-axis movement: 0.0000

Setting item	Setting value [Factory default]	Description
X-axis movement	-99999.9999 to 99999.9999 [0.0000]	Set the X axis movement amount from the reference position.
Y-axis movement	-99999.9999 to 99999.9999 [0.0000]	Set the Y axis movement amount from the reference position.

Setting item	Setting value [Factory default]	Description
θ-axis movement	-180.0000 to 180.0000 [0.0000]	Set the θ axis movement amount from the reference position.

Calibration Result (PLC Master Calibration)

The created calibration data is displayed in this item. The calibration data can be adjusted directly using the Edit function.

It is also possible to confirm the sampling data used for the calculation.

- 1** In the Item Tab area, click [Calibration result].
- 2** This item confirms the calibration data you created.

The screenshot shows the calibration interface with three main sections:

- Display setting:** A field for "Data No." with a value of 0 and navigation buttons.
- Calibration data:** A list of parameters:

A:	1.000000	D:	0.000000
B:	0.000000	E:	1.000000
C:	0.000000	F:	0.000000
X magnification:	1.000000	X-axis angle:	0.000000
Y magnification:	1.000000	Y-axis angle:	90.000000
Origin X:	0.000000	XY-axis angle:	90.000000
Origin Y:	0.000000		

 An "Edit enable" button is located at the bottom right of this section.
- Sampling data list:** A table with 7 columns: No., Data type, X-axis movement, Y-axis movement, TH-axis movement, Camera X, and Camera Y.

No.	Data type	X-axis movement	Y-axis movement	TH-axis movement	Camera X	Camera Y
0.	Standard position	0.0000	0.0000	0.0000	0.0000	0.0000
1.	Parallel position1	0.0000	0.0000	0.0000	0.0000	0.0000
2.	Parallel position2	0.0000	0.0000	0.0000	0.0000	0.0000
3.	Rotation position1	0.0000	0.0000	0.0000	0.0000	0.0000
4.	Rotation position2	0.0000	0.0000	0.0000	0.0000	0.0000

Item	Description
"Display setting" area	Sets the data number for which calculation results are displayed.
"Calibration data" area	Displays details about the calibration parameters. Clicking [Enable direct edit] will let you change the numbers for A to F. If any number has been changed, the message "This data has been directly edited" appears at the left of [Enable direct edit].
"Sampling data list" area	Displays sampling data used for creating the calibration parameters.

Key Points for Test Measurement and Adjustment (PLC Master Calibration)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Calibration method	Calibration method

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image.	Explanation of image to be displayed
0	Measurement image + calibration progress status
1	Measurement image only

Key Points for Adjustment

Select the adjustment method referring to the following points.

While executing calibration

State	Parameter to be adjusted	Troubleshooting
Unit judgement NG occurred during calibration	Refer "Troubleshooting"	<p>Confirm the "NG cause" appears in the detail result display and perform appropriate countermeasures.</p> <p>Setting NG</p> <ul style="list-style-type: none"> The processing item setting is not correct. Check if the settings are correct including the processing items being referred to. <p>Sequence NG</p> <ul style="list-style-type: none"> Measurement is executed regardless of whether calibration has been completed. Do not execute measurements with the calibration progress type set to 3 in the external reference table. <p>Calibration calculation NG</p> <ul style="list-style-type: none"> Calibration data calculation has failed. Check if the camera coordinates in the sampling data list in the Calculation Result Confirmation Tab are set correctly. If any data is set incorrectly, the processing items used in measurement may not be set properly. Check that the settings are correct. <p>Sampling NG</p> <ul style="list-style-type: none"> The sampling measurement has failed. Adjust the setting data so that the processing items used in the measurement is not NG. If it still continues to occur, the judgement formula and condition may not be set correctly. Check if the settings are correct or not.
To start all over again	-	Execute the clear measurement result or external reference data #5009 "Clear step counter".

Other

State	Parameter to be adjusted	Troubleshooting
It cannot be selected because the reference unit No. is <none>.	Machine setting	Check if the reference scene number is selected correctly. Check if stage data processing items or robot data processing items are registered in the selected reference scene.
The reference unit number does not change during flow editing.	Machine setting	The system is designed this way. While a scene other than the current scene is referenced, the reference unit number does not change according to the editing of the flow. Change the flow so that the current scene will be referenced, or set the reference unit number again.

Measurement Results for Which Output Is Possible (PLC Master Calibration)

The following values can be output using processing items related to results output. It is also possible to refer to measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Calibration progress status flag	CT	Calibration progress status flag
NG cause	CNG	NG cause -1: Setting NG -2: Sequence NG -3: Operation range NG -4: Calibration calculation NG -5: Error detection value NG -6: Sampling NG -100: Other NG

External Reference Tables (PLC Master Calibration)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
18	Calibration progress type	Get only	0: Reference position 1: Parallel movement 2: Rotational movement 3: End calibration
19	Calibration progress number	Get only	-
20	NG cause	Get only	-1: Setting NG -2: Sequence NG -3: Operation range NG -4: Calibration calculation NG -5: Error detection value NG -6: Sampling NG -100: Other NG
120	Calibration execution flag	Set/Get	0: Not executed 1: Executed
121	Number of parallel movement points	Set/Get	2 to 100
122	Number of rotational movement points	Set/Get	2 to 100
123	Scene number for referring to the external device data	Set/Get	-1: Refer to the current scene 0 to 9999: Refer to the designated scene number
124	Unit number for referring to the external device data	Set/Get	-1: No reference 0 to 9999: Refer to the designated unit number
125	Calibration method	Set/Get	0: Normal 1: Simplified
200 + N × 10 (N = 0 to 7)	Calibration execution flag for data N	Set/Get	0: OFF 1: ON
201 + N × 10 (N = 0 to 7)	Expression for camera coordinate X of data N	Set/Get	-

No.	Data name	Set/Get	Data range
202 + N × 10 (N = 0 to 7)	Expression for camera coordinate Y of data N	Set/Get	-
203 + N × 10 (N = 0 to 7)	Expression that judges whether the sampling of data N was successful	Set/Get	-
204 + N × 10 (N = 0 to 7)	The upper limit value for the calculation formula that judges whether the sampling of data N was successful	Set/Get	-999999999.9999 to 999999999.9999
205 + N × 10 (N = 0 to 7)	The lower limit value for the calculation formula that judges whether the sampling of data N was successful	Set/Get	-999999999.9999 to 999999999.9999
1000 + N × 10 (N = 0 to 7)	X axis movement amount for parallel movement position N	Set/Get	-99999.9999 to 99999.9999
1001 + N × 10 (N = 0 to 7)	Y axis movement amount for rotational movement position N	Set/Get	-99999.9999 to 99999.9999
2000 + N × 10 (N = 0 to 7)	X axis movement amount for rotational movement position N	Set/Get	-99999.9999 to 99999.9999
2001 + N × 10 (N = 0 to 7)	Y axis movement amount for rotational movement position N	Set/Get	-99999.9999 to 99999.9999
2002 + N × 10 (N = 0 to 7)	θ axis movement amount for rotational movement position N	Set/Get	-180.0000 to 180.0000
5000	Calibration start/end	Setting only	0: End the calibration 1: Start the calibration
5001	Calibration target setting	Setting only	Each bit of the set data corresponds to the data No. 0 to 7. 0: Calibration is not executed 1: Calibration is executed
5002	Reference position registration	Setting only	0: Not executed 1 : Executed
5003	Parallel movement position registration	Setting only	1 to 100
5004	Rotation movement position registration	Setting only	1 to 100
5005	Calibration parameter calculation	Setting only	0: Not executed 1 : Executed
5006	Error value calculation	Setting only	0: Not executed 1 : Executed
5007	Sampling data clear	Setting only	0: Not executed 1 : Executed
5009	Clear step counter	Setting only	0: Not executed 1 : Executed
14000 + N × 10000 (N = 0 to 7)	Data N error value	Get only	-
14001 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter A	Set/Get	-99999.999999 to 99999.999999
14002 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter B	Set/Get	-99999.999999 to 99999.999999
14003 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter C	Set/Get	-99999.999999 to 99999.999999
14004 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter D	Set/Get	-99999.999999 to 99999.999999

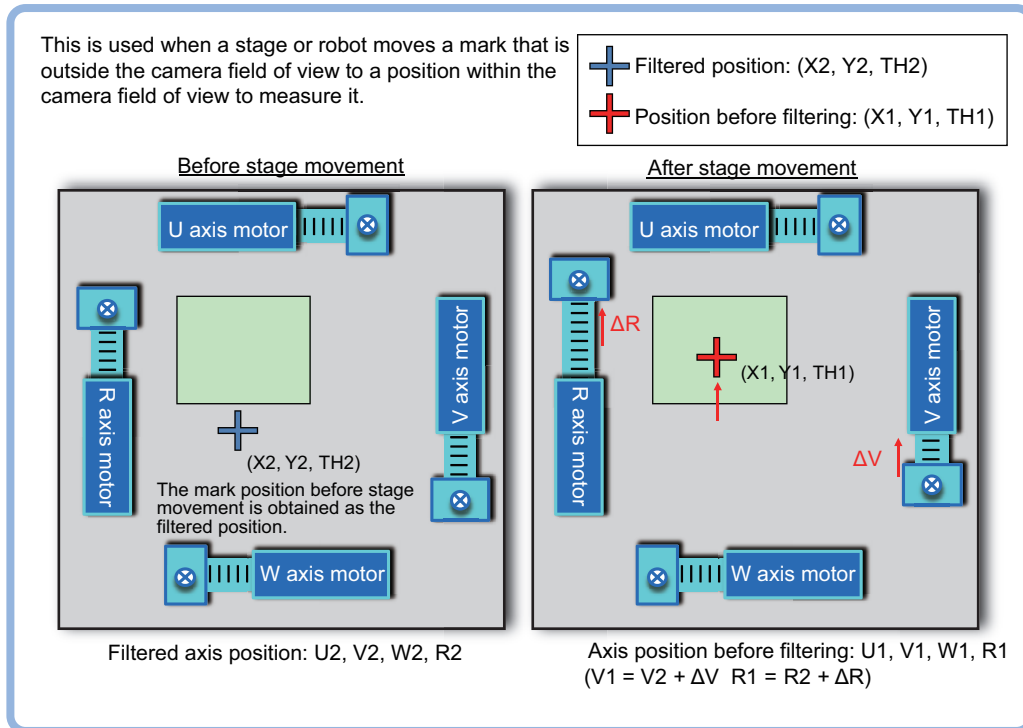
No.	Data name	Set/Get	Data range
14005 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter E	Set/Get	-99999.999999 to 99999.999999
14006 + N × 10000 (N = 0 to 7)	Data N initial calibration Parameter F	Set/Get	-99999.999999 to 99999.999999
14007 + N × 10000 (N = 0 to 7)	Data N X magnification	Get only	-
14008 + N × 10000 (N = 0 to 7)	Data N Y magnification	Get only	-
14009 + N × 10000 (N = 0 to 7)	Data N origin X	Get only	-
14010 + N × 10000 (N = 0 to 7)	Data N origin Y	Get only	-
14011 + N × 10000 (N = 0 to 7)	Data N X axis angle	Get only	-
14012 + N × 10000 (N = 0 to 7)	Data N Y axis angle	Get only	-
14013 + N × 10000 (N = 0 to 7)	Data N XY angles	Get only	-

Convert Position Data

Calculates the post movement position/angle data when each axis of a stage or robot is moved for a given distance. Use this when you want to measure the stage after moving a given distance and obtain the pre-movement position/angle data.

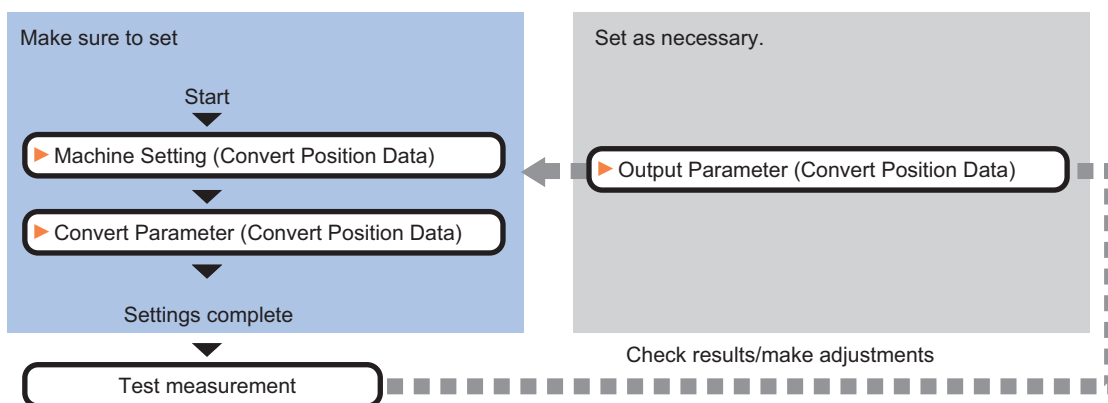
Used in the Following Case

- When you want to position the FPD panel



Settings Flow (Convert Position Data)

The position/angle conversion should be set up with the following procedure.



Item list of Convert Position Data

Item name	Description
Machine setting	Select a processing item (stage data or robot data) under which external device information needed for calculation of axis movement amount is held. Reference: ▶ Machine Setting (Convert Position Data) (p.675)
Conversion parameter	The item sets data related to conversion. Sets a calculation formula using the pre-conversion position and axis position and post-conversion axis position. Reference: ▶ Convert Parameter (Convert Position Data) (p.676)
Output parameter	Select whether or not the judgement results of this processing unit is reflected in the scene overall judgement. Reference: ▶ Output Parameter (Convert Position Data) (p.679)

Machine Setting (Convert Position Data)

Select a processing item (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.

Important

- [Convert Position Data] refers to [Stage Data] or [Robot Data]. Be sure to register [Stage Data] or [Robot Data] in the referenced scene.

1 In the Item Tab area, click [Machine setting].

2 Select the processing unit that retains information on external device.

Information of the selected processing unit is displayed in the reference data display area.

Machine setting data

Reference scene No. : Present scene

Reference unit No. : 1.Stage data

Setting item	Setting value [Factory default]	Description
Reference scene No.	[Present scene] Scenes 0 to 127	Select a scene number (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.
Reference unit No.	-	From among the referenced scene numbers, select a processing item (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.

Note

- If the number of scenes is increased using the scene group conversion tool, the maximum value that can be selected in "Reference scene No." changes.

Convert Parameter (Convert Position Data)

The item sets data related to conversion. Sets a calculation formula using the pre-conversion position and axis position and post-conversion axis position.

- 1 Click [Convert parameter] in the Item Tab area.
- 2 Set each item in the "Current pos." area.

Setting item	Setting value [Factory default]	Description
Position X	-	Set the calculation formula that obtains the position X of the conversion target.
Position Y	-	Set the calculation formula that obtains the position Y of the conversion target.
Position angle	-	Set the calculation formula that obtains the angle of the conversion target. To convert positions X and Y only, set 0 as the angle.

- 3 Set each item in the "Axis position" area before conversion.

Set how far each axis moved from the origin return state (all axes are at the origin point) when the "Pre-correction position/angle" is measured.

If the stage type of the reference data is the XY stage or the robot type is 3-axis robot

Setting item	Setting value [Factory default]	Description
X-axis	-	Set how far the X axis position moved from the origin.
Y-axis	-	Set how far the Y axis position moved from the origin.

If the stage type of the reference data is the XYθ stage, θXY stage or the robot type is 4-axis robot

Setting item	Setting value [Factory default]	Description
X-axis	-	Set how far the X axis position moved from the origin.
Y-axis	-	Set how far the Y axis position moved from the origin.
θ-axis	-	Set how far the θ axis position moved from the origin.

If the stage type of the reference data is the UVW stage

Setting item	Setting value [Factory default]	Description
U-axis	-	Set how far the U axis position moved from the origin.
V-axis	-	Set how far the V axis position moved from the origin.
W-axis	-	Set how far the W axis position moved from the origin.

If the stage type of the reference data is the UVWR stage

Setting item	Setting value [Factory default]	Description
U-axis	-	Set how far the U axis position moved from the origin.
V-axis	-	Set how far the V axis position moved from the origin.
W-axis	-	Set how far the W axis position moved from the origin.
R-axis	-	Set how far the R axis position moved from the origin.

4 Set each item in the "Convert axis" area.

Set how far each axis in the "Post-correction position/angle" moved from the origin return state (all axes are at the origin point).

If the stage type of the reference data is the XY stage or the robot type is 3-axis robot

Setting item	Setting value [Factory default]	Description
X-axis	-	Set how far the X axis position moved from the origin.
Y-axis	-	Set how far the Y axis position moved from the origin.

If the stage type of the reference data is the XYθ stage, θXY stage or the robot type is 4-axis robot

Setting item	Setting value [Factory default]	Description
X-axis	-	Set how far the X axis position moved from the origin.
Y-axis	-	Set how far the Y axis position moved from the origin.
θ-axis	-	Set how far the θ axis position moved from the origin.

If the stage type of the reference data is the UVW stage

Setting item	Setting value [Factory default]	Description
U-axis	-	Set how far the U axis position moved from the origin.
V-axis	-	Set how far the V axis position moved from the origin.
W-axis	-	Set how far the W axis position moved from the origin.

If the stage type of the reference data is the UVWR stage

Setting item	Setting value [Factory default]	Description
U-axis	-	Set how far the U axis position moved from the origin.
V-axis	-	Set how far the V axis position moved from the origin.
W-axis	-	Set how far the W axis position moved from the origin.
R-axis	-	Set how far the R axis position moved from the origin.

- 5** Click [Measure] to check the measurement results.
- 6** Set the judgement condition.

Note

- The values beside each item are measurement results of the displayed image. Take these values into consideration to determine the upper and lower limit values.

Setting item	Setting value	Description
Converted pos. X	-99999.9999 to 99999.9999	Specify the range of X-axis conversion that is judged to be OK.
Converted pos. Y	-99999.9999 to 99999.9999	Specify the range of Y-axis conversion that is judged to be OK.
Converted angle	-180.0000 to 180.0000	Specify the range of angle conversion that is judged to be OK.

Output Parameter (Convert Position Data)

Select whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Choose whether or not to reflect the judgement result in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Setting value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Specify whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Test Measurement and Adjustment (Convert Position Data)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Post-conversion position X	Displays the position X of the post-conversion measurement data.
Post-conversion position Y	Displays the position Y of the post-conversion measurement data.
Post-conversion angle	Displays the angle of the post-conversion measurement data.

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image.	Explanation of image to be displayed
0	Measurement image

Key Points for Adjustment

Select the adjustment method referring to the following points.

State	Parameter to be adjusted	Troubleshooting
Judgement was NG.	Calculation setting	The arithmetic expression may be empty. Set the correct arithmetic expression.
It cannot be selected because the reference unit No. is <none>.	Machine setting	Check if the reference scene number is selected correctly. Check if stage data processing items or robot data processing items are registered in the selected reference scene.
The reference unit number does not follow during flow editing.	Machine setting	The system is designed this way. While a scene other than the current scene is referenced, the reference unit number does not change according to the editing of the flow. Change the flow so that the current scene will be referenced, or set the reference unit number again.

Measurement Results for Which Output Is Possible (Convert Position Data)

The following values can be output using processing items related to results output. It is also possible to refer to measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Post-conversion position X	X	Post-conversion position X
Post-conversion position Y	Y	Post-conversion position Y
Post-conversion angle	TH	Post-conversion angle

External Reference Tables (Convert Position Data)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Post-conversion position X	Get only	-
6	Post-conversion position Y	Get only	-
7	Post-conversion angle	Get only	-
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Reference scene No.	Set/Get	-1: Refer to the current scene 0 to 9999: Refer to the designated scene number
121	Reference unit No.	Set/Get	-1: No reference 0 to 9999: Refer to the designated unit number
122	Pre-conversion position X	Set/Get	Exp. character string
123	Pre-conversion position Y	Set/Get	Exp. character string
124	Pre-conversion angle	Set/Get	Exp. character string
130	Pre-conversion X axis position	Set/Get	Exp. character string
131	Pre-conversion Y axis position	Set/Get	Exp. character string
132	Pre-conversion θ axis position (direct drive)	Set/Get	Exp. character string
133	Pre-conversion θ axis position (linear drive)	Set/Get	Exp. character string
134	Pre-conversion U axis position	Set/Get	Exp. character string
135	Pre-conversion V axis position	Set/Get	Exp. character string
136	Pre-conversion W axis position	Set/Get	Exp. character string
137	Pre-conversion R axis position	Set/Get	Exp. character string
140	Pre-conversion X axis position	Set/Get	Exp. character string

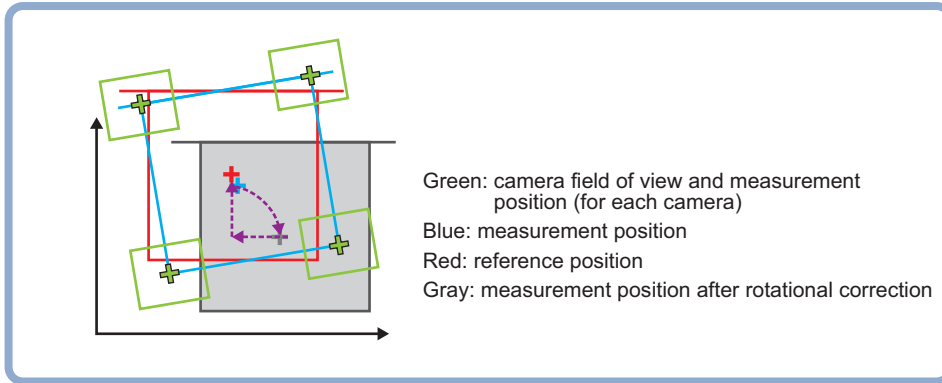
No.	Data name	Set/Get	Data range
141	Post-conversion Y axis position	Set/Get	Exp. character string
142	Post-conversion θ axis position (direct drive)	Set/Get	Exp. character string
143	Post-conversion θ axis position (linear drive)	Set/Get	Exp. character string
144	Post-conversion U axis position	Set/Get	Exp. character string
145	Post-conversion V axis position	Set/Get	Exp. character string
146	Post-conversion W axis position	Set/Get	Exp. character string
147	Post-conversion R axis position	Set/Get	Exp. character string
150	Upper limit value for judging the post-conversion position X	Set/Get	-99999.9999 to 99999.9999
151	Lower limit value for judging the post-conversion position X	Set/Get	-99999.9999 to 99999.9999
152	Upper limit value for judging the post-conversion position Y	Set/Get	-99999.9999 to 99999.9999
153	Lower limit value for judging the post-conversion position Y	Set/Get	-99999.9999 to 99999.9999
154	Upper limit value for judging the post-conversion angle	Set/Get	-180.0000 to 180.0000
155	Lower limit value for judging the post-conversion angle	Set/Get	-180.0000 to 180.0000

Movement Single Position

Calculate the movement amount of each axis of the external device necessary to adjust the measurement position and angle to the reference position and angle. Set the measurement position/angle and reference position/angle using an arithmetic expression.

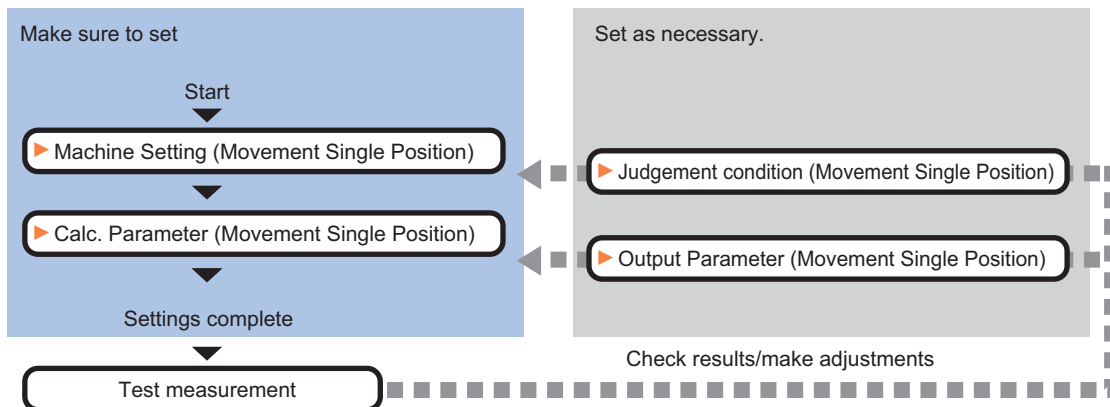
Used in the Following Case

- When you want to position the FPD panel



Settings Flow (Movement Single Position)

Set the axis movement amount calculation following the procedure below..



List of Movement Single Position Items

Item name	Description
Machine setting	Select a processing item (stage data or robot data) under which external device information needed for calculation of axis movement amount is held. Reference: ▶ Machine Setting (Movement Single Position) (p.683)
Calc. parameter	Set the reference position/angle and measurement position/angle using an arithmetic expression. If multiple cameras are used, the setting data can be created easily by using the position/angle calculation processing items. Reference: ▶ Calc. Parameter (Movement Single Position) (p.684)
Judgement condition	This item specifies the judgement condition for measurement results. Reference: ▶ Judgement Condition (Movement Single Position) (p.687)
Output parameter	This item can be changed if necessary. Set whether or not the judgement results of this processing unit is reflected in the scene overall judgement. Reference: ▶ Output Parameter (Movement Single Position) (p.688)

Machine Setting (Movement Single Position)

Select a processing item (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.

1 In the Item Tab area, click [Machine setting].

2 Select the reference scene No. and reference unit No.

Information of the selected processing unit is displayed in the reference data display area.

Setting item	Setting value [Factory default]	Description
Reference scene No.	[Present scene] Scenes 0 to 127	Select a scene number (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.
Reference unit No.	-	From among the referenced scene numbers, select a processing item (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.

Note

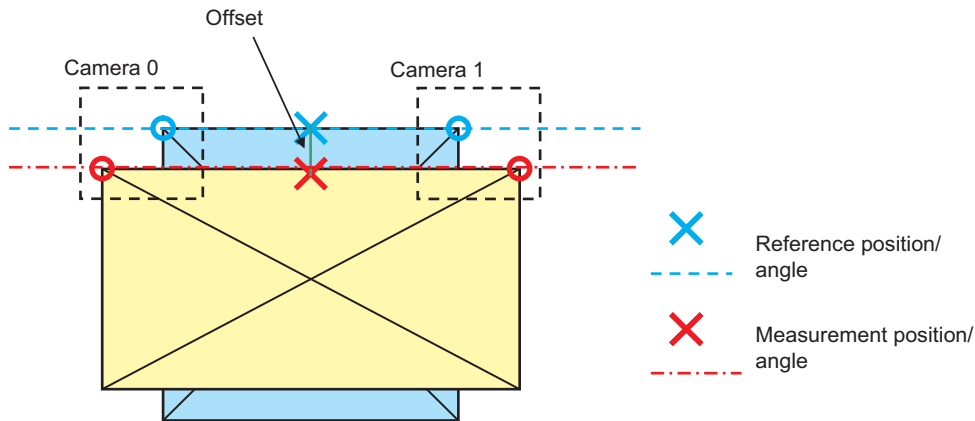
- If the number of scenes is increased using the scene group conversion tool, the maximum value that can be selected in "Reference scene No." changes.

Calc. Parameter (Movement Single Position)

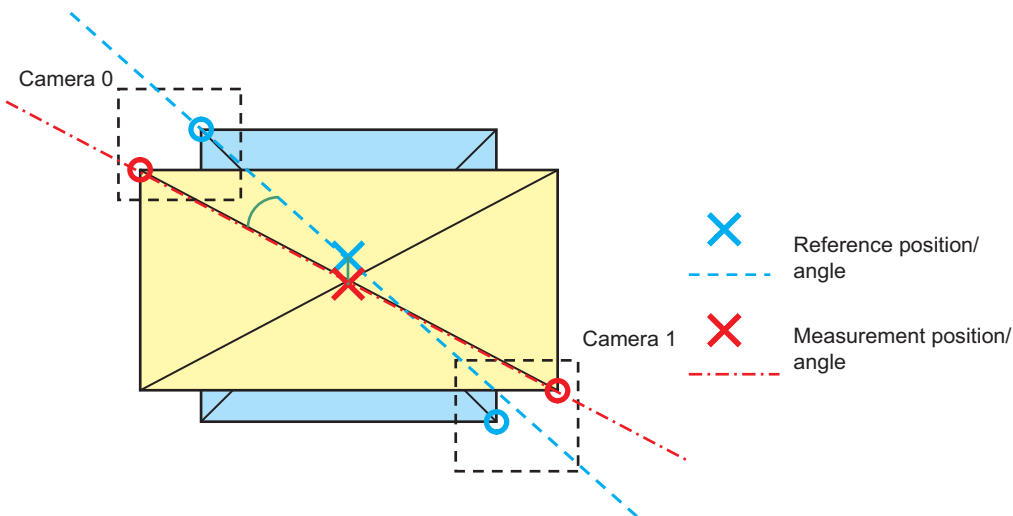
Set the reference position/angle and measurement position/angle using an arithmetic expression. If multiple cameras are used, the setting data can be created easily by using the position/angle calculation processing items.

In case there is a difference between the reference position/angle and the measurement position/angle, you can compensate it by setting the offset. Example1 shows the application to align the center of a couple of sheets which have the different size. In this case, a precise alignment can be realized by setting the vertical offset as below. In example2, the angular offset is necessary in addition.

Example 1) When an offset in the vertical direction is required



Example 2) When offsets in the vertical direction and angle direction are required



- 1 Click [Calc. parameter] in the Item Tab area.

2 Set each parameters using arithmetic expressions.

The image shows a software interface with four panels for parameter settings:

- Reference setting:** Position X, Position Y, Position angle.
- Reference offset setting:** Position X, Position Y, Position angle, Initial angle.
- Measure setting:** Position X, Position Y, Position angle.
- Measure offset setting:** Position X, Position Y, Position angle, Initial angle.

If no reference data is selected

The following parameters are displayed in this menu based on the stage type.

Displayed content		Not selected	XY	XY θ	θ XY	UVW	UVWR	3 axes	4 axes
	Reference X	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	Reference Y	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	Reference angle	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>
	Measurement position X	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	Measurement position Y	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	Measure angle	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>
Offset	Reference X	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	Reference Y	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	Reference angle	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>
	Angle at the definition time	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>
	Measurement position X	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	Measurement position Y	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	Measure angle	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>
	Angle at the definition time	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>
Current axis position	X axis	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>
	Y axis	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>
	θ axis	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>
	U axis	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
	V axis	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
	W axis	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
	R axis	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>

O: Show, \times : Hide

Initial angle

Initial angle is an angle when the offset amount is calculated.

Example) Positioning of a ceramic chip by using the angle of the diagonal line and the center position.

Definition of symbol in the following figure

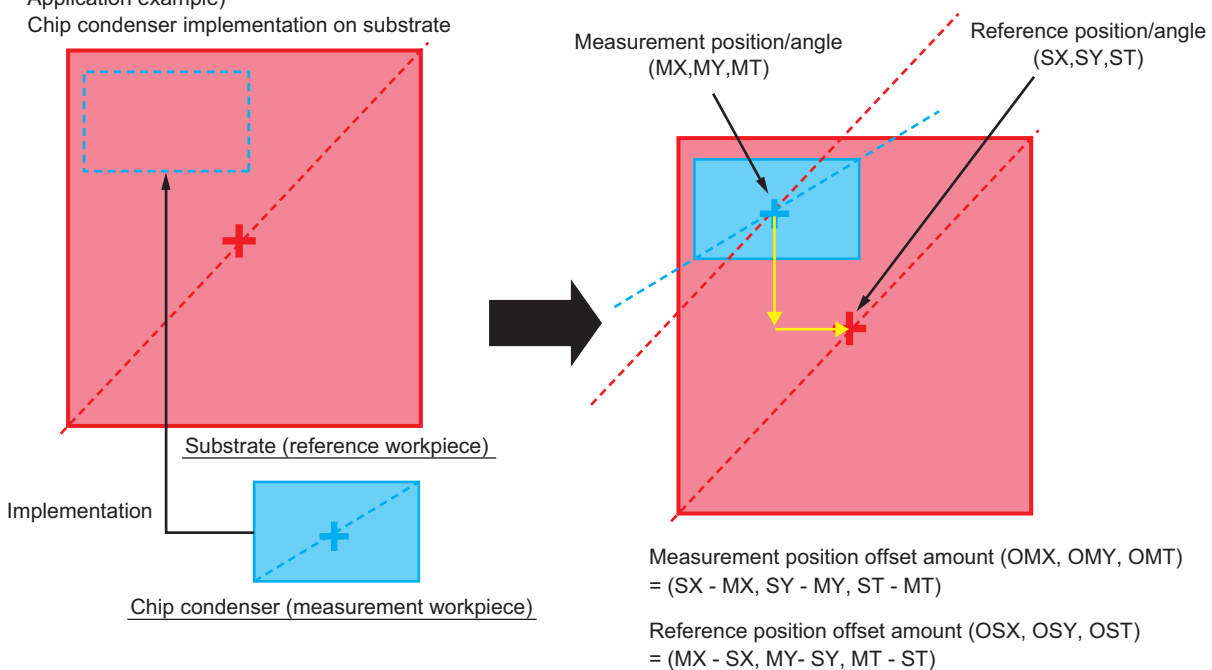
- Measurement position/angle of when the offset amount is calculated (MX, MY, MT)
- Reference position/angle when the offset amount is calculated (SX, SY, ST)
- Offset amount of measurement position/angle (OMX, OMY, OMT)
- Offset amount of the reference position/angle (OSX, OSY, OST)

Setting contents for "Measurement position offset setting" of the Movement Single Position

- Position X : $OMX = SX - MX$
- Position Y : $OMY = SY - MY$
- Angle : $OMT = ST - MT$
- Angle at the definition time : MT

Application example)

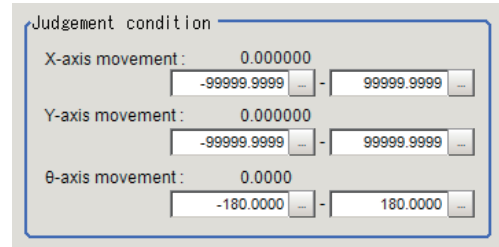
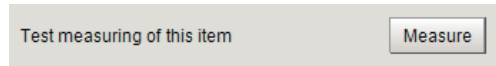
Chip condenser implementation on substrate



Judgement Condition (Movement Single Position)

This item specifies the judgement condition for measurement results.

- 1 When the setting has been changed, click [Measure] to verify whether measurements can be made correctly.
- 2 In the "Judgement condition" area, set each item.



If the reference data is the UVWR stage

The following parameters are displayed in this menu based on the stage type.

Displayed content	Not selected	XY	XY θ	θ XY	UVW	UVWR	3 axes	4 axes
X axis movement amount Judgement upper/lower limit values	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="radio"/>	<input type="radio"/>
Y axis movement amount Judgement upper/lower limit values	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="radio"/>	<input type="radio"/>
θ axis angle movement amount Judgement upper/lower limit values	<input type="radio"/>	<input checked="" type="checkbox"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="radio"/>
θ axis movement amount Judgement upper/lower limit values	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
U axis movement amount Judgement upper/lower limit values	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
V axis movement amount Judgement upper/lower limit values	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
W axis movement amount Judgement upper/lower limit values	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
R axis movement amount Judgement upper/lower limit values	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="radio"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>

O: Show, \times : Hide

Output Parameter (Movement Single Position)

Set how to treat the coordinates to be output to the external device as measurement results. This item can be changed if necessary. Normally, the factory default value will be used.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Setting value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Specify whether or not the judgement results of this processing unit is reflected in the scene overall judgement.
Output type	<ul style="list-style-type: none"> • [Opposite moving] • Absolute moving 	Opposite moving: Outputs the movement amount from the current axis position. Absolute moving: Outputs the movement amount from the origin.

Key Points for Test Measurement and Adjustment (Movement Single Position)

The following results are displayed.

Displayed item	Character string	Description
Judgement	JG	Judgement result
Position X difference	DX	Position X difference
Position Y difference	DY	Position Y difference
Angle difference	DT	Angle difference
Measurement X	X	Measurement X
Measurement Y	Y	Measurement Y
Measure angle	TH	Angle θ
Reference X	SX	Reference X
Reference Y	SY	Reference Y
Reference angle	ST	Reference angle θ
X axis movement	MX	X axis movement amount (*)
Y axis movement	MY	Y axis movement amount (*)
θ axis angle movement	MT	θ axis angle movement amount (*)
θ axis linear movement	ML	θ axis movement amount (*)
U axis movement	MU	U axis movement amount (*)
V axis movement	MV	V axis movement amount (*)
W axis movement	MW	W axis movement amount (*)
R axis movement	MR	R axis movement amount (*)

* The following parameters are displayed in this menu based on the stage type.

Displayed content	XY	XY θ	θ XY	UVW	UVWR	3 axes	4 axes
X axis movement amount	○	○	○	×	×	○	○
Y axis movement amount	○	○	○	×	×	○	○
θ axis angle movement amount	×	○	○	×	×	×	○

Displayed content	XY	XYθ	θXY	UVW	UVWR	3 axes	4 axes
θ axis movement amount	×	○ (θ axis linear drive)	×	×	×	×	×
U axis movement amount	×	×	×	×	○	×	×
V axis movement amount	×	×	×	×	○	×	×
W axis movement amount	×	×	×	×	○	×	×
R axis movement amount	×	×	×	×	○	×	×

○: Show, ×: Hide

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are false

State	Parameter to be adjusted	Troubleshooting
The sign of the measurement result (positive/negative) output is opposite.	-	The reference position/angle and measurement position/angle may be set in reverse. The axis movement amount calculates the movement amount from the measurement position/angle to the reference position/angle.

Other

State	Parameter to be adjusted	Troubleshooting
The reference unit number is <"None"> and cannot be selected.	Machine setting	Check if the reference scene number is selected correctly. Check if stage data processing items or robot data processing items are registered in the selected reference scene.
The reference unit number does not follow during flow editing.	Machine setting	The system is designed this way. While a scene other than the current scene is referenced, the reference unit number does not change according to the editing of the flow. Change the flow so that it refers to from the current scene or set the reference unit number again.

Measurement Results for Which Output Is Possible (Movement Single Position)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Displayed item	Character string	Description
Judge	JG	Judgement result
Position X difference	DX	Position X difference
Position Y difference	DY	Position Y difference
Angle difference	DT	Angle difference
Measurement position X	X	Measurement position X
Measurement position Y	Y	Measurement position Y
Measure angle	TH	Angle θ
Reference X	SX	Reference X
Reference Y	SY	Reference Y

Displayed item	Character string	Description
Reference angle	ST	Reference angle θ
X axis movement	MX	X axis movement amount (*)
Y axis movement	MY	Y axis movement amount (*)
θ axis angle movement	MT	θ axis angle movement amount (*)
θ axis linear movement	ML	θ axis linear movement amount (*)
U axis movement	MU	U axis movement amount (*)
V axis movement	MV	V axis movement amount (*)
W axis movement	MW	W axis movement amount (*)
R axis movement	MR	R axis movement amount (*)

* The following parameters are displayed in this menu based on the stage type.

Output contents	XY	XY θ	θ XY	UVW	UVWR	3 axes	4 axes
X axis movement	○	○	○	×	×	○	○
Y axis movement	○	○	○	×	×	○	○
θ axis angle movement	×	○	○	×	×	×	○
θ axis movement	×	○ (θ axis linear drive)	×	×	×	×	×
U axis movement	×	×	×	×	○	×	×
V axis movement	×	×	×	×	○	×	×
W axis movement	×	×	×	×	○	×	×
R axis movement	×	×	×	×	○	×	×

○: Output, ×: Do not output

External Reference Tables (Movement Single Position)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	X axis movement	Get only	-
6	Y axis movement	Get only	-
7	θ axis angle movement	Get only	-180.0000 to 180.0000
8	θ axis linear movement	Get only	-
9	U axis movement	Get only	-
10	V axis movement	Get only	-
11	W axis movement	Get only	-
12	R axis movement	Get only	-
13	Reference X	Get only	-
14	Reference Y	Get only	-
15	Reference angle	Get only	-
16	Measurement X	Get only	-
17	Measurement Y	Get only	-

No.	Data name	Set/Get	Data range
18	Measure angle	Get only	-
19	Position X difference	Get only	-
20	Position Y difference	Get only	-
21	Angle difference	Get only	-
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	External device reference scene number	Set/Get	-1: Reference the current scene 0 to 9999: Reference the scene of the specified number
121	External device data reference unit number	Set/Get	-1: No reference unit 0 to 9999: Reference the unit of the specified number
130	Reference X	Set/Get	Exp. character string
131	Reference Y	Set/Get	Exp. character string
132	Reference angle	Set/Get	Exp. character string
133	Measurement position X	Set/Get	Exp. character string
134	Measurement position Y	Set/Get	Exp. character string
135	Measure angle	Set/Get	Exp. character string
140	Reference position X offset	Set/Get	Exp. character string
141	Reference position Y offset	Set/Get	Exp. character string
142	Reference angle offset	Set/Get	Exp. character string
143	Measurement position X offset	Set/Get	Exp. character string
144	Measurement position Y offset	Set/Get	Exp. character string
145	Measurement angle offset	Set/Get	Exp. character string
146	Calculation formula for the angle at the definition time (reference)	Set/Get	Exp. character string
147	Calculation formula for the angle at the definition time (measured)	Set/Get	Exp. character string
150	Current X axis movement amount	Set/Get	Exp. character string
151	Current Y axis movement amount	Set/Get	Exp. character string
152	Current θ axis angle movement amount	Set/Get	Exp. character string
153	The current θ axis linear movement amount	Set/Get	Exp. character string
154	Current U axis movement amount	Set/Get	Exp. character string
155	Current V axis movement amount	Set/Get	Exp. character string
156	Current W axis movement amount	Set/Get	Exp. character string
157	Current R axis movement amount	Set/Get	Exp. character string
160	X axis movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999

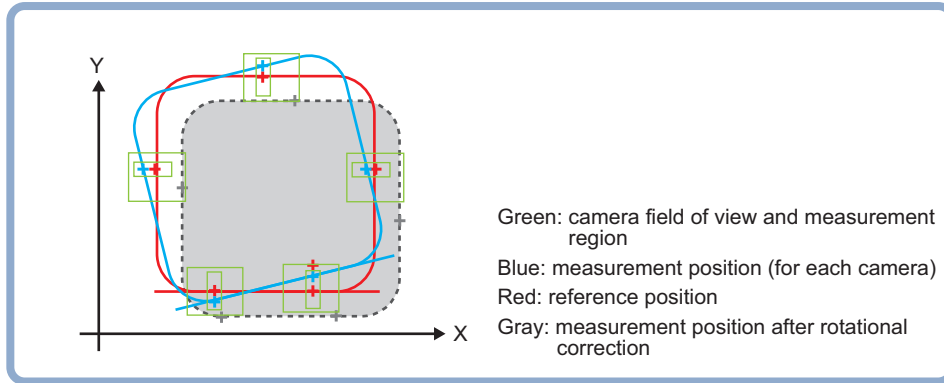
No.	Data name	Set/Get	Data range
161	X axis movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999
162	Y axis movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999
163	Y axis movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999
164	θ axis angle movement amount judgement upper limit value	Set/Get	-180.0000 to 180.0000
165	θ axis angle movement amount judgement lower limit value	Set/Get	-180.0000 to 180.0000
166	θ axis linear movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999
167	θ axis linear movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999
168	U axis movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999
169	U axis movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999
170	V axis movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999
171	V axis movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999
172	W axis movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999
173	W axis movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999
174	R axis movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999
175	R axis movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999
176	Output method	Set/Get	0: Absolute position 1: Relative position

Movement Multi Points

Calculate the movement amount of each axis of the external device necessary to adjust the measurement position to the reference position. Set the measurement position and reference position using an arithmetic expression.

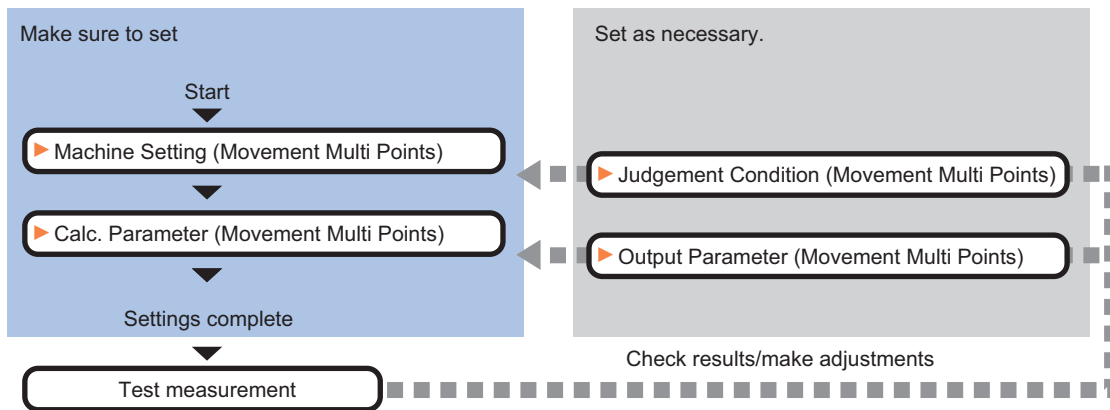
Used in the Following Case

- When you want to position the FPD panel



Settings Flow (Movement Multi Points)

Set the axis movement amount calculation following the procedure below.



List of Movement Multi Points Items

Item name	Description
Machine setting	Select the processing items (stage or robot data) containing information about external device necessary to calculate the axis movement amount. Reference: ▶ Machine Setting (Movement Multi Points) (p.694)
Calc. parameter	Set the reference position and measurement position using an arithmetic expression. Reference: ▶ Calc. Parameter (Movement Multi Points) (p.695)
Judgement condition	This item specifies the judgement condition for measurement results. Reference: ▶ Judgement Condition (Movement Multi Points) (p.699)
Output parameter	This item can be changed if necessary. Set whether or not the judgement results of this processing unit is reflected in the scene overall judgement. Reference: ▶ Output Parameter (Movement Multi Points) (p.700)

Machine Setting (Movement Multi Points)

Select a processing item (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.

- 1** In the Item Tab area, click [Machine setting].
- 2** Select the reference scene No. and reference unit No.

Information of the selected processing unit is displayed in the reference data display area.

Setting item	Setting value [Factory default]	Description
Reference scene No.	[Present scene] Scenes 0 to 127	Select a scene number (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.
Reference unit No.	-	From among the referenced scene numbers, select a processing item (stage data or robot data) under which external device information needed for calculation of axis movement amount is held.

Note

- If the number of scenes is increased using the scene group conversion tool, the maximum value that can be selected in "Reference scene No." changes.

Calc. Parameter (Movement Multi Points)

Set the reference position and measurement position using an arithmetic expression.
The displayed parameters differ depending on the selected stage type.

- 1 Click [Calc. parameter] in the Item Tab area.
- 2 Select the measurement method in the "Measure type" area.

Setting item	Setting value [Factory default]	Description
Measure type	<ul style="list-style-type: none"> • [Points alignment] • Side measure 	<p>Select the measurement method for the maximum error in the judgement condition.</p> <ul style="list-style-type: none"> • Points alignment Calculate the movement amount from the measurement position to the reference position based on the support position information. It is suitable when distances between all points should be within a specified value. • Side measure Alignment method based on the edges of the workpiece. This method could be used when "No alignment mark" or "Workpiece angle cannot be measured" exists.

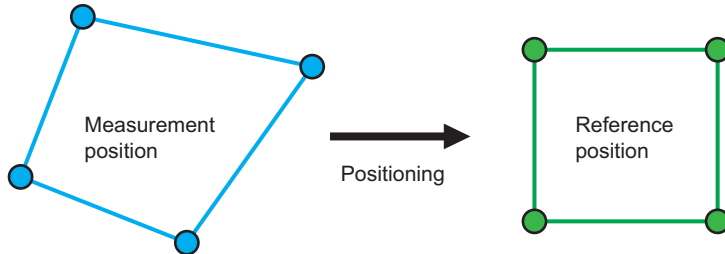
Points alignments

- 1 Set the reference position and measurement position in the "Position setting" area.

Setting item	Setting value [Factory default]	Description
Point number	2 to 8 [4]	Set the number of points
Ref.position X	[-]	Set the X coordinate of the reference position.
Ref.position Y	[-]	Set the Y coordinate of the reference position.
Measure position X	[-]	Set the X coordinate of the measurement position.
Measure position Y	[-]	Set the Y coordinate of the measurement position.

- 2 Set each item in the "Matching method" area.

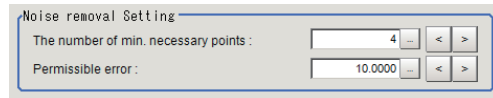
Setting item	Setting value [Factory default]	Description
Matching method	<ul style="list-style-type: none"> • [Least square method] • Maximum error minimization 	<ul style="list-style-type: none"> • Least square method Execute positioning as sum of squares of errors in all points (*) become the minimum. • Maximum error minimization Execute positioning as the maximum value of the errors in all points (*) become the minimum. * Errors in all points ... Distance between the reference position and the measurement position



Positioning result image

<p><u>Least square method</u></p> <p>The sum of squares of errors become the minimum. Reduces effects of noise point.</p>	<p><u>Maximum error minimization</u></p> <p>The maximum value of errors of all points become the minimum. Points with extremely large errors are not generated.</p>
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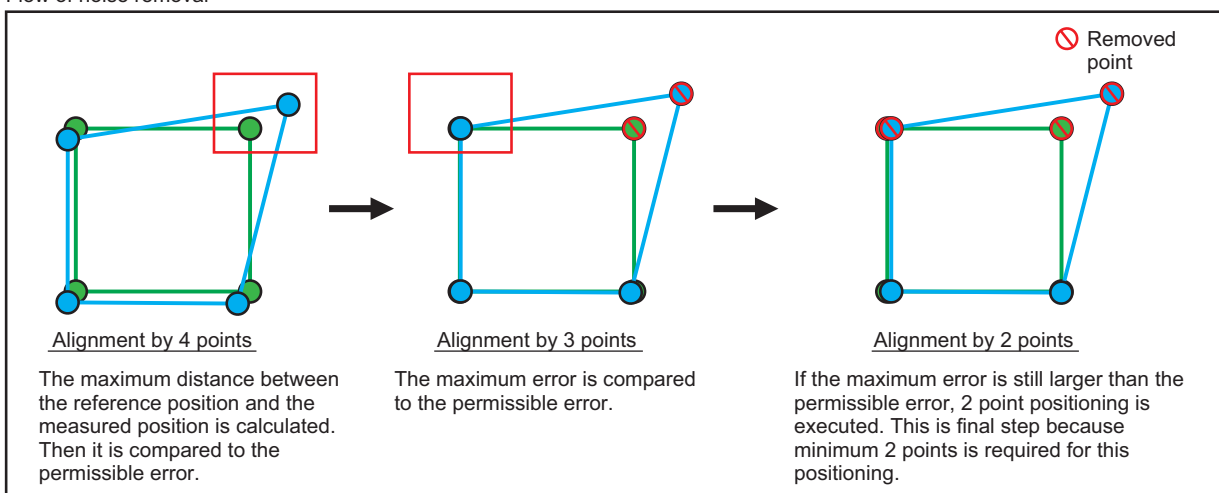
3 Set the noise reduction method in the "Noise removal Setting" area.



Setting item	Setting value [Factory default]	Description
The number of min. necessary points	2 to 8 [4]	This means the available mark number after the noise point removal. For example, when you need minimum 3 points for positioning and set 4 as a number of points in "Position setting" area, maximum 1 point could be removed as a noise.
Permissible error	0 to 99999.9999 [10.0000]	Set allowable error (distance of measurement position and reference position) is set. Calibrate by removing the noise points repeatedly until the required minimum number of points is reached.

The noise removal flow is explained by using a sample case that the required minimum points is 2 points, and that the allowable error is 10.0.

Flow of noise removal



4 Set the current axis position.

Set the axis position of an external device.

Side measurement

- 1 Set a number of points, measurement axis, reference position, and measurement position in the "Position setting" area.

Setting item	Setting value [Factory default]	Description
Point number	3 to 8 [5]	Set a number of sides to be measured.
Measure axis	<ul style="list-style-type: none"> • [X-axis side 1] • X-axis side 2 • Y-axis side 1 • Y-axis side 2 	Set the measurement axis.
Ref. position X	-	Set the X coordinate of the reference position.
Ref. position Y	-	Set the Y coordinate of the reference position.
Measure position X	-	Set the X coordinate of the measurement position.
Measure position Y	-	Set the Y coordinate of the measurement position.

- 2 In "Angle setting" area, specify the measurement axis and setting type.

Setting item	Setting value [Factory default]	Description
Measure axis	<ul style="list-style-type: none"> • [X-axis] • Y-axis 	Set a number of sides to be measured.
Method	<ul style="list-style-type: none"> • [2 points setting] • Calculation setting 	Set the method for angle specification.
Point 0	-	When the 2 points setting is selected for the method, specify two points to measure the angle. Select from the points specified in "Position setting" area.
Point 1	-	
Ref. angle	-	When the 2-point specification is selected for the method, set the reference angle and the measurement angle by the expression.
Measure angle	-	

Judgement Condition (Movement Multi Points)

This item specifies the judgement condition for measurement results.

- 1 In the Item Tab area, click [Judgement condition].
- 2 In the "Judgement condition" area, set each item.

If the reference data is the UVWR stage

The following parameters are displayed in this menu based on the stage type.

Displayed content	Not selected	XY	XYθ	θXY	UVW	UVWR	3 axes	4 axes
X axis movement amount Judgement upper/lower limit values	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	×	×	<input type="radio"/>	<input type="radio"/>
Y axis movement amount Judgement upper/lower limit values	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	×	×	<input type="radio"/>	<input type="radio"/>
θ axis angle movement amount Judgement upper/lower limit values	<input type="radio"/>	×	○ (*1)	○ (*1)	×	×	×	<input type="radio"/>
θ axis linear movement amount Judgement upper/lower limit values	×	×	○ (*2)	○ (*2)	×	×	×	×
U axis movement amount Judgement upper/lower limit values	×	×	×	×	○	○	×	×
V axis movement amount Judgement upper/lower limit values	×	×	×	×	○	○	×	×
W axis movement amount Judgement upper/lower limit values	×	×	×	×	○	○	×	×
R axis movement amount Judgement upper/lower limit values	×	×	×	×	×	○	×	×

○: Show, ×: Hide

*1 Displayed only when the θ axis type is direct drive.

*2 Displayed only when the θ axis type is linear drive.

Output Parameter (Movement Multi Points)

Set how the coordinates output to external equipment as measurement results are treated. Change this item as needed. Normally, the factory default value will be used.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Specify each of the following items.

Setting item	Setting value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Specify whether or not the judgement results of this processing unit is reflected in the scene overall judgement.
Output type	<ul style="list-style-type: none"> • [Opposite moving] • Absolute moving 	Opposite moving: Calculates the movement amount from the current axis position. Absolute moving: Calculates the movement amount from the origin.

Key Points for Test Measurement and Adjustment (Movement Multi Points)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
X axis movement	X axis movement amount
Y axis movement	Y axis movement amount
θ axis angle movement	θ axis angle movement amount (*)
θ axis movement	θ axis movement amount (*)
U axis movement	U axis movement amount
V axis movement	V axis movement amount
W axis movement	W axis movement amount
R axis movement	R axis movement amount
Position X difference	Position X difference
Position Y difference	Position Y difference
Angle difference	Angle difference
Maximum error	Maximum error

* The displayed contents differ depending on the stage type.

Output contents	XY	XY θ	θ XY	UVW	UVWR	3 axes	4 axes
θ axis angle movement amount	×	○	○				○
θ axis movement amount	×	○ (θ axis linear drive)	×	×	×	×	×

○: Show, ×: Hide

Key Points for Adjustment

Select the adjustment method referring to the following points.

When the measurement results are false

State	Parameter to be adjusted	Troubleshooting
The sign of the measurement result (positive/negative) that has been output is opposite.	-	The reference position and measurement position may be set in reverse. The axis movement amount calculates the movement amount from the measurement position to the reference position.

Other

State	Parameter to be adjusted	Troubleshooting
The reference unit number is <"None"> and cannot be selected.	Machine setting	Check if the reference scene number is selected correctly. Check if stage data processing items or robot data processing items are registered in the selected reference scene.
The reference unit number does not follow during flow editing.	Machine setting	The system is designed this way. While a scene other than the current scene is referenced, the reference unit number does not change according to the editing of the flow. Change the flow so that the current scene will be referenced, or set the reference unit number again.

Measurement Results for Which Output Is Possible (Movement Multi Points)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Displayed item	Character string	Description
Judge	JG	Judgement result
X axis movement	MX	X axis movement amount
Y axis movement	MY	Y axis movement amount
θ axis angle movement	MT	θ axis angle movement amount (*)
θ axis (linear drive)	ML	θ axis movement amount (*)
U axis movement	MU	U axis movement amount
V axis movement	MV	V axis movement amount
W axis movement	MW	W axis movement amount
R axis movement	MR	R axis movement amount
Position X difference	DX	Position X difference
Position Y difference	DY	Position Y difference
Angle difference	DT	Angle difference
Error max.	MAXE	Maximum error
Error min.	MINE	Minimum error
Error ave.	AVEE	Average error
Number of removed points	RPN	Number of removed points

* The contents that can be output differ depending on the stage type.

Output contents	XY	XYθ	θXY	UVW	UVWR	3 axes	4 axes
θ axis angle movement amount	×	○	○				○
θ axis movement amount	×	○ (θ axis linear drive)	×	×	×	×	×

○: Output, ×: Do not output

External Reference Tables (Movement Multi Points)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	X axis movement amount	Get only	-
6	Y axis movement amount	Get only	-
7	θ axis angle movement amount	Get only	-180.0000 to 180.0000
8	θ axis linear movement amount	Get only	-
9	U axis movement amount	Get only	-
10	V axis movement amount	Get only	-
11	W axis movement amount	Get only	-
12	R axis movement amount	Get only	-
13	Position X difference	Get only	-
14	Position Y difference	Get only	-
15	Angle difference	Get only	-
16	Maximum error	Get only	-
17	Minimum error	Get only	-
18	Average error	Get only	-
19	Number of removed points	Get only	-
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	External device reference scene number	Set/Get	-1: Reference the current scene 0 to 9999: Reference the scene of the specified number
121	External device data reference unit number	Set/Get	-1: No reference unit 0 to 9999: Reference the unit of the specified number
122	Measurement method	Set/Get	0: Side line measurement 1: Support point alignment
123	Expression for the reference angle	Set/Get	Exp. character string
124	Expression for the measurement angle	Set/Get	Exp. character string
125	Measurement axis	Set/Get	0 to 1
126	Specification method	Set/Get	0 to 1
127	Point 0	Set/Get	-1 to 7
128	Point 1	Set/Get	-1 to 7

No.	Data name	Set/Get	Data range
129	Number of measured side lines	Set/Get	3 to 8
130	Number of support point alignments	Set/Get	2 to 8
131	Minimum number of required points	Set/Get	2 to 8
132	Allowable error	Set/Get	0 to 99999.9999
133	Error judgment upper limit value	Set/Get	0 to 99999.9999
134	Combination method	Set/Get	0: Minimum square method 1: Minimizing the maximum error
150	Current X axis movement amount	Set/Get	Exp. character string
151	Current Y axis movement amount	Set/Get	Exp. character string
152	Current θ axis angle movement amount	Set/Get	Exp. character string
153	The current θ axis linear movement amount	Set/Get	Exp. character string
154	Current U axis movement amount	Set/Get	Exp. character string
155	Current V axis movement amount	Set/Get	Exp. character string
156	Current W axis movement amount	Set/Get	Exp. character string
157	Current R axis movement amount	Set/Get	Exp. character string
160	X axis movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999
161	X axis movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999
162	Y axis movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999
163	Y axis movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999
164	θ axis angle movement amount judgement upper limit value	Set/Get	-180.0000 to 180.0000
165	θ axis angle movement amount judgement lower limit value	Set/Get	-180.0000 to 180.0000
166	θ axis linear movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999
167	θ axis linear movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999
168	U axis movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999
169	U axis movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999

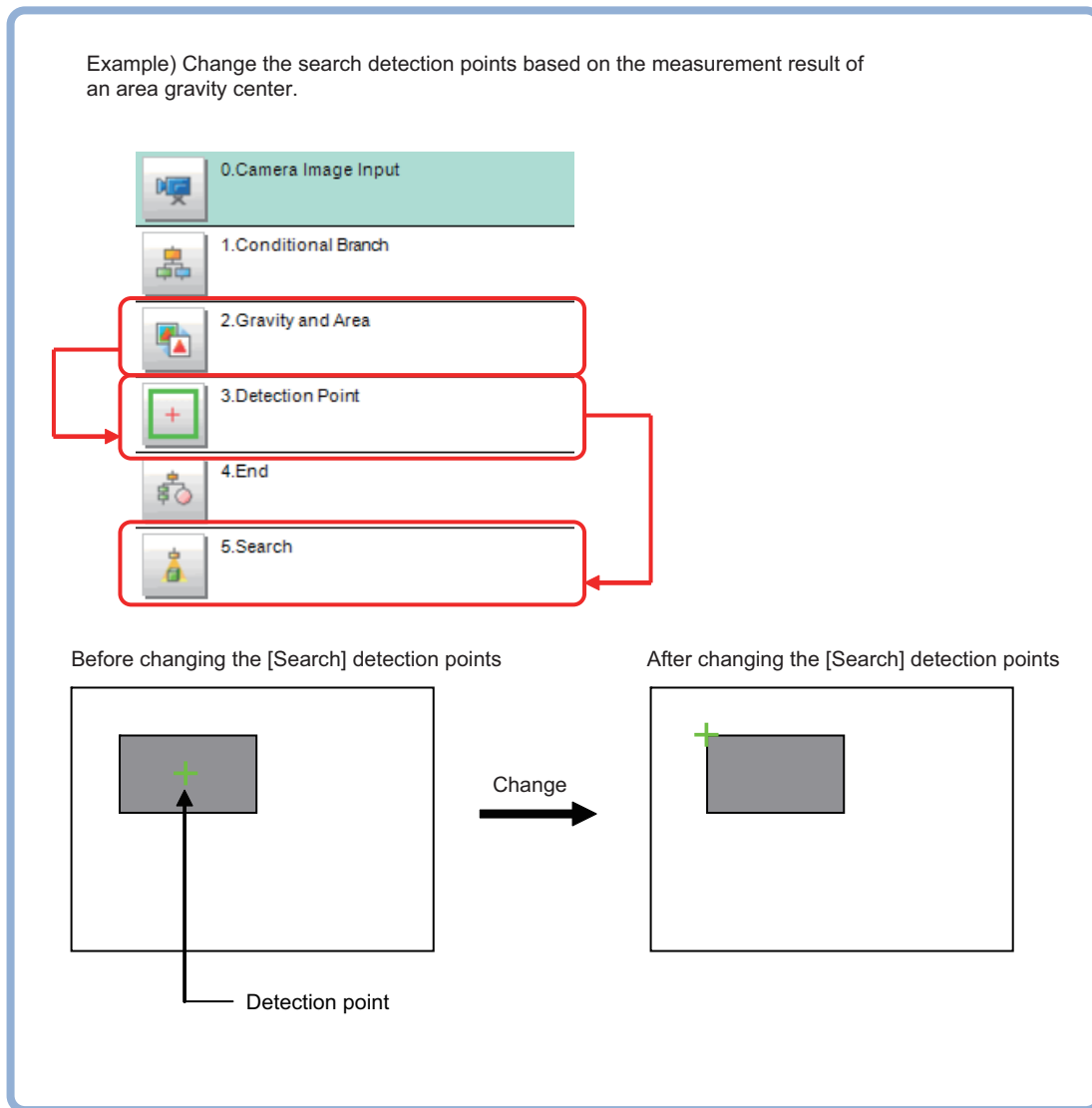
No.	Data name	Set/Get	Data range
170	V axis movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999
171	V axis movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999
172	W axis movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999
173	W axis movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999
174	R axis movement amount judgement upper limit value	Set/Get	-99999.9999 to 99999.9999
175	R axis movement amount judgement lower limit value	Set/Get	-99999.9999 to 99999.9999
176	Output method	Set/Get	0: Absolute position 1: Relative position
200 + N × 1 (N = 0 to 7)	Expression for the reference position coordinate X (N = 0 to 7)	Set/Get	Exp. character string
300 + N × 1 (N = 0 to 7)	Expression for the reference position coordinate Y (N = 0 to 7)	Set/Get	Exp. character string
400 + N × 1 (N = 0 to 7)	Expression for the measurement position coordinate X (N = 0 to 7)	Set/Get	Exp. character string
500 + N × 1 (N = 0 to 7)	Expression for the measurement position coordinate Y (N = 0 to 7)	Set/Get	Exp. character string
600 + N × 1 (N = 0 to 7)	Measurement axis N (N = 0 to 7)	Set/Get	Measurement axis (N = 0 to 7) 0: X axis side line 1 1: X axis side line 2 2: Y axis side line 1 3: Y axis side line 2

Detection Point

Obtains position/angle information by referring to the coordinate values measure with the Measurement Processing Unit. Measurement can be performed based on precise detection points and reference position data by making the Measurement Processing Unit with the detection point and reference position data refer to the Detection Point Processing Unit.

Used in the Following Case

- When using the measurement result of another Processing Unit as a detection point



Parameter Setting (Detection Point)

Set how to acquire position/angle data necessary to set detection points.

- 1 Select the setting method for detection points in the [Setting type] area.

Setting item	Setting value [Factory default]	Description
Setting type	[Nearest unit]	Calculate the position and angle used as the detection point from data in the previous Processing Unit. If the previous Processing Unit has not calculation strings X/Y, judgement in this Processing Unit will be NG during measurement.
	Calculation	Calculate the position and angle used as the detection point using the calculation formula. Selecting the arithmetic expression enables the "Position/Angle" area.

When you choose [Calculation] as the setting method.

- 2 Set the position and angle used as the detection point in the [Position angle] area using the arithmetic expression.

Reference: ▶ Layout of Setting Expression Window (p.535)

- 3 The position/angle values used as the detection point can be confirmed in the [Setting data] area.

The calculation result specified in the [Setting type] and [Position angle] areas is displayed. If the value is not updated, exit the setting screen once and display it again after executing the measurement.

Measurement Results for Which Output Is Possible (Detection Point)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Position X	X	X coordinate of the detection position to be retained
Position Y	Y	Y coordinate of the detection position to be retained
Angle	TH	Detection angle to be retained

External Reference Tables (Detection Point)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Position X	Get only	-99999.9999 to 99999.9999
6	Position Y	Get only	-99999.9999 to 99999.9999
7	Angle	Get only	-180 to 180
120	Method	Set/Get	0: Nearest unit 1: Expression
121	Position X	Set/Get	Exp. character string
122	Position Y	Set/Get	Exp. character string
123	Angle	Set/Get	Exp. character string

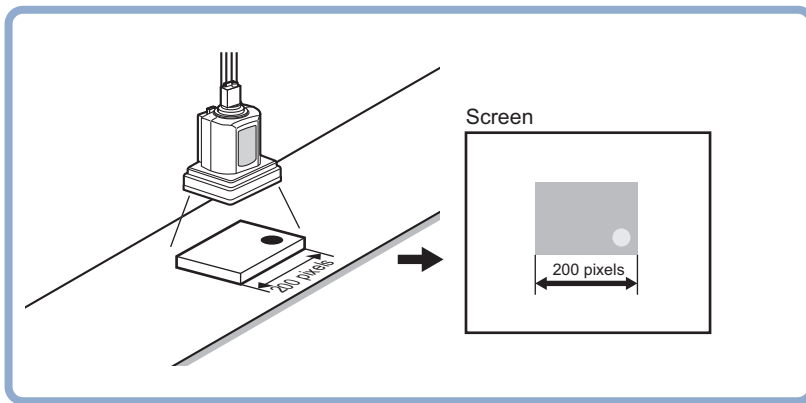
Camera Calibration

By setting the camera calibration, the measurement result can be converted and output as actual dimensions. It allows users to perform more flexible adjustment and edit using the measurement flow compared to the calibration function provided as the camera image input processing item.

- The sampling function can be used in combination with the Measurement Processing Unit in the measurement flow.
- Scaling can be calculated from the measured work width and actual work width.
- Generated calibration data can be adjusted or edited.

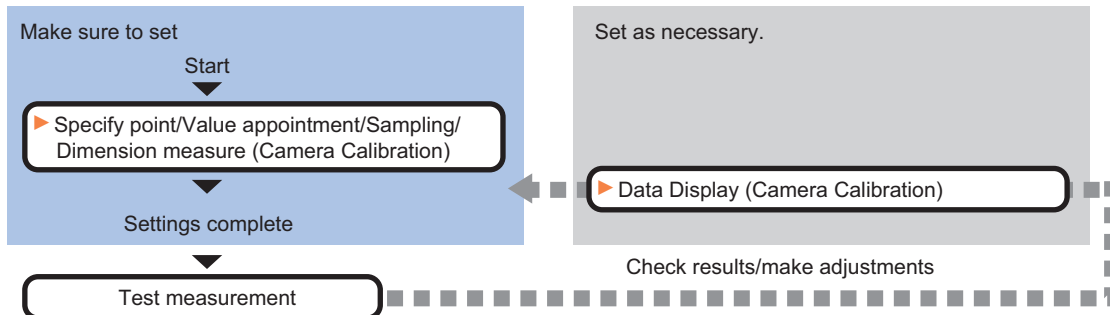
Used in the Following Case

- **When you want to output the measurement result of a Processing Unit as actual dimensions**
Example) When you want to output the measurement result of the Processing Unit as actual dimensions.



Settings Flow (Camera Calibration)

Set the camera calibration with the following steps.



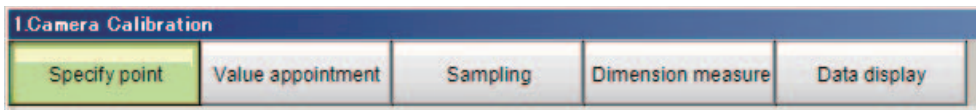
List of Camera Calibration Items

Item name	Description
Specify point	Set a given pixel to make the calibration setting. Calibration parameters are calculated automatically when actual coordinates of specified locations are set. Reference: ▶ Specify point (Camera Calibration) (p.709)
Value appointment	Set the magnification ratio as a numeric value to make the calibration setting. Reference: ▶ Value Appointment (Camera Calibration) (p.711)
Sampling	Make the calibration setting based on the measurement results. After measuring a position using the measurement processing items in the measurement flow, set the position as an actual coordinates to calculate calibration data. Reference: ▶ Sampling (Camera Calibration) (p.712)
Dimension measure	Make the calibration setting based on the measurement results. After measuring work width using the measurement processing items in the measurement flow, set the actual work width to calculate calibration data. Reference: ▶ Dimension Measure (Camera Calibration) (p.714)
Data display	Display the generated calibration data. The calibration data can be adjusted or edited as necessary. Reference: ▶ Data Display (Camera Calibration) (p.716)

Specify point (Camera Calibration)

Specify a given pixel to make the calibration setting. Calibration parameters can be calculated by setting the actual coordinates of specified locations. Up to 100 points can be set.

- 1 In the Item Tab area, click [Specify point].



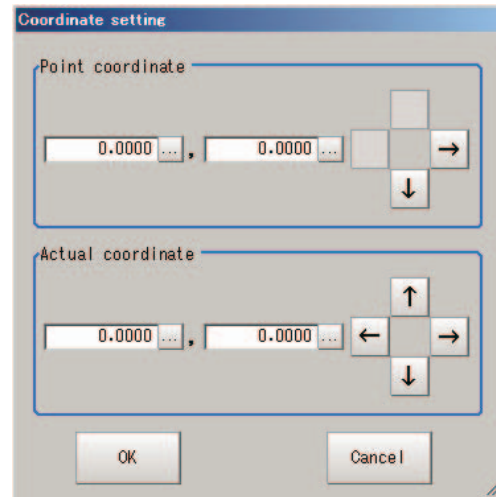
- 2 In the [Display] area, click [Change display] to select the camera image type.

Setting item	Setting value [Factory default]	Description
Display	Through image display	The latest image is always input from the camera and displayed.
	[Freeze image display]	The image that was scanned in the immediately preceding measurement is displayed.

- 3 Click the first point on the screen.

4 Set the actual coordinates for the specified point.

The actual coordinate input window is displayed.



Actual coordinate	Setting value [Factory default]
Point coordinate X, Y	0 to 9999.9999 [Point you clicked in the window]
Actual coordinate X, Y	-99999.9999 to 99999.9999 [0]

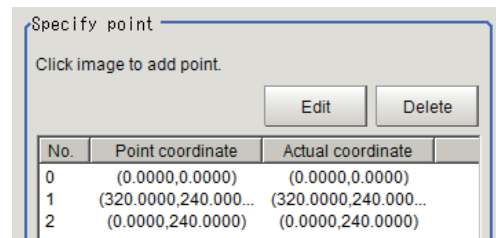
5 Set the 2nd, 3rd and subsequent points in the same way.

6 Edit or delete the coordinates as required.

Select the points to be edited or deleted from the list.

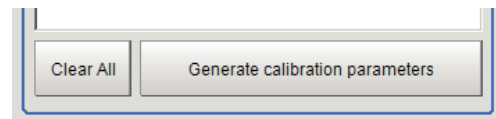
Click [Edit] or [Delete].

To delete all points, click [Clear All].



7 Click [Generate calibration parameters].

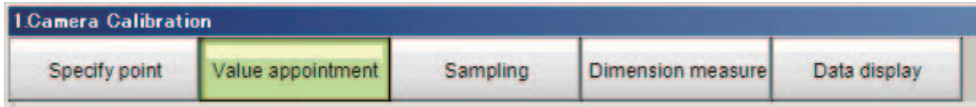
The calibration parameters will be generated.



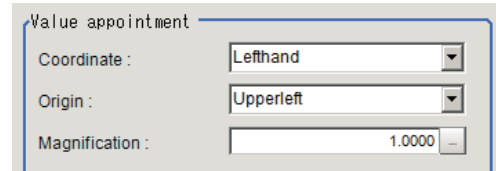
Value Appointment (Camera Calibration)

Set the magnification ratio as a numeric value to make the calibration setting.

1 In the Item Tab area, click [Value appointment].



2 Set the [Value appointment] area.



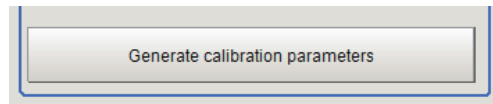
Setting item	Setting value [Factory default]	Description
Coordinate	<ul style="list-style-type: none"> • [Lefthand] • Righthand 	<p>Left-hand type</p> <p>Right-hand type</p> <p>Lefthand: Clockwise is forward when specifying the coordinates. Righthand: Counter-clockwise is forward when specifying the coordinates.</p>
Origin	<ul style="list-style-type: none"> • [Upperleft] • Lowerleft • Center • Specify point 	<p>Upperleft</p> <p>Lowerleft</p> <p>Select where the origin of the actual coordinates will be.</p>
Magnification	0.0001 to 9.9999 [1.0000]	Specify the ratio of 1 pixel to the actual dimensions.

If "Specify point" is selected for [Origin].

Setting item	Setting value [Factory default]	Description
Camera X and Y	-99999.9999 to 99999.9999 [0]	Set the camera coordinates for a given point. If the origin of the actual coordinates is included in the field of view, measure the origin position of the actual coordinates in advance and set them to the camera coordinates X and Y.
Changed X and Y	-99999.9999 to 99999.9999 [0]	Set the actual coordinate values set as the camera coordinates. If the origin position of the actual coordinates is set as the camera coordinates, set (0.0, 0.0).

3 Click [Generate calibration parameters].

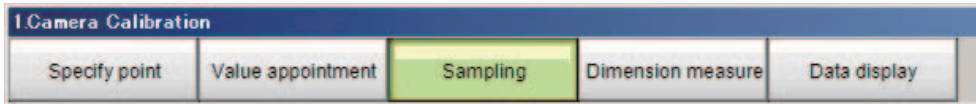
The calibration parameters will be generated.



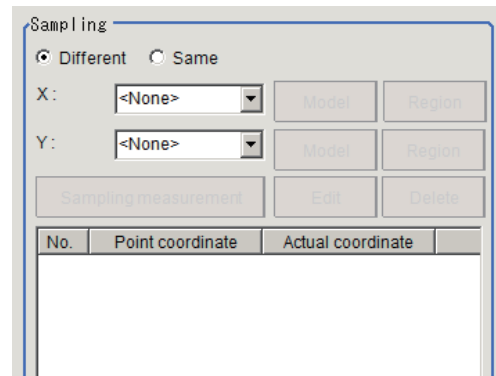
Sampling (Camera Calibration)

Make the calibration setting based on the measurement results. After measuring a position using the measurement processing items in the measurement flow, set the position as an actual coordinates to calculate calibration data.

1 In the Item Tab area, click [Sampling].



2 Set the [Sampling] area.



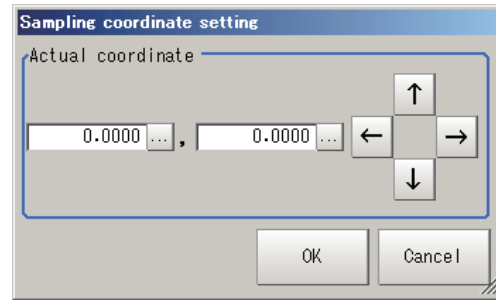
Setting item	Setting value [Factory default]	Description
XY specification method	<ul style="list-style-type: none"> • [Different] • Same 	Different: Set X and Y individually. Same: Use the measurement results of the Processing Unit selected for X specification to specify Y.
X specification	<ul style="list-style-type: none"> • Processing Unit that can measure positions during the measurement flow. • [None] 	Select the Processing Unit in the measurement flow used to sample the X coordinate.
Y specification	<ul style="list-style-type: none"> • Processing Unit that can measure positions during the measurement flow. • [None] 	Select the Processing Unit in the measurement flow used to sample the Y coordinate. If "Same" is specified as the XY specification method, this cannot be selected.

3 Click [Model] and [Region] as needed to set sampling measurement conditions.

4 Click [Sampling measurement].

5 Set the actual coordinates for the specified point.

The actual coordinate input window is displayed.



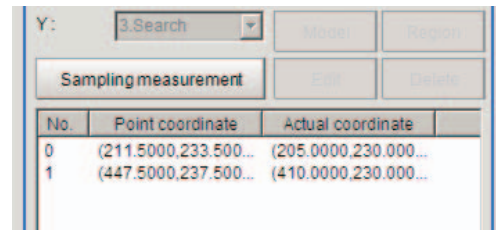
Actual coordinate	Setting value [Factory default]
Actual coordinate X, Y	-99999.9999 to 99999.9999 [0]

The measurement result is added to the list.

6 Set the 2nd, 3rd and subsequent points in the same way.

7 Edit or delete the coordinates as required.

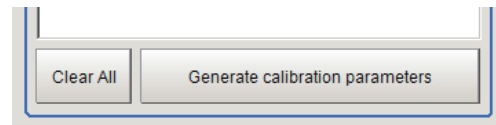
Select the points to be edited or deleted from the list.



Click [Edit] or [Delete].

To delete all points, click [Clear All].

8 Click [Generate calibration parameters].



The calibration parameters will be generated.

Note

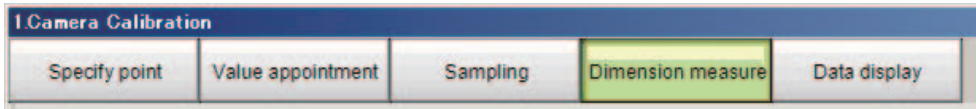
The following processing items can be used for two point measurement in sampling.

- Search
- EC Circle Search
- ECM Search
- Ec Corner
- Ec Cross
- Shape Search II
- Shape Search III
- Edge Position
- Scan Edge Position
- Intersection Coordinates
- Gravity and Area
- Labeling

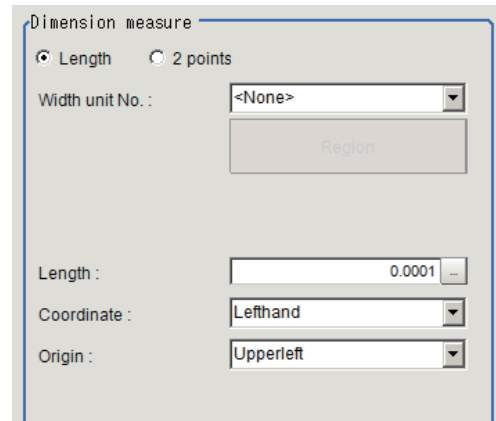
Dimension Measure (Camera Calibration)

Make the calibration setting based on the measurement results. After measuring work width using the measurement processing items in the measurement flow, set the actual work width to calculate calibration data.

1 In the Item Tab area, click [Dimension measure].



2 Set the [Dimension measure] area.



Setting item	Setting value [Factory default]	Description
Dimension measure	<ul style="list-style-type: none"> • [Length] • 2 points 	<p>Length: Measures dimensions using the measurement results of the Processing Unit that measures the width. The width reference unit selection and area measurement buttons are displayed.</p> <p>2 points: Measures dimensions using the measurement results of the processing unit that measures points. The select point reference units 1/2 and area measurement buttons are displayed.</p>
Length	0.0001 to 99999.9999 [0.0001]	Set actual dimensions as the work dimensions.
Coordinate	<ul style="list-style-type: none"> • [Lefthand] • Righthand 	<p>Lefthand: Clockwise is forward when specifying the coordinates.</p> <p>Righthand: Counter-clockwise is forward when specifying the coordinates.</p>
Origin	<ul style="list-style-type: none"> • [Upperleft] • Lowerleft • Center • Specify point 	<p>Select where the origin of the actual coordinates will be.</p>

If "Length" is selected for [Dimension measure].

Setting item	Setting value [Factory default]	Description
Width unit No.	<ul style="list-style-type: none"> Width reference unit in the measurement flow [<None>] 	Select the scan edge width processing unit in the current scene.

If "2 points" is selected for [Dimension measure].

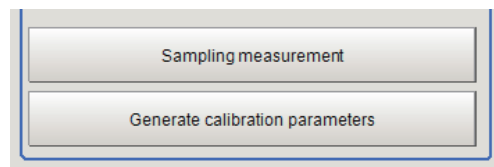
Setting item	Setting value [Factory default]	Description
Point 1 and 2 unit No.	<ul style="list-style-type: none"> Point width measurement unit in the measurement flow [<None>] 	Select the processing unit that can perform point measurement in the current scene.

If "Specify point" is selected for [Origin].

Setting item	Setting value [Factory default]	Description
Camera X and Y	-99999.9999 to 99999.9999 [0]	Set the camera coordinates for a given point. If the origin of the actual coordinates is included in the field of view, measure the origin position of the actual coordinates in advance and set them to the camera coordinates X and Y.
Changed X and Y	-99999.9999 to 99999.9999 [0]	Set the actual coordinate values set as the camera coordinates. If the origin position of the actual coordinates is set as the camera coordinates, set (0.0, 0.0).

3 Click [Region] as needed to set sampling measurement conditions.

4 Click [Sampling measurement].



5 Click [Generate calibration parameters].

The calibration parameters will be generated.

Note

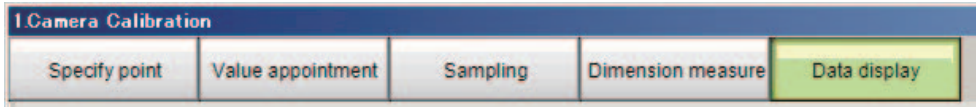
The following processing items can be used for two point measurement in sampling.

- Search
- EC Circle Search
- ECM Search
- Ec Corner
- Ec Cross
- Shape Search II
- Shape Search III
- Edge Position
- Scan Edge Position
- Intersection Coordinates
- Gravity and Area
- Labeling

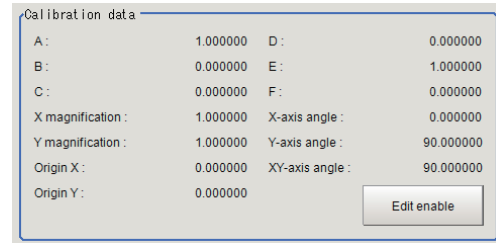
Data Display (Camera Calibration)

Display the generated calibration data. The calibration data can be adjusted or edited as necessary.

- 1 In the Item Tab area, click [Data display].



- 2 In the [Calibration data] area, confirm the calibration data.



Item	Description
A	These are calibration conversion values. Camera coordinates are converted to actual coordinates based on these values. The conversion formulas for actual coordinates are as follows: (X, Y): Measurement point (camera coordinates), Unit: pix (X', Y'): Conversion point (actual coordinates)
B	
C	
D	
E	
F	
X magnification	Magnification ratio for the X axis in the coordinate system after calibration
Y magnification	Magnification ratio for the Y axis in the coordinate system after calibration
Origin X	The origin X position in the coordinate system after calibration
Origin Y	The origin Y position in the coordinate system after calibration
X-axis angle	The X axis angle in the coordinate system after calibration
Y-axis angle	The Y axis angle in the coordinate system after calibration
XY-axis angle	Angle created by the X and Y axes in the coordinate system after calibration.

Edit the calibration result

If, for example, you already know calibration parameters, you can directly edit the generated calibration parameters.

1 Click [Edit disable] in the [Calibration data] area.

This will enable you to edit calibration parameters A to F.

The screenshot shows a dialog box titled "Calibration data" with the following fields and values:

A:	1.000000	D:	0.000000
B:	0.000000	E:	1.000000
C:	0.000000	F:	0.000000
X magnification:	1.000000	X-axis angle:	0.000000
Y magnification:	1.000000	Y-axis angle:	90.000000
Origin X:	0.000000	XY-axis angle:	90.000000
Origin Y:	0.000000		

An "Edit disable" button is located at the bottom right of the dialog box.

2 In the [Calibration data] area, confirm the modification made.

The screenshot shows the same "Calibration data" dialog box as above, but with the "Edit enable" button highlighted at the bottom right.

Compensate the calibration result

The calibration result can be compensated by setting the compensation amounts such as magnification ratios and offsets for the actual dimensions and actual coordinates.

1 Set the compensation values in the [Parameter] area.

The screenshot shows a dialog box titled "Parameter" with the following fields and values:

Corrected X magnification:	1.0000
Corrected Y magnification:	1.0000
Corrected X-axis angle:	0.0000
Corrected Y-axis angle:	0.0000
Origin X offset:	0.0000
Origin Y offset:	0.0000

A "Clear" button is located at the bottom right of the dialog box.

Setting item	Setting value [Factory default]	Description
Corrected X/Y magnification	0.5000 to 1.5000 [1.0000]	Set the compensation amounts for the X axis ratio and Y axis ratio respectively.
Corrected X/Y-axis angle	-180.0000 to 180.0000 [0]	Set the compensation amounts for the X axis angle and Y axis angle respectively.
Origin X/Y offset	-9999.9999 to 9999.9999 [0]	Set the compensation amounts for the X and Y coordinates of the origin respectively.

2 In the [Calibration data] area, confirm the compensation result.

Note

The following relational expressions can be made for calibration parameters and compensation values. Be careful about the relationships between the pre-compensation and post-compensation parameters when adjusting parameters.

Before adjustment: A1, B1, C1, D1, E1, F1

After adjustment: A2, B2, C2, D2, E2, F2

Compensation ratio X: KX, Compensation ratio Y: KY

Compensation angle X: θX , Compensation angle Y: θY

X origin offset setting: OX

Y origin offset setting: OY

- $A2 = KX \times (A1 \times \cos\theta X - D1 \times \sin\theta X)$
- $B2 = KY \times (B1 \times \cos\theta Y - E1 \times \sin\theta Y)$
- $C2 = C1 - OX$
- $D2 = KX \times (A1 \times \sin\theta X + D1 \times \cos\theta X)$
- $E2 = KY \times (B1 \times \sin\theta Y + E1 \times \cos\theta Y)$
- $F2 = F1 - OY$

Measurement Results for Which Output Is Possible (Camera Calibration)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Camera Calibration)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK 2: Judgement result NG
5	Calibration parameter A (after compensation)	Get only	-
6	Calibration parameter B (after compensation)	Get only	-
7	Calibration parameter C (after compensation)	Get only	-
8	Calibration parameter D (after compensation)	Get only	-
9	Calibration parameter E (after compensation)	Get only	-
10	Calibration parameter F (after compensation)	Get only	-
11	X magnification ratio (after compensation)	Get only	-
12	Y magnification ratio (after compensation)	Get only	-
13	Origin X (after compensation)	Get only	-
14	Origin Y (after compensation)	Get only	-
15	X axis angle (after compensation)	Get only	-
16	Y axis angle (after compensation)	Get only	-

No.	Data name	Set/Get	Data range
17	XY angle (after compensation)	Get only	-
120	Number of point specifications	Set/Get	0 to 100
121	Operational point number	Set/Get	-1 to 99
130	Coordinate	Set/Get	0: Right-hand type 1: Left-hand type
131	Origin	Set/Get	0: Upperleft 1: Lowerleft 2: Center 3: Specify the coordinates
132	Magnification	Set/Get	0.0001 to 9.9999
134	Camera coordinate X	Set/Get	-99999.9999 to 99999.9999
135	Camera coordinate Y	Set/Get	-99999.9999 to 99999.9999
136	Post-conversion coordinate X	Set/Get	-99999.9999 to 99999.9999
137	Post-conversion coordinate Y	Set/Get	-99999.9999 to 99999.9999
140	Number of sampling specifications	Set/Get	0 to 100
141	Operational sampling number	Set/Get	-1 to 99
142	Sampling unit X	Set/Get	-1: OFF 0 to 9999
144	Sampling unit Y	Set/Get	-1: OFF 0 to 9999
146	Maximum number of figure data	Get only	-
147	Sampling mode	Set/Get	0: Individual 1: Global
150	Coordinate	Set/Get	0: Right-hand type 1: Left-hand type
151	Origin	Set/Get	0: Upperleft 1: Lowerleft 2: Center 3: Specify the coordinates
152	Actual width	Set/Get	0.0001 to 99999.9999
154	Camera coordinate X	Set/Get	-99999.9999 to 99999.9999
155	Camera coordinate Y	Set/Get	-99999.9999 to 99999.9999
156	Post-conversion coordinate X	Set/Get	-99999.9999 to 99999.9999
157	Post-conversion coordinate Y	Set/Get	-99999.9999 to 99999.9999
158	Width reference unit	Set/Get	-1: OFF 0 to 9999
159	Point reference unit 1	Set/Get	-1: OFF 0 to 9999
160	Point reference unit 2	Set/Get	Point 2 reference unit No.
161	Dimensional measurement mode	Set/Get	0: Width specification 1: 2-point specification
170	Calibration parameter A (before compensation)	Set/Get	-99999.999999 to 99999.999999
171	Calibration parameter B (before compensation)	Set/Get	-99999.999999 to 99999.999999
172	Calibration parameter C (before compensation)	Set/Get	-99999.999999 to 99999.999999

No.	Data name	Set/Get	Data range
173	Calibration parameter D (before compensation)	Set/Get	-99999.999999 to 99999.999999
174	Calibration parameter E (before compensation)	Set/Get	-99999.999999 to 99999.999999
175	Calibration parameter F (before compensation)	Set/Get	-99999.999999 to 99999.999999
176	X magnification ratio (before compensation)	Get only	-
177	Y magnification ratio (before compensation)	Get only	-
178	Origin X (before compensation)	Get only	-
179	Origin Y (before compensation)	Get only	-
180	X axis angle (before compensation)	Get only	-
181	Y axis angle (before compensation)	Get only	-
182	XY angle (before compensation)	Get only	-
183	Compensation ratio X	Set/Get	0.5000 to 1.5000
184	Compensation Y	Set/Get	0.5000 to 1.5000
185	Compensation angle X	Set/Get	-180.0000 to 180.0000
186	Compensation angle Y	Set/Get	-180.0000 to 180.0000
187	Origin offset X	Set/Get	-9999.9999 to 9999.9999
188	Origin offset Y	Set/Get	-9999.9999 to 9999.9999
200 + N × 1 (N = 0 to 99)	Camera coordinate X for Point N (point specification)	Set/Get	0.0000 to 99999.9999
300 + N × 1 (N = 0 to 99)	Camera coordinate Y for Point N (point specification)	Set/Get	0.0000 to 99999.9999
400 + N × 1 (N = 0 to 99)	Actual coordinate X for Point N (point specification)	Set/Get	-99999.9999 to 99999.9999
500 + N × 1 (N = 0 to 99)	Actual coordinate Y for Point N (point specification)	Set/Get	-99999.9999 to 99999.9999
600 + N × 1 (N = 0 to 99)	Camera coordinate X for sampling N (sampling)	Set/Get	0.0000 to 99999.9999
700 + N × 1 (N = 0 to 99)	Camera coordinate Y for sampling N (sampling)	Set/Get	0.0000 to 99999.9999
800 + N × 1 (N = 0 to 99)	Actual coordinate X for sampling N (sampling)	Set/Get	-99999.9999 to 99999.9999
900 + N × 1 (N = 0 to 99)	Actual coordinate Y for sampling N (sampling)	Set/Get	-99999.9999 to 99999.9999

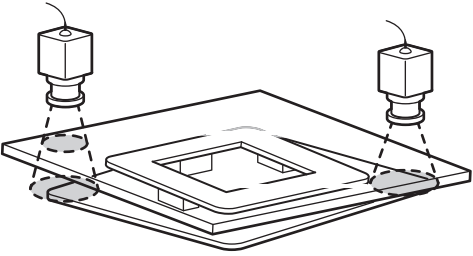
Data Save

Set data that you want to manage or store in units of scenes in this processing item using an arithmetic expression.

The set data can be saved in the controller main unit or as scene data.

Used in the Following Case

- If you want to store measurement values and count values even after powering off the controller



Use example)

- Calculate in a flow without using the reference position of measurement processing unit
→ Retains the calculated reference position.
- To use offset function in an axis movement amount calculation
→ Retains the offset value.

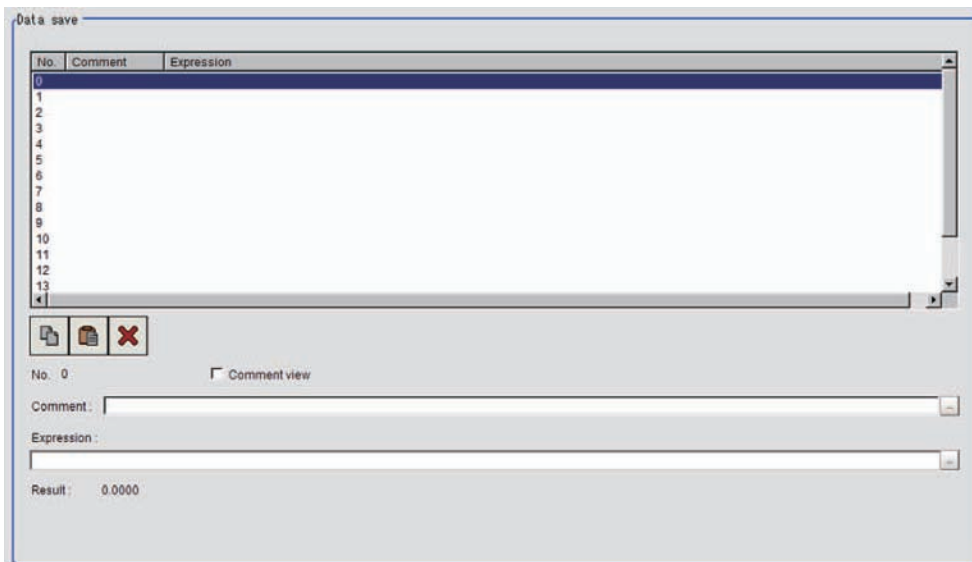
Setting (Data Save)

Set data retained in this processing item.

It can be set freely using expressions.

- 1** In the Item Tab area, click [Setting].
- 2** Set each item in the "Data save" area.

Up to 16 data can be saved.



Setting item	Setting value [Factory default]	Description
Comment	-	Set a comment that describes the expression for the data to be saved.
Expression	-	Set the expression of the data to be saved.

- 3** To display comments in the "Detail result display" area, check "Comment view".

No. 0	<input checked="" type="checkbox"/> Comment view
Comment :	Measure

Key Points for Test Measurement and Adjustment (Data Save)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Judge	Judgement result
Save data N (N = 0 to 15)	Stored data

Key Points for Adjustment

Select the adjustment method referring to the following points.

State	Parameter to be adjusted	Troubleshooting
Saved data is updated unintentionally.	-	Update can be controlled by setting the following flow. Example) 0. Camera image input 1. Input condition branching : N. Measurement completion N+1. Save data Control the DI signal so that it branches to saving data when updating saved data.

Measurement Results for Which Output Is Possible (Data Save)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Save data N (N = 0 to 15)	D00 to D15	Stored data

External Reference Tables (Data Save)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5 + N (N = 0 to 15)	Expression result of expression N (N = 0 to 15)	Get only	-999999999.9999 to 999999999.9999
120 + N (N=0 to 15)	Save data calculation N	Set/Get	Exp. character string (*)
168 + N (N=0 to 15)	Expressions comment N	Set/Get	Character string
200 + N (N=0 to 15)	Comment view N	Set/Get	0:OFF 1:ON

* Numeric data can be set by the processing item of the processing unit data setting.

Branch

This chapter describes setting methods for when branch processing is performed.

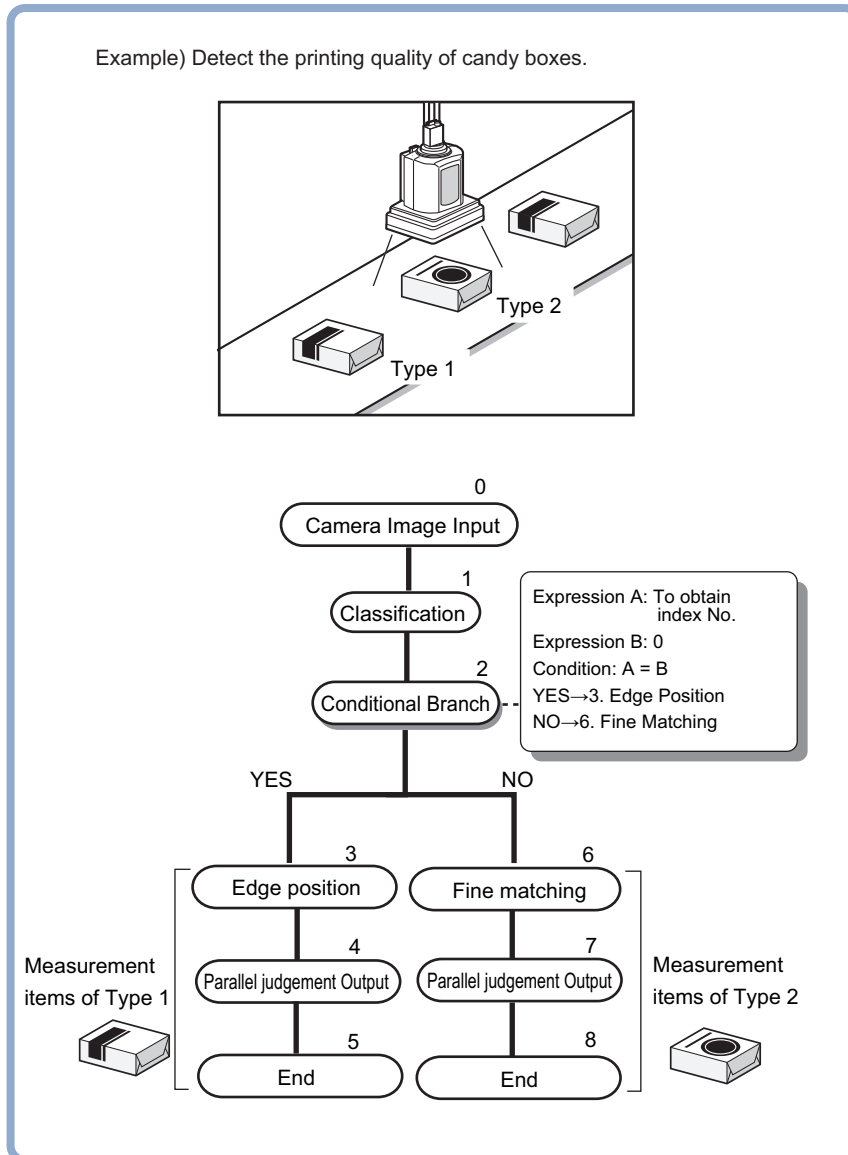
Conditional Branch	724
End.....	728
DI Branch.....	729
Control Flow Normal	731
Control Flow PLC Link.....	734
Control Flow Parallel.....	738
Control Flow Fieldbus.....	741
Selective Branch.....	745

Conditional Branch

Expressions and conditions are set, and processing after this processing item is divided into two according to the comparison calculation.

Used in the Following Case

- When two more types of products are on the production line and inspection is to be performed separately for each



List of Conditional Branch Items

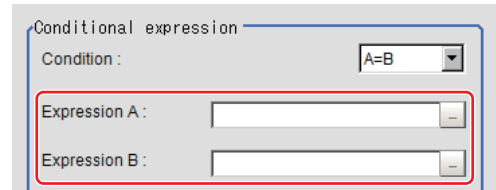
Set	Set value [Factory default]	Description
Condition	<ul style="list-style-type: none"> • $[A = B]$ • $A \leq B$ • $A < B$ • $A \geq B$ • $A > B$ 	Select the method to compare expression A and B. Compare two data items that are obtained through conditional expressions.

Set	Set value [Factory default]	Description
Expression A	Up to 256 characters	Set the evaluation expression that is to be the basis for branching. Set the expression through calculation. Reference: ► Settings (Calculation) (p.533)
Expression B		
Destination unit	YES	• -1: [End processing] • 0 to 32767: unit No.
	NO	• -1: [End processing] • 0 to 32767: unit No.

Conditional Branch

Specify expression A and B for the branching conditions.

1 Set expression A and B separately.



Reference: ► Layout of Setting Expression Window (p.535)

2 Click [icon] to set up conditions.

Condition	Description
A=B	If the value from expression A is equal to that from expression B, moves to the unit in which "Destination unit" is YES. If not, moves to the NO unit.
A<=B	If the value from expression A is equal to that of expression B, or if the value of A is lower than that of B, moves to the unit in which "Destination unit" is "YES". If A is larger, moves to the unit with "NO".
A<B	If the value from expression A is lower than the value from expression B, moves to the unit in which "Destination unit" is YES. If A is equal to or greater than B, moves to the NO unit.
A>=B	If the value from expression A is equal to that of expression B, or if the value of A is higher than that of B, moves to the unit in which "Destination unit" is "YES". If B is higher, moves to the unit with "NO".
A>B	If the value from expression A is higher than the value from expression B, moves to the unit in which "Destination unit" is YES. If A is equal to or less than B, moves to the NO unit.

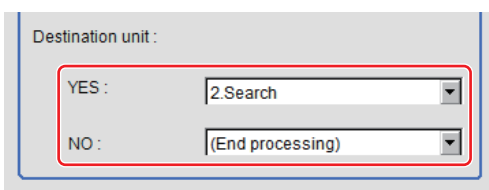
5

Branch

3 Set the branch destination.

Important

- In order to avoid measurement processing looping, for the branch destination, set a processing unit number that is after the [Conditional Branch].
- Make sure to set "End" at the last branch destination to indicate the end of the branch.
Reference: ► End (p.728)



Note

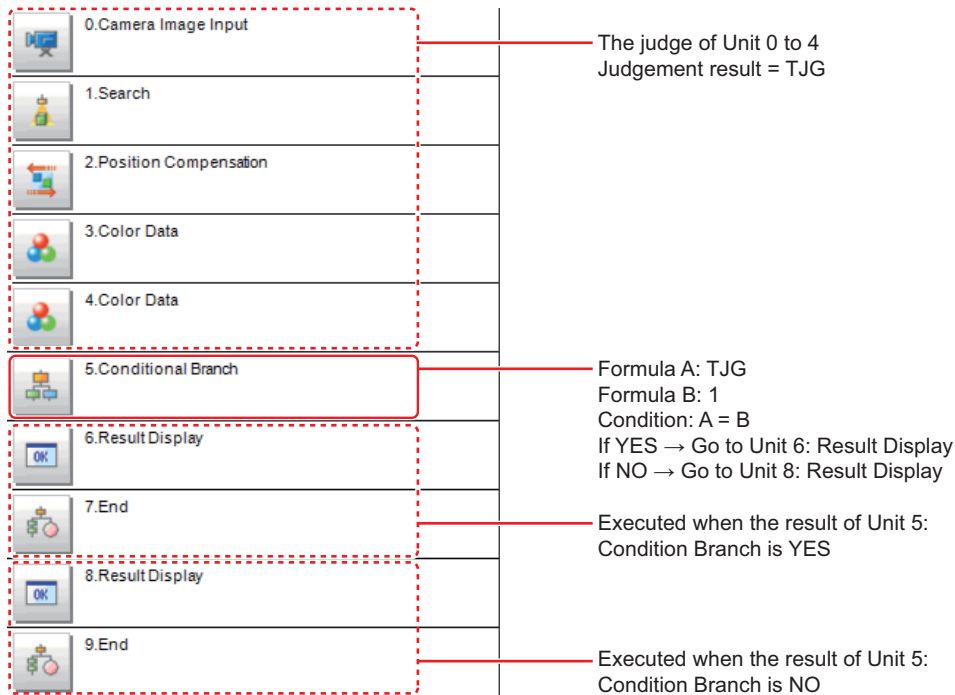
- The judgement result for a processing unit is finalized when that processing unit is processed.
- The overall judgement is finalized when all processing unit measurement is complete.

Conditional Branch Settings Examples

The overall judgement result for processing up to the unit number in which the expression is set is acquired and subsequent measurement is branched according to the result.

For example, condition branching is performed based on the overall judgement result of Units 0 to 4.

Sample Display



1 Set [Conditional Branch] in Unit 5. Set the following expressions in Expression A and B, respectively.

• **Expression A: TJG**

Acquire the overall judgement results from Unit 0 to Unit 4. The overall results based on the judgement results of Unit 0 to Unit 4 are output in the following manner.

Result of unit 0 to unit 4	TJG output
All the unit's judgement results are OK	1
The judgement results of one or more units are NG	-1

• **Expression B: 1**

Set the value that will be compared with the value of A (TJG value).

2 Set the condition of the conditional expression to "A = B".

A = B, which means that TJG = 1, is set as the condition. As a result, if all the unit judgement results from 0 to 4 are OK, then the condition judgement result will be "YES".

3 Set each of the Conditional Branch destinations.

If "Yes", branch to unit 6. If "No", branch to unit 8.

Important

- Parameters for units that do not pass through a conditional branch
The measurement results other than the unit judgement result (JG) retain the measurement results from the previous time the unit passed through the conditional branch. The JG for units that do not pass through the condition branch becomes unmeasured (0). Note, however, that the unit JG becomes unmeasured at the point in time when all the measurement processing ends. During flow processing, the previous time judgement (JG) is retained.

Measurement Results for Which Output Is Possible (Conditional Branch)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Expression A result	D0	Operational result of expression selected in expression A
Expression B result	D1	Operational result of expression selected in expression B
Comparison result	RS	Result from comparing the expressions (0: NO, 1: YES)
Destination unit No.	BU	Unit No. at destination based on the compares results of expressions

External Reference Tables (Conditional Branch)

No.	Data name	Set/Get	Data range
0	Judge	Get	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Expression A result	Get	Maximum 256 characters (result of calculation selected in expression A)
6	Expression B result	Get	Maximum 256 characters (result of calculation selected in expression B)
7	Comparison result	Get	0: NO 1: YES
8	Destination unit No.	Get	0 to 32767
120	Condition type	Set/Get	0: A = B 1: A ≤ B 2: A < B 3: A ≥ B 4: A > B
121	YES branch destination Unit No.	Set/Get	-1: End processing 0 to 32767: unit No.
122	NO Destination Unit No.	Set/Get	-1: End processing 0 to 32767: unit No.
123	Expression A	Set/Get	Expression character string
124	Expression B	Set/Get	Expression character string

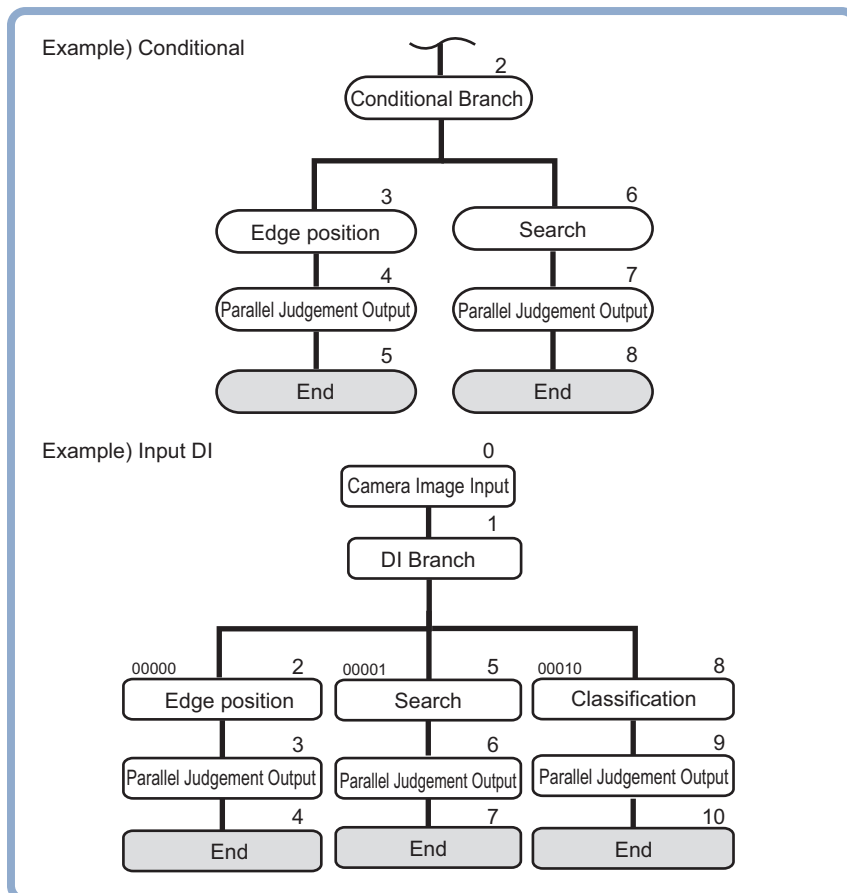
End

This processing item only needs to be added to the scene. Operations such as condition setting are unnecessary.

Please set at the last unit of each branch.

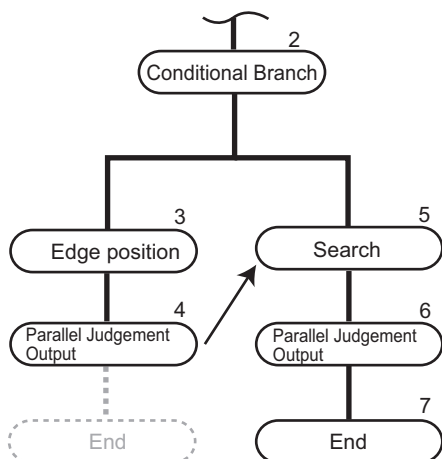
Used in the Following Case

- When finishing the last Processing Item of a branch



Note

- If [End] is not set at the end of a branch, the processing in the scene will continue to move to the next unit No. even if the branch has been completed.

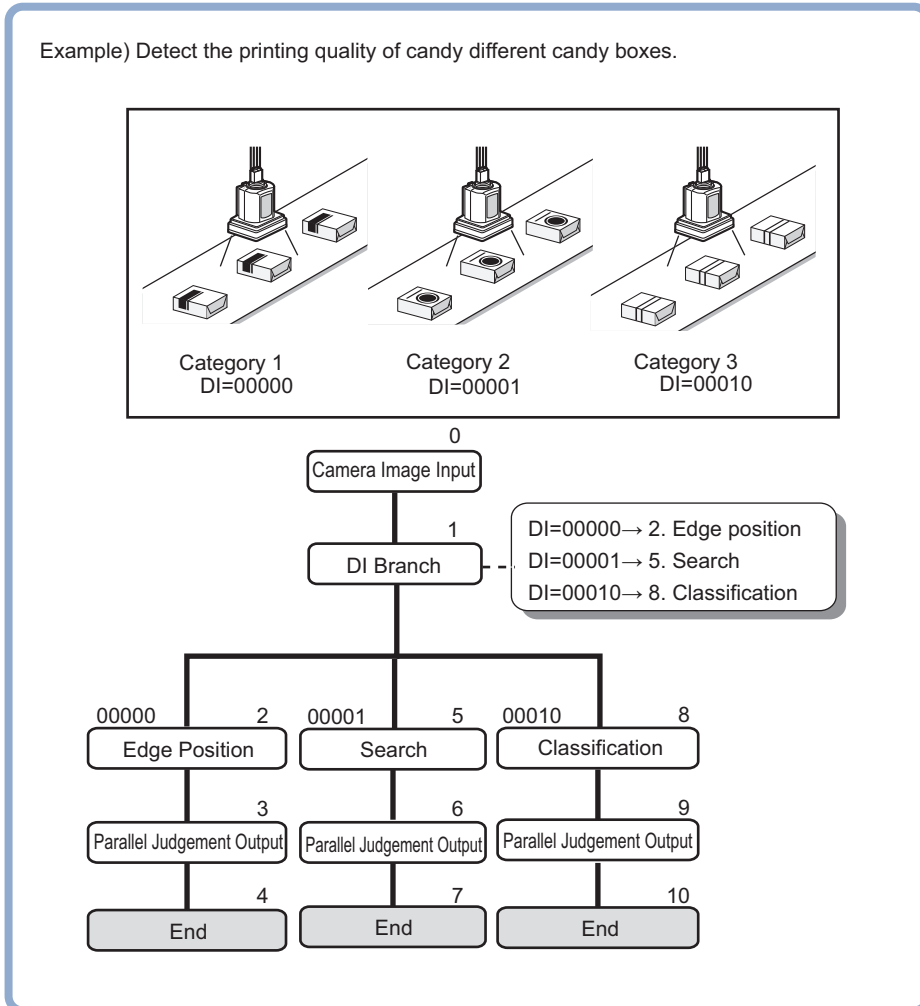


DI Branch

Starting from this processing item, processing is branched according to the information input to terminal blocks DI0 to DI4. Up to 32 branch destinations can be set.

Used in the Following Case

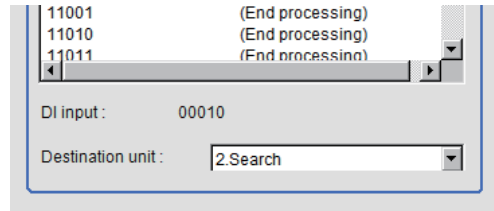
- When products on one production line are to be inspected according to a time interval



Settings (DI Branch)

Select the destination unit. Perform settings according to the information input in DI.

- 1 In the item tab area, click [Setting].
- 2 Click the DI input from the input signal list for which the branch destination is to be set up.
- 3 At "Destination unit", click [▼] and set the destination unit.



Important

- In order to avoid measurement processing looping, for the branch destination, set a processing unit number that is after the [DI Branch].
- Make sure to set "End" at the last branch destination to indicate the end of the branch.
Reference: ► End (p.728)
- If the operation mode (FZ5-11xx) is set to [Multi-line random-trigger mode], DI inputs are handled differently as follows.
Line 0: Conform to the statuses of DI0 and 1 inputs.
Line 1: Conform to the statuses of DI2 and 3 inputs.

- 4 Repeat the steps Reference: ► 2 (p.730) to Reference: ► 3 (p.730) and set the destination units for other input signals.

Note

- Up to 32 (0 to 31) branch destinations can be set.
- The controller references the DI signal when the [DI Branch] measurement is executed.

- 5 Click [OK].

The settings are finalized.

Measurement Results for Which Output Is Possible (DI Branch)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
DI input No.	DI	No. used to indicate DI input (00000 to 11111)
Unit No	BU	Unit number at destination corresponding to DI input

External Reference Tables (DI Branch)

No.	Data name	Set/Get	Data range
0	Judge	Get	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	DI input No.	Get	No. used to indicate DI input (00000 to 11111)
6	Unit No	Get	Unit number at destination corresponding to DI input
120 to 151	Destination Unit No. 0 - Destination Unit No. 31	Set/Get	-1: End processing 0 to 9999: Unit number

Control Flow Normal

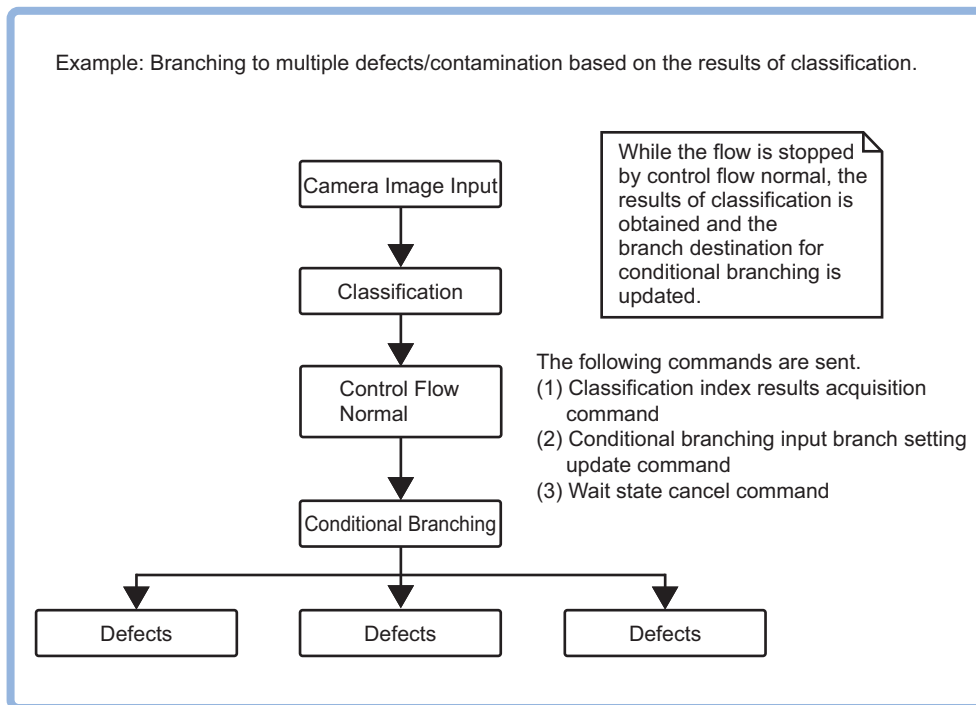
Set the measurement flow processing into the wait state in which the specific command can be executed. There are two methods to clear the wait state: Release with an external reference command or by setting the timeout time.

In the wait state, the following commands can be executed.

Command	Abbreviation	Function
UNITDATA	UD	Acquires the parameters and/or measurement values of specified processing units
UNITDATA	UD	Sets the parameters of specified processing units
BRUNCHSTART	BSU	Branches to the flow head (processing unit No. 0)

Used in the Following Case

- To execute commands during measurement flow processing



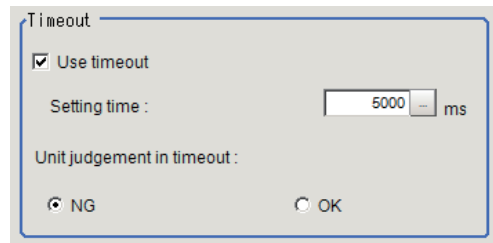
Settings (Control Flow Normal)

Set the communication method and usage of timeout function as follows.

- In the Item Tab area, click [Setting].
- In the Communication Method area, select the communication method.

Setting item	Set value [Factory default]	Description
Communication method	[RS-232C/RS-422]	Communication is performed via RS-232C/RS-422.
	Ethernet	Communication is performed via the Ethernet.

3 In the Timeout area, set the timeout function.



Setting item	Set value [Factory default]	Description
Use timeout	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Place a check here to use the timeout function.
Setting time	0 to 120000 [5000]	Set the timeout time for when you use the timeout function. The unit is milliseconds.
Unit judgment in timeout	<ul style="list-style-type: none"> • [NG] • OK 	Select the unit judgment for a timeout.

Output Parameters (Control Flow Normal)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Choose whether or not to reflect this in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgment results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (Control Flow Normal)

The following content can be confirmed in the "Detail result" area using text.

Displayed item	Description
Judge	Judgement result

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number.	Explanation of image to be displayed
0 to 31	Measurement image

Measurement Results for Which Output Is Possible (Control Flow Normal)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Control Flow Normal)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	State	Get only	0: Flow not stopped 1: Flow stopped
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Timeout	Set/Get	0: Not used 1 : Used
121	Timeout time [ms]	Set/Get	Timeout time (set data)
122	Communication method	Set/Get	0: RS-232C/RS-422 1: Ethernet
123	Unit judgment for a timeout	Set/Get	0: NG 1: OK
5000	Wait state clear command	Setting only	Changing from "0" to "1" clears the wait state. 1: Clear the wait state.

Control Flow PLC Link

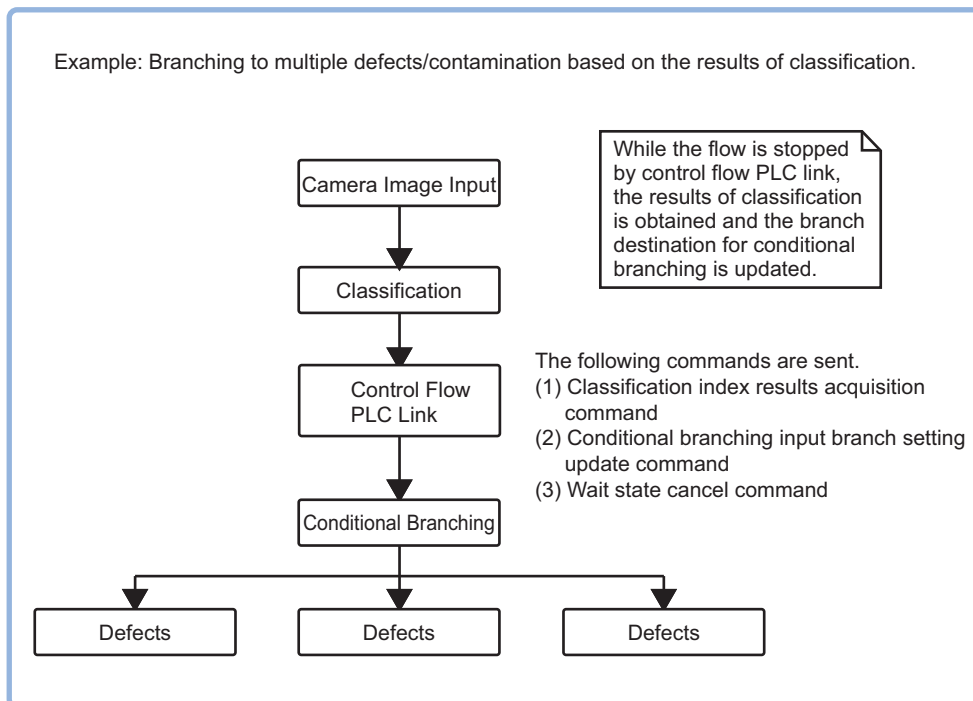
Set the measurement flow processing into the wait state in which the specific command can be executed. There are two methods to clear the wait state: Release with an external reference command or by setting the timeout time.

In the wait state, the following commands can be executed.

Command area top channel		Function
+3	+2	
40	1000	Acquires unit data
50	1000	Sets unit data
10	B010	Branches to the flow head (processing unit No. 0)

Used in the Following Case

- To execute commands during measurement flow processing



Settings (Control Flow PLC Link)

Set the communication method and usage of timeout function as follows.

- 1 In the Item Tab area, click [Setting].
- 2 In the Communication Method area, select the communication method.

Setting item	Set value [Factory default]	Description
Communication method	[RS-232C/RS-422]	Communication is performed via RS-232C/RS-422.
	Ethernet	Communication is performed via the Ethernet.

- 3 In the Timeout area, set the timeout function.

Setting item	Set value [Factory default]	Description
Use timeouts	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Place a check here to use the timeout function.
Setting time	0 to 120000 [5000]	Set the timeout time for when you use the timeout function. The unit is milliseconds.
Unit judgment when timeout occurs	<ul style="list-style-type: none"> • [NG] • OK 	Select the unit judgment for a timeout.

Output Parameters (Control Flow PLC Link)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Choose whether or not to reflect this in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgment results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (Control Flow PLC Link)

The following content can be confirmed in the "Detail result" area using text.

Displayed item	Description
Judge	Judgement result

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number.	Explanation of image to be displayed
0 to 31	Measurement image

Measurement Results for Which Output Is Possible (Control Flow PLC Link)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

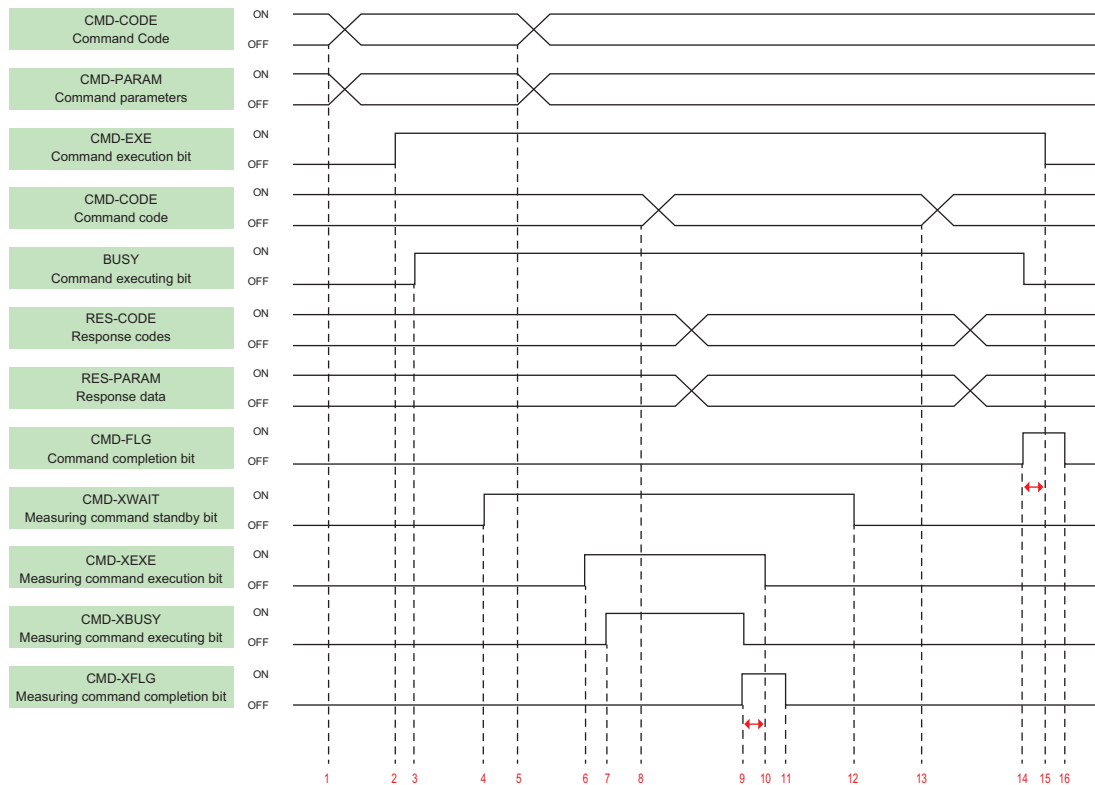
Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Control Flow PLC Link)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	State	Get only	0: Flow not stopped 1: Flow stopped
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Timeout	Set/Get	0: Not used 1 : Used
121	Timeout time [ms]	Set/Get	Timeout time (set data)
122	Communication method	Set/Get	0: RS-232C/RS-422 1: Ethernet
123	Unit judgment for a timeout	Set/Get	0: NG 1: OK
5000	Wait state clear command	Setting only	Changing from "0" to "1" clears the wait state. 1: Clear the wait state.

Timing Chart for Command Execution During Flow (Control Flow PLC Link)

Example: Execute Measurement command → Set Unit Data command (Execution during flow)



1. The PLC sets the command codes and command parameters to execute. (In the example above, the Measure command)
2. The PLC switches ON the command execution bit (EXE).
3. The FZ switches ON the command executing bit (BUSY).
4. When the measurement processing for this processing item is executed in the flow, the FZ switches ON the measuring command standby bit (XWAIT).
5. The PLC sets the command codes and command parameters to execute during measurement. (Unit Data Setting Command)
6. The PLC switches ON the measuring command execution bit (XEXE).
7. The FZ switches ON the measuring command executing bit (XBUSY).
8. The FZ sets the command codes, response codes, and response data executed during measurement.
9. The FZ switches ON the measuring command completion bit (XFLG).
10. The PLC switches OFF the measuring command execution bit (XEXE). Unless you switch to OFF within the retry interval (*), processing proceeds to 11.
11. The FZ switches OFF the measuring command executing bit (XBUSY) and the measuring command completion bit (XFLG).
12. When the measurement processing for this processing item ends, the FZ switches OFF the measuring command standby bit (XWAIT).
13. The FZ sets the executed command codes, response codes, and response data.
14. The FZ switches ON the command completion bit (FLG).
15. The PLC switches OFF the command execution bit (EXE). Unless you switch to OFF within the retry interval (*), processing proceeds to 16.
16. The FZ switches OFF the command executing bit (BUSY) and the command completion bit (FLG).

Control Flow Parallel

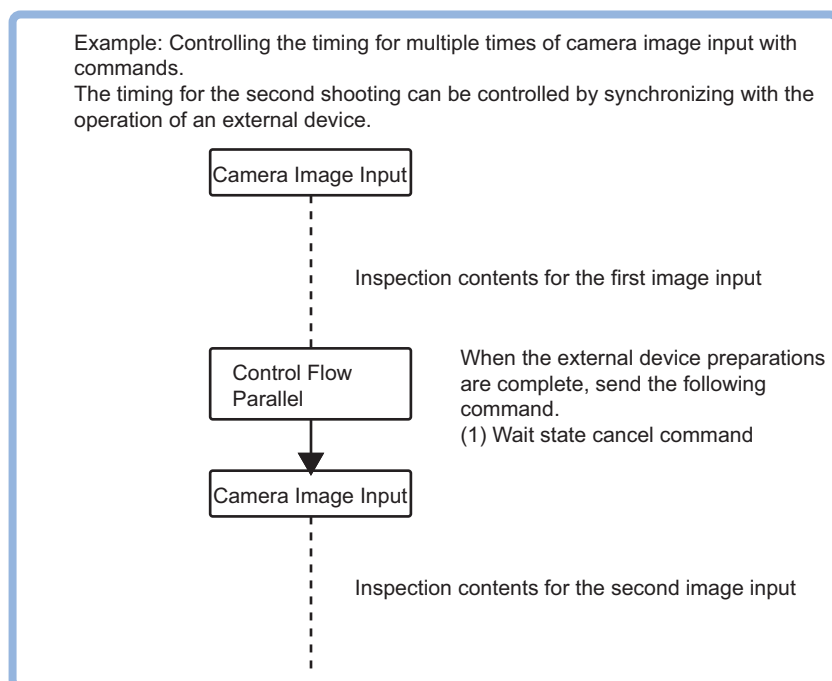
Set the measurement flow processing into the wait state in which the specific command can be executed. There are two methods to clear the wait state: Release with an external reference command or by setting the timeout time.

In the wait state, the following commands can be executed.

Item	Description	Input format (DI7 to DI0)			Input example (DI7 to DI0)
		Execute (DI7)	Command (DI6, DI5)	Command information (DI4 to 0)	
Wait state clear	Clear wait state of control flow parallel processing item.	1	10	01111	11001111

Used in the Following Case

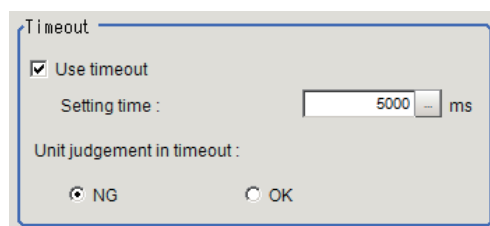
- To execute commands during measurement flow processing



Settings (Control Flow Parallel)

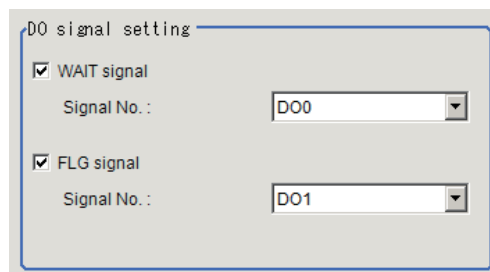
Set the communication method and usage of timeout function as follows.

- 1 In the Item Tab area, click [Setting].
- 2 In the Timeout area, set the timeout function.



Setting item	Set value [Factory default]	Description
Use timeout	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Place a check here to use the timeout function.
Setting time	0 to 120000 [5000]	Set the timeout time for when you use the timeout function. The unit is milliseconds.
Unit judgment in timeout	<ul style="list-style-type: none"> • [NG] • OK 	Select the unit judgment for a timeout.

3 In the DO Allocation Area, select an allocation signal.



Setting item	Set value [Factory default]	Description
WAIT signal	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Check this option if you want to use a signal indicating that a command is available during a measurement flow.
	Signal No.	DO0 (0) to DO15 (15) [DO0]
		This specifies a number that allocates a signal indicating that a command is available during a flow.
FLG signal	<ul style="list-style-type: none"> • [Checked] • Unchecked 	Check this option if you want to use a signal indicating that a command is being executed during a measurement flow.
	Signal No.	DO0 (0) to DO15 (15) [DO1]
		This specifies a number that allocates a signal indicating that a command is being executed during a flow.

Output Parameters (Control Flow Parallel)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Choose whether or not to reflect this in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgment results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (Control Flow Parallel)

The following content can be confirmed in the "Detail result" area using text.

Displayed item	Description
Judge	Judgement result

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number.	Explanation of image to be displayed
0 to 31	Measurement image

Measurement Results for Which Output Is Possible (Control Flow Parallel)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Control Flow Parallel)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	State	Get only	0: Flow not stopped 1: Flow stopped
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Timeout	Set/Get	0: Not used 1: Used
121	Timeout time [ms]	Set/Get	Timeout time (set data)
122	Signal indicating that a command is available during a flow	Set/Get	Signal indicating that a command is available during a flow
123	Signal number indicating that a command is available during a flow	Set/Get	0 to 15, DO0 to DO15
124	Signal indicating that a command is being executed during a flow	Set/Get	Signal indicating that a command is being executed during a flow
125	Signal number indicating that a command is being executed during a flow	Set/Get	0 to 15, DO0 to DO15
126	Unit judgment for a timeout	Set/Get	0: NG 1: OK
5000	Wait state clear command	Setting only	Changing from "0" to "1" clears the wait state. 1: Clear the wait state.

Control Flow Fieldbus

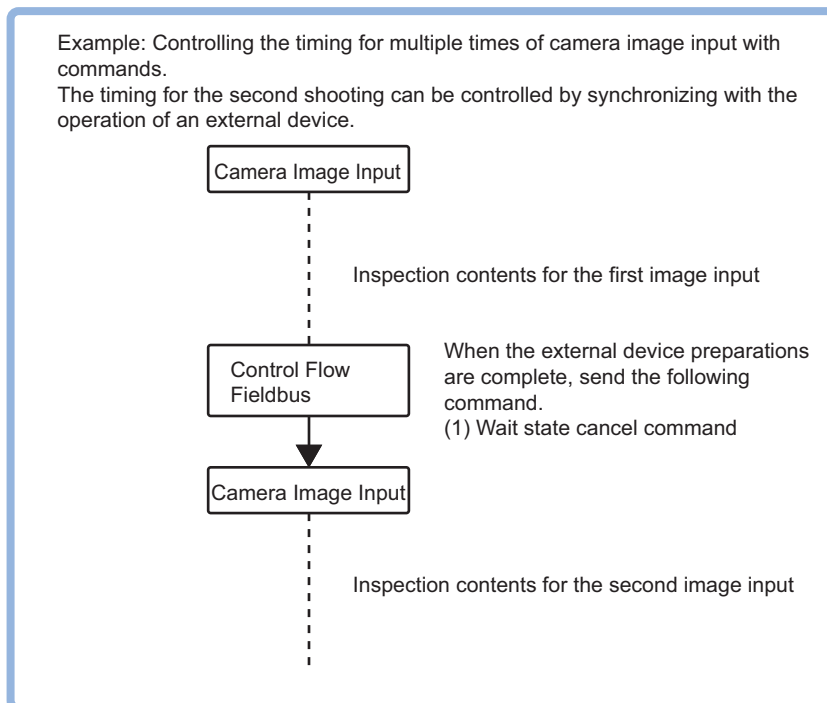
Set the measurement flow processing into the wait state in which the specific command can be executed. There are two methods to clear the wait state: Release with an external reference command or by setting the timeout time.

In the wait state, the following commands can be executed.

Command area top channel		Function
+3	+2	
40	1000	Acquires unit data
50	1000	Sets unit data
10	B010	Branches to the flow head (processing unit No. 0)

Used in the Following Case

- To execute commands during measurement flow processing



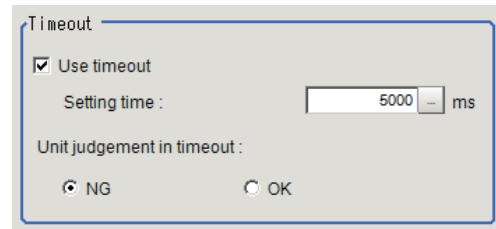
Settings (Control Flow Fieldbus)

Set the communication method and usage of timeout function as follows.

- 1 In the Item Tab area, click [Setting].
- 2 In the Communication Method area, select the communication method.

Setting item	Set value [Factory default]	Description
Command method	[EtherNet/IP]	Communicates with EtherNet/IP.
	EtherCAT	Communicates with EtherCAT. (This cannot be selected in FZ5.)

- 3 In the Timeout area, set the timeout function.



Setting item	Set value [Factory default]	Description
Use timeout	<ul style="list-style-type: none"> • [Checked] • [Unchecked] 	Place a check here to use the timeout function.
Setting time	0 to 120000 [5000]	Set the timeout time for when you use the timeout function. The unit is milliseconds.
Unit judgment in timeout	<ul style="list-style-type: none"> • [NG] • OK 	Select the unit judgment for a timeout.

Output Parameters (Control Flow Fieldbus)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Choose whether or not to reflect this in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgment results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (Control Flow Fieldbus)

The following content can be confirmed in the "Detail result" area using text.

Displayed item	Description
Judge	Judgement result

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number.	Explanation of image to be displayed
0 to 31	Measurement image

Measurement Results for Which Output Is Possible (Control Flow Fieldbus)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

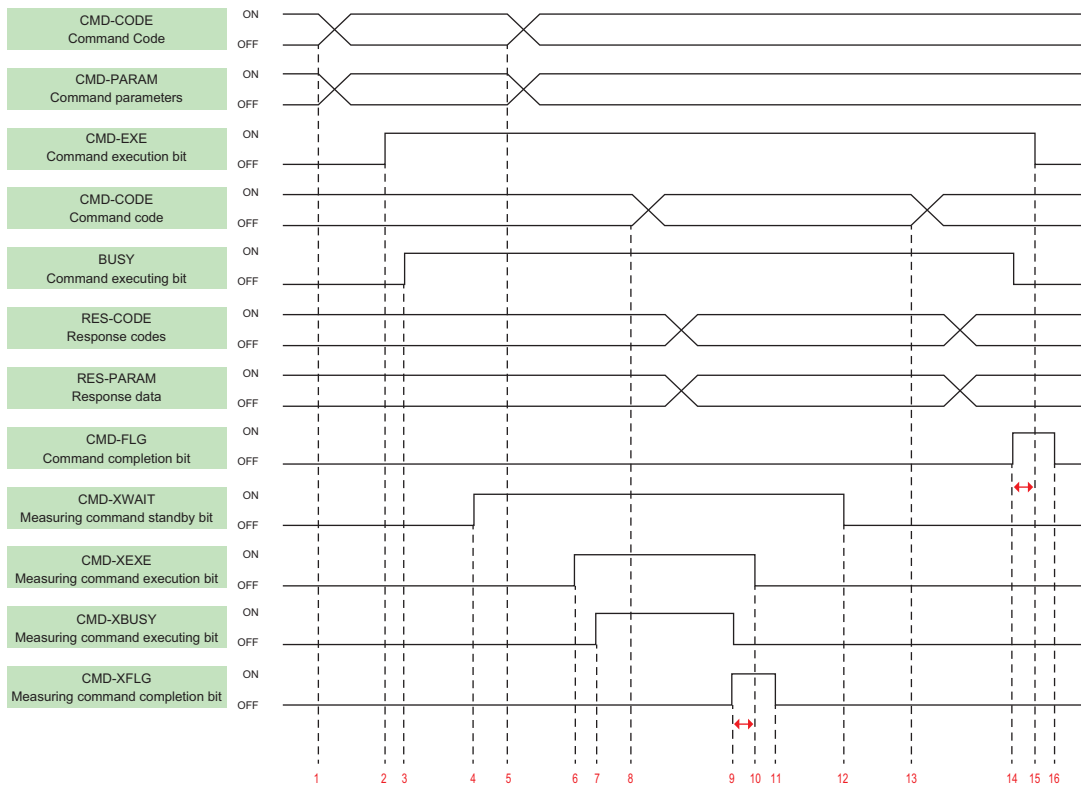
Measurement items	Character string	Description
Judge	JG	Judgement result

External Reference Tables (Control Flow Fieldbus)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	State	Get only	0: Flow not stopped 1: Flow stopped
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Timeout	Set/Get	0: Not used 1 : Used
121	Timeout time [ms]	Set/Get	Timeout time (set data)
122	Communication method	Set/Get	0: EtherNet/IP 1: EtherCAT
123	Unit judgment for a timeout	Set/Get	0: NG 1: OK
5000	Wait state clear command	Setting only	Changing from "0" to "1" clears the wait state. 1: Clear the wait state.

Timing Chart for Command Execution During Flow (Control Flow Fieldbus)

Example: Execute Measurement command → Set Unit Data command (Execution during flow)



1. The PLC sets the command codes and command parameters to execute. (In the example above, the Measure command)
2. The PLC switches ON the command execution bit (EXE).
3. The FZ switches ON the command executing bit (BUSY).
4. When the measurement processing for this processing item is executed in the flow, the FZ switches ON the measuring command standby bit (XWAIT).
5. The PLC sets the command codes and command parameters to execute during measurement. (Unit Data Setting Command)
6. The PLC switches ON the measuring command execution bit (XEXE).
7. The FZ switches ON the measuring command executing bit (XBUSY).
8. The FZ sets the command codes, response codes, and response data executed during measurement.
9. The FZ switches OFF the measuring command executing bit (XBUSY) and switches ON the measuring command completion bit (XFLG).
10. The PLC switches OFF the measuring command execution bit (XEXE). Unless you switch to OFF within the retry interval (*), processing proceeds to 11.
11. The FZ switches OFF the measuring command completion bit (XFLG).
12. When the measurement processing for this processing item ends, the FZ switches OFF the measuring command standby bit (XWAIT).
13. The FZ sets the executed command codes, response codes, and response data.
14. The FZ switches OFF the command executing bit (BUSY) and switches ON the command completion bit (FLG).
15. The PLC switches OFF the command execution bit (EXE). Unless you switch to OFF within the retry interval (*), processing proceeds to 16.
16. The FZ switches OFF the command completion bit (FLG).

* The retry interval is fixed to 10 seconds.

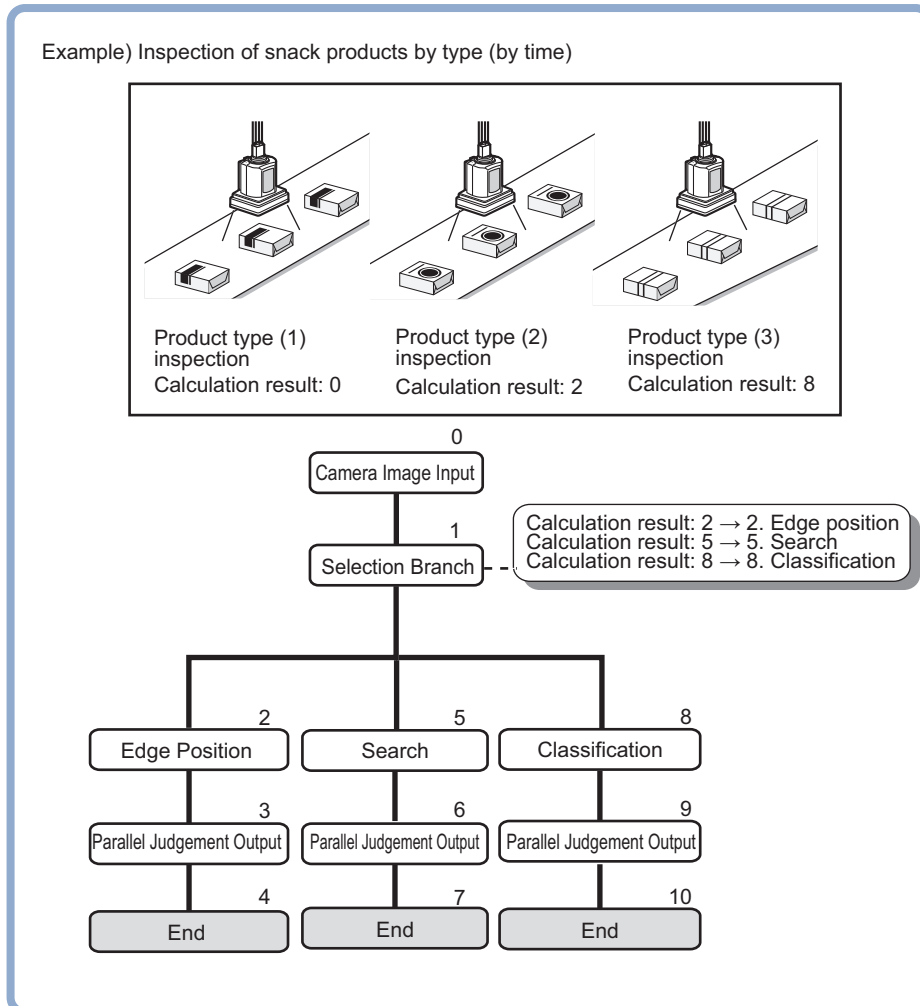
Selective Branch

The calculation and selection value are set, and based on the matching results of the calculation result and selection value, they branch out from this processing item.

Up to 32 branch destinations can be set.

Used in the Following Case

- When products on one production line are to be inspected according to a time interval



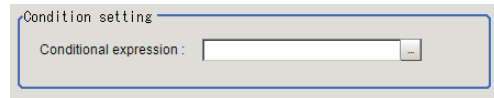
List of Selective Branch Items

Item name	Description
Selective Branch	This item sets the branch conditions. Reference: ▶ Selective Branch (Selective Branch) (p.746)
Output parameter	This item can be changed if necessary. Normally, the factory default value will be used. Reference: ▶ Output Parameter (Selective Branch) (p.747)

Selective Branch (Selective Branch)

This item sets the branch conditions. Up to 32 branch destinations can be set. Branch destinations can be easily enabled or disabled using the checkboxes. Only set the necessary items.

- 1 In the Item Tab area, click [Selective Branch].
- 2 In the "Condition setting" area, set the expression of the condition to branch.

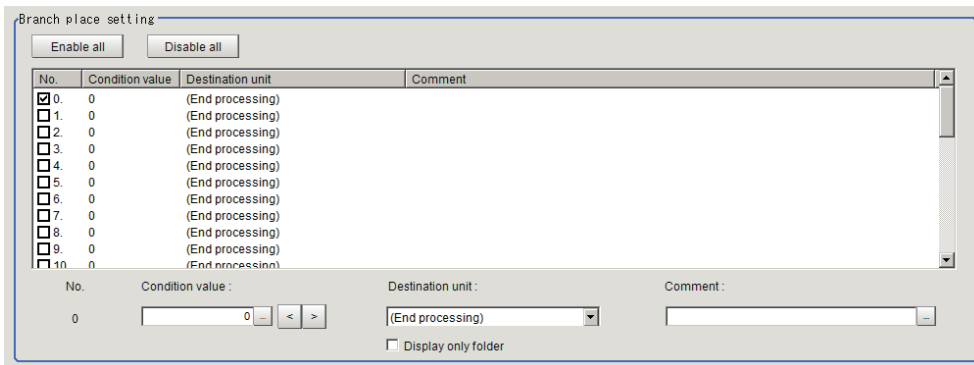


Condition setting

Conditional expression :

- 3 In the "Branch place setting" area, click the number of the branch destination that will set the condition to branch.

Clicking [Enable all] will enable all branch destinations.
Clicking [Disable all] will enable all branch destinations.



Branch place setting

Enable all Disable all

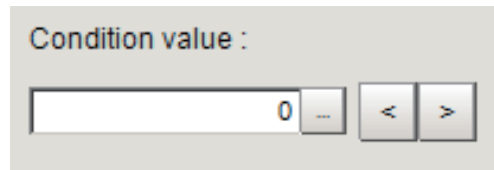
No.	Condition value	Destination unit	Comment
<input checked="" type="checkbox"/> 0	0	(End processing)	
<input type="checkbox"/> 1	0	(End processing)	
<input type="checkbox"/> 2	0	(End processing)	
<input type="checkbox"/> 3	0	(End processing)	
<input type="checkbox"/> 4	0	(End processing)	
<input type="checkbox"/> 5	0	(End processing)	
<input type="checkbox"/> 6	0	(End processing)	
<input type="checkbox"/> 7	0	(End processing)	
<input type="checkbox"/> 8	0	(End processing)	
<input type="checkbox"/> 9	0	(End processing)	
<input type="checkbox"/> 10	0	(End processing)	

No. Condition value : Destination unit : Comment :

0 (End processing)

Display only folder

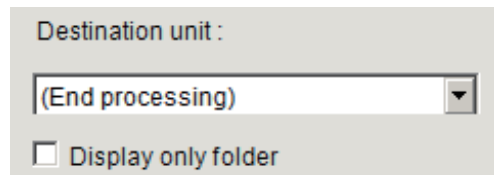
- 4 Click [<] or [>], or click [...] in [Condition value] to set the selection value.



Condition value :

- 5 Click [▼] in [Destination unit] and select the destination unit.

If [Display only folder] is checked, only the folder first unit will be set.



Destination unit :

(End processing)

Display only folder

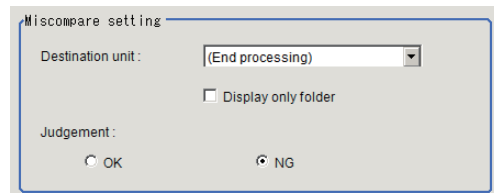
- 6 Click [...] in [Comment] to enter a comment.



Comment :

- 7 Click [▼] in [Destination unit] in the "Miscompare setting" area and set the destination unit.

If [Display only folder] is checked, only the folder first unit will be set.



Miscompare setting

Destination unit : (End processing)

Display only folder

Judgement :

OK NG

- 8 Select [Judgement].
- 9 Click [OK].

Output Parameter (Selective Branch)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- 1 Click [Output parameter] in the Item Tab area.
- 2 Select the "Reflect to overall judgement".

Setting item	Setting value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Specify whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

Key Points for Adjustment (Selective Branch)

Select the adjustment method referring to the following points.

When the system freezes after executing the measurement

Parameter to be adjusted	Troubleshooting
Selection branch	An infinite loop occurs when the branch destination unit is incorrect. In order to avoid a measurement processing looping, for the branch destination, set a processing unit number that is after the [Selection branch].

When measurement processing of an unintended unit is executed

Parameter to be adjusted	Troubleshooting
-	If [End] is not registered at the end of a branch, the processing in the scene will continue to move to the next unit No. even if the branch has been completed. Make sure to set "End" at the last branch destination.

When the judgement results (JG) of the unit within the flow is updated or not updated

Parameter to be adjusted	Troubleshooting
-	The system is designed this way. For results other than the unit's judgement results (JG), the measurement result during the previous pass is retained. The JG for units that do not pass through the condition branch becomes unmeasured (0). Note, however, that the unit JG becomes unmeasured at the point in time when all the measurement processing ends. During flow processing, the previous time judgement (JG) is retained.

Measurement Results for Which Output Is Possible (Selective Branch)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Condition No	JN	Condition number that matches the selection condition expression result
Destination	BU	Branch destination unit number of the condition that matches the selection condition expression result
Conditional expression	DJ	Expression result of the selection conditional expression

External Reference Tables (Selective Branch)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5	Condition No.	Get only	0 to 32767
6	Branch place	Get only	0 to 32767
7	Conditional expression	Get only	-99999.9999 to 99999.9999
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Miscompare branch place	Set/Get	-1: End (initial value) 0 to 9999
121	Miscompare judgement	Set/Get	0: NG 1: OK
122	Condition value judge	Set/Get	Exp. character string
130 + N × 10 (N = 0 to 31)	Destination unit No. N	Set/Get	-1: End 0 to 9999
131 + N × 10 (N = 0 to 31)	Condition value N	Set/Get	-9999 to 9999
132 + N × 10 (N = 0 to 31)	Comment N	Set/Get	Character string
133 + N × 10 (N = 0 to 31)	Validation Flag N	Set/Get	0: No validation 1: Validation

Output result

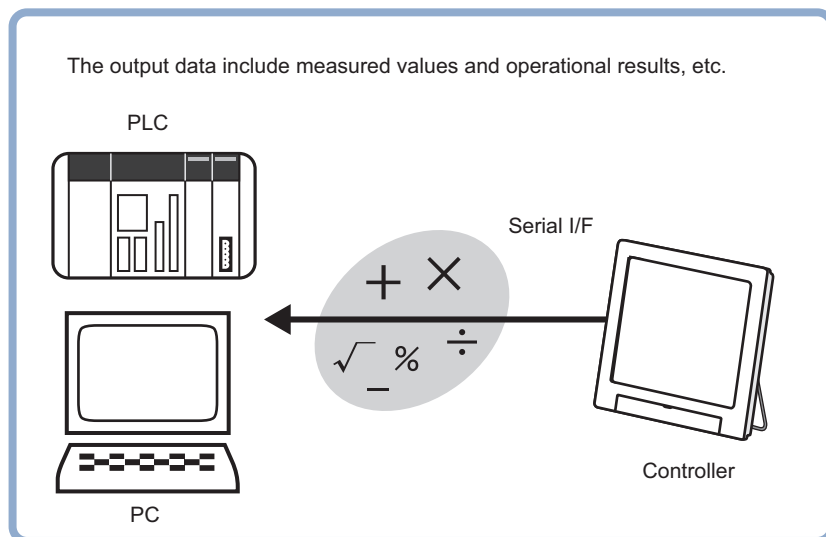
This chapter describes setting methods for when measurement results are output to the external devices.

Data Output	750
Parallel Data Output	751
Parallel Judgement Output.....	752
Fieldbus Data Output	753

Data Output

Used in the Following Case

- Output data to the external devices such as programmable controller and PC with the no-order mode via the serial interface. With serial data output, output starts immediately after the end of processing of serial data output in the flow.

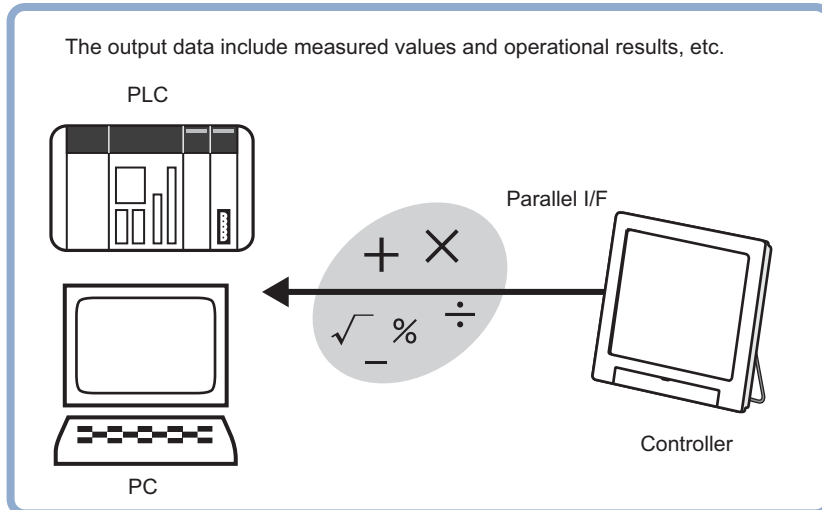


Reference: ▶ The settings for the serial data output, refer to "Chapter 2 Methods for Connecting and Communicating with External Devices" in the "Vision System FH/FZ5 Series User's Manual for Communications Settings (Z342)"

Parallel Data Output

Used in the Following Case

- Used when outputting data to external devices such as a programmable controller or a PC via the parallel interface.

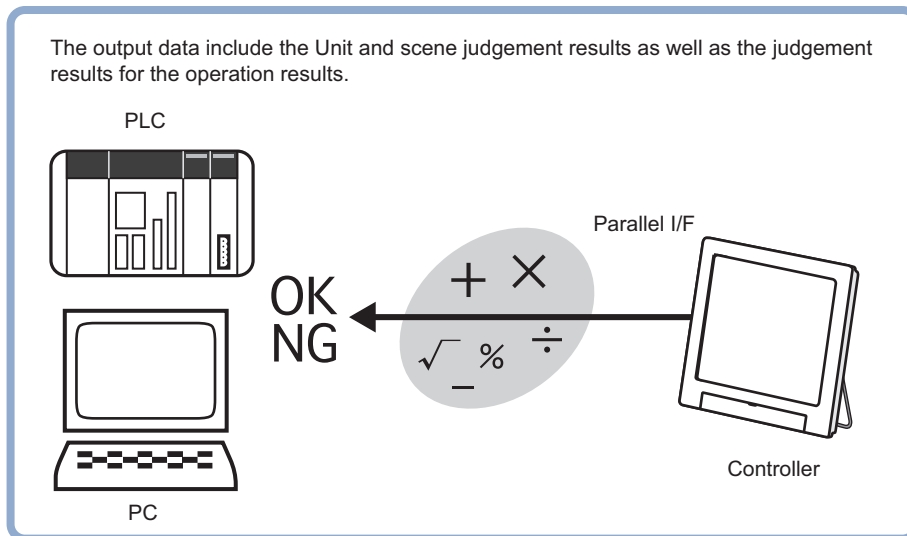


Reference: ▶ The settings for the parallel data output, refer to "Chapter 2 Methods for Connecting and Communicating with External Devices Parallel Communications" in the "Vision System FH/FZ5 Series User's Manual for Communications Settings (Z342)"

Parallel Judgement Output

Used in the Following Case

- Used when outputting judgement results to external devices such as a programmable controller or PC via the parallel interface.

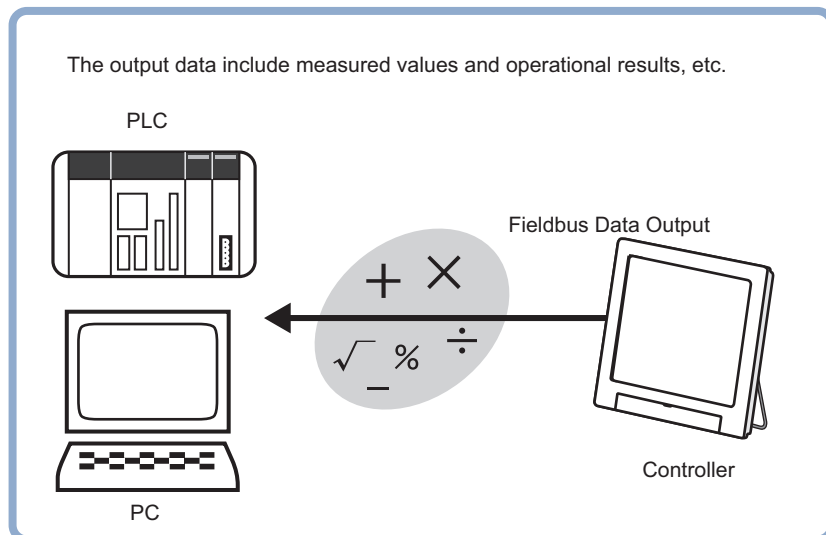


Reference: ▶ The settings for the parallel judgement output, refer to "Chapter 2 Methods for Connecting and Communicating with External Devices Parallel Communications" in the "Vision System FH/FZ5 Series User's Manual for Communications Settings (Z342)"

Fieldbus Data Output

Used in the Following Case

- Used when outputting data to an external device, such as a programmable controller, via the Fieldbus interface.



Reference: ▶ The settings for the Fieldbus data output, refer to "Chapter 2 Methods for Connecting and Communicating with External Devices EtherCAT Connections (FH Only) / Communicating with EtherNet/IP" in the "Vision System FH/FZ5 Series User's Manual for Communications Settings (Z342)"

Display result

This chapter describes how to display strings and figures in the window that displays the measurement results.

Result Display	756
Display Image File	761
Display Last NG Image.....	763

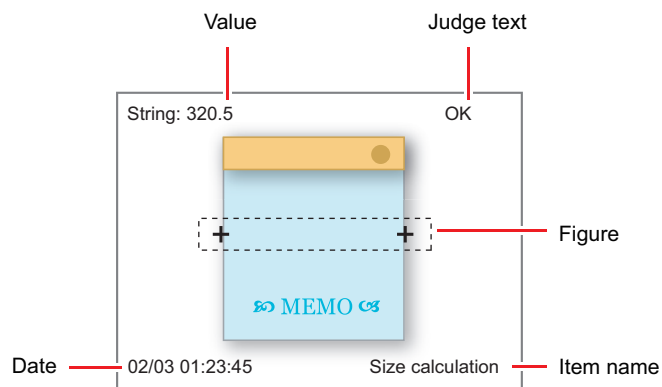
Result Display

Used in the Following Case

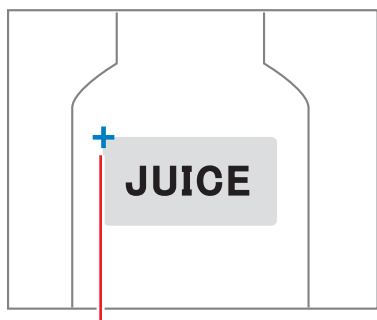
For your convenience in verifying measurement results, text and figures will be displayed in the "Image display" area.

The following content can be displayed.

Example) Displaying options, such as Display string, Display value, Display judge, Display item name, Display date, on screen.



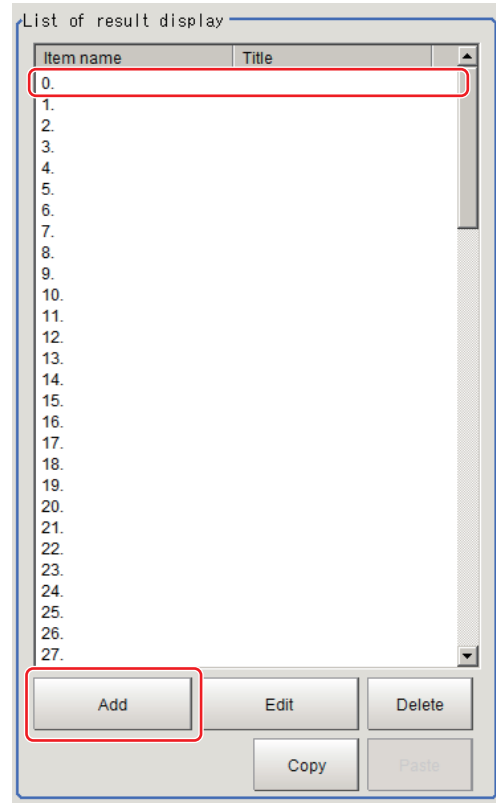
Example) Display the cross-shaped cursor at the measured position of the label.



Display the cross-shaped cursor at the measured position.

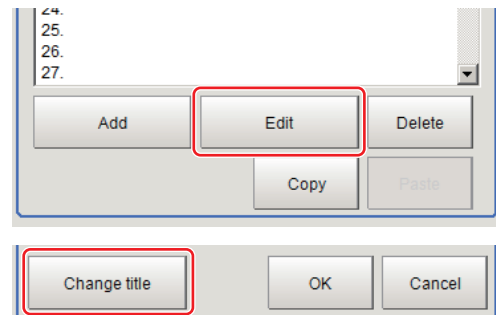
Result Display

- 1 In the "List of result display" area, select the number with which to set the object and click [Add].



- 2 Select the object to be added in the Select Items to Display window and click [OK].
The selected object is added to the "List of result display" area and the Image Display area.
- 3 In the "List of result display" area, select the object and click [Edit].

Setting options are displayed. The setting items are different depending on the object.



- 4 Click [Change title] as necessary to change titles displayed in the list of result display.

Up to 31 characters can be entered.

When Rectangle, Line, Wide Circle, Ellipse, Arc, Crosshair Cursor Display or Cross Line Is Selected

Specify display position, style, width, and color of figure.

Setting item	Setting item	Description
Display position Disp pos	Figure (or Numerical)	Select this if you would like the figure to always display in the same location. Methods for specifying display position include drawing the figure on the window and indicating coordinates numerically. If you would like to always display the figure in a reference position, set up an expression using "Operation".
	Operation	Select this when you would like to change display position for each measurement based on the measured value. Set up the expression to specify the display position.

Setting item	Setting item	Description
Style	<ul style="list-style-type: none"> • Solid line • Dashed line 	Select the line type.
Width	1 to 10	Modify the line width.
Color	OK Color	Displayed in green.
	NG Color	Displayed in red.
	Judgement	Displayed using OK color or NG color based on the judgment results. Specify measurement values subject to judgment and set up respective judgment conditions.
	Arbitrary color	Displayed using specified color. Methods for specifying color include specifying by clicking on a color chart and specifying RGB values.

When String Display, Measurement, Processing Item Name, Judge Display, Display Date, or Display Unit String Is Selected

Sets display position, size, and color etc. of characters.

Common settings

Setting item	Setting item	Description
Display position	Figure (or Numerical)	Select this if you would like the figure to always display in the same location. Methods include specifying by clicking on the window and specifying coordinate values. However, if you would like to always display the figure in a reference position, set an expression using "Operation".
	Operation	Select this when you would like to change display position for each measurement based on the measured value. Set up the expression to specify the display position.

Detail

Setting item	Setting item	Description
Align	<ul style="list-style-type: none"> • Top • Bottom • Left • Center • Right 	Specify the alignment of the text.
Size	10 to 200	Specify the font size.
Angle	0 to 359	Specify the display angle.
Style	<ul style="list-style-type: none"> • Bold • Italic • Under line • Mark out 	Specify the character decoration.
Color	OK Color	Displayed in green.
	NG Color	Displayed in red.
	Judgement	Displayed using OK color or NG color based on the judgment results. Specify measurement values subject to judgment and set up respective judgment conditions.
	Arbitrary color	Displayed using specified color. Methods for specifying color include specifying by clicking on a color chart and specifying RGB values.

String display

Setting item	Description
Set letter	Set characters within 64 characters.

Judge display

Setting item	Description
Judge type	Specify measurement values subject to judgment and set up respective judgment conditions. Displays using OK letter or NG letter based on the judgment results.
Judgement condition	
OK letter	Sets characters displayed for the case that judgment results are OK.
NG letter	Sets characters displayed for the case that judgment results are NG.

Display date

Setting item	Setting item	Description
Date kind	<ul style="list-style-type: none"> • Month/Day/Hour/Minute/Second • Month/Day/Hour/Minute • Hour/Minute/Second • Hour/Minute 	Select display format Please adjust the calendar time that comes with the controller in advance. Reference: ▶ "Chapter 6 Changing the System Environment Setting the System Operation Environment Setting the Date and Time [Date-time Setting]" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Measurement

Setting item	Setting item	Description
Measurement	-	Specify the measurement value you would like to display using expression.
Digits of integer	1 to 10	Specify the digits of the integer part including the sign. For positive numbers, the plus sign is not output. Example Setting: 4 digits, data -5619 -999 is output.
Decimal	0 to 4	Set the number of decimal fraction digits. Decimals are rounded up and output. When 0 is selected, the decimal digits will be rounded off.

Processing item name

Setting item	Description
Processing item	Choose processing item name from among the scenes being displayed.

Grid display

Setting item	Setting item	Description
Scale display	-	Place a check to show the scale.
Unit	<ul style="list-style-type: none"> • [Calibration] • Pixels 	Select the unit used when grids are displayed.
Interval	0.0000 to 9999.9999 [50.0000]	Set the intervals of the scale on the grids.
Line length	0.0000 to 9999.9999 [10.0000]	Set the length of the scale line on the grids.

Display Unit String

Setting item	Description
Item	Select the processing item name from among the scenes being displayed. Processing items for barcode, 2D code, and character inspection can be selected.
Set unit string	Select a character string contained in the selected processing item name. <ul style="list-style-type: none"> • Character inspection: Reading string, verification string • Barcode : Reading string, comparison string, error output character string • 2D code : Reading string, comparison string, error output character string
String range specify	Place a check to set the display range of character string. Specify a number in the range of 1 to 999.

Toggle between Show/Hide by judgement

Show/Hide can be toggled by judgement.

Setting item	Setting item	Description
Display condition	<ul style="list-style-type: none"> • [Always display] • Only OK display • Only NG display 	Place a check to show the scale.
Judge exp.	-	Set an expression to determine whether it is OK or NG.
Judge condition	-999999999.99999 to 999999999.99999	Specify the range where the measurement result is judged to be OK.

External Reference Tables (Result Display)

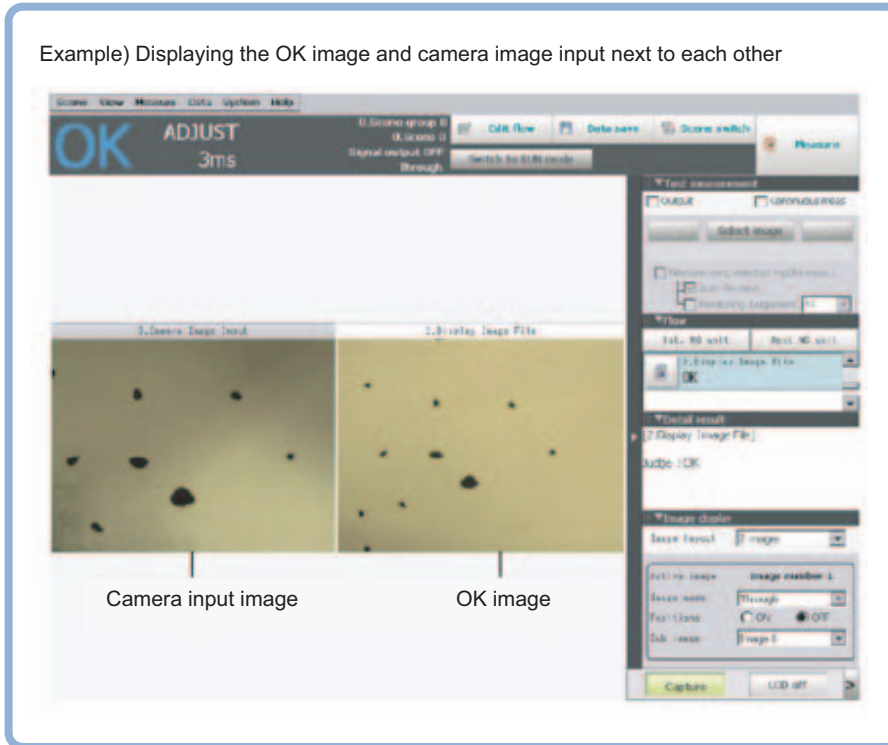
No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK

Display Image File

Displays image files in USB memory or RAMDisk.

Used in the Following Case

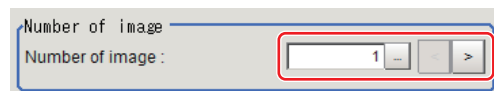
- Use when you want to display camera input images to be used as reference or work images that are OK.



Select Image (Display Image File)

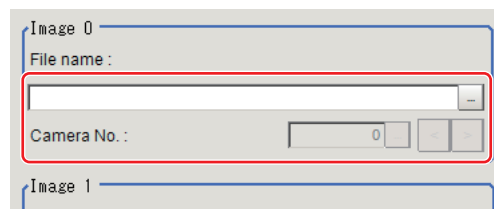
- 1 Set the number of image files to be registered.

Up to 4 can be specified.



- 2 Specify image to be displayed.

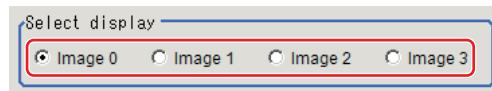
In the case that there are multiple images in an image file, specify the camera number.



Important

- Only image logging files (ifz format) and BMP format image files for which the region size is 1600 × 1200 or less can be specified.

3 Select image to be displayed using select display.



4 Click [OK].

The settings are finalized.

Note

- The images in image file 0 to 3 can be displayed by specifying the sub image number on the RUN window/ ADJUST window.
Reference: ▶"Chapter 3 Performing Test Measurement/Starting Operation Arranging the Window Changing Display Contents, such as Image Mode" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Key Points for Test Measurement and Adjustment (Display Image File)

The following content can be confirmed in the "Detail result" area using text.

Displayed item	Description
Judge	Judgement result

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number.	Explanation of image to be displayed
0	Image 0
1	Image 1
2	Image 2
3	Image 3

External Reference Tables (Display Image File)

No.	Data name	Set/Get	Data range
120	Number of files	Set/Get	1 to 4
121	Camera No. [0]	Set/Get	0 to 3
122	Camera No. [1]	Set/Get	0 to 3
123	Camera No. [2]	Set/Get	0 to 3
124	Camera No. [3]	Set/Get	0 to 3
125	File name [0]	Set/Get	Character string
126	File name [1]	Set/Get	Character string
127	File name [2]	Set/Get	Character string
128	File name [3]	Set/Get	Character string

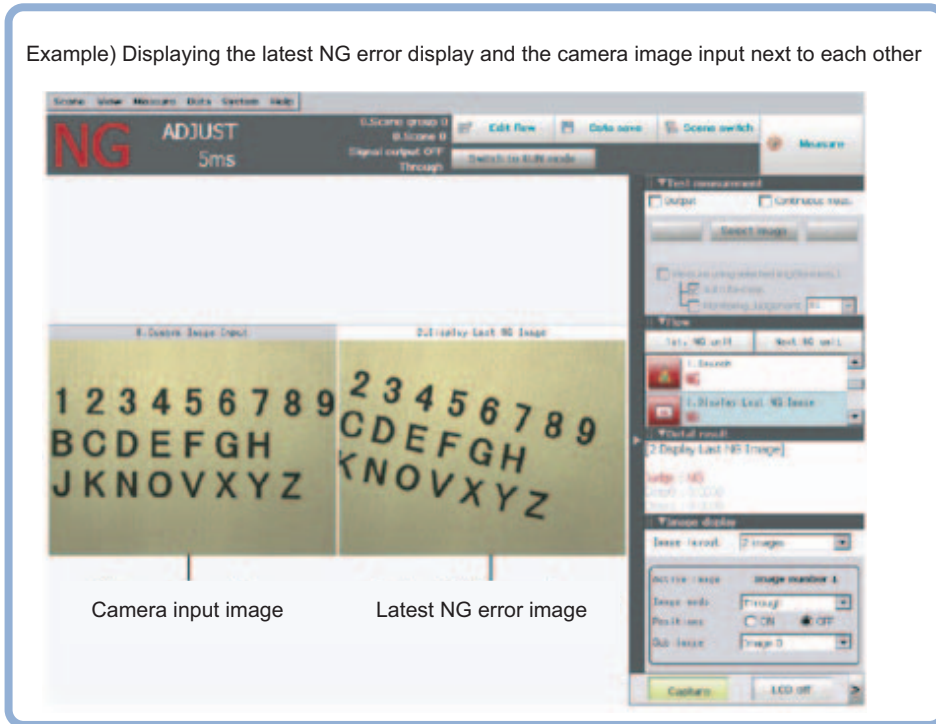
Display Last NG Image

Data, images and drawn data (up to 4 sets) for a NG based on NG conditions defined using an expression can be saved. As the saved image is stored in memory, it is maintained even if operations are performed in the window.

Used in the Following Case

- Image and data for NG case are saved.

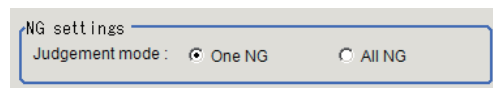
Example) Displaying the latest NG error display and the camera image input next to each other



NG Error Judgement (Display Last NG Image)

Sets conditions for NG judgement.

- 1 Click [Judge NG] in the Item Tab area.
- 2 Set the judgment mode in the "NG settings" area.

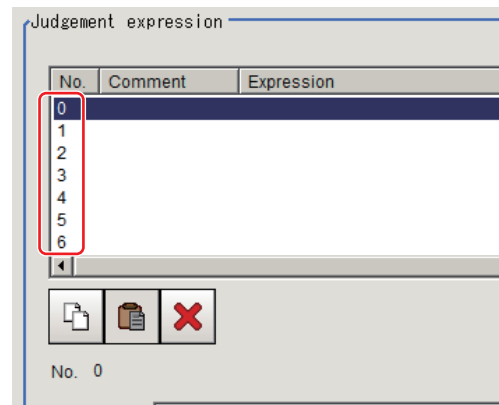


Setting item	Set value [Factory default]	Description
Judgement mode	[One NG]	The image is saved even if only one of the judgment criteria set using "Judgment expression" has a judgment of NG.
	All NG	The image is saved if all of the judgment criteria set using "Judgment expression" have a judgment of NG.

Expression Settings

The measurement details used for NG judgment are set up using an expression.

- 1 Click the "No." for setting the expression from the list in the "Expression setting" area



The No. selected will be displayed below the list.

- 2 Click [...] for the expression and set the expression.

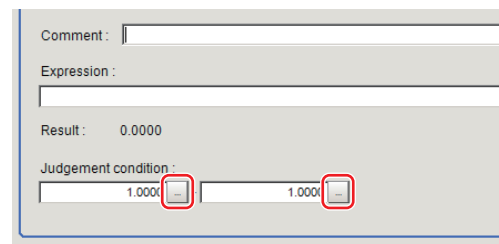
The Setting Expression window is displayed.

- 3 After setting up the expression, click [OK].

The expression is confirmed.

- 4 Click [...] for "Comment" and input an explanation of the expression as necessary.

- 5 Set up the judgement upper limit and the judgement lower limit for "Judgement".



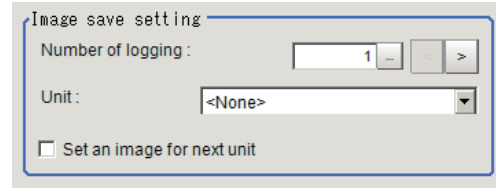
Setting item	Setting value [Factory default]	Description
Judgement condition	-999999999.9999 to 999999999.9999	This is a judgement condition for the expression. Set upper and lower limits for judging as OK.

- 6 Repeat the Reference: ▶ 1 (p.764) to Reference: ▶ 6 (p.764) and set up the expression.

Image Saving (Display Last NG Image)

Specifies the target unit to be saved and number of times images are saved when an NG occurs.

- 1 Click [Image save] in the Item Tab area.
- 2 Specify each of the following items.



Setting item	Set value [Factory default]	Description
Number of logging	[1] to 4	Sets the number of NG images that are saved. A maximum of 4 NG images consisting of Last NG, Last 1 NG, Last 2 NG, Last 3 NG can be saved.
Unit	-	Specifies target processing unit for saving image. Select the unit (camera input image, image with pre-processing or position compensation) with the image you would like to save. Please select a unit from earlier than the unit being processed as the target unit.
Set an image for next unit	<ul style="list-style-type: none"> • Checked • [Unchecked] 	Check when using an image acquired by a processing unit after this unit.

3 Set up the expression.

Reference: ▶ Expression Settings (p.764)

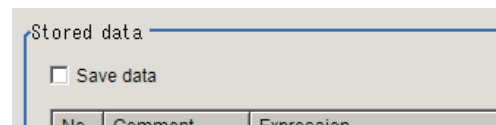
Note

- Saved images are stored in sub images 0 to 3.
To display sub images
Reference: ▶ "Chapter 3 Performing Test Measurement/Starting Operation Arranging the Window Changing Display Contents, such as Image Mode" in the "Vision System FH/FZ5 Series User's Manual (Z340)"

Data Saving (Display Last NG Image)

Sets data to be saved when NG occurs.

- 1 Click [Saving data] in the Item Tab area.
- 2 Specify each of the following items.



Setting item	Set value [Factory default]	Description
Save data	<ul style="list-style-type: none"> [Unchecked] Checked 	Check when saving measurement data using an expression when NG occurs. In conjunction with the number of saves, a maximum of 4 items of measurement data from Last NG, Last 1 NG, Last 2 NG, Last 3 NG can be saved for one expression. Please set the expression to reference a unit prior to the unit currently being processed.

3 Set up the expression.

Reference: ▶ Expression Settings (p.764)

4 Set up the judgement condition.

Output Parameters (Display Last NG Image)

Specifies whether or not the judgement results of this processing unit is reflected in the scene overall judgement.

- 1** Click [Output parameter] in the Item Tab area.
- 2** Choose whether or not to reflect the judgement result in the scene overall judgement in "Reflect to overall judgement" area.

Setting item	Set value [Factory default]	Description
Reflect to overall judgement	<ul style="list-style-type: none"> • [ON] • OFF 	Enables choosing whether or not the judgment results of this processing unit is reflected in the scene overall judgment.

Key Points for Test Measurement and Adjustment (Display Last NG Image)

The following content is displayed in the "Detail result" area as text.

Displayed items	Description
Data 0 comment	Expression result of Expression 0
Data 1 comment	Expression result of Expression 1
Data 2 comment	Expression result of Expression 2
Data 3 comment	Expression result of Expression 3
Data 4 comment	Expression result of Expression 4
Data 5 comment	Expression result of Expression 5
Data 6 comment	Expression result of Expression 6
Data 7 comment	Expression result of Expression 7
Data 8 comment	Expression result of Expression 8
Data 9 comment	Expression result of Expression 9
Data 10 comment	Expression result of Expression 10
Data 11 comment	Expression result of Expression 11
Data 12 comment	Expression result of Expression 12
Data 13 comment	Expression result of Expression 13
Data 14 comment	Expression result of Expression 14
Data 15 comment	Expression result of Expression 15

The image specified in the sub image in image display setting is displayed in the image display area.

Sub image number.	Explanation of image to be displayed
0	Last NG
1	Previous NG error image (Displayed when there are 2 or more saved images. Otherwise, "Last NG" is displayed.)
2	NG error image from 2 previous (Displayed when there are 3 or more saved images. Otherwise, "Last NG" is displayed.)
3	NG error image from 3 previous (Displayed when there are 4 or more saved images. Otherwise, "Last NG" is displayed.)

Measurement Results for Which Output Is Possible (Display Last NG Image)

The following values can be output using processing items related to results output. It is also possible to reference measurement values from expressions and other processing units.

Measurement items	Character string	Description
Judge	JG	Judgement result
Judge data 00 to 07	JD 00 to 07	Calculation data 00 to 07 for inclusion 0
Judge judge 00 to 07	JJ 00 to 07	Calculation judgment 00 to 07 for inclusion 0
Last NG data 00 to 15	D000 to 15	NG data 00 to 15
Last NG judge 00 to 15	J000 to 15	Judge NG 00 to 15
Last 1 NG data 00 to 15	D100 to 15	Last N NG data 00 to 15
Last 1 NG judge 00 to 15	J100 to 15	Last N NG judge 00 to 15
Last 2 NG data 00 to 15	D200 to 15	Last N NG data 00 to 15
Last 2 NG judge 00 to 15	J200 to 15	Last N NG judge 00 to 15
Last 3 NG data 00 to 15	D300 to 15	Last N NG data 00 to 15
Last 3 NG judge 00 to 15	J300 to 15	Last N NG judge 00 to 15

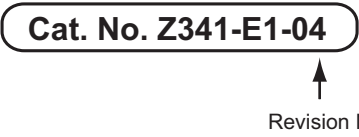
External Reference Tables (Display Last NG Image)

No.	Data name	Set/Get	Data range
0	Judge	Get only	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
5 to 12	Judge data N (N = 0 to 7)	Set/Get	-999999999.9999 to 999999999.9999
13 to 20	Judge judge N (N = 0 to 7)	Set/Get	0: No judgement (unmeasured) 1: Judgement result OK -1: Judgement result NG
103	Reflect to overall judgement	Set/Get	0: ON 1: OFF
120	Judgement mode	Set/Get	0: One NG 1: All NG
121	Save type	Set/Get	0: Image 1: Image + data
122	Number of logging	Set/Get	1 to 4
123	Target processing unit number	Set/Get	-1 to 9999 -1: Save the image of itself
124	Image memory setting flag	Set/Get	0: OFF 1: ON
140 to 147	Condition exp N (N = 0 to 7)	Set/Get	Exp character string for inclusion processing unit 0
148 to 163	Upper limit of condition calculation M (M = 0 to 15)	Set/Get	Even number is upper limit, odd number is lower limit Exp upper and lower limits for inclusion processing unit 0
	Lower limit of condition calculation M (M = 0 to 15)	Set/Get	

No.	Data name	Set/Get	Data range
164 to 171	Condition comment M (M = 0 to 15)	Set/Get	Exp comment character string for inclusion processing unit 0
180 to 195	Data exp M (M = 0 to 15)	Set/Get	Exp character string for inclusion processing unit 1/2 First half is 1, second half is 2.
196 to 227	Upper limit for data calculation M (M = 0 to 15)	Set/Get	Even number is upper limit, odd number is lower limit Exp upper and lower limits for inclusion processing unit 1/2 First half is 1, second half is 2.
	Lower limit for data calculation M (M = 0 to 15)	Set/Get	
228 to 243	Data comment M (M = 0 to 15)	Set/Get	Exp comment character string for inclusion processing unit 1/2. First half is 1, second half is 2.
500 to 515	NG data [] [M] (M = 0 to 15)	Set/Get	-999999999.9999 to 999999999.9999

Manual Revision History

The manual revision symbol is an alphabet appended at the end of the manual number found in the bottom left-hand corner of the front or back cover.



Rev. No.	Reprint symbol	Rev. Date	Revision Contents	Software Version
01	(1)	Jul. 2013	Original production	Ver.5.00
02	(1)	Aug. 2013	Additions for lighting controllers.	Ver.5.10
03	(1)	Aug. 2013	Additions for software version upgrade.	Ver.5.10
04	(1)	Sep. 2013	Additions for software version update.	Ver.5.12

MEMO

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